# Financial Econometrics Econ 40357 ARIMA Part 2: Autoregressive Models

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# Autoregressive (AR) models.

These are models with more durable, persistent dependence over time.

Let  $\epsilon_t \stackrel{\textit{iid}}{\sim} (0, \sigma_\epsilon^2)$ , and  $|\rho| < 1$ . Then **the AR(1) model** is

$$y_t = a + \rho y_{t-1} + \epsilon_t$$

where

$$\mathsf{E}(y_t) = \mu = \frac{a}{(1-\rho)}, \ \mathsf{Var}(y_t) = \frac{\sigma_e^2}{(1-\rho^2)}, \ \rho(y_t, y_{t-k}) = \rho^k$$

Note:  $a = \mu (1 - \rho)$ , which means we can also write it as

$$y_t = \mu (1 - \rho) + \rho y_{t-1} + \epsilon_t$$

# The MA representation of the AR(1)

The AR(1) can also be represented as an  $MA(\infty)$ .

$$y_{t} = a + \rho \underbrace{(a + \rho y_{t-2} + \epsilon_{t-1})}_{y_{t-1}} + \epsilon_{t}$$

$$= a + \rho a + \rho^{2} \underbrace{(a + \rho y_{t-3} + \epsilon_{t-2})}_{y_{t-2}} + \rho \epsilon_{t-1} + \epsilon_{t}$$

$$= a + \rho a + \rho^{2} a + \epsilon_{t} + \rho \epsilon_{t-1} + \rho^{2} \epsilon_{t-2} + \rho^{2} y_{t-3}$$

$$\vdots$$

$$= \underbrace{a \left(1 + \rho + \rho^{2} + \rho^{3} + \cdots\right)}_{a/(1-\rho)} + \epsilon_{t} + \rho \epsilon_{t-1} + \rho^{2} \epsilon_{t-2} + \rho^{3} \epsilon_{t-3} + \cdots$$

$$= \frac{a}{1-\rho} + \epsilon_{t} + \rho \epsilon_{t-1} + \rho^{2} \epsilon_{t-2} + \rho^{3} \epsilon_{t-3} + \cdots$$

What is the mean  $E(y_t)$ ?

$$E(y_t) = E\left(\frac{a}{1-\rho} + \epsilon_t + \rho\epsilon_{t-1} + \rho^2\epsilon_{t-2} + \rho^3\epsilon_{t-3} + \cdots\right)$$

$$= \left(\frac{a}{1-\rho} + E\epsilon_t + \rho E\epsilon_{t-1} + \rho^2 E\epsilon_{t-2} + \rho^3 E\epsilon_{t-3} + \cdots\right)$$

$$= \frac{a}{1-\rho}$$

What is the Variance  $Var(y_t)$ ?

$$\begin{split} \sigma_y^2 &= \operatorname{Var}(y_t) = \operatorname{E}\left(\varepsilon_t + \rho\varepsilon_{t-1} + \rho^2\varepsilon_{t-2} + \rho^3\varepsilon_{t-3} + \cdots\right)^2 \\ &= \operatorname{E}\left(\varepsilon_t^2 + \rho^2\varepsilon_{t-1}^2 + \rho^4\varepsilon_{t-2}^2 + \cdots + 2\rho\varepsilon_t\varepsilon_{t-1} + 2\rho^2\varepsilon_t\varepsilon_{t-2} + \cdots\right) \\ &= \left(\operatorname{E}\varepsilon_t^2 + \rho^2\operatorname{E}\varepsilon_{t-1}^2 + \rho^4\operatorname{E}\varepsilon_{t-2}^2 + \cdots + 2\rho\operatorname{E}\varepsilon_t\varepsilon_{t-1} + 2\rho^2\operatorname{E}\varepsilon_t\varepsilon_{t-2} + \cdots\right) \\ &= \sigma_\varepsilon^2\left(1 + \rho^2 + \rho^4 + \cdots\right) \\ &= \frac{\sigma_\varepsilon^2}{1 - \rho^2} \end{split}$$

What is the autocorrelation function? First, write the AR(1) in deviations from the mean form,

$$y_{t} = \mu (1 - \rho) + \rho y_{t-1} + \epsilon_{t}$$
  
$$y_{t} - \mu = \rho (y_{t-1} - \mu) + \epsilon_{t}$$

Then,

$$\gamma_{1} = \operatorname{Cov}(y_{t}, y_{t-1}) = \operatorname{E}(y_{t} - \mu)(y_{t-1} - \mu)$$

$$= \operatorname{E}(\rho(y_{t-1} - \mu) + \epsilon_{t})(y_{t-1} - \mu)$$

$$= \rho \underbrace{\operatorname{E}(y_{t-1} - \mu)^{2}}_{\operatorname{Var}(y_{t-1})} + \underbrace{\operatorname{E}(\epsilon_{t}(y_{t-1} - \mu))}_{0}$$

$$= \rho \operatorname{Var}(y_{t}) = \rho \sigma_{y} \sigma_{y}$$

Hence,

$$\rho\left(y_{t},y_{t-1}\right)=\rho$$

$$\begin{split} \gamma_2 &= \operatorname{Cov}\left(y_t, y_{t-2}\right) = \operatorname{E}\left(y_t - \mu\right) \left(y_{t-2} - \mu\right) \\ &= \operatorname{E}\left(\rho\left(y_{t-1} - \mu\right) + \epsilon_t\right) \left(y_{t-2} - \mu\right) \\ &= \rho \underbrace{\operatorname{E}\left(y_{t-1} - \mu\right) \left(y_{t-2} - \mu\right)}_{\gamma_1} + \underbrace{\operatorname{E}\left(\epsilon_t\left(y_{t-2} - \mu\right)\right)}_{0} \\ &= \rho \gamma_1 \\ &\rho\left(y_t, y_{t-2}\right) = \frac{\rho \gamma_1}{\sigma_y \sigma_y} = \frac{\rho \rho \sigma_y \sigma_y}{\sigma_y \sigma_y} = \rho^2 \end{split}$$

We can infer that

$$\rho\left(\mathbf{y}_{t},\mathbf{y}_{t-k}\right)=\rho^{k}$$

#### AR(1) forecasts

$$E_t(\tilde{y}_{t+1}) = \rho \tilde{y}_t$$

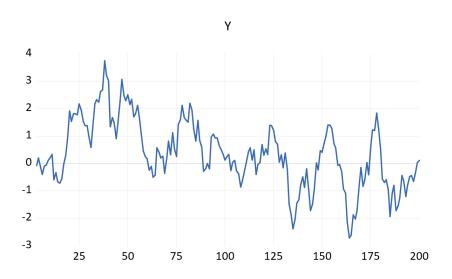
$$E_t(\tilde{y}_{t+2}) = \rho E_t(\tilde{y}_{t+1}) = \rho^2 \tilde{y}_t$$

Hence,

$$E_t(\tilde{\mathbf{y}}_{t+k}) = \rho^k \tilde{\mathbf{y}}_t$$

Try it out on daily stock returns.

# Realization of an AR(1) with $\rho = 0.96$



# How to generate in Eviews

```
'Generate white noise process
series e = nrnd
'Generate persistent AR(1)
smpl @first @first
series sto = 0 'Initial conditions
smpl @first+1 @last
series sto = .96*sto(-1)+.5*e 'Recursion
series v = sto
delete sto
(To get impulse response: Quick, estimate VAR)
(arima_models.wf1 and pgm)
```

#### Impulse Response Function

The impulse response function traces the effect of a one time, one-standard deviation shock today  $\epsilon_t = \sigma_\epsilon$ , on the current and all future values  $y_t, y_{t+1}, y_{t+2}, \dots$  Stationary processes will revert to their

mean values. Let's analyze as deviations from the mean (set  $\mu=0$ ). AR(1):  $y_t=\rho y_{t-1}+\epsilon_t$ ,  $0<\rho<1$ .

$$y_t = \epsilon_t$$

$$y_{t+1} = \rho y_t = \rho \epsilon_t$$

$$y_{t+2} = \rho y_{t+1} = \rho^2 \epsilon_t$$

$$y_{t+k} = \rho^k \epsilon_t$$

Another representation of impulse response. MA representation (mean suppressed  $\mu=0$ ),

$$y_t = \epsilon_t + \rho \epsilon_{t-1} + \rho^2 \epsilon_{t-2} + \rho^3 \epsilon_{t-3} + \cdots$$

One time shock  $\epsilon_t$ , with all other shocks shut down,  $\epsilon_k = 0$ ,  $k \neq t$ 

$$y_t = \epsilon_t$$

$$y_{t+1} = \rho \epsilon_t$$

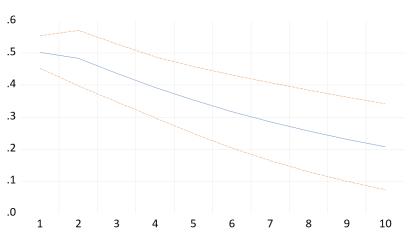
$$y_{t+2} = \rho^2 \epsilon_t$$

and so on.

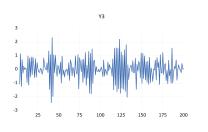
Later, I will show you how to generate implulse responses in Eviews.

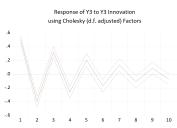
## Impulse response of AR(1)

Response of Y to Y Innovation using Cholesky (d.f. adjusted) Factors



# AR(1) with negative $\rho$

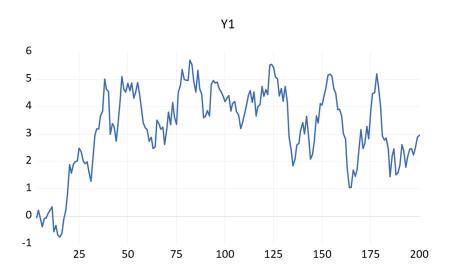




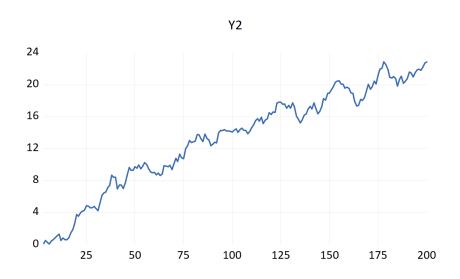
### **Unit Root Nonstationarity**

- Why  $|\rho| <$  1 is necessary for stationarity?
- It is usually the case that  $0 < \rho < 1$  in economics and finance (persistence).
- What happens to the mean and the variance of  $y_t$  when  $\rho = 1$ ?
- What happens to the impulse response function when  $\rho=1$ ? (permanent effect).

#### Realization of a driftless Random Walk



#### Random walk with drift



# The AR(2) model. Back to Stationary Models.

Let  $\epsilon_t \stackrel{\textit{iid}}{\sim} (0, \sigma_\epsilon^2)$  . The second-order autoregressive model (AR(2)) is

$$y_t = a + \rho_1 y_{t-1} + \rho_2 y_{t-2} + \epsilon_t$$

and is stationary if  $|\rho_1+\rho_2|<$  1. Assume stationarity, take expectations

$$\mu_y = a + \rho_1 \mu_y + \rho_2 \mu_y$$
$$a = \frac{\mu_y}{1 - \rho_1 - \rho_2}$$

Computing variance and autocovariances by hand is too complicated. It involves taking variance and first-order covariance

$$\begin{array}{rcl} \sigma_y^2 & = & \rho_1^2 \sigma_y^2 + \rho_2^2 \sigma_y^2 + 2\rho_1 \rho_2 \gamma_1 + \sigma_\epsilon^2 \\ \\ \gamma_1 & = & \rho_1 \sigma_y^2 + \rho_2 \gamma_1 \rightarrow \gamma_1 = \frac{\rho_1 \sigma_y^2}{1 - \rho_2} \end{array}$$

Then you must to solve these two equations for  $\sigma_y^2$  and  $\gamma_1$ .

# AR(2) Impulse Response Function

AR(2) with  $\mu = 0$  (or in deviation from mean form).

$$y_t = \rho_1 y_{t-1} + \rho_2 y_{t-2} + \epsilon_t$$

Let  $y_0 = y_{-1} = 0$ , One-time shock at time 1,  $\epsilon_1$ , with all other shocks shut down. Trace effect recursively

$$y_{1} = \epsilon_{1}$$

$$y_{2} = \rho_{1}y_{1} = \rho_{1}\epsilon_{1}$$

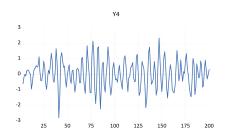
$$y_{3} = \rho_{1}y_{2} + \rho_{2}y_{1} = (\rho_{1}^{2} + \rho_{2})\epsilon_{t}$$

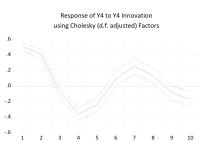
$$y_{4} = \rho_{1}y_{3} + \rho_{2}y_{2} = \rho_{1}(\rho_{1}^{2} + 2\rho_{2})\epsilon_{1}$$

and so on Is possible to get **cyclical** impulse responses.

# Realization and Impulse Response AR(2)

$$\rho_1 = 0.8, \rho_2 = -0.8$$





#### AR(2) forecasts

Form the forecasts and input recursively.

$$E_{t}(\tilde{y}_{t+1}) = \rho_{1}\tilde{y}_{t} + \rho_{2}\tilde{y}_{t-1}$$

$$E_{t}(\tilde{y}_{t+2}) = \rho_{1}(E_{t}(\tilde{y}_{t+1})) + \rho_{2}\tilde{y}_{t}$$

$$E_{t}(\tilde{y}_{t+3}) = \rho_{1}(E_{t}(\tilde{y}_{t+2})) + \rho_{2}E_{t}(\tilde{y}_{t+1})$$

#### **Extensions**

- No need to stop at AR(2). Can add more and more lags.
- In MA model, can add more and more lagged shocks.
- Oifference between MA and AR. AR is dependence across time of observations. MA is dependence across time of shocks.
- MA memory is finite
- AR memory is infinite (but diminishes exponentially)
- Can combine MA and AR. Here's ARMA(1,1)

$$y_t = a + \rho y_{t-1} + \epsilon_t + \theta_1 \epsilon_{t-1}$$