

Product Specification

NHD-C160100DiZ-FSW-FBW

COG (Chip-On-Glass) Liquid Crystal Display Module

NHD- Newhaven Display

C160100- 160 x 100 Pixels

DiZ- Model

F- Transflective

SW- Side white LED Backlight

F- FSTN (+)

B- 6:00 Optimal View

W- Wide Temperature







Table of Contents

ocument Revision History	2
lechanical Drawing	
n Descriptionn	
/iring Diagram	
ectrical Characteristics	
ptical Characteristics	
· ontroller Information	
able of Commands	
ming Characteristics	9
cample Initialization Program	
uality Informationuality Information	14

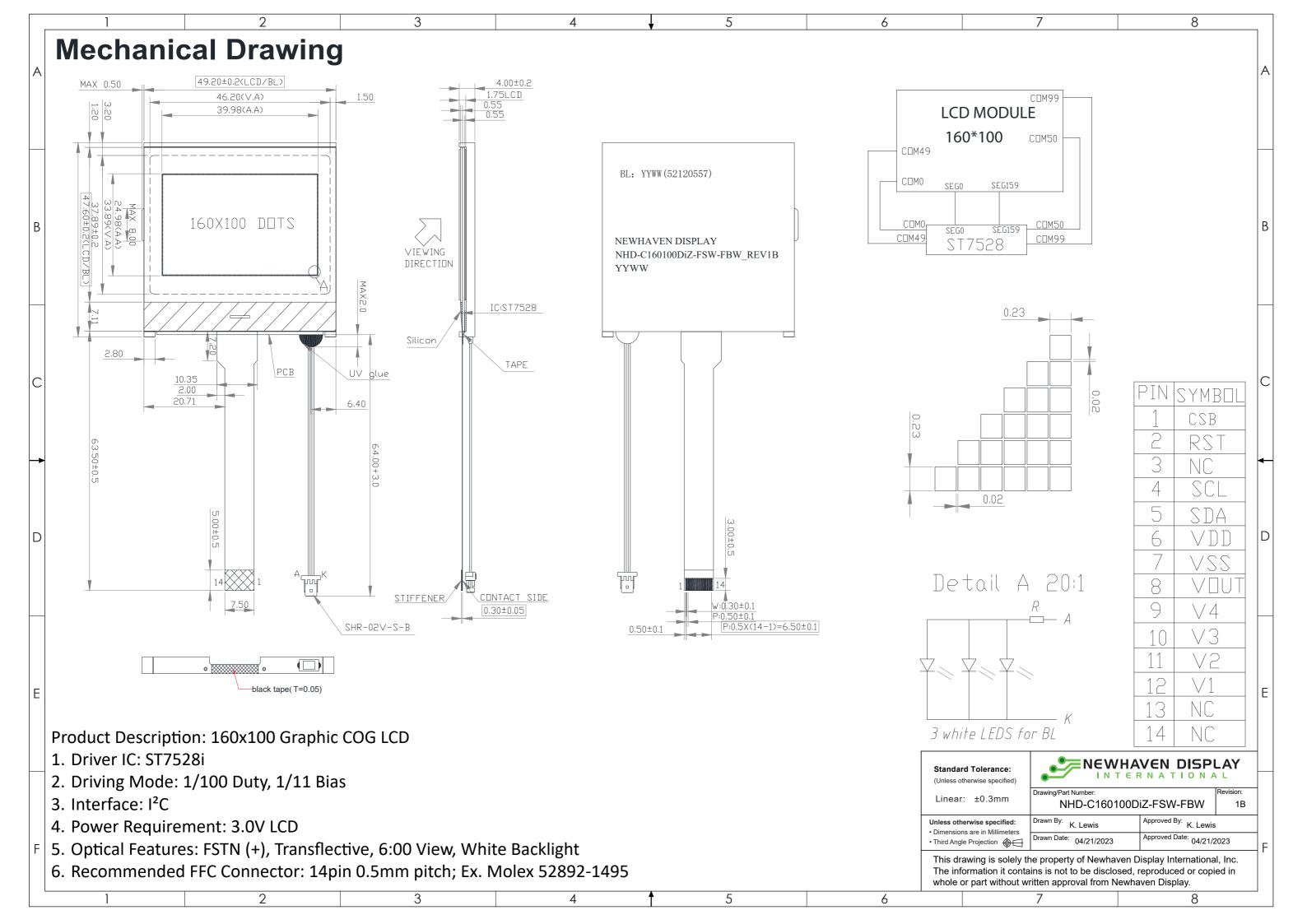
Additional Resources

- > Support Forum: https://support.newhavendisplay.com/hc/en-us/community/topics
- ➤ **GitHub:** https://github.com/newhavendisplay
- **Example Code:** https://support.newhavendisplay.com/hc/en-us/categories/4409527834135-Example-Code/
- **Knowledge Center:** https://www.newhavendisplay.com/knowledge center.html
- ➤ Quality Center: https://www.newhavendisplay.com/quality center.html
- Precautions for using LCDs/LCMs: https://www.newhavendisplay.com/specs/precautions.pdf
- ➤ Warranty / Terms & Conditions: https://www.newhavendisplay.com/terms.html



Document Revision History

Revision	Date	Description	Changed By
0	01/06/2008	Initial Release	-
1	09/18/2009	User Guide Reformat	BE
2	10/14/2009	Updated Electrical Characteristic	MC
3	11/09/2009	Slave Address Updated	BE
4	11/17/2009	Slave Address Updated	MC
5	11/20/2009	Updated Backlight Supply Current Max / Updated Table of Commands	MC
6	12/14/2010	Updated Backlight Cable Length	CL
7	08/25/2016	Mechanical Drawing, Electrical & Optical Char. Updated	SB
8	03/24/2017	Mechanical Drawing Updated	SB
9	05/25/2017	Electrical Characteristics Updated	TM
10	05/10/2018	Module Redesign	SB
11	09/11/2019	Backlight Characteristics and Supply Current Updated	SB
12	04/15/2020	Supply Voltage Updated	SB
13	04/21/2023	Date Code Format Updated on Mechanical Drawing	KL





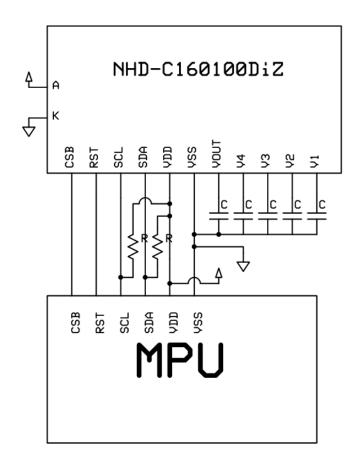
Pin Description

Pin No.	Symbol	External Connection	Function Description
1	CSB	MPU	Active Low Chip Select
2	RST	MPU	Active Low Reset signal
3	NC	-	No Connect
4	SCL	MPU	Serial Clock input (requires pull-up)
5	SDA	MPU	Serial Data input (requires pull-up)
6	V_{DD}	Power Supply	Supply Voltage for LCD and logic (+3.0V)
7	V_{SS}	Power Supply	Ground
8	V_{OUT}	Power Supply	Connect to 1uF cap to V _{SS} or V _{DD}
9	V_4	Power Supply	1.0uF-2.2uF cap to V _{SS}
10	V_3	Power Supply	1.0uF-2.2uF cap to V _{SS}
11	V_2	Power Supply	1.0uF-2.2uF cap to V _{SS}
12	V_1	Power Supply	1.0uF-2.2uF cap to V _{SS}
13	NC	-	No Connect
14	NC	-	No Connect

Recommended LCD connector: 0.5mm pitch pins. Molex p/n: 52892-1495

Backlight connector: SHR-02V-S-B **Mates with**: SM02B-SRSS-TB

Wiring Diagram





Electrical Characteristics

Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Operating Temperature Range	T _{OP}	Absolute Max	-20	-	+70	°C
Storage Temperature Range	T _{ST}	Absolute Max	-40	-	+80	°C
Supply Voltage	V_{DD}	-	2.4	3.0	3.6	V
Supply Current	I _{DD}	V _{DD} =3.0V	0.32	0.75	1.5	mA
Supply for LCD (contrast)	V_{LCD}	T _{OP} =25°C	11.2	11.5	11.8	V
"H" Level input	V _{IH}	-	2.2	-	V_{DD}	٧
"L" Level input	VIL	-	V_{SS}	-	0.6	V
"H" Level output	V _{OH}	-	2.4	-	V_{DD}	٧
"L" Level output	Vol	-	V_{SS}	-	0.4	V
Backlight Supply Voltage	V_{LED}	-	2.8	3.0	3.2	٧
Backlight Supply current	I _{LED}	V _{LED} = 3.0V	30	50	70	mA

Optical Characteristics

	Ite	em	Symbol	Condition	Min.	Тур.	Max.	Unit
Outing al	Тор		φΥ+		-	15	-	0
Optimal	Bot	tom	φΥ-	CD > 2	-	40	-	0
Viewing	Left		θХ-	CR ≥ 2	-	30	-	0
Angles	Righ	nt	θХ+		-	30	-	0
Contrast Rat	io		CR	-	2	10	-	-
Dosmonso T	ina a	Rise	T _R	T - 25°C	-	50	200	ms
Response T	ime	Fall	T _F	$T_{OP} = 25^{\circ}C$	-	300	350	ms

Controller Information

Built-in ST7528i Controller at: https://support.newhavendisplay.com/hc/en-us/articles/4414862822295--ST7528

I²C Interface:

I2C interface requires 2 lines, Serial Data and Serial Clock. Both lines must be connected to the positive supply via a pull-up resistor. Data transfer may be initiated only when the bus is not busy.

Bit transfer:

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse, changes in the data line at this time will be interpreted as a control signal.

Start and Stop conditions:

Both data and clock lines remain HIGH when the bus is not busy. A HIGH-to-LOW transition of the data line while the clock is HIGH is define as the START condition. A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition.

Acknowledge:

Each byte of eight bits is followed by an acknowledge bit. The ACK bit is a HIGH signal put on the bus by the transmitter, during which time the master generates an extra ACK related clock pulse. The LCD generates an ACK after the reception of each byte. The LCD will pull-down the SDA line during the ACK clock pulse, so that the SDA line is stable LOW during the HIGH period of the ACK clock pulse.

Slave Address = 0x3F



Table of Commands

Instruction	Α0	RW	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Description
EXT=0 or 1								•			
	0	0	0	0	1	1	1	0	0	0	2-byte instruction to set
Mode Set	0	0	FR3	FR2	FR1	FR0	0	BE	x'	EXT	FR(Frame frequency control) BE(Booster efficiency control)
EXT=0								•			
Read display data	1	1				Read	data				Read data into DDRAM
Write display data	1	0				Write	data				Write data into DDRAM
Read status	0	1	BUSY	ON	RES	MF2	MF1	MF0	DS1	DS0	Read the internal status
ICON control register ON/OFF	0	0	1	0	1	0	0	0	1	ICON	ICON=0: ICON disable(default) ICON=1: ICON enable & set the page address to 16
Set page address	0	0	1	0	1	1	P3	P2	P1	P0	Set page address
Set column address MSB	0	0	0	0	0	1	Y9	Y8	Y7	Y6	Set column address MSB
Set column address LSB	0	0	0	0	0	0	Y5	Y4	Y3	Y2	Set column address LSB
Set modify-read	0	0	1	1	1	0	0	0	0	0	Set modify-read mode
Reset modify-read	0	0	1	1	1	0	1	1	1	0	release modify-read mode
Display ON/OFF	0	0	1	0	1	0	1	1	1	D	D=0: Display OFF D=1: Display ON
Set initial display line register	0	0	0	1	0	0	0	0	x'	x'	2-byte instruction to specify the initial display line to realize
octimizations of the state of t	0	0	x'	S6	S5	S4	S3	S2	S1	S0	vertical scrolling
Set initial COM0 register	0	0	0	1	0	0	0	1	x'	x'	2-byte instruction to specify the initial COM0 to realize
octimizar octivo register	0	0	x'	C6	C5	C4	С3	C2	C1	C0	window scrolling
Sat partial display duty ration	0	0	0	1	0	0	1	0	x'	x'	2-byte instruction to set partial
Set partial display duty ration	0	0	D7	D6	D5	D4	D3	D2	D1	D0	display duty ratio
	0	0	0	1	0	0	1	1	x'	x'	2-byte instruction to set N-line
Set N-line inversion	0	0	x'	x'	x'	N4	N3	N2	N1	N0	inversion register
Release N-line inversion	0	0	1	1	1	0	0	1	0	0	Release N-line inversion mode
Reverse display ON/OFF	0	0	1	0	1	0	0	1	1	REV	REV=0: normal display REV=1: reverse display
Entire display ON/OFF	0	0	1	0	1	0	0	1	0	EON	EON=0: normal display EON=1: entire display ON



ST7528

Instruction	A0	RW	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Description
Ext=0											
Power control	0	0	0	0	1	0	1	VC	VR	VF	Control power circuit operation
Select DC-DC step-up	0	0	0	1	1	0	0	1	DC1	DC0	Select the step-up of internal voltage converter
Select regulator register	0	0	0	0	1	0	0	R2	R1	R0	Select the internal resistance ratio of the regulator resistor
Select electronic volumn	0	0	1	0	0	0	0	0	0	1	2-byte instruction to specify
register	0	0	x'	x'	EV5	EV4	EV3	EV2	EV1	EV0	the reference voltage
Select LCD bias	0	0	0	1	0	1	0	B2	B1	В0	Select LCD bias
Bias Power Save	0	0	1	1	1	1	0	0	1	1	Bias Power save Save the Bias
bias Fower Save	0	0	0	0	0	0	0	0	0	0	current consumption
SHL select	0	0	1	1	0	0	SHL	x'	x'	x'	COM bi-directional selection SHL=0: normal direction SHL=1: reverse direction
ADC select	0	0	1	0	1	0	0	0	0	ADC	SEG bi-direction selection ADC=0: normal direction ADC=1: reverse direction
Oscillator on start	0	0	1	0	1	0	1	0	1	1	Start the built-in oscillator
Set power save mode	0	0	1	0	1	0	1	0	0	Р	P=0: normal mode P=1: sleep mode
Release power save mode	0	0	1	1	1	0	0	0	0	1	release power save mode
Reset	0	0	1	1	1	0	0	0	1	0	initial the internal function
Set data direction &	×	x'	1	1	1	0	1	0	0	0	2-byte instruction to specify
display data length(DDL)	x	x'	D7	D6	D5	D4	D3	D2	D1	D0	the number of data bytes. (SPI mode)
Select FRC and PWM mode	0	0	1	0	0	1	0	FRC	PWM1	PWM0	FRC(1:3FRC, 0:4FRC) PWM1 PWM0 0 0 45PWM 0 1 45 PWM 1 0 60PWM 1 1
NOP	0	0	1	1	1	0	0	0	1	1	No operation
Test Instruction	0	0	1	1	1	1	x'	x'	x'	x'	Don't use this instruction



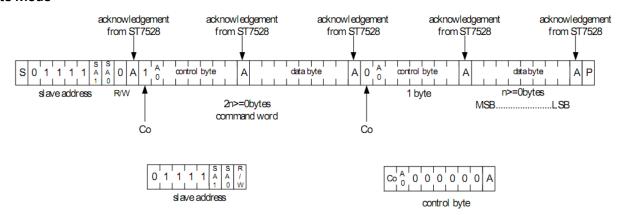
ST7528

ST7528										
A 0	RW	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0	Description
0	0	1	0	0	0	0	0	0	0	Set white mode and 1st frame
0	0	X'	X'	GA05	GA04	GA03	GA02	GA01	GA00	Get writte filode and 1st frame
0	0	1	0	0	0	0	0	0	1	Set white mode and 2nd
0	0	X'	X'	GA05	GA04	GA03	GA02	GA01	GA00	frame
0	0	1	0	0	0	0	0	1	0	Set white mode and 3rd
0	0	X'	X'	GA05	GA04	GA03	GA02	GA01	GA00	frame
0	0	1	0	0	0	0	0	1	1	Set white mode and 4th
0	0	X'	X'	GA05	GA04	GA03	GA02	GA01	GA00	frame
0	0			84	ŀH~87⊦	1 (4 b	ytes)			Set gray level1
0	0			88	8H∼8BI	H (4 b	ytes)			Set gray level2
0	0			80	CH~8F	H (4b)	ytes)			Set gray level3
0	0			90)H~93I	H (4b)	/tes)			Set gray level4
0	0			94	4H~97l	H (4b)	/tes)			Set gray level5
0	0			98	8H∼9BI	H (4 b	ytes)			Set gray level6
0	0			A)H~A3I	H (4 b	ytes)			Set gray level8
0	0			A	₽H~A7I	H (4 b	ytes)			Set gray level9
0	0			A8	3H∼ABI	H (4 b	ytes)			Set gray level10
0	0			AC	CH~AF	H (4 b	ytes)			Set gray level11
0	0			В)H~B3I	Ч (4 b	ytes)			Set gray level12
0	0			B4	IH∼B7I	H (4 b	ytes)			Set gray level13
0	0			B8	3H∼BBI	H (4 b	ytes)			Set gray level14
0	0	1	0	1	1	1	1	0	0	Set Dark mode and 1st
0	0	X'	X'	GAF5	GAF4	GAF3	GAF2	GAF1	GAF0	frame, set pulse width
0	0	1	0	1	1	1	1	0	1	Set Dark mode and 2nd
0	0	X'	X'	GAF5	GAF4	GAF3	GAF2	GAF1	GAF0	frame, set pulse width
0	0	1	0	1	1	1	1	1	0	Set Dark mode and 3rd
0	0	X'	X'	GAF5	GAF4	GAF3	GAF2	GAF1	GAF0	frame, set pulse width
0	0	1	0	1	1	1	1	1	1	Set Dark mode and 4th
0	0	X'	X'	GAF5	GAF4	GAF3	GAF2	GAF1	GAF0	frame, set pulse width
		O	0 0 1 0 0 X' 0 1 0 0 X' 0 0 1 0 0 X' 0 0 1	0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 0 1 0 0 <	0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0

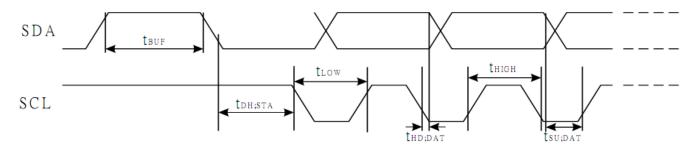


Timing Characteristics

Write Mode



Со	0	Last control byte to be sent. Only a stream of data bytes is allowed to follow. This stream may only be terminated by s STOP or RE-START condition.
	1	Another control byte will follow the data byte unless a STOP or RE-START condition is received.



(V_{DD}=3.3V,Ta=25°C)

Item	Signal	Symbol	Condition	Ra	ting	Units
item	Signal	Symbol	Condition	Min.	Max.	Units
SCL clock frequency	SCL	FSCLK		-	400	kHZ
SCL clock low period	SCL	TLOW		1.3	-	us
SCL clock high period	SCL	THIGH		0.6	-	us
Data set-up time	SI	TSU;Data		100	-	ns
Data hold time	SI	THD;Data		0	0.9	us
SCL,SDA rise time	SCL	TR		20+0.1Cb	300	ns
SCL,SDA fall time	SCL	TF		20+0.1Cb	300	ns
Capacitive load represented by each bus line		Cb		-	400	pF
Setup time for a repeated START condition	SI	TSU;SUA		0.6	-	us
Start condition hold time	SI	THD;STA		0.6	-	us
Setup time for STOP ondition		TSU;STO		0.6	-	us
Tolerable spike width on bus		TSW		-	50	ns
BUS free time between a STOP and StART condition	SCL	TBUF		1.3		us



Example Initialization Program

I2C_Stop();

Slave Address = 0x3F

```
const char Slave = 0x7E;
                                                                            //slave
address+Write bit
const char Comsend = 0x00;
const char Datasend = 0x40;
/****************
                                      //I2C Output
void I2C out(unsigned char j)
{
     int n;
     unsigned char d;
     d=j;
     for (n=0; n<8; n++) {
                                              //send 8 bits
           if((d&0x80) == 0x80)
                                              //get only the MSB
                                                   //if 1, then SDA=1
           SDA=1;
           else
           SDA=0;
                                                   //if 0, then SDA=0
           d = (d << 1);
                                                   //shift data byte left
           SCL = 0;
           SCL = 1;
                                                   //clock in data
           SCL = 0;
     SCL = 1;
     while(SDA==1){
                                                   //wait here until ACK
           SCL=0;
           SCL=1;
     SCL=0;
}
/*********************
void I2C_Start(void)
{
     SCL=1;
     SDA=1;
     SDA=0;
     SCL=0;
}
/***********************************
void I2C Stop(void)
{
     SDA=0;
     SCL=0;
     SCL=1;
     SDA=1;
}
/****************
void Show(unsigned char *text)
     int n,i;
     char page=0xB0;
                                        //first page
                                 //100 pixels = 12.5 pages
     for(i=0;i<13;i++){
           I2C Start();
           I2C out(Slave);
           I2C out(Comsend);
           I2C out(page);
           I2C_out(0x10);
                                        //column address Y9:Y6
                                       //column address Y5:Y2
           I2C_out(0x01);
```

I2C out (0x0B);

```
I2C_Start();
             I2C_out(Slave);
             I2C_out(Datasend);
             for (n=0; n<160; n++) {
                   I2C_out(*text);
                                              //send data 4 times for grayscaling
                    I2C_out(*text);
                    I2C_out(*text);
                    I2C out(*text);
                                                      //point to next byte of data
                    ++text;
                    delay(10);
             I2C_Stop();
             page++;
                                                  //move to next page
}
/**************
     Initialization
void init_LCD()
I2C Start();
I2C out(Slave);
I2C out(Comsend);
I2C out(0x48);
                         //partial display duty ratio
I2C out (0x64);
                         // 1/100 duty
                          //ADC select
I2C_out(0xA0);
                         //SHL select
I2C_out(0xC8);
I2C_out(0x44);
                         //initial Com0 register
I2C_out(0x00);
                          //scan from Com0
I2C_out(0xAB);
                          //OSC on
I2C_out(0x26);
I2C_out(0x81);
                          //set electronic volume
I2C_out(0x15);
                          //vopcode=0x1C
I2C out (0x56);
                          //set 1/11 bias
I2C out (0x64);
                           //3x
delay(2);
                          //
I2C out (0x2C);
I2C out(0x66);
                           //5x
delay(2);
                           //
I2C out (0x2E);
delay(2);
I2C_out(0x2F);
                          //power control
I2C_out(0xF3);
                          //bias save circuit
I2C_out(0x00);
I2C_out(0x96);
                          //frc and pwm
I2C_out(0x38);
I2C_out(0x75);
I2C_out(0x97);
                          //external mode
                          //
                          //3frc, 45 pwm
I2C out(0x80);
                          //start 16-level grayscale settings
I2C out (0x00);
                          //
I2C out (0x81);
                          //
I2C out(0x00);
                          //
I2C out(0x82);
                          //
I2C out (0x00);
                          //
I2C out(0x83);
                           //
                           //
I2C_out(0x00);
I2C_out(0x84);
                           //
I2C_out(0x06);
                           //
I2C_out(0x85);
                           //
I2C_out(0x06);
I2C_out(0x86);
I2C_out(0x06);
                           //
                           //
                           //
I2C out(0x87);
                           //
I2C out(0x06);
                           //
I2C out(0x88);
                           //
I2C_out(0x0B);
                           //
I2C out(0x89);
```

```
I2C_out(0x8A);
I2C_{out(0x0B)};
                                //
I2C_out(0x8B);
                                //
I2C_out(0x0B);
I2C_out(0x8C);
I2C_out(0x10);
                                //
                                //
I2C_out(0x8D);
                                //
I2C out(0x10);
I2C out (0x8E);
I2C out (0x10);
I2C out (0x8F);
                                //
I2C_out(0x10);
                                //
I2C_out(0x90);
I2C_out(0x15);
                                //
I2C_out(0x91);
                                //
                                //
I2C_out(0x15);
I2C_{out}(0x92);
I2C_out(0x15);
I2C_out(0x93);
I2C_out(0x15);
                                //
I2C_out(0x94);
                                //
I2C_out(0x1A);
                                //
I2C out (0x95);
I2C out (0x1A);
I2C out(0x96);
                                //
I2C out (0x1A);
                                //
I2C_{out}(0x97);
                                //
I2C_out(0x1A);
                                //
I2C_out(0x98);
I2C_out(0x1E);
                                //
I2C_out(0x99);
                                //
I2C_out(0x1E);
I2C_out(0x9A);
                                //
                                //
12C_out(0x1E);
                                //
12C_out(0x9B);
                                //
I2C out(0x1E);
                                //
I2C out(0x9C);
                                //
I2C out (0x23);
I2C out (0x9D);
I2C out(0x23);
                                //
I2C out (0x9E);
I2C_out(0x23);
                                //
                                //
I2C_{out}(0x9F);
I2C_out(0x23);
                                //
I2C_out(0xA0);
                                //
                                //
I2C_{out}(0x27);
I2C_out(0xA1);
I2C_out(0x27);
I2C_out(0xA2);
I2C_out(0x27);
                                //
I2C out(0xA3);
                                //
I2C out (0x27);
                                //
I2C out (0xA4);
I2C out (0x2B);
I2C out (0xA5);
I2C out (0x2B);
                                //
I2C_out(0xA6);
                                //
I2C_{out(0x2B)};
                                //
I2C_out(0xA7);
                                //
                                //
I2C_out(0x2B);
I2C_out(0xA8);
                                //
I2C_out(0x2F);
I2C_out(0xA9);
                                //
12C_out(0x2F);
                                //
I2C out(0xAA);
                                //
I2C out (0x2F);
                                //
I2C out(0xAB);
I2C out (0x2F);
I2C_out(0xAC);
```



```
I2C_out(0x32);
I2C_out(0xAD);
                               //
I2C_out(0x32);
I2C_out(0xAE);
I2C_out(0x32);
I2C_out(0xAF);
                               //
                               //
                               //
                               //
I2C_out(0x32);
                               //
I2C out(0xB0);
                               //
I2C out (0x35);
I2C out(0xB1);
                               //
I2C out (0x35);
                               //
I2C_out(0xB2);
                               //
I2C_out(0x35);
I2C_out(0xB3);
                               //
                               //
I2C_out(0x35);
12C_out(0xB4);
                               //
I2C_out(0x38);
I2C_out(0x85);
I2C_out(0x38);
I2C_out(0x86);
I2C_out(0x38);
                               //
                               //
                               //
                               //
I2C_out(0xB7);
                               //
I2C_out(0x38);
                               //
I2C out(0xB8);
                               //
I2C out (0x3A);
                               //
I2C out(0xB9);
I2C_out(0x3A);
                               //
12C_out(0xBA);
                               //
I2C_out(0x3A);
                               //
I2C_out(0xBB);
                               //
I2C_out(0x3A);
                               //
I2C_out(0xBC);
I2C_out(0x3C);
I2C_out(0xBD);
I2C_out(0x3C);
                               //
                               //
                               //
                               //
12C_out(0xBE);
                               //
12C_out(0x3C);
                               //
I2C out(0xBF);
I2C_out(0x3C);
                               //end grayscale settings
I2C out(0x38);
I2C out (0x74);
                               //
                               //display on
I2C_out(0xAF);
I2C_Stop();
```



Quality Information

Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage	+80°C , 48hrs	2
	temperature for a long time.		
Low Temperature storage	Endurance test applying the low storage	-30°C , 48hrs	1,2
	temperature for a long time.		
High Temperature	Endurance test applying the electric stress	+70°C, 48hrs	2
Operation	(voltage & current) and the high thermal		
	stress for a long time.		
Low Temperature	Endurance test applying the electric stress	-20°C , 48hrs	1,2
Operation	(voltage & current) and the low thermal		
	stress for a long time.		
High Temperature /	Endurance test applying the electric stress	+40°C, 90% RH, 48hrs	1,2
Humidity Operation	(voltage & current) and the high thermal		
	with high humidity stress for a long time.		
Thermal Shock resistance	Endurance test applying the electric stress	-0°C 30min -> 25°C 5min ->	
	(voltage & current) during a cycle of low	50°C 30min = 1 cycle	
	and high thermal stress.	For 10 cycles	
Vibration test	Endurance test applying vibration to	10-55Hz, 1.5mm amplitude.	3
	simulate transportation and use.	60 sec in each of 3 directions	
		X,Y,Z	
		For 15 minutes	
Static electricity test	Endurance test applying electric static	VS=800V, RS=1.5kΩ, CS=100pF	
	discharge.	One time	

Note 1: No condensation to be observed.

Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.

Note 3: Test performed on product itself, not inside a container.