

Final Contest

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A. ACTG Matrix

Find substrings of given strings s and t with the largest *similarity*.

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The answer is $\max_{i,j} dp_{i,j}$. Complexity is $O(|s| \cdot |t|)$.

B. Boundary String

Given is a description of a proper rectilinear polygon boundary, as a sequence of left and right turns. Find the smallest bounding box area.

It is guaranteed the intersection of any vertical line with the polygon interior is a segment (or empty).

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- The total widths of both boundary halves are equal.
- At any x -coordinate the upper half is strictly higher than the lower half.
- For any pair of consecutive horizontal sides in a boundary half, one should be strictly higher/lower than the other depending on the turn directions at those sides.

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Since DP is $O(n^2)$, and $H = O(n)$, this is an $O(n^3)$ solution.

C. Convex Shell

For a convex polyhedron P , find the volume of the set P_d of points at distance at most d from the polyhedron.

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Each edge contributes $l \cdot d^2 \cdot (\pi - \alpha)$, where l is the edge length, α is the *dihedral angle* between faces adjacent to the edge.
- q is a polygon vertex.
For each vertex, the region is a ball wedge. These wedges can be combined to form a single ball of radius d , thus the total volume is $\frac{4}{3}\pi d^3$.

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D. Determine The Lap Length

ByteDance



There is a lap of unknown integer length $L \leq 10^9$. We can make queries: run k more meters around the lap, get the total number of completed laps so far. Find L in at most 100 queries.

D. Determine The Lap Length

For an arbitrary x , how can we check if $L \leq x$? Let D be the total distance we ran so far, and $kx > D$ be the closest multiple of x . Query $kx - D$, and check that the number of laps is $\geq k$.

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Now, binary search, keeping track of the total travelled distance. $\log_2 10^9 \sim 30$ queries.

E. Empires

There is a graph, with vertices divided between three empires. For each empire, build the smallest number of bases in its vertices, so that for each other vertex a base is reachable when vertices of a single other empire become impassable.

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The task now becomes: choose the smallest number of vertices, such that for each $x = 1, \dots, X$ at least one vertex with $x_i = x$ is chosen (same for y_i).

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Find maximum matching with Kuhn's algorithm. Repeat for empires 2 and 3 similarly. Complexity is $O(m + n^2)$.

F. Finish Time Expectation

For a given convex polygon, find the expected Manhattan distance between uniformly chosen points inside the polygon.

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Let S be the polygon area, and $L(x)$ be the area to the left of coordinate x . The answer is then equal to

$$\int_{x_{min}}^{x_{max}} \frac{2L(x)(S - L(x))}{S^2} dx.$$

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Big decimals are highly recommended.

G. Generate Optimal Tree

Given are n bit strings of equal length. Build a decision tree of minimum height that can distinguish the given strings by single character lookups.

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Complexity $O(2^n n |s|)$, or $O(2^n |s|)$ with bitsets.

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H. Heavy Rain

 ByteDance

There are n cacti in a row, i -th having height h_i . Process queries: if rain falls on a segment $[L, R]$, how much water will be collected?

H. Heavy Rain

For a query $[L, R]$, water will be kept at height h_i to the left/right of cactus i if the rightmost/leftmost closest cactus j higher or equal than h_i is outside of the segment.

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The water profile is *bitonic*: left part of it is non-decreasing, and right part is non-increasing. For each query, let's find both parts independently.

H. Heavy Rain

To find the left non-decreasing part, use *monotonic stack*.
 Consider cacti $n, \dots, 1$, and for the current position L maintain a stack $n = j_1 > \dots > j_k = L$ of indices of cacti that are higher than any cactus to their left we've seen so far. To introduce cactus $L - 1$, pop several elements from the stack while $h_{j_k} \leq h_{L-1}$, and push $L - 1$.

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Now, for any query $[L, R]$, cacti in the left part of the profile are a suffix of the monotonic stack. Process queries offline by decreasing of L , and use binary search to find the relevant suffix. If we additionally store prefix sums of $h_{j_s} \times (j_s - j_{s+1})$, we can then compute the area of the left part of the profile. Subtract the range sum of h_i to find out the amount of water.

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Repeat the algorithm in the other direction to find the right part of the profile. If there are several highest cacti between L and R , additionally add water kept between them.

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Complexity of this solution is $O(n + q \log n)$.

I. Improved Werewolf

Given an array, process queries:

- add x to elements in a range with indices in arithmetic progression spaced 2 or 3;
- find RMQ in a range $[l, r]$;
- erase i -th element;
- insert a previously erased element to its original relative position, and set it to 0.

I. Improved Werewolf

Let's split the array into 6 subarrays, based on their indices modulo 6. The add operation then affects some of the remainders modulo 6, and is a "range add" operation in each of the subarrays.

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All this can be done if each of the subarrays is stored in, say, a treap, for $\sim 6 \log n$ operations per query.

J. Juggle Sort

Process given in the statement is equivalent to the following:

Given an array, perform operations sequentially. If the leftmost element is (one of the) largest in the array, erase it. Otherwise, pay 1 coin and move it to the right end. Proceed until the array is empty.

How many coins will be paid?

J. Juggle Sort

Suppose that the array is initially empty. Consider all elements by decreasing, in groups of equal numbers. Insert numbers in each group to their relative positions, and see how the score updates. Maintain a position i of the element that will be erased last, as well as the number c of coins we pay for this element.

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If we insert a new group, its elements will be erased cyclically starting from the leftmost element to the right of i (if any). Elements to right of i infer a cost of c each, while elements to the left i infer cost $c + 1$ each. Thus, we can update the costs, as well as values of i and c .

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This is easily implemented in $O(n \log n)$ time.

K. King And Toll Roads

There is a graph with n vertices. Vertices i and $i + 1$ are adjacent for each $i = 1, \dots, n - 1$ (*trivial* edges), and m extra (*non-trivial*) edges are present.

We can make two edges have cost 1 to travel through. What is the largest sum of pairwise smallest travel costs we can achieve?

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 ByteDance

If the answer is not zero, then removing both toll edges should make the graph disconnected.

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We can check for each trivial edge $i \leftrightarrow i + 1$ if its a bridge with Tarjan's algorithm, or simply by checking that no non-trivial edge xy satisfies $x \leq i < i + 1 \leq y$.

Suppose we cut away A leftmost vertices and B rightmost vertices. The answer is then $A(n - A) + B(n - B)$.

The answer is maximized when both toll bridges are closest to the middle $n/2$.

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In this graph, each equivalence class consists of several trivial edge, and at most one non-trivial edge (when present, it connects leftmost and rightmost parts of the graph with respect to trivial edges).

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Choosing two best edges in each class reduces to finding a segment in the sequence of part sizes that is closest to $n/2$, and can be done with two pointers.

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This results in $O(n \log n)$ solution.

L. LTE Broadcasting Stations II

Basically:

There are n points in the real line. We can add directed edge from point x_i to point x_j , paying $f(|x_i - x_j|)$, where $f(D) = D \lfloor \sqrt{D} \rfloor$.

For each $h = 1, \dots, n - 1$, find the smallest cost of constructing a rooted tree with height at most h .

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Proof sketch: assuming the contrary, there are points $x_1 < x_2 < x_3$ such that x_1, x_3 are in the subtree of a point x (maybe one of x_1, x_3), but x_2 is not.

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WLOG assume $x > x_2$.

If $d(x_2) \leq d(x)$, we can improve by making x_2 an ancestor of x_1 by changing its, or one of its ancestors' parent to x .

L. LTE Broadcasting Stations II

Let $d(x_i)$ be the distance from x_i to the root in the tree.

Let $p(x_i) = x_j$ — the coordinate of the parent of the point x_i (undefined for the root).

Claim

In an optimal answer the subtree of each vertex forms a contiguous segment of points.

Proof sketch: assuming the contrary, there are points $x_1 < x_2 < x_3$ such that x_1, x_3 are in the subtree of a point x (maybe one of x_1, x_3), but x_2 is not.

WLOG assume $x > x_2$.

If $d(x_2) \leq d(x)$, we can improve by making x_2 an ancestor of x_1 by changing its, or one of its ancestors' parent to x .

If $d(x_2) > d(x)$, we can improve by making x an ancestor of x_2 .

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We can now find the answer with subsegment DP.

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- nothing, if $p = 0$;
- $l - 1$, if $p = 1$;
- $r + 1$, if $p = 2$.

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Then, say,

$$dp[l, r, h, 0] = \min_{i=l}^r dp[l, i - 1, h - 1, 2] + dp[i + 1, r, h - 1, 1],$$

and $p = 1, 2$ differ by an extra summand $f(|x_i - x_{l-1}|)$ or $f(|x_i - x_{r+1}|)$.

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The answer for height h is $dp[1, n, h, 0]$. This results in $O(n^4)$ complexity.