6T2: Fundamental frequency detection

Xavier Serra

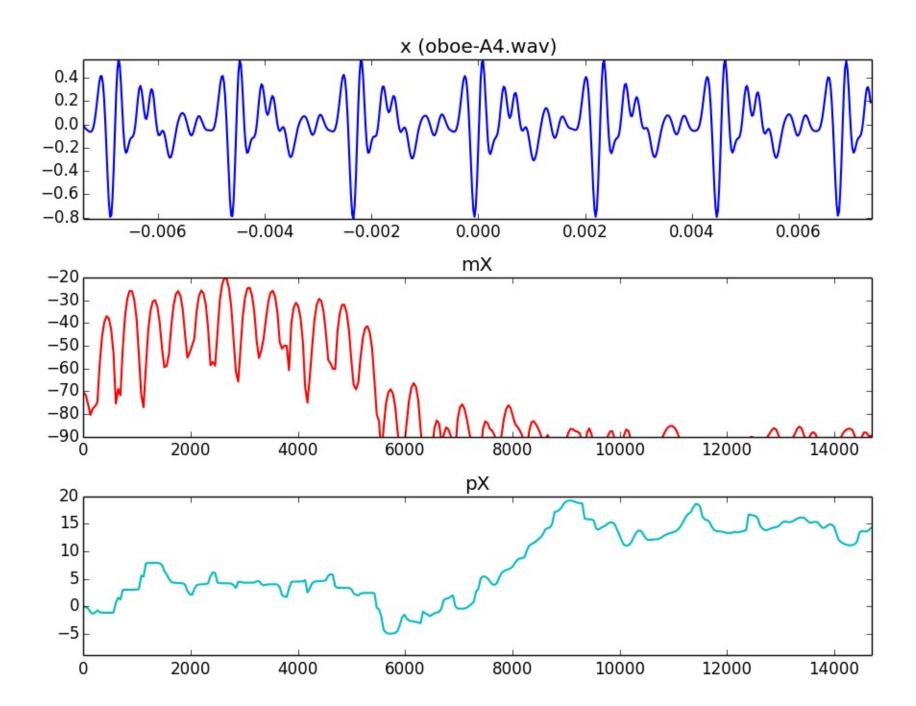
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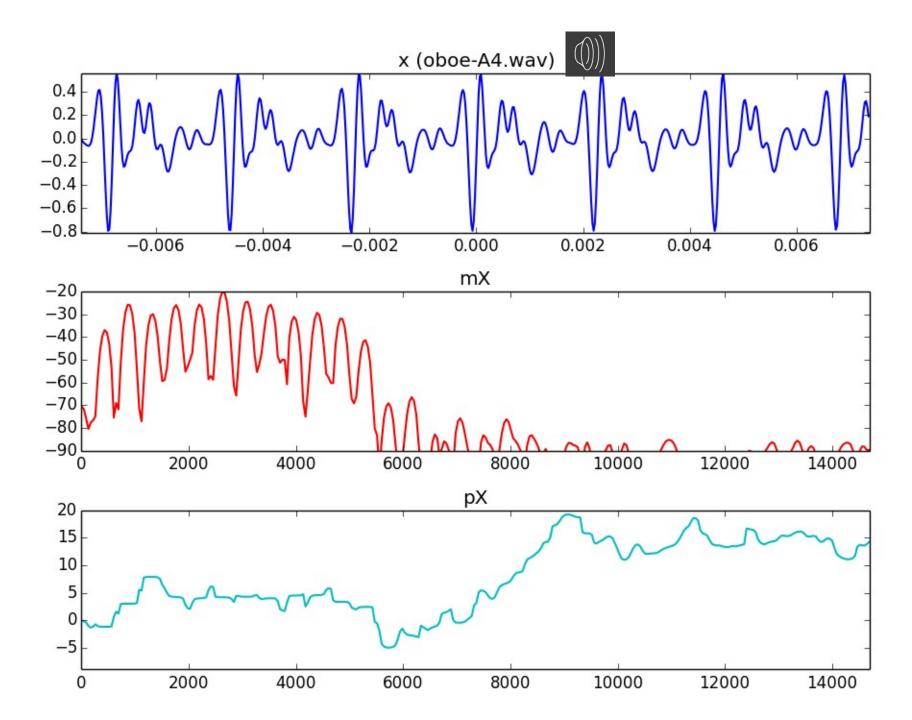
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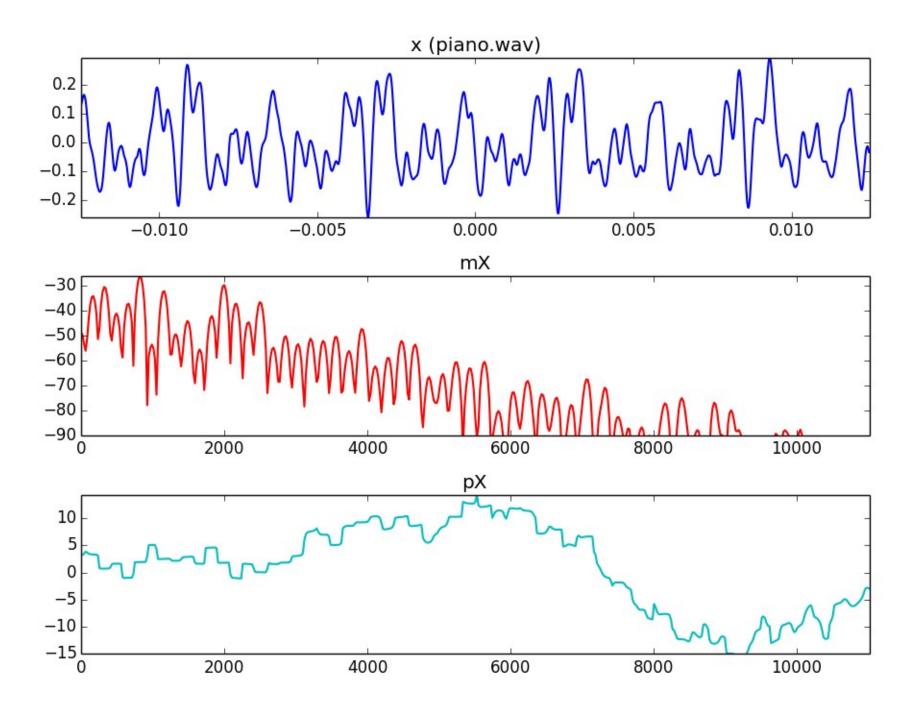
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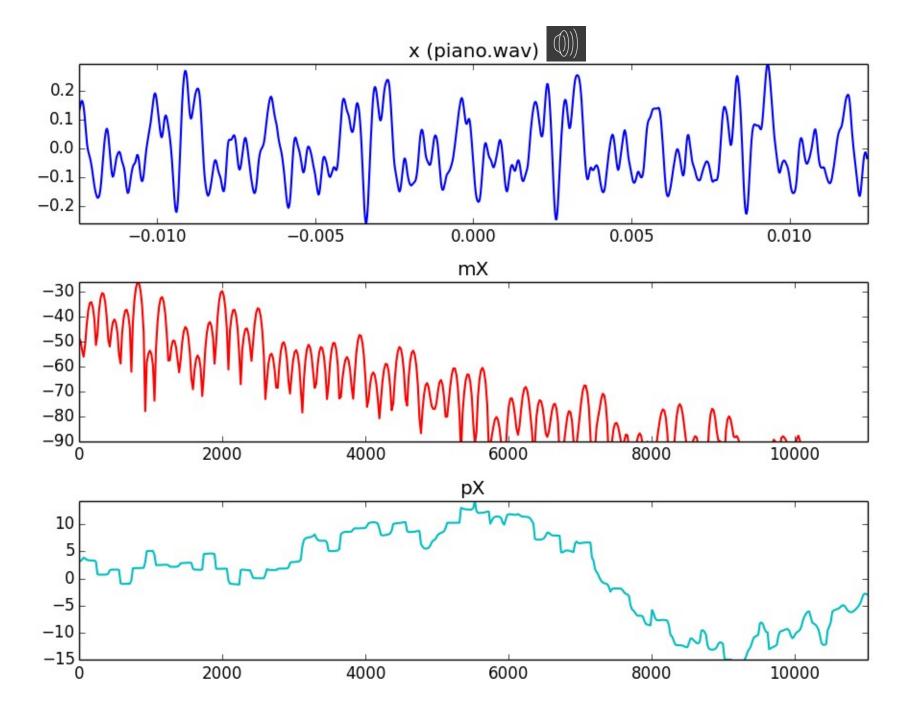
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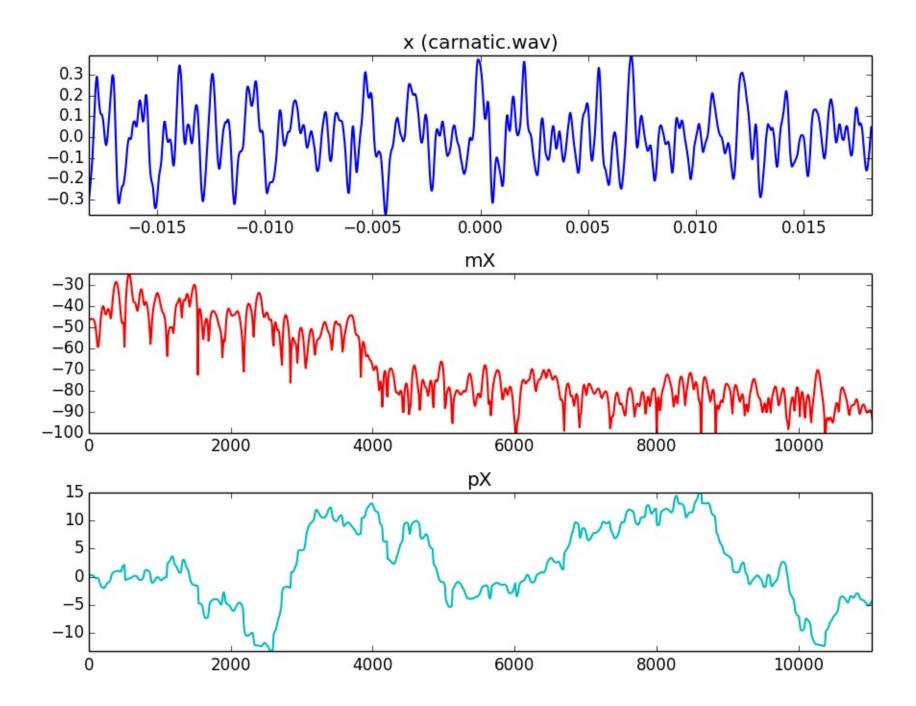
- F0 detection in time domain
 - monophonic signals
- F0 detection in frequency domain
 - monophonic and polyphonic signals

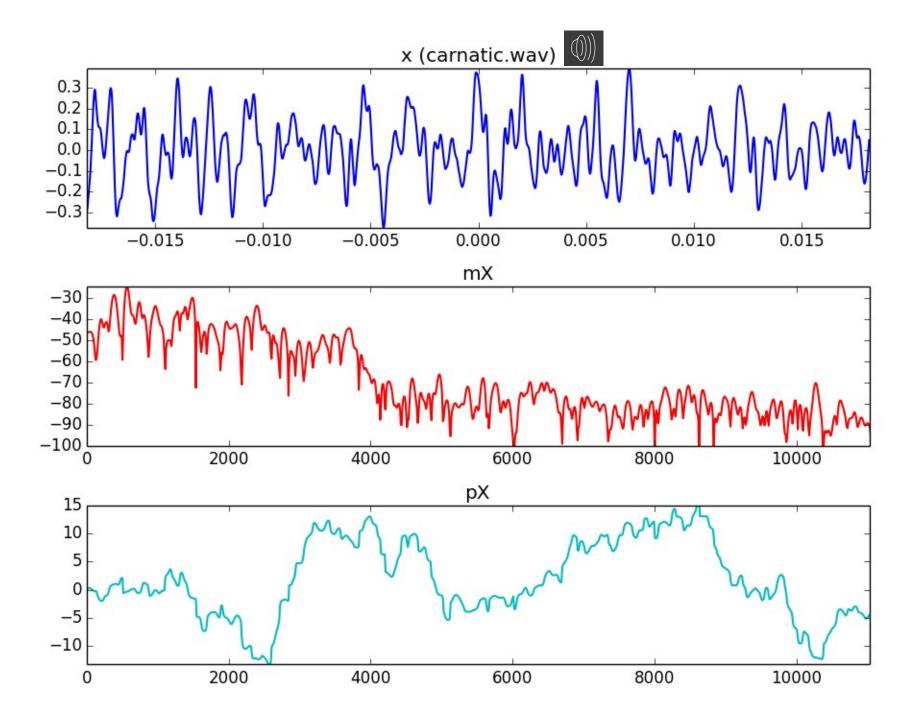










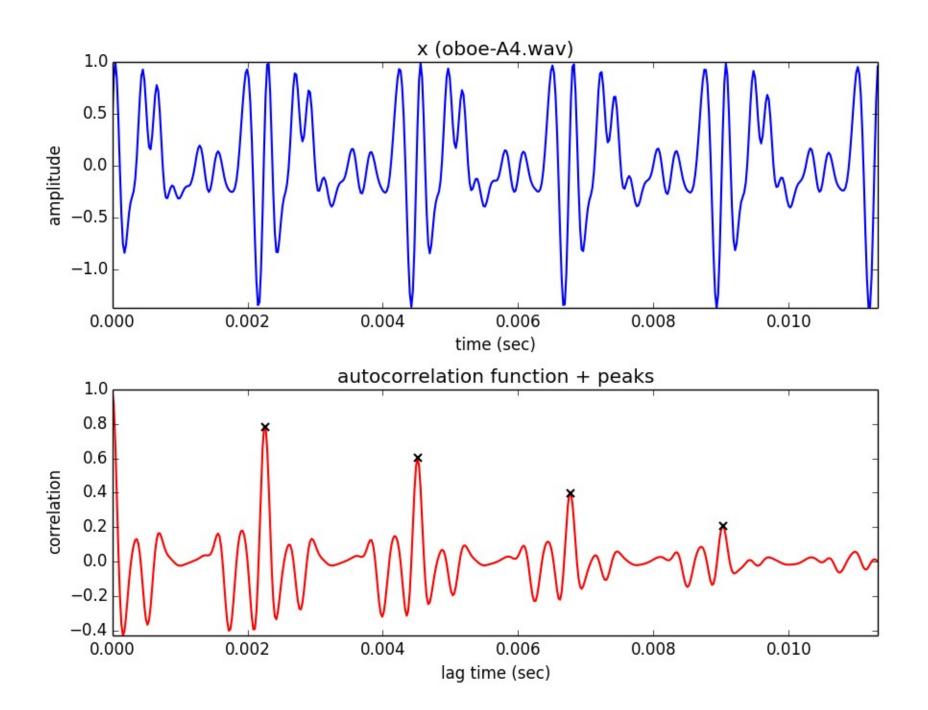


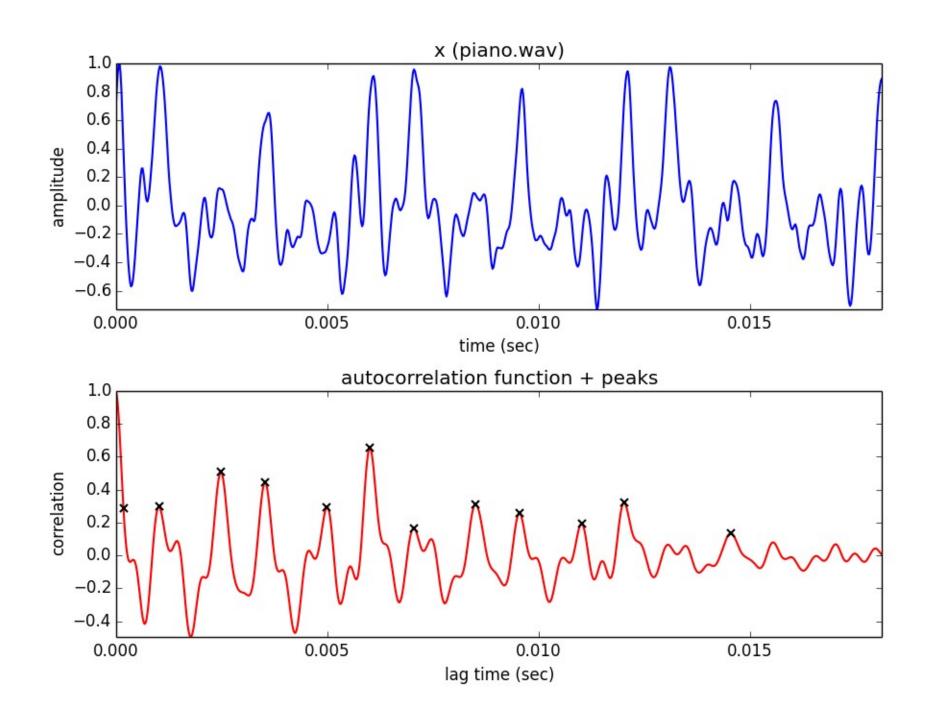
F0 detection in time domain

Autocorrelation function (with tapering)

$$r_x[l] = \sum_{n=0}^{n=N-1-l} x[n]x[n+l]$$
 $l=0,1,...,N-1$

where l = lag



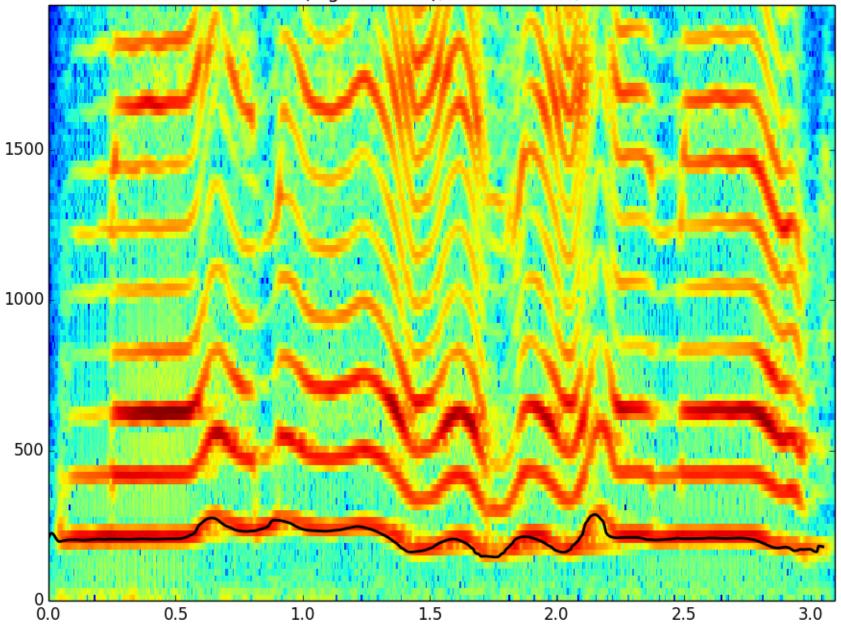


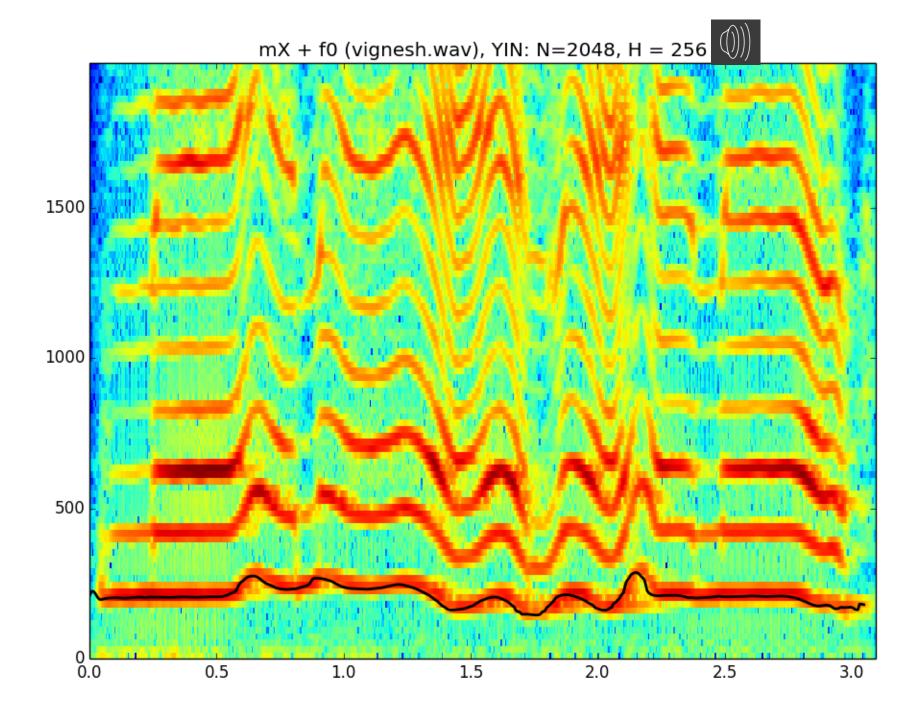
YIN Algorithm (Cheveigné and Kawahara, 2002)

Based on the difference function

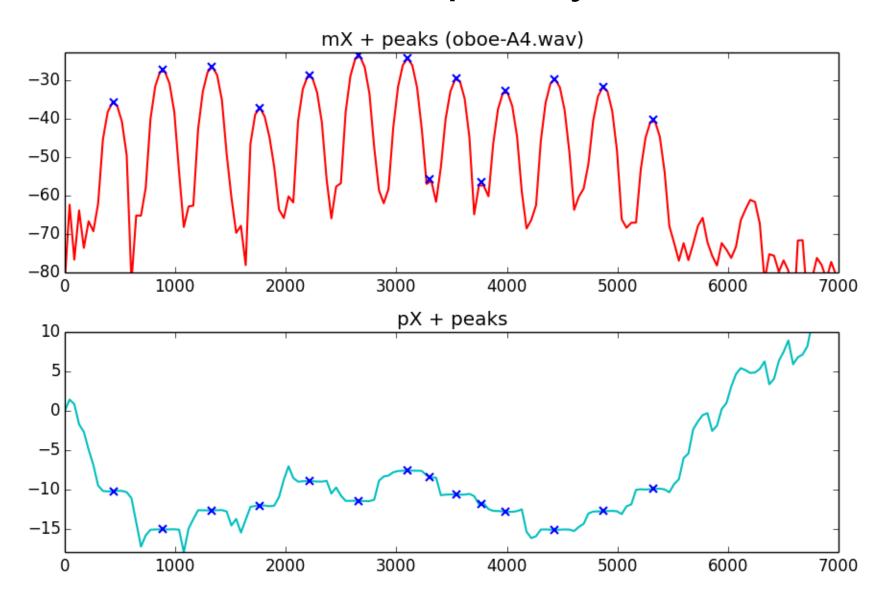
$$d[l] = \sum_{n=0}^{n=N-1-l} (x[n]-x[n+l])^2 \qquad l=0,1,...,N-1$$

mX + f0 (vignesh.wav), YIN: N=2048, H=256



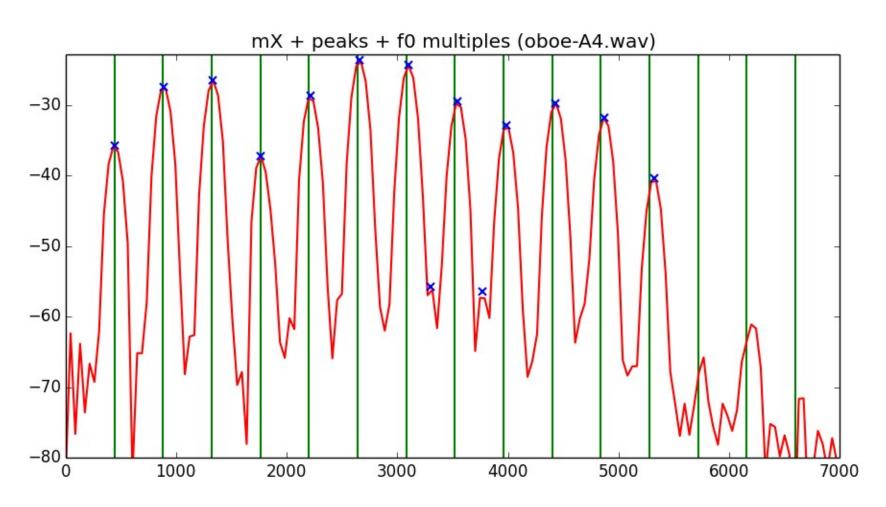


F0 detection in frequency domain



F0 in the spectrum

The F0 can be defined as the common divisor of the harmonic series that best explains the spectral peaks.

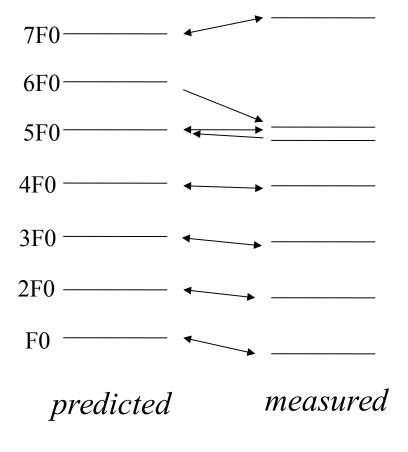


Pattern matching

Two-way mismatch algorithm (Maher and Beauchamp, 1994)

$$\begin{aligned} \operatorname{Err}_{p \to m} &= \sum_{n=1}^{N} E_{\omega}(\Delta f_{n}, f_{n}, a_{n}, A_{\max}) \\ &= \sum_{n=1}^{N} \Delta f_{n} \cdot (f_{n})^{-p} \\ &+ \left(\frac{a_{n}}{A_{\max}}\right) \times \left[q \Delta f_{n} \cdot (f_{n})^{-p} - r\right] \end{aligned}$$

 Δf_n : diff. between predicted and the closest measured peaks f_n , a_n : frequency and magnitude of predicted peaks A_{max} : maximum peak magnitude



$$\begin{aligned} \operatorname{Err}_{m \to p} &= \sum_{k=1}^{K} E_{\omega} (\Delta f_{k}, f_{k}, a_{k}, A_{\max}) \\ &= \sum_{k=1}^{K} \Delta f_{k} \cdot (f_{k})^{-p} + \left(\frac{a_{k}}{A_{\max}}\right) \times \left[q \Delta f_{k} \cdot (f_{k})^{-p} - r\right] \end{aligned}$$

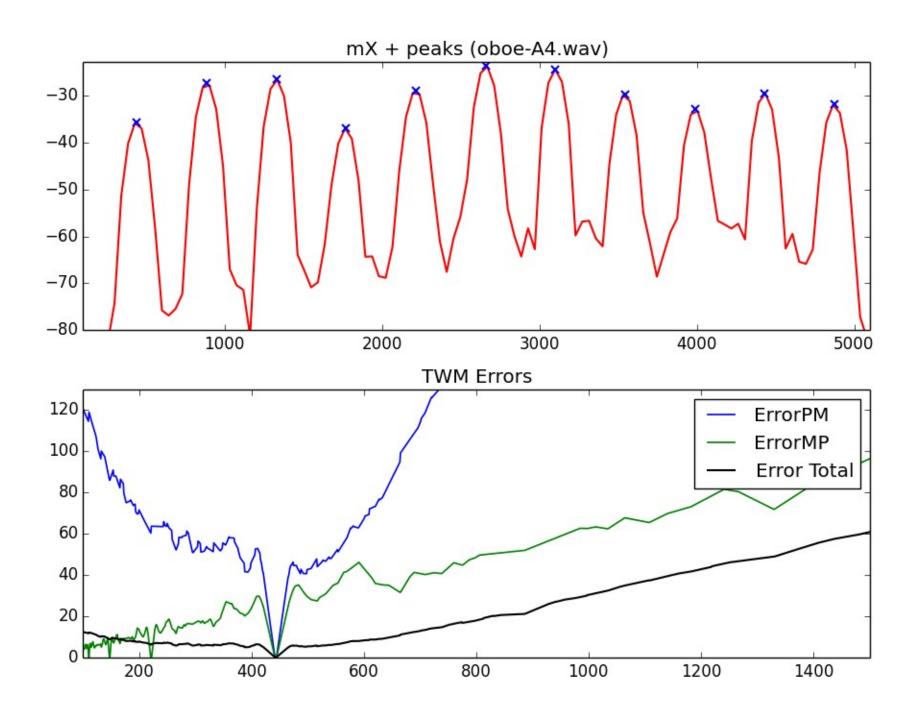
 Δf_k : diff. between predicted and its closest measured peaks f_k , a_k : frequency and magnitude of predicted peaks A_{\max} : maximum peak magnitude

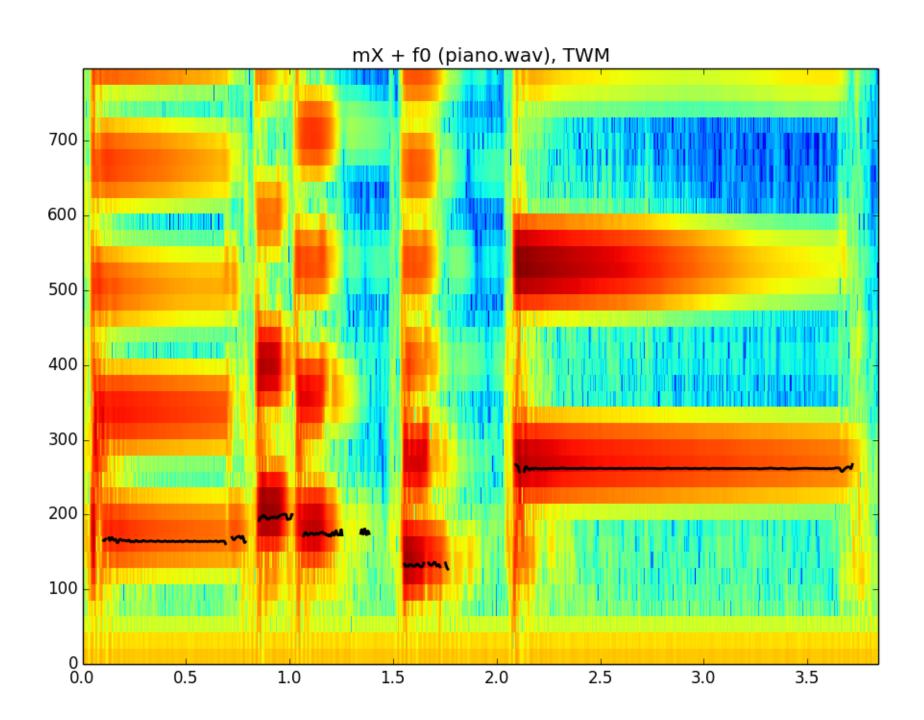
Total error: $\operatorname{Err}_{\text{total}} = \operatorname{Err}_{p \to m} / N + \rho \operatorname{Err}_{m \to p} / K$

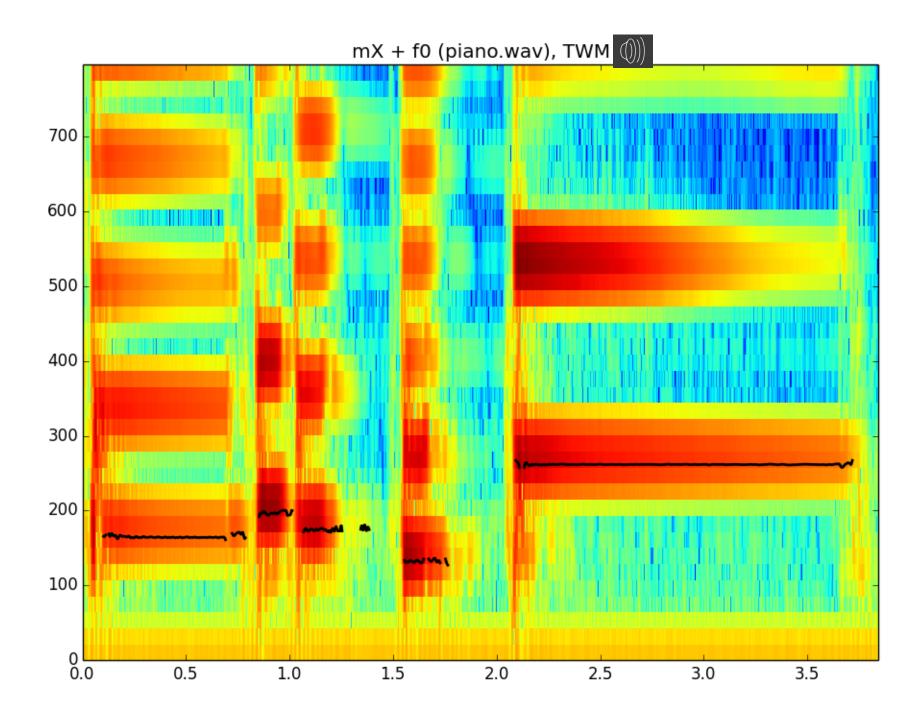
Maher and Beauchamp propose: $p=0.5, q=1.4, r=0.5, \rho=0.33$

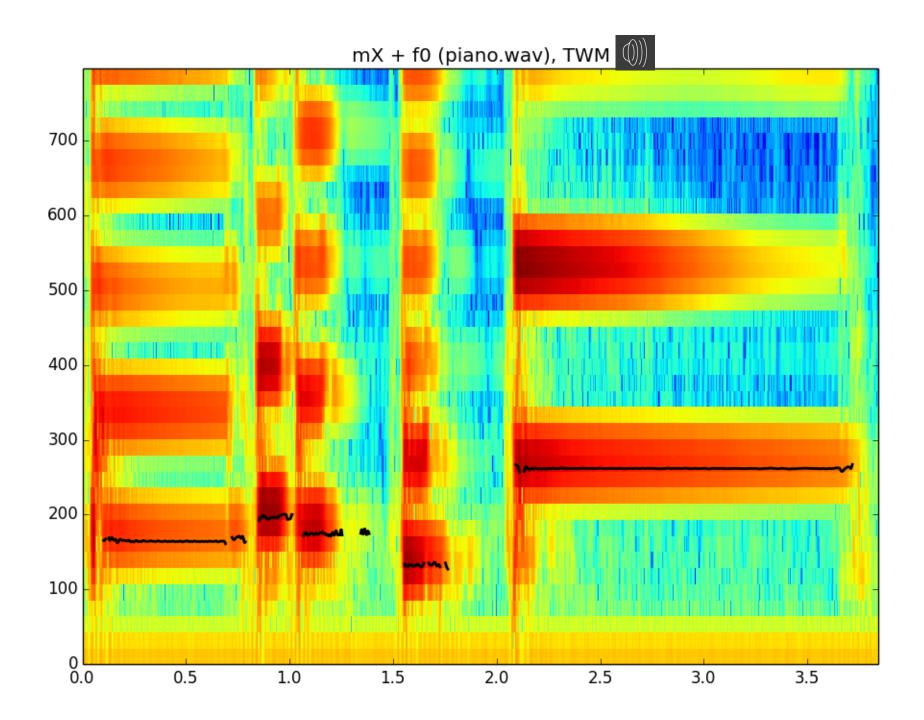
	Err _{p->m}	Err _{m->p}	Err
50Hz	122.58	-3.0	7.49
100Hz	32.0	-3.0	3.83
200Hz	10.0	30.66	4.2

TWM error calculation from the frequencies: 200, 300, 500, 600, 700, 800.

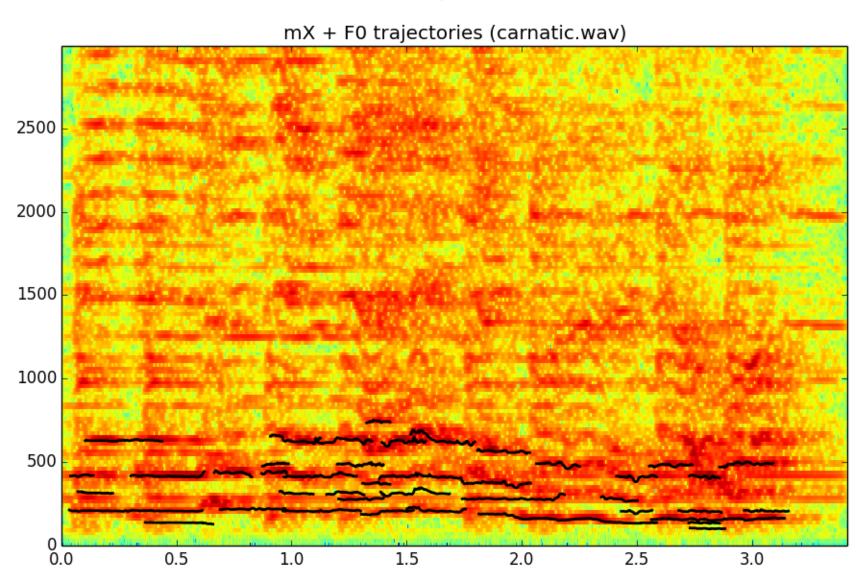




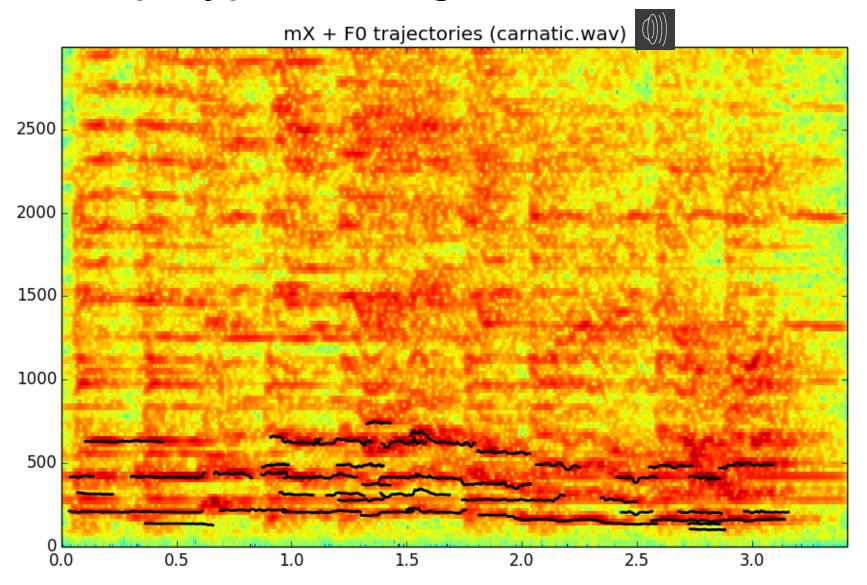




F0 in polyphonic signals

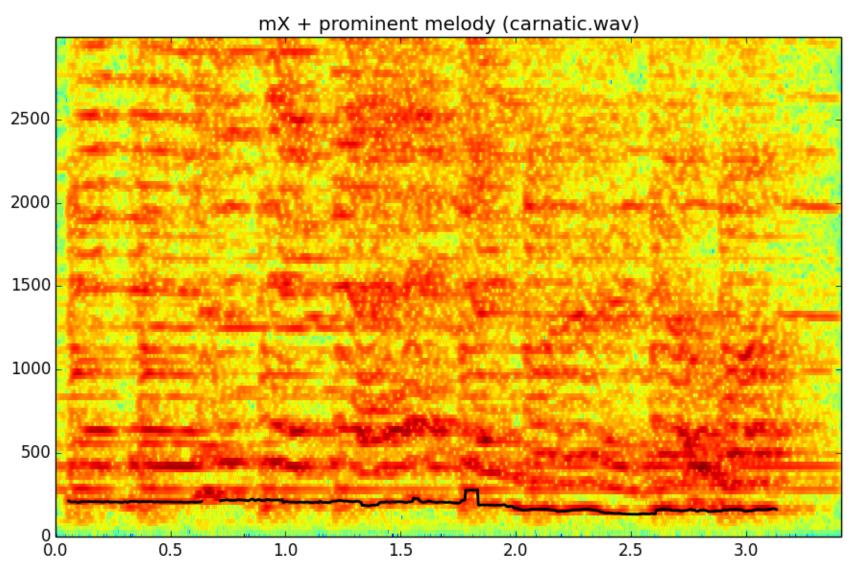


F0 in polyphonic signals



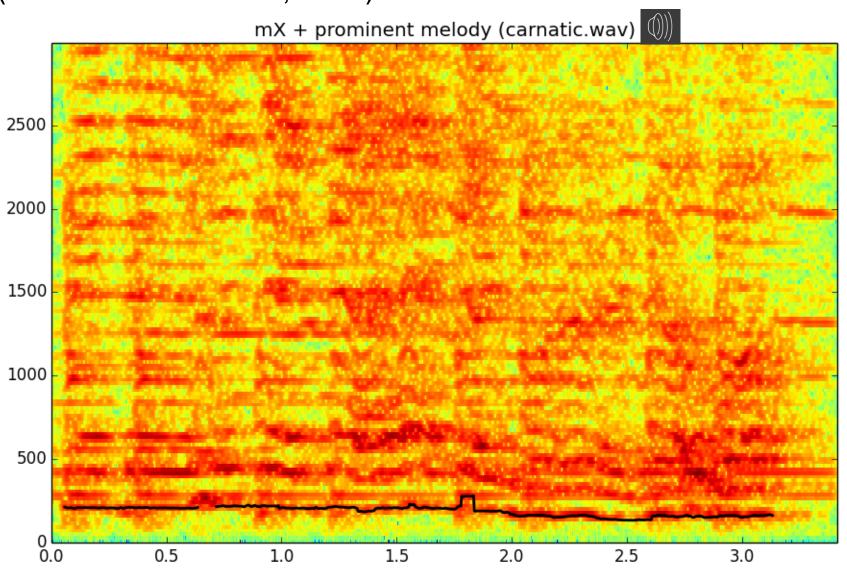
Prominent pitch in polyphonic signals

(Salamon and Gómez, 2012)



Prominent pitch in polyphonic signals

(Salamon and Gómez, 2012)



References and credits

- More information in:
 - http://en.wikipedia.org/wiki/Fundamental_frequency
 - http://en.wikipedia.org/wiki/Pitch_detection_algorithm
 - http://en.wikipedia.org/wiki/Autocorrelation
- F0 detection algorithms:
 - A. de Cheveigné and H. Kawahara. "YIN, a fundamental frequency estimator for speech and music," J. Acoust. Soc. Am. 111, 1917 (2002).
 - R. C. Maher and J. W. Beauchamp, "Fundamental frequency estimation of musical signals using a Two-Way Mismatch procedure," J. Acoust. Soc. Am., vol. 95., no. 4, pp. 2254-2263 (1994).
 - J. Salamon and E. Gómez, "Melody extraction from polyphonic music signals using pitch contour characteristics," IEEE Transactions on Audio, Speech, and Language Processing, vol. 20, no. 6, pp. 1759–1770 (2012).
- Sounds from: http://www.freesound.org/people/xserra/packs/13038/
- Slides and code released using the CC Attribution-Noncommercial-Share Alike license or the Affero GPL license and available from https://github.com/MTG/sms-tools

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