

# The Kinetic Stress Index (KSI): A Mathematical Explanation and Justification

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Version: 8.0 (Generalized Framework)

## I. Introduction: A Dynamic Approach to Systemic Risk

This document presents the mathematical framework for the **Kinetic Stress Index (KSI)**, a quantitative measure of systemic risk. The KSI models the market's correlation structure as a single, high-dimensional object whose motion reveals underlying stress. We analyze the six distinct correlations between key global assets—**Stocks (SPY)**, **Bonds (TLT)**, **Gold (GLD)**, and a **Currency Risk proxy (AUDJPY)**—which define a point in an abstract "correlation space."

The KSI's primary function is to analyze the dynamics of this point by approximating its derivatives up to the sixth order: Velocity, Acceleration, Jerk, and the higher-order Snap, Crackle, and Pop. These higher-order components are crucial for detecting progressively more violent, high-frequency shocks and discontinuous breaks in the market's correlation structure. This allows us to observe the degree to which a shock cascades during each KSI spike.

While stable regimes feature slow, predictable drifts in correlation, a crisis often manifests as a violent, systemic *snap*. The KSI is engineered to detect these moments by measuring how anomalously the system's state is evolving compared to its own recent history. By capturing this full dynamic spectrum, from slow structural drifts to ultra-fast shocks, the framework aims to provide deeper and earlier insight into systemic risk.

## II. The Building Blocks: System Variables and Parameters

Before delving into the mathematics, it is prudent to define the key symbols and parameters used to construct the model, which correspond directly to the v8.0 implementation.

Symbol	Definition	Value in Code	Purpose in the Model
$n$	Number of assets	4 (SPY, TLT, etc.)	The set of assets whose systemic inter-relationships are being analysed.
$w$	Correlation window	60 days	The lookback period for measuring the current correlation structure.
$l$	Mahalanobis lookback	252 days	The historical window used to establish the baseline of "normal" system behaviour.
$\rho_{ij,t}$	Spearman correlation	$[-1, 1]$	A robust measure of the non-linear co-movement between two assets.
$\theta_t$	<b>Position Vector</b>	$\mathbb{R}^6$	A vector representing the complete correlation structure at a single point in time.
$\Delta^n \theta_t$	$n$ -th order derivative	(Kinetic Components)	Metrics describing the rate of change of the correlation structure at multiple time scales.
$d$	State vector dimension	$6 \times 7 = 42$	The total number of variables defining the system's complete dynamic state.
$\mathbf{s}_t$	<b>State Vector</b>	$\mathbb{R}^{42}$	The comprehensive vector containing the system's position and full dynamic state.
$\mu_{t-1}$	Historical mean vector	$\mathbb{R}^{42}$	The historically normal state of the system, learned from the lookback period.
$\Sigma_{t-1}$	Covariance matrix	$\mathbb{R}^{42 \times 42}$	A map of the system's normal modes of variation and their interdependencies.

### III. Constructing the State Vector: From Prices to a Dynamic Representation

To analyze the market's correlation structure, we first construct its state vector. This begins by defining the system's "position" through three robust statistical transformations of asset prices.

#### 1. Logarithmic Returns

Non-stationary daily closing prices ( $P_{i,t}$ ) are converted into stationary logarithmic returns. This standard transformation is chosen for its **time-additivity** and for producing more stable sta-

tistical properties.

$$r_{i,t} = \ln \left( \frac{P_{i,t}}{P_{i,t-1}} \right)$$

## 2. Spearman's Rank Correlation

To create a measure robust against extreme outliers (fat tails), we use **Spearman's rank correlation** ( $\rho_{ij,t}$ ). This is calculated on asset ranks within a 60-day rolling window, not the raw returns.

$$\rho_{ij,t} = \frac{\text{cov}(R_i, R_j)}{\sigma_{R_i} \sigma_{R_j}}$$

By ranking returns on a bounded integer scale, the influence of any single extreme event is mathematically capped, yielding a more stable picture of the underlying asset relationships.

## 3. Fisher Z-Transform

The correlation coefficient  $\rho$  is bounded by  $[-1, +1]$ , which creates statistical distortion. The **Fisher z-transform** corrects this by mapping  $\rho$  to an unbounded scale, ensuring that changes near the boundaries are given appropriately greater weight.

$$\theta_{ij,t} = \tanh^{-1}(\rho_{ij,t}) = \frac{1}{2} \ln \left( \frac{1 + \rho_{ij,t}}{1 - \rho_{ij,t}} \right)$$

The transform's derivative,  $\frac{d\theta}{d\rho} = \frac{1}{1-\rho^2}$ , amplifies the significance of shifts in highly correlated or decorrelated regimes.

The six resulting values from this process form the system's **Position Vector**,  $\boldsymbol{\theta}_t \in \mathbb{R}^6$ . This vector is a statistically robust representation of the market's complete correlation structure, ready for dynamic analysis.

## Step 2: Analysing the System's Dynamics

To capture the system's **\*\*dynamics\*\***, we approximate its motion using a spectrum of **\*\*finite differences\*\***. The  $n$ -th order difference is a vector sum calculated with the causal, backward-looking formula:

$$\Delta^n \boldsymbol{\theta}_t = \sum_{k=0}^n (-1)^k \binom{n}{k} \boldsymbol{\theta}_{t-k}$$

For lower orders, these vectors are analogues for **\*\*velocity\*\*** ( $n = 1$ ) and **\*\*acceleration\*\*** ( $n = 2$ ), while higher orders highlight more abrupt shifts. This process, however, **\*\*amplifies noise\*\***, with variance growing by a factor of  $\binom{2n}{n}$ . To solve this, we apply a regularizing weight,  $w_n = \alpha^n / \sqrt{\binom{2n}{n}}$ , which combines two parts:

1. A **statistical normalizer** ( $1/\sqrt{\binom{2n}{n}}$ ) that directly counters variance growth.
2. A tunable **exponential decay** ( $\alpha^n$ , for  $\alpha < 1$ ) that reduces emphasis on noisier, higher orders.

This weighting scheme controls for noise while retaining a multi-scale view of market dynamics.

### Step 3: Assembling the Full State Vector

The final step is to integrate the system's static position ( $\theta_t$ ) and its weighted dynamic components ( $\Delta^n \theta_t$ ) into a single, comprehensive state vector,  $\mathbf{s}_t$ . This is done by vertically concatenating the components:

$$\mathbf{s}_t = \begin{bmatrix} w_0 \Delta^0 \theta_t \\ w_1 \Delta^1 \theta_t \\ \vdots \\ w_6 \Delta^6 \theta_t \end{bmatrix} \in \mathbb{R}^{42}$$

The dimension arises from 7 dynamic orders (position at  $n = 0$  through the 6th difference) for each of the 6 correlation pairs. This unified vector is crucial because it allows subsequent analysis to capture not just variance *within* each dynamic order, but also the **correlations between them** (e.g., the typical relationship between a correlation's velocity and its position). This final vector,  $\mathbf{s}_t$ , provides a complete description of correlation dynamics and is the mathematical object used to quantify market stress as a geometric distance.

## IV. The KSI Calculation: Quantifying Anomalous Dynamics

The Kinetic Stress Index (KSI) quantifies stress by measuring how improbably the market's correlation structure is evolving relative to its own recent history. It achieves this using the **Mahalanobis distance**—a multivariate z-score that accounts for the scales and interdependencies among all 42 components of the state vector. The KSI is the square root of this value, yielding an intuitive "distance" in statistical standard deviations:

$$\text{KSI}_t = \sqrt{(\mathbf{s}_t - \boldsymbol{\mu}_{t-1})^\top \boldsymbol{\Sigma}_{t-1}^{-1} (\mathbf{s}_t - \boldsymbol{\mu}_{t-1})}$$

In this formula,  $\mathbf{s}_t$  is the complete 42-dimensional state vector, while  $\boldsymbol{\mu}_{t-1}$  and  $\boldsymbol{\Sigma}_{t-1}$  are its historical mean and regularized covariance matrix, respectively, estimated from a preceding lookback period.

### Derivation and Superiority

The Mahalanobis distance measures a point's distance from a distribution's center, but unlike Euclidean distance, it is invariant to scale and rotation. It is derived by "whitening" the data—transforming it via  $\mathbf{y} = \boldsymbol{\Sigma}^{-1/2}(\mathbf{s}_t - \boldsymbol{\mu})$  so its covariance becomes the identity matrix—and then calculating the standard Euclidean distance in this new, decorrelated space.

This approach is superior because it correctly handles that the state vector's components are correlated and have unequal variances. By using the inverse covariance matrix ( $\boldsymbol{\Sigma}^{-1}$ ), the KSI penalizes deviations based on their historical improbability, not their raw magnitude.

### Adaptive Historical Baseline

The model's baseline for "normal" dynamics, captured by  $\boldsymbol{\mu}_{t-1}$  and  $\boldsymbol{\Sigma}_{t-1}$ , is adaptive. It's estimated over a rolling window of the past  $l = 252$  trading days, ensuring the model evolves with market regimes. The historical mean is the simple sample average of the state vector:

$$\boldsymbol{\mu}_{t-1} = \frac{1}{l} \sum_{k=1}^l \mathbf{s}_{t-k}.$$

While the mean is straightforward, the sample covariance matrix,  $\mathbf{S}_{t-1}$ , is often noisy and ill-conditioned in high dimensions ( $p = 42$ ), making its inverse unstable.

## Regularization via Ledoit-Wolf Shrinkage

To create a robust and invertible covariance matrix, we apply **Ledoit-Wolf shrinkage**. This method optimally combines the noisy sample covariance  $\mathbf{S}$  with a stable, structured target matrix  $\mathbf{T}$ . The resulting regularized covariance is a weighted average:

$$\mathbf{\Sigma}_{t-1} = (1 - \phi^*)\mathbf{S}_{t-1} + \phi^*\mathbf{T},$$

where the optimal shrinkage intensity,  $\phi^* \in [0, 1]$ , is analytically derived to minimize estimation error. This process systematically reduces noise, yielding a more stable and reliable KSI value.

A high KSI value emerges when the system's state vector  $\mathbf{s}_t$  occupies a low-probability region under its own recent history, signaling that the market's correlation structure is evolving in a truly anomalous way.

## V. Interpreting Stress Peaks: Decomposing the Anomaly

When the KSI value spikes, we can decompose the event to understand *why* the market is under stress. The method is **Principal Component Analysis (PCA)** on the historical covariance matrix,  $\mathbf{\Sigma}_{t-1}$ , via its eigendecomposition:

$$\mathbf{\Sigma}_{t-1} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^\top$$

Here, the columns of  $\mathbf{V}$  are the 42-dimensional **eigenvectors** ( $\mathbf{v}_j$ ), representing the system's fundamental modes of co-movement. The corresponding **eigenvalues** ( $\lambda_j$ ) on the diagonal of  $\mathbf{\Lambda}$  quantify the historical variance, or "energy," of each mode.

The squared KSI (the Mahalanobis distance) decomposes perfectly along these modes. If we define the current deviation as  $\mathbf{d}_t = \mathbf{s}_t - \boldsymbol{\mu}_{t-1}$ , the contribution of each mode to the total stress is:

$$\text{KSI}_t^2 = \sum_{j=1}^{42} \frac{(\mathbf{v}_j^\top \mathbf{d}_t)^2}{\lambda_j}$$

This decomposition shows that stress arises from **surprising** deviations. A large contribution to the KSI occurs when the system deviates along a historically stable mode—one with a **small eigenvalue**  $\lambda_j$ —because the small denominator amplifies the statistical surprise.

To diagnose a peak, we can inspect the eigenvectors of the top contributing modes. Each eigenvector consists of 42 "loadings," and by identifying the largest loadings, we can determine which specific dynamics (e.g., the velocity of the stock-bond correlation) were the primary drivers of the stress, providing a rich, diagnostic view.

## VI. Conclusion and Future Directions

The Kinetic Stress Index (KSI) framework offers a nuanced measure of systemic risk by modeling the market's correlation structure as a high-dimensional dynamical system and analyzing its full spectrum of motion. It aims to provide an intuitive early warning system for financial crises and is presented here for testing and critique.

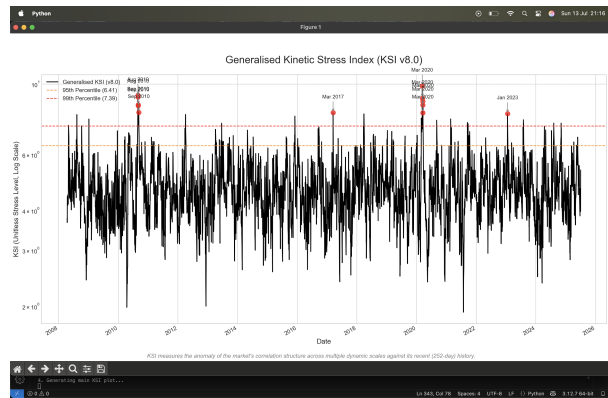


Figure 1: Enter Caption

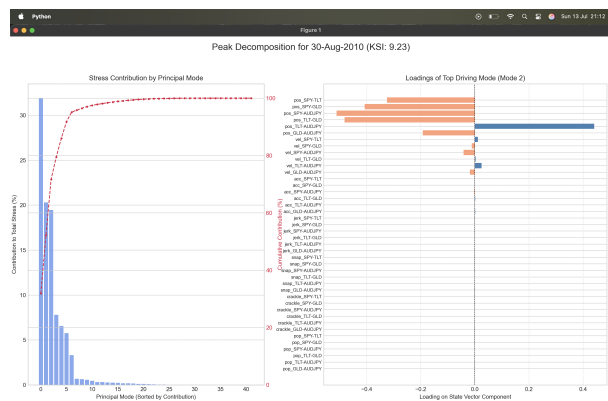


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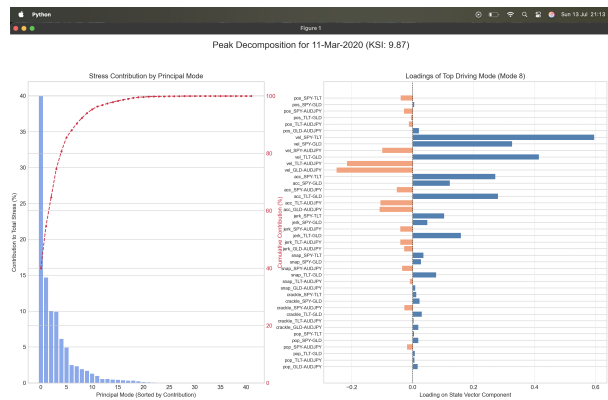


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