

Improving Multispectral Pedestrian Detection by Addressing Modality Imbalance Problems

Computational Imaging Lab @ Nanjing University

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How to detect pedestrians at night?

traditional pedestrian detection dataset



Caltech, CityPersons, INRIA...

pedestrian detection dataset at night



NightOwls^[2]

The performance of SDS RCNN^[1] (Miss Rate)

Train	Test	Caltech	NightOwls
Caltech		7.36%	63.99% ↑

The performance of pedestrian detection model suffers at night!

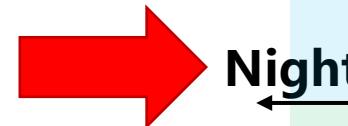
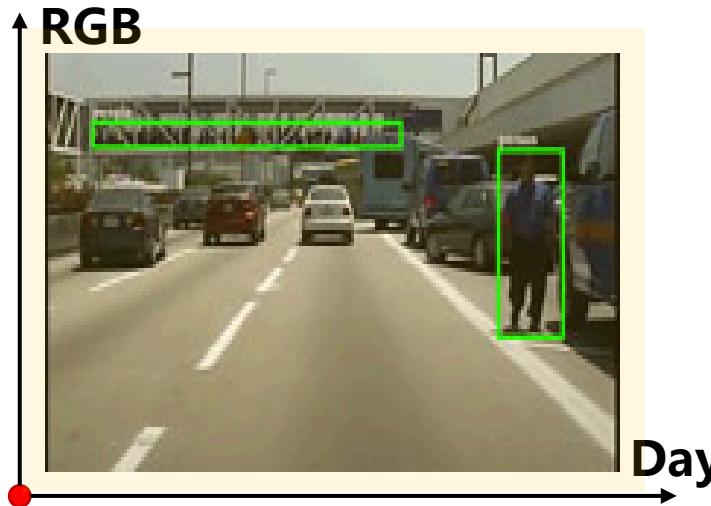
SOLUTION: multispectral (RGB+thermal)

[1] Garrick Brazil et al. Illuminating Pedestrians via Simultaneous Detection & Segmentation. ICCV2017

[2] Lukáš Neumann et al. NightOwls: A Pedestrians at Night Dataset. ACCV2018

Multispectral Pedestrian Detection: RGB + Thermal

traditional pedestrian
detection dataset



KAIST [1]

RGB



Night



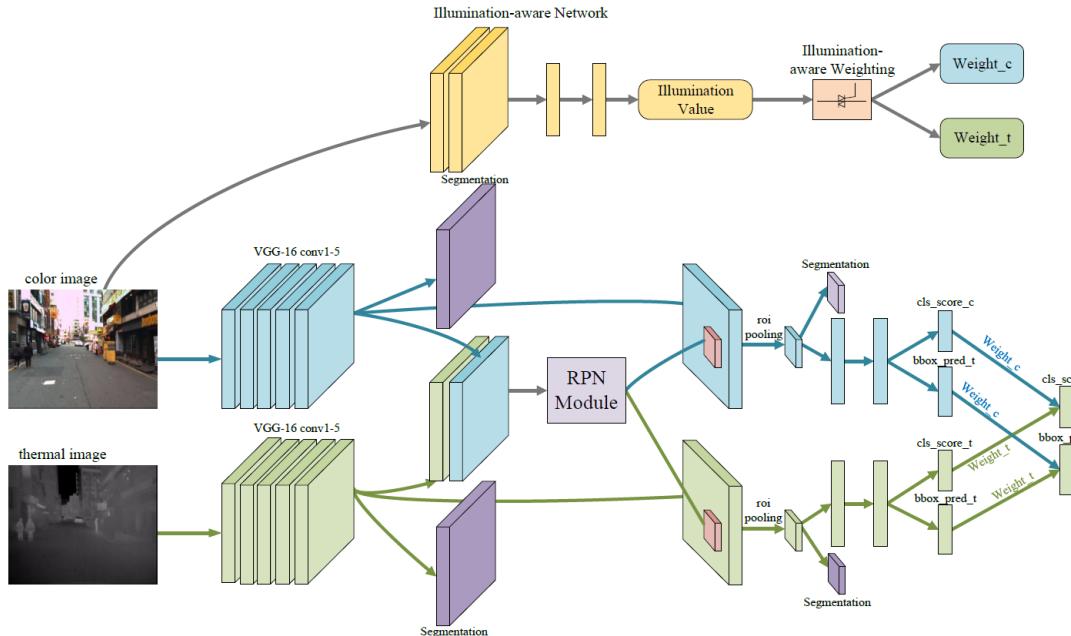
one modality → four modalities

◆ RGB & Thermal ◆ Night & Day

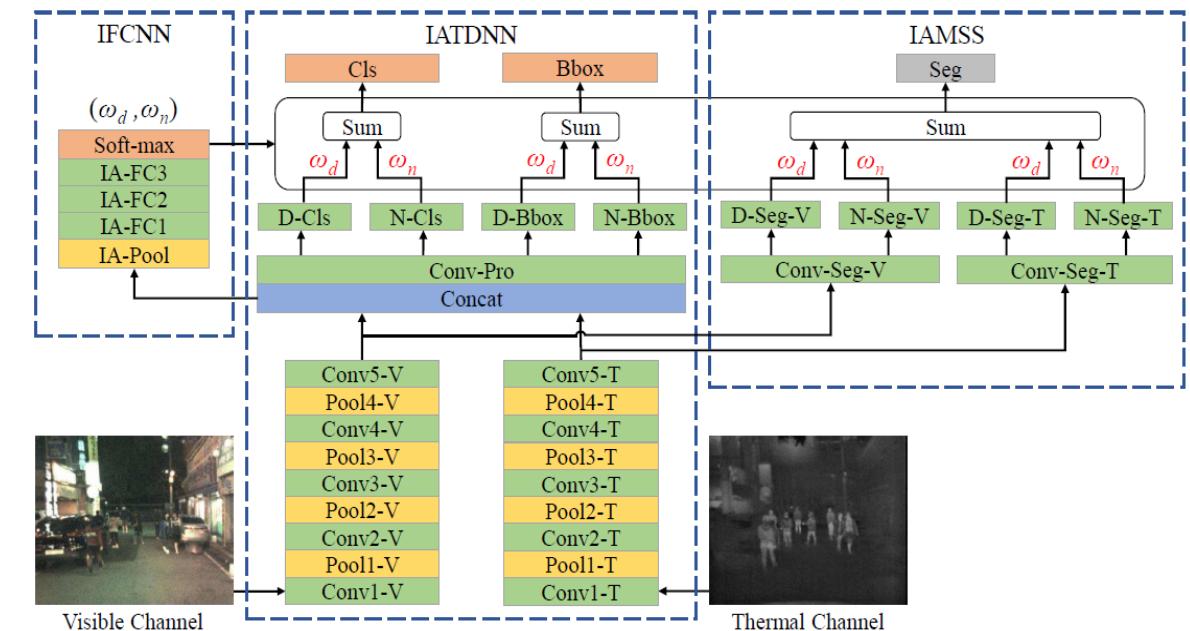
Review of Existing Works

- How to adapt to different illumination conditions
- How to fuse the RGB and thermal features

IAF-RCNN [1]



IATDNN-IAMSS [2]



Illumination – aware score fusion

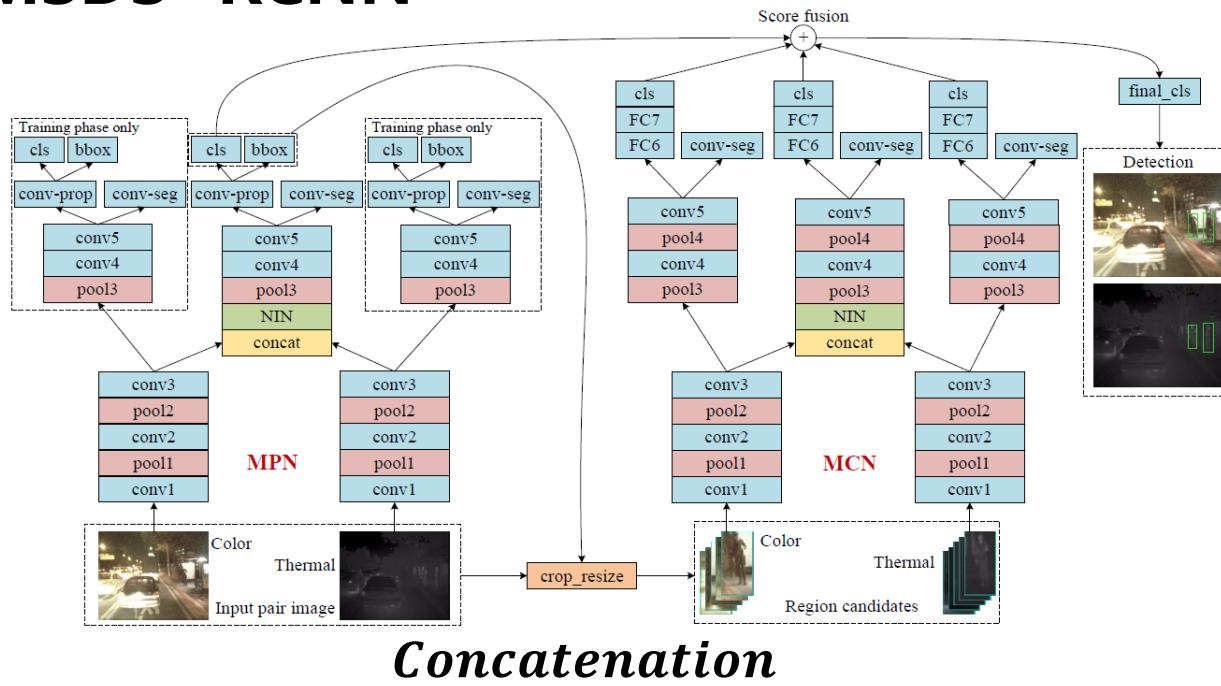
[1] Chengyang Li et al. Illumination-aware Faster R-CNN for Robust Multispectral Pedestrian. BMVC2018

[2] Dayan Guan et al. Fusion of Multispectral Data Through Illumination-aware Deep Neural Networks for Pedestrian Detection[J]. Information Fusion, 2019: 148-157.

Review of Existing Works

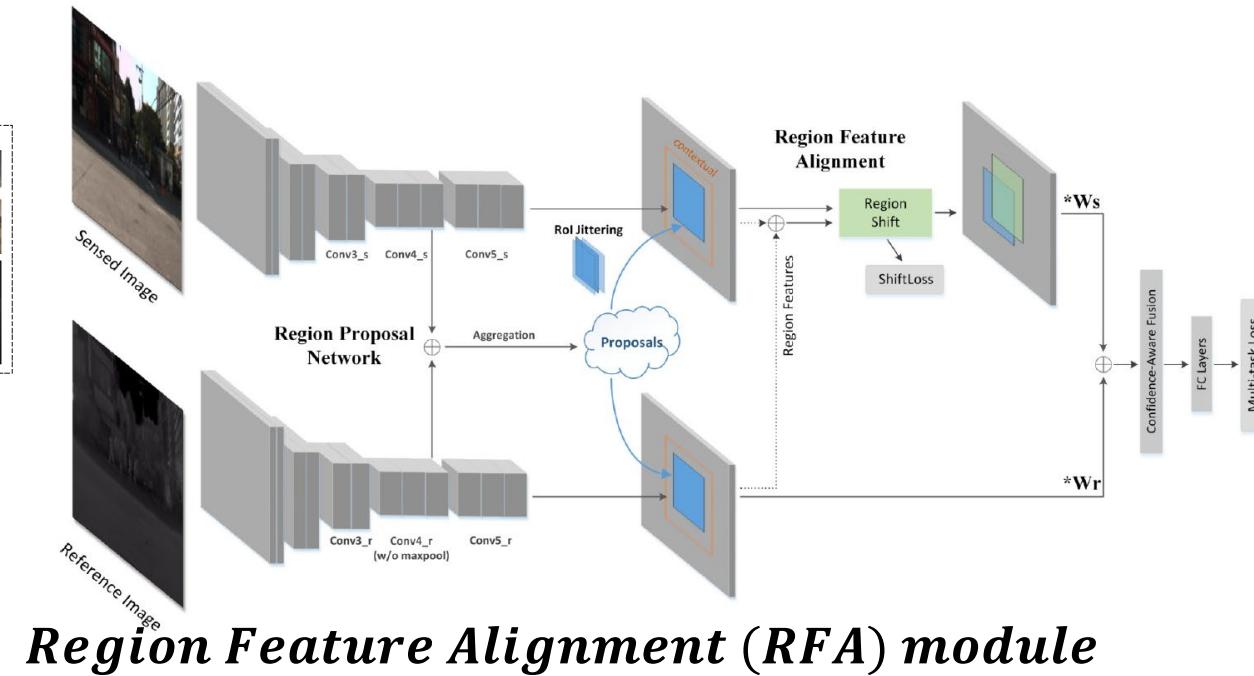
- How to adapt to different illumination conditions
- How to fuse the RGB and thermal features

MSDS-RCNN [1]



Concatenation

AR-CNN [2]



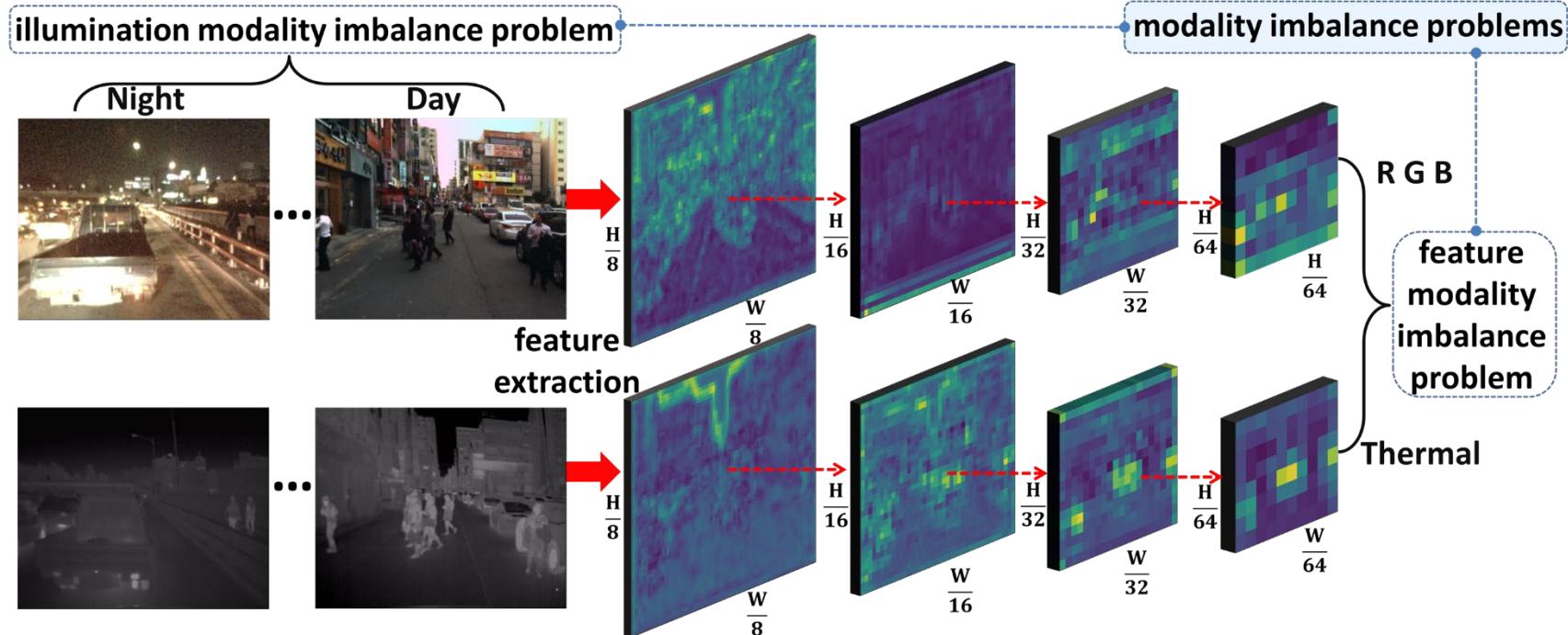
Region Feature Alignment (RFA) module

[1] Chengyang Li et al. Multispectral Pedestrian Detection via Simultaneous Detection and Segmentation. BMVC2018

[2] Lu Zhang et al et al. Weakly Aligned Cross-Modal Learning for Multispectral Pedestrian Detection. ICCV2019

Modality Imbalance Problems

- ❑ How to adapt to different illumination conditions
- ❑ How to fuse the RGB and thermal features



illumination modality imbalance

- ◆ Under different illumination conditions

Day&Night modalities
contribute out-off-balance

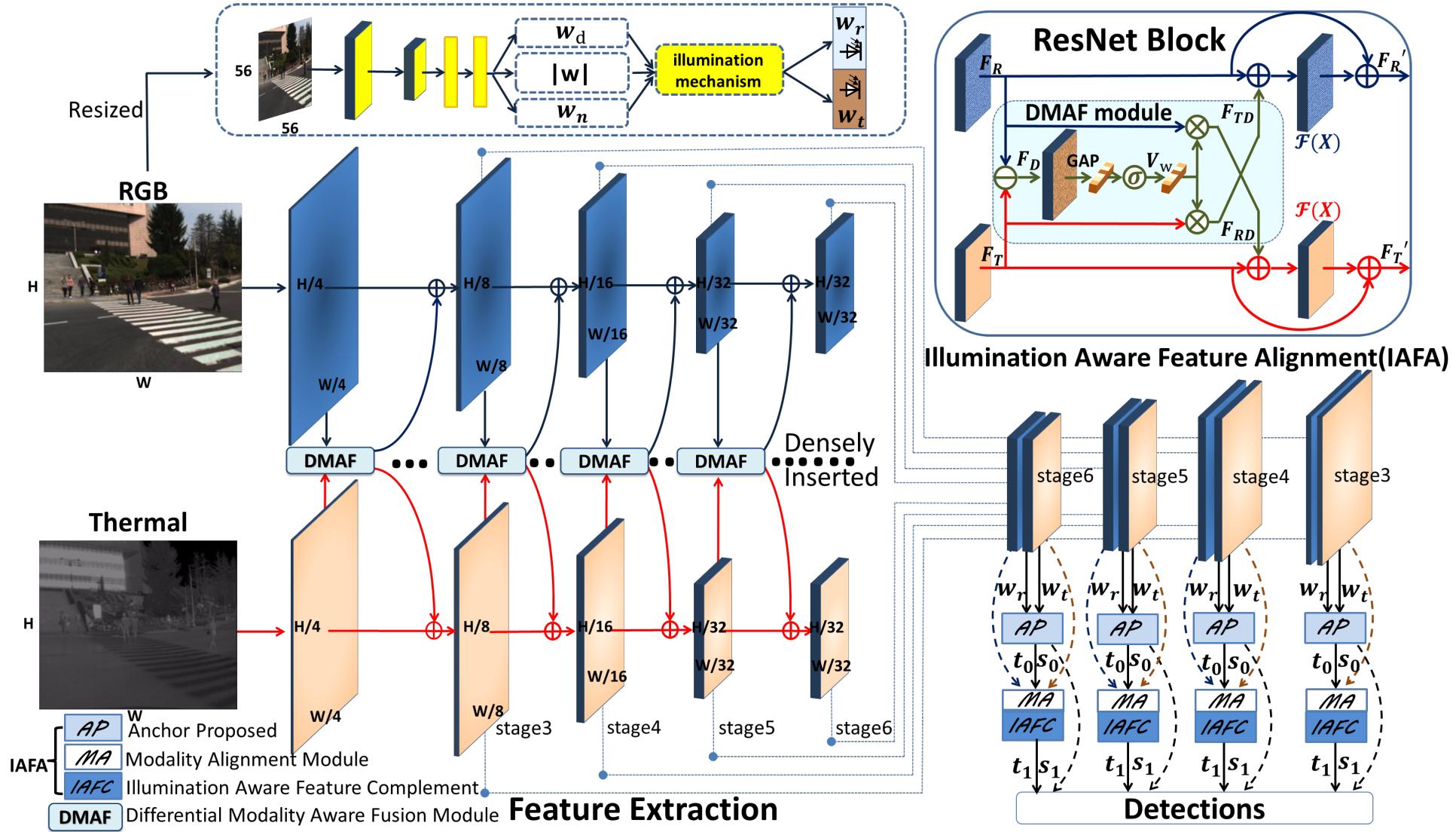
feature modality imbalance

- ◆ Feature Misalignment ◆ Inadequate Fusion

RGB&Thermal modalities
contribute out-off-balance

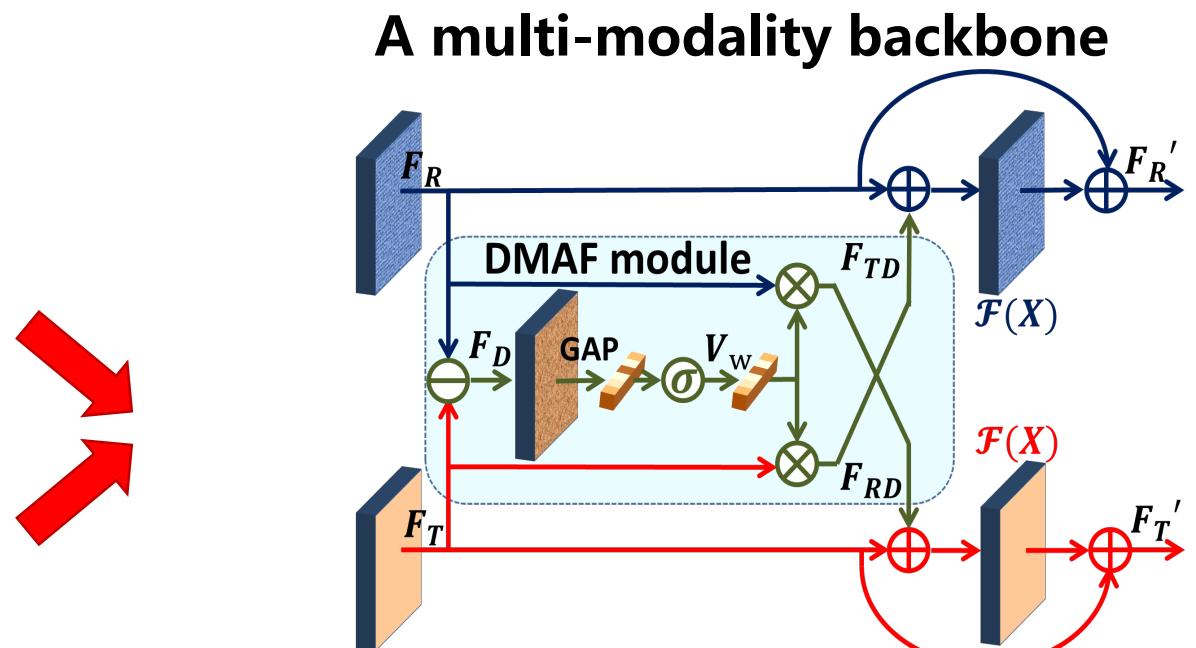
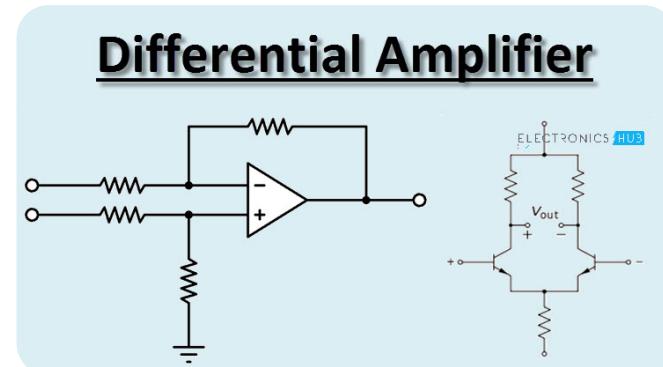
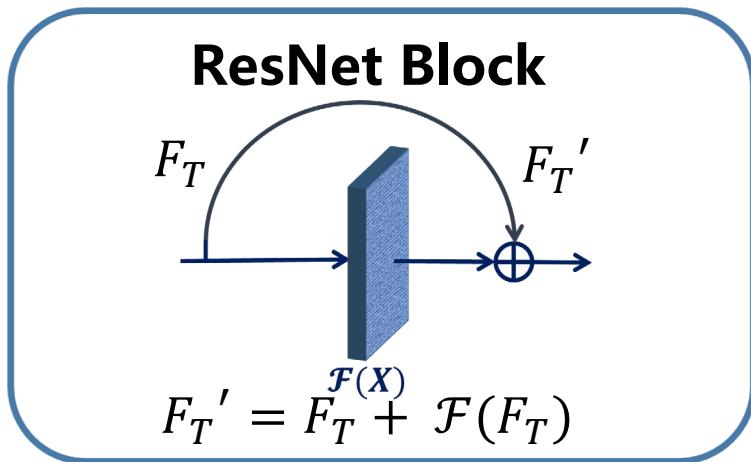
Our Works

Modality Balance Network (MBNet)



Differential Modality Aware Fusion (DMAF) Module

- Differential Amplifier: **amplify** differential signals & **suppress** common signals
- DMAF module: **compensate** differential features & **retain** original features



$$F_T' = F_T + \mathcal{F}(F_T \oplus F_{RD}) = F_T + \mathcal{F}(F_T \oplus \sigma(GAP(F_D) \odot F_R))$$

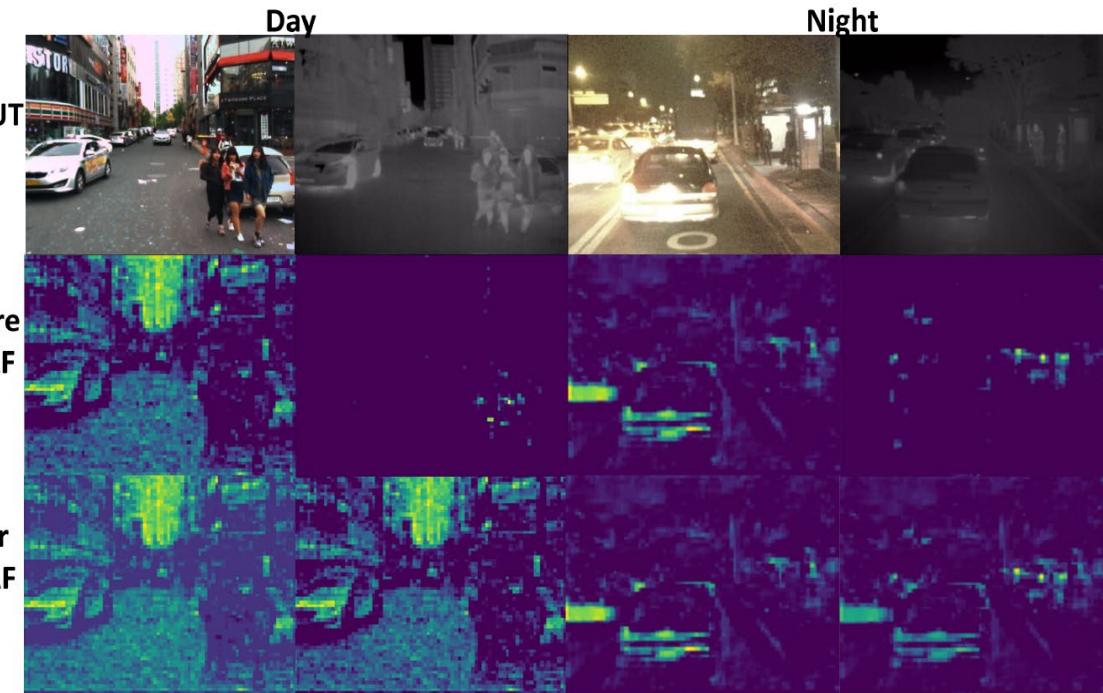
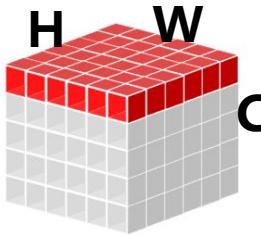
$$F_R' = F_R + \mathcal{F}(F_R \oplus F_{TD}) = F_R + \mathcal{F}(F_R \oplus \sigma(GAP(F_D) \odot F_T))$$

\oplus : element-wise sum \odot : element-wise multiplication GAP :Global Average Pooling

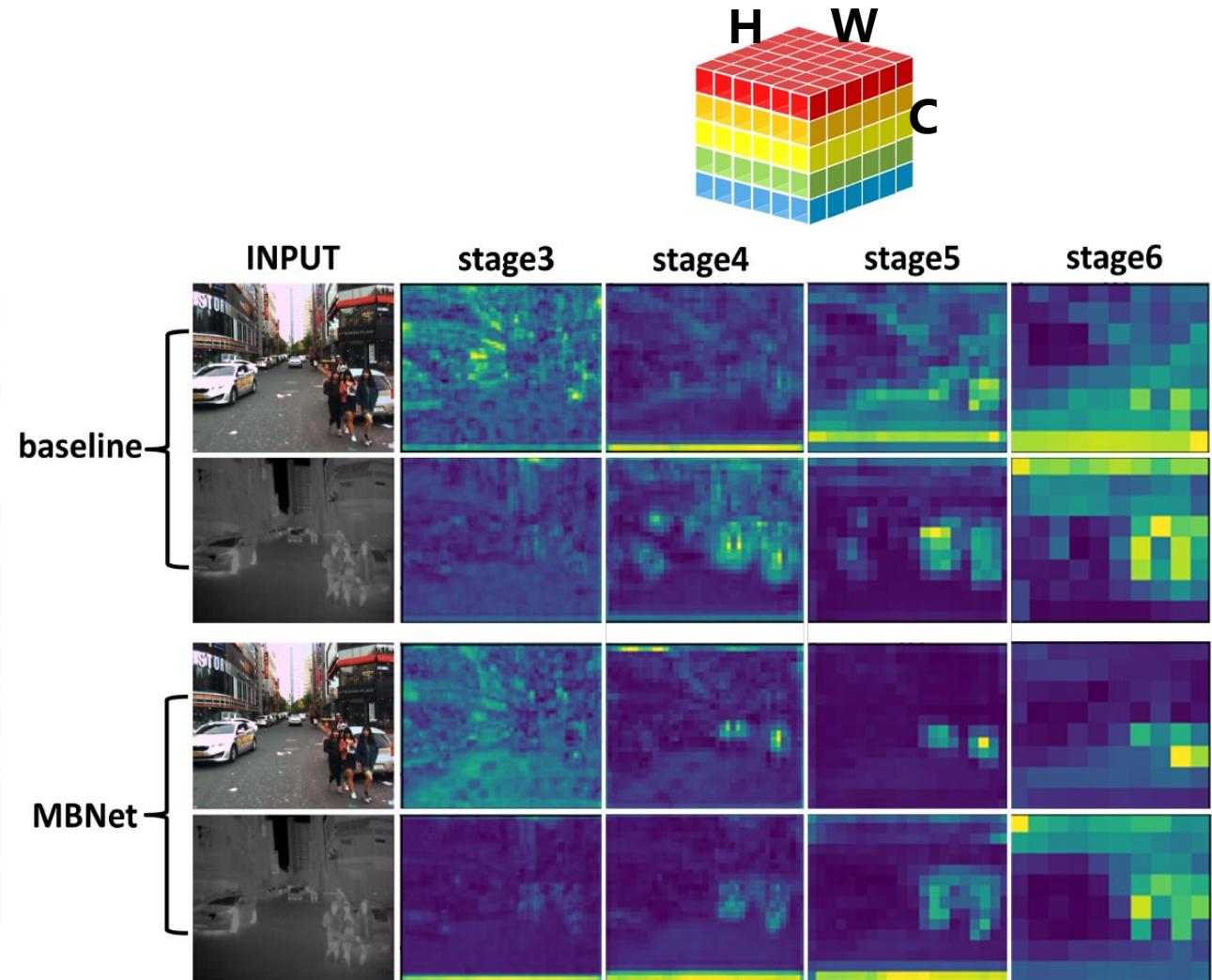


sufficient fusion in the backbone with no extra parameters

Visualization of the DMAF Module

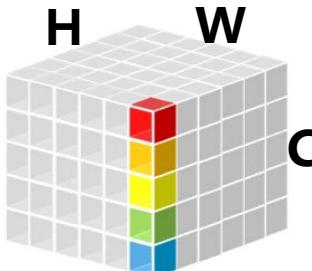


one channel

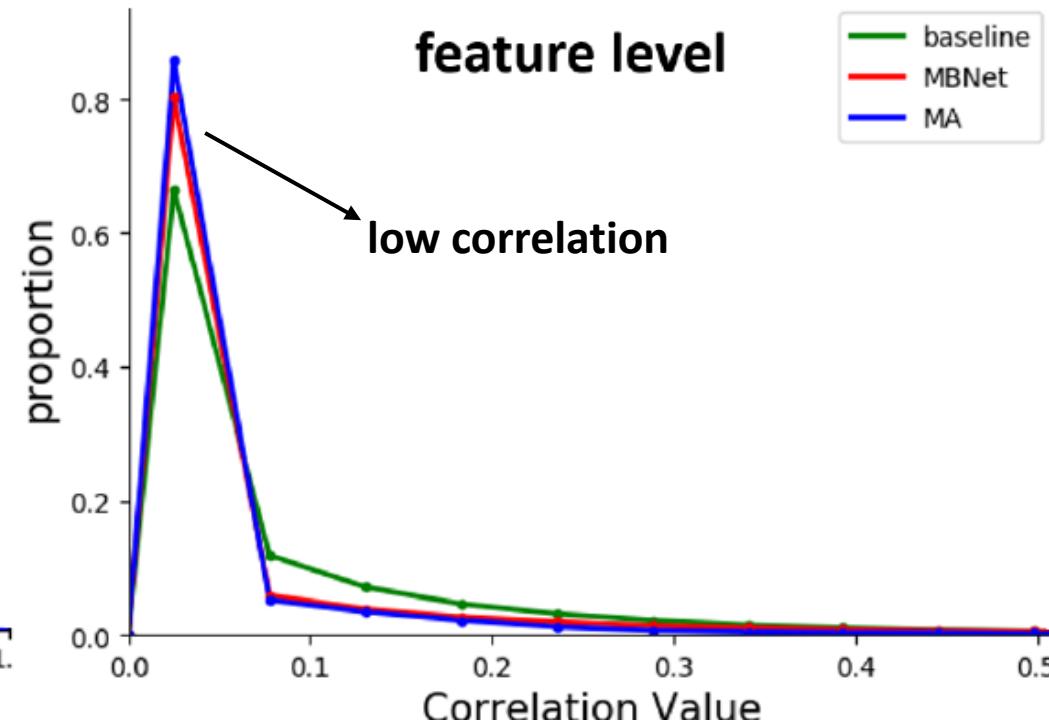
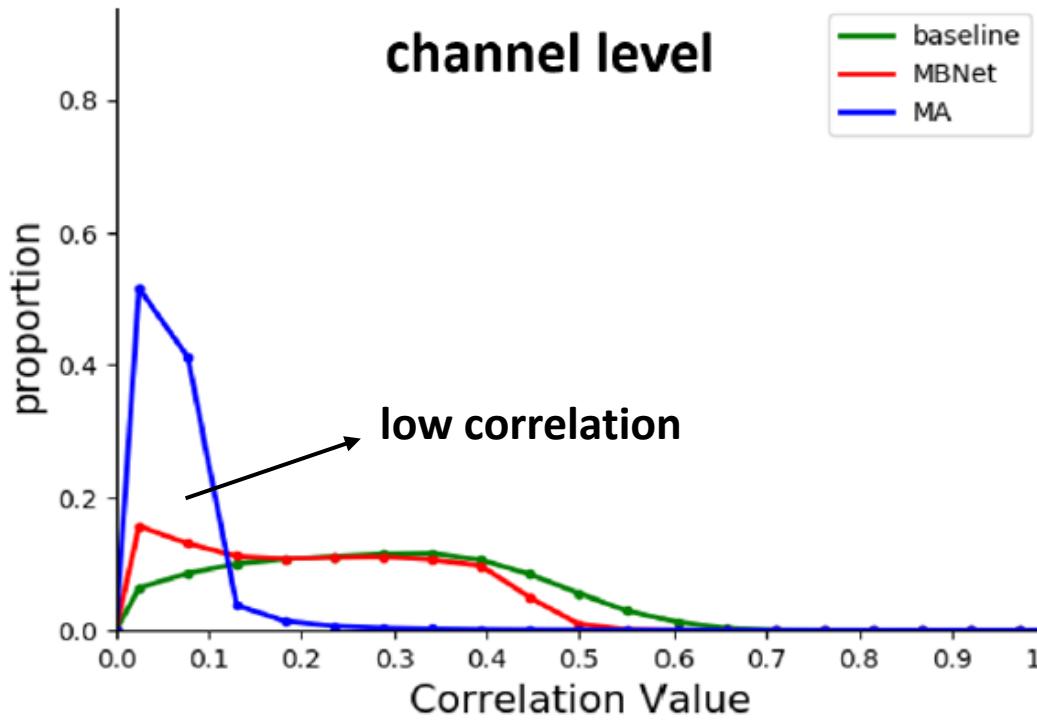
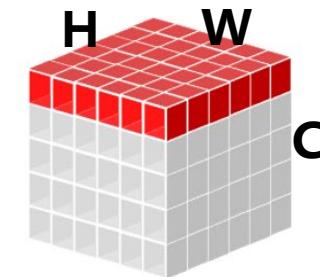


the whole feature map

An explanatory perspective: Redundancy Analysis



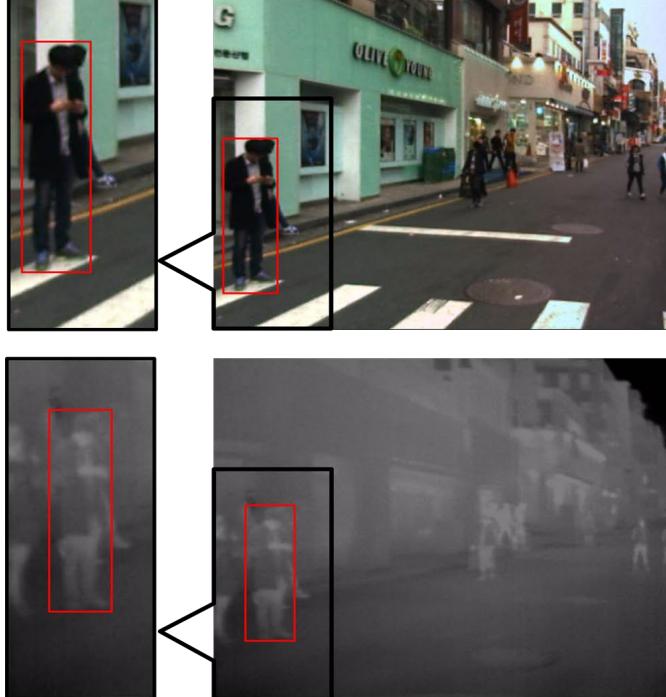
Pearson product-moment correlation coefficient $|\rho|$ between two modalities



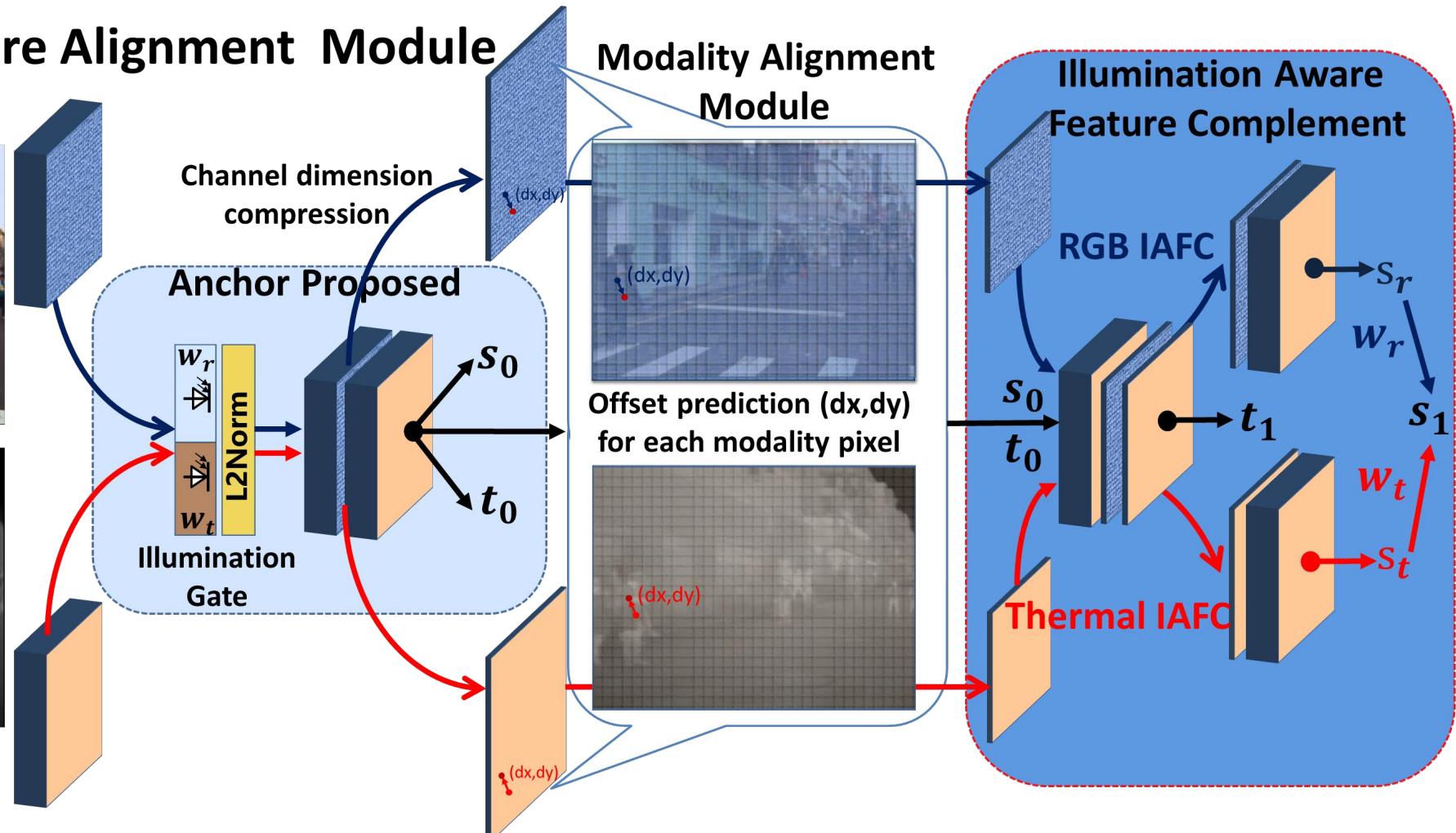
the DMAF module facilitates modality interaction in the backbone which reduces the learning of redundancy and conveys more information.

Illumination Aware Feature Alignment (IAFA) Module

Illumination Aware Feature Alignment Module



RGB modality and thermal modality are not aligned!



- fix the misalignment between two modality features
- be adaptive to illumination changes

Results and Comparisons

Table 1. Comparisons with the state-of-the-art methods on the KAIST reasonable subset in terms of MR^{-2} [17] with different thresholds of IoU. In addition, Comparisons of running time are also provided.

Methods	MR^{-2} (IoU = 0.5)			MR^{-2} (IoU = 0.75)			Plateform	Speed(s)
	All	Day	Night	All	Day	Night		
ACF [17]	47.32	42.57	56.17	88.79	87.70	91.22	MATLAB	2.73
Halfway Fusion[27]	25.75	24.88	26.59	81.29	78.43	86.80	TITAN X	0.43
Fusion RPN+BF [21]	18.29	19.57	16.27	72.97	68.14	81.35	MATLAB	0.80
IAF R-CNN [23]	15.73	14.55	18.26	75.50	72.34	81.12	TITAN X	0.21
IATDNN + IASS[13]	14.95	14.67	15.72	76.69	76.46	77.05	TITAN X	0.25
RFA[42]	14.61	16.78	10.21	-	-	-	TITAN X	0.08
CIAN [43]	14.12	14.77	11.13	74.45	71.42	80.16	1080 Ti	0.07
MSDS-RCNN [22]	11.34	10.53	12.94	70.57	67.36	79.25	TITAN X	0.22
AR-CNN [44]	9.34	9.94	8.38	64.22	57.87	76.82	1080 Ti	0.12
MBNet(ours)	8.13	8.28	7.86	60.12	54.90	68.34	1080 Ti	0.07

Results and Comparisons

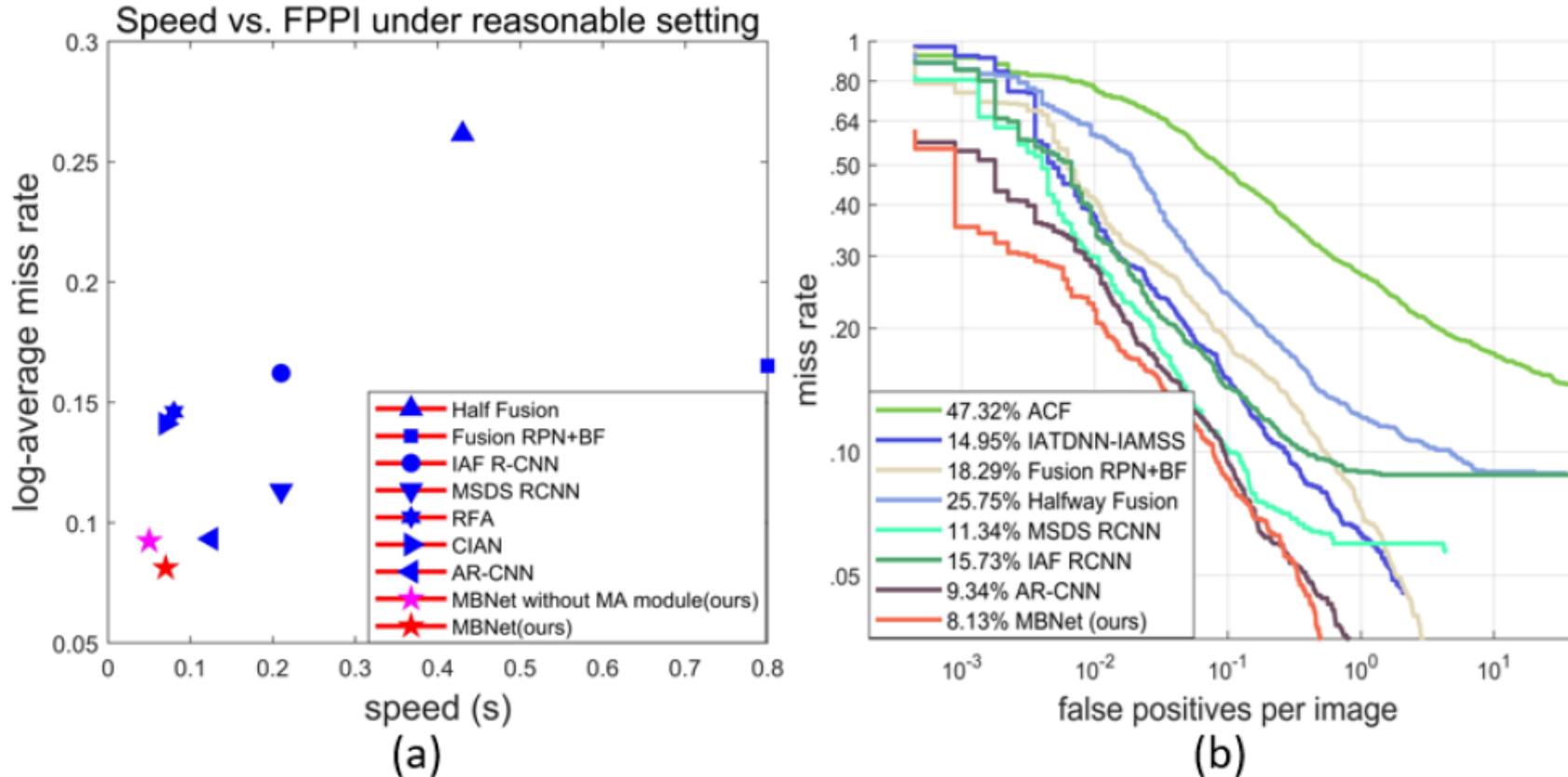


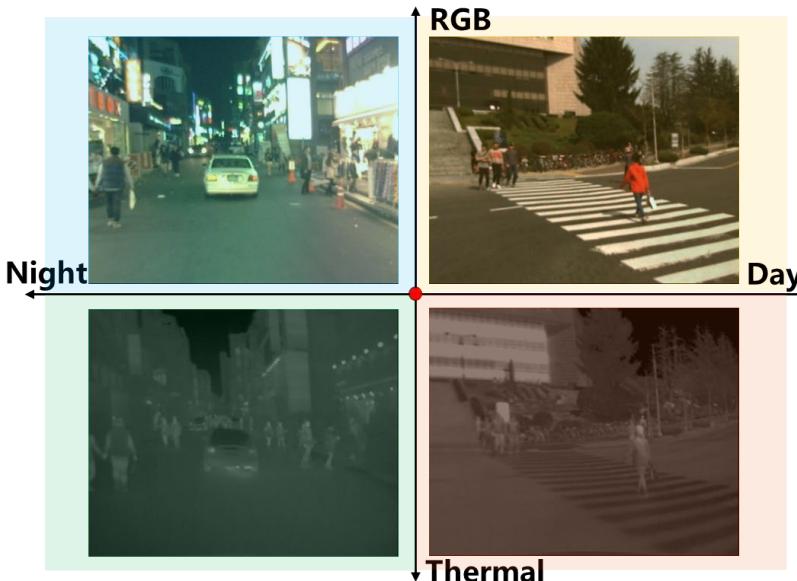
Fig. 5. (a) Log-average miss rate versus the running time of each detector. (b) Performance comparisons with the state-of-the-art methods on the KAIST dataset under reasonable subset.

Demo



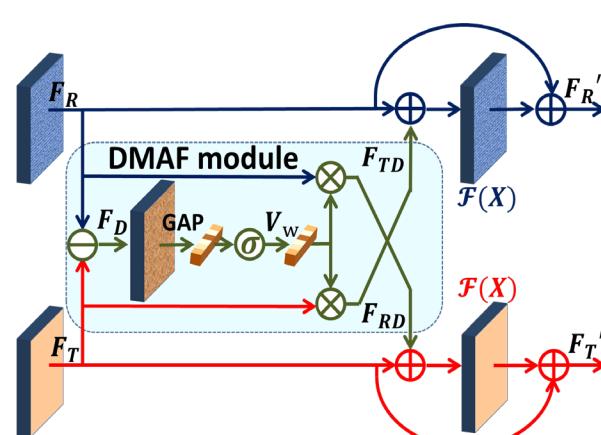
Contribution

□ modality imbalance problems



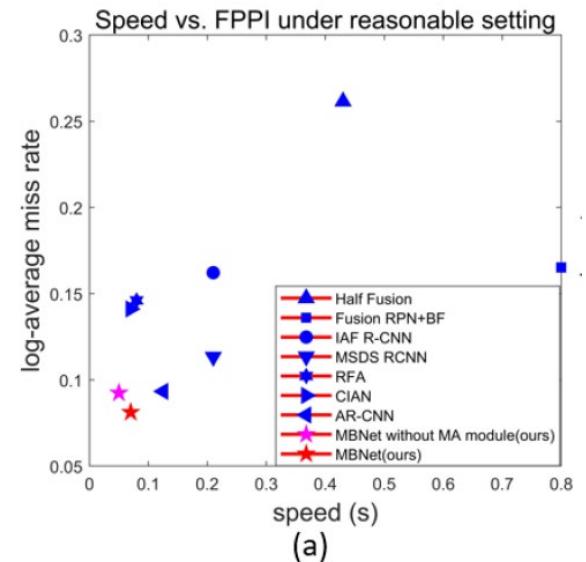
- RGB & Thermal
- Night & Day

□ the DMAF module



- Inspired by differential amplifier
- A multi-modality backbone
- No extra parameters
- Redundancy Analysis

□ performance



- Best results on KAIST and CVC14 dataset



16TH EUROPEAN CONFERENCE ON
COMPUTER VISION

WWW.ECCV2020.EU

Thanks for your attention

Computational Imaging Technology & Engineering Lab
CITE @ Nanjing University



Code Link

Demo Link