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*****
;Program Name:  "magic.asm"
;Description:
;
;Author:      Jacob Watts & Jack Fernald
;Organization: Weber State University ECE 3710
;Revision History
;Date[YYYYMMDD] Author      Description
;-----
;20230221      Jacob W.      initial commit
*****
$include (c8051f020.inc)
;-----
;----- Registry -----
;R0 - clr RAM but only in the beginning
;R1 - Counter for 10
;R2 -
;R3 -
;R4 -
;R5 -
;R6 -
;R7 -
;----- DSEG -----
        DSEG AT 30H
current_button: ds 1
last_button:   ds 1
led_position:  ds 1
rand_int:     ds 1
;----- CSEG -----
;----- Crystal Setup Code -----
mov wdtcn,#0DEh ; disable watchdog
mov wdtcn,#0ADh
mov xbr2,#40h ; enable port output
mov xbr0,#04h ; enable uart 0
mov oscxcn,#67H ; turn on external crystal
mov tmod,#21H ; wait 1ms using T1 mode 2
mov th1,#256-167 ; 2MHz clock, 167 counts = 1ms
setb tr1

wait1:  jnb tfl,wait1
        clr tr1 ; 1ms has elapsed, stop timer
        clr tfl

wait2:  mov a,oscxcn ; now wait for crystal to stabilize
        jnb acc.7,wait2
        mov oscicn,#8 ; engage! Now using 22.1184MHz

        mov scon0,#50H ; 8-bit, variable baud, receive enable
        mov th1,#-6 ; 9600 baud
        setb tr1 ; start baud clock

        ;clear all internal ram
        mov r0,#255
clrall: mov @r0,#0
        djnz r0,clrall
;-----PLACE CODE BELOW THIS LINE-----

;----- Initialization Code -----
init:
        mov A, #0FFh
        mov P3, A
        mov P5, A
        RI1 bit 0C0h ;turn on flag for serial send
        mov R1, #10

;----- Main Code -----
main:
        call delay 10ms
        call check_buttons
        mov A, current_button
        cjne A, last_button, cont
        jmp serial_check

cont:   cjne A, #001h, serial_check ;if button pressed jmp
        jmp tx_sub

; ----- This is where we check for
serial_check:
        jnb ri, main ;jump to main if ri not set
        clr ri
        jmp tx_sub

;----- tx -----
tx_sub:
        call update_disp
        call get_address

        setb TR1
        clr A
        movc A, @A+DPTR
        jz main
        call sendcom
        inc DPTR
        sjmp fn

sendcom:
        mov sbuf0,a
herel:  jnb TI, herel
        clr TI
        ret

;----- LED Display -----
update_disp:
        mov led_position, rand_int
        mov A, led_position
update_p3_0:
        cjne A, #0Ah, update_p3_1
        mov A, #02h
        mov P3, A
        mov A, #0FFh
        mov P5, A
        ret

update_p3_1:
        cjne A, #01h, update_p5
        mov A, #01h
        mov P3, A
        mov A, #0FFh
        mov P5, A
        ret

update_p5:
        mov dptr, #led_table
        movc A, @A+dptr
        mov P5, A
        mov A, #0FFh
        mov P3, A

        ret

;----- get string addr -----
get_address:
        mov A, rand_int
        r1 A
        mov B, A
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    mov dptr, #msg_idx
    movc A, @a+dptr ;msb of address
    xch a,b
    inc a
    movc a,@a+dptr
    mov dpl, a
    mov dph, b
    clr a
    clr c

    ret

;----- message table -----
msg_1: DB "It is certain", 0Dh, 0Ah, 0
msg_2: DB "You may rely on it", 0Dh, 0Ah, 0
msg_3: DB "Without a doubt", 0Dh, 0Ah, 0
msg_4: DB "Yes", 0Dh, 0Ah, 0
msg_5: DB "Most likely", 0Dh, 0Ah, 0
msg_6: DB "Reply hazy, try again", 0Dh, 0Ah, 0
msg_7: DB "Concentrate and ask again", 0Dh, 0Ah, 0
msg_8: DB "Don't count on it", 0Dh, 0Ah, 0
msg_9: DB "Very doubtful", 0Dh, 0Ah, 0
msg_10: DB "My reply is no", 0Dh, 0Ah, 0

;----- msg_idx table -----
msg_idx: DW msg_1, msg_2, msg_3, msg_4, msg_5, msg_6, msg_7, msg_8, msg_9, msg_10

;----- LED table -----
led_table: DB 0FFh, 0FFh, 0FEh, 0FDh, 0FBh, 0F7h, 0EFh, 0DFh, 0BFh, 07Fh

;----- Check Buttons -----
check_buttons: MOV A, P1
               MOV last_button, current_button ; Memory for next loop
               CPL A ; Complement A
               ANL A, #001h ; Mask out other bits from P1, we only care about the single button bit. Anding it with 1 will keep the state of the button
               ; e.g. button = 1 and with 1 = 1, button = 0 and with 1 = 0. T
               MOV current_button, A ; Move this newly found button state into current_button
               RET

;----- 10ms Delay -----
delay_10ms:
    djnz R1,here
    mov R1,#10

here:    mov TL0, #000h ; -9216 for 5ms
         mov TH0, #0DCh
         setb TR0 ; start timer
again:   jnb TF0, again
         clr TR0
         clr TF0

         mov A, R1
         mov rand_int, A
         clr A; for good measure
         clr C; for good measure
         ret

END
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