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第二章 应势方程

$$\Delta u = f \quad \text{in } \Omega \quad \begin{cases} f=0 & \text{Laplace} \\ f \neq 0 & \text{Poisson} \end{cases}$$

u 只为 x 函数

$$\text{Dirichlet} \quad u|_{\partial\Omega} = \varphi$$

$$\text{Neumann} \quad \frac{\partial u}{\partial n}|_{\partial\Omega} = \varphi$$

$$\text{Robin} \quad \frac{\partial u}{\partial n} + \sigma u|_{\partial\Omega} = \varphi$$

Rmk. 波方程 $\partial_t^2 u - \Delta u = f$, 若不随 t 变化, 则此为应势方程

应势方程可视作波动方程的稳态解

§ 2.1 调和函数

def 1. 调和函数

$u: \Omega \rightarrow \mathbb{R}$, 有 2 阶连续偏导数, $\Delta u = 0$

def. u 为调和函数

Recall. 公式

1. $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\int_{\mathbb{R}^n} f(x) dx = \int_0^\infty \int_{\partial B(x_0, r)} f(y) dS(y) dr$$

$$(y = x_0 + rw) = \int_0^\infty \int_{|\omega|=1} f(x_0 + rw) dS(\omega) r^{n-1} dr$$

$$\int_{B_{r_0}(x_0)} f(x) dx = \int_0^{r_0} \int_{|\omega|=1} f(x_0 + rw) dS(\omega) r^{n-1} dr$$

$$2. \frac{d}{dr} \int_{B(x_0, r)} f(y) dy = \int_{\partial B(x_0, r)} f(y) dS(y)$$

def 2. 平均值性质

$u \in C(\bar{\Omega})$, u 满足平均值:

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$$\forall B_r(x) \subseteq \Omega, \text{ 有 } u(x) = \frac{1}{|B_r(x)|} \int_{B_r(x)} u(y) dy \quad ①$$

$$\Omega \in \mathbb{R}^3, |B_r(x)| = \frac{4}{3}\pi r^3$$

u 满足第二类切线:

$$\forall B_r(x) \subseteq \Omega, \text{ 有 } u(x) = \frac{1}{|\partial B_r(x)|} \int_{\partial B_r(x)} u(y) dS(y) \quad ②$$

$$\Omega \in \mathbb{R}^3, |\partial B_r(x)| = 4\pi r^2, u(x) = \frac{1}{4\pi} \int_{|w|=1} u(x+r w) dw$$

claim: ① \Leftrightarrow ②

② \Rightarrow ①:

$$\begin{aligned} \forall B_r(x) \subseteq \Omega, \int_{B_r(x)} u(y) dy &= \int_0^r \left(\int_{\partial B(x,p)} u(y) dS(y) \right) dp \\ &\stackrel{②}{=} \int_0^r |\partial B(x,p)| u(x) dp \\ &= u(x) \int_0^r |\partial B(x,p)| dp = u(x) |\partial B(x,r)| \Rightarrow ① \end{aligned}$$

$$(\text{注: } |\partial B(x,r)| = \int_0^r |\partial B(x,p)| dp)$$

$$\forall B_r(x) \subseteq \Omega, |B_r(x)| u(x) = \int_{B_r(x)} u(y) dy$$

$$\exists r \text{ 使 } \forall B_r(x) \subseteq \Omega, |\partial B(rw)| u(x) = \int_{\partial B(x,r)} u(y) dS(y) \Leftrightarrow ②$$

thm 1. 调和函数 \Rightarrow 平均值

$u \in C^2(\Omega)$, 为 Ω 上调和函数, 对任一 $B_r(x) \subseteq \Omega$,

$$u(x) = \frac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} u(y) dS(y)$$

pr: $\Delta u = 0$. in Ω $\forall B_r(x) \subseteq \Omega$

$$0 = \int_{B_r(x)} \Delta u dy = \int_{B_r(x)} \operatorname{div}(\nabla u) dy = \int_{\partial B(x,r)} \nabla u \cdot \vec{n} dS(y)$$

$$= \int_{|y-x|=r} \nabla u(y) \cdot \frac{y-x}{r} dS(y)$$

$$y=x+r w \quad u \cdot \nabla u (x+r w) r^n dw \quad (u \text{ 在球面上的面积元})$$

$$= r^{n-1} \int_{|w|=1} \frac{d}{dr} (u(x+r w)) dw$$

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$$\begin{aligned} &= r^{n-1} \frac{d}{dr} \int_{|w|=1} u(x+rw) dw \\ \Rightarrow &\forall r, \int_{|w|=1} u(x+rw) dw = \int_{|w|=1} u(x) dw = |\partial B(0,1)| u(x) \\ \text{to } &u(x) = \frac{1}{|\partial B(x,r)|} \int_{|w|=1} u(x+rw) dw \\ &= \frac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} u(y) dS(y) \end{aligned}$$

Thm 2. 平均值 \Rightarrow 润滑、光滑

$u \in C(\Omega)$, 则 $\forall B_r(x) \subset \Omega$,

$$u(x) = \frac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} u(y) dS(y)$$

则 u 光滑且为润和函数

Recall 看书。

$$(f+g)(x) \stackrel{\text{def.}}{=} \int f(x-y) g(y) dy$$

f, g 中若一者光滑，则 $(f+g)(x)$ 光滑

pr.: $\exists \varphi \in C_0^\infty(B_1(0))$ (在一个零集外恒为0)

$$\int_{\mathbb{R}^n} \varphi(x) dx = 1 = \int_{B_1(0)} \varphi(x) dx$$

$\varphi(x) = \varphi(|x|)$ (镜像，球面对称，又为r函数，与角度无关)

$$\text{则 } \int_0^1 \int_{|w|=1} \varphi(r) r^{n-1} dw dr$$

$$= w_n \int_0^1 \varphi(r) r^{n-1} dr \quad (w_n 表示 n 维单位球面面积)$$

$$= 1 \quad (\text{利用了径向对称})$$

$$\text{def: } \varphi_\varepsilon(x) = \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right)$$

$$\varphi_\varepsilon \in C_0^\infty(B_\varepsilon(0))$$

$$\text{且 } \int_{\mathbb{R}^n} \varphi_\varepsilon(x) dx = \int_{\mathbb{R}^n} \frac{1}{\varepsilon^n} \varphi\left(\frac{x}{\varepsilon}\right) dx = \int_{\mathbb{R}^n} \varphi(y) dy = 1$$

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claim:

$\forall x \in \Omega, \exists \varepsilon < \frac{1}{4} \text{dist}(x, \partial\Omega)$, 则

$$u(x) = (u * \varphi_\varepsilon)(x)$$

$$(u * \varphi_\varepsilon)(x) = \int_{\Omega} u(y) \varphi_\varepsilon(x-y) dy$$

$$= \int_{\Omega \cap B_\varepsilon(x)} u(y) \frac{1}{\varepsilon^n} \varphi\left(\frac{x-y}{\varepsilon}\right) dy$$

$$= \int_{B_\varepsilon(x)} u(y) \frac{1}{\varepsilon^n} \varphi\left(\frac{x-y}{\varepsilon}\right) dy$$

$$\stackrel{y=x+rw}{=} \int_0^\varepsilon \int_{|w|=1} u(x+r w) \frac{1}{\varepsilon^n} \varphi\left(\frac{r}{\varepsilon}\right) r^{n-1} dr dw$$

$$\stackrel{t=r}{=} \int_0^1 \int_{|w|=1} u(x+r w) dw t^{n-1} \varphi(t) dt$$

$$\int_{|w|=1} u(x+r w) dw = \int_{|w|=1} u(x) dw = w_n u(x)$$

$$\text{则 } (u * \varphi_\varepsilon)(x) = w_n \int_0^1 t^{n-1} \varphi(t) dt u(x) = u(x)$$

φ_ε 光滑, 由卷积性质 u 光滑

下说明 u 为和

step 1 $u \in C^2(\Omega)$

step 2 $\Delta u = 0$

claim: $\forall x, r > 0, \int_{B_r(x)} \Delta u(y) dy = 0$

则 $\Delta u = 0$

否则, $\exists x_0$ s.t. $(\Delta u)(x_0) \neq 0$. 不妨设 $C > 0$

则 $\exists r_0 > 0, (\Delta u)(x_0) > \frac{C}{2}, \forall x \in B_{r_0}(x_0)$

则 $\int_{B_{r_0}(x_0)} \Delta u(y) dy \geq \frac{C}{2} |B_{r_0}(x_0)| > 0$

事实上, $\int_{B_r(x)} \Delta u(y) dy = \int_{B_r(x)} \operatorname{div}(\nabla u)(y) dy = \int_{\partial B_r(x)} \nabla u \cdot \frac{y-x}{r} dS(y)$

$= \int_{|w|=1} w \cdot \nabla u(x+r w) r^{n-1} dw = r^{n-1} \frac{1}{dr} \int_{|w|=1} u(x+r w) dw = 0$

即 $\int_{|w|=1} u(x+r w) dw$ 与 r 无关 \Leftrightarrow $\int_{|w|=1} u(x+r w) dw = 0$

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Rmk. 平均值性质即函数值 = 合域内 / 表面上函数值的平均

满足平均值性质仅需可积

满足调和需要二阶连续可微

调和函数古典型滑

thm 3. (Harnack 不等式)

设 u 为 Ω 上非负连续函数, u 调和, 对 Ω 上任意联通紧集 V .

$$\exists C = C(\text{dist}(V, \partial\Omega), n), \text{ st. } \text{dist}(V, \partial\Omega) = \inf_{\substack{x \in V \\ y \in \partial\Omega}} |x - y|$$
$$\sup_V u \leq C \inf_V u$$

Rmk. C 与 V, n 有关, 与函数 u 无关

pr: claim: $u(y) \leq C u(x)$

$$\text{令 } r = \frac{1}{4} \text{ dist}(V, \partial\Omega)$$

① $\forall x, y \quad |x - y| < r, \text{ 则 } B(x, 2r) \supset B(y, r)$

($\forall z \in B(y, r), |y - z| < r$

$$|z - x| \leq |z - y| + |y - x| < 2r, z \in B(x, 2r)$$

u 调和, 则 u 满足平均值性质

$$\begin{aligned} u(x) &= \frac{1}{|B_{2r}(x)|} \int_{B_{2r}(x)} u(z) dz \\ &\geq \frac{1}{2^n} \frac{1}{|B_r(y)|} \int_{B_r(y)} u(z) dz \\ &= \frac{1}{2^n} u(y) \Leftrightarrow u(y) \leq 2^n u(x) \end{aligned}$$

② $\forall x, y \in V$

$\exists B_1, \dots, B_N, B_i \cap B_{j \neq i} = \emptyset$, 半径为 $\frac{r}{2}$, $x \in B_i, y \in B_N$

$\forall x_1, x_2 \in B_i$, 有 $|x_1 - x_2| < r$. 由①, $u(y) \leq 2^N u(x)$

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N 与 V 有关

由 x, y 有关, $\sup_{x \in V} u \leq \inf_{x \in V} u$

Rmk. 有限覆盖来限于 $\bigcup_{x \in V} B_\delta(x)$

Thm 4. (梯度估计)

$u \in C(\overline{B_R(x_0)})$ 是调和的, 则

$$|\nabla u(x_0)| \leq \frac{n}{R} \max_{\overline{B_R(x_0)}} |u| \quad (\text{度量为最大分量})$$

pr: $\exists u \in C^1(\overline{B_R(x_0)})$

(u 调和 $\Rightarrow u \in C^\infty(B_R(x_0))$ 但未知边界光滑性)

u 调和, 则 u 在 B_R 上光滑 ($\overline{B_R(x_0)} = \overline{B_R}$)

$\forall x_i$; u 也调和

$$\begin{aligned} \text{由平均值性质 } \partial x_i u(x_0) &= \frac{1}{|B_R(x_0)|} \int_{B_R(x_0)} \partial x_i u(y) dy \\ &= \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u \cdot dS \\ \Rightarrow |\partial x_i u(x_0)| &\leq \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} |u(y)| dS(y) \\ &\leq \max_{\overline{B_R}} |u| \cdot \frac{n}{R} \end{aligned}$$

Thm 5.

若 $u \in C(\overline{B_R})$ 为非负调和函数, 则

$$|\nabla u(x_0)| \leq \frac{n}{R} u(x_0)$$

$$\text{pr: } |\nabla u(x_0)| \leq \frac{1}{|B_R(x_0)|} \int_{\partial B_R(x_0)} u(y) dS(y) = \frac{\int_{\partial B_R(x_0)} u(y) dS(y)}{|B_R(x_0)|} u(x_0) = \frac{n}{R} u(x_0)$$

↑ 平均值性质

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Cor. (Liouville)

\mathbb{R}^n 上的上有界/下有界调和函数为常数

pr: $u \leq M \Rightarrow u = \text{const}$

令 $v = M - u$, 则 v 调和, $v \geq 0$

$\forall x_0, R > 0, \exists v, |\nabla V(x_0)| \leq \frac{n}{R} V(x_0) = \frac{n}{R} (M - u(x_0))$

令 $R \rightarrow \infty$, $|\nabla V(x_0)| = 0$. 则 $\nabla V \equiv 0$, ∇V 为常数

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§2.2 基本解和 Green 函数

def 1. 基本解

若 $\Delta u = \delta$, 称 u 为基本解

δ 类似于电荷, δ 为算子, $\langle \delta, f \rangle = f(0)$

特别地, $\Delta u = 0, \forall x \neq 0$

椭圆方程特解的形式

圆对称 $u(x) = u(|x|)$

$$\Delta u = \partial_r^2 u + \frac{n-1}{r} \partial_r u + \frac{1}{r^2} \Delta_{\theta} u = \partial_r^2 u + \frac{n-1}{r} \partial_r u$$

$$\text{令 } v = \partial_r u, \text{ 则 } \partial_r v + \frac{n-1}{r} v = 0$$

$$\Rightarrow v = C_1 r^{-(n-1)}$$

$$\Rightarrow u(r) = \begin{cases} C_1 r^{-(n-2)} + C_2 & n \geq 3 \\ C_1 \ln r + C_2 & n=2 \end{cases}$$

def 2. 基本解

$$\forall x \in \mathbb{R}^n, x \neq 0, \Gamma(x) = \begin{cases} \frac{1}{2\pi} \ln|x| & n=2 \\ \frac{1}{(n-2)\omega_n} \frac{1}{|x|^{n-2}} & n \geq 3 \end{cases}$$

$$\text{km. } \Delta \Gamma = \delta \neq 0$$

thm 1. (Green)

$u \in C^2(\Omega) \cap C^1(\bar{\Omega})$, 则

$$\begin{aligned} \int_{\Omega} u \nabla v \, dx &= \int_{\Omega} \nabla \cdot (u \nabla v) - \nabla u \cdot \nabla v \, dx = \int_{\partial \Omega} u \nabla v \cdot \vec{n} \, ds - \int_{\Omega} \nabla u \cdot \nabla v \, dx \\ &= \int_{\partial \Omega} u \frac{\partial v}{\partial n} \, ds - \int_{\Omega} \nabla u \cdot \nabla v \, dx \quad (\text{第 } 2 \text{ Green}) \end{aligned}$$

$$\int_{\Omega} u \nabla v - v \nabla u \, dx = \int_{\partial \Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, ds \quad (\text{第 } 1 \text{ Green})$$

进一步研究方程解的表达形式

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Thm 2. 三维下 $\Delta u = 0$ in Ω 的解

$u \in C^2(\Omega) \cap C(\bar{\Omega})$, $\Delta u = 0$ in Ω

$$\forall x_0 \in \Omega, \text{ 有 } u(x_0) = \frac{1}{4\pi} \int_{\partial\Omega} \left[-u \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n} \right] dS(x) \quad (\star)$$

pr: 假设利用 Green 公式, 但 $\frac{1}{|x-x_0|}$ 具有奇性

在 $\Omega_\delta = \Omega \setminus \overline{B_\delta(x_0)}$ 用第 = Green 公式

事实上 Laplace 方程满足平移不变性, 则不妨设 $x_0 = 0$

$$\text{考虑: 若 } u \in \Omega, u(x) = \frac{1}{4\pi} \int_{\partial\Omega} \left[-u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n} \right] dS(x) \quad (\star\star)$$

若 $(\star)(\star\star)$ 成立, 对 $u(+x_0)$ 应用 $(\star\star)$

$$u(x_0) = \frac{1}{4\pi} \int_{\partial(\Omega+x_0)} \left[-u(x+x_0) \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) + \frac{1}{|x|} \frac{\partial u}{\partial n}(x+x_0) \right] dS$$

$$= \frac{1}{4\pi} \int_{\partial\Omega} \left[-u(x) \frac{\partial}{\partial n} \left(\frac{1}{|x-x_0|} \right) + \frac{1}{|x-x_0|} \frac{\partial u}{\partial n} \right] dS$$

$$\text{在 } \Omega_\delta = \Omega \setminus \overline{B_\delta(0)} \text{ 上应用第 = Green, 对 } u, v = \frac{1}{4\pi|x|}$$

$$\int_{\Omega_\delta} (u \Delta v - v \Delta u) dx = 0$$

$$= \int_{\partial\Omega_\delta} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} ds$$

$$= \frac{1}{4\pi} \int_{\partial\Omega} u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) - \frac{1}{|x|} \frac{\partial u}{\partial n} ds - \frac{1}{4\pi} \int_{\partial B_\delta} u \frac{\partial}{\partial n} \left(\frac{1}{|x|} \right) - \frac{1}{|x|} \frac{\partial u}{\partial n} ds \stackrel{?}{=} 1$$

$$1 = \frac{1}{4\pi} \int_{|x|=\varepsilon} u \frac{-1}{r^2} ds - \frac{1}{4\pi} \int_{|x|=\varepsilon} \frac{1}{|x|} \frac{\partial u}{\partial n} ds$$

$$= \frac{-1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} u(x) ds - \frac{1}{4\pi\varepsilon} \int_{B(0, \varepsilon)} \Delta u dx$$

$$\therefore \varepsilon \rightarrow 0, 1 = -u(0)$$

Rmk. 也可利用估计

$$\frac{1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} |u(x) - u(0)| ds \leq \frac{1}{4\pi\varepsilon^2} \int_{|x|=\varepsilon} |(\Delta u)(s)| |x| ds \leq \max_{s \in \bar{\Omega}} |(\Delta u)(s)| \frac{\varepsilon}{4\pi\varepsilon^2} \cdot 4\pi\varepsilon^2 \rightarrow 0$$

$$\frac{1}{4\pi} \int_{|x|=\varepsilon} \frac{1}{|x|} \frac{\partial u}{\partial n} ds \leq \max_{x \in \partial\Omega} \left| \frac{\partial u}{\partial n} \right| \frac{1}{4\pi\varepsilon} \cdot 4\pi\varepsilon^2 \rightarrow 0$$

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需要 u . 然在边界的值，但通常不给定

若 g 在 Ω 内调和， $g|_{\partial\Omega} = \frac{1}{4\pi|x-x_0|}$ ，则对 u , g 在 Ω 上用第二 Green

$$0 = \int_{\partial\Omega} (u \frac{\partial g}{\partial n} - g \frac{\partial u}{\partial n}) ds$$

$$\Rightarrow u(x) = \int_{\partial\Omega} [u \frac{\partial}{\partial n} \left(g - \frac{1}{4\pi|x-x_0|} \right) - \left(g - \frac{1}{4\pi|x-x_0|} \right) \frac{\partial u}{\partial n}] ds \\ = \int_{\partial\Omega} u \frac{\partial}{\partial n} \left(g - \frac{1}{4\pi|x-x_0|} \right) ds$$

$$\text{令 } G(x, x_0) = g(x) + \frac{1}{4\pi|x-x_0|}$$

$$\text{则 } u(x_0) = - \int_{\partial\Omega} u(x) \frac{\partial G}{\partial n}(x, x_0) dS(x) \quad \text{Poisson 公式 (2.1)}$$

g 的表达形式应同样被给出

def 3. Green 函数

Ω 上的算子 $-\Delta$ 的 Green 函数，满足

(1) $G(x)$ 在 Ω 内除 x_0 外二阶连续可微且调和

(2) $G(x) = 0, \forall x \in \partial\Omega$

(3) $-G(x) + \frac{1}{4\pi|x-x_0|}$ 在 x_0 有限，处处二阶连续可微且调和

Thm 3.1 性质： $G(x, x_0) = G(x_0, x)$

设 $u = G(x, a), v = G(b, x)$ 在 $\Omega_E = \Omega \setminus (\overline{B_E(a)} \cup \overline{B_E(b)})$ 应用第二 Green

$$\text{则 } 0 = \int_{\partial\Omega_E} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds$$

$$= \int_{\partial\Omega} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds + \int_{|x-a|=E} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds + \int_{|x-b|=E} (u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n}) ds$$

$$\stackrel{\text{II} \Delta}{\Omega} \quad \stackrel{\text{II} \Delta}{A_E} \quad \stackrel{\text{II} \Delta}{B_E}$$

$$A_E = \int_{|x-a|=E} \left[\left(u - \frac{1}{4\pi|x-a|} \right) \frac{\partial v}{\partial n} - v \frac{\partial}{\partial n} \left(u - \frac{1}{4\pi|x-a|} \right) \right] ds + \int_{|x-a|=E} \frac{1}{4\pi|x-a|} \frac{\partial v}{\partial n} ds - \int_{|x-a|=E} v \frac{\partial}{\partial n} \left(\frac{1}{4\pi|x-a|} \right) ds$$

$$\textcircled{1} \quad \textcircled{2} \quad \textcircled{3}$$

$$\textcircled{1} = - \int_{|x-a| \leq E} \left[\Delta \left(u - \frac{1}{4\pi|x-a|} \right) v - (u - \frac{1}{4\pi|x-a|}) \Delta v \right] dx = 0$$

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$$\textcircled{2} = \frac{1}{4\pi\varepsilon} \int_{|x-a|=r} \frac{\Delta v}{|x-a|} ds = \frac{1}{4\pi\varepsilon} \int_{|x-a|=r} \Delta v dx = 0$$

$$\textcircled{3} = \int_{|x-a|=r} \frac{v \cdot \frac{\partial}{\partial r} (\frac{1}{4\pi\varepsilon})}{|x-a|} ds = \frac{-1}{4\pi\varepsilon^2} \int_{|x-a|=r} v ds \rightarrow -v(a) = -G(b, a)$$

$$B_p A_\varepsilon \rightarrow -G(b, a) \quad \left. \begin{array}{l} \\ \text{同理 } B_\varepsilon \rightarrow G(a, b) \end{array} \right\} \Rightarrow G(a, b) = G(b, a)$$

若给出了f的表达式，则给出了g的表达式，下节查Green函数求解。

1. 半空间

$$\text{取 } x_0^* = (x_0^1, x_0^2, -x_0^3)$$

$$\text{def } G(x, x_0) = \frac{1}{4\pi|x-x_0|} - \frac{1}{4\pi|x-x_0^*|}$$

则 G 高是 (1)(2)(3)

2. $B_R(0)$

$$G(x, x_0) = \frac{1}{4\pi|x-x_0|} - \frac{C}{4\pi|x-x_0^*|}$$

x_0^* 在球外，此时 (1)(3) 自然高是

由(2), $\forall |x|=R$, 有 $G(x, x_0) = 0$

$$\text{令 } |x-x_0| = \rho, |x-x_0^*| = \rho^* \Rightarrow \frac{\rho^*}{\rho} = C$$

$$\text{若 } \Delta \text{ 小 } \sim \Delta \text{ 大}, \text{ 则 } \frac{\rho^*}{\rho} = \frac{|x_0^*|}{R} = \frac{R}{|x_0|}$$

$$\text{取 } x_0^* \text{ 为 } x_0^* = \frac{R^2}{|x_0|^2} x_0 \text{ 可}$$

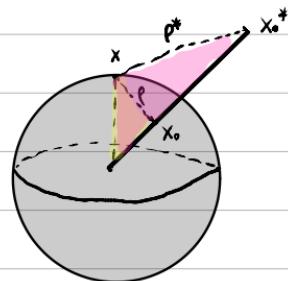
$$\text{则 } G(x, x_0) = \frac{1}{4\pi|x-x_0|} - \frac{C}{4\pi|x-x_0^*|}$$

$$C = \frac{R}{|x_0|}, \quad x_0^* = \frac{R^2}{|x_0|^2} x_0 \quad B_p G$$

将 $B_R(0)$ 下的 Green 函数带入 (2.1), $x \in \partial\Omega$ 时

$$\nabla G(x, x_0) = -\frac{x-x_0}{4\pi|x-x_0|^3} + \frac{C(x-x_0^*)}{4\pi|x-x_0^*|^3} = -\frac{x-x_0}{4\pi|x-x_0|^3} + \frac{|x_0|^2}{4\pi R^2} \frac{x-x_0^*}{|x-x_0^*|^3}$$

$$= -\frac{x}{4\pi|x-x_0|^3} \left(1 - \frac{|x_0|^2}{R^2}\right) + \frac{1}{4\pi|x-x_0|^3} \left(x_0 - \frac{|x_0|^2}{R^2} x_0^*\right) = -\frac{x}{4\pi|x-x_0|^3} \left(1 - \frac{|x_0|^2}{R^2}\right)$$



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$$\frac{\partial f_1}{\partial n} = n \cdot \nabla f_1 = \frac{x}{|x|} \cdot \left(\frac{R^2 - |x_0|^2}{R^2} \frac{x}{4\pi|x-x_0|^3} \right) = \frac{R^2 - |x_0|^2}{R} \frac{1}{4\pi|x-x_0|^3}$$

$$\text{故 } u(x_0) = \frac{R^2 - |x_0|^2}{4\pi R} \int_{|x|=R} \frac{u(y)}{|x-y|^3} dS(y) \quad (y \text{ 为边界})$$

$$P_p u(x) = \frac{R^2 - x^2}{4\pi R} \int_{|y|=R} \frac{u(y)}{|x-y|^3} dS(y) \quad \text{Poisson 公式}$$

thm 4. (Harnack 不等式)

设 u 在 $B_R(x_0)$ 内调和且 $u \geq 0$, 则

$$\frac{R}{R+r} \frac{R-r}{R+r} u(x_0) \leq u(x) \leq \frac{R}{R-r} \frac{R+r}{R-r} u(x_0), \text{ 其中 } r = |x-x_0| < R$$

Rmk. 2.1 中也有 Harnack 不等式, 但说明在通常紧集中任意两点处函数值可互相比较, 区别在于该 thm 给出了具体的界

pr: 不妨设 $x_0 = 0$ (平移不变性)

则 $r = |x| < R$, 只需证:

$$\frac{R}{R+r} \frac{R-r}{R+r} u(0) \leq u(x) \leq \frac{R}{R-r} \frac{R+r}{R-r} u(0)$$

由 Poisson 公式, $u(x) = \frac{R^2 - x^2}{4\pi R} \int_{|y|=R} \frac{u(y)}{|x-y|^3} dS(y)$

由于 $R-r \leq |x-y| \leq R+r$, 则

$$\frac{R^2 - r^2}{4\pi R} \frac{1}{(R+r)^3} \int_{|y|=R} u(y) dS(y) \leq u(x) \leq \frac{R^2 - r^2}{4\pi R} \frac{1}{(R-r)^3} \int_{|y|=R} u(y) dS(y)$$

u 调和, 由平均值性质, 则 $\int_{|y|=R} u(y) dS(y) = 4\pi R^2 u(0)$

$$\frac{R(R^2 - r^2)}{(R+r)^3} u(0) \leq u(x) \leq \frac{R(R^2 - r^2)}{(R-r)^3} u(0) \quad \text{P.S. 2}$$

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几维情形下的推导:

$$-\Delta u = 0$$

$$u|_{\partial\Omega} = g$$

对 u 基本解为 v , 在 $\Omega \setminus B_\varepsilon(0) \equiv \Omega_\varepsilon$ 上用第二 Green 公式

$$\int_{\Omega_\varepsilon} u \Delta v - v \Delta u \, dx = 0$$

$$= \int_{\partial B_\varepsilon} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) = \int_{\partial\Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) - \int_{\partial B(0, \varepsilon)} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x)$$

$$\textcircled{1} \quad \int_{\partial B(0, \varepsilon)} u \frac{\partial v}{\partial n} \, dS(x)$$

$$= \int_{\partial B(0, \varepsilon)} u \frac{\partial}{\partial r} \left(\frac{1}{n(n-2)\alpha(n)} \frac{1}{|x|^{n-2}} \right) \, dS(x)$$

$$= \int_{\partial B(0, \varepsilon)} u \cdot \frac{1}{n(n-2)\alpha(n)} \frac{2-n}{r^{n-1}} \, dS(x)$$

$$= \frac{-1}{n\alpha(n)} \frac{1}{\varepsilon^{n-1}} \int_{\partial B(0, \varepsilon)} u \, dS(x) \rightarrow -u(0) (\varepsilon \rightarrow 0)$$

$$\textcircled{2} \quad \int_{\partial B(0, \varepsilon)} v \frac{\partial u}{\partial n} \, dS(x)$$

$$= \int_{\partial B(0, \varepsilon)} \frac{1}{n(n-2)\alpha(n)} \frac{1}{|x|^{n-2}} \frac{\partial u}{\partial n} \, dS(x)$$

$$= \frac{1}{n(n-2)\alpha(n)} \frac{1}{|\varepsilon|^{n-2}} \int_{B(0, \varepsilon)} \Delta u \, dx = 0$$

$$\text{由 } u(0) = \int_{\partial\Omega} u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x)$$

$$\text{若 } -\Delta u = f, \text{ 则 } \int_{\partial B(0, \varepsilon)} v \frac{\partial u}{\partial n} \, dS(x) = \frac{1}{n(n-2)\alpha(n)} \frac{-1}{|\varepsilon|^{n-2}} \int_{B(0, \varepsilon)} f \, dx$$

$$\text{有 } \int_{\Omega_\varepsilon} v f \, dx = \int_{\partial\Omega} u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} \, dS(x) + u(0) + \frac{1}{n(n-2)\alpha(n)} \frac{-1}{|\varepsilon|^{n-2}} \int_{B(0, \varepsilon)} f \, dx$$

$$\Rightarrow u(0) = \int_{\partial\Omega} -u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x) + \frac{1}{n(n-2)\alpha(n)} \frac{1}{|\varepsilon|^{n-2}} \int_{B(0, \varepsilon)} f \, dx$$

$$= \int_{\partial\Omega} -u \frac{\partial v}{\partial n} + v \frac{\partial u}{\partial n} \, dS(x) + \int_{\Omega} v f \, dx$$

$$\Leftrightarrow u(x) = \int_{\Omega} f(y) \Gamma(x-y) \, dy - \int_{\partial\Omega} g(y) \frac{\partial \Gamma}{\partial n}(x-y) + \int_{\partial\Omega} \frac{\partial u}{\partial n}(y) \Gamma(x-y) \, dS(y)$$

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用 $\tilde{g}_1(x, y) \stackrel{\text{def}}{=} \Gamma(x-y) - \phi^*(y)$ 代替 $\Gamma(x-y)$

要求 $\tilde{g}_1|_{\partial\Omega} = 0, \Delta \tilde{g}_1(x, y) = 0$



$\phi^*(y)|_{\partial\Omega} = \Gamma(x-y), \Delta \phi^*(y) = 0$

$$u(x) = \int_{\Omega} f(y) \tilde{g}_1(x-y) dy - \int_{\partial\Omega} \frac{\partial \tilde{g}_1}{\partial n}(x-y) g(y) d\sigma(y)$$

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§2.3 极值原理和最大模估计

$$\text{拉普拉斯方程 } \Delta u = -\Delta u + C(x)u = f(x), C(x) \geq 0, x \in \Omega$$

Thm 1. 弱极大值原理

$C(x) \geq 0, -f(x) < 0, u \in C^2(\Omega) \cap C(\bar{\Omega})$, 且满足以上方程, 则

$u(x)$ 不能在 $\bar{\Omega}$ 上达到它在 $\bar{\Omega}$ 上的非负最大值,

即 $u(x)$ 只能在 Ω 上达到非负最大值

(注意, 并不意味在边界上一定能取到非负最大值)

pr: 假设 u 在 $x_0 \in \Omega$ 达到非负最大值 $M \geq 0$

$$\text{则 } (\nabla u)(x_0) = 0, (\Delta u)(x_0) = \text{tr}(\text{Hesse } u(x_0)) \leq 0$$

$$(\Delta u)(x_0) = -\Delta u(x_0) + C(x_0)u(x_0) \geq 0 \quad \Rightarrow f(x_0) < 0 \text{ 矛盾}$$

Thm 2.

$C(x) \geq 0, -f(x) \leq 0, u \in C^2(\Omega) \cap C(\bar{\Omega})$, 且满足以上方程

且在 $\bar{\Omega}$ 上存在的最大值, 则 $u(x)$ 只能在 Ω 上到达在 $\bar{\Omega}$ 上的非负最大值

$$\text{且 } \max_{x \in \bar{\Omega}} u(x) \leq \max_{\partial \Omega} u^+(x)$$

$$u^+ = \max \{ u(x), 0 \}$$

pr: 不妨设 $d \in \Omega$, 全 $d = \text{diam } \Omega$

$$\text{令 } V(x) = -(d^2 - |x|^2) \leq 0 \quad u^\varepsilon(x) = u(x) + \varepsilon V(x)$$

$$\mathcal{L}u^\varepsilon = \mathcal{L}u + \varepsilon \mathcal{L}V = f + \varepsilon (-\Delta(d^2 - |x|^2) + C(x)d^2 + |x|^2))$$

$$= f - 2\varepsilon d + \varepsilon C(x)(-d^2 + |x|^2) < 0$$

应用 Thm 1.

$$\max_{\bar{\Omega}} u - \varepsilon d^2 = \max_{\bar{\Omega}} (u - \varepsilon d^2) \leq \max_{\Omega} u_\varepsilon \leq \max_{\partial \Omega} (u + \varepsilon V)^+ \leq \max_{\partial \Omega} u^+$$

$$\varepsilon \rightarrow 0, \max_{\bar{\Omega}} u \leq \max_{\partial \Omega} u^+$$

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Rmk. 若 u 在 \bar{B}_R 上最大值为负数, 与 thm 1.2 矛盾

下面我们将证明极值原理.

thm 3. (Hopf 引理)

设 B_R 为 \mathbb{R}^n ($n=2, 3$) 上以 R 为半径的球, 在 B_R 上 $u(x) \geq 0$ 有界,

若 $u \in C^2(B_R) \cap C^1(\bar{B}_R)$ 满足

$$(1) \quad \Delta u = -\Delta u + c(x)u \leq 0, \quad x \in B_R$$

(2) $\exists x_0 \in \partial B_R$, st. u 在 x_0 处达到 \bar{B}_R 上的非负最大值

则 $\max_{\bar{B}_R} u(x_0) = \max_{\bar{B}_R} u \geq 0$ 且当 $x \in B_R$ 时, $u(x) < u(x_0)$.

$\frac{\partial u}{\partial n} \Big|_{x=x_0} > 0$, M 与 ∂B_R 在 x_0 处单连通且 n 具角小于 $\frac{\pi}{2}$

pr: 由(1) 易知 $\frac{\partial u}{\partial n} \Big|_{x=x_0} \geq 0$

令 $v(x) = e^{-\alpha|x|^2} - e^{-\alpha R^2}$ $\alpha > 0$ 适当

$$w(x) = u(x) - u(x_0) + \varepsilon v(x) \quad \varepsilon > 0$$

$$\nabla v = e^{-\alpha|x|^2} \cdot (-2\alpha x)$$

$$\begin{aligned} \Delta v &= \sum_i \delta x_i \cdot (-2\alpha x_i e^{-\alpha|x|^2}) = \sum_i (-2\alpha + 4\alpha^2 |x_i|^2) e^{-\alpha|x|^2} \\ &= (-2\alpha n + 4\alpha^2 |x|^2) e^{-\alpha|x|^2} \end{aligned}$$

$$l_w = l_u - c(x)u(x_0) + \varepsilon l_v$$

$$= l_u - c(x)u(x_0) + \varepsilon [-4|\alpha|^2|x|^2 + 2\alpha n] e^{-\alpha|x|^2} + c(x)(e^{-\alpha|x|^2} - e^{-\alpha R^2})$$

$$= l_u - c(x)u(x_0) + \varepsilon [(-4|\alpha|^2|x|^2 + 2\alpha n + c(x)) e^{-\alpha|x|^2} - c(x)e^{-\alpha R^2}]$$

$$\leq 0 \quad \leq 0 \quad > 0 \quad \geq 0$$

$$\leq \varepsilon (-4|\alpha|^2|x|^2 + 2\alpha n + C) e^{-\alpha|x|^2} \quad C \text{ 为 } c(x) \text{ 的界}$$

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$$\text{在 } B_R^* = \left\{ \frac{R}{2} \leq |x| \leq R \right\} \text{ 上取 } |x| = R,$$

$$\leq \varepsilon (-R^2\alpha^2 + 2\alpha n + C) e^{-\alpha|x|^2}$$

$$< 0 (\alpha \text{ 充分大})$$

由 thm 1, 在 B_R^* 对 w 应用极大值原理,

w 在 \overline{B}_R 上的非负最大值在边界上取到

$$|x| = \frac{R}{2} \text{ 时, } w(x) = u(x_0) - u(x_0) + \varepsilon (e^{-\alpha \frac{R^2}{4}} - e^{-\alpha R^2})$$

$$\Rightarrow w(x) \leq \max_{|x|=\frac{R}{2}} u(x) - u(x_0) + \varepsilon (e^{-\alpha \frac{R^2}{4}} - e^{-\alpha R^2})$$

$$< 0 (\varepsilon \text{ 充分小})$$

$|x| = R$ 时, $w(x)$ 在 x_0 处取得最大值

$$\Rightarrow \frac{\partial w}{\partial \mu} \geq 0$$

$$\text{且 } \frac{\partial u}{\partial \mu} + \varepsilon \frac{\partial v}{\partial \mu} \geq 0$$

$$\text{而 } \frac{\partial v}{\partial \mu} = \mu \cdot \nabla v = \mu \cdot e^{-\alpha|x|^2} (-2\alpha \bar{x}) < 0$$

$$\Rightarrow \frac{\partial u}{\partial \mu} > 0$$

thm 4. 强极大值原理

假设 Ω 为 \mathbb{R}^n 中有界连通开集, $u(x) \geq 0$ 有界

若 $u \in C^1(\Omega) \cap C(\bar{\Omega})$ 在 Ω 上满足 $Lu \leq 0$, 且 u 在 Ω 内达到在 $\bar{\Omega}$ 上非负最大值, 则 u 在 $\bar{\Omega}$ 上恒为常数.

pr. 令 $M = \max_{x \in \bar{\Omega}} u(x) \geq 0$, 令 $\Omega = \{x \in \Omega \mid u(x) = M\}$, 则 $\Omega = \emptyset$

step 1. $\Omega \neq \emptyset$.

step 2. Ω 闭. $\exists x_n \in \Omega, x_n \rightarrow \bar{x}$, 则 $\bar{x} \in \Omega$

u 连续, 则 $u(\bar{x}) = \lim_{n \rightarrow \infty} u(x_n) = M$, 则 $\bar{x} \in \Omega$

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Step 3. O 为.

若不为开集, 则 $\exists x_0 \in \Omega \setminus O$ (Ω 开而 O 不开, $O \subseteq \Omega$)

$\Omega \setminus O$ 开, $\exists R > 0$, s.t. $B_R(x_0)$ 与 $\partial\Omega$ 相切于 y_0 .

claim: ① u 在 y_0 达到 \bar{u} 上的非负最大值

② $\forall x \in B_R(x_0)$, $u(x) < M$

由 Hopf 定理, $\frac{\partial u}{\partial \mathbf{n}}(y_0) > 0$

($y_0 \in \Omega$, 由于 $\Omega^c \cap O = \emptyset$, Ω^c 非闭, $\text{dist}(\Omega^c, O) > 0$)

而 $y_0 \in \Omega$ 达到最大值, $\nabla u(y_0) = 0$, $\frac{\partial u}{\partial \mathbf{n}}(y_0) = 0$ 矛盾

则 O 为开集

结合 1.2.3 知 $O = \Omega$

Rm. ① 若 $-\Delta u < 0$, 则 u 只在边界处达到最大值.

(若在 $x_0 \in \Omega$ 处达到, 则 $-\Delta u(x_0) \geq 0$ 矛盾)

② 若 u 闭和 ($u \in C(\bar{\Omega})$ 满足平均值性质), 则 u 只在 $\partial\Omega$ 达到最大值和最小值, 除非 u 为常数 (即若最大值/最小值在内部取到, 则必为常数)

pr: 不妨最大值在内部取到, 设 $M = \max_{\bar{\Omega}} u(x)$

$\Omega^c = \{x \in \Omega \mid u(x) = M\}$, O 非空闭

只需证 O 为开集

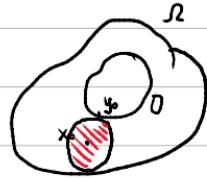
$\forall x_0 \in O$, $\exists B_R(x_0) \subseteq \Omega$, 由平均值性质

$$M = u(x_0) = \frac{1}{|B_R(x_0)|} \int_{B_R(x_0)} u(y) dy \leq M$$

$\Rightarrow u(x) = M$, $x \in B_R(x_0)$, 则 $B_R(x_0) \subseteq M$

故 O 为开集

① ② 表明 $\Delta u \geq 0$, 则仅能在边界处达到最大值, 无非负性要求.



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下利用极值原理证明最大模估计

$$\begin{cases} -\Delta u = f & \text{in } \Omega \\ u = g & \text{on } \partial\Omega \end{cases} \quad (2.41)$$

thm 5. 最大模估计

$u \in C^2(\Omega) \cap C(\bar{\Omega})$ 为 (2.41) 的解, 则

$$\max_{\bar{\Omega}} |u(x)| \leq G_1 + CF, \quad G_1 = \max_{\partial\Omega} |g|, \quad F = \max_{\bar{\Omega}} |f|, \quad C = C(n, \text{diam}(\Omega))$$

$$\text{idea. } \Delta u \geq 0, \quad u|_{\partial\Omega} \leq 0 \Rightarrow u \leq 0$$

pr: 不妨 $0 \in \Omega$, $\forall x \in \Omega, |x| < d$

$$\text{令 } w(x) = u - (G_1 + \frac{F}{2n}(d^2 - |x|^2))$$

$$\text{则 } -\Delta w = -\Delta u - F = f - F \leq 0$$

$$w|_{\partial\Omega} = g - G_1 - \frac{F}{2n}(d^2 - |x|^2) \leq g - G_1 \leq 0$$

由弱极值原理, $\max_{\bar{\Omega}} w - \max_{\partial\Omega} w \leq 0$

$$0 \geq \max_{\bar{\Omega}} \left(u(x) - \left(G_1 + \frac{F}{2n}d^2 \right) + \frac{F}{2n}|x|^2 \right) \geq \max_{\bar{\Omega}} u(x) - \left(G_1 + \frac{F}{2n}d^2 \right)$$

$$\Rightarrow u(x) \leq G_1 + \frac{d^2}{2n}F$$

$$\text{再令 } \tilde{w}(x) = -u - (G_1 + \frac{F}{2n}(d^2 - |x|^2))$$

$$\text{则 } -\Delta \tilde{w} = -f - F \leq 0$$

$$\tilde{w}|_{\partial\Omega} \leq -g - G_1 \leq 0$$

由弱极值原理, $\max_{\bar{\Omega}} \tilde{w} - \max_{\partial\Omega} \tilde{w} \leq 0$

$$\Rightarrow -u(x) \leq G_1 + \frac{d^2}{2n}F$$

$$\text{故 } |u(x)| \leq G_1 + \frac{d^2}{2n}F \quad \forall x \in \Omega.$$

Rmk. 最大模估计蕴含解的唯一性与稳定性.

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设 u_1, u_2 为 (2.41) 的解, 设 $v = u_1 - u_2$

则 $\begin{cases} -\Delta v = 0 \\ v|_{\partial\Omega} = 0 \end{cases}$

由最大模估计 $\max_{\bar{\Omega}} |v(x)| \leq 0 + C \cdot 0 = 0 \Rightarrow u_1 = u_2$, 即唯一性

设 u_1, u_2 为

$$\begin{cases} -\Delta u = f_1 \\ u|_{\partial\Omega} = g_1 \end{cases} \quad \text{与} \quad \begin{cases} -\Delta u = f_2 \\ u|_{\partial\Omega} = g_2 \end{cases}$$

的解

由最大模估计 $\max_{\bar{\Omega}} |u_1(x) - u_2(x)| \leq \max_{\partial\Omega} |g_1 - g_2| + C \max_{\bar{\Omega}} |f_1 - f_2|$

蕴含稳定性

而唯一性与稳定性可通过能量法给出

$$\begin{aligned} \text{弱方程 } & \begin{cases} -\Delta u = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases} \end{aligned}$$

$$\int_{\Omega} u(-\Delta u) dx = \int_{\Omega} fu dx = \int_{\Omega} -\operatorname{div}(u\nabla u) + |\nabla u|^2 dx = -\int_{\partial\Omega} u \frac{\partial u}{\partial n} ds + \int_{\Omega} |\nabla u|^2 dx$$

claim. (Friedrichs 不等式)

$$u \in C_0^1(\Omega), \text{ 则 } \int_{\Omega} |u(x)|^2 dx \leq 4d^2 \int_{\Omega} |\nabla u(x)|^2 dx \quad d = \operatorname{diam}(\Omega)$$

$$\text{则 } \int_{\Omega} fu dx \leq \varepsilon \int_{\Omega} |u|^2 dx + \frac{1}{4\varepsilon} \int_{\Omega} |f|^2 dx$$

$$\int_{\Omega} |\nabla u|^2 dx \leq \varepsilon \cdot 4d^2 \int_{\Omega} |\nabla u|^2 dx + \frac{1}{4\varepsilon} \int_{\Omega} |f|^2 dx$$

$$\text{选取合适的 } \varepsilon \text{ 可 st. } \int_{\Omega} |\nabla u|^2 dx \leq C \int_{\Omega} |f|^2 dx$$

Rmk. 该表达式蕴含 $|\nabla u|, |u|$ 的控制, Poisson 方程的能量为方程两边 $\times u$.

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第三章 热传导方程

$$u_t - \Delta u = f(x, t) \quad x \in \Omega, t > 0$$

$$u(x, 0) = \varphi(x)$$

$$(Dirichlet) \quad u|_{\partial\Omega} = g(x, t)$$

$$(Neumann) \quad \frac{\partial u}{\partial n}|_{\partial\Omega} = g(x, t)$$

$$(Robin) \quad \frac{\partial u}{\partial n} + \sigma u|_{\partial\Omega} = g(x, t)$$

u 表示温度 etc., 描述传热过程、扩散过程;

f 表示热源.

3.1 初值问题

解法 1. 分离变量法

$\Omega = [0, l]$, 矩形区域, 圆盘 etc.

解法 2. Fourier 变换法

热传导方程 $\begin{cases} u_t - \Delta u = f(x, t) & x \in \mathbb{R}^n, t > 0 \\ u(x, 0) = \varphi(x) \end{cases}$

Recall. (\mathbb{R}^n 上的 Fourier 变换)

$f \in L^1(\mathbb{R}^n)$, ($\int_{\mathbb{R}^n} |f(x)| dx < +\infty$)

def. $\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx$

性质 $f \in S(\mathbb{R}^n)$, (f 光滑, 高阶导数衰减速度快)

则不考虑分部积分边界项

1. 令 $(T_{x_0} f)(x) = f(x - x_0)$, 则 $\widehat{T_{x_0} f}(\xi) = e^{-2\pi i x_0 \cdot \xi} \widehat{f}(\xi)$

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$$\begin{aligned} \text{pr. } \widehat{\mathcal{L}_{x_0} f}(\xi) &= \int_{\mathbb{R}^n} f(x-x_0) e^{-2\pi i x \cdot \xi} dx \\ &= \int_{\mathbb{R}^n} f(y) e^{-2\pi i (x_0+y) \cdot \xi} dy \\ &= e^{-2\pi i x_0 \cdot \xi} \int_{\mathbb{R}^n} f(y) e^{-2\pi i y \cdot \xi} dy \\ &= e^{-2\pi i x_0 \cdot \xi} \widehat{f}(\xi) \end{aligned}$$

2. 因 $(S_x f)(x) = f(\lambda x)$, 则 $\widehat{S_x f}(\xi) = \lambda^{-n} \widehat{f}(\lambda^{-1} \xi)$

$$\begin{aligned} \text{pr. } \widehat{S_x f}(\xi) &= \int_{\mathbb{R}^n} f(\lambda x) e^{-2\pi i x \cdot \xi} dx \\ &= \int_{\mathbb{R}^n} f(y) e^{-2\pi i \frac{y}{\lambda} \cdot \xi} \lambda^{-n} dy \\ &= \lambda^{-n} \int_{\mathbb{R}^n} f(y) e^{-2\pi i y \cdot \frac{\xi}{\lambda}} dy \\ &= \lambda^{-n} \int_{\mathbb{R}^n} \widehat{f}(\lambda^{-1} \xi) \end{aligned}$$

3. 对多重指数标 $\alpha = (\alpha_1, \dots, \alpha_n)$, 且 $|\alpha| = \alpha_1 + \dots + \alpha_n$, $X^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$

$$\partial^\alpha = \partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}, \text{ 则 } \widehat{\partial^\alpha f}(\xi) = (2\pi i \xi)^\alpha \widehat{f}(\xi)$$

$$\begin{aligned} \text{pr. } \widehat{\partial x_j f}(\xi) &= \int_{\mathbb{R}^n} f(x_j) e^{-2\pi i x \cdot \xi} dx \\ &= - \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} (-2\pi i \xi_j) dx \\ &= 2\pi i \xi_j \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx \\ &= 2\pi i \xi_j \widehat{f}(\xi) \end{aligned}$$

$$4. \widehat{(-2\pi i x)^{\alpha} f}(\xi) = \partial_\xi^\alpha \widehat{f}(\xi)$$

$$\begin{aligned} \text{pr. } \widehat{(-2\pi i x_j)^{\alpha} f}(\xi) &= \int_{\mathbb{R}^n} -2\pi i x_j f(x) e^{-2\pi i x \cdot \xi} dx \\ &= \int_{\mathbb{R}^n} (e^{-2\pi i x \cdot \xi})_{x_j} f(x) dx \\ &= \partial_{x_j} \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx \\ &= \partial_{x_j} \widehat{f}(\xi) \end{aligned}$$

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5. 令 $(f+g)(x) = \int_{\mathbb{R}^n} f(x-y) g(y) dy = \int_{\mathbb{R}^n} f(y) g(x-y) dy$
若 $f, g \in \mathcal{S}(\mathbb{R}^n)$, 则 $\widehat{f+g}(s) = \widehat{f}(s) \widehat{g}(s)$

6. 逆变换

$\widehat{f}(x) = \int_{\mathbb{R}^n} f(s) e^{2\pi i x \cdot s} ds$, 则若 $f \in \mathcal{S}(\mathbb{R}^n)$, 有

$$\widehat{f} \in \mathcal{S}(\mathbb{R}^n), \quad \widehat{\widehat{f}} = f$$

例. 若 $f(x) = e^{-x^2}$, $x \in \mathbb{R}$, 则 $\widehat{f}(s) = \sqrt{\pi} e^{-\pi s^2}$

令 $F(s) = \widehat{f}(s) = \int_{\mathbb{R}} e^{-x^2} e^{-2\pi i x s} dx$

$$F'(s) = \int_{\mathbb{R}} e^{-x^2} (-2\pi i x) e^{-2\pi i x s} dx$$

$$= -2\pi i \int_{\mathbb{R}} (e^{-x^2})' e^{-2\pi i x s} dx$$

$$= -2\pi i \widehat{f}'(s) = -2\pi i \cdot 2\pi i s \widehat{f}(s)$$

$$= -4\pi^2 s F(s)$$

$$F(0) = \int_{\mathbb{R}} e^{-x^2} dx = \sqrt{\pi}$$

$$\Rightarrow F(s) = \sqrt{\pi} e^{\int -4\pi^2 s^2 ds} = \sqrt{\pi} e^{-\pi s^2}$$

注: $f(x) \in \mathcal{S}(\mathbb{R})$, 则 $(e^{-\pi s^2})^V(x) = \frac{1}{\sqrt{\pi}} e^{-x^2}$

$$(e^{-4\pi^2 s^2 t})^V(x) = \frac{1}{2\sqrt{\pi t}} e^{-\frac{x^2}{4t}}$$

$$n \geq 1 \text{ 时}, (e^{-4\pi^2 t_1 t_2 t})^V(x) = \prod_{j=1}^n (e^{-4\pi^2 s_j^2 t})^V(x_j) = \prod_{j=1}^n \frac{1}{2\sqrt{\pi t}} e^{-\frac{x_j^2}{4t}} = \frac{1}{(4\pi t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}}$$

回到热传导方程的解.

对方程 $\begin{cases} u_t - \Delta u = 0 & x \in \mathbb{R}^n, t > 0 \\ u|_{t=0} = \varphi(x) & x \in \mathbb{R}^n \end{cases}$

两边关于 x 作 Fourier 变换, 则 $\begin{cases} \partial_t \widehat{u}(s) + 4\pi^2 |s|^2 \widehat{u}(s) = 0 \\ \widehat{u}(s)|_{t=0} = \widehat{\varphi}(s) \end{cases}$

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$$\Rightarrow \hat{u}(s, t) = \hat{\varphi}(s) e^{-42^2 |s|^2 t}$$

做逆变换, 由 12.5 $f * g = (\hat{f} \hat{g})^\vee = \hat{f}^\vee * \hat{g}^\vee$ (相乘的逆变换 = 逆变换的卷积)

$$\Rightarrow u(x, t) = (e^{-42^2 |s|^2 t})^\vee * \varphi$$

$$= \frac{1}{(42t)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4t}} * \varphi$$

$$= \frac{1}{(42t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} \varphi(y) dy$$

貌似在 $t=0$ 有奇性, 丁说明 $t=0$ 时满足初值

$$\text{令 } k(x) = \frac{1}{(42)^{\frac{n}{2}}} e^{-\frac{|x|^2}{4}} \quad (\text{Heat kernel})$$

$$k_t(x) = t^{-\frac{n}{2}} k(t^{-\frac{1}{2}}x), t>0$$

$$(2) u(x, t) = \int_{\mathbb{R}^n} k_t(x-y) \varphi(y) dy = \int_{\mathbb{R}^n} k_t(y) \varphi(x-y) dy$$

$$\{k_t\}_{t>0} \text{ 有: (i) } \int_{\mathbb{R}^n} k_t(x) dx = \int_{\mathbb{R}^n} k(x) dx = 1$$

$$x = \int_{\mathbb{R}^n} t^{-\frac{n}{2}} k(t^{-\frac{1}{2}}x) dx = \int_{\mathbb{R}^n} k(y) dy = \frac{1}{(42)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4}} dy = 1$$

$$\left(\int_{\mathbb{R}} e^{-x^2} dx = \sqrt{\pi} \right)$$

$$(ii) \int_{\mathbb{R}^n} |k_t(x)| dx = 1$$

$$(iii) \forall y > 0, \int_{|x|>y} k_t(x) dx = \int_{|y|>\frac{y}{\sqrt{t}}} k(y) dy \rightarrow 0 (t \rightarrow 0^+)$$

$\{k_t\}_{t>0}$ 为一族逐点连续

$$u(x, t) = k_t * \varphi \xrightarrow{t \rightarrow 0^+} \varphi \quad (\varphi \in C(\mathbb{R}^n), \text{ 有界})$$

$$|u(x, t) - \varphi(x)| = \left| \int_{\mathbb{R}^n} k_t(y) \varphi(x-y) dy - \int_{\mathbb{R}^n} k_t(y) \varphi(x) dy \right|$$

$$= \left| \int_{\mathbb{R}^n} k_t(y) (\varphi(x-y) - \varphi(x)) dy \right|$$

$$\leq \frac{1}{(42t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} |\varphi(x-y) - \varphi(x)| dy$$

$$= \frac{1}{(42)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|z|^2}{4}} |\varphi(x - z\sqrt{t}) - \varphi(x)| dz$$

$$z = \frac{y}{\sqrt{t}}$$

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$$\textcircled{1} = \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|>R} e^{-\frac{|z|^2}{4}} |\varphi(x-z)| dz \leq \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|>R} e^{-\frac{|z|^2}{4}} dz \cdot 2\|\varphi\|_{L^\infty} \rightarrow 0 \quad (R \rightarrow \infty)$$

$$\textcircled{2} = \frac{1}{(4\pi)^{\frac{n}{2}}} \int_{|z|<R} e^{-\frac{|z|^2}{4}} |\varphi(x-z) - \varphi(x)| dz$$

由于 φ 连续，且 $|z| < R$, $|\varphi(x-z) - \varphi(x)| < \varepsilon$, $t \rightarrow 0^+$

$$\text{则 } \textcircled{2} \leq C\varepsilon \Rightarrow |u(x,t) - \varphi(x)| \rightarrow 0, t \rightarrow 0^+$$

Rmk. 1. 由 u 的光滑性 $|x|$ 及 $u(x,t) = k_0(x) + \varphi$ 说明 u 具有光滑性

$$2. \sup_x |u(x,t)| \leq \sup_x |\varphi(x)|$$

$$\text{由于 } u(x,t) = \frac{1}{(4\pi t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} \varphi(x-y) dy$$

$$\sup_x |u(x,t)| \leq \frac{1}{(4\pi t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|y|^2}{4t}} \sup_x |\varphi(x)| dy = \sup_x |\varphi(x)|$$

即温度最大值小于初始最大值，同时 t 足够大时 $u(x,t) \rightarrow 0$ (衰减)

3. 热方程沿时间不反向演化，即从未态无法推及初态

4. 无限传播速度，且位置 x 的 $u(x,t) > 0$

拓展非齐次方程

$$\text{对方程 } \left\{ \begin{array}{l} u_t - \Delta u = f(x,t) \quad x \in \mathbb{R}^n, t > 0 \\ u(x,0) = \varphi(x) \quad x \in \mathbb{R}^n \end{array} \right.$$

$$u(x,0) = \varphi(x) \quad x \in \mathbb{R}^n$$

对 Fourier 变换，有 $\partial_t \hat{u} + 4\pi^2 |\xi|^2 \hat{u} = \hat{f}(\xi, t)$

$$\hat{u}(\xi, 0) = \hat{\varphi}(\xi)$$

$$\Rightarrow \hat{u}(\xi, t) = \hat{\varphi}(\xi) e^{-4\pi^2 |\xi|^2 t} + \int_0^t e^{-4\pi^2 |\xi|^2 (t-s)} \hat{f}(\xi, s) ds$$

对 Fourier 逆变换，有

$$u(x,t) = \frac{1}{(4\pi t)^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4t}} \varphi(y) dy + \int_0^t \frac{1}{(4\pi(t-s))^{\frac{n}{2}}} \int_{\mathbb{R}^n} e^{-\frac{|x-y|^2}{4(t-s)}} f(y, s) dy ds$$

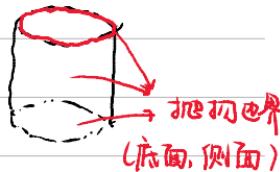
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3.2 极值原理和最大模估计

$$\text{方程 } \begin{cases} u_t - \Delta u = 0 & \text{in } \Omega \times \{t > 0\} \\ u|_{t=0} = \varphi(x) & \text{in } \Omega \end{cases}$$

$$u(x, t) = h(x, t) \quad \text{on } \partial\Omega \times \{t > 0\}$$

令 $\bar{\Omega}_T = \Omega \times [0, T]$, 定义抛物边界 $\Gamma_T = \overline{\Omega}_T \setminus Q_T$



Thm 1. 极值原理

$u \in C^{2,1}(\bar{\Omega}_T) \cap C(\overline{\Omega}_T)$ 满足 $\mathcal{L}u = u_t - \Delta u = f \leq 0$

则 $u(x, t)$ 在 $\overline{\Omega}_T$ 上最大值必在 Γ_T 上达到. Bp

$$\max_{\overline{\Omega}_T} u(x, t) = \max_{\Gamma_T} u(x, t)$$

$$\text{pr: } \exists M = \max_{\overline{\Omega}_T} u(x, t), m = \max_{\Gamma_T} u(x, t)$$

Step 1. $f < 0$, 若 $M > m$,

则 f 在 $(x_0, t_0) \in Q_T$ 上达到最大值

则 $u_{xx}(x_0, t_0) \leq 0$, $u_t(x_0, t_0) \geq 0$

$$\mathcal{L}u(x_0, t_0) = u_t(x_0, t_0) - (u_{xx}(x_0, t_0)) \geq 0 \text{ 矛盾}$$

Step 2. $f = 0$, 令 $v = u - Et$, 则 $\mathcal{L}v = \mathcal{L}u - E = f - E < 0$

由 Step 1.

$$\max_{\overline{\Omega}_T} u - Et \leq \max_{\Gamma_T} v = \max_{\Gamma_T} V \leq \max_{\Gamma_T} u$$

$$\text{由 } E \text{ 的任意性, } \max_{\overline{\Omega}_T} u = \max_{\Gamma_T} u$$

$$\text{由 } E \text{ 的任意性, } \max_{\overline{\Omega}_T} u = \max_{\Gamma_T} u$$

故 u 在 Γ_T 上最小值必在边界上取到

Thm 2. 比较原理

$u, v \in C^{2,1}(\bar{\Omega}_T) \cap C(\overline{\Omega}_T)$ 满足 $\mathcal{L}u \leq \mathcal{L}v$, $u|_{\partial\Omega_T} \leq v|_{\partial\Omega_T}$, 则在 $\overline{\Omega}_T$, $u(x, t) \leq v(x, t)$

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$$\text{pr: } \Delta w(x,t) = u(x,t) - v(x,t)$$

$$\mathcal{L}w = \mathcal{L}u - \mathcal{L}v \leq 0, \quad w|_{\partial Q_T} \leq 0$$

故由极值原理, $\max_{\overline{Q}_T} w = \max_{\overline{Q}_T} W$

$$\text{则 } u(x,t) \leq v(x,t) \quad \forall (x,t) \in \overline{Q}_T$$

thm 3. 最大模估计

设 $u \in C^{2,1}(\overline{Q}_T) \cap C(\overline{Q}_T)$ 为方程 $\begin{cases} \mathcal{L}u = f, \quad x \in (0,1) \times [t_0, T] \\ u|_{t=0} = \varphi(x) \quad x \in [0,1] \end{cases}$

的解, 则

$$\max_{\overline{Q}_T} |u(x,t)| \leq FT + B \quad \begin{cases} u|_{x=0} = \varphi(x) & x \in [0,1] \\ u|_{x=0} = g_1(t), \quad u|_{x=1} = g_2(t) & \end{cases}$$

$$F = \max_{Q_T} |f|, \quad B = \max \left\{ \max_{x \in [0,1]} |\varphi(x)|, \max_{[0,T]} |g_1(t)|, \max_{[0,T]} |g_2(t)| \right\}$$

$$\text{pr: } v = Ft + B - u$$

$$\begin{cases} \mathcal{L}v = F - f \geq 0 \\ v|_{\partial Q_T} = Ft + B - g_1/g_2 \geq 0 \end{cases}$$

由极大值原理, $\min_{\overline{Q}_T} v = \min_{\overline{Q}_T} V \geq 0$

$$\Rightarrow v(x,t) \geq 0 \quad \forall (x,t) \in \overline{Q}_T$$

$$\text{则 } u(x,t) \leq Ft + B$$

$$\text{对 } v = Ft + B + u \text{ 完成相同过程} \Rightarrow -u(x,t) \leq Ft + B$$

$$\Rightarrow |u(x,t)| \leq Ft + B \leq FT + B$$

Rmk. 可证明热方程解的唯一性、稳定性

下节课其余两类边值问题解的唯一性与稳定性

第三类边值问题

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$$\begin{cases} u_t - u_{xx} = f(x, t) \\ u(0, t) = M_1(t), \quad u_x + hu(l, t) = M_2(t), \quad h > 0 \\ u(x, 0) = \varphi(x) \end{cases}$$

pr: 只需证明 $\begin{cases} u_t - u_{xx} = 0 \\ u(0, t) = 0, \quad u_x + hu(l, t) = 0, \quad h > 0 \\ u(x, 0) = 0 \end{cases}$

只有零解.

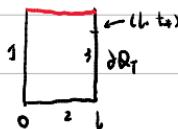
否则在 \mathbb{R}_T 上有非零解, 其有正时最大值或负的最小值.

设 $u=0$. 由极值原理, 最大值和最小值均在边界处取到

不妨设正的最大值在边界取到

$u(0, t) = u(x, 0) = 0 \Rightarrow$ 正的最大值在 \mathbb{R}_T 取到

设 u 在 (l, t_+) 取到正的最大值



$u_x(l, t_+) \geq 0, \text{ 且 } u_x + hu(l, t_+) > 0$ 与边条件矛盾

进而给出了第三类边值下解的唯一性

第二类边值问题

$$\begin{cases} u_t - u_{xx} = f(x, t) \\ u(0, t) = M_1(t), \quad u_x(l, t) = M_2(t) \\ u(x, 0) = \varphi(x) \end{cases}$$

只需求证 $\begin{cases} u_t - u_{xx} = 0 \\ u(0, t) = 0, \quad u_x(l, t) = 0 \\ u(x, 0) = 0 \end{cases}$

只有零解.

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pr: idea $(uw)_x = u_x w + uw_x$

将第二类边值问题为第三类边值

令 $\tilde{u}(x,t) = w(x)u(x,t)$, $U = \frac{\tilde{u}}{w}$

则 $U_t = \frac{\tilde{u}_t}{w} - \frac{\tilde{u}w - w\tilde{u}}{w^2}$, $U_{xx} = (-\frac{w_{xx}}{w^3} + 2\frac{w_x^2}{w^3})\tilde{u} - 2\frac{w_x}{w^2}\tilde{u}_x + \frac{1}{w}\tilde{u}_{xx}$

$\Rightarrow \frac{\tilde{u}_t}{w} + (\frac{w_{xx}}{w^3} - 2\frac{w_x^2}{w^3})\tilde{u} + \frac{2w_x}{w^2}\tilde{u}_x - \frac{1}{w}\tilde{u}_{xx}$

$\Rightarrow \tilde{u}_t - \tilde{u}_{xx} = -2\frac{w_x}{w}\tilde{u}_x - (\frac{w_{xx}}{w} - 2\frac{w_x^2}{w^3})\tilde{u}$

$\left\{ \begin{array}{l} \tilde{u}(0,t) = 0, \quad \tilde{u}_x(l,t) = w_x u + u_x w \quad (l,t) = w_x(l)u(l,t) = w_x(l), \frac{\tilde{u}(l,t)}{w(l)} \\ \tilde{u}(x,0) = 0 \end{array} \right.$

hope $\frac{w_x(l)}{w(l)} = -1$, $\Rightarrow w(x) = -x + l + 1$

则 $\left\{ \begin{array}{l} \tilde{u}_t - \tilde{u}_{xx} = \frac{2}{-x+l+1}\tilde{u}_x + 2\frac{1}{(-x+l+1)^2}\tilde{u} \quad (*) \\ \tilde{u}(0,t) = 0, \quad (\tilde{u}_x + \tilde{u})(l,t) = 0 \end{array} \right.$

$\tilde{u}(x,0) = 0$

令 $v(x,t) = e^{-\lambda t}\tilde{u}(x,t)$, $\tilde{u} = e^{\lambda t}v$

$\tilde{u}_t = V_t e^{\lambda t} + \lambda e^{\lambda t}v$

$\tilde{u}_x = e^{\lambda t}V_x \quad \tilde{u}_{xx} = e^{\lambda t}V_{xx}$

则 $\left\{ \begin{array}{l} V_t - V_{xx} - \frac{2}{-x+l+1}V_x + (\lambda - \frac{2}{(-x+l+1)^2})V = 0 \end{array} \right.$

$\left\{ \begin{array}{l} V(0,t) = 0, \quad (V_x + v)(l,t) = 0 \\ V(x,0) = 0 \end{array} \right.$

取 $\lambda > 2$, 则 $\lambda - \frac{2}{(-x+l+1)^2} > 0$

claim: V 在 \mathbb{R}_+ 上飞的最大值在边界取到

事实上, 若在 $V(x_0, t_0) = M > 0$, $(x_0, t_0) \in \Omega_T$

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则 $V_t(x_0, t_0) \geq 0$, $V_x(x_0, t_0) = 0$, $V_{xx}(x_0, t_0) \leq 0$

与方程条件矛盾

再利用第三类问题的处理给出第二类问题解的唯一性

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§3.3 初值问题的最大模估计

考虑初值问题的初值问题

$$\begin{cases} u_t - u_{xx} = f(x, t) & x \in \mathbb{R}, 0 < t \leq T \\ u(x, 0) = \psi(x) & x \in \mathbb{R} \end{cases}$$

Thm 1. 最大模估计

假设 $u \in C^{2,1}(\mathbb{Q}_T) \cap C(\bar{\mathbb{Q}}_T)$ 为上述问题的有界解

则 $\sup_{\mathbb{Q}_T} |u(x, t)| \leq T \sup_{\mathbb{Q}_T} |f(x, t)| + \sup_{x \in \mathbb{R}} |\psi(x)|$

令 $F = \sup_{\mathbb{Q}_T} |f(x, t)|$, $\Psi = \sup_{x \in \mathbb{R}} |\psi(x)|$, $M = \sup_{\mathbb{Q}_T} |u(x, t)|$

pr: $\forall L > 0$. 存在 $\mathbb{Q}_T^L = (-L, L) \times (0, T]$ 上的辅助函数

$$w(x, t) = Ft + \Psi + V_L(x, t) \pm u(x, t)$$

$$V_L(x, t) = \frac{M}{L^2} (x^2 + 2t)$$

(idea: $V_L(x, t)$ 为自由方程 $u_t - u_{xx} = 0$ 的解)

则 $w_t - w_{xx} = F \pm f \geq 0$

由极值原理, 最小值在边界处取到

$$w|_{t=0} = \Psi + \frac{M}{L^2} x^2 \pm \psi(x) \geq 0$$

$$w|_{x=L} = Ft + \Psi + M \sin \geq 0$$

$$\Rightarrow w(x, t) \geq 0 \quad (x, t) \in \mathbb{Q}_T^L$$

$\forall (x_0, t_0) \in \mathbb{Q}_T$. 取 L 充分大, st. $(x_0, t_0) \in \mathbb{Q}_T^L$

由于 $w(x_0, t_0) \geq 0$, 故

$$|u(x_0, t_0)| \leq Ft_0 + \Psi + \frac{M}{L^2} (x_0^2 + 2t_0)$$

$$\leq FT + \Psi + \frac{M}{L^2} (x_0^2 + 2t_0)$$

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令 $L \rightarrow +\infty$, 则 $|u(x_0, t_0)| \leq FT + \Phi$

由 (x_0, t_0) 的任意性, $\sup_{\Omega_T} |u(x, t)| \leq T \sup_{\Omega_T} |f(x, t)| + \sup_{x \in \mathbb{R}} |\psi(x)|$

Rmk. 有界性可以放宽为 $|u(x, t)| \leq M e^{\lambda x^2}, (x, t) \in \Omega_T$

下面用能量估计证明解的唯一性

考虑方程

$$\begin{cases} u_t - u_{xx} = f & (x, t) \in \Omega_T = [0, l] \times [0, T] \\ u|_{t=0} = \psi(x) \\ u|_{x=0} = u|_{x=l} = 0 \end{cases}$$

thm 2. 唯一性不等式

设 $u \in C^{1,0}(\bar{\Omega}_T) \cap C^{2,1}(\Omega_T)$ 为上述问题的解,

$$\begin{aligned} \text{则 } \sup_{0 \leq t \leq T} \int_0^l u^2(x, t) dx + 2 \int_0^T \int_0^l u_x^2(x, t) dx dt \\ \leq M \left(\int_0^l \psi^2(x) dx + \int_0^T \int_0^l f^2(x, t) dx dt \right) \end{aligned}$$

pr: $(u_t - u_{xx})u = fu$

$$u_t = \frac{1}{2}(u^2)_t - (u u_x)_x + (u_x)^2 = fu$$

在 $[0, l]$ 上积分, 有

$$\begin{aligned} \frac{d}{dt} \left[\frac{1}{2} \int_0^l u^2 dx - u u_x \right] \Big|_{x=0}^{x=l} + \int_0^l u_x^2 dx &= \int_0^l f u dx \\ \Rightarrow \frac{d}{dt} \left(\frac{1}{2} \int_0^l u^2 dx \right) + \int_0^l u_x^2 dx &\leq \frac{1}{2} \int_0^l f^2 dx + \frac{1}{2} \int_0^l u^2 dx \\ \Rightarrow \frac{d}{dt} \left(\int_0^l u^2 dx \right) &\leq \int_0^l f^2 dx + \int_0^l u^2 dx \\ \frac{d}{dt} \left(e^{-t} \int_0^l u^2 dx \right) &\leq e^{-t} \int_0^l f^2 dx \end{aligned}$$

$$u(0, t) \text{ 为 } \Rightarrow e^{-t} \int_0^l u^2 dx - y(0) \leq \int_0^t e^{-s} \int_0^l f^2(x, s) dx ds$$

$$\text{def } y(t) = \int_0^l u^2(x, t) dx$$

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$$\text{则 } y(t) \leq e^t y(0) + e^t \int_0^t \int_0^l f^2(x,s) dx ds$$

$$\Rightarrow \int_0^l u^2 dx \leq e^t \left(\int_0^l \varphi^2 dx + \int_0^t \int_0^l f^2(x,s) dx ds \right)$$

$$\leq e^t \left(\int_0^l \varphi^2 dx + \int_0^t \int_0^l f^2(x,s) dx ds \right) \quad \forall 0 < t \leq T$$

$$tx \frac{d}{dt} \left(\frac{1}{2} \int_0^l u^2 dx \right) + \int_0^l u_x^2 dx \leq \frac{1}{2} \int_0^l f^2 dx + \frac{1}{2} e^t \left(\int_0^l \varphi^2 dx + \int_0^t \int_0^l f^2(x,s) dx ds \right)$$

再从 0 到 t 积分，有

$$\frac{1}{2} \int_0^t \int_0^l u^2 dx + \int_0^t \int_0^l u_x^2 dx dt \leq \frac{1}{2} \int_0^l \varphi^2 dx + \frac{1}{2} \int_0^t \int_0^l f^2 dx dt$$

$$+ \frac{1}{2} (e^{2t} - 1) \left[\int_0^l \varphi^2 dx + \int_0^t \int_0^l f^2(x,s) dx ds \right]$$

$$\leq \frac{1}{2} e^t \int_0^t \int_0^l f^2(x,s) dx ds \quad \forall 0 < t \leq T$$

$$\Rightarrow \sup_{0 \leq t \leq T} \int_0^l u^2(x,t) dx + 2 \int_0^T \int_0^l u_x^2(x,t) dx dt$$

$$\leq e^T \left(\int_0^l \varphi^2 dx + \int_0^T \int_0^l f^2(x,t) dx dt \right)$$

Rmk. 可得到解的唯一性与稳定性.

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第四章 振动方程

方程的来源：均质弦/薄板/弹性体的自由/强迫振动

$u(x, t)$ 未知 $\Delta u = \partial_{x_1}^2 + \dots + \partial_{x_n}^2 u$

$$\begin{cases} \partial_t^2 u - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = f(x) & x \in \Omega \\ u_t(x, 0) = g(x) & x \in \Omega \end{cases}$$

初值，为关于 x 的函数
边值

Rmk. 物理意义

$f(x, t)$ 表示单位质量所受外力

第一类边值 (Dirichlet) $u(x, t) = h(x, t) \quad \forall x \in \partial\Omega$

第二类边值 (Newmann) $\frac{\partial u}{\partial n}(x, t) = h(x, t) \quad \forall x \in \partial\Omega$

第三类边值 (Robin) $\frac{\partial u}{\partial n}(x, t) + \alpha(x, t) u(x, t) = h(x, t) \quad \forall x \in \partial\Omega \quad \alpha(x, t) > 0$

Rmk. 边值意义

(Dirichlet) 边界点位移变化

若 $h(x, t) = h(x)$ ，则边界点固定

(Newmann) 边界点复力情况

若 $h(x, t) \equiv 0$ ，则无外力通过此对弹性体作用

(Robin) 位移与复力随性组合

若 $h(x, t) \equiv 0$ ，则此固定在支架

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§4.1 初值问题

§4.1.1 一阶偏微分方程的解

$$\begin{cases} \frac{\partial u}{\partial t} + a(x,t) \frac{\partial u}{\partial x} + b(x,t)u = f(x,t) \\ u(x,0) = \phi(x) \end{cases}$$

$u(x,t)$ 为未知函数 $-\infty < x < +\infty, t > 0$

若 $x = x(t)$, 令 $u(x(t), t) = U(t)$

$$\frac{dU}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} x'(t)$$

$x(t)$ 称为特征函数
 $\underbrace{x'(t)}_{= a(x(t), t)}, \frac{dU}{dt} + b(x(t), t)U(t) = f(x(t), t)$

令 $x(0) = C$, 则 $U(0) = u(x(0), 0) = \phi(C)$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = a(x(t), t) \\ x(0) = C \end{cases} \quad \begin{cases} \frac{dU}{dt} + b(x(t), t)U(t) = f(x(t), t) \\ U(0) = \phi(C) \end{cases}$$

转化为 2 个 ode

ex. $\begin{cases} \frac{\partial u}{\partial t} - a \frac{\partial u}{\partial x} = 0 \\ u(x,0) = \phi(x) \end{cases}$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = -a \\ x(0) = C \end{cases} \Rightarrow x(t) = -at + C$$

$$\begin{cases} \frac{dU}{dt} = 0 \\ U(0) = \phi(C) \end{cases} \Rightarrow U = \phi(C)$$

$$U(t) = \phi(x(t) + at) = u(x(t), t).$$

即 $u(x,t) = \phi(x+at)$.

ex. $\begin{cases} \frac{\partial u}{\partial t} - a \frac{\partial u}{\partial x} = f(x,t) \\ u(x,0) = \phi(x) \end{cases}$

$$\Rightarrow \begin{cases} \frac{dx}{dt} = -a \\ x(0) = C \end{cases} \Rightarrow x(t) = -at + C$$

$$\begin{cases} \frac{dU}{dt} = f(x(t), t) \\ U(0) = \phi(C) \end{cases}$$

$$X(t) \text{ 为 } \frac{dU}{dt} = f(-at+C, t)$$

$$\Rightarrow U(t) = \phi(C) + \int_0^t f(-a\tau + C, \tau) d\tau$$

$$u(x,t) = \phi(x+at) + \int_0^t f(x+a(t-\tau), \tau) d\tau$$

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ex. $\begin{cases} \frac{du}{dt} + (x+t) \frac{du}{dx} + u = x \\ u|_{t=0} = x \end{cases}$

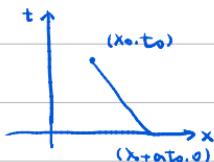
$\left\{ \begin{array}{l} \frac{du}{dt} = x+t \quad (\text{-阶线性}) \\ u(0) = C \end{array} \right. \Rightarrow u(t) = Ce^t - t - 1$

$\left\{ \begin{array}{l} \frac{du}{dt} + U(t) = Ce^t + e^t - t - 1 \\ U(0) = C \end{array} \right. \Rightarrow U(t) = -t + \frac{1}{2}(e^t - e^{-t}) + \frac{C}{2}(e^t - e^{-t})$

 $\Rightarrow u(x, t) = \frac{1}{2}(x-t+1) - e^{-t} + \frac{1}{2}(x+t+1)e^{-2t}$

Rank. 对第一个方程有如下较为几何的解释

在 $x(t) = -at + C$ 上, 有 $\frac{dx}{dt} = 0$



根据初值 $u(x_0 + at_0, 0) = \phi(x_0 + at_0) = u(x_0, t_0) \quad \forall x_0, t_0$

$$\Rightarrow u(x, t) = \phi(x + at)$$

同样地, 对第二个方程

$$u(x_0 + at_0, 0) = \phi(x_0 + at_0)$$

$$\begin{aligned} u(x_0, t_0) &= u(x_0 + at_0, 0) + \int_0^{t_0} f(x(t), t) dt \\ &= \phi(x_0 + at_0) + \int_0^{t_0} f(x_0 + a(t_0 - t), t) dt \quad \forall x_0, t_0 \\ \Rightarrow u(x, t) &= \phi(x + at) + \int_0^t f(x + a(t-T), T) dT \end{aligned}$$

操作方法将 PDE 转化为 ODE, 最终结果即在待分榜上对时间积分

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§4.1.2 问题的简化

对 \mathbb{R}^n , 反需提出初值条件(无边界)

考虑初值问题

$$\begin{cases} \partial_t^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x) \quad x \in \mathbb{R}^n, t > 0 \\ \partial_t u(x, 0) = \psi(x) \end{cases} \quad (4.6)$$

用构造的办法给出初值问题的解, 虽未说明唯一性

令 u_1 满足 $\begin{cases} \partial_t^2 u_1 - \Delta u_1 = 0 \\ u_1(x, 0) = \varphi(x) \end{cases}$ (4.7)

令 u_2 满足 $\begin{cases} \partial_t^2 u_2 - \Delta u_2 = 0 \\ u_2(x, 0) = 0 \end{cases}$ (4.8)

令 u_3 满足 $\begin{cases} \partial_t^2 u_3 - \Delta u_3 = f(x, t) \\ u_3(x, 0) = 0 \end{cases}$ (4.9)

“位移”

$\partial_t u_3(x, 0) = 0$ “外力”

则 $u_1 + u_2 + u_3$ 为 (4.6) 的解

thm 1. $u_2 = M_{\psi}(x, t)$ 为 (4.8) 解, 则 (4.7)、(4.9) 的解为

$$u_1 = \frac{\partial}{\partial t} M_{\psi}, \quad u_3 = \int_0^t M_{f(\cdot, t-\tau)} d\tau$$

pr. 令 $\tilde{u}_1 = M_{\psi}$, 则 $\begin{cases} \partial_t^2 \tilde{u}_1 - \Delta \tilde{u}_1 = 0 \\ \tilde{u}_1(x, 0) = 0 \\ \partial_t \tilde{u}_1(x, 0) = \varphi(x) \end{cases}$

令 $v = \partial_t \tilde{u}_1$, 则 $\begin{cases} \partial_t^2 v - \Delta v = 0 \\ v(x, 0) = \varphi(x) \\ \partial_t v(x, 0) = \partial_t^2 \tilde{u}_1(x, 0) = \Delta \tilde{u}_1(x, 0) = 0 \end{cases}$

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Rmk. 初值为先给函数，如 u_0 , u_t , u_{tt} . 再赋值 先赋值，再给函数

$$\text{在上述过程} \quad v(x,0) = \hat{u}_t(x,0) = \frac{\partial}{\partial t} \hat{u}(x,0) \times \frac{\partial}{\partial t} 0 = 0$$

对其余变量求偏导时，可交换给函数与赋值顺序

$$\text{令 } \tilde{u}_i(x,t) = M_{f_T}(x,t), \text{ 则} \begin{cases} \partial_t^2 \tilde{u}_i - \Delta \tilde{u}_i = 0 \\ \tilde{u}_i(x,0) = 0 \\ \partial_t \tilde{u}_i(x,0) = f_T = f(x,T) \quad T \text{ 为参数} \end{cases}$$

$$\text{令 } v(x,t) = M_{f_T}(x,t-T) = \hat{u}_i(x,t-T), \text{ 则}$$

$$\begin{cases} \partial_t^2 v - \Delta v = (\partial_t^2 \tilde{u}_i - \Delta \tilde{u}_i)(x,t-T) = 0 \\ v|_{t=T} = \hat{u}_i(x,0) = 0 \\ \partial_t v|_{t=T} = \partial_t \hat{u}_i(x,0) = f(x,T) \end{cases}$$

$$u_3 = \int_0^t M_{f_T}(x,t-T) dT$$

$$\begin{aligned} \partial_t u_3 &= M_{f_T}(x,0) + \int_0^t \frac{\partial}{\partial t} M_{f_T}(x,t-T) dT \\ &= \int_0^t \frac{\partial}{\partial t} M_{f_T}(x,t-T) dT \end{aligned}$$

$$\begin{aligned} \partial_t^2 u_3 &= \frac{\partial}{\partial t} M_{f_T}(x,0) + \int_0^t \frac{\partial^2}{\partial t^2} M_{f_T}(x,t-T) dT \\ &= f(x,t) + \int_0^t \Delta M_{f_T}(x,t-T) dT \\ &= f(x,t) + \Delta \int_0^t M_{f_T}(x,t-T) dT \\ &= f(x,t) + \Delta u_3 \end{aligned}$$

$$\text{且 } u_3(x,0) = 0, \quad \partial_t u_3(x,0) = 0$$

Rmk. “ Δ ”可写出来，由于为对 x 的导数，积分限不含 x

该过程被称为冲量原理 (Duhamel) 非齐次方程 \rightarrow 具有初速度齐次方程解的和

$$u_3(x,t) = \lim_{\|z\| \rightarrow 0} \sum_{i=0}^{n-1} M_{f_{T_i}}(x,t-T_i) \Delta t_i = \lim_{\|z\| \rightarrow 0} \sum_{i=0}^{n-1} M_{f_{T_i+\Delta t_i}}(x,t-T_i)$$

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变问题转换为如何求查方程 $\begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, 0) = 0, \quad \partial_t u(x, 0) = \psi(x) \end{cases}$

的解，thm 1. 指出了“速度”曲线具有平移性。

Recall: 傅立叶变换 $\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x) e^{-2\pi i x \cdot \xi} dx$ ξ 为向量

$$\begin{aligned} \widehat{\Delta f}(\xi) &= \int_{\mathbb{R}^n} \Delta f(x) e^{-2\pi i x \cdot \xi} dx = \sum_j \int_{\mathbb{R}^n} f_{x_j} e^{-2\pi i x \cdot \xi} dx \\ &= -\sum_j \int_{\mathbb{R}^n} f_{x_j} \cdot (-2\pi i \xi_j) e^{-2\pi i x \cdot \xi} dx \end{aligned}$$

f, f_{x_j} 在无穷远处 $\rightarrow 0$

$$\begin{aligned} &= -\sum_j (-2\pi i \xi_j) \int_{\mathbb{R}^n} f_{x_j} e^{-2\pi i x \cdot \xi} dx \\ &= \sum_j (-2\pi i \xi_j)^2 \int_{\mathbb{R}^n} f e^{-2\pi i x \cdot \xi} dx \\ &= -4\pi^2 |\xi|^2 \hat{f}(\xi) \end{aligned}$$

将分析运算转化为代数运算

方程 $\begin{cases} \partial_t^2 u - \Delta u = 0 \\ u|_{t=0} = \varphi(x), \quad u_t|_{t=0} = \psi(x) \end{cases}$

两边关于 x 的傅立叶变换， $\begin{cases} \partial_t^2 \hat{u}(\xi, t) + 4\pi^2 |\xi|^2 \hat{u}(\xi, t) = 0 \\ \hat{u}(\xi, 0) = \hat{\varphi}(\xi), \quad \partial_t \hat{u}(\xi, 0) = \hat{\psi}(\xi) \end{cases}$

ξ 视作参数，则为二阶常微分方程， $\lambda^2 + 4\pi^2 |\xi|^2 = 0 \Rightarrow \lambda = \pm 2\pi |\xi| i$

$$\Rightarrow \hat{u}(\xi, t) = C_1 \cos(2\pi t |\xi|) + C_2 \sin(2\pi t |\xi|)$$

$$\hat{u}(\xi, 0) = \hat{\varphi} = \hat{\varphi}(\xi)$$

$$\partial_t \hat{u}(\xi, 0) = C_2 \cdot 2\pi |\xi| = \hat{\psi}(\xi)$$

$$\Rightarrow \hat{u}(\xi, t) = \cos(2\pi t |\xi|) \hat{\varphi}(\xi) + \frac{\sin(2\pi t |\xi|)}{2\pi |\xi|} \hat{\psi}(\xi)$$

Rmk. 也说明了 u_1, u_2 有解的关系

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$$\begin{cases} \partial_t^2 u_3 - \Delta u_3 = f(x, t) \\ u_3(x, 0) = 0, \quad \partial_t u_3(x, 0) = 0 \end{cases}$$

关于 x 又傅立叶变换， $\begin{cases} \partial_t^2 \hat{u}_3 + 4\omega^2 |\xi|^2 \hat{u}_3 = \hat{f}(\xi, t) \\ \hat{u}_3(\xi, 0) = 0, \quad \partial_t \hat{u}_3(\xi, 0) = 0 \end{cases}$

$$\Rightarrow \hat{u}_3(\xi, t) = \int_0^t \frac{\sin(2\omega|\xi|(t-\tau))}{2\omega|\xi|} \hat{f}(\xi, \tau) d\tau$$

Rmk. 也说明了 u_2, u_3 的关系。

若对 x, t 同时变换 $x \rightarrow \xi, t \rightarrow s$

$$-4\omega^2 s^2 \hat{u} + 4\omega^2 |\eta|^2 \hat{u} = 0$$

$$\Rightarrow (|\eta|^2 - s^2) \hat{u}(s, \xi) = 0$$

$$\Rightarrow s^2 = |\eta|^2 \quad (s, \eta) \in \mathbb{R}^{+n} \text{ 构成锥面}$$

表明 \hat{u} 仅在锥面上可不为 0，波方程对时间的 Fourier 变换

只在锥面上。

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§ 4.1.3 一维初值问题

若在 \mathbb{R} 上波动方程 $\begin{cases} \partial_t^2 u - \partial_x^2 u = f(x,t) & x \in \mathbb{R}, t > 0 \\ u(x,0) = \varphi(x) & x \in \mathbb{R} \\ \partial_t u(x,0) = \psi(x) & x \in \mathbb{R} \end{cases} \quad (4.13)$

Rmk. x 的范围会影响解方程的方法与结果

$$\begin{cases} \partial_t^2 u_2 - \partial_x^2 u_2 = 0 \\ u_2(x,0) = 0 \\ \partial_t u_2(x,0) = \psi(x) \end{cases} \quad (4.8) \quad (\text{由上节 thm 知只需求解该方程即得一维波动方程的解})$$

$$\text{Bp } (\partial_t + \partial_x)(\partial_t - \partial_x)u = 0$$

$$\begin{cases} \text{令 } V(x,t) = (\partial_t - \partial_x)u, \text{ Bp } \begin{cases} \partial_t V + \partial_x V = 0 \\ V(x,0) = (\partial_t - \partial_x)u(x,0) = \psi(x) \end{cases} \end{cases}$$

$$\Rightarrow V(x,t) = \psi(x-t)$$

$$\begin{cases} \partial_t u - \partial_x u = \psi(x-t) \\ u(x,0) = 0 \end{cases}$$

$$\Rightarrow u(x,t) = \int_0^t \underbrace{\psi(x-t-\tau)}_{y} d\tau$$

$$= \frac{1}{2} \int_{x-t}^{x+t} \psi(y) dy$$

$$\text{Bz } u_2(x,t) = \frac{1}{2} \int_{x-t}^{x+t} \psi(y) dy$$

Bz (4.13) 解为

$$u_1(x,t) = \frac{1}{2} \left(\int_{x-t}^{x+t} \psi(y) dy \right)$$

$$u_1 + u_2 + u_3 \quad (4.20)$$

$$= \frac{1}{2} (\varphi(x+t) + \varphi(x-t))$$

thm 2 (D'Alembert 公式)

$$u_3(x,t) = \int_0^t \frac{1}{2} \int_{x-(t-\tau)}^{x+(t-\tau)} f(y,\tau) dy d\tau$$

$$= \frac{1}{2} \int_0^t \int_{x-t-\tau}^{x+(t-\tau)} f(y,\tau) dy d\tau$$

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$$\text{若 } f \equiv 0, \text{ 则 } F(x) = \frac{1}{2} \psi(x) + \frac{1}{2} \int_0^x \psi(y) dy$$

$$f_t(x) = \frac{1}{2} \psi'(x) + \frac{1}{2} \int_x^0 \psi'(y) dy$$

$$\Rightarrow u(x, t) = F(x+t) + f_t(x-t)$$

均匀波 石行波

thm 3 满足形式解存在条件 (形式解 \rightarrow 古典解)

$$\psi \in C^2(\mathbb{R}), \quad \psi' \in C^1(\mathbb{R}), \quad f \in C^1(\mathbb{R} \times \mathbb{R}_+)$$

则 (4.20) 满足的函数 $u \in C^2(\mathbb{R} \times \mathbb{R}_+)$, 且为初值问题 (4.13) 的解

$$\text{pr. } u(x, t) = \frac{1}{2} (\psi(x+at) + \psi(x-at)) + \frac{1}{2a} \int_{x-at}^{x+at} \psi(y) dy + \frac{1}{2a} \int_0^t \int_{x-a(t-\tau)}^{x+a(t-\tau)} f(y, \tau) dy d\tau$$

① $u(x, t) \in C(\mathbb{R} \times \mathbb{R}_+)$ 为连续函数 复合/变限积分

$$\begin{aligned} \textcircled{2} \quad u_x(x, t) &= \frac{a}{2} \psi'(x+at) - \frac{a}{2} \psi'(x-at) + \frac{1}{2a} (a \psi'(x+at) + a \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t a f(x+a(t-\tau), \tau) + a f(x-a(t-\tau), \tau) d\tau \end{aligned}$$

$$\begin{aligned} u_x(x, t) &= \frac{1}{2} \psi'(x+at) + \frac{1}{2} \psi'(x-at) + \frac{1}{2a} (\psi'(x+at) - \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t [f(x+a(t-\tau), \tau) - f(x-a(t-\tau), \tau)] d\tau \end{aligned}$$

$u(x, t) \in C^1(\mathbb{R} \times \mathbb{R}_+)$, 由于 $u_t, u_x \in C(\mathbb{R} \times \mathbb{R}_+)$

$$\begin{aligned} \textcircled{3} \quad u_{tt}(x, t) &= \frac{a^2}{2} \psi''(x+at) + \frac{a^2}{2} \psi''(x-at) + \frac{1}{2a} (a^2 \psi'(x+at) - a^2 \psi'(x-at)) \\ &\quad + \frac{1}{2a} [2a f(x, t) + \int_0^t a^2 f_x(x+a(t-\tau), \tau) - a^2 f_x(x-a(t-\tau), \tau) d\tau] \end{aligned}$$

$$\begin{aligned} u_{xx}(x, t) &= \frac{1}{2} \psi''(x+at) + \frac{1}{2} \psi''(x-at) + \frac{1}{2a} (\psi'(x+at) - \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t [f_x(x+a(t-\tau), \tau) - f_x(x-a(t-\tau), \tau)] d\tau \end{aligned}$$

$$\begin{aligned} u_{tx}(x, t) &= \frac{a}{2} \psi'(x+at) - \frac{a}{2} \psi'(x-at) + \frac{1}{2} (\psi'(x+at) + \psi'(x-at)) \\ &\quad + \frac{1}{2a} \int_0^t a f_x(x+a(t-\tau), \tau) + a f_x(x-a(t-\tau), \tau) d\tau \end{aligned}$$

$$C(C(\mathbb{R} \times \mathbb{R}_+)) = u_{tx}(x, t)$$

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$$u(x, t) \in C^2(\mathbb{R} \times \mathbb{R}_+)$$

$$\textcircled{4} \quad u_{tt} - a^2 u_{xx} = f(x, t)$$

$$u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x)$$

则 u 为初值问题的解

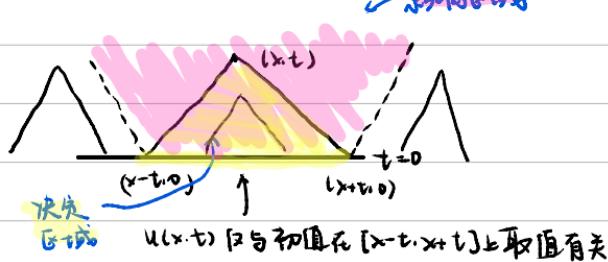
thm 4 利用形式解分析性质

若 φ, ψ, f 为 x 的偶/奇/周期为 1 函数

由 (4.20) 得出的解 u 为 x 的偶/奇/周期为 1 函数

Rmk. 具何性质

对 $f \equiv 0$,



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§ 4.1.4 一维半无界问题

初值问题 $\begin{cases} \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = f(x, t) & x > 0, t > 0 \\ u(x, 0) = \varphi(x) & x \geq 0 \\ \frac{\partial u}{\partial t}(x, 0) = \psi(x) & x \geq 0 \\ u(0, t) = g(t) & t \geq 0 \end{cases}$ (4.21)

1. 若 $g(t) \equiv 0$, 则奇延拓.

$$\begin{aligned} \bar{u}(t, x) &= \begin{cases} \varphi(x), & x \geq 0 \\ -\varphi(-x), & x < 0 \end{cases} & \bar{u}(x) &= \begin{cases} \varphi(x), & x \geq 0 \\ -\varphi(-x), & x < 0 \end{cases} & \bar{f}(x, t) &= \begin{cases} f(x, t), & x \geq 0 \\ -f(-x, t), & x < 0 \end{cases} \end{aligned}$$

Rmk. 奇延拓, 则 $u(0) = 0$; 偶延拓, 则 $u'(0) = 0$

令 $\bar{u}(x, t)$ 为方程 $\begin{cases} \frac{\partial^2 \bar{u}}{\partial t^2} - \frac{\partial^2 \bar{u}}{\partial x^2} = \bar{f}(x, t) & x \in \mathbb{R}, t > 0 \\ \bar{u}(x, 0) = \bar{\varphi}(x) & x \in \mathbb{R} \\ \frac{\partial \bar{u}}{\partial t}(x, 0) = \bar{\psi}(x) & x \in \mathbb{R} \end{cases}$

的解, 由于对 x 的奇性, $\bar{u}(0, t) = 0, t \geq 0$ 为边值

$$由 (4.20), \bar{u}(x, t) = \frac{1}{2}(\bar{\varphi}(x+t) + \bar{\varphi}(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} \bar{\psi}(y) dy + \frac{1}{2} \int_0^t \int_{x-(t-\tau)}^{x+(t-\tau)} \bar{f}(y, \tau) dy d\tau$$

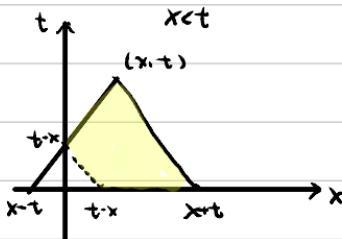
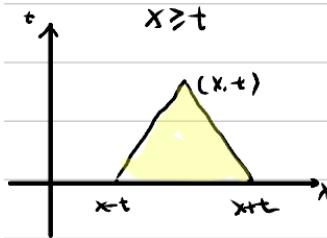
$x > 0, x \geq t$ 时,

$$u(x, t) = \frac{1}{2}(\varphi(x+t) + \varphi(x-t)) + \int_{x-t}^{x+t} \psi(y) dy + \frac{1}{2} \int_0^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau \quad (4.23)$$

$x > 0, x < t$ 时,

$$\begin{aligned} u(x, t) &= \frac{1}{2}(\varphi(x+t) - \varphi(t-x)) + \frac{1}{2} \int_0^{x+t} \psi(y) dy + \frac{1}{2} \int_{x-t}^0 -\psi(-y) dy \\ &+ \frac{1}{2} \int_{t-x}^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_0^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_{x-(t-\tau)}^0 -f(-y, \tau) dy d\tau \\ &= \frac{1}{2}(\varphi(x+t) - \varphi(t-x)) + \frac{1}{2} \int_{t-x}^{x+t} \psi(y) dy \\ &+ \frac{1}{2} \int_{t-x}^t \int_{x-(t-\tau)}^{x+(t-\tau)} f(y, \tau) dy d\tau + \frac{1}{2} \int_0^{t-x} \int_{(t-\tau)-x}^{(t-\tau)+x} f(y, \tau) dy d\tau \quad (4.24) \end{aligned}$$

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黄色部分所示为积分区域。

如何完成从形式解到古典解过度? Rem. 古典解: 所需的各阶偏导数连续可微, 相容性条件: 且在边界处连续

$$\textcircled{1} \quad \lim_{\substack{x \rightarrow 0^+ \\ \parallel}} u(x, 0) = u(0, 0) = \lim_{\substack{t \rightarrow 0^+ \\ \parallel}} u(0, t) \\ \varphi(0) \qquad \qquad \qquad g(0) = 0 \quad \varphi(0) = 0 \quad (4.25)$$

$$\textcircled{2} \quad \lim_{\substack{x \rightarrow 0^+ \\ \parallel}} u_x(x, 0) = u_t(0, 0) = \lim_{\substack{t \rightarrow 0^+ \\ \parallel}} u_t(0, t) \\ \psi(0) \qquad \qquad \qquad g'(0) = 0 \quad \psi(0) = 0 \quad (4.26)$$

$$\textcircled{3} \quad \lim_{\substack{x \rightarrow 0^+ \\ \parallel}} u_{tt}(x, 0) = u_{tt}(0, 0) = \lim_{\substack{t \rightarrow 0^+ \\ \parallel}} u_{tt}(0, t) \\ \lim_{x \rightarrow 0^+} (\partial_x^2 u(x, 0) + f(x, 0)) \qquad \qquad g''(0) = 0 \quad \varphi''(0) + f(0, 0) = 0 \quad (4.27)$$

thm 5

若 (4.21) 初值 $\varphi(x) \in C^2(\mathbb{R}^+)$, $\psi(x) \in C^1(\mathbb{R}^+)$, $f(x, t) \in C^1(\overline{\mathbb{R}^+} \times \mathbb{R}^+)$

满足相容性条件, 且边值 $g(t) \equiv 0$. (4.23), (4.24) 险些函数 $u \in C^2(\overline{\mathbb{R}^+} \times \mathbb{R}^+)$

且为 (4.21) 的解

2. 若 $g(t) \neq 0$, 令 $v(x, t) = u(x, t) - g(t)$

$$\text{则 } v(0, t) = u(0, t) - g(t) = 0$$

原方程转化为

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$$\begin{cases} \partial_t^2 v - \partial_x^2 v = f(x, t) - g''(t) \\ V(x, 0) = u(x, 0) - g(0) = \varphi(x) - g(0) \\ \partial_t V(x, 0) = \partial_t u(x, 0) - g'(0) = \psi(x) - g'(0) \end{cases}$$

即转化为情形 1.

再给出更一般相容性条件

thm 6 相容性条件

$$\varphi(0) = g(0), \quad \psi(0) = g'(0), \quad f(0, 0) + \varphi''(0) = g''(0)$$

Rmk. 相容性条件保证了初值与边值在二阶可微时的自洽。

thm 7 第二类边值问题

给定 $u_{x,0}(t) = g(t)$. 则令 $u(x, t) = xg_1(t) + V(x, t)$

$V(x, t)$ 满足 $V_x(0, t) = 0$, 之后利用隔延拓得到 $V(x, t)$, 进而得到 $u(x, t)$

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§ 4.1.5 三维初值问题

$$n=3 \quad \left\{ \begin{array}{l} \partial_t^2 u - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \end{array} \right.$$

齐次坐标系下, $\Delta u = \partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u$ (Δ_S 表示 S^2 上 Laplace 算子)

$$\partial_r^2 u - (\partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u) = f(x, t)$$

$$\Delta \equiv \operatorname{div} \nabla$$

1. 先考虑 $f(x, t) = 0$ 的情形

$$\partial_r^2 u - (\partial_r^2 u + \frac{2}{r} \partial_r u + \frac{1}{r^2} \Delta_S u) = 0$$

$$\begin{aligned} \int_{S^2} \Delta_S u \, d\omega &= \int_{S^2} \operatorname{div} \nabla u \, d\omega \\ &= \int_{\partial S^2} \frac{\partial u}{\partial n} \, ds = 0 \end{aligned}$$

对方程两边在 S^2 上积分, S^2 为单位球面

$$\partial_r^2 \int_{S^2} u \, d\omega - (\partial_r^2 \int_{S^2} u \, d\omega + \frac{2}{r} \partial_r \int_{S^2} u \, d\omega) = 0$$

$$\therefore \bar{u}(t, r) = \frac{1}{4\pi} \int_{S^2} u \, d\omega$$

$$\text{则 } \partial_r^2 \bar{u} - \partial_r^2 \bar{u} - \frac{2}{r} \partial_r \bar{u} = 0$$

$$\therefore \bar{u}(t, r) = r^{-k} V(t, r)$$

$$\partial_r \bar{u} = -k r^{-k-1} V(t, r) + r^{-k} \partial_r V$$

$$\begin{aligned} \partial_r^2 \bar{u} &= -k [(-k-1)r^{-k-2} V(t, r) + r^{-k-1} \partial_r V] + (-k)r^{-k-1} \partial_r V + r^{-k} \partial_r^2 V \\ &= k(k+1)r^{-k-2} V - 2kr^{-k-1} \partial_r V + r^{-k} \partial_r^2 V \end{aligned}$$

$$\begin{aligned} \partial_r^2 \bar{u} + \frac{2}{r} \partial_r \bar{u} &= k(k+1)r^{-k-2} V - 2kr^{-k-1} \partial_r V + r^{-k} \partial_r^2 V \\ &\quad - 2kr^{-k-2} V + 2r^{-k-1} \partial_r V \end{aligned}$$

$$\text{设 } k=1, \quad V(t, r) = r \bar{u}(t, r)$$

$$\therefore \partial_r^2 V - \partial_r^2 V = 0$$

$$\left\{ \begin{array}{l} V(r, 0) = r \bar{u}(r, 0) = r \bar{\varphi}(r) \quad r \geq 0, \text{ "表示积分} \\ \partial_r V(r, 0) = r \partial_r \bar{u}(r, 0) = r \bar{\psi}(r) \end{array} \right.$$

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将 V 关于 r 作偶延拓，得到 \bar{V}

以下由 “ $-$ ” 表示延拓后函数

$$\Rightarrow \bar{V}(r, t) = \frac{1}{2} ((r+t)\bar{\varphi}(r+t) + (r-t)\bar{\varphi}(r-t)) + \frac{1}{2} \int_{r-t}^{r+t} y \bar{\Psi}(y) dy$$

Rmk.

$\partial_t^2 u - \Delta u = 0$ 和以下变换中不变：

时间平移： $u(x, t) \mapsto u(x, t+t_0)$

空间平移： $u(x, t) \mapsto u(x+x_0, t)$

伸缩变换： $u(x, t) \mapsto u\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right), \lambda > 0 \equiv u^\lambda(x, t)$

$$(\partial_t^2 u^\lambda)(x, t) = \partial_t^2(u\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right)) = (\partial_t^2 u)\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right) \cdot \frac{1}{\lambda^2}$$

$$\partial_t^2 u^\lambda(x, t) = (\partial_t^2 u)\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right) \cdot \frac{1}{\lambda^2}$$

$$\text{且 } \partial_t^2 u^\lambda - \Delta u^\lambda = (\partial_t^2 u)\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right) \cdot \frac{1}{\lambda^2} - \frac{1}{\lambda^2}(\Delta u)\left(\frac{x}{\lambda}, \frac{t}{\lambda}\right) = 0$$

Lorentz 变换： $u(x, t) \rightarrow u(x-x_v + \frac{x_v-vt}{\sqrt{1-v^2}}, \frac{t-v \cdot x}{\sqrt{1-v^2}})$

$$x_v \equiv \left(x \frac{v}{|v|}\right) \frac{v}{|v|}$$

以上方程中 $\bar{V} \rightarrow V \rightarrow \bar{u}$ ，下考察 \bar{u} 与 u 的关系

$$\bar{U}(r, t) = \frac{1}{4\pi} \int_{S^2} u d\omega = \frac{1}{4\pi} \int_{S^2} u(r, w) d\omega$$

$$\bar{u}(r, t) = u(r, t) = \partial_r(r \bar{u}(r, t)) \Big|_{r=0}$$

$$= \partial_r V \Big|_{r=0}$$

$$= \frac{1}{2} (\bar{\varphi}(t) + t \bar{\varphi}'(t) + \bar{\varphi}(-t) - t \bar{\varphi}'(-t))$$

$$+ \frac{1}{2} (t \bar{\Psi}(t) - (-t) \bar{\Psi}(-t))$$

$$= \bar{\varphi}(t) + t \bar{\varphi}'(t) + t \bar{\Psi}(t)$$

$$= \frac{d}{dt} (t \bar{\varphi}(t)) + t \bar{\Psi}(t)$$

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$$\begin{aligned} &= \frac{d}{dt} (t \bar{\varphi}(t)) + t \bar{\psi}(t) \\ &= \frac{d}{dt} \left(\frac{t}{4\pi} \int_{S^2} \varphi(tw) dw \right) + \frac{t}{4\pi} \int_{S^2} \psi(tw) dw \end{aligned}$$

对 $U(x+x_0, t)$ 应用于上一步,

其初值为 $\varphi(x+x_0), \psi(x+x_0)$

$\sum x = 0$.

$$U(x_0, t) = \frac{d}{dt} \left(\frac{t}{4\pi} \int_{S^2} \varphi(x_0 + tw) dw \right) + \frac{t}{4\pi} \int_{S^2} \psi(x_0 + tw) dw$$

$$x_0 \rightarrow x, \quad y = x + tw$$

$$U(x, t) = \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|y-x|=t} \varphi(y) dS(y) \right) + \frac{1}{4\pi t} \int_{|y-x|=t} \psi(y) dS(y)$$

(kirchhoff)

2. f 不恒为 0

$$\begin{aligned} U(x, t) &= \frac{1}{4\pi t} \int_{|y-x|=t} \varphi(y) dS(y) + \frac{1}{4\pi t} \int_{|y-x|=t} \psi(y) dS(y) \\ &\quad + \int_0^t \frac{1}{4\pi(t-\tau)} \int_{|x-y|=t-\tau} f(y, z) dy dz \end{aligned}$$

Rmk: $t \geq n=3$ 时可良好转化为一个主微分方程问题

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§ 4.1.b 二维初值问题

$$n=2, \begin{cases} \frac{\partial^2 u}{\partial t^2} - \Delta u = f(x, t) \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \end{cases}$$

$$1. f(x, t) \equiv 0$$

$$\text{令 } \tilde{u}(x, t) = u(x, t) \quad \tilde{x} = (x_1, x_2, x_3)$$

$$\tilde{\varphi}(x) = \varphi(x_1, x_2)$$

$$\tilde{\psi}(x) = \psi(x_1, x_2)$$

则 $\tilde{u}(x, t)$ 为三维波方程的解.

$$\text{By } \begin{cases} \Delta^2 \tilde{u} - \Delta \tilde{u} = 0 \\ \tilde{u}(x, 0) = \tilde{\varphi}(x), \quad \Delta \tilde{u}(x, 0) = \tilde{\psi}(x) \end{cases}$$

由 Kirchhoff,

$$\tilde{u}(x, t) = \frac{1}{at} \left(\frac{1}{4\pi t} \int_{|x-\tilde{y}|=t} \tilde{\varphi}(\tilde{y}) dS(\tilde{y}) \right) + \frac{1}{4\pi t} \int_{|x-\tilde{y}|=t} \tilde{\psi}(\tilde{y}) dS(\tilde{y})$$

$u(x, t)$

$$x_1, x_2, x_3 = 0 \text{ 时}, \quad \tilde{u}(0, t) = u(0, t) = \frac{1}{at} \left(\frac{1}{4\pi t} \int_{|y_1|=t} \varphi(y_1, y_2) dS(\tilde{y}) \right) + \frac{1}{4\pi t} \int_{|y_1|=t} \psi(y_1, y_2) dS(\tilde{y})$$

注意到 $\int_{|y_1|=t} \psi(y_1, y_2) dS(\tilde{y})$

$$= 2 \int_{y_3 = \sqrt{t^2 - y_1^2 - y_2^2}} \psi(y_1, y_2) dS(\tilde{y})$$

$$= 2 \int_{y_1^2 + y_2^2 \leq t^2} \psi(y_1, y_2) \sqrt{1 + \left(\frac{\partial y_1}{\partial y_3}\right)^2 + \left(\frac{\partial y_2}{\partial y_3}\right)^2} dy_1 dy_2$$

$$= 2 \int_{y_1^2 + y_2^2 \leq t^2} \psi(y_1, y_2) \frac{t}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2$$

$$\frac{\partial y_3}{y_3} = \frac{-y_1}{\sqrt{t^2 - y_1^2 - y_2^2}}$$

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$$\Rightarrow u(0,t) = \frac{1}{dt} \left(\frac{1}{2\pi} \int_{B(0,t)} \frac{\psi(y_1, y_2)}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2 \right) + \frac{1}{2\pi} \int_{B(0,t)} \frac{\psi(y_1, y_2)}{\sqrt{t^2 - y_1^2 - y_2^2}} dy_1 dy_2$$

2. $u(x+x_0, t)$ 利用结论

$$u(x, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{|y| < t} \frac{\psi(y+x_0)}{\sqrt{t^2 - y^2}} dy \right) + \frac{1}{2\pi} \int_{|y| < t} \frac{\psi(y+x_0)}{\sqrt{t^2 - y^2}} dy$$

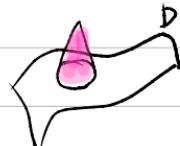
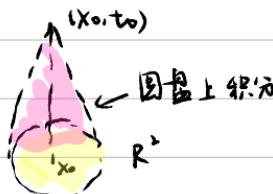
由 x_0 附着性 $u(x, t) = \frac{d}{dt} \left(\frac{1}{2\pi} \int_{|y-x| < t} \frac{\psi(y)}{\sqrt{t^2 - |y-x|^2}} dy \right) + \frac{1}{2\pi} \int_{|y-x| < t} \frac{\psi(y)}{\sqrt{t^2 - |y-x|^2}} dy$

2. $f \neq 0$

3. 1维

$$u(x, t) = \frac{d}{dt} \left(\frac{1}{4\pi t} \int_{|y-x|=t} \psi(y) dS(y) \right) + \frac{1}{4\pi t} \int_{|y-x|=t} \psi(y) dS(y) \quad (\text{Kirchhoff})$$

(x_0, t_0) 又与初值在球面上积分有关

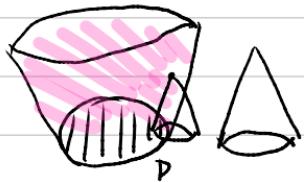


依赖区域: (x_0, t_0) 依赖于 $\{x \mid |x-x_0| \leq t_0\}$ 的值

$$\|u\|_{x_0, t_0}$$

决定区域: $\{(x, t) \mid D_{x, t} \subset D\}$ 为 D 的决定区域

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影响区域

Rmk. 光的性质

1. 光传播具有有限传播速度

2. Huygens 原理

$n=3$, 依赖于球面

$n=2$, 依赖于圆盘内

3.



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§4.1.7 能量估计

$$U_{tt} - \Delta U = 0 \Rightarrow U_t(U_{tt} - \Delta U) = 0$$

$$U_t U_{tt} = \frac{1}{2} \partial_t (U_t)^2$$

$$\begin{aligned} U_t \Delta U &= \sum_{i=1}^n U_{ti} U_{xi} = \sum_{i=1}^n [\partial x_i (U_t U_{xi}) - \partial_t \partial x_i U U_{xi}] \\ &= \sum_{i=1}^n [\partial x_i (U_t U_{xi}) - \frac{1}{2} \partial_t (U_{xi})^2] \\ &= \operatorname{div}(U_t \nabla U) - \frac{1}{2} \partial_t |\nabla U|^2 \end{aligned}$$

$$\Rightarrow \partial_t [\frac{1}{2} (U_t)^2 + \frac{1}{2} |\nabla U|^2] - \operatorname{div}(U_t \nabla U) = 0$$

物理能量守恒微分形式

U、密度等参数空间无界 $\rightarrow 0$

$$\text{RJ } \partial_t \int_{\mathbb{R}^n} (\frac{1}{2} U_t^2 + \frac{1}{2} |\nabla U|^2) dx - \int_{\mathbb{R}^n} \operatorname{div}(U_t \nabla U) = 0$$

$$\text{取度量 } \int_{\Omega} \operatorname{div} \bar{F} dx = \int_{\partial\Omega} \bar{F} \cdot \bar{n} ds$$

$$\Rightarrow \partial_t \int_{\mathbb{R}^n} (\frac{1}{2} U_t^2 + \frac{1}{2} |\nabla U|^2) dx = 0$$

$$\text{令 } E(t) = \int_{\mathbb{R}^n} \frac{1}{2} U_t^2 + \frac{1}{2} |\nabla U|^2 dx, \text{ RJ } E(t) = E(0)$$

物理能量守恒积分形式

$$\text{若 } \left\{ \begin{array}{l} \partial_t^2 U - \Delta U = 0 \quad x \in \Omega \subset \mathbb{R}^n, t > 0 \\ U|_{\partial\Omega} = 0, \quad U(x, 0) = \varphi(x), \quad U_t(x, 0) = \psi(x) \end{array} \right.$$

$$U|_{\partial\Omega} = 0, \quad U(x, 0) = \varphi(x), \quad U_t(x, 0) = \psi(x)$$

$$\partial_t [\frac{1}{2} (U_t)^2 + \frac{1}{2} |\nabla U|^2] = \operatorname{div}(U_t \nabla U)$$

$$\frac{d}{dt} \int_{\Omega} \frac{1}{2} (U_t)^2 + \frac{1}{2} |\nabla U|^2 dx = \int_{\Omega} \operatorname{div}(U_t \nabla U) dx$$

$$= \int_{\partial\Omega} U_t \nabla U \cdot \bar{n} ds$$

$$= \int_{\partial\Omega} U_t \frac{\partial U}{\partial n} ds$$

$$U|_{\partial\Omega} = 0 \Rightarrow U_t|_{\partial\Omega} = 0 \Rightarrow E(t) = \int_{\Omega} \frac{1}{2} (U_t)^2 + \frac{1}{2} |\nabla U|^2, \text{ RJ } E(t) = E(0)$$

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若 $\begin{cases} \partial_t^2 u - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = \psi(x), \quad u_t(x, 0) = \psi_t(x) & x \in \Omega \end{cases}$ 有唯一解 $u(x, t)$

$u|_{\partial\Omega} = h(x, t) \quad t \geq 0$ 第一类边值

该方程最多有一个右解.

pr: 设 (类为) 有两个解 u_1, u_2 .

$$\text{令 } u(x, t) = u_1(x, t) - u_2(x, t)$$

则 $\begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, 0) = 0, \quad u_t(x, 0) = 0 \\ u|_{\partial\Omega} = 0 \end{cases}$

由能量估计, 令 $E(t) = \frac{1}{2} \int_{\Omega} u_t^2 + |\nabla u|^2 dx$

则 $E(t) = E(0) = 0$

$$\Rightarrow u_t = 0, \quad \nabla u = 0 \quad \forall x \text{ in } \Omega, \quad t \geq 0$$

$$\Rightarrow u = \text{const} \quad \text{in } \Omega$$

由于 u 边值为 0, 为使得 u 在 Ω 上, $u \equiv 0$

Rmk. 对第二类边值, 能量估计时

$$\frac{d}{dt} \int_{\Omega} \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 dx = \int_{\partial\Omega} u_t \frac{\partial u}{\partial n} ds$$

给出 $\frac{\partial u}{\partial n} = 0$ 的条件可类比 u_t 对于

对第三类边值, $\frac{\partial u}{\partial n} + \alpha u = 0 (\alpha > 0), \quad x \in \partial\Omega$

def. $E(t) = \frac{1}{2} \int_{\Omega} u_t^2 + |\nabla u|^2 dx + \frac{1}{2} \int_{\partial\Omega} \alpha u^2 dx$

则 $\frac{dE(t)}{dt} = 0$

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若 $\begin{cases} \partial_t^2 u - \Delta u = f(x, t) & x \in \Omega, t > 0 \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) & x \in \Omega \end{cases}$ 初值 (3.3)

$$u|_{\partial\Omega} = 0 \quad t \geq 0 \quad \text{第二边值}$$

(3.3) 的解在下述意义下关于初值和右端项稳定:

$$\forall \varepsilon > 0, \exists \eta = \eta(\varepsilon, T), \text{ s.t.}$$

若 $\|\varphi_1 - \varphi_2\|_{L^2(\Omega)} \leq \eta, \|\nabla \varphi_1 - \nabla \varphi_2\|_{L^2(\Omega)} \leq \eta, \|\psi_1 - \psi_2\|_{L^2(\Omega)} \leq \eta$

$$\|f_1 - f_2\|_{L^2(0, T, \Omega)} \leq \eta$$

则以 φ_1, ψ_1 为初值, f_1 为右端项的解 u_1 ,

与以 φ_2, ψ_2 为初值, f_2 为右端项的解 u_2 .

其差在 $0 \leq t \leq T$ 上满足 $\|u_1 - u_2\|_{L^2(\Omega)} + \|\nabla u_1 - \nabla u_2\|_{L^2(\Omega)} \leq \varepsilon$

$$\|\partial_t u_1 - \partial_t u_2\|_{L^2(\Omega)} \leq \varepsilon$$

Rmk. $\|f\|_{L^2(\Omega)} = \left(\int_{\Omega} |f(x)|^2 dx \right)^{\frac{1}{2}}$

$$\|f\|_{L^2(0, T, \Omega)} = \left(\int_0^T \int_{\Omega} |f(x, t)|^2 dx dt \right)^{\frac{1}{2}}$$

pr: $\hat{u}^k u(x, t) = u_1(x, t) - u_2(x, t)$

$$f = f_1 - f_2, \quad \varphi = \varphi_1 - \varphi_2, \quad \psi = \psi_1 - \psi_2.$$

则 $\begin{cases} \partial_t^2 u - \Delta u = f_1 - f_2 = f \\ u(x, 0) = \varphi_1 - \varphi_2 = \varphi, \quad u_t(x, 0) = \psi_1 - \psi_2 = \psi \\ u|_{\partial\Omega} = 0 \end{cases}$

$$\begin{aligned} u_t (\partial_t^2 u - \Delta u) &= \partial_t \left[\frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 \right] - \operatorname{div}(u_t \nabla u) = u_t \cdot f \\ \text{在 } \Omega \text{ 上取分部积分, } \partial_t \int_{\Omega} \frac{1}{2} (u_t)^2 + \frac{1}{2} |\nabla u|^2 dx &= \int_{\Omega} u_t f dx \leq \int_{\Omega} \frac{1}{2} f^2 + \frac{1}{2} (u_t)^2 dx \end{aligned}$$

$$\frac{d}{dt} E(u) \leq \frac{1}{2} \int_{\Omega} f^2 dx + \frac{1}{2} \int_{\Omega} (u_t)^2 dx \leq \int_{\Omega} \frac{1}{2} f^2 dx + E(t)$$

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$$\frac{d}{dt} (e^{-t} E(t)) \leq \frac{1}{2} e^{-t} \int_{\Omega} f^2 dx$$

由 Gronwall, $e^{-t} E(t) - E(0) \leq \frac{1}{2} \int_0^t e^{-s} \int_{\Omega} f^2(x,s) dx ds$

$$\Rightarrow E(t) \leq e^t (E(0) + \frac{1}{2} \int_0^t e^{-s} \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq e^t (E(0) + \frac{1}{2} \int_0^t \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq e^T (E(0) + \frac{1}{2} \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

$$\leq C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds) \quad \forall 0 \leq t \leq T \quad C_T = \text{const. 与 } T \text{ 有关}$$

$E(0)$ 表示 $\int_{\Omega} \frac{1}{2} (u_0)^2 + \frac{1}{2} |\nabla u|^2 dx$ 的值

$$\frac{1}{2} y(t) = \int_{\Omega} |u|^2 dx$$

$$y'(t) = 2 \int_{\Omega} u u_t dx \leq \int_{\Omega} u^2 + u_t^2 dx \leq y(t) + 2 E(t)$$

$$\leq y(t) + 2 C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

与 T 有关常数
↓

$$\frac{d}{dt} (e^{-t} y(t)) \leq 2 C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

由 Gronwall, $e^{-t} y(t) - y(0) \leq t \cdot 2 C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$

$$\Rightarrow y(t) \leq e^t [y(0) + t \cdot 2 C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)]$$

$$\leq e^t [y(0) + T \cdot 2 C_T (E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)]$$

$$\leq C_T (y(0) + E(0) + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

$$\text{且 } \|u(t)\|_{L^2(\Omega)}^2 + \|u_t\|_{L^2(\Omega)}^2 + \|\nabla u\|_{L^2(\Omega)}^2$$

$$\leq C_T (\|\psi\|_{L^2(\Omega)}^2 + \|\varphi\|_{L^2(\Omega)}^2 + \|\nabla \varphi\|_{L^2(\Omega)}^2 + \int_0^T \int_{\Omega} f^2(x,s) dx ds)$$

与 T 有关的常数

$$\leq 4 \eta^2 C_T = \frac{\varepsilon}{2} < \varepsilon$$

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$$\begin{cases} \partial_t^2 u - \Delta u = 0 \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \end{cases} \quad x \in \mathbb{R}^3$$

两边同乘 u_t , 有 $\partial_t e(u) - \operatorname{div}(u_t \nabla u) = 0$

在矩形 B $|x-x_0| \leq R-t$ 上积分

$$\iint_{\Delta} \partial_t e(u) - \operatorname{div}(u_t \nabla u) dx dt = 0$$

$$\Rightarrow \iint_{\Delta} (\partial_t e(u)) \cdot (e(u), -u_t \nabla u) dx dt$$

$$= \int_{\partial D} (e(u), -u_t \nabla u) \cdot \bar{n} ds$$

$$= - \int_B e(u)(0) dx + \int_T e(u)(t_0) dx$$

\uparrow 表示时间取值

$$+ \int_T (e(u), -u_t \nabla u) \cdot \frac{1}{\sqrt{2}} \left(\frac{R-t}{|x-x_0|}, \frac{x-x_0}{|x-x_0|} \right)$$

$$\Rightarrow \int_B e(u)(0) dx = \int_T e(u)(t_0) dx + \frac{1}{\sqrt{2}} \int_K \left(\frac{1}{2}(u_0)^2 + \frac{1}{2}|\nabla u|^2 \right) \frac{R-t}{|x-x_0|} - u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} ds$$

$$= \int_T e(u)(t_0) dx + \frac{1}{2\sqrt{2}} \int_K (u_t)^2 + |\nabla u|^2 - 2u_t \nabla u \cdot \frac{x-x_0}{|x-x_0|} ds$$

$$= \int_T e(u)(t_0) dx + \frac{1}{2\sqrt{2}} \int_K \underbrace{|u_t - \frac{x-x_0}{|x-x_0|} \cdot \nabla u|^2 + |\nabla u|^2 - \left(\frac{x-x_0}{|x-x_0|} \cdot \nabla u \right)^2}_{\text{Flux [0, t]}} ds$$

$$\text{Flux [0, t]} \geq 0$$

$$\mathbb{B}_p \int_B e(u)(0) dx = \int_T e(u)(t_0) dx + \text{Flux [0, t]}$$

($t=0$ 处能量)

($t=t_0$ 处能量)

(能量溢出)

若 $(u, u_t) \Big|_{t=0} = 0$, 在 B 上能量为 0, 则在 (u, u_t) 在 T 上恒为 0

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§4.2 混合问题

混合问题是即初边值问题

$$\begin{cases} \partial_t^2 u - \alpha u = f(x, t) \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \\ u|_{\partial\Omega} = g(x, t) / \frac{\partial u}{\partial n}|_{\partial\Omega} = g(x, t) / \frac{\partial u}{\partial n} + \alpha u|_{\partial\Omega} = g(x, t) \end{cases} \quad x \in \Omega, t > 0$$

4.2.1 简单分离变量又边值问题

$$\begin{cases} \frac{\partial^2 X}{\partial x^2} + \lambda X(x) = 0, \quad x \in (0, l) \\ -\alpha_1 X'(0) + \beta_1 X(0) = 0 \\ \alpha_2 X'(l) + \beta_2 X(l) = 0 \end{cases} \quad (3.15)$$

$$\alpha_1 > 0, \quad \beta_1 > 0, \quad \alpha_i + \beta_i > 0, \quad i = 1, 2$$

称为 Sturm-Liouville 特征值问题，入称为特征值

入 $\in \mathbb{R}$ 称为特征值，相应于入的非零解 $X(x)$ 称为对应于这个特征值的特征函数

thm 1) 所有特征值为非负实数

$\beta_1 + \beta_2 > 0$ 时，所有特征值为正数

(2) 不同特征值对应特征函数正交。

$$\text{B.P. } \int_0^l X_\lambda(x) X_\mu(x) dx = 0$$

(3) $\lambda_1, \dots, \lambda_n, \dots$ 为特征值

$$0 \leq \lambda_1 < \lambda_2 < \dots < \lambda_n < \dots \quad \lim_{n \rightarrow \infty} \lambda_n = +\infty$$

(4) $f(x) \in L^2(0, l)$ 可按特征函数系展开为

$$f(x) = \sum_{n=1}^{\infty} C_n X_n(x)$$

$$C_n = \frac{\int_0^l f(x) X_n(x) dx}{\int_0^l X_n^2(x) dx}$$

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$$pr=111 \quad x'' + \lambda x = 0 \Rightarrow x x'' + \lambda x^2 = 0$$

$$x x'' + \lambda x^2 = (x x')' - (x')^2 + \lambda x^2 = 0$$

$$\Rightarrow \lambda \int_0^l x^2 dx = \int_0^l (x'(x))^2 dx - \int_0^l (x(x)x'(x))' dx$$

$$= \int_0^l (x'(x))^2 dx - x(0)x'(0) \Big|_{x=0}^{x=l}$$

$$= \int_0^l (x'(x))^2 dx + x(0)x'(0) - x(l)x'(l)$$

$$-\alpha_1 x'(0) + \beta_1 x(0) = 0 \Rightarrow -\alpha_1 x'(0)^2 + \beta_1 x(0)x'(0) = 0$$

$$-\alpha_1 x'(0)x(0) + \beta_1 x(0)^2 = 0$$

$$\Rightarrow x(0)x'(0) = \frac{\alpha_1}{\alpha_1 + \beta_1} x'(0)^2 + \frac{\beta_1}{\alpha_1 + \beta_1} x(0)^2$$

$$\text{类似地 } x(l)x'(l) = -\frac{\alpha_2 x'(l)^2 + \beta_2 x(l)^2}{\alpha_2 + \beta_2}$$

代入题设式有

$$\lambda \int_0^l x^2 dx = \int_0^l (x'(0))^2 dx + \frac{\alpha_1}{\alpha_1 + \beta_1} x'(0)^2 + \frac{\beta_1}{\alpha_1 + \beta_1} x(0)^2 + \frac{\alpha_2}{\alpha_2 + \beta_2} x'(l)^2 + \frac{\beta_2}{\alpha_2 + \beta_2} x(l)^2$$

$$\geq 0 \Rightarrow \lambda \geq 0$$

$$\lambda = 0 \Leftrightarrow x' = 0, \text{ 且 } \frac{\beta_1}{\alpha_1 + \beta_1} x(0)^2 + \frac{\beta_2}{\alpha_2 + \beta_2} x(l)^2 = 0$$

若 β_1, β_2 中存在不为 0, $x(x) = \text{const} = 0$, 0 不为特值

若 β_1, β_2 中存在不为 0, $x(x) = \text{const} = 0$, 0 不为特值

(2) 设 X_λ, X_M 为不同特征值 λ, M 的特征函数

$$\text{则 } X_\lambda'' + \lambda X_\lambda = 0$$

$$X_M'' + M X_M = 0$$

$$\lambda \int_0^l x_\lambda x_M dx = - \int_0^l x_M x_\lambda'' dx = - \int_0^l x_M d(x_\lambda') = \int_0^l x_\lambda' x_M' dx - x_M x_\lambda' \Big|_0^l$$

$$= X_M(0)x_\lambda'(0) - X_M(l)x_\lambda'(l) + \int_0^l x_\lambda' x_M' dx$$

$$\text{同理有结果, } M \int_0^l x_\lambda x_M dx = X_\lambda(0)x_M'(0) - X_M(l)x_\lambda'(l) + \int_0^l x_\lambda' x_M' dx$$

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相减可得

$$(\lambda - M) \int_0^l X_\lambda X_M dx = (\lambda \chi'_\lambda(0) \chi_M(0) - \chi_\lambda(0) \chi'_M(0)) - (\chi'_M(l) \chi_\lambda(l) - \chi_M(l) \chi'_\lambda(l))$$

$$\text{即边界条件 } \begin{cases} -\alpha_1 \chi'_\lambda(0) + \beta_1 \chi_\lambda(0) = 0 & (1) \\ \alpha_2 \chi'_\lambda(l) + \beta_2 \chi_\lambda(l) = 0 & (2) \end{cases}$$

$$\begin{cases} -\alpha_1 \chi'_M(0) + \beta_1 \chi_M(0) = 0 & (3) \\ \alpha_2 \chi'_M(l) + \beta_2 \chi_M(l) = 0 & (4) \end{cases}$$

(1)(2) 构成关于 α_1, β_1 的线性方程, 有非零解, 则

$$\begin{vmatrix} \chi'_\lambda(0) & \chi_\lambda(0) \\ \chi'_M(0) & \chi_M(0) \end{vmatrix} = 0 \Rightarrow \chi'_\lambda(0) \chi_M(0) - \chi_\lambda(0) \chi'_M(0) = 0$$

同理 $\chi'_M(l) \chi_\lambda(l) - \chi_M(l) \chi'_\lambda(l) = 0$

$$\lambda \neq M \Rightarrow \int_0^l X_\lambda X_M dx = 0$$

Rmk. (3)(4) 的证明在泛函分析中得到

相成 L^2 -基是由于算子 $\frac{d^2}{dx^2}$ 为对称算子

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§ 4.2.2 分离变量法

解得 $\begin{cases} \partial_t^2 u - \partial_x^2 u = f(x, t) & 0 < x < l, t > 0 \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) & 0 \leq x \leq l \\ u(0, t) = g_1(t), \quad u(l, t) = g_2(t) & t > 0 \end{cases}$

(一维定长弦的振动)

1. $f \equiv 0, g_1(t), g_2(t) \equiv 0$

则 $\begin{cases} \partial_t^2 u - \partial_x^2 u = 0 & 0 < x < l, t > 0 \\ u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) & 0 \leq x \leq l \\ u(0, t) = 0, \quad u(l, t) = 0 & t > 0 \end{cases}$

① u 只与 t 有关，则 $\partial_t^2 u = 0 \Rightarrow u = C_1 t + C_2$

$u(0, t) = C_1 t + C_2$ 不满足边值

② u 只与 x 有关，则 $\partial_x^2 u = 0 \Rightarrow u = C_1 x + C_2$

$u(x, 0) = C_1 x + C_2 = \varphi(x)$ 不容易确定初值

③ 令 $u(x, t) = T(t)X(x)$

则 $T''(t)X(x) - T(t)X''(x) = 0$

$T(t) \cdot X(x) \neq 0 \Rightarrow \frac{T'(t)}{T(t)} = \frac{X''(x)}{X(x)} \triangleq -\lambda$

$\Rightarrow \begin{cases} X''(x) + \lambda X(x) = 0 \\ T''(t) + \lambda T(t) = 0 \end{cases}$

$\begin{cases} u(0, t) = 0 \\ u(l, t) = 0 \end{cases} \Rightarrow \begin{cases} T(t)X(0) = 0 \\ T(t)X(l) = 0 \end{cases} \quad \forall t \geq 0$

$\Rightarrow X(0) = X(l) = 0$

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若素对于x的 Sturm-Liouville边值问题

$$\begin{cases} X''(x) + \lambda X(x) = 0 \\ X(0) = 0 \\ X(l) = 0 \end{cases}$$

$$0 = \int_0^l X(x) (X''(x) + \lambda X(x)) dx = X(x) X'(x) \Big|_0^l - \int_0^l (X'(x))^2 dx + \lambda \int_0^l (X(x))^2 dx$$
$$\Rightarrow \lambda \int_0^l (X(x))^2 dx = \int_0^l (X'(x))^2 dx$$
$$\Rightarrow \lambda \geq 0$$

若 $\lambda = 0$, 则 $X''(x) = 0 \Rightarrow X(x) = C_1 x + C_2$

$$X(0) = C_2 = 0, X(l) = C_1 l + C_2 = 0 \Rightarrow C_1 = 0 \Rightarrow X(x) \equiv 0$$

若 $\lambda > 0$, $X''(x) + \lambda X(x) = 0$

$$\Rightarrow X(x) = C_1 \cos \sqrt{\lambda} x + C_2 \sin \sqrt{\lambda} x$$

$$X(0) = C_1 = 0, X(l) = C_2 \sin \sqrt{\lambda} l = 0 \quad \sqrt{\lambda} l = n\pi, n \in \mathbb{Z}^*$$

$$\Rightarrow \lambda_n = \left(\frac{n\pi}{l}\right)^2 \quad n=1,2,\dots$$

与之对应的特征函数 $X_n(x) = \sin\left(\frac{n\pi}{l}x\right)$ (事实上为 $C_2 \sin\left(\frac{n\pi}{l}x\right)$, 但系数可设 "Cn" "Dn" 顺次)

由于 $T_n''(t) + \lambda_n T_n(t) = 0$

$$T_n(t) = C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right)$$

$$\therefore u(x,t) = \sum_{n=1}^{\infty} [C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right)] \sin\left(\frac{n\pi}{l}x\right)$$

再利用初值条件.

$$u(x,0) = \sum_{n=1}^{\infty} C_n \sin\left(\frac{n\pi}{l}x\right) = \psi(x)$$

$$u_t(x,0) = \sum_{n=1}^{\infty} \frac{n\pi}{l} D_n \sin\left(\frac{n\pi}{l}x\right) = \psi_t(x)$$

由 Sturm-Liouville, $\left\{ \sin\left(\frac{n\pi}{l}x\right) \right\}_{n=1}^{\infty}$ 为 L^2 中一组正交基

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$$\psi(x) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{l}x\right)$$

$$\psi_n = \frac{\int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx}{\int_0^l \sin^2\left(\frac{n\pi}{l}x\right) dx} = \frac{2}{l} \int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx$$

$$\Psi(x) = \sum_{n=1}^{\infty} \Psi_n \sin\left(\frac{n\pi}{l}x\right)$$

$$\Psi_n = \frac{\int_0^l \Psi(x) \sin\left(\frac{n\pi}{l}x\right) dx}{\int_0^l \sin^2\left(\frac{n\pi}{l}x\right) dx} = \frac{2}{l} \int_0^l \Psi(x) \sin\left(\frac{n\pi}{l}x\right) dx$$

$$\Rightarrow C_n = \psi_n = \frac{2}{l} \int_0^l \psi(x) \sin\left(\frac{n\pi}{l}x\right) dx \quad \left. \begin{array}{l} \\ D_n = \frac{l}{n\pi} \Psi_n = \frac{2}{n\pi} \int_0^l \Psi(x) \sin\left(\frac{n\pi}{l}x\right) dx \end{array} \right\} (x)$$

双周期解的解

$$u(x, t) = \sum_{n=1}^{\infty} [C_n \cos\left(\frac{n\pi}{l}t\right) + D_n \sin\left(\frac{n\pi}{l}t\right)] \sin\left(\frac{n\pi}{l}x\right)$$

其中 C_n, D_n 由 (x) 给出

thm 相似性条件

若 $\psi \in C^3([0, l]), \Psi \in C^3([0, l]), \psi(x), \Psi(x) \in (0, l) \times (0, +\infty) \stackrel{d}{\neq} \emptyset$

且 $\int_0^l \Psi(x) dx > 0$ 是相似性条件 $\psi(0) = \psi(l) = \psi''(0) = \psi''(l) = \Psi(0) = \Psi(l) = 0$

则 $u(x, t) \in C^2(\bar{\Omega})$ 为古典解

Rmk. 若 $u(x, t) = \sum_{n=1}^{\infty} T_n(t) X_n(x)$

T_n, X_n 满足弱解, 使微分求导与求和可交换

$$\text{则 } dt^2 u - dx^2 u = \sum_{n=1}^{\infty} T_n''(t) X_n(x) - T_n(t) X_n''(x)$$

$$= \sum_{n=1}^{\infty} (T_n''(t) + \lambda_n T_n(t)) X_n(x) = 0$$

2. $f \neq 0, g_1(t), g_2(t) \equiv 0$

$$\Leftrightarrow f(x, t) = \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{l}x\right)$$

$$\psi(x) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{l}x\right), \Psi(x) = \sum_{n=1}^{\infty} \Psi_n \sin\left(\frac{n\pi}{l}x\right)$$

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$$\sum_{n=1}^{\infty} U_n(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi}{L}x\right)$$

$$R^2 \lambda \partial_t^2 u - \partial_x^2 u = f(x, t)$$

$$\text{有 } \sum_{n=1}^{\infty} (T_n''(t) + \lambda_n T_n(t)) \sin\left(\frac{n\pi}{L}x\right) = \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{L}x\right)$$

$$\text{即 } T_n(t) \text{ 是方程 } T_n''(t) + \lambda_n T_n(t) = f_n(t)$$

$$U(x, 0) = \sum_{n=1}^{\infty} T_n(0) \sin\left(\frac{n\pi}{L}x\right) = \sum_{n=1}^{\infty} \psi_n \sin\left(\frac{n\pi}{L}x\right) \Rightarrow T_n(0) = \psi_n$$

$$U_t(x, 0) = \sum_{n=1}^{\infty} T_n'(0) \sin\left(\frac{n\pi}{L}x\right) = \sum_{n=1}^{\infty} \psi'_n \sin\left(\frac{n\pi}{L}x\right) \Rightarrow T_n'(0) = \psi'_n$$

$$\Rightarrow T_n(t) = \psi_n \cos\left(\frac{n\pi}{L}t\right) + \frac{1}{n\pi} \psi'_n \sin\left(\frac{n\pi}{L}t\right) + \frac{1}{n\pi} \int_0^t f_n(\tau) \sin\left(\frac{n\pi}{L}(t-\tau)\right) d\tau \quad (4)$$

故得解为

$$U(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin\left(\frac{n\pi}{L}x\right) \quad T_n \text{ 由 (4) 得出}$$

3. $f \neq 0, g_1, g_2 \neq 0$

$$\sum_{n=1}^{\infty} V_n(x, t) = U(x, t) - \frac{((1-x)g_1(t) + xg_2(t))}{l}$$

$$\left. \begin{array}{l} V(0, t) = U(0, t) - g_1(t) = 0 \\ V(l, t) = U(l, t) - g_2(t) = 0 \end{array} \right\} \text{边值为 0}$$

$$V(l, t) = U(l, t) - g_2(t) = 0$$

$$\left. \begin{array}{l} \partial_t^2 v - \partial_x^2 v = f(x, t) - \frac{((1-x)g_1''(t) + xg_2''(t))}{l} \\ V(x, 0) = \psi(x) - \frac{((1-x)g_1(0) + xg_2(0))}{l} \\ V_l(x, 0) = \psi_l(x) - \frac{((1-x)g_1'(0) + xg_2'(0))}{l} \end{array} \right.$$

进而转化为零边值问题

结论：本质为 S-L 边值问题的特征系展开，与方程类型无关。

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ex. (热传导方程)

$$\begin{cases} U_t = U_{xx}, \quad 0 < x < l \\ U(x, 0) = \varphi(x) \\ U(0, t) = 0, \quad U_x(l, t) + hU(l, t) = 0 \quad h > 0 \end{cases}$$

$$\Rightarrow U(x, t) = T(t)x(X(x))$$

$$\text{则 } T'(t)x(X(x)) = T(t)x''(x)$$

$$\Rightarrow \frac{T'(t)}{T(t)} = \frac{x''(x)}{x(x)} \stackrel{!}{=} -\lambda$$

$$U(0, t) = 0 \Rightarrow T(t)x(0) = 0$$

$$U_x(l, t) + hU(l, t) = 0 \Rightarrow T(t)x'(l) + hT(t)x(l) = 0$$

$$\text{对 } \forall t \in \mathbb{R}, \text{ 只有 } x'(l) + hx(l) = 0$$

故 $x(x)$ 为边值问题

$$\begin{cases} x''(x) + \lambda x(x) = 0 \\ x(0) = 0 \\ x'(l) + hx(l) = 0 \end{cases}$$

$$\textcircled{1} \quad \lambda < 0 \text{ 时, } x(x) = C_1 e^{\sqrt{-\lambda}x} + C_2 e^{-\sqrt{-\lambda}x}$$

$$x(0) = 0 \Rightarrow C_1 + C_2 = 0$$

$$C_1 \sqrt{-\lambda} e^{\sqrt{-\lambda}l} - C_2 \sqrt{-\lambda} e^{-\sqrt{-\lambda}l} + h(C_1 e^{\sqrt{-\lambda}l} + C_2 e^{-\sqrt{-\lambda}l}) = 0$$

$$C_1 [\sqrt{-\lambda} e^{\sqrt{-\lambda}l} + \sqrt{-\lambda} e^{-\sqrt{-\lambda}l}] + h(e^{\sqrt{-\lambda}l} - e^{-\sqrt{-\lambda}l}) = 0$$

$$\Leftrightarrow C_1 = 0 \quad \begin{cases} \sqrt{-\lambda} + h = 0 \\ \sqrt{-\lambda} - h = 0 \end{cases} \Rightarrow h = 0$$

$$\text{故 } C_1 = 0, C_2 = 0$$

Rmk. 利用本方法同样可证明 $\lambda \geq 0$, 同乘 x 为 S-L 问题的手段

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② $\lambda = 0$ 时, $X(x) = C_1 x + C_2$

$$X(0) = C_2 = 0$$

$$X'(0) + hX(0) = C_1 + hC_1 \cdot 0 = 0 \Rightarrow C_1 = 0 \Rightarrow X(x) \equiv 0$$

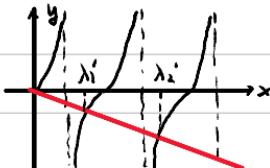
由 $\lambda > 0$, 则 $X(x) = C_1 \cos(\sqrt{\lambda}x) + C_2 \sin(\sqrt{\lambda}x)$

$$X(0) = C_1 = 0$$

$$X'(0) + hX(0) = C_2 \sqrt{\lambda} \cos(\sqrt{\lambda} \cdot 0) + hC_2 \sin(\sqrt{\lambda} \cdot 0) = 0$$

$$C_2 \neq 0 \Rightarrow \tan(\sqrt{\lambda} \cdot 0) = -\frac{C_2}{h}$$

考虑方程 $\tan x = -\frac{x}{h}$ 的解



$$\exists 0 < \lambda_1 < \dots < \lambda_n < \dots, \text{ 使 } \tan(\sqrt{\lambda} \cdot 0) = -\frac{C_2}{h}$$

令 $X_n(x) = \sin(\sqrt{\lambda_n}x)$ 为 λ_n 对应的特征函数

$$T_n(t) \text{ 为方程 } T_n' + \lambda_n T_n = 0 \Rightarrow T_n(t) = A_n e^{-\lambda_n t}$$

$$\text{则 } u(x, t) = \sum_{n=1}^{\infty} A_n e^{-\lambda_n t} \sin(\sqrt{\lambda_n} x)$$

$$\text{而 } u(x, 0) = \sum_{n=1}^{\infty} A_n \sin(\sqrt{\lambda_n} x) = \varphi(x) = \sum_{n=1}^{\infty} \varphi_n \sin(\sqrt{\lambda_n} x)$$

$$\Rightarrow A_n = \varphi_n = \frac{\int_0^l \varphi(x) \sin(\sqrt{\lambda_n} x) dx}{\int_0^l \sin^2(\sqrt{\lambda_n} x) dx}$$

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Ex. 1) 例題方程

$$\text{全 } \Omega = \{(x,y) \mid x^2 + y^2 < 1\}$$

考慮且上位勢方程：

$$\begin{cases} \Delta u = 0 & \text{in } \Omega \\ u = \varphi & \text{in } \partial\Omega \end{cases}$$

$$\text{全 } \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$\Rightarrow \begin{cases} \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = 0 & \text{in } \Omega \\ u|_{r=1} = \varphi(\cos \theta, \sin \theta) \cong \widetilde{\varphi}(\theta) \end{cases}$$

$$\text{全 } u(r, \theta) = R(r)\Theta(\theta)$$

$$\text{則 } R''(r)\Theta(\theta) + \frac{1}{r} R'(r)\Theta(\theta) + \frac{1}{r^2} R(r)\Theta''(\theta) = 0$$

$$\Rightarrow -r^2 \frac{R''(r) + \frac{1}{r} R'(r)}{R(r)} = \frac{\Theta''(\theta)}{\Theta(\theta)} \cong -\lambda$$

若素 $\Theta(\theta)$ 週期為 2π

$$\begin{cases} \Theta''(\theta) + \lambda \Theta(\theta) = 0 \\ \Theta(\theta) = \Theta(\theta + 2\pi) \end{cases}$$

$$\text{若 } \lambda < 0, \Theta(\theta) = C_1 e^{-\sqrt{-\lambda}\theta} + C_2 e^{\sqrt{-\lambda}\theta}, \text{ 不以 } 2\pi \text{ 为周期}$$

$$\text{若 } \lambda = 0, \Theta(\theta) = C_1 \theta + C_2, \text{ 不以 } 2\pi \text{ 为周期, 除非 } C_1 = 0, \text{ 即 } \Theta(\theta) \text{ 为常数}$$

$$\text{若 } \lambda > 0, \Theta(\theta) = C_1 \cos(\sqrt{\lambda}\theta) + C_2 \sin(\sqrt{\lambda}\theta)$$

$$\text{若 } \lambda > 0 \text{ 为周期} \Leftrightarrow \sqrt{\lambda} \in \mathbb{Z}^*$$

$$\text{则 } \Theta_n(\theta) = C_n \cos(n\theta) + D_n \sin(n\theta) \text{ 为 } \lambda = n^2 \text{ 对应特征函数, } n = 1, 2, \dots$$

可构成一个圆-直基由于 $\frac{d^2}{dr^2}$ 为对称算子

$$(\text{补充 } \Theta_0(\theta) = C_0)$$

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考虑 $R(r)$ 满足的方程

$$r^2 R_n''(r) + r R_n'(r) - n^2 R_n = 0$$

为 Euler 方程。

$$\text{令 } r = e^t, \frac{dR_n}{dt} = R_n'(r)r, \frac{d^2R_n}{dt^2} = R_n''(r)r^2 + R_n'(r)r = R_n''(r)r^2 + \frac{dR_n}{dt}$$

$$\Rightarrow \frac{d^2R_n}{dt^2} - n^2 R_n = 0$$

$$\Rightarrow R_n(t) = \begin{cases} C_1 e^{nt} + C_2 e^{-nt} = C_1 r^n + C_2 r^{-n} & n \neq 0 \\ C_1 t + C_2 = C_1 \ln r + C_2 & n = 0 \end{cases}$$

为使 $r=0$ 处连续可微，应满足 $R_n(r) = \begin{cases} C_1 r^n & n \neq 0 \\ C_2 & n = 0 \end{cases}$

设 $u(r, \theta) = C_0 + \sum_{n=1}^{\infty} r^n (C_n \cos(n\theta) + D_n \sin(n\theta))$

$$u|_{r=1} = C_0 + \sum_{n=1}^{\infty} C_n \cos(n\theta) + D_n \sin(n\theta) = \hat{\varphi}(\theta)$$

$$C_n \int_0^{2\pi} \cos^2(n\theta) d\theta = \int_0^{2\pi} \hat{\varphi}(\theta) \cos(n\theta) d\theta \Rightarrow C_n = \frac{1}{2} \int_0^{2\pi} \hat{\varphi}(\theta) \cos(n\theta) d\theta$$

$$D_n \int_0^{2\pi} \sin^2(n\theta) d\theta = \int_0^{2\pi} \hat{\varphi}(\theta) \sin(n\theta) d\theta \Rightarrow D_n = \frac{1}{2} \int_0^{2\pi} \hat{\varphi}(\theta) \sin(n\theta) d\theta$$

$$C_0 \int_0^{2\pi} d\theta = \int_0^{2\pi} \hat{\varphi}(\theta) d\theta \Rightarrow C_0 = \frac{1}{2\pi} \int_0^{2\pi} \hat{\varphi}(\theta) d\theta$$

从高到低对区域、算子较为敏感