## Econ 204 – Problem Set 5

Due Friday, August 14

1. Let be X the set of at most second degree polynomials and  $T: X \to X$  a linear transformation defined by T(f(x)) = 2f(x) + xf'(x). Compute the matrix representation of T with respect to the basis  $V = \{1, x, x^2\}$ , compute  $\ker T$ , characterize  $X/\ker T$ , compute the eigenvalues and the corresponding eigenvectors of T. Is T diagonalizable?

**Solution** For the matrix representation note that

$$T(1) = 3$$
$$T(x) = 3x + 1$$
$$T(x^{2}) = 4x^{2} + 1$$

hence

$$crd_V(T(1)) = \begin{pmatrix} 3\\0\\0 \end{pmatrix}$$
$$crd_V(T(x)) = \begin{pmatrix} 1\\3\\0 \end{pmatrix}$$
$$crd_V(T(x^2)) = \begin{pmatrix} 1\\0\\4 \end{pmatrix}$$

hence

$$Mtx_V(T) = \begin{pmatrix} 3 & 1 & 1 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{pmatrix}$$

For the kernel of T compute  $\ker Mtx_V(T) = \{x \in \mathbb{R}^3 : Mtx_V(T)x = 0\}$ . Solving this linear system gives the only solution is the zero vector, hence  $\ker Mtx_V(t) = \{0\}$  is just the zero vector, therefore  $\ker T = \{0\}$  is just the constant zero function.

Since the kernel of T is just the zero element of X, then  $[x] = \{x\}$  itself only.

For the eigenvalues of T compute the eigenvalues of  $Mtx_V(t)$ , hence the roots of the characteristic polynomial of

$$Mtx_V(T) - \lambda I = \begin{pmatrix} 3 - \lambda & 1 & 1\\ 0 & 3 - \lambda & 0\\ 0 & 0 & 4 - \lambda \end{pmatrix}$$

what is  $\lambda_1 = 3$  with multiplicity of two and  $\lambda_2 = 4$  with multiplicity of one.

The eigenvectors of  $Mtx_V(T)$  corresponding to  $\lambda_1 = 3$  solve the equation

$$(A-3I)x = 0$$
 hence has the form  $E_3 = \left\{ \begin{pmatrix} a \\ 0 \\ a \end{pmatrix} : a \in \mathbb{R} \right\}$ . Hence the corre-

sponding eigenvectors of T are the polynomials  $E_3 = \{f(x) = a + ax^2 : a \in \mathbb{R}\}$ . And the eigenvectors of  $Mtx_V(T)$  corresponding to  $\lambda_2 = 4$  solve the

equation 
$$(A - 4I)x = 0$$
 hence has the form  $E_4 = \left\{ \begin{pmatrix} a \\ 0 \\ 0 \end{pmatrix} : a \in \mathbb{R} \right\}$  hence

the corresponding eigenvectors of T are the polynomials  $E_4 = \{f(x) = a : a \in \mathbb{R}\}.$ 

Finally since the eigenspace corresponding the eigenvalue with multiplicity two has a dimension of one, since  $dim(E_3) = 1$  then T is not diagonalizable.

2. For the following functions, determine at what points the derivative exists, and if the derivative function is continuous (you may use that the derivative of  $\sin x$  is  $\cos x$ ):

$$f(x) = \begin{cases} x \cdot \sin\left(\frac{1}{x}\right) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}, \quad g(x) = \begin{cases} x^2 \cdot \sin\left(\frac{1}{x}\right) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$$

**Solution** For  $x \neq 0$  we can find the derivatives of f and g using the simple properties of derivatives:

$$f'(x) = \sin\frac{1}{x} - \frac{1}{x}\cos\frac{1}{x}, \quad g'(x) = 2x\sin\frac{1}{x} - \cos\frac{1}{x}$$

At x=0 we use directly the definition of the derivative. Note that for  $h \neq 0$  we have

$$\frac{f(h) - f(0)}{h} = \sin \frac{1}{h}, \quad \frac{g(h) - g(0)}{h} = h \sin \frac{1}{h}$$

Since  $\lim_{h\to 0} \sin\frac{1}{h}$  is not defined, f'(0) is not defined. However, note  $\left|h\sin\frac{1}{h}\right| \leq |h|$  so g'(0) = 0 and the derivative of g exists everywhere. But  $\lim_{x\to 0} \cos\frac{1}{x}$  is not defined, so  $\lim_{x\to 0} g'(x) \neq g'(0)$ , ie g' is not continuous at x=0

3. Let  $f: \mathbb{R} \to \mathbb{R}$  be a differentiable function. Prove that  $f'(\mathbb{R})$ , the image of the derivative function, is an interval (possibly a singleton).

**Solution** To prove the claim it suffices to show that for any  $a, b \in f'(\mathbb{R})$  with a < b, and any  $c \in (a, b)$ , we have  $c \in f'(\mathbb{R})$ . Note that if there are no two distinct values, since f is differentiable we have  $f'(\mathbb{R}) \neq \emptyset$ ; so  $f'(\mathbb{R}) = \{c\}$  and we're done (this occurs if f is a constant function).

Choose  $x_1, x_2$  such that  $f'(x_1) = a, f'(x_2) = b$ , and assume without loss of generality that  $x_1 < x_2$ . Define the function  $g : \mathbb{R} \to \mathbb{R}$  where g(x) = a

f(x) - cx. g is also a differentiable function with g'(x) = f'(x) - x. This implies that g is continuous, hence by the Extreme Value Theorem g attains its minimum (and maximum) on the closed interval  $[x_1, x_2]$ .

Now note that  $g'(x_1) = a - c < 0$ , which says

$$\lim_{h \to 0} \frac{g(x_1 + h) - g(x_1)}{h} < 0$$

So for some h'>0 we have that for every  $0<\varepsilon< h', \frac{g(x_1+\varepsilon)-g(x_1)}{\varepsilon}<0 \implies g(x_1+\varepsilon)-g(x_1)<0 \implies g(x_1+\varepsilon)< g(x_1), \text{ so } g(x_1)$  is not a minimum of  $g([x_1,x_2])$ . A similar argument shows that since  $g'(x_2)=b-c>0, g(x_2)$  is not a minimum either. So g attains its minimum at some  $x_0\in(x_1,x_2)$ , and the same argument implies that  $g'(x_0)=0$ . Thus we have  $f'(x_0)=c\iff c\in f'(\mathbb{R})$ .

**Remark:** Note that we can't use the Intermediate Value Theorem since we can't assume f' is a continuous function.

4. If  $a_0 + \frac{1}{2}a_1 + \dots + \frac{1}{n}a_{n-1} + \frac{1}{n+1}a_n = 0$ , where  $a_0, \dots, a_n$  are real constants, prove that the equation

$$a_0 + a_1 x + \dots + a_{n-1} x^{n-1} + a_n x^n = 0$$

has at least one real root between 0 and 1.

**Solution** Let  $f(x) = a_0x + \frac{a_1}{2}x^2 + \cdots + \frac{a_n}{n+1}x^{n+1}$ . This function is clearly differentiable everywhere, with  $f'(x) = a_0 + a_1x + \cdots + a_{n-1}x^{n-1} + a_nx^n$ . Applying the mean value theorem we have f(1) - f(0) = f'(c)(1-0) for some  $c \in (0,1)$ . Clearly f(0) = 0 and from how the coefficients were constructed we also have f(1) = 0. Thus we must have f'(c) = 0.

5. Compute the second-order Taylor expansion of  $f(x) = \sin^2 x + \cos x \sin x$  around the point  $x_0 = \frac{\pi}{2}$ 

**Solution** The derivatives are

$$f'(x) = \cos^2 x - \sin^2 x + 2\cos x \sin x$$
  
 $f''(x) = 2\cos^2 x - 2\sin^2 x - 4\cos x \sin x$ 

hence  $f'(x_0) = -1$  and  $f''(x_0) = -2$ , therefore

$$f(x) = -1 - \left(x - \frac{\pi}{2}\right) - \left(x - \frac{\pi}{2}\right)^2$$