Wil Thomason

Cornell University 804.591.7318 Contact Department of Computer Science wbthomason@cs.cornell.edu Information 343 Campus Road https://www.cs.cornell.edu/~wil Ithaca, NY 14853 Research Robotics, integrated task and motion planning, ML for planning, constrained planning, Interests formal methods for robotics, synthesis, motion planning, multi-agent coordination Professional Graduate Research Assistant January 2020 - Present EXPERIENCE VRRG, Department of Computer Science, Cornell University. August 2015 - December 2019 Graduate Research Assistant Robotic Personal Assistants Lab, Department of Computer Science, Cornell University. Software Engineering Intern May 2015 - August 2015 Fluencia, Alexandria, VA. Worked on adding voice recognition for speech practice exercises. Undergraduate Research Assistant August 2014 - July 2015 Department of Computer Science, The University of Virginia. Work with Professor Westley Weimer on automatic software functionality transplantation. Software Development Engineer Intern May 2014 - August 2014 Accounts Client Team, Microsoft, Redmond, WA. Implemented cryptographic operations and network protocol for passwordless login feature in Microsoft Accounts Android app. Software Development Engineer Intern May 2013 - August 2013 Xbox LIVE Cloud Security Team, Microsoft, Redmond, WA. Designed and implemented a service for real-time logging and auditing of security records in Xbox LIVE. Initiated and completed a rewrite of an internal library to improve performance and provide a better API. Undergraduate Research Assistant January 2013 - May 2014 Department of Computer Science, The University of Virginia. Work with Professor Gabriel Robins on real-time localization of objects using passive RFID tags. **EDUCATION** Cornell University, Ithaca, NY Present Ph.D. in Computer Science. Advisor: Hadas Kress-Gazit. Cornell University, Ithaca, NY June 2019 MS in Computer Science. Advisor: Ross A. Knepper. University of Virginia, Charlottesville, VA August 2012 – May 2015 BS (with high distinction) in Computer Science and Mathematics **Outstanding Teaching Assistant Award** AWARDS May 2017 Cornell University Department of Computer Science NDSEG Fellow April 2017 American Society for Engineering Education

March 2017

May 2016

NSF GRFP Fellow

The National Science Foundation

Outstanding Teaching Assistant Award

Cornell University Department of Computer Science

The National Science Foundation

Louis T. Rader Outstanding Education Undergraduate Student May 2015 University of Virginia Department of Computer Science

PEER-REVIEWED CONFERENCE PUBLICATIONS

- 5. Ensuring Safety and Progress for Independent Multi-Robot Teams in Shared Space. Wil Thomason, Claire Liang, Elizabeth Ricci, and Soham Sankaran. WAFR 2020, in submission.
- 4. Automatic Distributed Multi-Agent Coordination of Single-Agent Robot Controllers. Wil Thomason, Abhishek Anand, Greg Morrisett, Ross Knepper. IROS 2020, in submission.
- 3. A Unified Sampling-Based Approach to Integrated Task and Motion Planning. Wil Thomason, Ross Knepper. ISRR 2019.
- Social Momentum: A Framework for Legible Navigation in Dynamic Multi-Agent Environments. Christoforos Mavrogiannis, Wil Thomason, Ross Knepper. HRI 2018.
- 1. Zero-Shot Learning for Unfamiliar Gesture Recognition. Wil Thomason, Ross Knepper. ISER 2016.

JOURNAL PUBLICATIONS

- Automatic Distributed Multi-Agent Coordination of Single-Agent Robot Controllers. Wil Thomason, Abhishek Anand, Greg Morrisett, Ross Knepper. Robotics and Automation Letters. February 2020, in submission.
- An Accurate Real-Time RFID-Based Location System. Kirti Chawla, Christopher McFarland, Gabriel Robins, Wil Thomason. International Journal of Radio Frequency Identification Technology and Applications. July 2016, authors listed in alphabetical order.

Workshop Presentations

- "A Flexible Sampling-Based Approach to Task and Motion Planning." June 23, 2019. RSS 2019 Workshop on Robust Task and Motion Planning
- "Which comes first, the task plan or the motion plan?." June 30, 2018. RSS 2018 Workshop on Exhibition and Benchmarking of Task and Motion Planners. Joint with Ross A. Knepper.
- "Exploiting Heterogeneity in Robot Teams Through a Formalism of Capabilities." July 15, 2017. RSS 2018 Workshop on Heterogeneity and Diversity for Resilience in Multi-Robot Systems
- "Toward Contextual Grounding of Unfamiliar Gestures for Human-Robot Interaction." May 30, 2017. FG 2017: First International Workshop on Adaptive Shot Learning for Gesture Understanding and Production
- "Recognizing Unfamiliar Gestures for Human-Robot Interaction through Zero-Shot Learning." June 19th, 2016. 2nd Workshop on Model Learning for Human-Robot Communication, RSS 2016

TEACHING EXPERIENCE

- CS 4750 (Foundations of Robotics) Cornell University, Fall 2016 & Fall 2017 Graduate TA (syllabus creation, coding project creation and implementation, grading, office hours, occasional lecturing). Senior and graduate-level elective.
- CS 1110 (Introduction to Computing Using Python) Cornell University, Fall 2015 Head graduate TA (coordinating staff, giving review lectures, supervising lab sessions, grading, office hours). Introductory undergraduate CS course.
- ENG 1501 (Introduction to Aerial Robotics) University of Virginia, Fall 2014

Designed and taught 1-credit special-topics undergraduate elective introducing core topics in robotics. Students built and programmed their own quadrotor robots and learned about basic kinematics, control, and perception.

University of Virginia, Spring 2015 CS 4610 (Programming Languages) Undergraduate TA. Senior-level elective.

CS 4710 (Artificial Intelligence) University of Virginia, Spring 2015 Undergraduate TA. Senior-level elective.

CS 4414 (Operating Systems) University of Virginia, Spring 2014 Undergraduate TA (office hours, assignment creation). Senior-level core course.

CS 2150 (Program and Data Representation) University of Virginia, (Fall 2013, Spring 2013, Fall 2014, Spring 2015). Undergraduate TA (office hours, lab supervision, grading). Sophomore-level core course.

OUTREACH Mentor for Black in AI: Advised mentee on Ph.D. application process. 2019–2020

> Reviewer for Black in AI: Reviewed abstracts for BAI workshop. 2017-2019 Expanding Your Horizons: Workshop Organizer/Leader. Spring 2016, 2017, 2018 UVa HS Programming Contest: Organizer/volunteer. Spring 2014, 2015 UVa CS Education Week Ran intro CS workshop. Winter 2014, 2015

SERVICE Reviewer: ICRA (2016, 2019, 2020), IROS (2019), MRS (2019), RO-MAN (2016),

RSS (2019), WAFR (2018), AURO, and SIMPAR (2018).

Departmental Service: Colloquim Czar (2016–2020), Administrative Colloquium

Czar (2016–2019), Ph.D. Mentor Czar (2016–2018)

Programming Languages: C++, Python, Rust, C, CL, Haskell, OCaml, etc. TECHNICAL SKILLS

Technologies: Linux, ROS, OMPL, PyTorch, TensorFlow, Git, CUDA, etc.