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1. a. What is the time constant τ of the following system? (1 pt)

$$\dot{x} + 2x = 0$$

$$\dot{y} + 2\zeta\omega_n\dot{y} + \omega_n^2 y = 0$$

- b. What is the general solution form for the system in 1 a.? (1 pt)

$$y(t) = C_1 e^{p_1 t} + C_2 e^{p_2 t}$$

$$\zeta = 0 \quad \omega_n = \sqrt{2}$$

2. Consider the following system:

$$\ddot{x} + \dot{x} + x = 0$$

- a. What is the natural frequency ω_n ? (1 pt)

$$\omega_n = 1$$

$$\frac{-1 \pm \sqrt{1-4}}{2} = \frac{-1 \pm \sqrt{-3}}{2}$$

- b. What is the damping ratio ζ ? (1 pt)

$$\zeta = 1/2$$

- c. What is the damped natural frequency ω_d ? (1 pt)

$$\omega_d = \omega_n \sqrt{1-\zeta^2} = \sqrt{1/2^2 - 1} = \sqrt{3/4}$$

- c. What are the poles of the system? (1 pt)

$$p_{1,2} = -1/2 \pm j\sqrt{3}/2$$

- d. According to your previous answers, is the system overdamped, critically damped,

underdamped, or undamped? (1 pt)

overdamped

3. Solve the following ODE subject to initial conditions $x(0) = 1$, $\dot{x}(0) = 0$. (3 pts)

$$0 = \sqrt{1} \left(\frac{t}{\sqrt{1}} - C_2 \right) e^{\sqrt{1}t} - \sqrt{1} C_2 e^{\sqrt{1}t} \quad \ddot{x} + x = 0$$

$$0 = \ln(t - \sqrt{1}C_2) \sqrt{1}t - \ln(\sqrt{1}C_2) \sqrt{1}t$$

$$= \ln(t - \sqrt{1}C_2) \sqrt{1}t + \ln(\sqrt{1}C_2) (-\sqrt{1}t) \quad r = \pm \sqrt{1}$$

$$x(t) = C_1 e^{\sqrt{1}t} + C_2 e^{-\sqrt{1}t}$$

$$x(0) = 1 = C_1 e^{\sqrt{1}t} + C_2 e^{-\sqrt{1}t}$$

$$x'(0) = 0 = \sqrt{1} C_1 e^{\sqrt{1}t} - \sqrt{1} C_2 e^{-\sqrt{1}t}$$

$$C_2 = 0$$

$$y(t) = \frac{t}{\sqrt{1}} e^{\sqrt{1}t} + 0$$

$$\ln(1) = \ln(1) \cdot \ln e^{\sqrt{1}t} + \ln(1) \ln e^{-\sqrt{1}t}$$

$$\ln(1) = \ln(1) \sqrt{1}t - \ln(1) \sqrt{1}t$$

$$\frac{t}{\sqrt{1}} - C_2 = C_1$$