## Eigenvalues and Eigenvectors

Recap: If A is an nxn matrix, then an eigenvector of A with eigenvalue  $\lambda$  is a non-zero vector  $\vec{V}$ Setisfying  $A\vec{V} = \lambda\vec{V}$  (equiv.  $(A-\lambda I)\vec{V} = \vec{0}$ )

Theorem: The eigenvalues are all roots of the characteristic polynomial p(x) = det (A-xI)

Quest: Who cares?

- · physics and engineering
- mathematics
  data science.

What are eigenvalues?

- · algebraic description < last time

## Geometric Description:

Remember that an non matrix A describes a linear transformation of n-dimensional space

2x2 matrix + transformation of x, y-plane 3x3 matrix + > transferration of 3d-space x,4,2- space

and so on

$$p(x) = det(A-xI) = det\left[\begin{bmatrix} \frac{1}{12} & -\frac{1}{12} \\ \frac{1}{12} & \frac{1}{12} \end{bmatrix} - x\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right)$$

$$= \left(\frac{1}{12} \times \right)^2 - \left(-\frac{1}{2}\right)$$

$$\left(\frac{1}{12} - x\right)^2 + \frac{1}{2} = 0 \Rightarrow \left(\frac{1}{12} - x\right)^2 = -\frac{1}{2}$$

$$\Rightarrow x = \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}}$$

Eigenvalues are 
$$\lambda = \frac{1}{12} + \frac{1}{12}$$
:
$$\lambda = \frac{1}{12} - \frac{1}{12}$$

For rotations we will always see the presence of non-real eigenvalus.

Ex: 
$$A = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$
. Try to find both the eigenvalues and circumsectors

Eigenvalues are roots of

$$p(x) = det(A - xI) = det\left(\begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} - x\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right)$$

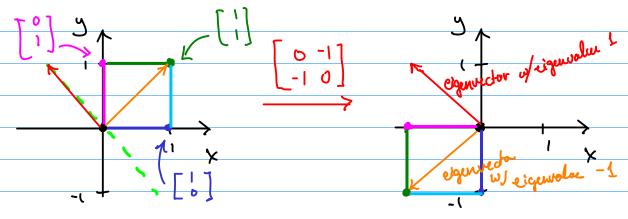
$$= det\left(\begin{bmatrix} -x \\ -1 \end{bmatrix} - x\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right)$$

$$= det\left(\begin{bmatrix} -x \\ -1 \end{bmatrix} - x\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right)$$

Eigenvectors?  $A - \lambda I = 0$ 

Figure  $A = 1$ :  $A$ 

specific eigenvector: [-1]



Reflection a cross line y=-x

exactly be some as the direction of
the eigenvelve I

orthogonal to the direction of the eigenvelve
with eigenvelve -1

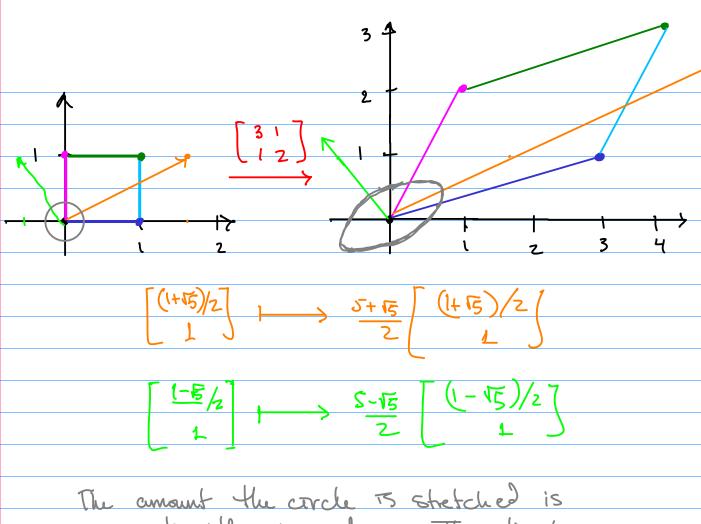
$$\frac{E_{\times}}{}$$
:  $A = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ 

eigenvectors and eigenvolues?

Chear poly: 
$$(3-x)(2-x)-1 = x^2-5x+6-1$$
  
=  $x^2-5x+5$ 

$$\lambda = \frac{5 \pm \sqrt{25 - 4.15}}{2} = \frac{5 \pm \sqrt{5}}{2}$$

Eigenvectors  $\omega$ /eigenvalue  $\frac{5+15}{2}$ :  $\frac{5}{2}$   $\frac{(1+15)c}{2c}$   $\frac{5-15}{2}$ :  $\frac{5}{2}$   $\frac{(1+15)c}{2c}$   $\frac{5+5}{2}$ 



The amount the circle is stretched is given by the eigenvalue. The direction it is stretched is the eigenvector!

Geometric Merpetation:

The transformation stretches, shrowes, reflects,...

The the directions of the eigenvectors!

Two notable exceptions:

· when eigenvolues are not real

- indicative of the presence of totation

when eigenvolues are repeated but

the matrix is not diagrand

- indicative of the presence of Shear!

$$\underline{\mathsf{Ex}}: A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$
 eigenvalues = 1, 1  
eigenvectors =  $\begin{cases} \binom{c}{0} & 1 \\ 0 & 1 \end{cases}$ 

## MATLAS commands:

det(A) — colculatio the determinant
eig(A) — calculates the eigenvalues

[P,D] = eig(A) — set > P = motrix whose columns

are the eigenvectors and

D to a dragonal matrix whose

values are the corresponding

eigenvalues