

ML HW4

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1. 請使用不同的 **Autoencoder model**，以及不同的降維方式(降到不同維度)，討論其 **reconstruction loss & public / private accuracy**。（因此模型需要兩種，降維方法也需要兩種，但 **clustrering** 不用兩種。）

AE models:

A: DNN, 由 6 層 Fully Connected Layer 組成

B: CNN, 由 Convolution/Deconvolution Layer 各 4 層組成

降維方式:

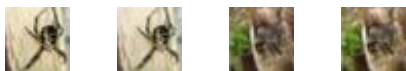
C: PCA, 降至 256 維

D: t-SNE, 降至 2 維

	AC	AD
BC	Loss = 0.00073, Acc = 0.61630	Loss = 0.00068, Acc = 0.73925
BD	Loss = 0.00027, Acc = 0.68149	Loss = 0.00031, Acc = 0.68259

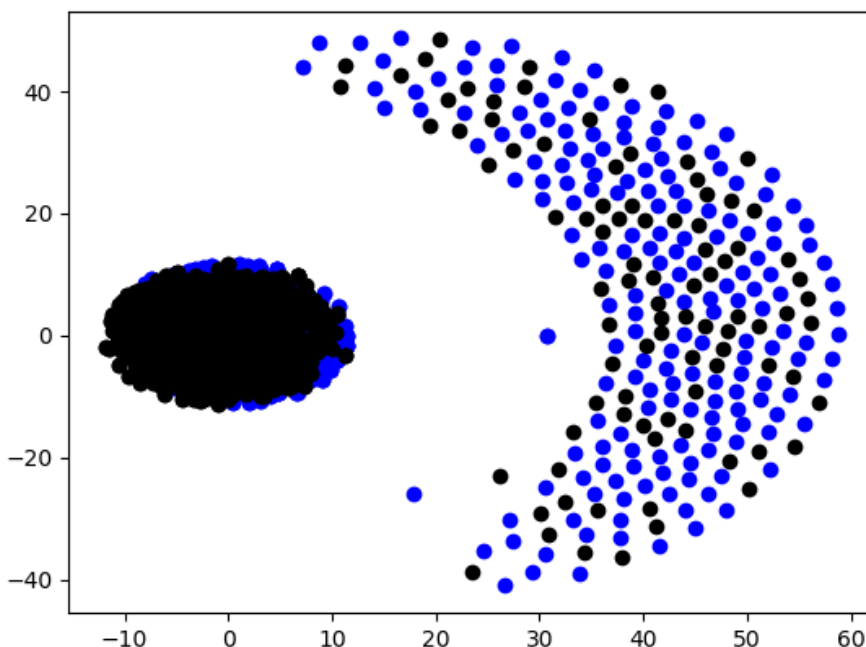
2. 從 **dataset** 選出 2 張圖，並貼上原圖以及經過 **autoencoder** 後 **reconstruct** 的圖片。

下方圖中 左圖為原圖 右圖為經過 autoencoder 後 reconstruct 的圖片



3. 請在二維平面上視覺化 **label** 的分佈。

經 AE, PCA, t-SNE 後之分布圖



4. Refer to math problem

$$1. \begin{matrix} (1, 2, 3) & (4, 8, 5) & (3, 12, 9) & (1, 8, 5) & (5, 14, 2) \\ (7, 4, 1) & (9, 8, 9) & (3, 8, 1) & (11, 5, 6) & (10, 11, 7) \end{matrix} \left. \vphantom{\begin{matrix} (1, 2, 3) \\ (7, 4, 1) \end{matrix}} \right\} \begin{matrix} \mu_x = 5.4 \\ \mu_y = 8 \\ \mu_z = 4.8 \end{matrix}$$

$$(a) \Sigma = \frac{1}{10} \sum_{i=1}^{10} (x_i - \mu)(x_i - \mu)^T = \begin{bmatrix} 12.04 & 0.50 & 3.28 \\ 0.50 & 17.20 & 2.90 \\ 3.28 & 2.90 & 8.16 \end{bmatrix}$$

$$\Sigma = U \Lambda U^T \Rightarrow U = \begin{bmatrix} 0.6166 & -0.6782 & -0.3999 \\ 0.5888 & 0.7344 & -0.3376 \\ 0.5226 & -0.6773 & 0.8521 \end{bmatrix}$$

$$\Rightarrow u_1 = (0.6166, 0.5888, 0.5226)$$

$$u_2 = (-0.6782, 0.7344, -0.0273)$$

$$u_3 = (-0.3999, -0.3376, 0.8521)$$

(b) samples \rightarrow principle components ($= u_i^T x$)

$$u_1 = (0.6166, 0.5888, 0.5226)$$

$$u_2 = (-0.6782, 0.7344, -0.0273)$$

$$u_3 = (-0.3999, -0.3376, 0.8521)$$

(1, 2, 3)	\rightarrow	-1.9393	1.0448	3.0245
(4, 8, 5)	\rightarrow	-4.9583	6.5424	6.1328
(3, 12, 9)	\rightarrow	-9.8871	7.5408	8.9097
(1, 8, 5)	\rightarrow	-6.8081	4.7760	4.5650
(5, 14, 2)	\rightarrow	-7.2112	12.5304	3.9353
(7, 4, 1)	\rightarrow	1.2036	6.7217	4.4012
(9, 8, 9)	\rightarrow	-3.4748	8.1362	12.1544
(3, 8, 1)	\rightarrow	-3.9755	7.3040	2.2016
(11, 5, 6)	\rightarrow	0.9925	8.1234	10.7250
(10, 11, 7)	\rightarrow	-4.0930	11.6033	10.8908

(c) reconstructed error = 0.1894×10^{-2}

2. (a) $A \in \mathbb{R}^{m \times n}$ by $(AB)^T = B^T A^T$,

$$(A^T A)^T = A^T (A^T)^T = A^T A \rightarrow \text{symmetric}$$

$$(A A^T)^T = (A^T)^T A^T = A A^T \rightarrow \text{symmetric}$$

Let λ be a non-zero eigenvalue of $A A^T$, q be eigenvector of λ

$$\Rightarrow (A A^T) \cdot q = \lambda q$$

$$\Rightarrow A^T (A A^T) q = (A^T A) (A^T q) = \lambda (A^T q)$$

$\Rightarrow \lambda$ is an eigenvalue of $A^T A$, $A^T q$ is the eigenvector

$$(A A^T) q = \lambda q \quad \Rightarrow \text{' , ' } q^T q > 0 \text{ and } z^T z \geq 0$$

$$\rightarrow q^T (A A^T) q = \lambda q^T q \quad \Rightarrow \lambda \geq 0, A A^T \text{ is positive semi-definite}$$

$$\rightarrow \lambda = \frac{q^T (A A^T) q}{q^T q} = \frac{z^T z}{q^T q} \quad (z = A^T q) \quad \text{[b/c] } A^T A \text{ is also positive semi-definite}$$

2 (b) Let $X = [x_1 \ x_2 \ \dots \ x_n] \in \mathbb{R}^{m \times n}$

If X can be written as $U D V^T$, $U \in \mathbb{R}^{m \times m}$, $D \in \mathbb{R}^{m \times n}$, $V \in \mathbb{R}^{n \times n}$

U, V are orthogonal. D is diagonal

$$\Rightarrow \hat{X} = \left[\sum_{i=1}^n u_i u_i^T x_1 \quad \sum_{i=1}^n u_i u_i^T x_2 \quad \dots \quad \sum_{i=1}^n u_i u_i^T x_n \right]$$

$$= \sum_{i=1}^n u_i u_i^T [x_1 \ x_2 \ \dots \ x_n] = \sum_{i=1}^n u_i u_i^T X$$

$$= \sum_{i=1}^n u_i u_i^T U D V^T$$

$$\Sigma = \frac{1}{N} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T$$

$$\mu = \frac{1}{n} \sum_{i=1}^n x_i$$

2 (c) Let $X = [x_1 \ x_2 \ \dots \ x_n]$ proof:

$$\begin{aligned} \Sigma &= \frac{1}{N} X X^T = U \Lambda U^T & \text{Trace}(\Phi \Sigma \Phi) &= \text{Trace}(\Phi^T U \Lambda U^T \Phi) \\ \text{Trace}(\Phi^T \Sigma \Phi) & & (\text{let } B &= U^T \Phi) &= \text{Trace}(B^T \Lambda B) \\ &= \frac{1}{N} \text{Trace}(\Phi^T X X^T \Phi) & \text{let } \beta_j &= \sum_{i=1}^k (B_{ji})^2 \\ &= \frac{1}{N} \|\Phi^T X\|_F^2 & B^T B &= \Phi^T U U^T \Phi = I_k \\ &= \frac{1}{N} \sum_{i=1}^N \|\Phi^T x_i\|_F^2 & \Rightarrow \|\beta\|_1 &= \sum_{j=1}^k \beta_j = \text{Tr}(B B^T) = \text{Tr}(I_k) = k \\ &= \frac{1}{N} \sum_{i=1}^N \|\hat{x}_i^{(S)}\|^2 & \Rightarrow \text{Trace}(\Phi \Sigma \Phi) &\geq \min_{\beta \in [0,1]^k} \sum_{j=1}^k \lambda_j \beta_j = \sum_{j=1}^k \lambda_j \\ &\geq \frac{1}{N} \sum_{i=1}^N \|\hat{x}_i^{(PCA)}\|^2 & & \|\beta\|_1 \geq k \\ &\Phi_{\text{opt}} = [\hat{u}_1 \ \dots \ \hat{u}_k] & \text{set } \Phi_{\text{opt}} &= [\hat{u}_1 \ \dots \ \hat{u}_k] \text{ where } \sum \hat{u}_i = \lambda_i \hat{u}_i \\ & & \Rightarrow \text{Trace}(\Phi_{\text{opt}}^T \Sigma \Phi_{\text{opt}}) &= \sum_{j=1}^k \lambda_j \end{aligned}$$

3. Algorithm

$$g_0 = 0$$

For $t = 0, 1, \dots, \frac{T}{k} - 1$

For $k = 1, 2, \dots, K$

$$t = l \cdot K + k$$

Find $f_t \in F$ s.t.

$$\frac{\partial}{\partial \alpha} L(g_{x-1}^1, g_{x-1}^2, \dots, g_{x-1}^{k-1}, g_{x-1}^k + \alpha f_t, g_{x-1}^{k+1}, \dots, g_{x-1}^K) \text{ is minimized}$$

Find α s.t.

$$L(g_{x-1}^1, \dots, g_{x-1}^{k-1}, g_{x-1}^k + \alpha f_t, g_{x-1}^{k+1}, \dots, g_{x-1}^K) \text{ is minimized.}$$

$$L(g_1^1 \dots g_T^K) = \sum_{i=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq j} g_j^k(x_i) - g_j^{\hat{y}_i}(x_i)\right)$$

$$g_j^k(x) = \sum_{t=1}^T a_t^k f_t(x)$$

$$h(x) = \arg\max_k g_T^k(x)$$