

函数的近似方法

—常用的插值法与基于最小二乘法的拟合法

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Outline

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- 线性插值
- 多项式插值
- 拉格朗日插值

2 拟合法

- 最小二乘法
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- 多项式拟合

3 作业

课件及讨论通过 “新 计算物理” 联系方式来进行交流.

作业也可发到

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上节课的回顾

- Matlab基本特点及简单应用

基于矩阵

help name

- 程序设计的基本特点

程序设计的基本结构：顺序、循环、分支等；

- 如何体现物理特点

如何控制程序，写程序一定要理解公式的物理含义。

1 插值法

- 线性插值
- 多项式插值
- 拉格朗日插值

2 拟合法

3 作业

定义

假设一组观测点和对就的测量值之间的列表如下,

x	x_1	x_2	\cdots	x_n
y	y_1	y_2	\cdots	y_n

假定满足的函数关系为

$$y_i(x) = y(x_i), i = 1, 2, \cdots, n$$

根据这个对应关系寻求 $y(x_i)$ 的一个近似函数关系 $f(x_i)$, 得到的 $f(x)$ 称为插值函数, x_i 称为插值点(或节点)。插值函数在插值点要满足的最基本条件:

- ① 在插值点 x_i ($i = 1, 2, \cdots, n$)上, 要求插值函数 $f(x_i)$ 的值与插值 y_i 相等;
- ② 在插值点一阶导数连续, 甚至二阶导连续;
- ③ 对于 m 次插值多项式, 要求有 $m + 1$ 个插值条件, 以唯一确定 $m + 1$ 个系数。

两点一次插值

在两插值点 $[x_i, y_i]$ 和 $[x_{i+1}, y_{i+1}]$ 用直线连接，在区间 $[x_i, x_{i+1}]$ 内构造的线性插值函数为

$$y = f(x) = ax + b$$

系数可由两个插值点确定

$$f(x_i) = ax_i + b = y_i, \quad f(x_{i+1}) = ax_{i+1} + b = y_{i+1}$$

得插值函数

$$y(x) = \frac{x - x_{i+1}}{x_i - x_{i+1}}y(x_i) + \frac{x - x_i}{x_{i+1} - x_i}y(x_{i+1}), \quad x_i \leq x \leq x_{i+1}$$

$$f(x) = l_i(x)f(x_i) + l_{i+1}(x)f(x_{i+1})$$

上式被称为拉格朗日一次插值多项式。

两点二次插值

对于两个插值点 $[x_i, y_i]$ 和 $[x_{i+1}, y_{i+1}]$,在此区间内构造二次函数 $y = f(x) = ax^2 + bx + c$,系数 a, b, c 的确定方法二个插值点及其左端一阶导数连续为条件, *i.e.*

$$\begin{aligned}f(x_i) &= ax_i^2 + bx_i + c = y_i \\f(x_{i+1}) &= ax_{i+1}^2 + bx_{i+1} + c = y_{i+1} \\f'(x_i) &= y'_i; 2ax_i + b = y'_i\end{aligned}$$

容易得到

$$f(x) = a(x - x_i)^2 + y'_i(x - x_i) + y_i, a = \frac{\Delta y_i - y'_i \Delta x_i}{(\Delta x_i)^2}$$

其中, $\Delta y_i = y_{i+1} - y_i$, $\Delta x_i = x_{i+1} - x_i$.

三点抛物线插值

给定三个插值点 $(x_{i-1}, y(x_{i-1}))$, $(x_i, y(x_i))$, and $(x_{i+1}, y(x_{i+1}))$, 假定过三个节点的三次插值函数为,

$$y(x) = a + bx + cx^2$$

由三个节点可求得 a , b and c , 得三点插值函数

$$y(x) = l_{i-1}(x)y(x_{i-1}) + l_i(x)y(x_i) + l_{i+1}(x)y(x_{i+1})$$

$$x_{i-1} \leq x \leq x_{i+1}$$

$$\begin{aligned} l_{i-1}(x) &= \frac{(x - x_i)(x - x_{i+1})}{(x_{i-1} - x_i)(x_{i-1} - x_{i+1})} \\ l_i(x) &= \frac{(x - x_{i-1})(x - x_{i+1})}{(x_i - x_{i-1})(x_i - x_{i+1})} \\ l_{i+1}(x) &= \frac{(x - x_{i-1})(x - x_i)}{(x_{i+1} - x_{i-1})(x_{i+1} - x_i)} \end{aligned}$$

上式被称为拉格朗日二次插值多项式, 也称为抛物线插值.

$n + 1$ 点 n 次插值

采用逐次线性插值方法可以构造出高次的插值多项式。定义 $y_{i,i+1,\dots,i+m}$ 为通过 $m + 1$ 个节点 (x_i, y_i) , (x_{i+1}, y_{i+1}) 的 m 次插值多项式, 有关系

$$y_{i,i+1,\dots,i+m}(x) = \frac{x - x_{i+m}}{x_i - x_{i+m}} y_{i,i+1,\dots,i+m-1}(x) + \frac{x - x_i}{x_{i+m} - x_i} y_{i+1,i+2,\dots,i+m}(x)$$

或记为

$$y_{i\dots j} = \frac{x - x_j}{x_i - x_j} y_{i\dots j-1} + \frac{x - x_i}{x_j - x_i} y_{i+1\dots j}$$

例如:

$$\begin{aligned} y_{123} &= \frac{x - x_3}{x_1 - x_3} y_{12} + \frac{x - x_1}{x_3 - x_1} y_{23} = \frac{x - x_3}{x_1 - x_3} \left(\frac{x - x_2}{x_1 - x_2} y_1 + \frac{x - x_1}{x_2 - x_1} y_2 \right) \\ &\quad \frac{x - x_1}{x_3 - x_1} \left(\frac{x - x_3}{x_2 - x_3} y_2 + \frac{x - x_2}{x_3 - x_2} y_3 \right) \\ &= \left(\frac{x - x_3}{x_1 - x_3} \frac{x - x_2}{x_1 - x_2} \right) y_1 + \left(\frac{x - x_3}{x_2 - x_3} \frac{x - x_1}{x_2 - x_1} \right) y_2 + \left(\frac{x - x_1}{x_3 - x_1} \frac{x - x_2}{x_3 - x_2} \right) y_3 \end{aligned}$$

为三点插值公式.

5个插值点的逐次线性插值

$$y_{12345} = \frac{x - x_5}{x_1 - x_5} y_{1234} + \frac{x - x_1}{x_5 - x_1} y_{2345}$$

x_1	y_1				
		y_{12}			
x_2	y_2		y_{123}		
		y_{23}		y_{1234}	
x_3	y_3		y_{234}		y_{12345}
		y_{34}		y_{2345}	
x_4	y_4		y_{345}		
		y_{45}			
x_5	y_5				

Lagrange插值多项式

多项式插值:

设已知函数 $f(x)$ 在区间 $[a,b]$ 的 $n+1$ 个点

$$a = x_0 < x_1 < x_2 < \cdots < x_i < \cdots < x_n = b$$

的函数值为

$$y_k = f(x_k), k = 0, 1, 2, \cdots, n$$

采用多项式

$$P(x) = a_0x^n + a_1x^{n-1} + \cdots + a_{n-1}x + a_n$$

a_0, a_1, \cdots, a_n 为待定系数, $p(x)$ 满足条件

$$p(x) = y_0l_0(x) + y_1l_1(x) + \cdots + y_nl_n(x)$$

$l_0(x), l_1(x), \cdots, l_n(x)$ 满足下列条件

$$l_i(x) = \begin{cases} 1 & x = x_j \quad i = j \\ 0 & x = x_j \quad i \neq j \end{cases}$$

Lagrange插值多项式

因此,

$$p(x_i) = y_i, i = 0, 1, \dots, n.$$

$$\frac{w(x_0, x_1, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n)}{w(x_0, x_1, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n)} = \begin{cases} 1 & x = x_j \quad i = j \\ 0 & x = x_j \quad i \neq j \end{cases}$$

Lagrange polynomials are defined as

$$L_i(x) = \frac{(x - x_0) \cdots (x - x_{i-1})(x - x_{i+1}) \cdots (x - x_n)}{(x_i - x_0) \cdots (x_i - x_{i-1})(x_i - x_{i+1}) \cdots (x_i - x_n)}$$

$$p(x) = \sum_{i=0}^n f_i L_i(x) = \sum_{i=0}^n f_i \prod_{k=0, k \neq i}^n \frac{x - x_k}{x_i - x_k}$$

Lagrange插值程序

```
function v=lagrange(x,y,u)
n=length(x);
v=zero(size(u));
for k=1:n
w=ones(size(u));
    for j=[1:k-1 k+1:n]
        w=(u-x(i))./(x(k)-x(j)).*w;
    end
v=v+w*y(k);
end
```

其中， x 为插值点； y 为插值； u 为计算序列点； v 为计算序列点值。

例子：

x	0.0	1.0	2.0	3.0
y	-5.0	-6.0	-1.0	16

样条函数插值(Spline interpolation)

$$p_i(x) = y_i + \frac{y_{i+1} - y_i}{x_{i+1} - x_i}(x - x_i)$$

$$s(x) = p_i(x), x_i \leq x < x_{i+1}$$

The most important case is the cubic spline which is given in the interval $x_i \leq x < x_{i+1}$ by

$$p_i(x) = \alpha_i + \beta_i(x - x_i) + \gamma_i(x - x_i)^2 + \delta_i(x - x_i)^3$$

If we hope to get smooth curve and assume that the interpolating function and their first two derivatives are continuous, we have for the inner boundaries

$$\begin{aligned} p_i(x_{i+1}) &= p_{i+1}(x_{i+1}), \\ p'_i(x_{i+1}) &= p'_{i+1}(x_{i+1}), \\ p''_i(x_{i+1}) &= p''_{i+1}(x_{i+1}). \end{aligned}$$

$$P_i''(x) = a_i x + b, x \in [x_i, x_{i+1}]$$

$$\begin{aligned} a_i x_i + b_i &= P_i''(x) = y_i'' \\ a_i x_{i+1} + b_i &= P_i''(x_{i+1}) = y_{i+1}'' \end{aligned}$$

$$a_i = \frac{y_{i+1}'' - y_i''}{x_{i+1} - x_i}, \quad b_i = \frac{x_{i+1} y_i'' - x_i y_{i+1}''}{x_{i+1} - x_i}$$

where y_i'' and y_{i+1}'' are unknown. But we can use

$$\begin{aligned} S_i'(x) &= \frac{1}{2} a_i x^2 + b_i x + c_i \\ S_i(x) &= \frac{1}{6} a_i x^3 + \frac{1}{2} b_i x^2 + c_i x + d_i \end{aligned}$$

The coefficient c_i and d_i

$$c_i = \frac{1}{6(x_{i+1} - x_i)} [(x_i^2 - 2x_{i+1}^2 - 2x_i x_{i+1})y_i'' + (2x_i^2 - x_{i+1}^2 + 2x_i x_{i+1})y_{i+1}'' + 6(y_{i+1} - y_i)]$$

$$d_i = \frac{1}{6(x_{i+1} - x_i)} [(x_i x_{i+1}(-2x_{i+1} + x_i)y_i'' + x_i x_{i+1}(2x_i - x_{i+1})y_{i+1}'' + 6(x_i y_{i+1} - x_{i+1} y_i)]$$

There exists n unknown parameters $y_i'' (i = 1, 2, \dots, n)$ in $\{S_i(x), i = 1, 2, \dots, n-1\}$. 根据一阶导数的连续性有关系,

$$S'_{i-1}(x_i) = S'_i(x_i)$$

i.e.

$$\frac{1}{2}a_{i-1}x_i^2 + b_{i-1}x_i + c_{i-1} = \frac{1}{2}a_i x_i^2 + b_i x_i + c_i$$

三对角矩阵

把含有未知量 $y_i'' (i = 1, 2, \dots, n)$ 的系数 $a_i, b_i, c_i, a_{i-1}, c_{i-1}$ 代入上式, 得

$$\alpha_{i-1} y_{i-1}'' + \beta_i y_i'' + \gamma_i y_{i+1}'' = f_i$$

$$\alpha_{i-1} = x_i - x_{i-1}, \beta_i = 2(x_{i+1} - x_{i-1}), \gamma_i = x_{i+1} - x_i$$

$$f_i = 6\left(\frac{y_{i+1} - y_i}{\gamma_i} - \frac{y_i - y_{i-1}}{\alpha_{i-1}}\right), i = 2, \dots, n-1$$

是一个系数为三对角矩阵的代数方程。

$$\begin{pmatrix} b_1 & c_1 & & & \\ a_2 & b_2 & c_2 & & \\ & \ddots & \ddots & \ddots & \\ & & a_{n-1} & b_{n-1} & c_{n-1} \\ & & & a_n & b_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_{n-1} \\ f_n \end{pmatrix}$$

再结合两个条件以决定 n 个未知量 y_i'' ($i = 1, 2, \dots, n$), 通常采用

- ① 根据两端点的一阶导数, 获得 y'' 联立三对角矩阵构建线性代数方程组;
- ② 设两端点的二阶导数为0。

利用三次样条插值。可求出差值曲线的一阶和二阶导数插值函数。

Examples:

对于函数 $y = \frac{1}{1+x^2}$ 在区间 $[-1, 1]$ 求出三次样条插值函数。

1 插值法

2 拟合法

- 最小二乘法
- 线性拟合
- 多项式拟合

3 作业

The definition of fitting method

Fitting functions to data points, Most commonly, one fits a function of the form

$$y = f(x)$$

特点:

- ① 拟合函数不必通过所有已知点 (x_i, y_i) , 拟合的曲线能反映给定数据的整体趋势, 并使拟合数据与已知节点的误差最小;
- ② 拟合方法给出了一组分立数据的整体性质;
- ③ 函数通常可以反映一定的物理含义;

For instance, fitting lines and polynomial functions to data points

$$p(x) = p_m(x) = \sum_{j=1}^{m+1} a_j x^{j-1}, m < n$$

The least squares fitting is often used, namely

$$q(a_1, a_2, \dots, a_{m+1}) = \sum_{i=1}^n [p(x_i) - y_i]^2$$

For the given data (x_i, y_i) ($i = 1, 2, \dots, n$), they satisfy the following equation,

$$p(x) = a + bx$$

According to the least squares method, how to find the fitting parameters a and b make the all data points above satisfy the following equation

$$q(a, b) = \sum_{i=1}^n [(a + bx_i) - y_i]^2$$

and $q(a, b)$ have local minimum.

为使 $q(a, b)$ 极小, a, b 必须满足下列方程组:

$$\begin{cases} \frac{\partial q}{\partial a} = 2 \sum_{i=1}^n [(a + bx_i) - y_i] = 0 \\ \frac{\partial q}{\partial b} = 2 \sum_{i=1}^n [(a + bx_i) - y_i] x_i = 0 \end{cases}$$

we can get

$$\begin{cases} a = \frac{n \sum y_i - \sum x_i^2 - \sum x_i \sum x_i y_i}{n \sum x_i^2 - (\sum x_i)^2} \\ b = \frac{n \sum x_i y_i - \sum x_i \sum y_i}{n \sum x_i^2 - (\sum x_i)^2} \end{cases}$$

The code for matlab

linearfit.m

```
function [a b]=linearfit (x,y)
```

```
n=length(x);
```

```
x2=x.*x; xy=x.*y;
```

```
sx=sum(x); sy=sum(y);
```

```
sxy=sum(xy); sx2=sum(x2);
```

```
deno=n*sx2-sx*sx;
```

```
a=(sy*sx2-sx*sxy)/deno;
```

```
b=(n*sxy-sx*sy)/deno;
```

```
end
```


Polynomial fitting

For m-order polynomial fitting,

$$p_m(x) = \sum_{j=1}^{m+1} a_j x^{j-1}, m < n$$

then the sum of squares for Error

$$Q(a_1, a_2, \dots, a_{m+1}) = \sum_{i=1}^n \left(\sum_{j=1}^{m+1} a_j x_i^{j-1} - y_i \right)^2$$

Partial derivatives

$$\frac{\partial Q}{\partial a_k} = 2 \sum_{i=1}^n \left(\sum_{j=1}^{m+1} a_j x_i^{j-1} - y_i \right) x_i^{k-1} = 0,$$

$k = 1, 2, \dots, m+1$; or

$$\sum_{i=1}^n y_i x_i^{k-1} = \sum_{j=1}^{m+1} a_j \sum_{i=1}^n x_i^{j+k-2}$$

we define

$$S_k = \sum_{i=1}^n x_i^{k-1}, \quad T_k = \sum_{i=1}^n y_i x_i^{k-1}$$

$$\sum_{j=1}^{m+1} a_j S_{j+k-1} = T_k, \quad k = 1, 2, \dots, m+1$$

Code for the matlab

```
multifit.m
function a=multifit(x,y,m)
n=length(x);
c(1:(2*m+1))=0; T(1:(m+1))=0;
for j=1:(2*m+1)
for k=1:n
c(j)=c(j)+x(k)(j-1)
if (j < (m+2))
T(j)=T(j)+y(k)*x(k)(j-1);
end; end; end
S(1,:)=c(1: (m+1));
for k=2:(m+1)
S(k,:)=c(k:(m+k));
end
a=S / T';
```

1 插值法

2 拟合法

3 作业

作业

1. 利用二次插值计算(1) $f(0.472)$; (2) $f(x)=0.5$, $x=?$, 所依据的数据表为

x	0.46	0.47	0.48	0.49	...
$f(x)$	0.4846555	0.4937452	0.5027498	0.5116683	...

2. 区间 $[0,2]$ 上的三次样条插值函数

$$s(x) = \begin{cases} 2x^3 & 0 \leq x \leq 1 \\ x^3 + ax^2 + bx + c & 1 \leq x \leq 2 \end{cases}$$

求 a , b , c .

3. 已知函数数据表

x_i	1	2	3	4	6	7	8
y_i	2	3	6	7	5	3	2

试用最小二乘法拟合二次多项式.

建议大家熟悉下列matlab中关于插值和拟合的函数命令：

- ① `interp1(x0,y0,x,'method')`;可实现一维情况下的x的插值y,方法有线性, 三次样条等; `interp2`, `interp3`, `meshgrid`, etc.
- ② `P=polyfit(x0,y0,n)`, 通过基于最小二乘法的方法, 可找拟合 (x_0,y_0) 的n次多项式的系数; `[P,S]=polyfit(x0,y0,N)`: returns the polynomial coefficients P and a structure S for use with `POLYVAL` to obtain error estimates for predictions.
- ③ 另了解`lsqcurvefit`, `fminunc`, `nlinfit`函数的使用。