J. McCarthy



AN INTERESTING LISP FUNCTION

Ikuo Takeuchi (1978) of the Electrical Communication Laboratory of Nippon Telephone and Telegraph Co. (Japan's Bell Labs) devised a recursive function program for comparing the speeds of LISP systems. It can be made to run a long time without generating large numbers or using much stack. The program is

$$tak(x, y, z) \leftarrow \text{ if } x \leq y \text{ then } y$$

$$\text{else } tak(tak(x-1, y, z), tak(y-1, z, x), tak(z-1, x, y)),$$

where the variables may range over the integers (including negative) or else over real numbers. The program has similar properties in the two cases, but proving termination seems more tedious if arbitrary real numbers are allowed. The program has several interesting features.

1. Inspection suggests that tak satisfies the equation

$$tak(x+a,y+a,z+a) = tak(x,y,z) + a,$$

whenever the computation terminates, and this can be shown by subgoal induction. Namely, it is true for the non-recursive case, and assuming it for the referred sets of arguments yields it for the main set. A formal proof can proceed along the lines suggested in (McCarthy 1978).

- 2. Experiment using LISP indicates first of all that the value of tak(x, y, z) is always one of x, y or z. I don't see a proof of this fact in isolation.
- 3. Like the 91-function, the program computes a simple non-recursive function. Using LISP to compute some values of tak leads to the guess that it is the same as

$$tak0(x, y, z) = if x \le y then y else if y \le z then z else x.$$

Substitution shows that tak0 satisfies the functional equation for tak, and therefore by the minimization schema of (McCarthy 1978),

$$tak(x, y, z) = tak0(x, y, z)$$

whenever the former terminates. A fortiori, this establishes that tak(x, y, z) takes one of the variables as value, but maybe that fact could be proved separately.

4. In order to prove that tak is total, we write a "derived program" dtak(x, y, z) that computes the depth of recursion involved in computing tak(x, y, z) using call-

by-value. We have

$$\begin{aligned} dtak(x,y,z) \leftarrow & \text{ if } x \leq y \text{ then } 0 \\ & \text{ else } 1 + \max(dtak(x-1,y,z), \\ & dtak(y-1,x,z), \\ & dtak(z-1,x,y), \\ & dtak(tak(x-1,y,z),tak(y-1,z,x),tak(z-1,x,y))). \end{aligned}$$

Experiment with LISP leads to the conjecture that for integer values of the variables, dtak is extensionally equivalent to

$$dtak0(x, y, z) = dtak00(x - y, z - y),$$

where

$$dtak00(m,n) = \text{ if } m \leq 0 \text{ then } 0$$

$$\text{else if } n \geq 2 \text{ then } m + n(n-1)/2 - 1$$

$$\text{else if } n \geq 0 \text{ then } m$$

$$\text{else if } n = -1 \text{ then } (m+1)(m+2)/2 - 1$$

$$\text{else } (m-n)(m-n+1)/2 - m - 1.$$

We don't bother to verify the conjecture. Instead we use dtak0 as a rank function to prove $\forall i.\Phi(i)$ by course-of-values induction where

$$\Phi(i) \equiv \forall xyz. (dtak0(x, y, z) = i \supset tak(x, y, z) = tak0(x, y, z)).$$

Since we already know that tak0 satisfies the functional equation of tak, we need only show that in the recursive case of tak, i.e. when x > y, the referred arguments are of lower rank than the main ones. Thus we must show that each of dtak0(x-1,y,z), dtak0(y-1,z,x), dtak0(z-1,x,y), and dtak0(tak0(x-1,y,z),tak0(y-1,z,x)), tak0(z-1,x,y) is strictly less than dtak0(x,y,z). Each inequality follows from a separate easy case analysis. Presumably termination could be proved for the non-integer case by a similar argument with a more complicated formula for dtak00. We leave this as an exercise for the reader.

5. Like Morris's program

$$morris(x, y) \leftarrow \text{ if } x = 0 \text{ then } 1 \text{ else } morris(x - 1, morris(x, y)),$$

tak is more quickly computed by call-by-need (Vuillemin 1973). In fact the number of function calls appears to be exponential with call-by-value and quadratic with call-by-need. The culprit is the third argument of the outer call, namely tak(z-1,x,y) which is often unneeded. Unlike morris, however, tak is total.

A call-by-need version of tak is given by

$$ntak(x, y, z) \leftarrow vtak\langle x, y, z \rangle$$
,

where

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vtak \ u \leftarrow \text{ if } numberp \ u \text{ then } u
\text{else if } n \ d \ u \text{ then } vtak(\ a \ u) - 1
\text{else } \{vtak \ a \ u, vtak \ ad \ u\}[\lambda xy.
\text{if } x \leq y \text{ then } y
\text{else } vtak(\langle x-1, y, \text{ add } u \rangle, \langle y-1, \text{ add } u, x \rangle, \langle \text{ add } u-1, x, y \rangle)].
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vtak is obtained from tak in a somewhat ad hoc way. Since we don't always compute all arguments of a function we must work with triples whose elements are either numbers or applications of functions to arguments. The only functions that occur are vtak itself and subtracting one. Therefore, a number stands for itself, an application of vtak is represented by a triple, and an application of subtracting one is represented by a list of one element—the inner expression from which one is to be subtracted. Perhaps I'm being thick, but it seems to me that call-by-need requires lists or at least putting symbols on the stack.

MACLISP versions of tak and friends are in the file TAK.LSP[F78,JMC] at SU-AI. I thank Don Knuth for suggesting call-by-need. The external or publication LISP notation is as in (McCarthy and Talcott 1978). It has the following features: (1) a and d are used for car and cdr, and their compounds are formed similarly. (2) The infix. is used for cons, and $\langle x, y, ..., z \rangle$ is used for list[x, y, ..., z]. (3) $\{x, y, ..., z\}f$ is used for f[x, y, ..., z] whenever we prefer to write the arguments first and the function name later.

References

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