## Determinants

## 2x2 objerminants:

A = ad-bc (different notation for same thing)

$$E_{\times}: A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$E_{X}$$
:  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$   $det(A) = 1.4 - 2.3 = 4-6 = (-2)$ 

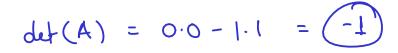
What is the determinant good for?

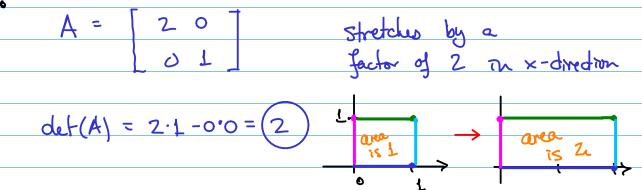
(1) 
$$det(A) \neq 0 \Leftrightarrow A^{-1} exists!$$

$$A = \begin{bmatrix} a b \\ c d \end{bmatrix} \implies A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d-b \\ -c a \end{bmatrix}$$

• 
$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ & & \cos \theta \end{bmatrix}$$
 rotation

$$dut(A) = \cos^2\theta + \operatorname{sm}^2(\theta) = (1) !!$$

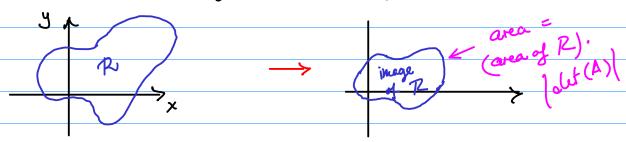




Theorem: Let A be a 2x2, Mun

(det(A)) = area of the mage of the unit square

In fact, for any region  $R \subseteq \mathbb{R}^2$ , area of A unage of  $R = (area of R) \cdot det(A)$ 

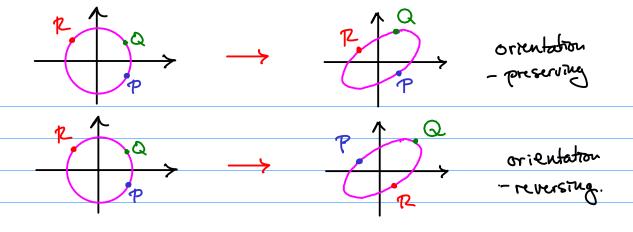


Note: if we rotate, it doesn't change the area so it makes sense that det(A)=1 for rotation motrices!

Quest: where does the sign of the determinant come from?

Juf: A 2x2 matrix A is orrentation-preserving if sends a circle with three points to a curve with those points in the same order.

Otherwise it is errentation-reversing



Theorem: Suppose A 2x2 matrix and det(A) ≠0

Then det(A) >0 ⇔ A 73 or rentation - preserving.

What kind of transformation is A?

|det(A) =1 >> transformation preserves area

reflection rotation

det(A) <0 ) transformation does not porcerve

How to calculate determinants:

$$A = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \end{bmatrix}$$

$$\begin{bmatrix} \alpha_{21} & \alpha_{22} & \alpha_{23} \\ \alpha_{31} & \alpha_{32} & \alpha_{33} \end{bmatrix}$$

$$\begin{bmatrix} \alpha_{31} & \alpha_{32} & \alpha_{33} \\ \alpha_{32} & \alpha_{33} \end{bmatrix}$$

Do a row expansion or column expansion:

$$det(A) = a_{11} \cdot det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \cdot det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \cdot det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$

$$= a_{11} \cdot (a_{22}a_{33} - a_{32}a_{23}) - a_{12} \cdot (a_{21}a_{33} - a_{23}a_{31}) + a_{13} \cdot (a_{21}a_{32} - a_{22}a_{31})$$

$$E_{\times}: A = \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 2 & 1 & 0 \end{bmatrix}$$

$$= 1 \cdot (-2) - 1 (-4) + (-1)(-2) = 4$$

$$\frac{E_{\times}: A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & -1 & 1 \end{bmatrix}}{\begin{bmatrix} 0 & 2 & 1 \end{bmatrix}} = \frac{1}{2}$$

$$dut(A) = 1 \cdot dut \begin{bmatrix} -1 & 1 \\ 2 & 1 \end{bmatrix} - 2 \cdot dut \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} + 3 \cdot dut \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix}$$

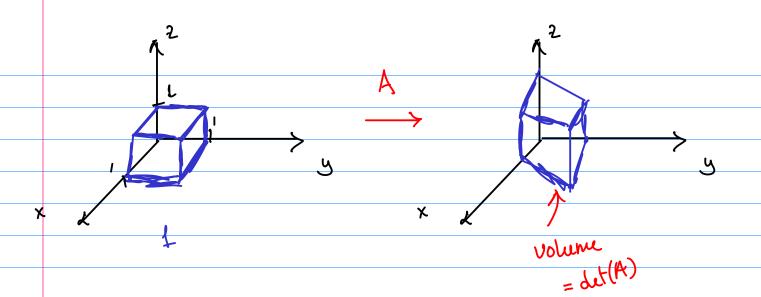
$$= -3 - 2 + 6 = (1)$$

$$A = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \end{bmatrix}$$

$$\begin{bmatrix} \alpha_{21} & \alpha_{22} & \alpha_{23} \end{bmatrix}$$

$$\begin{bmatrix} \alpha_{31} & \alpha_{32} & \alpha_{33} \end{bmatrix}$$

$$\frac{Ex}{A} = \begin{bmatrix} 3 & 100 & 4 \\ 0 & 7 & 21 \\ 0 & 0 & 3 \end{bmatrix} \quad det(A) = ?$$



## Properties of Determanents:

- · A, B be nxn matrices · c EC complex number
- \* (1) A is muertible if and only if det (A) \$0
  - (2) det(AB) = det(A) det(B)
  - (3) def (AB) = def (BA)
  - (4) if A-1 exists, Hun det (A-1) = det(A)
  - (5) the system of linear equations AX = To has a unique solution  $\Leftrightarrow$  det(A)  $\neq \delta$ .

Def: An non matrix A is called singular of det (A) = 0. Otherwise A is called non-snaywar.

$$Ex:$$

$$A = \begin{bmatrix} 16 & 02 \\ 311707077 & dut(A) = ? \\ 210907 & dut(A) = ? \end{bmatrix}$$

Cofactor matrix:

$$\begin{bmatrix} a & b & -1 \\ c & d & \end{bmatrix} = \frac{1}{aal-bc} \cdot \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Cofeator matrix

Generalize Mis formula for larger matrices

Def: The cofactor matrix cof(A) of A is the nxn matrix whose ijth entry is

 $cof(A)_{ij} = (-1)^{i+j} det(A_{ij})$   $A_{ij} = (n-1) \times (n-1)^{i+1} modrix dotorned by deletry :th row$ and jeth column

Ex: 
$$A = \begin{bmatrix} 3 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix}$$
  $cof(A) = \begin{bmatrix} -1 & -1 & 1 \\ +1 & 3 & -3 \\ 1 & -1 & -1 \end{bmatrix}$ 

Theorem: A-L = lat(A) Cof(A) T

