

**MISR UNIVERSITY FOR SCIENCE AND TECHNOLOGY**  
**COLLEGE OF ENGINEERING**  
**MECHATRONICS DEPARTMENT**



# MTE 506 DIGITAL CONTROL

LAB 6 – SPRING 2019

Lab 6

# Goals of The Lab



Z- Transform and unit delay

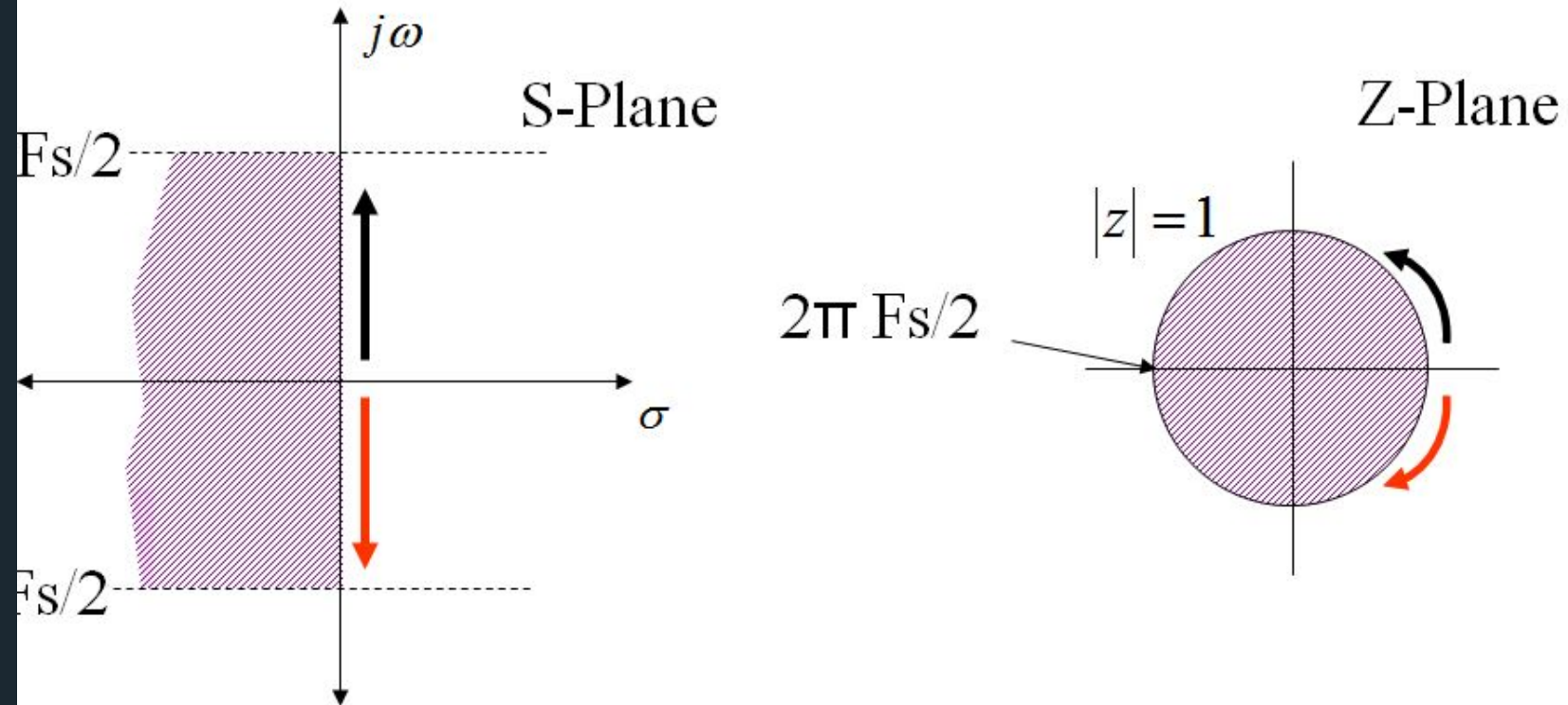


Conversion to Z-Transform

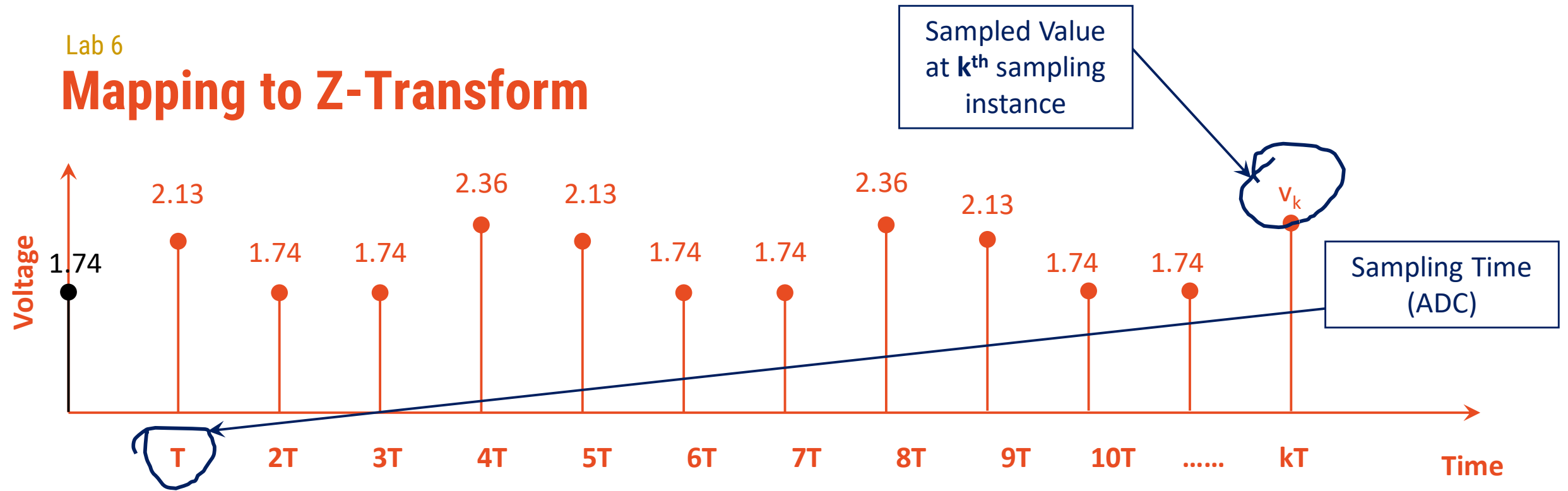
## Z - Transform

## Mapping from s to z

$$z = e^{sT} = e^{\frac{s}{F_s}}$$



# Mapping to Z-Transform



$$v(t) = 1.74 \delta(t) + 2.13 \delta(t - T) + 1.74 \delta(t - 2T) + 1.74 \delta(t - 3T) + 2.36 \delta(t - 4T) + 2.13 \delta(t - 5T) + \dots + v_k \delta(t - kT)$$

$$V(s) = 1.74 + 2.13 e^{-sT} + 1.74 e^{-2sT} + 1.74 e^{-3sT} + 2.36 e^{-4sT} + 2.13 e^{-5sT} + \dots + v_k e^{-ksT}$$

# Mapping to Z-Transform

$$\text{Let } z = e^{sT}$$

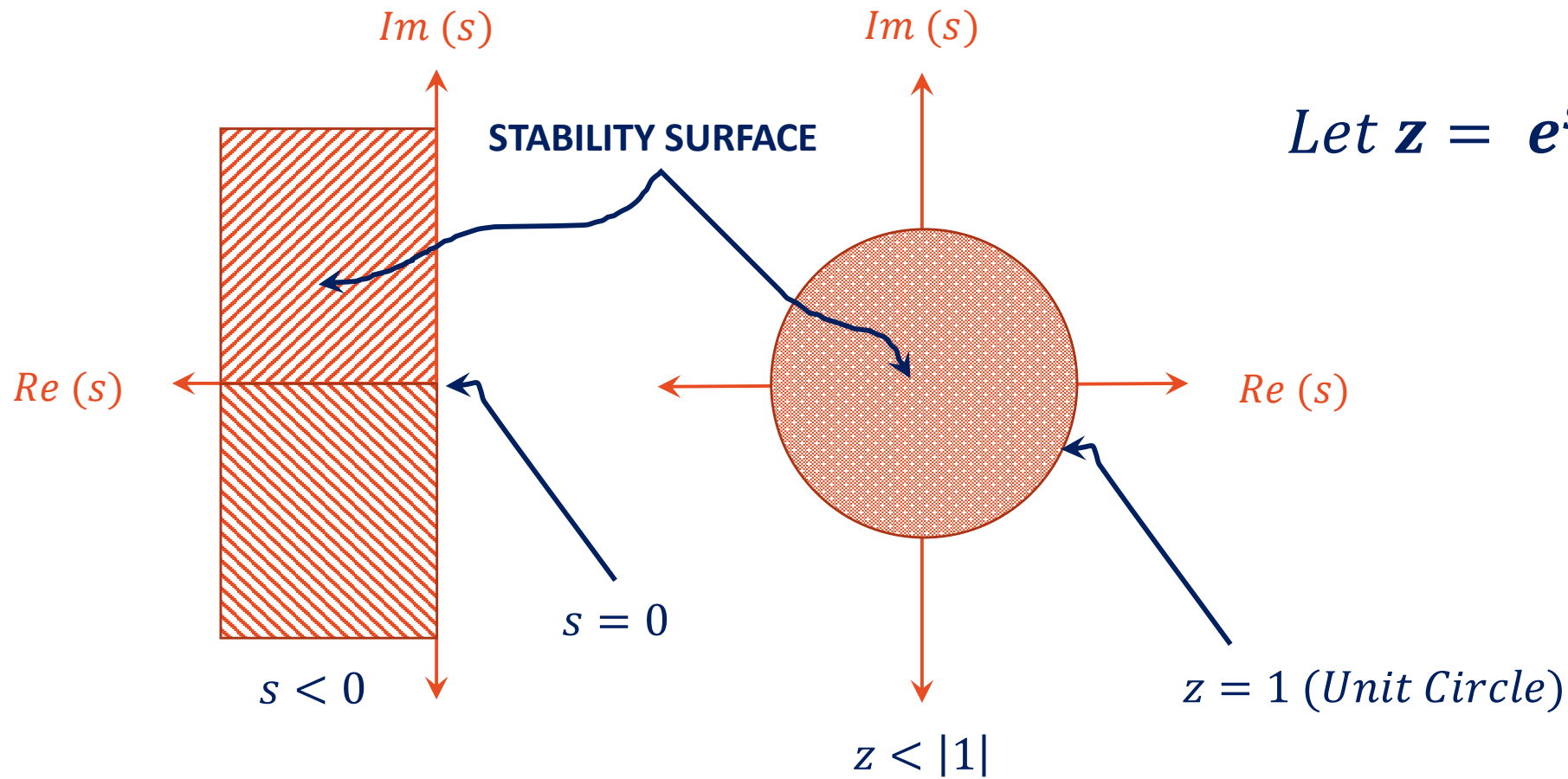
$$v(t) = 1.74 \delta(0) + 2.13 \delta(t - T) + 1.74 \delta(t - 2T) + 1.74 \delta(t - 3T) + 2.36 \delta(t - 4T) + 2.13 \delta(t - 5T) + \dots + v_k \delta(t - kT)$$

$$V(s) = 1.74 + 2.13 e^{-sT} + 1.74 e^{-2sT} + 1.74 e^{-3sT} + 2.36 e^{-4sT} + 2.13 e^{-5sT} + \dots + v_k e^{-ksT}$$

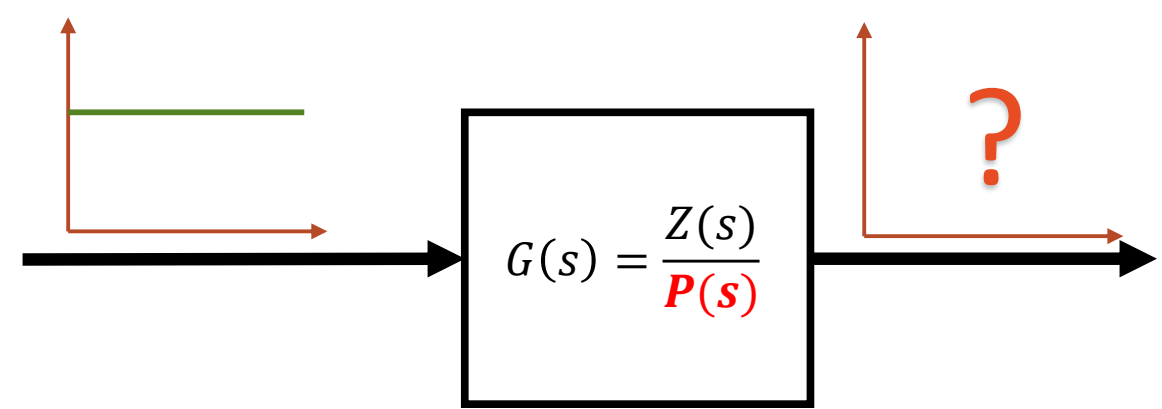
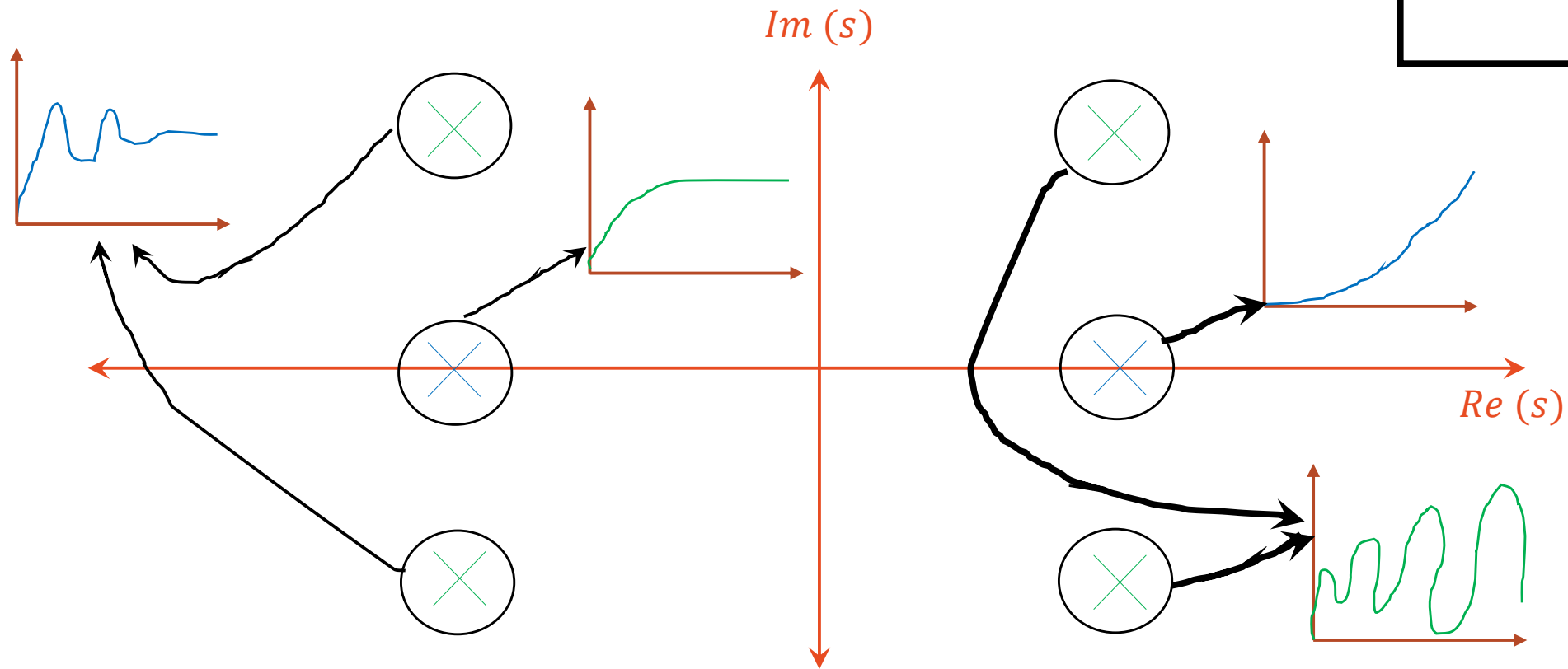
$$V(z) = 1.74 + 2.13 z^{-1} + 1.74 z^{-2} + 1.74 z^{-3} + 2.36 z^{-4} + 2.13 z^{-5} + \dots + v_k z^{-k}$$

$$V(z) = \underbrace{\sum_{k=0}^N v_k z^{-kT}}_{\text{Sequence}} \quad V(z) = \sum_{k=0}^N v_k z^{-k}, T = 1$$

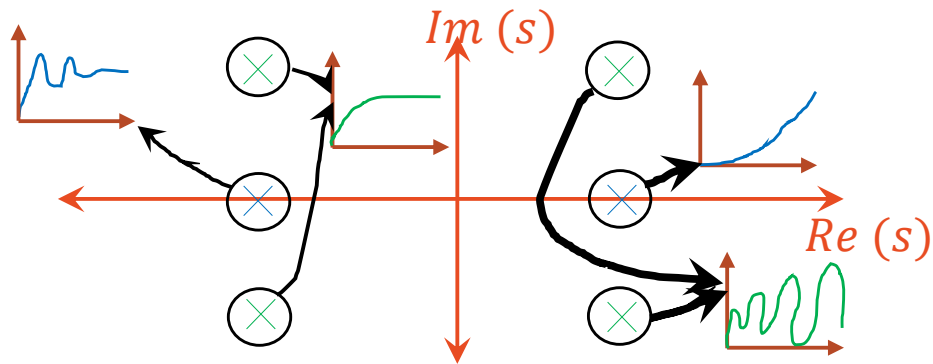
# Mapping to Z-Transform



# System Stability



# Assignment



Map using any sketching software same points to **z-plane** using numeric examples (values for poles)

*e.g.*  $s = -3$  (real)  $\rightarrow z = ?$

*e.g.*  $s = -3 \pm 4j$  (complex)  $\rightarrow z = ?$

*e.g.*  $s = 0 \rightarrow z = ?$

*e.g.*  $s = \infty \rightarrow z = ?$

$$z = e^{sT} \text{ or } s = \frac{1}{T} \ln z$$

*Due before : 07 – 04 – 2020*



## Lab 6

# Z – Transform Closed Form

## Transforms

$f(kT), k \geq 0$	$F(z)$
$\begin{cases} 1, k=0 \\ 0, k \neq 0 \end{cases}$	1
$\begin{cases} 1, k=n \\ 0, k \neq n \end{cases}$	$z^{-n}$
1	$\frac{z}{z-1}$
$kT$	$\frac{Tz}{(z-1)^2}$
$\frac{1}{2}(kT)^2$	$\frac{T^2 z(z+1)}{2(z-1)^3}$
$e^{-akT}$	$\frac{z}{z-e^{-aT}}$
$(kT)e^{-akT}$	$\frac{T e^{-aT} z}{(z-e^{-aT})^2}$

$f(t), t \geq 0$	$F(s)$	$f(kT), k \geq 0$
$1 - e^{-at}$	$\frac{a}{s(s+a)}$	$1 - e^{-akT}$
$e^{-at} - e^{-bt}$	$\frac{b-a}{(s+a)(s+b)}$	$e^{-akT} - e^{-bkT}$
$\sin(\omega t)$	$\frac{\omega}{s^2 + \omega^2}$	$\sin(\omega kT)$
$\cos(\omega t)$	$\frac{s}{s^2 + \omega^2}$	$\cos(\omega kT)$
$e^{-at} \sin(\omega t)$	$\frac{\omega}{(s+a)^2 + \omega^2}$	$e^{-akT} \sin(\omega kT)$
$e^{-at} \cos(\omega t)$	$\frac{s+a}{(s+a)^2 + \omega^2}$	$e^{-akT} \cos(\omega kT)$
—	—	$a^k$
—	—	$k \cdot a^{k-1}$

# Z-Transform Infinite Power Series

$$\begin{aligned} U(z) &= u_0 + u_1 z^{-1} + u_2 z^{-2} + u_3 z^{-3} + \cdots + u_k z^{-k} \\ &= \sum_{k=0}^N u_k z^{-k} \text{ (sequence)} \end{aligned}$$

# Z-Transform Infinite Power Series

$$U(z) = u_0 + u_1 z^{-1} + u_2 z^{-2} + u_3 z^{-3} + \cdots + u_k z^{-k}$$

$$= \sum_{k=0}^N u_k z^{-k} \text{ (sequence)}$$

## Sampled Unit Step 1(k)

$$u(k)_{k=0}^{\infty} = \{1, 1, 1, 1, \dots\}$$

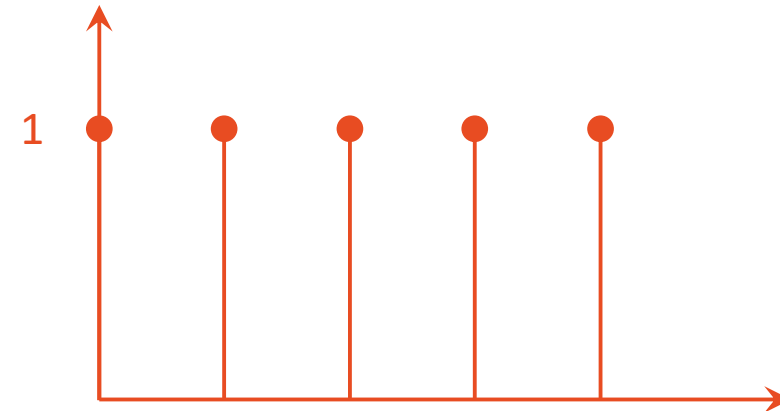
$$U(z) = 1 + 1 z^{-1} + 1 z^{-2} + 1 z^{-3} + \cdots + 1 z^{-k}$$

$$= \sum_{k=0}^N 1 z^{-k}$$

$$U(z) = \frac{1}{1 - z^{-1}} = \frac{z}{z - 1}$$

and  $\sum_{k=0}^{\infty} a^k = \frac{1}{1 - a}$

(infinite power series)



# Z-Transform Infinite Power Series

$$U(z) = u_0 + u_1 z^{-1} + u_2 z^{-2} + u_3 z^{-3} + \cdots + u_k z^{-k}$$

$$= \sum_{k=0}^N u_k z^{-k} \text{ (sequence)}$$

## Exponential $a^k$

$$u(k)\}_{k=0}^{\infty} = \{1, a, a^2, a^3, a^4, \dots, a^k\}$$

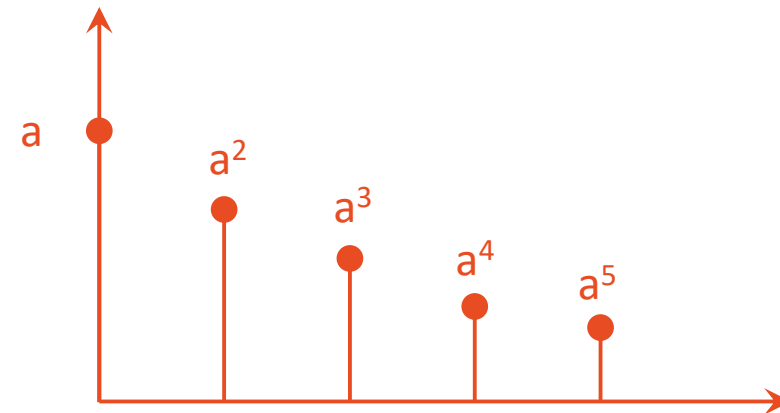
$$U(z) = 1 + a z^{-1} + a^2 z^{-2} + a^3 z^{-3} + \cdots + a^k z^{-k}$$

$$= \sum_{k=0}^N a^k z^{-k}$$

$$\mathbf{1}(z) = = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

and  $\sum_{k=0}^{\infty} a^k = \frac{1}{1 - a}$

(power infinite series)



# Z-Transform Properties

## *Time delay*

$$\mathcal{Z}\{f(k - N)\} = z^{-N} F(z)$$

## *Examples*

$$\mathcal{Z}\{1(k - 2)\} = z^{-2} F(1(k)) = z^{-2} \frac{z}{z - 1} = \frac{1}{z(z - 1)}$$

## *Remember*

$$\mathcal{Z}\{1(k)\} = \frac{z}{z - 1}$$

# Z-Transform Properties

## Time advance

$$\mathcal{Z}\{f(k + N)\} = z^N F(z) - z^N f(0) - z^{(N-1)} f(1) - \dots - z f(N - 1)$$

## Examples

$$f(k) = \{4, 8, 16, 32, \dots\} \rightarrow f(k) = 2^{k+2} \rightarrow f(k+2) \rightarrow f(k) = 2^k$$

$$\mathcal{Z}\{f(k+2)\} = z^2 F(2^k) - z^2 f(0) - z f(1)$$

$$\because f(k) = 2^k \rightarrow f(0) = 1, f(1) = 2$$

$$\therefore \mathcal{Z}\{f(k+2)\} = z^2 \frac{z}{z-2} - z^2 - 2z = \frac{(z^3) - (z^3 - 2z^2) - (2z^2 - 4z)}{z-2}$$

$$\mathcal{Z}\{f(k+2)\} = \frac{4z}{z-2}$$

# Z-Transform Properties

## *Multiplication by exponential*

$$\mathcal{Z}\{a^{-k} f(k)\} = F(az)$$

## *Examples*

$$f(k) = e^{-3k}, k = 0, 1, 2, 3, \dots$$

$$\therefore e^{-3kT} = (\mathbf{e^3})^{-k} = a^{-k} * 1(k) \rightarrow \mathcal{Z}\{1(k)\} = \frac{1}{1 - z^{-1}}$$

$$\therefore \mathcal{Z}\{a^{-k} * 1(k)\} = \frac{1}{1 - (az)^{-1}} = \frac{z}{z - a^{-1}} = \frac{\mathbf{z}}{\mathbf{z} - \mathbf{e^{-3}}}$$

# Z-Transform Properties

## *Complex Differentiation*

$$\mathcal{Z}\{k^m f(k)\} = \left(-z \frac{d}{dz}\right)^m F(z)$$

### *Examples*

$$f(k) = k, k = 0, 1, 2, 3, \dots$$

$$\because f(k) = k * 1(k) = \left(-z \frac{d}{dz}\right) \frac{z}{z-1} = (-z) \frac{(z-1)(1) - (z)(1)}{(z-1)^2} = \frac{z}{(z-1)^2}$$



## Solved Example

*Given the linear difference equation*

$$y(k + 1) - y(k) = u(k + 1), \quad u(k) \text{ is a unit step}$$

*Find  $Y(z)$*

*Solution*

$$\mathcal{Z}\{y(k + 1)\} = zF(z) - zf(0) = zY(z) - z(0) = zY(z)$$

$$\mathcal{Z}\{y(k)\} = Y(z)$$

$$\mathcal{Z}\{u(k + 1)\} = zF(z) - zf(0) = z \frac{z}{z - 1} - (z)(1) = \frac{z^2 - z^2 + z}{z - 1} = \frac{z}{z - 1}$$

$$\therefore zY(z) - Y(z) = \frac{z}{z - 1} \rightarrow Y(z)[z - 1] = \frac{z}{z - 1} \rightarrow Y(z) = \frac{z}{(z - 1)^2}$$

## Assignment 3

1. Find the  $z$  – transform of the following difference equations

a)  $y(k + 1) - 0.8y(k) = 1(k), y(0) = 1$

b)  $y(k + 2) - 0.7y(k + 1) + 0.06y(k) = \delta(k), y(0) = 0, y(1) = 2$

2. Find  $z$  – transform of the following sequence (try to find closed form)

a)  $\{0, 0, 0, 1, 1, 1, \dots\}$

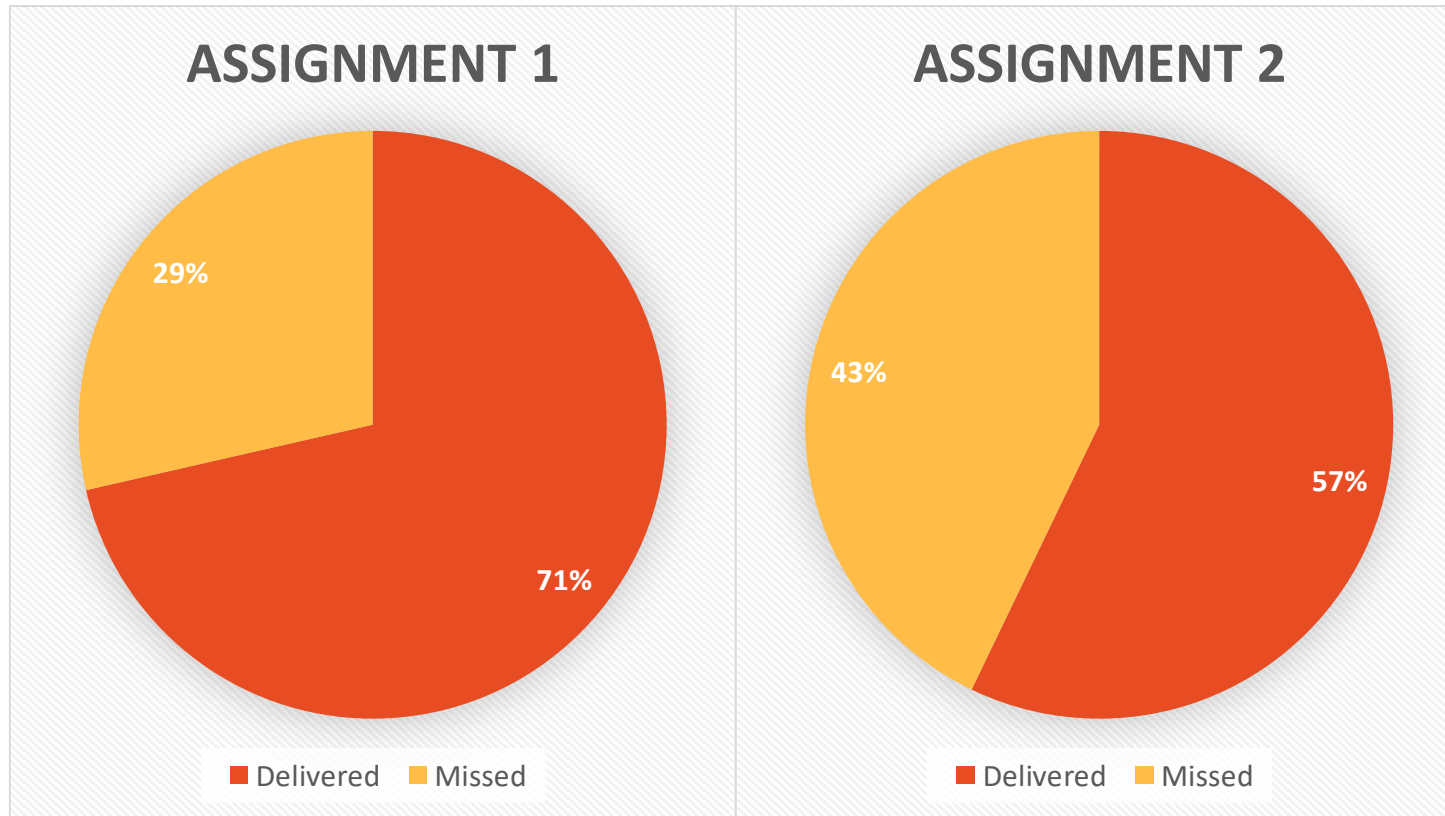
b)  $\{0, 1, 2, 4, 0, 0, \dots\}$

***Due before : 07 – 04 – 2020***

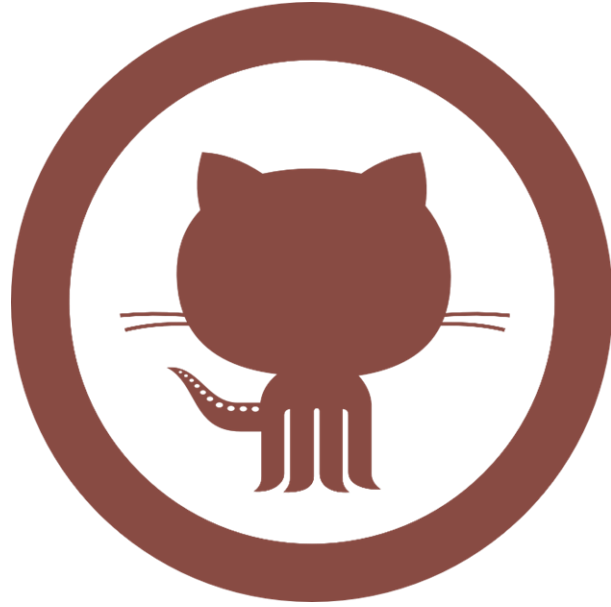
# Past Assignments



## Quick Feedback about past assignments



- Copied reports or code will be *discarded*
- Delayed reports are already *discarded*



Don't forget to pull the lab update from.

<http://github.com/wbadry/mte506>

# END OF Lab 6