Dept. of Biomechatronics Engineering, National Taiwan University
Automated System Design
Lab 2

Complete the assembly of Duckiebot, install the relevant software, set the necessary parameters, and use the remote control to control the motion of forward, backward, left, and right movements.

References

- Lecture note: 220929Duckiebot AGV_v2.pdf and 220929_lab2_v2

- Relevant education resources on the website shown in the lecture note