

南京大学 ACM-ICPC 集训队代码模版库



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1 General

1.1 Code library checksum

```
ab14 #!/usr/bin/python3
c502 import re, sys, hashlib
427e
f7db for line in sys.stdin.read().strip().split("\n") :
ddf5     print(hashlib.md5(re.sub(r'\s|//[.]*', '', line).encode('utf8')).hexdigest()
        [-4:], line)
```

1.2 Makefile

```
dab2 .PHONY : run
427e
207e $(t) : $(t).cpp
2d16     g++ --std=c++14 -Wall -D__LOCAL_DEBUG__ -fsanitize=undefined -fsanitize=
        address -ggdb -pipe -o $@ $<
427e
5f25 run : $(t)
bf3e     ./$$(t) < $(t).in
```

1.3 .vimrc

```
914c set nocompatible
733d syntax on
6bbc colorscheme slate
7db5 set number
b0e3 set cursorline
061b set shiftwidth=2
8011 set softtabstop=2
a66d set tabstop=2
d23a set expandtab
5245 set magic
740c set smartindent
bee8 set backspace=indent,eol,start
815d set cmdheight=1
0a40 set laststatus=2
1c67 set whichwrap=b,s,<,>,[,]
```

1.4 Stack

```
const int STK_SZ = 2000000;
char STK[STK_SZ * sizeof(void)];
void *STK_BAK;

#if defined(__i386__)
#define SP "%esp"
#elif defined(__x86_64__)
#define SP "%rsp"
#endif

int main() {
    asm volatile("movl SP, %0; movl %1, SP: =g(STK_BAK):g(STK+sizeof(STK));");
    ;

    // main program

    asm volatile("movl %0, SP::g(STK_BAK);");
    return 0;
}
```

1.5 Template

```
#include <bits/stdc++.h>
using namespace std;

#ifdef __LOCAL_DEBUG__
# define _debug(fmt, ...) fprintf(stderr, "[%s] " fmt "\n", \
    __func__, ##_VA_ARGS_)
#else
# define _debug(...) ((void) 0)
#endif

#define rep(i, n) for (int i=0; i<(n); i++)
#define Rep(i, n) for (int i=1; i<=(n); i++)
#define range(x) begin(x), end(x)
typedef long long LL;
typedef unsigned long long ULL;
```

2 Miscellaneous Algorithms

2.1 2-SAT

```

0f42 const int MAXN = 100005;
03a9 struct twoSAT{
5c83     int n;
8f72     vector<int> G[MAXN*2];
d060     bool mark[MAXN*2];
b42d     int S[MAXN*2], c;
427e
d34f     void init(int n){
b985         this->n = n;
f9ec         for (int i=0; i<n*2; i++) G[i].clear();
0609         memset(mark, 0, sizeof(mark));
95cf     }
427e
3bd5     bool dfs(int x){
bd70         if (mark[x^1]) return false;
c96a         if (mark[x]) return true;
fd23         mark[x] = true;
4bea         S[c++] = x;
1ce6         for (int i=0; i<G[x].size(); i++)
d942             if (!dfs(G[x][i])) return false;
3361         return true;
95cf     }
427e
5894     void add_clause(int x, bool xval, int y, bool yval){
6afe         x = x * 2 + xval;
e680         y = y * 2 + yval;
81cc         G[x^1].push_back(y);
6835         G[y^1].push_back(x);
95cf     }
427e
d0cb     bool solve() {
7c39         for (int i=0; i<n*2; i+=2){
e63f             if (!mark[i] && !mark[i+1]){
88fb                 c = 0;
f4b9                 if (!dfs(i)){
3f03                     while (c > 0) mark[S[--c]] = false;
86c5                     if (!dfs(i+1)) return false;
95cf                 }
95cf             }

```

```

    }
    return true;
}

inline bool value(unsigned i){return mark[2*i+1];}
};

```

95cf
3361
95cf
427e
5f0a
329b

2.2 Knuth's optimization

```

int n;
int dp[256][256], dc[256][256];

template <typename T>
void compute(T cost) {
    for (int i = 0; i <= n; i++) {
        dp[i][i] = 0;
        dc[i][i] = i;
    }
    rep (i, n) {
        dp[i][i+1] = 0;
        dc[i][i+1] = i;
    }
    for (int len = 2; len <= n; len++) {
        for (int i = 0; i + len <= n; i++) {
            int j = i + len;
            int lbnd = dc[i][j-1], rbnd = dc[i+1][j];
            dp[i][j] = INT_MAX / 2;
            int c = cost(i, j);
            for (int k = lbnd; k <= rbnd; k++) {
                int res = dp[i][k] + dp[k][j] + c;
                if (res < dp[i][j]) {
                    dp[i][j] = res;
                    dc[i][j] = k;
                }
            }
        }
    }
};

```

5c83
d77c
427e
b7ec
0bc7
0423
8f5e
9488
95cf
be8e
95b5
aa0f
95cf
ec08
88b8
d3da
9824
a24a
f933
90d2
9bd0
26b5
e6af
9c88
95cf
95cf
95cf
95cf
329b

2.3 Mo's algorithm

All intervals are closed on both sides. When running functions `enter()` and `leave()`, the global `l` and `r` has not changed yet.

Usage:

```
add_query(id, l, r)    Add id-th query [l, r].
run()                 Run Mo's algorithm.
init()                TODO. Initialize the range [l, r].
yield(id)             TODO. Yield answer for id-th query.
enter(o)              TODO. Add o-th element.
leave(o)              TODO. Remove o-th element.
```

```
5194 constexpr int BLOCK_SZ = 300;
427e
3ec4 struct query { int l, r, id; };
d26a vector<query> queries;
427e
1e30 void add_query(int id, int l, int r) {
54c9     queries.push_back(query{l, r, id});
95cf }
427e
9f6b int l, r;
427e
427e // ----- functions to implement -----
62b4 inline void init();
50e1 inline void yield(int id);
b20d inline void enter(int o);
13af inline void leave(int o);
427e
37f0 void run() {
ab0b     if (queries.empty()) return;
8508     sort(range(queries), [](query lhs, query rhs) {
c7f8         int lb = lhs.l / BLOCK_SZ, rb = rhs.l / BLOCK_SZ;
03e7         if (lb != rb) return lb < rb;
0780         return lhs.r < rhs.r;
b251     });
6196     l = queries[0].l;
9644     r = queries[0].r;
07e2     init();
5bc9     for (query q : queries) {
7bc7         while (l > q.l) enter(l - 1), l--;
d646         while (r < q.r) enter(r + 1), r++;
13f0         while (l < q.l) leave(l), l++;
e1c6         while (r > q.r) leave(r), r--;
```

```
        yield(q.id);
    }
}
```

```
82f5
95cf
95cf
```

3 String

3.1 Knuth-Morris-Pratt algorithm

```
const int SIZE = 10005;

struct kmp_matcher {
    char p[SIZE];
    int fail[SIZE];
    int len;

    void construct(const char* needle) {
        len = strlen(p);
        strcpy(p, needle);
        fail[0] = fail[1] = 0;
        for (int i = 1; i < len; i++) {
            int j = fail[i];
            while (j && p[i] != p[j]) j = fail[j];
            fail[i + 1] = p[i] == p[j] ? j + 1 : 0;
        }
    }

    inline void found(int pos) {
        // ! add codes for having found at pos
    }

    void match(const char* haystack) { // must be called after construct
        const char* t = haystack;
        int n = strlen(t);
        int j = 0;
        rep(i, n) {
            while (j && p[j] != t[i]) j = fail[j];
            if (p[j] == t[i]) j++;
            if (j == len) found(i - len + 1);
        }
    }
};
```

```
2836
427e
d02b
2d81
9847
57b7
427e
60cf
aaa1
3a87
3dd4
d8a8
147f
3c79
4643
95cf
95cf
427e
c464
427e
95cf
427e
2daf
700f
8482
8fd0
be8e
4e19
b5d5
f024
95cf
95cf
329b
```

3.2 Manacher algorithm

```

81d4 struct Manacher {
cd09     int Len;
9255     vector<int> lc;
b301     string s;
427e
ec07     void work() {
c033         lc[1] = 1;
6bef         int k = 1;
427e
491f         for (int i = 2; i <= Len; i++) {
7957             int p = k + lc[k] - 1;
5e04             if (i <= p) {
24a1                 lc[i] = min(lc[2 * k - i], p - i + 1);
8e2e             } else {
e0e5                 lc[i] = 1;
95cf             }
74ff             while (s[i + lc[i]] == s[i - lc[i]]) lc[i]++;
2b9a             if (i + lc[i] > k + lc[k]) k = i;
95cf         }
95cf     }
427e
bfd5     void init(const char *tt) {
aaaf         int len = strlen(tt);
f701         s.resize(len * 2 + 10);
7045         lc.resize(len * 2 + 10);
8e13         s[0] = '*';
ae54         s[1] = '#';
1321         for (int i = 0; i < len; i++) {
e995             s[i * 2 + 2] = tt[i];
69fd             s[i * 2 + 1] = '#';
95cf         }
43fd         s[len * 2 + 1] = '#';
75d1         s[len * 2 + 2] = '\0';
61f7         Len = len * 2 + 2;
3e7a         work();
95cf     }
427e
b194     pair<int, int> maxpal(int l, int r) {
901a         int center = l + r + 1;
ffb2         int rad = lc[center] / 2;
ab54         int rmid = (l + r + 1) / 2;

```

```

int rl = rmid - rad, rr = rmid + rad - 1;
if ((r ^ 1) & 1) {
} else rr++;
return {max(l, rl), min(r, rr)};
}
};

```

```

17e4
3908
69f3
69dc
95cf
329b

```

3.3 Aho-corasick automaton

```

struct AC : Trie {
    int fail[MAXN];
    int last[MAXN];

    void construct() {
        queue<int> q;
        fail[0] = 0;
        rep(c, CHARN) {
            if (int u = tr[0][c]) {
                fail[u] = 0;
                q.push(u);
                last[u] = 0;
            }
        }
        while (!q.empty()) {
            int r = q.front();
            q.pop();
            rep(c, CHARN) {
                int u = tr[r][c];
                if (!u) {
                    tr[r][c] = tr[fail[r]][c];
                    continue;
                }
                q.push(u);
                int v = fail[r];
                while (v && !tr[v][c]) v = fail[v];
                fail[u] = tr[v][c];
                last[u] = tag[fail[u]] ? fail[u] : last[fail[u]];
            }
        }
    }

    void found(int pos, int j) {

```

```

a1ad
9143
daca
427e
8690
93d2
a7a6
ce3c
b1c6
a506
3e14
f689
95cf
95cf
cc78
31f0
15dd
ce3c
ab59
0ef5
9d58
b333
95cf
3e14
b3ff
d2ea
c275
654c
95cf
95cf
95cf
427e
7752

```

```

043e     if (j) {
427e         // ! add codes for having found word with tag[j]
4a96         found(pos, last[j]);
95cf     }
95cf }
427e
9785 void find(const char* text) { // must be called after construct()
80a4     int p = 0, c, len = strlen(text);
9c94     rep(i, len) {
b3db         c = id(text[i]);
f119         p = tr[p][c];
f08e         if (tag[p])
389b             found(i, p);
1e67         else if (last[p])
299e             found(i, last[p]);
95cf     }
95cf }
329b };

```

3.4 Trie

```

e6f1 const int MAXN = 12000;
dd87 const int CHARN = 26;
427e
8ff5 inline int id(char c) { return c - 'a'; }
427e
a281 struct Trie {
5c83     int n;
f4f5     int tr[MAXN][CHARN]; // Trie tree, 0 denotes fail
35a5     int tag[MAXN];
427e
4fee     Trie() {
3ccc         memset(tr[0], 0, sizeof(tr[0]));
4d52         tag[0] = 0;
46bf         n = 1;
95cf     }
427e
427e // tag should not be 0
30b0 void add(const char* s, int t) {
d50a     int p = 0, c, len = strlen(s);
9c94     rep(i, len) {
3140         c = id(s[i]);

```

```

if (!tr[p][c]) {
    memset(tr[n], 0, sizeof(tr[n]));
    tag[n] = 0;
    tr[p][c] = n++;
}
p = tr[p][c];
}
tag[p] = t;
}

// returns 0 if not found
// AC automaton does not need this function
int search(const char* s) {
    int p = 0, c, len = strlen(s);
    rep(i, len) {
        c = id(s[i]);
        if (!tr[p][c]) return 0;
        p = tr[p][c];
    }
    return tag[p];
}
};

```

```

d6c8
26dd
2e5c
73bb
95cf
f119
95cf
35ef
95cf
427e
427e
427e
216c
d50a
9c94
3140
f339
f119
95cf
840e
95cf
329b

```

3.5 Suffix array

The character immediately after the end of the string **MUST** be set to the **UNIQUE SMALLEST** element.

Usage:

<code>s[]</code>	the source string
<code>sa[i]</code>	the index of starting position of i -th suffix
<code>rk[i]</code>	the number of suffixes less than the suffix starting from i
<code>h[i]</code>	the longest common prefix between the i -th and $(i-1)$ -th lexicographically smallest suffixes
<code>n</code>	size of source string
<code>m</code>	size of character set

```

void radix_sort(int x[], int y[], int sa[], int n, int m) {
    static int cnt[1000005]; // size > max(n, m)
    fill(cnt, cnt + m, 0);
    rep(i, n) cnt[x[y[i]]]++;
    partial_sum(cnt, cnt + m, cnt);
    for (int i = n - 1; i >= 0; i--) sa[--cnt[x[y[i]]]] = y[i];
}

```

```

de09
ec00
6066
93b7
9154
acac
95cf

```

```

427e void suffix_array(int s[], int sa[], int rk[], int n, int m) {
c939     static int y[1000005]; // size > n
a69a     copy(s, s + n, rk);
7306     iota(y, y + n, 0);
afb6     radix_sort(rk, y, sa, n, m);
7b42     for (int j = 1, p = 0; j <= n; j <= 1, m = p, p = 0) {
c8c2         for (int i = n - j; i < n; i++) y[p++] = i;
8c3a         rep (i, n) if (sa[i] >= j) y[p++] = sa[i] - j;
9323         radix_sort(rk, y, sa, n, m + 1);
9e9d         swap_ranges(rk, rk + n, y);
ae41         rk[sa[0]] = p = 1;
ffd2         for (int i = 1; i < n; i++)
445e             rk[sa[i]] = ((y[sa[i]] == y[sa[i-1]] and y[sa[i]+j] == y[sa[i-1]+j])
f8dc                 ? p : ++p);
02f0         if (p == n) break;
95cf     }
97d9     rep (i, n) rk[sa[i]] = i;
95cf }
427e
1715 void calc_height(int s[], int sa[], int rk[], int h[], int n) {
c41f     int k = 0;
f313     h[0] = 0;
be8e     rep (i, n) {
0883         k = max(k - 1, 0);
527d         if (rk[i]) while (s[i+k] == s[sa[rk[i]-1]+k]) ++k;
56b7         h[rk[i]] = k;
95cf     }
95cf }

```

3.6 Rolling hash

PLEASE call `init_hash()` in `int main()`!

Usage:

`build(str)` Construct the hasher with given string.
`operator()(l, r)` Get hash value of substring $[l, r)$.

```

1e42 const LL mod = 1006658951440146419, g = 967;
9f60 const int MAXN = 200005;
0291 LL pg[MAXN];
427e
dfe7 inline LL mul(LL x, LL y) { return __int128_t(x) * y % mod; }
427e

```

```

void init_hash() { // must be called in `int main()`
    pg[0] = 1;
    for (int i = 1; i < MAXN; i++) pg[i] = mul(pg[i-1], g);
}

struct hasher {
    LL val[MAXN];

    void build(const char *str) { // assume lower-case letter only
        for (int i = 0; str[i]; i++)
            val[i+1] = (mul(val[i], g) + str[i]) % mod;
    }

    LL operator() (int l, int r) { // [l, r)
        return (val[r] - mul(val[l], pg[r-l]) + mod) % mod;
    }
};

```

4 Math

4.1 Extended Euclidean algorithm and Chinese remainder theorem

```

void exgcd(LL a, LL b, LL &g, LL &x, LL &y) {
    if (!b) g = a, x = 1, y = 0;
    else {
        exgcd(b, a % b, g, y, x);
        y -= x * (a / b);
    }
}

LL crt(LL r[], LL p[], int n) {
    LL q = 1, ret = 0;
    rep (i, n) q *= p[i];
    rep (i, n) {
        LL m = q / p[i];
        LL d, x, y;
        exgcd(p[i], m, d, x, y);
        ret = (ret + y * m * r[i]) % q;
    }
    return (q + ret) % q;
}

```


4.2 Linear basis

```

8b44 const int MAXD = 30;
03a6 struct linearbasis {
3558     ULL b[MAXD] = {};
427e
1566     bool insert(LL v) {
9b2b         for (int j = MAXD - 1; j >= 0; j--) {
de3e             if (!(v & (1ll << j))) continue;
ee78             if (b[j] v ^= b[j]
037f                 else {
7836                 for (int k = 0; k < j; k++)
f0b4                     if (v & (1ll << k)) v ^= b[k];
b0aa                 for (int k = j + 1; k < MAXD; k++)
46c9                     if (b[k] & (1ll << j)) b[k] ^= v;
8295                 b[j] = v;
3361                 return true;
95cf             }
95cf         }
438e     return false;
95cf }
329b };

```

4.3 Gauss elimination over finite field

```

b784 const LL p = 1000000007;
427e
2a2c LL powmod(LL b, LL e) {
95a2     LL r = 1;
3e90     while (e) {
1783         if (e & 1) r = r * b % p;
5549         b = b * b % p;
16fc         e >>= 1;
95cf     }
547e     return r;
95cf }
427e
c130 typedef vector<LL> VLL;
42ac typedef vector<VLL> WVLL;
427e
2c62 LL gauss(WVLL &a, WVLL &b) {
561b     const int n = a.size(), m = b[0].size();

```

```

vector<int> irow(n), icol(n), ipiv(n);
LL det = 1;

rep (i, n) {
    int pj = -1, pk = -1;
    rep (j, n) if (!ipiv[j])
        rep (k, n) if (!ipiv[k])
            if (pj == -1 || a[j][k] > a[pj][pk]) {
                pj = j;
                pk = k;
            }
    if (a[pj][pk] == 0) return 0;
    ipiv[pk]++;
    swap(a[pj], a[pk]);
    swap(b[pj], b[pk]);
    if (pj != pk) det = (p - det) % p;
    irow[i] = pj;
    icol[i] = pk;

    LL c = powmod(a[pk][pk], p - 2);
    det = det * a[pk][pk] % p;
    a[pk][pk] = 1;
    rep (j, n) a[pk][j] = a[pk][j] * c % p;
    rep (j, m) b[pk][j] = b[pk][j] * c % p;
    rep (j, n) if (j != pk) {
        c = a[j][pk];
        a[j][pk] = 0;
        rep (k, n) a[j][k] = (a[j][k] + p - a[pk][k] * c % p) % p;
        rep (k, m) b[j][k] = (b[j][k] + p - b[pk][k] * c % p) % p;
    }
}

for (int j = n - 1; j >= 0; j--) if (irow[j] != icol[j]) {
    for (int k = 0; k < n; k++) swap(a[k][irow[j]], a[k][icol[j]]);
}
return det;
}

```

a25e
2976
427e
be8e
d2b5
6b4a
e582
6112
a905
657b
95cf
d480
0305
8dad
aad8
be4d
d080
f156
427e
4ecd
865b
c36a
dd36
1b23
f8f3
e97f
c449
820b
f039
95cf
95cf
427e
37e1
50dc
95cf
f27f
95cf

4.4 Berlekamp-Massey algorithm

Call `berlekamp()` with input sequence $(x_0, x_1, \dots, x_{n-1})$. Return a vector of coefficients $(c_0 = 1, c_1, \dots, c_{m-1})$ with minimum m , such that $\sum_{i=0}^m c_i x_{j-i} = 0$ for all possible j .

```

6e50 LL mod = 1000000007;
97db vector<LL> berlekamp(const vector<LL>& a) {
8904     vector<LL> p = {1}, r = {1};
075b     LL dif = 1;
8bc9     rep (i, a.size()) {
1b35         LL u = 0;
bd0b         rep (j, p.size()) u = (u + p[j] * a[i-j]) % mod;
eae9         if (u == 0) {
b14c             r.insert(r.begin(), 0);
8e2e         } else {
0c78             auto op = p;
02f6             p.resize(max(p.size(), r.size() + 1));
0a2e             LL idif = powmod(dif, mod - 2);
9b57             rep (j, r.size())
dacc                 p[j+1] = (p[j+1] - r[j] * idif % mod * u % mod + mod) % mod;
bcd1             dif = u; r = op;
95cf         }
95cf     }
e149     return p;
95cf }

```

4.5 Fast Walsh-Hadamard transform

```

061e void fwt(int* a, int n){
5595     for (int d = 1; d < n; d <= 1)
05f2         for (int i = 0; i < n; i += d << 1)
b833             rep (j, d){
7796                 int x = a[i+j], y = a[i+j+d];
427e                 // a[i+j] = x+y, a[i+j+d] = x-y; // xor
427e                 // a[i+j] = x+y; // and
427e                 // a[i+j+d] = x+y; // or
95cf             }
95cf }
427e
4db1 void ifwt(int* a, int n){
5595     for (int d = 1; d < n; d <= 1)
05f2         for (int i = 0; i < n; i += d << 1)
b833             rep (j, d){
7796                 int x = a[i+j], y = a[i+j+d];
427e                 // a[i+j] = (x+y)/2, a[i+j+d] = (x-y)/2; // xor
427e                 // a[i+j] = x-y; // and
427e                 // a[i+j+d] = y-x; // or

```

```

    }
}

void conv(int* a, int* b, int n){
    fwt(a, n);
    fwt(b, n);
    rep(i, n) a[i] *= b[i];
    ifwt(a, n);
}

```

4.6 Fast fourier transform

```

const int NMAX = 1<<20;

typedef complex<double> cplx;

const double PI = 2*acos(0.0);
struct FFT{
    int rev[NMAX];
    cplx omega[NMAX], oinv[NMAX];
    int K, N;

    FFT(int k){
        K = k; N = 1 << k;
        rep (i, N){
            rev[i] = (rev[i>>1]>>1) | ((i&1)<<(K-1));
            omega[i] = polar(1.0, 2.0 * PI / N * i);
            oinv[i] = conj(omega[i]);
        }
    }

    void dft(cplx* a, cplx* w){
        rep (i, N) if (i < rev[i]) swap(a[i], a[rev[i]]);
        for (int l = 2; l <= N; l *= 2){
            int m = l/2;
            for (cplx* p = a; p != a + N; p += l)
                rep (k, m){
                    cplx t = w[N/l*k] * p[k+m];
                    p[k+m] = p[k] - t; p[k] += t;
                }
        }
    }
}

```

```

427e void fft(cplx* a){dft(a, omega);}
617b void ifft(cplx* a){
a123     dft(a, oinv);
3b2f     rep (i, N) a[i] /= N;
57fc }
95cf
427e void conv(cplx* a, cplx* b){
bdc0     fft(a); fft(b);
6497     rep (i, N) a[i] *= b[i];
12a5     ifft(a);
f84e }
95cf };
329b

```

4.7 Number theoretic transform

```

4ab9 const int NMAX = 1<<21;
427e
427e // 998244353 = 7*17*2^23+1, G = 3
fb9a const int P = 1004535809, G = 3; // = 479*2^21+1
427e
87ab struct NTT{
c47c     int rev[NMAX];
0eda     LL omega[NMAX], oinv[NMAX];
81af     int g, g_inv; // g: g_n = G^((P-1)/n)
9827     int K, N;
427e
2a2c     LL powmod(LL b, LL e){
95a2         LL r = 1;
3e90         while (e){
6624             if (e&1) r = r * b % P;
489e             b = b * b % P;
16fc             e >>= 1;
95cf         }
547e         return r;
95cf     }
427e
f420     NTT(int k){
e209         K = k; N = 1 << k;
7652         g = powmod(G, (P-1)/N);
4b3a         g_inv = powmod(g, N-1);
e04f         omega[0] = oinv[0] = 1;

```

```

rep (i, N){
    rev[i] = (rev[i>>1]>>1) | ((i&1)<<(K-1));
    if (i){
        omega[i] = omega[i-1] * g % P;
        oinv[i] = oinv[i-1] * g_inv % P;
    }
}

void _ntt(LL* a, LL* w){
    rep (i, N) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int l = 2; l <= N; l *= 2){
        int m = l/2;
        for (LL* p = a; p != a + N; p += l)
            rep (k, m){
                LL t = w[N/l*k] * p[k+m] % P;
                p[k+m] = (p[k] - t + P) % P;
                p[k] = (p[k] + t) % P;
            }
    }
}

void ntt(LL* a){_ntt(a, omega);}
void intt(LL* a){
    LL inv = powmod(N, P-2);
    _ntt(a, oinv);
    rep (i, N) a[i] = a[i] * inv % P;
}

void conv(LL* a, LL* b){
    ntt(a); ntt(b);
    rep (i, N) a[i] = a[i] * b[i] % P;
    intt(a);
}
};

```

4.8 Sieve of Euler

```

const int MAXX = 1e7+5;
bool p[MAXX];
int prime[MAXX], sz;

```

b393
7ba3
ad4f
8d8b
9e14
95cf
95cf
95cf
427e
9668
a215
ac6e
2969
7a1d
c24f
0ad3
6209
fa1b
95cf
95cf
95cf
427e
92ea
5daf
1f2a
9910
a873
95cf
427e
3a5b
ad16
e49e
5748
95cf
329b

```

9bc6 void sieve(){
9628     p[0] = p[1] = 1;
1ec8     for (int i = 2; i < MAXX; i++){
bf28         if (!p[i]) prime[sz++] = i;
e82c         for (int j = 0; j < sz && i*prime[j] < MAXX; j++){
b6a9             p[i*prime[j]] = 1;
5f51             if (i % prime[j] == 0) break;
95cf         }
95cf     }
95cf }

```

```

        } else {
            pval[x] = prime[j];
            pcnt[x] = 1;
        }
        if (x != pval[x]) {
            f[x] = f[x / pval[x]] * f[pval[x]]
        }
        if (i % prime[j] == 0) break;
    }
}
}
}
}

```

```

8e2e
cc91
6322
95cf
6191
d614
95cf
5f51
95cf
95cf
95cf
95cf
95cf

```

4.9 Sieve of Euler (General)

```

b62e namespace sieve {
6589     constexpr int MAXN = 10000007;
e982     bool p[MAXN]; // true if not prime
6ae8     int prime[MAXN], sz;
cbf7     int pval[MAXN], pcnt[MAXN];
6030     int f[MAXN];
427e
76f6     void exec(int N = MAXN) {
9628         p[0] = p[1] = 1;
427e
8a8a         pval[1] = 1;
bdda         pcnt[1] = 0;
c6b9         f[1] = 1;
427e
a643         for (int i = 2; i < N; i++) {
01d6             if (!p[i]) {
b2b2                 prime[sz++] = i;
37d9                 for (LL j = i; j < N; j *= i) {
758c                     int b = j / i;
81fd                     pval[j] = i * pval[b];
e0f3                     pcnt[j] = pcnt[b] + 1;
a96c                     f[j] = ____; // f[j] = f(i^pcnt[j])
95cf                 }
95cf             }
34c0             for (int j = 0; i * prime[j] < N; j++) {
f87a                 int x = i * prime[j]; p[x] = 1;
20cc                 if (i % prime[j] == 0) {
9985                     pval[x] = pval[i] * prime[j];
3f93                     pcnt[x] = pcnt[i] + 1;

```

4.10 Miller-Rabin primality test

The array `a[]` (excluding sentinel, i.e. `LLONG_MAX`) should be

{2}	when $n < 2,047$.
{2, 7, 61}	when $n < 4,759,123,141 (2^{32})$.
{2, 3, 5, 7, 11}	when $n < 2.1 \times 10^{12}$.
{2, 325, 9375, 28178, 450775, 9780504, 1795265022}	when $n < 2^{64}$.

```

bool test(LL n){
    if (n < 3) return n==2;
    // ! The array a[] should be modified if the range of x changes.
    const LL a[] = {2LL, 7LL, 61LL, LLONG_MAX};
    LL r = 0, d = n-1, x;
    while (~d & 1) d >>= 1, r++;
    for (int i=0; a[i] < n; i++){
        x = powmod(a[i], d, n); // ! powmod must use for 64bit mulmod
        if (x == 1 || x == n-1) goto next;
        rep (i, r) {
            x = mulmod(x, x, n);
            if (x == n-1) goto next;
        }
        return false;
    }
next:;
}
return true;
}

```

```

f16f
59f2
427e
3f11
c320
f410
2975
ece1
7f99
e257
d7ff
8d2e
95cf
438e
d490
95cf
3361
95cf

```

4.11 Integer factorization (Pollard's rho)

```

2e6b ULL gcd(ULL a, ULL b) {return b ? gcd(b, a % b) : a;}
427e
54a5 ULL PollardRho(ULL n){
45eb     ULL c, x, y, d = n;
d3e5     if (~n&1) return 2;
3c69     while (d == n){
0964         x = y = 2;
4753         d = 1;
5952         c = rand() % (n - 1) + 1;
9e5b         while (d == 1){
33d5             x = (mulmod(x, x, n) + c) % n;
e1bf             y = (mulmod(y, y, n) + c) % n;
e1bf             y = (mulmod(y, y, n) + c) % n;
a313             d = gcd(x>y ? x-y : y-x, n);
95cf         }
95cf     }
5d89     return d;
95cf }

```

5 Graph Theory

5.1 Strongly connected components

```

837c const int MAXV = 100005;
427e
2ea0 struct graph{
88e3     vector<int> adj[MAXV];
9cad     stack<int> s;
3d02     int V; // number of vertices
8b6c     int pre[MAXV], lnk[MAXV], scc[MAXV];
27ee     int time, sccn;
427e
bfab     void add_edge(int u, int v){
c71a         adj[u].push_back(v);
95cf     }
427e
d714     void dfs(int u){
7e41         pre[u] = lnk[u] = ++time;
80f6         s.push(u);

```

```

for (int v : adj[u]){
    if (!pre[v]){
        dfs(v);
        lnk[u] = min(lnk[u], lnk[v]);
    } else if (!scc[v]){
        lnk[u] = min(lnk[u], pre[v]);
    }
}
if (lnk[u] == pre[u]){
    sccn++;
    int x;
    do {
        x = s.top(); s.pop();
        scc[x] = sccn;
    } while (x != u);
}
}

void find_scc(){
    time = sccn = 0;
    memset(scc, 0, sizeof scc);
    memset(pre, 0, sizeof pre);
    Rep (i, V){
        if (!pre[i]) dfs(i);
    }
}

vector<int> adjc[MAXV];
void contract(){
    Rep (i, V)
        rep (j, adj[i].size()){
            if (scc[i] != scc[adj[i][j]])
                adjc[scc[i]].push_back(scc[adj[i][j]]);
        }
}
};

```

18f6
173e
5f3c
002c
6068
d5df
95cf
95cf
8de2
660f
3c9e
a69f
3834
b0e9
6757
95cf
95cf
427e
4c88
f4a2
8de7
8c2f
6901
56d1
95cf
95cf
427e
27ce
364d
1a1e
21a2
b730
b46e
95cf
95cf
329b

5.2 Vertex biconnected components, cut vertex

A component root u is a cut vertex iff the size of $bccin[u]$ is at least 2; for any other vertice u , it is a cut vertex iff $bccin[u]$ is nonempty.

Usage:

`dfs(u)` Run `dfs(u)` for each connected component.
`bcc[i]` The edges of the i -th biconnected components, numbered from 0. If the bcc is a simple cycle, the edges are sorted in order.
`bccin[u]` The indices of biconnected components reachable from vertex u .

```
0f42 const int MAXN = 100005;
35b8 int n, m;
0b32 vector<int> adj[MAXN];
0a8f int dfn[MAXN], low[MAXN], idx = 0;
05d2 vector<int> bccin[MAXN];
2eab vector<vector<pair<int, int>>> bcc;
3eed stack<pair<int, int>> st;
427e
6576 void dfs(int u, int p = 0) {
9891     dfn[u] = low[u] = ++idx;
18f6     for (int v : adj[u]) {
3c64         if (!dfn[v]) {
c600             st.emplace(u, v);
e2f7             dfs(v, u);
a19f             low[u] = min(low[u], low[v]);
9cb7             if (low[v] >= dfn[u]) {
a0e8                 bccin[u].push_back(bcc.size());
7dc7                 vector<pair<int, int>> cur;
a69f                 do {
bfe3                     cur.push_back(st.top());
b439                     st.pop();
5f33                 } while (cur.back() != make_pair(u, v));
b854                 reverse(range(cur));
0c6c                 bcc.push_back(move(cur));
95cf             }
dddc         } else if (dfn[v] < dfn[u] and v != p) {
c600             st.emplace(u, v);
769a             low[u] = min(low[u], dfn[v]);
95cf         }
95cf     }
95cf }
```

5.3 Minimum spanning arborescence, faster

All vertices are 1-based. Clear the fields when reuse the struct.

Usage:

`add_edge(u, v, w)` Add an edge from u to v with weight w .
`run(n, rt)` Compute the total weight of MSA rooted at rt . If not exist, return `LLONG_MIN`.

Time Complexity: $O(|E| \log^2 |V|)$

```
const int MAXN = 300005;
typedef pair<LL, int> pii;
struct MDST {
    priority_queue<pii, vector<pii>, greater<pii>> heap[MAXN];
    LL shift[MAXN];
    int fa[MAXN], vis[MAXN];

    int find(int x) { return fa[x] == x ? x : fa[x] = find(fa[x]); }

    void unite(int x, int y) {
        x = find(x); y = find(y); fa[y] = x; if (x == y) return;
        if (heap[x].size() < heap[y].size()) {
            swap(heap[x], heap[y]);
            swap(shift[x], shift[y]);
        }
        while (heap[y].size()) {
            auto p = heap[y].top(); heap[y].pop();
            heap[x].emplace(p.first - shift[y] + shift[x], p.second);
        }
    }

    void add_edge(int u, int v, LL w) { heap[v].emplace(w, u); }

    LL run(int n, int rt) {
        LL ans = 0;
        iota(fa, fa + n + 1, 0);
        Rep(i, n) if (find(i) != find(rt)) {
            int u = find(i);
            stack<int, vector<int>> s;
            while (find(u) != find(rt)) {
                if (vis[u]) while (s.top() != u) {
                    vis[s.top()] = 0; unite(u, s.top()); s.pop();
                } else { vis[u] = 1; s.push(u); }
                while (heap[u].size()) {
                    ans += heap[u].top().first - shift[u];
                    shift[u] = heap[u].top().first;
                    if (find(heap[u].top().second) != u) break;
                    heap[u].pop();
                }
            }
        }
    }
}
```

5ece
2fef
1495
01b2
321d
fc06
427e
38dd
427e
29b0
0c14
6fa0
9c26
2ffc
95cf
9959
175b
c0c5
95cf
95cf
427e
0bbd
427e
a526
f7ff
81f2
19b3
a7b1
010e
eff5
0dda
c593
83c4
c76e
b385
dde2
da47
9fbb
95cf

```

6961         if (heap[u].empty()) return LLONG_MIN;
87e6         u = find(heap[u].top().second);
95cf     }
2d46     while (s.size()) { vis[s.top()] = 0; unite(rt, s.top()); s.pop(); }
95cf     }
4206     return ans;
95cf }
329b };
    
```

5.4 Minimum spanning arborescence, slow

All vertices are 1-based. Clear the fields when reuse the struct.

Usage:

init(n) Initialize the structure with n vertices, indexed from 1.
 add_edge(u, v, w) Add an edge from u to v with weight w .
 run(n, rt) Compute the total weight of MSA rooted at rt . If not exist, return LLONG_MIN.

Time Complexity: $O(|V|^2)$

```

1495 struct MDST {
3d02     int V;
d48e     LL heap[MAXN][MAXN];
321d     LL shift[MAXN];
fc06     int fa[MAXN], vis[MAXN];
427e
d34f     void init(int n) {
34cc         V = n;
3295         Rep (i, n) Rep (j, n) heap[i][j] = LLONG_MAX / 2;
95cf     }
427e
38dd     int find(int x) { return fa[x] == x ? x : fa[x] = find(fa[x]); }
427e
29b0     void unite(int x, int y) {
0c14         x = find(x); y = find(y); fa[y] = x; if (x == y) return ;
6506         Rep (i, V) heap[x][i] = min(heap[x][i], heap[y][i] - shift[y] + shift[x]);
95cf     }
427e
f09c     void add_edge(int u, int v, LL w) { heap[v][u] = min(heap[v][u], w); }
427e
a526     LL run(int n, int rt) {
34cc         V = n;
    
```

```

LL ans = 0;
iota(fa, fa + n + 1, 0);
Rep (i, n) if (find(i) != find(rt)) {
    int u = find(i);
    stack<int, vector<int>> s;
    while (find(u) != find(rt)) {
        if (vis[u]) while (s.top() != u) {
            vis[s.top()] = 0; unite(u, s.top()); s.pop();
        } else { vis[u] = 1; s.push(u); }

        Rep (i, V) if (find(i) == u) heap[u][i] = LLONG_MAX / 2;

        auto ptr = min_element(heap[u] + 1, heap[u] + V + 1);
        if (*ptr == LLONG_MAX / 2) return LLONG_MIN;
        ans += *ptr - shift[u];
        shift[u] = *ptr;

        u = ptr - heap[u];
    }
    while (s.size()) { vis[s.top()] = 0; unite(rt, s.top()); s.pop(); }
}
return ans;
};
    
```

5.5 Maximum flow (Dinic)

Usage:

add_edge(u, v, c) Add an edge from u to v with capacity c .
 max_flow(s, t) Compute maximum flow from s to t .

Time Complexity: For general graph, $O(V^2E)$; for network with unit capacity, $O(\min\{V^{2/3}, \sqrt{E}\}E)$; for bipartite network, $O(\sqrt{VE})$.

```

struct edge{
    int from, to;
    LL cap, flow;
};

const int MAXN = 1005;
struct Dinic {
    int n, m, s, t;
    vector<edge> edges;
    vector<int> G[MAXN];
    bcf8
60e2
5e6d
329b
427e
e2cd
9062
4dbf
9f0c
b891
    
```

```

bbb6  bool vis[MAXN];
b40a  int d[MAXN];
ddec  int cur[MAXN];
427e
5973  void add_edge(int from, int to, LL cap) {
7b55      edges.push_back(edge{from, to, cap, 0});
1db7      edges.push_back(edge{to, from, 0, 0});
fe77      m = edges.size();
dff5      G[from].push_back(m-2);
8f2d      G[to].push_back(m-1);
95cf  }
427e
1836  bool bfs() {
3b73      memset(vis, 0, sizeof(vis));
93d2      queue<int> q;
5d13      q.push(s);
2cd2      vis[s] = 1;
721d      d[s] = 0;
cc78      while (!q.empty()) {
66ba          int x = q.front(); q.pop();
3b61          for (int i = 0; i < G[x].size(); i++) {
b510              edge& e = edges[G[x][i]];
bba9              if (!vis[e.to] && e.cap > e.flow) {
cd72                  vis[e.to] = 1;
cf26                  d[e.to] = d[x] + 1;
ca93                  q.push(e.to);
95cf              }
95cf          }
95cf      }
b23b      return vis[t];
95cf  }
427e
9252  LL dfs(int x, LL a) {
6904      if (x == t || a == 0) return a;
8bf9      LL flow = 0, f;
f515      for (int& i = cur[x]; i < G[x].size(); i++) {
b510          edge& e = edges[G[x][i]];
2374          if(d[x] + 1 == d[e.to] && (f = dfs(e.to, min(a, e.cap-e.flow))) > 0)
{
1cce              e.flow += f;
e16d              edges[G[x][i]^1].flow -= f;
a74d              flow += f;
23e5              a -= f;
97ed              if(a == 0) break;

```

```

        }
    }
    return flow;
}

LL max_flow(int s, int t) {
    this->s = s; this->t = t;
    LL flow = 0;
    while (bfs()) {
        memset(cur, 0, sizeof(cur));
        flow += dfs(s, LLONG_MAX);
    }
    return flow;
}

vector<int> min_cut() { // call this after maxflow
    vector<int> ans;
    for (int i = 0; i < edges.size(); i++) {
        edge& e = edges[i];
        if(vis[e.from] && !vis[e.to] && e.cap > 0) ans.push_back(i);
    }
    return ans;
}
};

```

5.6 Maximum cardinality bipartite matching (Hungarian)

```

#include <bits/stdc++.h>
using namespace std;

#define rep(i, n) for (int i = 0; i < (n); i++)
#define Rep(i, n) for (int i = 1; i <= (n); i++)
#define range(x) (x).begin(), (x).end()
typedef long long LL;

struct Hungarian{
    int nx, ny;
    vector<int> mx, my;
    vector<vector<int>> > e;
    vector<bool> mark;

    void init(int nx, int ny){

```



```

c1d1     this->nx = nx;
f9c1     this->ny = ny;
ac92     mx.resize(nx); my.resize(ny);
3f11     e.clear(); e.resize(nx);
1023     mark.resize(nx);
95cf     }
427e
4589     inline void add(int a, int b){
486c         e[a].push_back(b);
95cf     }
427e
0c2b     bool augment(int i){
207c         if (!mark[i]) {
dae4             mark[i] = true;
6a1e             for (int j : e[i]){
0892                 if (my[j] == -1 || augment(my[j])){
9ca3                     mx[i] = j; my[j] = i;
3361                     return true;
95cf                 }
95cf             }
438e         return false;
95cf     }
427e
3fac     int match(){
5b57         int ret = 0;
b0f1         fill(range(mx), -1);
b957         fill(range(my), -1);
4ed1         rep (i, nx){
13a5             fill(range(mark), false);
cc89             if (augment(i)) ret++;
95cf         }
ee0f         return ret;
95cf     }
329b };

```

5.7 Maximum matching of general graph (Edmond's blossom)

Usage:

init(n) Initialize the template with n vertices, numbered from 1.
 add_edge(u, v) Add an undirected edge uv .
 solve() Find the maximum matching. Return the number of matched edges.
 mate[] The mate of a matched vertex. If it is not matched, then the value is 0.
Time Complexity: $O(|V|^3)$, but extremely fast in practice.

```

const int MAXN = 1024;
struct Blossom {
    vector<int> adj[MAXN];
    queue<int> q;
    int n;
    int label[MAXN], mate[MAXN], save[MAXN], used[MAXN];

    void init(int nv) {
        n = nv; for (auto& v : adj) v.clear();
        fill(range(label), 0); fill(range(mate), 0);
        fill(range(save), 0); fill(range(used), 0);
    }

    void add_edge(int u, int v) { adj[u].push_back(v); adj[v].push_back(u); }

    void rematch(int x, int y) {
        int m = mate[x]; mate[x] = y;
        if (mate[m] == x) {
            if (label[x] <= n) {
                mate[m] = label[x]; rematch(label[x], m);
            } else {
                int a = 1 + (label[x] - n - 1) / n;
                int b = 1 + (label[x] - n - 1) % n;
                rematch(a, b); rematch(b, a);
            }
        }
    }

    void traverse(int x) {
        Rep (i, n) save[i] = mate[i];
        rematch(x, x);
        Rep (i, n) {
            if (mate[i] != save[i]) used[i] ++;
            mate[i] = save[i];
        }
    }
}

```

c041
6ab1
0b32
93d2
5c83
0de2
427e
2186
3728
477d
bb35
95cf
427e
c2dd
427e
2a48
8af8
1aa4
f4ba
740a
8e2e
3341
2885
ef33
95cf
95cf
95cf
427e
8a50
43c0
2ef7
34d7
62c5
97ef
95cf
95cf

```

427e void relabel(int x, int y) {
8bf8     Rep (i, n) used[i] = 0;
d101     traverse(x); traverse(y);
c4ea     Rep (i, n) {
34d7         if (used[i] == 1 and label[i] < 0) {
dee9             label[i] = n + x + (y - 1) * n;
1c22             q.push(i);
eb31         }
95cf     }
95cf }
427e
a0ce int solve() {
34d7     Rep (i, n) {
a073         if (mate[i]) continue;
1fc0         Rep (j, n) label[j] = -1;
7676         label[i] = 0; q = queue<int>(); q.push(i);
1c7d         while (q.size()) {
66ba             int x = q.front(); q.pop();
b98c             for (int y : adj[x]) {
c07f                 if (mate[y] == 0 and i != y) {
7f36                     mate[y] = x; rematch(x, y); q = queue<int>(); break;
95cf                 }
d315                 if (label[y] >= 0) { relabel(x, y); continue; }
58ec                 if (label[mate[y]] < 0) {
c9c4                     label[mate[y]] = x; q.push(mate[y]);
95cf                 }
95cf             }
95cf         }
8abb         int cnt = 0;
b52f         Rep (i, n) cnt += (mate[i] > i);
6808         return cnt;
95cf     }
329b };

```

5.8 Minimum cost maximum flow

```

bcf8 struct edge{
60e2     int from, to;
d698     int cap, flow;
32cc     LL cost;

```

```

};

const LL INF = LLONG_MAX / 2;
const int MAXN = 5005;
struct MCMF {
    int s, t, n, m;
    vector<edge> edges;
    vector<int> G[MAXN];
    bool inq[MAXN]; // queue
    LL d[MAXN]; // distance
    int p[MAXN]; // previous
    int a[MAXN]; // improvement

    void add_edge(int from, int to, int cap, LL cost) {
        edges.push_back(edge{from, to, cap, 0, cost});
        edges.push_back(edge{to, from, 0, 0, -cost});
        m = edges.size();
        G[from].push_back(m-2);
        G[to].push_back(m-1);
    }

    bool spfa(){
        queue<int> q;
        fill(d, d + MAXN, INF); d[s] = 0;
        memset(inq, 0, sizeof(inq));
        q.push(s); inq[s] = true;
        p[s] = 0; a[s] = INT_MAX;
        while (!q.empty()){
            int u = q.front(); q.pop(); inq[u] = false;
            for (int i : G[u]) {
                edge& e = edges[i];
                if (e.cap > e.flow && d[e.to] > d[u] + e.cost){
                    d[e.to] = d[u] + e.cost;
                    p[e.to] = G[u][i];
                    a[e.to] = min(a[u], e.cap - e.flow);
                    if (!inq[e.to]) q.push(e.to), inq[e.to] = true;
                }
            }
        }
        return d[t] != INF;
    }

    void augment(){
        int u = t;

```

```

329b
427e
cc3e
2aa8
c6cb
9ceb
9f0c
b891
f74f
8f67
9524
b330
427e
f7f2
24f0
95f0
fe77
dff5
8f2d
95cf
427e
3c52
93d2
8494
fd48
5e7c
2dae
cc78
b0aa
3bba
56d8
3601
55bc
0bea
8249
e5d3
95cf
95cf
95cf
6d7c
95cf
427e
71a4
06f1

```

```

b19d         while (u != s){
db09             edges[p[u]].flow += a[t];
25a9             edges[p[u]^1].flow -= a[t];
e6c9             u = edges[p[u]].from;
95cf         }
95cf     }
427e
6e20 #ifndef GIVEN_FLOW
5972     bool min_cost(int s, int t, int f, LL& cost) {
590d         this->s = s; this->t = t;
21d4         int flow = 0;
23cb         cost = 0;
22dc         while (spfa()) {
bcd8             augment();
a671             if (flow + a[t] >= f){
b14d                 cost += (f - flow) * d[t]; flow = f;
3361                 return true;
8e2e             } else {
2a83                 flow += a[t]; cost += a[t] * d[t];
95cf             }
95cf         }
438e         return false;
95cf     }
a8cb #else
f9a9     int min_cost(int s, int t, LL& cost) {
590d         this->s = s; this->t = t;
21d4         int flow = 0;
23cb         cost = 0;
22dc         while (spfa()) {
bcd8             augment();
2a83             flow += a[t]; cost += a[t] * d[t];
95cf         }
84fb         return flow;
95cf     }
1937 #endif
329b };
    
```

5.9 Fast LCA

All indices of the tree are 1-based.

Usage:

preprocess(root)	Initialize with tree rooted at root.
lca(u, v)	Query the lowest common ancestor of u and v .

```

const int MAXN = 500005;
vector<int> adj[MAXN];
int id[MAXN], nid;
pair<int, int> st[MAXN << 1][33 - __builtin_clz(MAXN)];

void dfs(int u, int p, int d) {
    st[id[u] = nid++][0] = {d, u};
    for (int v : adj[u]) {
        if (v == p) continue;
        dfs(v, u, d + 1);
        st[nid++][0] = {d, u};
    }
}

void preprocess(int root) {
    nid = 0;
    dfs(root, 0, 1);
    int l = 31 - __builtin_clz(nid);
    rep (j, l) rep (i, 1+nid-(1<<j))
        st[i][j+1] = min(st[i][j], st[i+(1<<j)][j]);
}

int lca(int u, int v) {
    tie(u, v) = minmax(id[u], id[v]);
    int k = 31 - __builtin_clz(v-u+1);
    return min(st[u][k], st[v-(1<<k)+1][k]).second;
}
    
```

5.10 Heavy-light decomposition

Time Complexity: The decomposition itself takes linear time. Each query takes $O(\log n)$ operations.

```

const int MAXN = 100005;
vector<int> adj[MAXN];
int sz[MAXN], top[MAXN], fa[MAXN], son[MAXN], depth[MAXN], id[MAXN];

void dfs1(int x, int dep, int par){
    depth[x] = dep;
    sz[x] = 1;
    fa[x] = par;
    int maxn = 0, s = 0;
    
```

```

c861     for (int c: adj[x]){
fe45         if (c == par) continue;
fd2f         dfs1(c, dep + 1, x);
b790         sz[x] += sz[c];
f0f1         if (sz[c] > maxn){
c749             maxn = sz[c];
fe19             s = c;
95cf         }
95cf     }
0e08     son[x] = s;
95cf }
427e
ba54     int cid = 0;
3644     void dfs2(int x, int t){
8d96         top[x] = t;
d314         id[x] = ++cid;
c4a1         if (son[x]) dfs2(son[x], t);
c861         for (int c: adj[x]){
9881             if (c == fa[x]) continue;
5518             if (c == son[x]) continue;
13f9             else dfs2(c, c);
95cf         }
95cf     }
427e
0f04     void decomp(int root){
9fa4         dfs1(root, 1, 0);
1c88         dfs2(root, root);
95cf     }
427e
2c98     void query(int u, int v){
03a1         while (top[u] != top[v]){
45ec             if (depth[top[u]] < depth[top[v]]) swap(u, v);
427e             // id[top[u]] to id[u]
005b             u = fa[top[u]];
95cf         }
6083         if (depth[u] > depth[v]) swap(u, v);
427e         // id[u] to id[v]
95cf     }

```

5.11 Centroid decomposition

Note that the centroid here is not the exact centroid of the graph. It only guarantees that the size of each subtree does not exceed half of that of the original tree. This is enough to guar-

antee the correct time complexity. All vertices are numbered from 1. Call `decomp(root)` to use.

Usage:

`decomp(u, p)` Decompose the tree rooted at u with parent p .

Time Complexity: The decomposition itself takes $O(n \log n)$ time.

```

vector<int> adj[100005];
int sz[100005], sum;

void getsz(int u, int p) {
    sz[u] = 1; sum++;
    for (int v : adj[u]) {
        if (v == p) continue;
        getsz(v, u);
        sz[u] += sz[v];
    }
}

int getcent(int u, int p) {
    for (int v : adj[u])
        if (v != p and sz[v] > sum / 2)
            return getcent(v, u);
    return u;
}

void decompose(int u) {
    sum = 0; getsz(u, 0);
    u = getcent(u, 0); // update u to the centroid

    for (int v : adj[u]) {
        // get answer for subtree v
    }
    // get answer for the whole tree
    // don't forget to count the centroid itself

    for (int v : adj[u]) { // divide and conquer
        adj[v].erase(find(range(adj[v]), u));
        decompose(v);
        adj[v].push_back(u); // restore deleted edge
    }
}

```

5.12 DSU on tree

This implementation avoids parallel existence of multiple data structures but requires that the data structure is invertible. To use this template, implement `merge`, `enter`, `leave` as needed; first call `decomp(root, 0)`, then call `work(root, 0, false)`. Labels of vertices start from 1.

Usage:

`decomp(u, p)` Decompose the tree *u*.
`work(u, p, keep)` Work for subtree *u*. When `keep` is set, information is not cleared.

Time Complexity: $O(n \log n)$ times the complexity for `merge`, `enter`, `leave`.

```
1fb6 vector<int> adj[100005];
901d int sz[100005], son[100005];
427e
5559 void decomp(int u, int p) {
50c0     sz[u] = 1;
18f6     for (int v : adj[u]) {
bd87         if (v == p) continue;
a851         decomp(v, u);
8449         sz[u] += sz[v];
d28c         if (sz[v] > sz[son[u]]) son[u] = v;
95cf     }
95cf }
427e
b7ec template <typename T>
62f5 void trav(T fn, int u, int p) {
4412     fn(u);
30b3     for (int v : adj[u]) if (v != p) trav(fn, v, u);
95cf }
427e
7467 #define for_light(v) for (int v : adj[u]) if (v != p and v != son[u])
33ff void work(int u, int p, bool keep) {
72a2     for_light(v) work(v, u, 0); // process light children
427e
427e     // process heavy child
427e     // current data structure contains info of heavy child
9866     if (son[u]) work(son[u], u, 1);
427e
18a9     auto merge = [u] (int c) { /* count contribution of c */ };
1ab0     auto enter = [] (int c) { /* add vertex c */ };
f241     auto leave = [] (int c) { /* remove vertex c */ };
427e
3d3b     for_light(v) {
```

```
        trav(merge, v, u);
        trav(enter, v, u);
    }

    // count answer for root and add it
    // Warning: special check may apply to root!
    merge(u);
    enter(u);

    // leave current tree
    if (!keep) trav(leave, u, p);
}
```

74c6
c13d
95cf
427e
427e
427e
c54f
9dec
427e
427e
4e3e
95cf

6 Data Structures

6.1 Fenwick tree (point update range query)

```
struct bit_purq { // point update, range query
    int N;
    vector<LL> tr;

    void init(int n) { tr.resize(N = n + 5); }

    LL sum(int n) {
        LL ans = 0;
        while (n) { ans += tr[n]; n &= n - 1; }
        return ans;
    }

    void add(int n, LL x){
        while (n < N) { tr[n] += x; n += n & -n; }
    }
};
```

9976
d7af
99ff
427e
456d
427e
63d0
f7ff
6770
4206
95cf
427e
f4bd
968e
95cf
329b

6.2 Fenwick tree (range update point query)

```
struct bit_rupq{ // range update, point query
    int N;
    vector<LL> tr;
```

3d03
d7af
99ff
427e

```

456d void init(int n) { tr.resize(N = n + 5);}
427e
38d4 LL query(int n) {
f7ff     LL ans = 0;
3667     while (n < N) { ans += tr[n]; n += n & -n; }
4206     return ans;
95cf }
427e
f4bd void add(int n, LL x) {
0a2b     while (n) { tr[n] += x; n &= n - 1; }
95cf }
329b };

```

6.3 Segment tree

```

3942 LL p;
1ebb const int MAXN = 4 * 100006;
451a struct segtree {
27be     int l[MAXN], m[MAXN], r[MAXN];
4510     LL val[MAXN], tadd[MAXN], tmul[MAXN];
427e
ac35 #define lson (o<<1)
1294 #define rson (o<<1|1)
427e
1344 void pull(int o) {
bbe9     val[o] = (val[lson] + val[rson]) % p;
95cf }
427e
e4bc void push_add(int o, LL x) {
5dd6     val[o] = (val[o] + x * (r[o] - l[o])) % p;
6eff     tadd[o] = (tadd[o] + x) % p;
95cf }
427e
d658 void push_mul(int o, LL x) {
b82c     val[o] = val[o] * x % p;
aa86     tadd[o] = tadd[o] * x % p;
649f     tmul[o] = tmul[o] * x % p;
95cf }
427e
b149 void push(int o) {
3159     if (l[o] == m[o]) return;
0a90     if (tmul[o] != 1) {

```

```

push_mul(lson, tmul[o]);
push_mul(rson, tmul[o]);
tmul[o] = 1;
}
if (tadd[o]) {
push_add(lson, tadd[o]);
push_add(rson, tadd[o]);
tadd[o] = 0;
}
}

void build(int o, int ll, int rr) {
int mm = (ll + rr) / 2;
l[o] = ll; r[o] = rr; m[o] = mm;
tmul[o] = 1;
if (ll == mm) {
scanf("%lld", val + o);
val[o] %= p;
} else {
build(lson, ll, mm);
build(rson, mm, rr);
pull(o);
}
}

void add(int o, int ll, int rr, LL x) {
if (ll <= l[o] && r[o] <= rr) {
push_add(o, x);
} else {
push(o);
if (m[o] > ll) add(lson, ll, rr, x);
if (m[o] < rr) add(rson, ll, rr, x);
pull(o);
}
}

void mul(int o, int ll, int rr, LL x) {
if (ll <= l[o] && r[o] <= rr) {
push_mul(o, x);
} else {
push(o);
if (ll < m[o]) mul(lson, ll, rr, x);
if (m[o] < rr) mul(rson, ll, rr, x);
pull(o);
}
}

```

```

0f4a
045e
ac0a
95cf
1b82
9547
0e73
6234
95cf
95cf
427e
471c
0e87
9d27
ac0a
5c92
001f
e5b6
8e2e
7293
5e67
ba26
95cf
95cf
427e
4406
3c16
db32
8e2e
c4b0
4305
d5a6
ba26
95cf
95cf
427e
48cd
3c16
e7d0
8e2e
c4b0
d1ba
67f3
ba26

```

```

95cf     }
95cf     }
427e
0f62     LL query(int o, int ll, int rr) {
3c16         if (ll <= l[o] && r[o] <= rr) {
6dfe             return val[o];
8e2e         } else {
c4b0             push(o);
462a             if (rr <= m[o]) return query(lson, ll, rr);
5cca             if (ll >= m[o]) return query(rson, ll, rr);
bbf9             return query(lson, ll, rr) + query(rson, ll, rr);
95cf         }
95cf     }
4d99 } seg;

```

6.4 Treap

Self-balanced binary search tree which supports split and merge.

Usage:

push(x)	Push lazy tags to children.
pull(x)	Update statistics of node x .
Init(x, v)	Initialize node x with value v .
Add(x, v)	Apply addition to subtree x .
Reverse(x)	Apply reversion to subtree x .
Merge(x, y)	Merge trees rooted at x and y . Return the root of new tree.
Split(t, k, x, y)	Split out the left k elements of tree t . The roots of left part and right part are stored in x and y , respectively.
init(n)	Initialize the treap with array of size n .
work(op, l, r)	Range operation over $[l, r)$.

Time Complexity: Expected $O(\log n)$ per operation.

```

9f60     const int MAXN = 200005;
a7c5     mt19937 gen(time(NULL));
9542     struct Treap {
6d61         int ch[MAXN][2];
3948         int sz[MAXN], key[MAXN], val[MAXN];
5d9a         int add[MAXN], rev[MAXN];
2b1b         LL sum[MAXN] = {0};
a773         int maxv[MAXN] = {INT_MIN}, minv[MAXN] = {INT_MAX};
427e
a629         void Init(int x, int v) {
5a00             ch[x][0] = ch[x][1] = 0;

```

```

        key[x] = gen(); val[x] = v; pull(x);
    }

    void pull(int x) {
        sz[x] = 1 + sz[ch[x][0]] + sz[ch[x][1]];
        sum[x] = val[x] + sum[ch[x][0]] + sum[ch[x][1]];
        maxv[x] = max({val[x], maxv[ch[x][0]], maxv[ch[x][1]]});
        minv[x] = min({val[x], minv[ch[x][0]], minv[ch[x][1]]});
    }

    void Add(int x, int a) {
        val[x] += a; add[x] += a;
        sum[x] += LL(sz[x]) * a; maxv[x] += a; minv[x] += a;
    }

```

```

    void Reverse(int x) {
        rev[x] ^= 1;
        swap(ch[x][0], ch[x][1]);
    }

```

```

    void push(int x) {
        for (int c : ch[x]) if (c) {
            Add(c, add[x]);
            if (rev[x]) Reverse(c);
        }
        add[x] = 0; rev[x] = 0;
    }

```

```

    int Merge(int x, int y) {
        if (!x || !y) return x | y;
        push(x); push(y);
        if (key[x] > key[y]) {
            ch[x][1] = Merge(ch[x][1], y); pull(x); return x;
        } else {
            ch[y][0] = Merge(x, ch[y][0]); pull(y); return y;
        }
    }

```

```

    void Split(int t, int k, int &x, int &y) {
        if (t == 0) { x = y = 0; return; }
        push(t);
        if (sz[ch[t][0]] < k) {
            x = t; Split(ch[t][1], k - sz[ch[t][0]] - 1, ch[t][1], y);
        } else {

```

```

d8cd
95cf
427e
3bf9
e1c3
99f8
94e9
6bb9
95cf
427e
8c8e
a7b1
832a
95cf
427e
aaf6
52c6
7850
95cf
427e
1a53
5fe5
fd76
7a53
95cf
49ee
95cf
427e
9d2c
1b09
cd7e
bfffa
a3df
8e2e
bf9e
95cf
95cf
427e
dc7e
6303
f26b
3465
ffd8
8e2e

```

```

8a23         y = t; Split(ch[t][0], k, x, ch[t][0]);
95cf     }
89e3     if (x) pull(x); if (y) pull(y);
95cf     }
b1f4 } treap;
427e
24b6 int root;
427e
d34f void init(int n) {
34d7     Rep (i, n) {
7681         int x; scanf("%d", &x);
0ed8         treap.Init(i, x);
bcc8         root = (i == 1) ? 1 : treap.Merge(root, i);
95cf     }
95cf }
427e
d030 void work(int op, int l, int r) {
6639     int tl, tm, tr;
b6c4     treap.Split(root, l, tl, tm);
8de3     treap.Split(tm, r - 1, tm, tr);
3658     if (op == 1) {
c039         int x; scanf("%d", &x); treap.Add(tm, x);
1dcb     } else if (op == 2) {
ae78         treap.Reverse(tm);
581d     } else if (op == 3) {
e092         printf("%lld_%d_%d\n",
867f             treap.sum[tm], treap.minv[tm], treap.maxv[tm]);
95cf     }
6188     root = treap.Merge(treap.Merge(tl, tm), tr);
95cf }

```

6.5 Link/cut tree

Dynamic connectivity of undirected acyclic graph. Support single-vertex update, path aggregation and relative LCA query. Vertices are numbered from 1. Zero initialization is enough except for the statistic information.

Usage:

```

pull(x)           Update statistics of node  $x$ .
Root(u)           Get the root of tree where vertex  $u$  is in.
Link(u, v)        Link two unconnected trees.
Cut(u, v)         Cut an existent edge.
Query(u, v)       Path aggregation.
Update(u, x)      Single point modification.
LCA(u, v, root)   Get the lowest common ancestor of  $u$  and  $v$  in tree rooted
                  at root.

```

Time Complexity: $O(\log n)$ per operation

```

const int MAXN = 1000005;
struct LCT {
    int fa[MAXN], ch[MAXN][2], val[MAXN], sum[MAXN];
    bool rev[MAXN];

    bool isroot(int x) { return ch[fa[x]][0] == x || ch[fa[x]][1] == x; }
    void pull(int x) { sum[x] = val[x] ^ sum[ch[x][0]] ^ sum[ch[x][1]]; }
    void reverse(int x) { swap(ch[x][0], ch[x][1]); rev[x] ^= 1; }
    void push(int x) {
        if (rev[x]) rep (i, 2) if (ch[x][i]) reverse(ch[x][i]); rev[x] = 0;
    }
    void rotate(int x) {
        int y = fa[x], z = fa[y], k = ch[y][1] == x, w = ch[x][!k];
        if (isroot(y)) ch[z][ch[z][1] == y] = x;
        ch[x][!k] = y; ch[y][k] = w; if (w) fa[w] = y;
        fa[y] = x; fa[x] = z; pull(y);
    }
    void pushall(int x) { if (isroot(x)) pushall(fa[x]); push(x); }
    void splay(int x) {
        int y = x, z = 0;
        for (pushall(y); isroot(x); rotate(x)) {
            y = fa[x]; z = fa[y];
            if (isroot(y)) rotate((ch[y][0] == x) ^ (ch[z][0] == y) ? x : y);
        }
        pull(x);
    }
    void access(int x) {
        int z = x;
        for (int y = 0; x; x = fa[y = x]) { splay(x); ch[x][1] = y; pull(x); }
        splay(z);
    }
    void chroot(int x) { access(x); reverse(x); }
    void split(int x, int y) { chroot(x); access(y); }
}

```

2e73
ca06
6a6d
c6e1
427e
eba3
f19f
1c4d
1a53
89a0
95cf
425f
51af
e1fe
1e6f
6d09
95cf
52c6
f69c
d095
c494
ceef
4449
95cf
78a0
95cf
6229
1548
8854
7afd
95cf
a067
126d
427e


```

d87a     int Root(int x) {
f4f1         for (access(x); ch[x][0]; x = ch[x][0]) push(x);
0d77         splay(x); return x;
95cf     }
9e46     void Link(int u, int v) { chroot(u); fa[u] = v; }
7c10     void Cut(int u, int v) { split(u, v); fa[u] = ch[v][0] = 0; pull(v); }
0691     int Query(int u, int v) { split(u, v); return sum[v]; }
a999     void Update(int u, int x) { splay(u); val[u] = x; }
1f42     int LCA(int x, int y, int root) {
6cb2         chroot(root); access(x); splay(y);
02e5         while (fa[y]) splay(y = fa[y]);
c218         return y;
95cf     }
329b };

```

6.6 Balanced binary search tree from pb_ds

```

0475 #include <ext/pb_ds/assoc_container.hpp>
332d using namespace __gnu_pbds;
427e
43a7 tree<int, null_type, less<int>, rb_tree_tag, tree_order_statistics_node_update>
    rkt;
427e // null_tree_node_update
427e
427e // SAMPLE USAGE
190e rkt.insert(x);           // insert element
05d4 rkt.erase(x);          // erase element
add5 rkt.order_of_key(x);   // obtain the number of elements less than x
b064 rkt.find_by_order(i);   // iterator to i-th (numbered from 0) smallest element
c103 rkt.lower_bound(x);
4ff4 rkt.upper_bound(x);
b19b rkt.join(rkt2);         // merge tree (only if their ranges do not intersect)
cb47 rkt.split(x, rkt2);     // split all elements greater than x to rkt2

```

6.7 Persistent segment tree, range k-th query

```

f1a7 struct node {
2ff6     static int n, pos;
427e
7cec     int value;
70e2     node *left, *right;

```

```

void* operator new(size_t size);

```

```

static node* Build(int l, int r) {
    node* a = new node;
    if (r > l + 1) {
        int mid = (l + r) / 2;
        a->left = Build(l, mid);
        a->right = Build(mid, r);
    } else {
        a->value = 0;
    }
    return a;
}

```

```

static node* init(int size) {
    n = size;
    pos = 0;
    return Build(0, n);
}

```

```

static int Query(node* lt, node *rt, int l, int r, int k) {
    if (r == l + 1) return l;
    int mid = (l + r) / 2;
    if (rt->left->value - lt->left->value < k) {
        k -= rt->left->value - lt->left->value;
        return Query(lt->right, rt->right, mid, r, k);
    } else {
        return Query(lt->left, rt->left, l, mid, k);
    }
}

```

```

static int query(node* lt, node *rt, int k) {
    return Query(lt, rt, 0, n, k);
}

```

```

node *Inc(int l, int r, int pos) const {
    node* a = new node(*this);
    if (r > l + 1) {
        int mid = (l + r) / 2;
        if (pos < mid)
            a->left = left->Inc(l, mid, pos);
        else
            a->right = right->Inc(mid, r, pos);
    }
}

```

427e
20b0
427e
3dc0
b6c5
ce96
181e
3ba2
8aaf
8e2e
bfc4
95cf
5ffd
95cf
427e
5a45
2c46
7ee3
be52
95cf
427e
93c0
d30c
181e
cb5a
8edb
2412
8e2e
0119
95cf
95cf
427e
c9ad
9e27
95cf
427e
b19c
5794
ce96
181e
203d
f44a
649a
1024

```

95cf    }
2b3e    a->value++;
5ffd    return a;
95cf    }
427e
e80f    node *inc(int index) {
c246        return Inc(0, n, index);
95cf    }
865a    } nodes[8000000];
427e
99ce    int node::n, node::pos;
1987    inline void* node::operator new(size_t size) {
bb3c        return nodes + (pos++);
95cf    }

```

6.8 Block list

All indices are 0-based. All ranges are left-closed right-open.

Usage:

block::fix()	Apply tags to the current block.
Init(l, r)	Range initializer.
Reverse(l, r)	Reverse the range.
Add(l, r, x)	Add x to the range.
Query(l, r)	Range aggregation.

```

fd9e    const int BLOCK = 800;
76b3    typedef vector<int> vi;
427e
a771    struct block {
8fbc        vi data;
e3b5        LL sum; int minv, maxv;
41db        int add; bool rev;
427e
d7eb        block(vi&& vec) : data(move(vec)),
1f0c            sum(accumulate(range(data), 0ll)),
8216            minv(*min_element(range(data))),
527d            maxv(*max_element(range(data))),
6437            add(0), rev(0) { }
427e
b919        void fix() {
0694            if (rev) reverse(range(data));          rev = 0;
0527            if (add) for (int& x : data) x += add;    add = 0;
95cf        }

```

```

427e    void merge(block& another) {
8bc4        fix(); another.fix();
b895        vi temp(move(data));
f516        temp.insert(temp.end(), range(another.data));
d02c        *this = block(move(temp));
88ea    }
95cf
427e    block split(int pos) {
42e8        fix();
3e79        block result(vi(data.begin() + pos, data.end()));
ccab        data.resize(pos); *this = block(move(data));
861a        return result;
56b0    }
95cf
329b    };
427e
2a18    typedef list<block>::iterator lit;
427e
ce14    struct blocklist {
5540        list<block> blk;
427e
7b8e        void maintain() {
3131            lit it = blk.begin();
4628            while (it != blk.end() && next(it) != blk.end()) {
852d                lit it2 = it;
188c                while (next(it2) != blk.end() &&
3600                    it2->data.size() + next(it2)->data.size() <= BLOCK) {
93e1                    it2->merge(*next(it2));
e1fa                    blk.erase(next(it2));
95cf                }
5771                ++it;
95cf            }
95cf        }
427e
b7b3        lit split(int pos) {
2273            for (lit it = blk.begin(); ; it++) {
5502                if (pos == 0) return it;
8e85                while (it->data.size() > pos)
2099                    blk.insert(next(it), it->split(pos));
a5a1                pos -= it->data.size();
427e            }
95cf        }
95cf    }
427e

```

```

1c7b void Init(int *l, int *r) {
9919     for (int *cur = l; cur < r; cur += BLOCK)
8950         blk.emplace_back(vi(cur, min(cur + BLOCK, r)));
95cf }
427e
a22f void Reverse(int l, int r) {
997b     lit it = split(l), it2 = split(r);
dfd0     reverse(it, it2);
8f89     while (it != it2) {
6a06         it->rev ^= 1;
5283         it++;
95cf     }
b204     maintain();
95cf }
427e
3cce void Add(int l, int r, int x) {
997b     lit it = split(l), it2 = split(r);
8f89     while (it != it2) {
e927         it->sum += LL(x) * it->data.size();
03d3         it->minv += x; it->maxv += x;
4511         it->add += x; it++;
95cf     }
b204     maintain();
95cf }
427e
3ad3 void Query(int l, int r) {
997b     lit it = split(l), it2 = split(r);
c33d     LL sum = 0; int minv = INT_MAX, maxv = INT_MIN;
8f89     while (it != it2) {
e472         sum += it->sum;
72c4         minv = min(minv, it->minv);
e1c4         maxv = max(maxv, it->maxv);
5283         it++;
95cf     }
b204     maintain();
8792     printf("%lld_%d_%d\n", sum, minv, maxv);
95cf }
958e } lst;

```

6.9 Persistent block list

Block list that supports persistence. All indices are 0-based. All ranges are left-closed right-open. `std::shared_ptr` is used to ease memory management. One should modify

the constructor of `block` to maintain extra information. Here we use this policy that the size of each block does not exceed `BLOCK`, while the sum of sizes of two adjacent blocks does not less than `BLOCK`.

When some operation that breaks block list property, please call `maintain` in time to restore the property.

Usage:

<code>maintain()</code>	Maintain the block list property.
<code>split(pos)</code>	Split the block list at position <code>pos</code> . Returns an iterator to a block starting at <code>pos</code> .
<code>sum(l, r)</code>	An example function of list traversal between $[l, r)$.

Time Complexity: When `BLOCK` is properly selected, the time complexity is $O(\sqrt{n})$ per operation.

```

constexpr int BLOCK = 800;
typedef vector<int> vi;
typedef shared_ptr<vi> pvi;
typedef shared_ptr<const vi> pcvi;

struct block {
    pcvi data;
    LL sum;

    // add information to maintain
    block(pcvi ptr) :
        data(ptr),
        sum(accumulate(ptr->begin(), ptr->end(), 0ll))
    { }

    void merge(const block& another) {
        pvi temp = make_shared<vi>(data->begin(), data->end());
        temp->insert(temp->end(), another.data->begin(), another.data->end());
        *this = block(temp);
    }

    block split(int pos) {
        block result(make_shared<vi>(data->begin() + pos, data->end()));
        *this = block(make_shared<vi>(data->begin(), data->begin() + pos));
        return result;
    }
};

```

```
typedef list<block>::iterator lit;
```

```

ce14 struct blocklist {
5540     list<block> blk;
427e
7b8e     void maintain() {
3131         lit it = blk.begin();
5e44         while (it != blk.end() and next(it) != blk.end()) {
852d             lit it2 = it;
0b03             while (next(it2) != blk.end() and
029f                 it2->data->size() + next(it2)->data->size() <= BLOCK) {
93e1                 it2->merge(*next(it2));
e1fa                 blk.erase(next(it2));
95cf             }
5771             ++it;
95cf         }
95cf     }
427e
b7b3     lit split(int pos) {
2273         for (lit it = blk.begin(); ; it++) {
5502             if (pos == 0) return it;
d480             while (it->data->size() > pos) {
2099                 blk.insert(next(it), it->split(pos));
95cf             }
a1c8             pos -= it->data->size();
95cf         }
95cf     }
427e
fd38     LL sum(int l, int r) { // traverse
48b4         lit it1 = split(l), it2 = split(r);
ac09         LL res = 0;
9f1d         while (it1 != it2) {
8284             res += it1->sum;
61fd             it1++;
95cf         }
b204         maintain();
244d         return res;
95cf     }
329b };

```

6.10 Sparse table, range minimum query

The array is 0-based and the range is left-closed right-open.

```
db63 const int MAXN = 100007;
```

```

int a[MAXN], st[MAXN][30];

void init(int n){
    int l = log2(n);
    rep (i, n) st[i][0] = a[i];
    rep (j, l) rep (i, 1+n-(1<<j))
        st[i][j+1] = min(st[i][j], st[i+(1<<j)][j]);
}

int rmq(int l, int r){
    int k = log2(r - l);
    return min(st[l][k], st[r-(1<<k)][k]);
}

```

7 Geometrics

7.1 2D geometric template

```

#include <bits/stdc++.h>
using namespace std;

typedef int T;
typedef struct pt {
    T x, y;
    T operator , (pt a) { return x*a.x + y*a.y; } // inner product
    T operator * (pt a) { return x*a.y - y*a.x; } // outer product
    pt operator + (pt a) { return {x+a.x, y+a.y}; }
    pt operator - (pt a) { return {x-a.x, y-a.y}; }

    pt operator * (T k) { return {x*k, y*k}; }
    pt operator - () { return {-x, -y}; }
} vec;

typedef pair<pt, pt> seg;

bool ptOnSeg(pt& p, seg& s){
    vec v1 = s.first - p, v2 = s.second - p;
    return (v1, v2) <= 0 && v1 * v2 == 0;
}

// 0 not on segment

```

```

427e // 1 on segment except vertices
427e // 2 on vertices
8421 int ptOnSeg2(pt& p, seg& s){
ce77     vec v1 = s.first - p, v2 = s.second - p;
70ca     T ip = (v1, v2);
8b14     if (v1 * v2 != 0 || ip > 0) return 0;
0847     return (v1, v2) ? 1 : 2;
95cf }
427e
427e // if two orthogonal rectangles do not touch, return true
72bb inline bool nIntRectRect(seg a, seg b){
f9ac     return min(a.first.x, a.second.x) > max(b.first.x, b.second.x) ||
f486         min(a.first.y, a.second.y) > max(b.first.y, b.second.y) ||
39ce         min(b.first.x, b.second.x) > max(a.first.x, a.second.x) ||
80c7         min(b.first.y, b.second.y) > max(a.first.y, a.second.y);
95cf }
427e
427e // >0 in order
427e // <0 out of order
427e // =0 not standard
7538 inline double rotOrder(vec a, vec b, vec c){return double(a*b)*(b*c);}
427e
31ed inline bool intersect(seg a, seg b){
427e     // ! if (nIntRectRect(a, b)) return false; // if commented, assume that a
        and b are non-collinear
cb52     return rotOrder(b.first-a.first, a.second-a.first, b.second-a.first) >= 0 &&
059e         rotOrder(a.first-b.first, b.second-b.first, a.second-b.first) >= 0;
95cf }
427e
427e // 0 not intersect
427e // 1 standard intersection
427e // 2 vertex-line intersection
427e // 3 vertex-vertex intersection
427e // 4 collinear and have common point(s)
4d19 int intersect2(seg& a, seg& b){
5dc4     if (nIntRectRect(a, b)) return 0;
42c0     vec va = a.second - a.first, vb = b.second - b.first;
2096     double j1 = rotOrder(b.first-a.first, va, b.second-a.first),
72fe         j2 = rotOrder(a.first-b.first, vb, a.second-b.first);
5ac6     if (j1 < 0 || j2 < 0) return 0;
9400     if (j1 != 0 && j2 != 0) return 1;
83db     if (j1 == 0 && j2 == 0){
6b0c         if (va * vb == 0) return 4; else return 3;
fb17     } else return 2;

```

```

}

template <typename Tp = T>
inline pt getIntersection(pt P, vec v, pt Q, vec w){
    static_assert(is_same<Tp, double>::value, "must_be_double!");
    return P + v * (w*(P-Q)/(v*w));
}

// -1 outside the polygon
// 0 on the border of the polygon
// 1 inside the polygon
int ptOnPoly(pt p, pt* poly, int n){
    int wn = 0;
    for (int i = 0; i < n; i++) {

        T k, d1 = poly[i].y - p.y, d2 = poly[(i+1)%n].y - p.y;
        if (k = (poly[(i+1)%n] - poly[i])*(p - poly[i])){
            if (k > 0 && d1 <= 0 && d2 > 0) wn++;
            if (k < 0 && d2 <= 0 && d1 > 0) wn--;
        } else return 0;
    }
    return wn ? 1 : -1;
}

istream& operator >> (istream& lhs, pt& rhs){
    lhs >> rhs.x >> rhs.y;
    return lhs;
}

istream& operator >> (istream& lhs, seg& rhs){
    lhs >> rhs.first >> rhs.second;
    return lhs;
}

```

```

95cf
427e
2c68
5894
6850
7c9a
95cf
427e
427e
427e
427e
cbdd
5fb4
1294
427e
3cae
b957
8c40
3c4d
aad3
95cf
0a5f
95cf
427e
d4a3
fa86
331a
95cf
427e
07ae
5cab
331a
95cf

```

8 Appendices

8.1 Primes

8.1.1 First primes

p	$g(p)$	p	$g(p)$	p	$g(p)$	p	$g(p)$	p	$g(p)$
2	1	3	2	5	2	7	3	11	2
13	2	17	3	19	2	23	5	29	2
31	3	37	2	41	6	43	3	47	5
53	2	59	2	61	2	67	2	71	7
73	5	79	3	83	2	89	3	97	5
101	2	103	5	107	2	109	6	113	3
127	3	131	2	137	3	139	2	149	2
151	6	157	5	163	2	167	5	173	2
179	2	181	2	191	19	193	5	197	2
199	3	211	2	223	3	227	2	229	6

8.1.2 Arbitrary length primes

$\lg p$	p	$g(p)$	p	$g(p)$
3	967	5	1031	14
4	9859	2	10273	10
5	96331	10	102931	3
6	958543	6	1031137	5
7	9594539	2	10169651	2
8	96243449	3	103211039	7
9	980483981	2	1042484357	2
10	9858935453	2	10261276009	7
11	95748666809	3	101759940101	2
12	950781833849	3	1012797784423	5
13	9739822952371	7	10037217092377	7
14	96181051140397	5	104974966380359	11
15	981030138360889	13	1029038416465403	2
16	9655206098080843	3	10116299875820773	2
17	97687777921994419	3	101506415998163437	2

8.1.3 $\sim 1 \times 10^9$

p	$g(p)$	p	$g(p)$	p	$g(p)$
954854573	3	967607731	2	973215833	3
975831713	3	978949117	2	980766497	3
983879921	3	985918807	3	986608921	29
991136977	5	991752599	13	997137961	11
1003911991	3	1009775293	2	1012423549	6
1021000537	5	1023976897	7	1024153643	2
1037027287	3	1038812881	11	1044754639	3
1045125617	3	1047411427	3	1047753349	6

8.1.4 $\sim 1 \times 10^{18}$

p	$g(p)$	p	$g(p)$
951970612352230049	3	963284339889659609	3
967495386904694119	3	969751761517096213	2
983238274281901499	2	984647442475101409	23
989286107138674069	11	1002507954383424641	3
1006658951440146419	2	1020152326159075903	3
1034876265966119449	7	1042753851435034019	2
1043609016597371563	2	1045571042176595707	2
1048364250160580293	2	1049495624119026949	2

8.2 Pell's equation

$x^2 - ny^2 = 1$, where n is a positive nonsquare integer.

Let (x_0, y_0) be the smallest positive solution of the equation, then the k -th solution is:

$$\begin{pmatrix} x_k \\ y_k \end{pmatrix} = \begin{pmatrix} x_0 & ny_0 \\ y_0 & x_0 \end{pmatrix}^k \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

Some smallest solutions to Pell's equation:

n	2	3	5	6	7	8	10	11	12	13	14	15	17	18	19	20
x	3	2	9	5	8	3	19	10	7	649	15	4	33	17	170	9
y	2	1	4	2	3	1	6	3	2	180	4	1	8	4	39	2

8.3 Burnside's lemma and Polya's enumeration theorem

The Burnside's lemma says that

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

where G is a group acting on X , X^g is the set of elements in X that are fixed by g , i.e. $X^g = \{x \in X : gx = x\}$.

The unweighted version of Pólya enumeration theorem says that

$$|Y^X/G| = \frac{1}{|G|} \sum_{g \in G} m^{c_g}$$

where $m = |X|$ is the number of colors, c_g is the number of the cycles of permutation g .

8.4 Lagrange's interpolation

For sample points $(x_0, y_0), \dots, (x_k, y_k)$, define

$$l_j(x) = \prod_{0 \leq m \leq k, m \neq j} \frac{x - x_m}{x_j - x_m}$$

then the Lagrange polynomial is

$$L(x) = \sum_{j=0}^k y_j l_j(x).$$

To use the script below, type two lines

```
x0 x1 x2 ... xn
y0 y1 y2 ... yn
```

the script will print the fractional coefficient of the polynomial in ascending exponent order.

```
#!/usr/bin/python2
from fractions import *

def polymul(a, b) :
    p = [0] * (len(a)+len(b)-1)
    for e1, c1 in enumerate(a) :
        for e2, c2 in enumerate(b) :
            p[e1+e2] += c1*c2
    return p

x, y = [map(Fraction, raw_input().split()) for _ in 0,0]
n = len(x)
lj = [reduce(polymul, [[-x[m]/(x[j]-x[m]), 1/(x[j]-x[m])]
    for m in range(n) if m != j]]) for j in range(n)]
print '\n'.join(map(str, map(sum, zip(*map(
    lambda a, b : [x*a for x in b], y, lj)))))
```

6dc9
4b2b
427e
796b
83e4
f697
156c
dfce
5849
427e
f06d
e80a
a649
9dfa
3cae
7c0d