$$w(x) = (x-\lambda)/\sqrt{1-x^2}$$

$$p_n(x) = T_{n+1}(x) - T_{n+1}(x) T_n(x)$$

$$p_n(x) = T_{n+1}(x) - T_n(x)$$

$$T_n(x) = q_n, 7.3$$

$$K_n(x,y) = \sum_{j=0}^{n} \frac{P_j(x)P_j(y)}{\langle P_j(x)P_j(y)\rangle}$$
 Christoffel-Darboux

$$P_n(x) = Const \cdot K_n(x,\lambda)$$

$$r(x) = (x-\lambda_1)...(x-\lambda_d)/\sqrt{1-x^2}$$

$$P_{n}(x) = \sum_{k=0}^{d} \beta_{n_{j}k} T_{k+n}(x)$$

$$(x-\lambda_{j}) \dots (x-\lambda_{d})$$

$$p_n(x) poly \Rightarrow \sum_{k=0}^d \overline{P}_{n,k} T_{n+k}(\lambda_j) = 0 \quad \forall \quad j=1,...,d$$

$$\begin{bmatrix} T_{n}(\lambda_{1}) & T_{n+1}(\Omega_{1}) & \dots & T_{n+d}(\lambda_{1}) \\ T_{n}(\lambda_{2}) & T_{n+1}(\Omega_{2}) & \dots & T_{n+d}(\lambda_{2}) \\ T_{n}(\lambda_{3}) & T_{n+1}(\Omega_{d}) & \dots & T_{n+d}(\lambda_{d}) \\ T_{n}(\lambda_{d}) & T_{n+1}(\Omega_{d}$$

Cramers Rule: Brij = ith moner of matrix
of matrix Pn(x) = Z of motor of motor of motor of motor of The control of the co Paper in 2016: relates value of Mrs kond of determinent to Selberg integral:  $T_n(\lambda_i)$   $T_{n+1}(\lambda_i)$  ...  $T_{n+d}(\lambda_i)$ det Tn(22) Tn+1(22) --- Tn+d (22)

Tn (2d) Tn+1(20) Tn+d (26)

Tn(x) Tn+1(x) --- Tn+d (x) = const •  $\prod (x-\lambda_i) \prod (\lambda_i-\lambda_j) \int_{--}^{\infty} \frac{1}{\prod (y_i-x_i) \prod (y_k-\lambda_j) \prod (y_i-y_{ik})} \frac{1}{(y_i-y_i)} \frac{1}$ exciting that they dow up.

Relation to some sort of Gamena functions or bushing.

Slater determinant Tr. (xg) ... Tr. (xg) Cool and look at...  $p(x) = S(\lambda_1, ..., \lambda_d, x; n, n+d) / (x-\lambda_1)...(x-\lambda_d)$ Does it satisfy any differential equations?  $(-x^2) T_n(x) - x T_n(x) = -n^2 T_n(x)$  $\sum_{j=0}^{3} \left[ \left( 1 - x_{j}^{2} \right) \frac{\partial^{2}S}{\partial x_{j}^{2}} - x_{j} \frac{\partial S}{\partial x_{j}} \right] = \left( -\sum_{j=0}^{3} n_{j}^{2} \right) S$  $\left( \frac{1}{1} \left( (-x_{j}^{2}) \frac{\partial^{2}}{\partial x_{j}} - x_{j} \frac{\partial}{\partial x_{j}} \right) \cdot S = \frac{1}{1} \left( -n_{j}^{2} \right) \cdot S$  $\sum_{i=1}^{n} \frac{1}{2} S(\vec{x}; \vec{n} + \vec{e}_j) + \frac{1}{2} S(\vec{x}; \vec{n} - \vec{e}_j) = (\sum_{i=1}^{n} x_i) S(\vec{x}; \vec{n})$ S(X, n, n+1, n+z, ..., n+d)



