

Classical Mechanics (Phys 601) - October 18, 2011

* Note on notation (and summary of last lecture)

Notation **F&W** different from our notation:

- equilibrium q_i^0 where $\frac{\partial V}{\partial q_i} = 0$ and $q_i = q_i^0 + \eta_i$
- mass matrix $M = \underline{m}$: $M_{ij} = m_{ij} = \sum_k m_k \frac{\partial x_k}{\partial q_i} \bigg|_{q^0} \frac{\partial x_k}{\partial q_j} \bigg|_{q^0}$
- potential matrix $V = \underline{v}$: $V_{ij} = v_{ij} = \frac{\partial^2 V}{\partial q_i \partial q_j} \bigg|_{q^0}$

Generalized eigenvalue problem: $\eta_i = \text{Re } z_i = \text{Re } z_i^0 e^{i\omega t}$

$$(V - \omega^2 M) z = 0 \quad \text{or} \quad (\underline{v} - \omega^2 \underline{m}) p^{(n)} = 0$$

↑ eigenvectors $p^{(n)}$ with eigenvalue ω_n^2

Eigenvalue ω_i^2 with associate eigenvector z_i that describes combination of η_i that oscillate in normal mode

$$\text{Modal matrix } U = [z_1, \dots, z_n] = \underline{A} = [p^{(1)} \dots p^{(n)}]$$

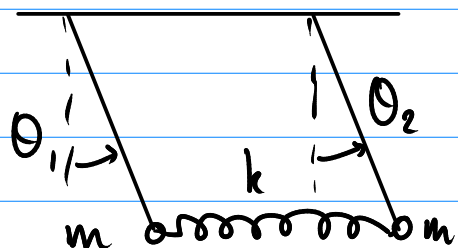
↳ transforms new set of generalized coordinates $\xi = \underline{z}$

$$\eta = U \xi \quad \eta = \underline{A} \xi$$

* Coupled double pendulum

$$L = \frac{1}{2} \dot{\eta}^T M \dot{\eta} - \frac{1}{2} \eta^T V \eta$$

$$M = ml^2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad V = ml^2 \begin{pmatrix} \frac{k}{m} + \frac{g}{l} & -\frac{k}{m} \\ -\frac{k}{m} & \frac{k}{m} + \frac{g}{l} \end{pmatrix}$$



\Rightarrow eigenvalue equation $(V - \omega^2 M)z = 0$

$$\omega^2 = \left(\frac{k}{m} + \frac{g}{l} \right) \pm \left(\frac{k}{m} \right)$$

$$\omega_1 = \sqrt{\frac{g}{l}} \quad \omega_2 = \sqrt{\frac{g}{l} + 2\frac{k}{m}}$$

$$\tilde{z}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \tilde{z}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

z_1 and z_2 are orthogonal, but not normalized yet.

$$z_1^T M z_1 = 2ml^2 \Rightarrow z_1 = \frac{1}{\ell\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

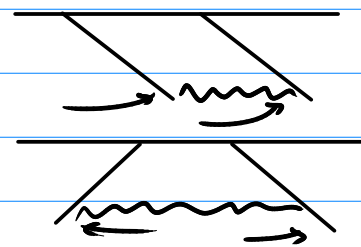
$$z_2^T M z_2 = 2ml^2 \Rightarrow z_2 = \frac{1}{\ell\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$U = A = [z_1, z_2] = \frac{1}{\ell\sqrt{2m}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

General solution is

$$\theta(t) = \begin{pmatrix} \theta_1(t) \\ \theta_2(t) \end{pmatrix} = c_1 z_1 \cos(\omega_1 t + \varphi_1) + c_2 z_2 \cos(\omega_2 t + \varphi_2)$$

$$= \frac{c_1}{\ell\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos(\omega_1 t + \varphi_1) + \frac{c_2}{\ell\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos(\omega_2 t + \varphi_2)$$



Example: initial conditions:

$$\overbrace{\theta_1(0) = \alpha, \theta_2(0) = 0}^{(1)}, \quad \overbrace{\dot{\theta}_1(0) = 0, \dot{\theta}_2(0) = 0}^{(2)}$$

$$(1) \quad \begin{pmatrix} \alpha \\ 0 \end{pmatrix} = \frac{c_1}{l\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos \varphi_1 + \frac{c_2}{l\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos \varphi_2$$

$$(2) \quad \begin{pmatrix} 0 \\ 0 \end{pmatrix} = -\frac{c_1 \omega_1}{l\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \sin \varphi_1 - \frac{c_2 \omega_2}{l\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \sin \varphi_2$$

$$\Rightarrow \varphi_1 = \varphi_2 = 0$$

$$(1) \Rightarrow \frac{c_1}{l\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \frac{c_2}{l\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} \alpha \\ 0 \end{pmatrix} \Rightarrow c_1 = c_2 = \alpha l \sqrt{\frac{m}{2}}$$

$$\Rightarrow \theta(t) = \frac{\alpha}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \cos \omega_1 t + \frac{\alpha}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \cos \omega_2 t$$

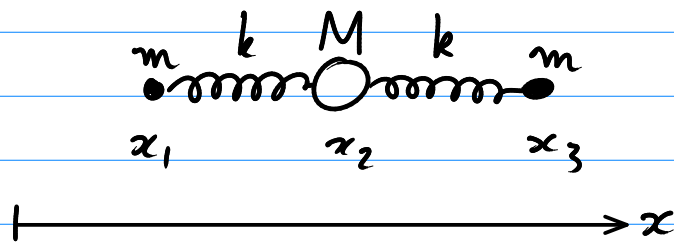
Weak coupling $\rightarrow k$ small $\rightarrow \omega_1 \approx \omega_2$

$$\Rightarrow \theta(t) = \alpha \begin{pmatrix} \cos \frac{\omega_2 - \omega_1}{2} t & \cos \frac{\omega_2 + \omega_1}{2} t \\ \sin \frac{\omega_2 - \omega_1}{2} t & \sin \frac{\omega_2 + \omega_1}{2} t \end{pmatrix}$$

$\begin{matrix} \cos \varepsilon t \\ \sin \varepsilon t \end{matrix} \left. \vphantom{\begin{matrix} \cos \varepsilon t \\ \sin \varepsilon t \end{matrix}} \right\} \text{amplitude modulation}$

For larger coupling: effects are crucial to dynamics of the entire system
 \rightarrow dynamic coupling

* One-dimensional tri-atomic molecule



Springs with equilibrium length

$$T = \frac{1}{2} m (\dot{x}_1^2 + \dot{x}_3^2) + \frac{1}{2} M \dot{x}_2^2$$

$$V = \frac{1}{2} k (x_1 - x_2 - L)^2 + \frac{1}{2} k (x_3 - x_2 - L)^2$$

$$\Rightarrow \text{equilibrium for } \begin{cases} x_2 = R & \text{center of mass position} \\ x_1 = R - L & \text{(assumed constant)} \\ x_3 = R + L \end{cases}$$

$$\downarrow \\ R(t) = R_0 + v_{cm}(t - t_0) \\ \text{in general case}$$

$$\Rightarrow \begin{cases} \eta_1 = x_1 - (R - L) \\ \eta_2 = x_2 - R \\ \eta_3 = x_3 - (R + L) \end{cases}$$

$$\Rightarrow T = \frac{1}{2} m (\dot{\eta}_1^2 + \dot{\eta}_3^2) + \frac{1}{2} M \dot{\eta}_2^2 = \frac{1}{2} (\dot{\eta}_1, \dot{\eta}_2, \dot{\eta}_3) M \begin{pmatrix} \dot{\eta}_1 \\ \dot{\eta}_2 \\ \dot{\eta}_3 \end{pmatrix}$$

$$V = \frac{1}{2} k (\eta_1 - \eta_2)^2 + \frac{1}{2} k (\eta_3 - \eta_2)^2 = \frac{1}{2} (\eta_1, \eta_2, \eta_3) V \begin{pmatrix} \eta_1 \\ \eta_2 \\ \eta_3 \end{pmatrix}$$

$$M = \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \quad V = \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix}$$

$$\Rightarrow (V - \omega^2 M) z = 0 \quad \text{eigenvalue problem}$$

$$\Rightarrow \det(V - \omega^2 M) = 0$$

$$\begin{vmatrix} k - \omega^2 m & -k & 0 \\ -k & 2k - \omega^2 M & -k \\ 0 & -k & k - \omega^2 m \end{vmatrix} = 0$$

$$\Leftrightarrow (k - \omega^2 m)(2k - \omega^2 M)(k - \omega^2 m) - 2k^2(k - \omega^2 m) = 0$$

$$\Leftrightarrow (k - \omega^2 m)(-k\omega^2 M - 2k\omega^2 m + \omega^4 M m) = 0$$

$$\Leftrightarrow \omega^2(k - \omega^2 m)(\omega^2 M m - k(2m + M)) = 0$$

$$\rightarrow \omega_1^2 = 0, \quad \omega_2^2 = \frac{k}{m}, \quad \omega_3^2 = \frac{k}{m} \left(1 + 2 \frac{m}{M}\right)$$

Zero frequency? What does that mean?

$$\ddot{\xi}_i + \omega_i^2 \xi_i = 0 \Rightarrow \ddot{\xi}_i = 0 \Rightarrow \xi_i = v_i t + \xi_{i0}$$

Eigenvectors and normal coordinates:

$$\omega_1: \begin{pmatrix} k & -k & 0 \\ -k & 2k & -k \\ 0 & -k & k \end{pmatrix} z_1 = 0 \Rightarrow z_1 = \frac{1}{\sqrt{N}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$z_1^T M z_1 = \frac{2m + M}{N} = 1 \Leftrightarrow N = 2m + M$$

$$\Rightarrow z_1 = \frac{1}{\sqrt{2m + M}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow \text{collective motion of all three masses}$$

$$\omega_2: \begin{pmatrix} 0 & -k & 0 \\ -k & k(2 - \frac{M}{m}) & -k \\ 0 & -k & 0 \end{pmatrix} z_2 = 0 \Rightarrow z_2 = \frac{1}{\sqrt{N}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

$$z_2^T M z_2 = \frac{2m}{N} = 1 \Leftrightarrow N = 2m$$

$$\Rightarrow z_2 = \frac{1}{\sqrt{2m}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \Rightarrow \text{outer masses oscillating in counterphase}$$

$$w_3: \begin{pmatrix} -2 \frac{m}{M} k & -k & 0 \\ -k & -k \frac{M}{m} & -k \\ 0 & -k \frac{m}{M} & -2 \frac{m}{M} k \end{pmatrix} z_3 = 0 \Rightarrow z_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -2 \frac{m}{M} \\ 1 \end{pmatrix}$$

$$z_3^T M z_3 = \frac{2m + 4 \frac{m^2}{M}}{N} \Leftrightarrow N = 2 \left(1 + 2 \frac{m}{M} \right) m$$

$$\Rightarrow z_3 = \frac{1}{\sqrt{2m(1+2\frac{m}{M})}} \begin{pmatrix} 1 \\ -2\frac{m}{M} \\ 1 \end{pmatrix}$$

Assume now $m = M$:


sume now $m = |M|$:


$$\Rightarrow U = [z_1 \ z_2 \ z_3] = \frac{1}{\sqrt{6m}} \begin{bmatrix} \sqrt{2} & \sqrt{3} & 1 \\ \sqrt{2} & 0 & -2 \\ \sqrt{2} & -\sqrt{3} & 1 \end{bmatrix}, \quad \eta = U \xi$$


Orthonormality: $U^T M U = \underset{m \text{ "}}{\mathbb{I}} = \mathbb{I}$

$$\Rightarrow m U^T U = 1$$
$$\Rightarrow U^{-1} = m U^T = \sqrt{\frac{m}{6}} \begin{bmatrix} \sqrt{2} & \sqrt{2} & \sqrt{2} \\ \sqrt{3} & 0 & -\sqrt{3} \\ 1 & -2 & 1 \end{bmatrix}$$

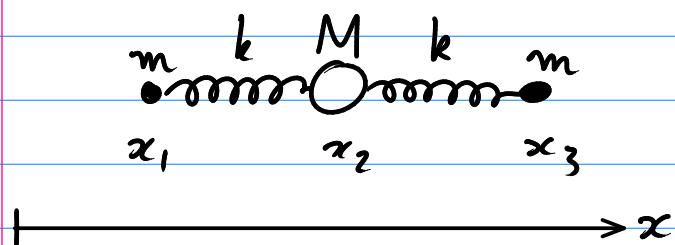
$$\eta = U \xi \Rightarrow \xi = m U^T \eta :$$

ξ_1 :  $\xi_1 = \sqrt{\frac{m}{3}} (\eta_1 + \eta_2 + \eta_3)$

ξ_2 :  $\xi_2 = \sqrt{\frac{m}{2}} (\eta_1 - \eta_3)$

ζ_3 :  $\zeta_3 = \sqrt{\frac{m}{6}} (\eta_1, -2\eta_2, \eta_3)$

* One-dimensional tri-atomic molecule



In center of mass system

$$m x_1 + M x_2 + m x_3 = (2m + M) R$$

$$\downarrow$$

$$x_2 = -\frac{m}{M} (x_1 + x_3)$$

$$T = \frac{1}{2} m (\dot{\eta}_1^2 + \dot{\eta}_3^2) + \frac{1}{2} M \dot{\eta}_2^2$$

eliminate center of mass motion

$$\underbrace{\frac{1}{2} \frac{m^2}{M} (\dot{\eta}_1 + \dot{\eta}_3)^2}$$

$$T = \frac{1}{2} m \left(1 + \frac{m}{M}\right) \dot{\eta}_1^2 + \frac{1}{2} m \left(1 + \frac{m}{M}\right) \dot{\eta}_3^2 + \frac{m^2}{M} \dot{\eta}_1 \dot{\eta}_3$$

$$= \frac{1}{2} (\dot{\eta}_1, \dot{\eta}_3) M \begin{pmatrix} \dot{\eta}_1 \\ \dot{\eta}_3 \end{pmatrix}$$

$$V = \frac{1}{2} k (\eta_1 - \eta_2)^2 + \frac{1}{2} k (\eta_3 - \eta_2)^2$$

$$= \frac{1}{2} k \left[\eta_1 + \frac{m}{M} (\eta_1 + \eta_3) \right]^2 + \frac{1}{2} k \left[\eta_3 + \frac{m}{M} (\eta_1 + \eta_3) \right]^2$$

$$= \frac{1}{2} k \left[\eta_1^2 \left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} \eta_3^2 + 2 \left(1 + \frac{m}{M}\right) \frac{m}{M} \eta_1 \eta_3 \right. \\ \left. + \eta_3^2 \left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} \eta_1^2 + 2 \left(1 + \frac{m}{M}\right) \frac{m}{M} \eta_1 \eta_3 \right]$$

$$= \frac{1}{2} k \left[\eta_1^2 \left(\left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} \right) + \eta_3^2 \left(\left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} \right) \right. \\ \left. + 4 \frac{m}{M} \left(1 + \frac{m}{M}\right) \eta_1 \eta_3 \right]$$

$$= \frac{1}{2} (\eta_1, \eta_3) V \begin{pmatrix} \eta_1 \\ \eta_3 \end{pmatrix} \rightarrow \text{only 2 variables}$$

$$M = m \begin{pmatrix} \left(1 + \frac{m}{M}\right) & \frac{m}{M} \\ \frac{m}{M} & \left(1 + \frac{m}{M}\right) \end{pmatrix}$$

$$V = k \begin{pmatrix} \left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} & 2 \frac{m}{M} \left(1 + \frac{m}{M}\right) \\ 2 \frac{m}{M} \left(1 + \frac{m}{M}\right) & \left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} \end{pmatrix}$$

Because $M = \begin{pmatrix} m_1 & m_2 \\ m_2 & m_1 \end{pmatrix}$ and $V = \begin{pmatrix} v_1 & v_2 \\ v_2 & v_1 \end{pmatrix}$

M and V commute: $MV = VM$

If $\exists U$: $\begin{cases} U^T M U = \text{diagonal with eigenvalues} = \Lambda_M \\ U^T V U = \text{diagonal with eigenvalues} = \Lambda_V \end{cases}$
with $U^T U = \mathbb{I}$ orthonormal

$$\hookrightarrow \Lambda_M \Lambda_V = U^T M U U^T V U = U^T M V U \\ = U^T V M U = U^T V U U^T M U = \Lambda_V \Lambda_M$$

Diagonalize M : $\begin{vmatrix} m\left(1 + \frac{m}{M}\right) - \lambda & \frac{m^2}{M} \\ \frac{m^2}{M} & m\left(1 + \frac{m}{M}\right) - \lambda \end{vmatrix} = 0$

$$\Leftrightarrow \begin{vmatrix} m - \lambda & \lambda - m \\ \frac{m^2}{M} & m\left(1 + \frac{m}{M}\right) - \lambda \end{vmatrix} = 0$$

$$\Leftrightarrow (\lambda - m) \begin{vmatrix} -1 & 1 \\ \frac{m^2}{M} & m\left(1 + \frac{m}{M}\right) - \lambda \end{vmatrix} = 0$$

$$\Leftrightarrow \lambda = m \text{ or } \lambda = m\left(1 + \frac{m}{M}\right) + \frac{m^2}{M} = m + 2 \frac{m^2}{M}$$

$$\Rightarrow \Lambda_M = \begin{pmatrix} m & 0 \\ 0 & m + 2\frac{m^2}{M} \end{pmatrix}, z_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}, z_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}, U^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\hookrightarrow V \text{ diagonalizes to } \Lambda_V = U^T V U$$

$$= \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} v_1 & v_2 \\ v_2 & v_1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} v_1 - v_2 & v_1 + v_2 \\ v_2 - v_1 & v_1 + v_2 \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 2(v_1 - v_2) & 0 \\ 0 & 2(v_1 + v_2) \end{pmatrix} = \begin{pmatrix} v_1 - v_2 & 0 \\ 0 & v_1 + v_2 \end{pmatrix}$$

$$\text{Also transform } \eta = U \xi = U \begin{pmatrix} \xi_1 \\ \xi_3 \end{pmatrix}, \xi = U^T \eta$$

$$\Rightarrow L = \frac{1}{2} \dot{\xi}^T U^T M U \dot{\xi} - \frac{1}{2} \xi^T U^T V U \xi$$

$$= \frac{1}{2} \dot{\xi}^T \Lambda_M \dot{\xi} - \frac{1}{2} \xi^T \Lambda_V \xi$$

$\Rightarrow \xi_1$ and ξ_3 are decoupled \rightarrow normal coordinates

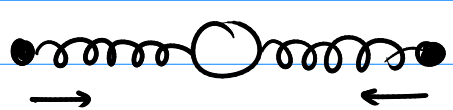
$$\xi_1 \text{ has frequency } \frac{v_1 - v_2}{m} = \frac{k}{m} \left[\left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} - 2\frac{m}{M} \left(1 + \frac{m}{M}\right) \right] = \frac{k}{m}$$


$$\xi_3 \text{ has frequency } \frac{v_1 + v_2}{m + 2\frac{m^2}{M}} = \frac{k}{m + 2\frac{m^2}{M}} \left[\left(1 + \frac{m}{M}\right)^2 + \frac{m^2}{M^2} + 2\frac{m}{M} \left(1 + \frac{m}{M}\right) \right]$$

$$\Rightarrow \omega_3 = \frac{k}{m} \frac{1}{1 + 2 \frac{m}{M}} \left(1 + 4 \frac{m}{M} + 4 \frac{m^2}{M^2} \right) = \frac{k}{m} \frac{\left(1 + 2 \frac{m}{M} \right)^2}{1 + 2 \frac{m}{M}}$$

$$= \frac{k}{m} \left(1 + 2 \frac{m}{M} \right)$$

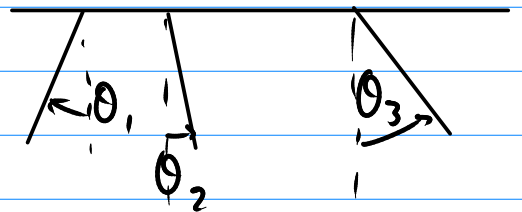
Normal modes are now just


 $\omega_1, z_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \xi_1 = \frac{1}{\sqrt{2}} (\eta_1 - \eta_3)$


 $\omega_3, z_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \xi_3 = \frac{1}{\sqrt{2}} (\eta_1 + \eta_3)$

* Degenerate eigenvalues and Gram-Schmidt procedure

Three coupled pendulums:



$$T = \frac{1}{2} (\dot{\theta}_1^2 + \dot{\theta}_2^2 + \dot{\theta}_3^2)$$

$$V = \frac{1}{2} (\theta_1^2 + \theta_2^2 + \theta_3^2) - 2\varepsilon \theta_1 \theta_2 - 2\varepsilon \theta_2 \theta_3 - 2\varepsilon \theta_1 \theta_3$$

$$\Rightarrow M = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix} \quad V = \begin{pmatrix} 1 & -\varepsilon & -\varepsilon \\ -\varepsilon & 1 & -\varepsilon \\ -\varepsilon & -\varepsilon & 1 \end{pmatrix}$$

Eigenvalues:

$$\det(V - \omega^2 M) = \begin{vmatrix} 1 - \omega^2 & -\varepsilon & -\varepsilon \\ -\varepsilon & 1 - \omega^2 & -\varepsilon \\ -\varepsilon & -\varepsilon & 1 - \omega^2 \end{vmatrix} = 0$$

Simplify first:

$$\begin{vmatrix} 1-\omega^2 & -\varepsilon & -\varepsilon \\ 0 & 1-\omega^2+\varepsilon & -\varepsilon-1+\omega^2 \\ -\varepsilon & -\varepsilon & 1-\omega^2 \end{vmatrix} = 0$$

row 2 = 2 - 3

$$\Leftrightarrow (1+\varepsilon-\omega^2) \begin{vmatrix} 1-\omega^2 & -\varepsilon & -\varepsilon \\ 0 & 1 & -1 \\ -\varepsilon & -\varepsilon & 1-\omega^2 \end{vmatrix} = 0$$

$$\Leftrightarrow (1+\varepsilon-\omega^2) \begin{vmatrix} 1-\omega^2 & -2\varepsilon & -\varepsilon \\ 0 & 0 & \textcircled{-1} \\ -\varepsilon & -\varepsilon+1-\omega^2 & 1-\omega^2 \end{vmatrix} = 0$$

column 3 = 2 + 3

$$\Leftrightarrow (1+\varepsilon-\omega^2) \begin{vmatrix} 1-\omega^2 & -2\varepsilon \\ -\varepsilon & 1-\varepsilon-\omega^2 \end{vmatrix} = 0$$

$$\Leftrightarrow (1+\varepsilon-\omega^2) \begin{vmatrix} 1-2\varepsilon-\omega^2 & -2\varepsilon \\ 1-2\varepsilon-\omega^2 & 1-\varepsilon-\omega^2 \end{vmatrix} = 0$$

column 1 = 1 + 2

$$\Leftrightarrow (1+\varepsilon-\omega^2)(1-2\varepsilon-\omega^2) \begin{vmatrix} 1 & -2\varepsilon \\ 1 & 1-\varepsilon-\omega^2 \end{vmatrix} = 0$$

$$\Leftrightarrow (1+\varepsilon-\omega^2)(1-2\varepsilon-\omega^2)(1+\varepsilon-\omega^2) = 0$$

$$\hookrightarrow \begin{matrix} \omega_1^2 = \omega_2^2 = 1+\varepsilon \\ \omega_3^2 = 1-2\varepsilon \end{matrix} \rightarrow \text{degeneracy!}$$

Eigenvectors:

$$z_3: \begin{pmatrix} 2\varepsilon & -\varepsilon & -\varepsilon \\ -\varepsilon & 2\varepsilon & -\varepsilon \\ -\varepsilon & -\varepsilon & 2\varepsilon \end{pmatrix} z_3 = 0 \quad \Rightarrow \quad z_3 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$z_1, z_2 : \begin{pmatrix} -\varepsilon & -\varepsilon & -\varepsilon \\ -\varepsilon & -\varepsilon & -\varepsilon \\ -\varepsilon & -\varepsilon & -\varepsilon \end{pmatrix} z_1 = 0 \Rightarrow \tilde{z}_1 = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}$$

$$\tilde{z}_2 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$$

Gram-Schmidt procedure :

- set of linear independent eigenvectors $\{\tilde{z}_1, \tilde{z}_2\}$
- normalize first eigenvector: $\tilde{z}_1^T M \tilde{z}_1 = 6$

$$z_1 = \frac{1}{\sqrt{6}} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}$$

- subtract projection of \tilde{z}_2 on z_1 :

$$\tilde{z}_2 - \underbrace{(z_1^T M \tilde{z}_2)}_{\frac{3}{\sqrt{6}}} z_1 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{3}{2} \\ \frac{3}{2} \end{pmatrix}$$

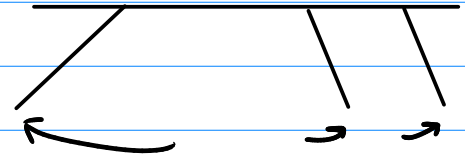
- normalize second eigenvector: $\tilde{z}_2^T M \tilde{z}_2 = 2 \left(\frac{3}{2}\right)^2$

$$z_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

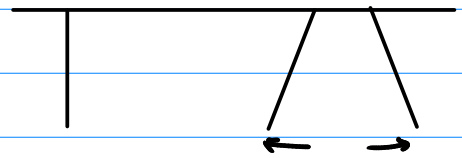
$$\Rightarrow \text{modal matrix } U = \frac{1}{\sqrt{6}} \begin{pmatrix} 2 & 0 & \sqrt{2} \\ -1 & \sqrt{3} & \sqrt{2} \\ -1 & -\sqrt{3} & \sqrt{2} \end{pmatrix}$$

$$\text{with } \xi = U^T \theta \text{ or } \theta = U \xi$$

$$\Rightarrow \xi_1 = \frac{1}{\sqrt{6}} (2\theta_1 - \theta_2 - \theta_3)$$



$$\xi_2 = \frac{1}{\sqrt{2}} (\theta_2 - \theta_3)$$



$$\xi_3 = \frac{1}{\sqrt{3}} (\theta_1 + \theta_2 + \theta_3)$$

