

TrackKnee: Knee Angle Measurement Using Stretchable Conductive Fabric Sensors

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Introduction



Knee injuries are prevalent among all demographics of patients



The biggest factor in recovery from a knee injury is adherence to the assigned rehabilitation protocol



Estimating joint angles is an important part of these protocols

Goals



Create a soft wearable device
that is comfortable to wear and
easy to use



Accurately calculate knee
angles using a soft sensor

Research Questions

How can we measure knee angles using stretchable conductive fabric?

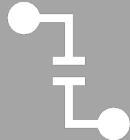
How can we design and fabricate a wearable device that tracks knee angles using conductive stretchable fabric and is comfortable to wear?

How accurately can we measure knee angles with our wearable device?

Modeling Knee Angles



Change in Length to Angle
Model

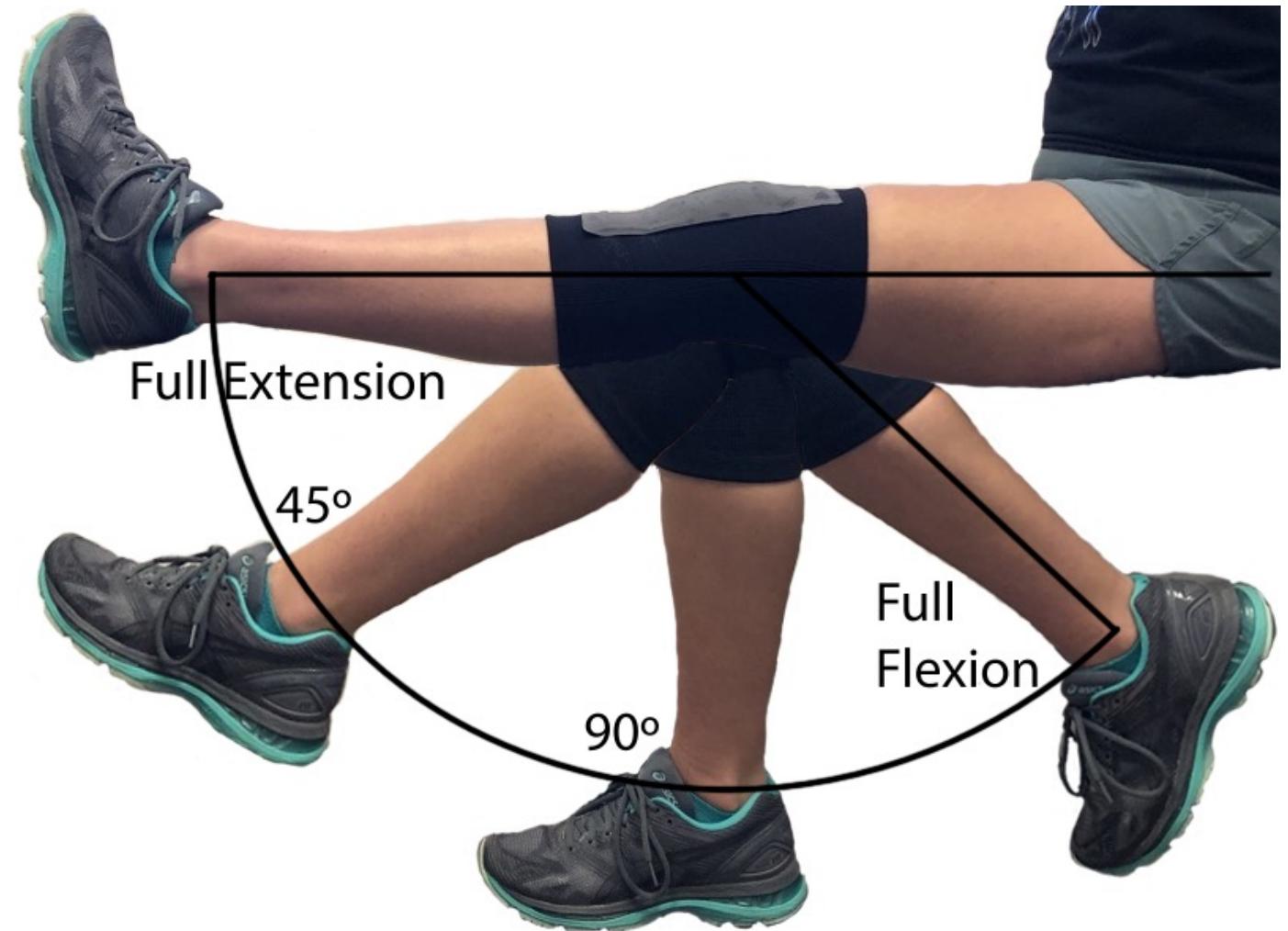


Resistance to Change in Length
Model



Voltage to Resistance Model

Knee Motion

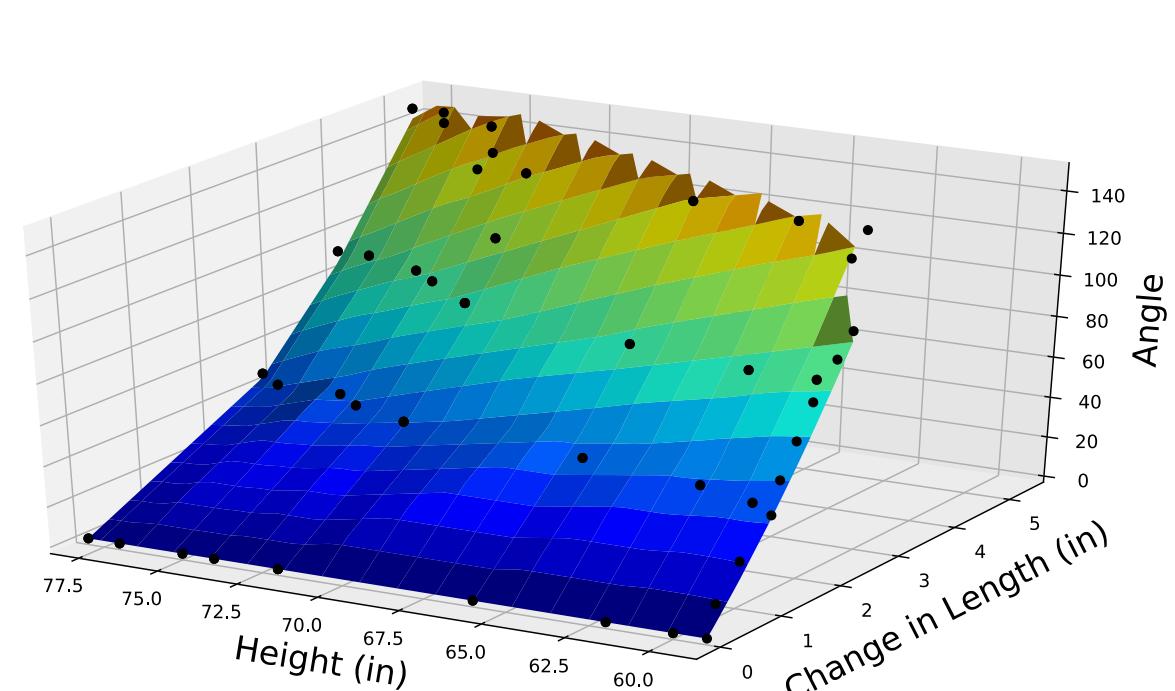
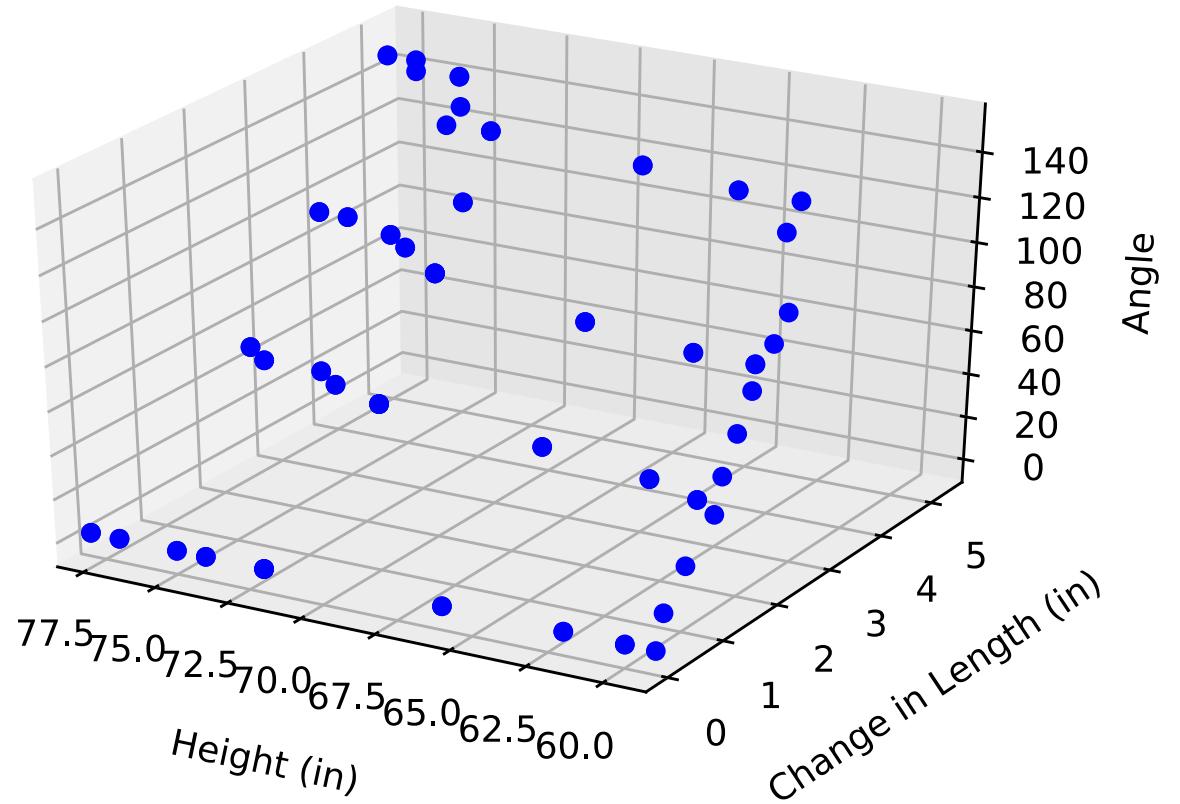


Survey Of Knee Motion

Height	Change in Length					Angle of Maximum Flexion	
	0°	45°	90°	Full Flexion Right	Full Flexion Left	Right	Left
4'11"	0"	1"	1.625"	2.5"	2.25"	125°	119°
5'0"	0"	1.5"	2.25"	2.75"	3"	142°	148°
5'2"	0"	1.5"	2.25"	3"	3"	145°	143°
5'6"	0"	1.75"	2.5"	2.5"	3.5"	148°	146°
6'0"	0"	2"	3"	3.5"	3.5"	113°	115°
6'0"	0"	2"	3"	4"	4"	139°	137°
6'2"	0"	2.25"	3.5"	4.25"	4.5"	135°	140°
6'3"	0"	2.5"	3.75"	5"	5"	148°	148°
6'5"	0"	2.5"	4"	5.25"	5"	145°	140°
6'6"	0"	2.75"	4"	5.25"	5.25"	148°	145°

Model of Change in Knee Motion

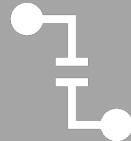
$$A = 148.948L + 4.428L^2 - 1.86251LH$$



Modeling Knee Angles



Change in Length to Angle
Model



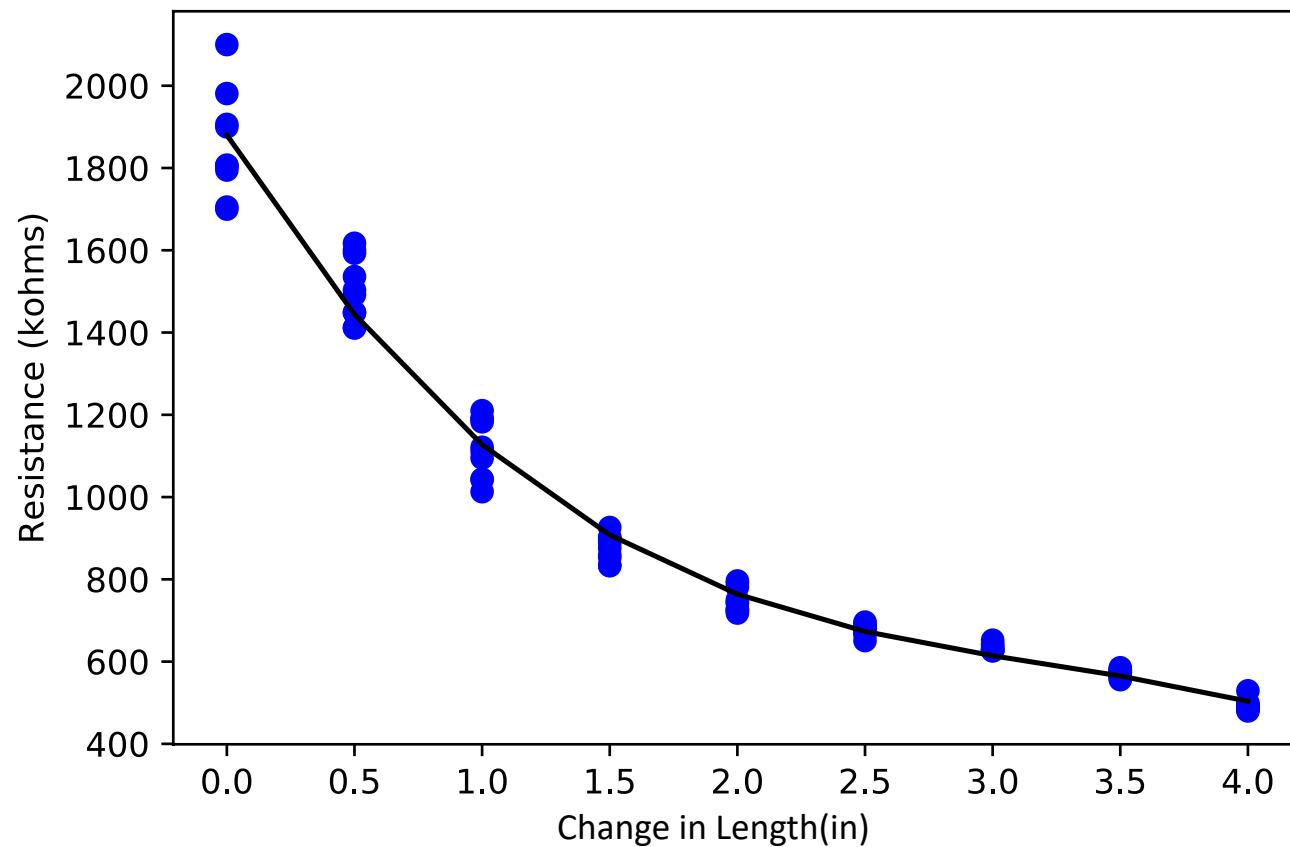
Resistance to Change in Length
Model



Voltage to Resistance Model

Resistance to Change in Length

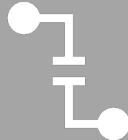
$$L = -29:184R^3 + 282:126 R^2 - 1005:642R + 1880.047$$



Modeling Knee Angles



Change in Length to Angle
Model

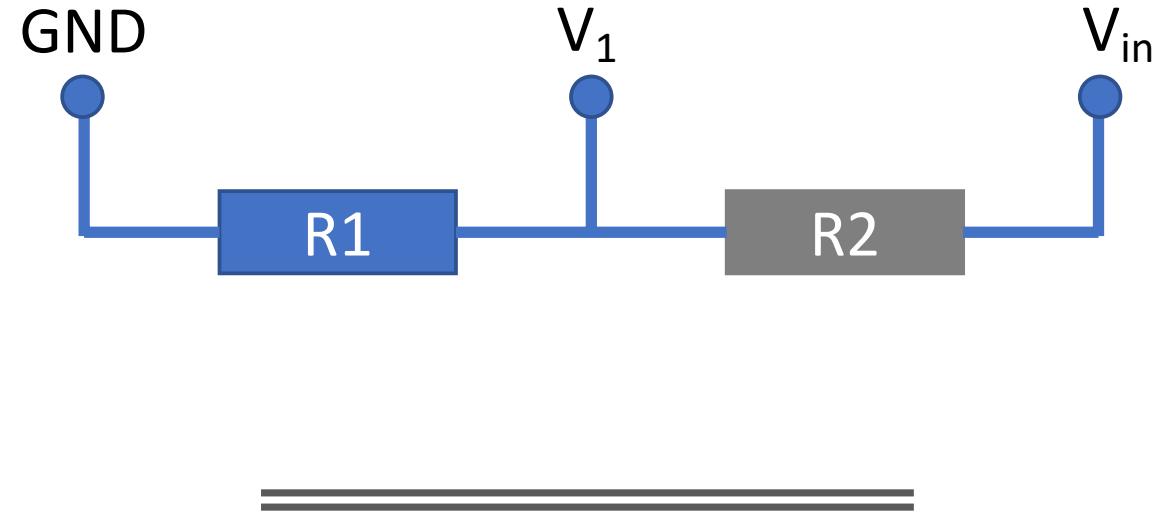


Resistance to Change in Length
Model



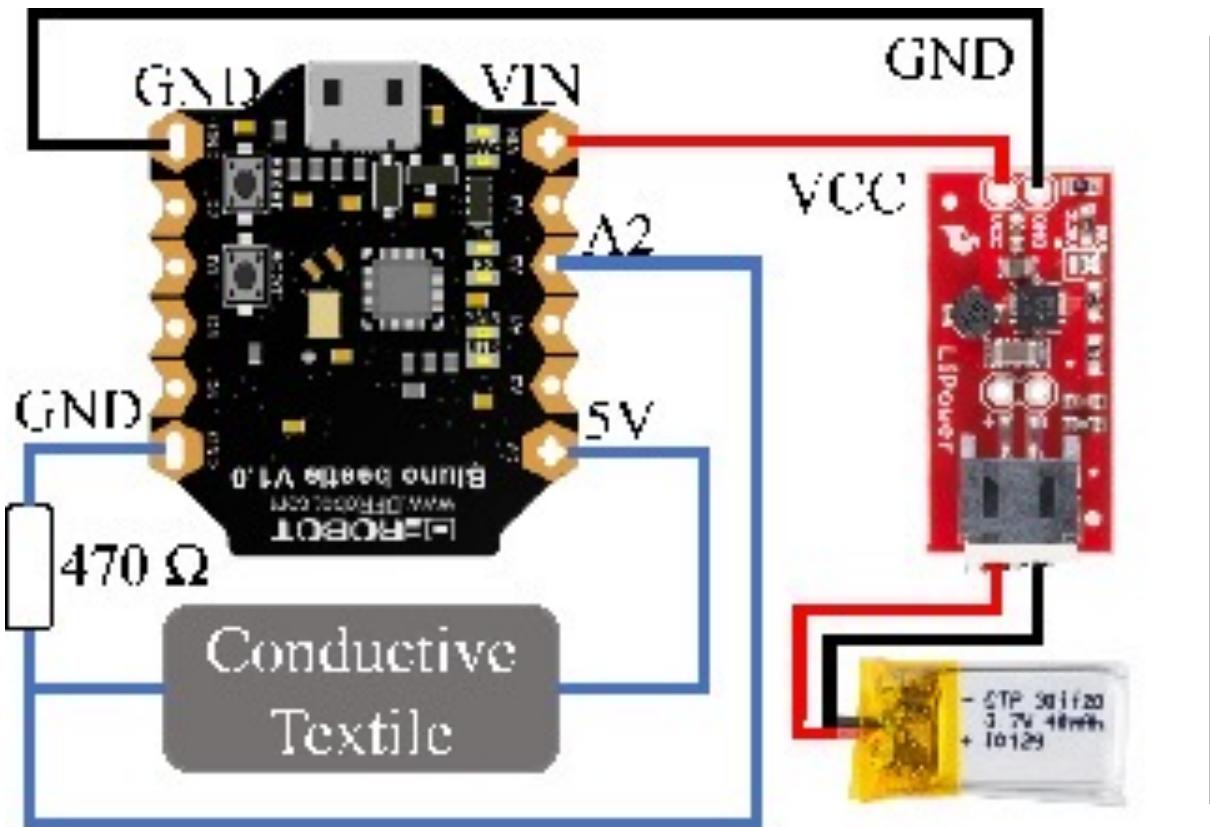
Voltage to Resistance Model

Voltage to Resistance Model

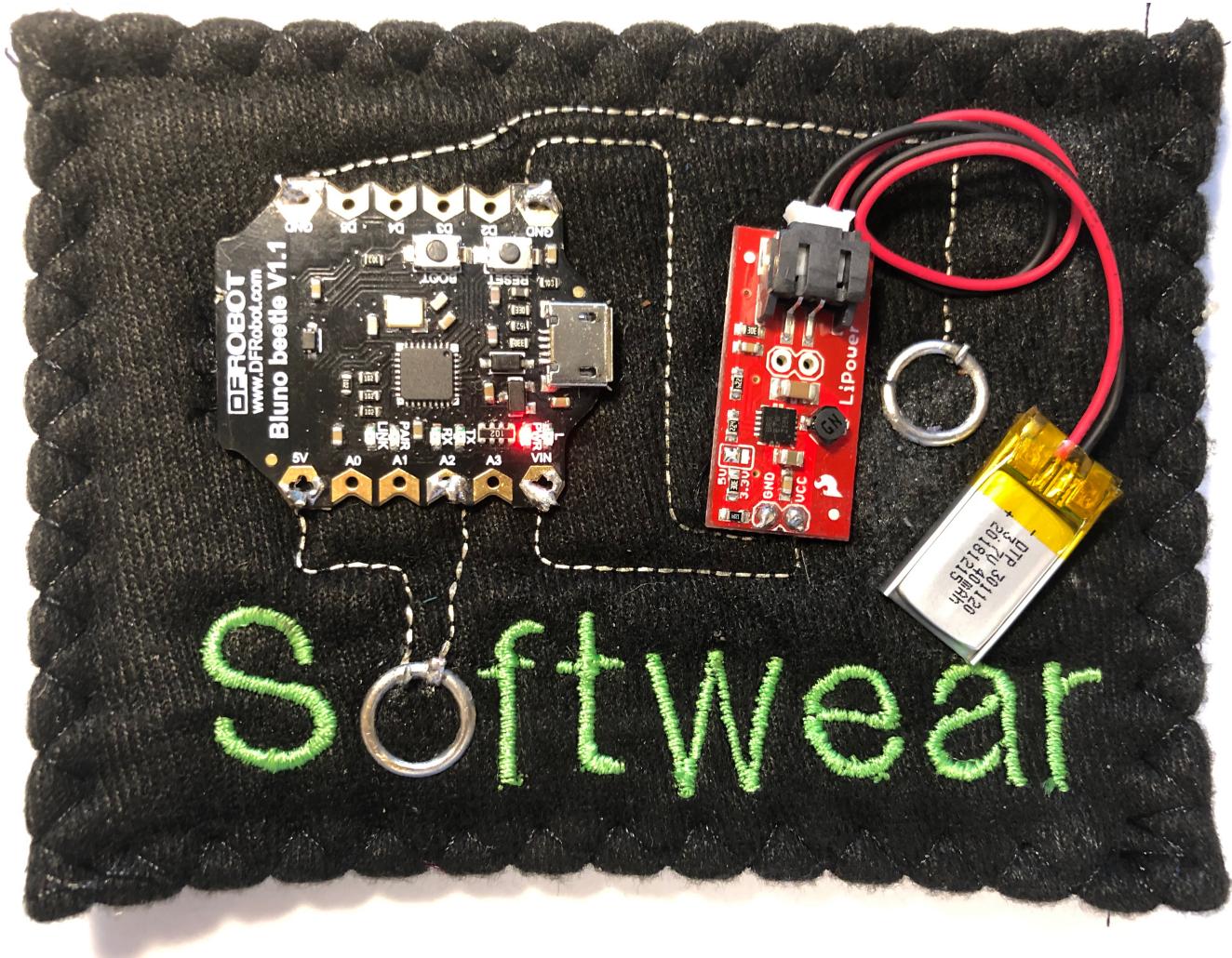


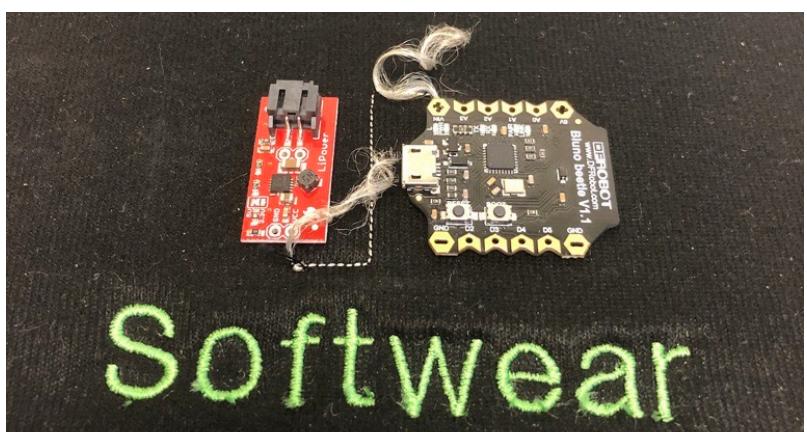
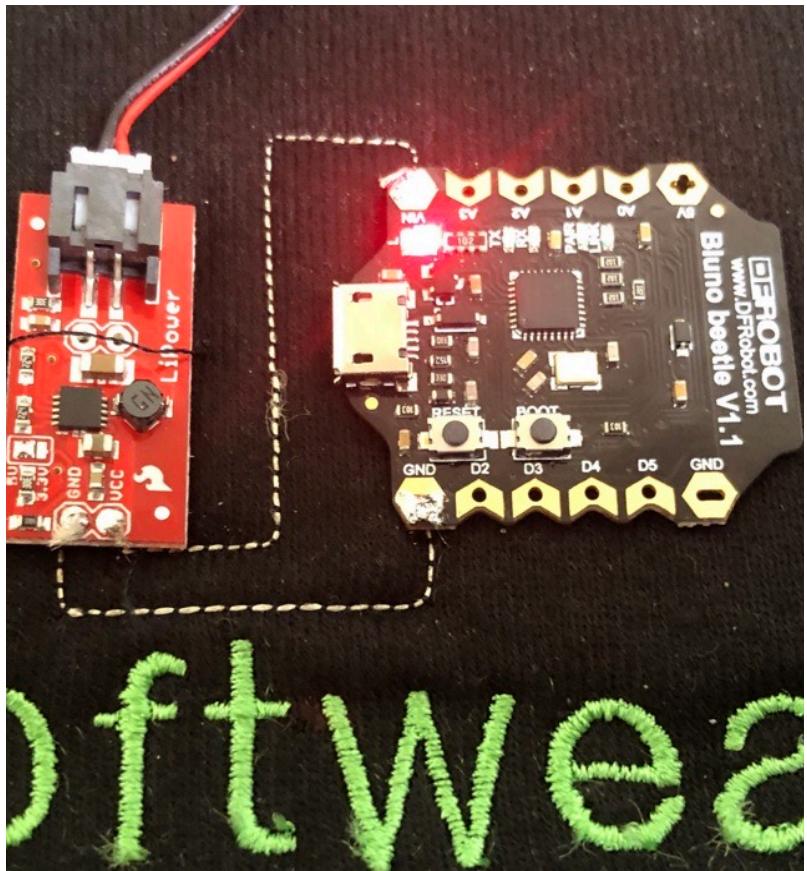
$$R_2 = \frac{V_1 * R_1}{V_{in} - V_1}$$

Tracknee Prototype Design



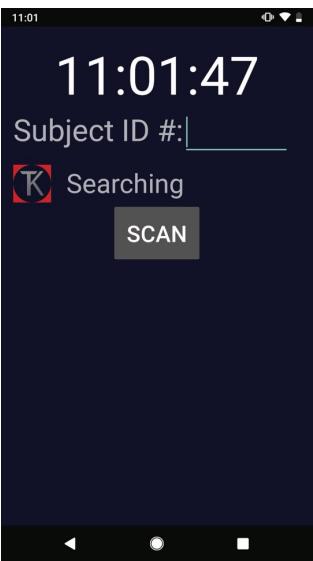
Control Patch



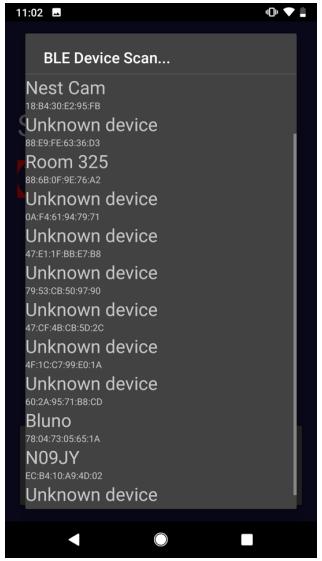


Data Collection Application

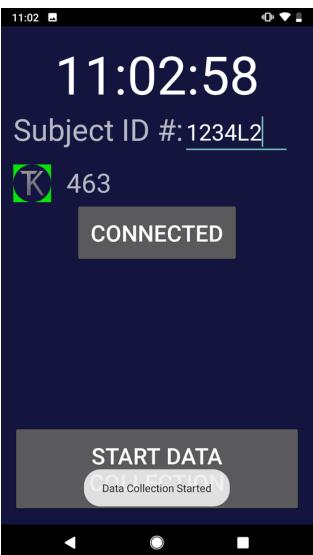
Initial State



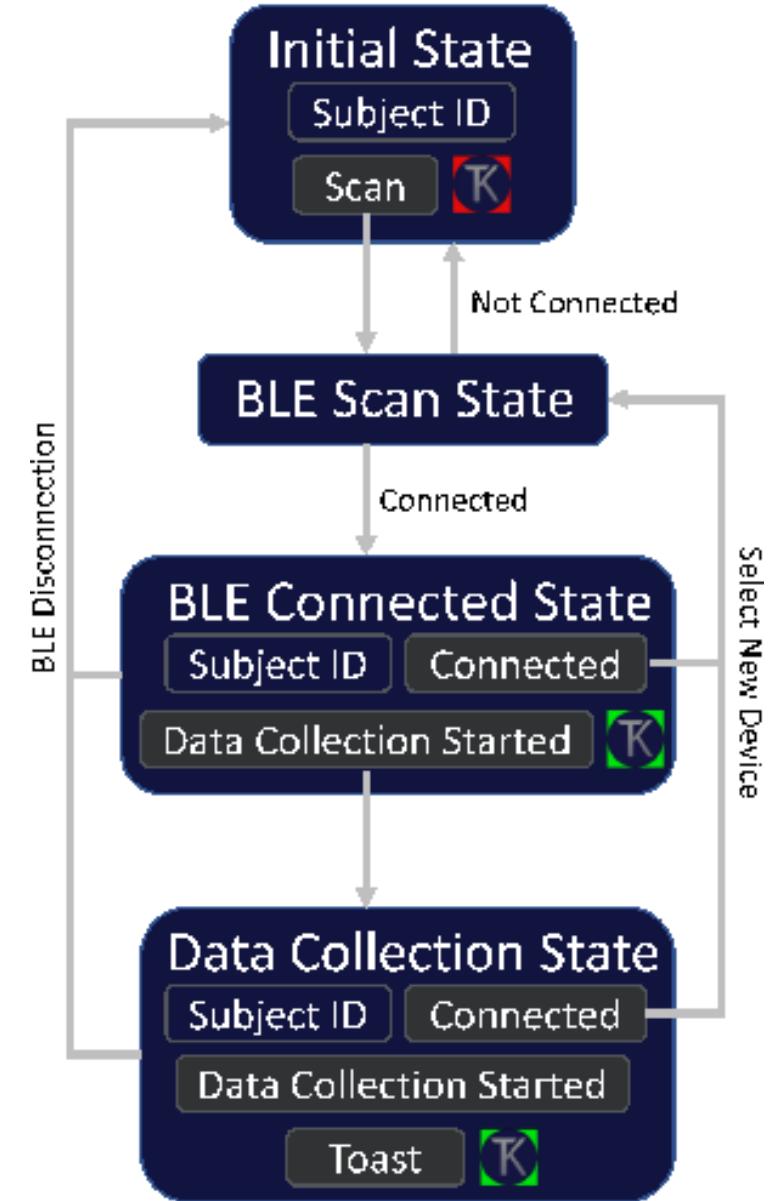
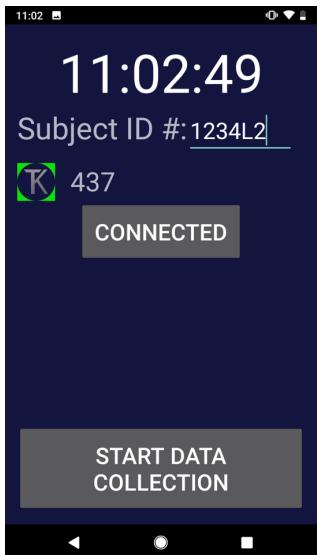
BLE Scan State



BLE Connected State

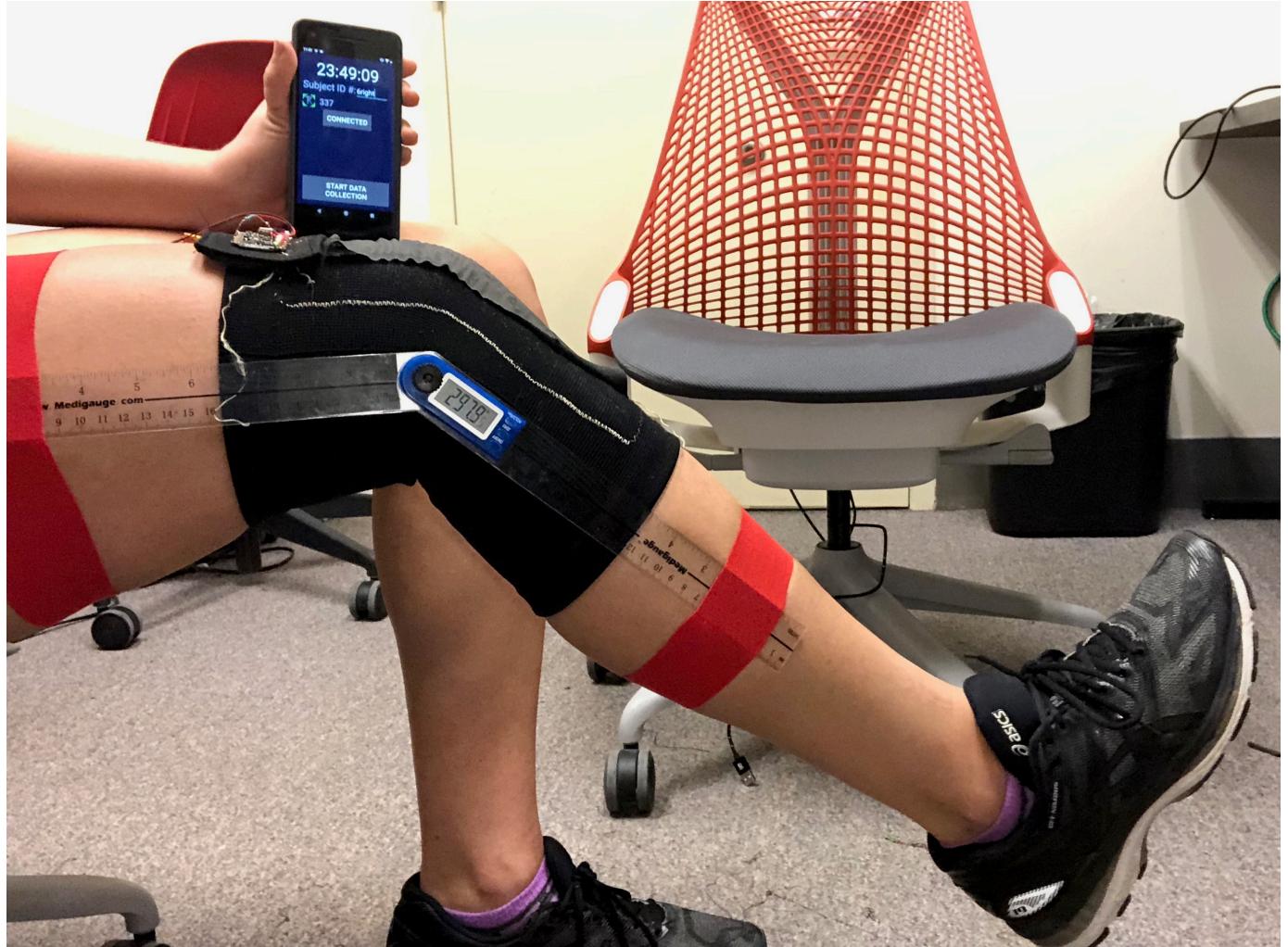


Data Collection State



User Study

- 240 total knee angles
- Knee Angles- 0° , 15° , 30° , 45° , 60° ,
 75° , 90° , 105° , 120° , and 135°
- All participants had a normal BMI
- Average age: 25.3
- 3 male/3 female

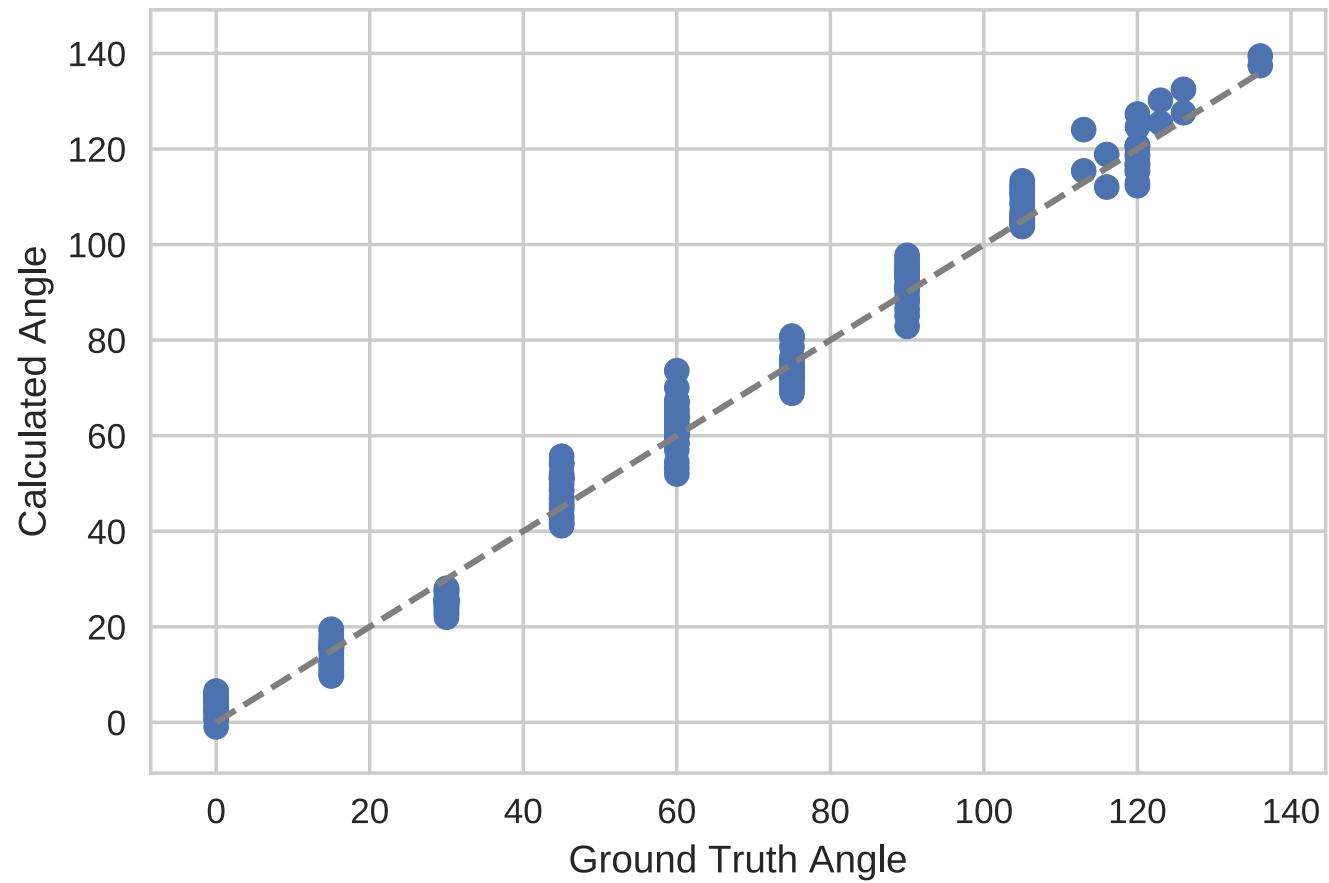


Data Collection

Participant #	Height	CLEF		Maximum Extension		Maximum Flexion	
		Right	Left	Right	Left	Right	Left
1	4'11"	2.5"	2.25"	123°	120°	-1°	0°
2	5'5"	3"	2.75"	147°	145°	0°	0°
3	5'6"	2.75"	2.5"	136°	126°	-2°	-4°
4	5'7"	3"	3.25"	123°	130°	0°	-1°
5	6'0"	3.25"	3.25"	113°	116°	-10°	-8°
6	6'0"	4"	4.25"	139°	137°	0°	0°

Results

- Accuracy: 94.86%
- Average error: 3.69 °



Results

Participant #	Height	Accuracy					Average Error
		15	12.5	10	7.5	5	
1	4'11"	94.44	86.11	80.56	63.89	41.67	3.29°
2	5'5"	94.29	88.57	77.14	60.00	40.00	3.34°
3	5'6"	100.00	80.55	66.67	58.33	50.00	3.35°
4	5'7"	91.67	83.33	72.22	52.78	41.66	3.79°
5	6'0"	94.44	83.33	69.44	47.22	33.33	3.99°
6	6'0"	94.29	82.86	54.29	37.14	25.71	4.42°
Overall		94.86	84.11	70.09	53.27	38.79	3.69°

Conclusion

- We proposed three models that can be used in succession to calculate knee angles given a voltage reading. Given a voltage reading, we first calculate the change in resistance of our conductive fabric, then its change in length, and finally the knee angle.
- We present TrackKnee a sensing knee sleeve made with a conductive fabric sensor that unobtrusively measures knee angles and was created while keeping in mind the comfort of the user. Because of this, we made sure the device was comfortable, unobtrusive, and washable.
- We ran a user study in which we collected data on 240 knee angles from six individuals. We used this data to calculate knee angles using our models.
- Our results show that our model is 94.86% accurate to the nearest 15th degree angle and that our average error per angle is 3.69.