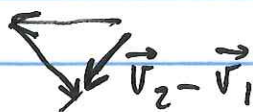
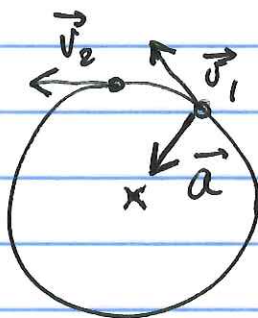


* Uniform circular motion

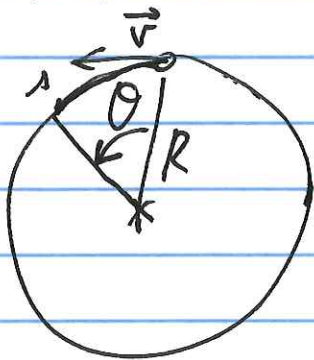
$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t}$$

$$\Delta \vec{v} = \vec{v}_2 - \vec{v}_1$$



* Uniform circular motion

$|\vec{v}| = v = \text{constant}$, but direction of \vec{v} changes



Δt time interval, object describes an angle θ , and crosses distance s

$$\theta = \frac{s}{R} \rightarrow s = \theta R$$

One full rotation: $\theta = 360^\circ$, $s = 2\pi R$

$$\underline{\theta} = \frac{s}{R} = \frac{2\pi R}{R} = \underline{2\pi} \text{ for 1 full rotation}$$

radians

radians

degree

$$2\pi$$

$$360^\circ$$

$$\pi$$

$$180^\circ$$

$$\pi/2$$

$$90^\circ$$

angle in radians

$$= (\text{angle in degrees}) \frac{\pi}{180^\circ}$$

Period of rotation T : one full rotation

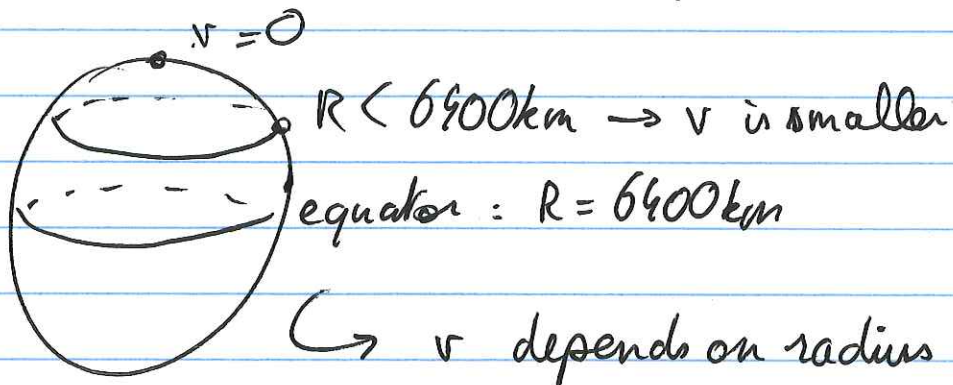
$$\underline{v} = |\underline{\vec{v}}| = \frac{d}{\Delta t} = \frac{2\pi R}{T}$$

Frequency of rotation $f = \frac{1}{T}$

T in units of $s \rightarrow f$ in units $\frac{1}{s} = \text{Hz}$

* Example: earth rotates with a period $T = 1$ day.
radius of $6400 \text{ km} = R$
what is the speed with which everyone (on the equator)
is rotating around the earth's center?

$$v = \frac{2\pi R}{T} = \frac{2\pi (6400 \times 10^3 \text{ m})}{(1 \text{ day}) \left(\frac{3600 \text{ s}}{\text{hour}} \right) \left(\frac{24 \text{ hours}}{\text{day}} \right)}$$
$$= 460 \text{ m/s} \text{ or } 920 \text{ mph}$$



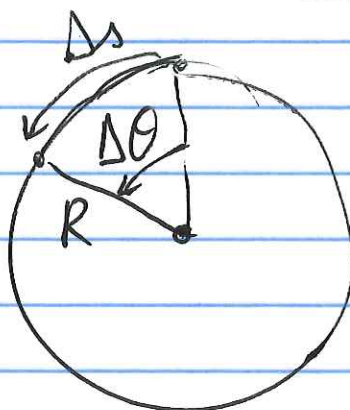
* Angular velocity

{ linear
"regular" velocity

$$\underline{\omega} = \frac{\Delta\theta}{\Delta t}$$

$$\underline{v} = \frac{\Delta x}{\Delta t}$$

$$\underline{\Delta\theta} = \frac{\Delta s}{R}$$



$$s = R\theta$$

$$\underline{\Delta t} = \frac{\Delta s}{v} = \frac{\Delta s}{\left(\frac{2\pi R}{T}\right)}$$

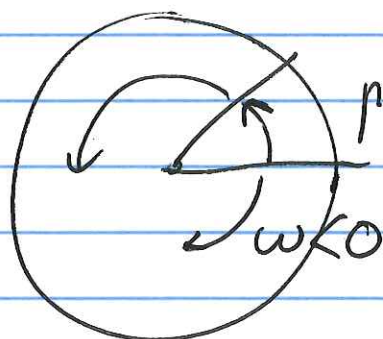
$$\underline{\omega} = \frac{\Delta\theta/R}{\Delta s / \left(\frac{2\pi R}{T}\right)} = \frac{1}{R} \left(\frac{2\pi R}{T}\right) = \frac{2\pi}{T} = \underline{2\pi f}$$

$$\underline{v} = \frac{2\pi R}{T} = \left(\frac{2\pi}{T}\right) R = \underline{\omega} R$$

* Signs of ω

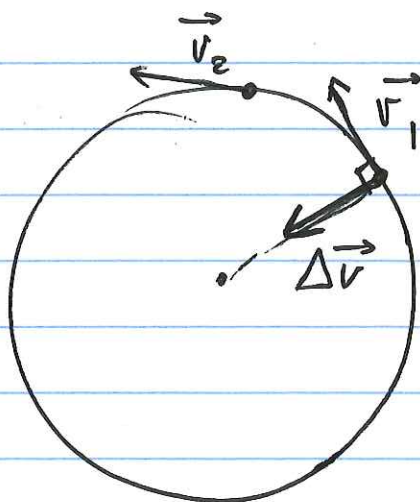
$\omega > 0$: CCW rotation

$\omega < 0$: CW rotation



positive angle $\rightarrow \omega > 0$

$\omega < 0$



$$\Delta \vec{v} = \vec{v}_2 - \vec{v}_1$$

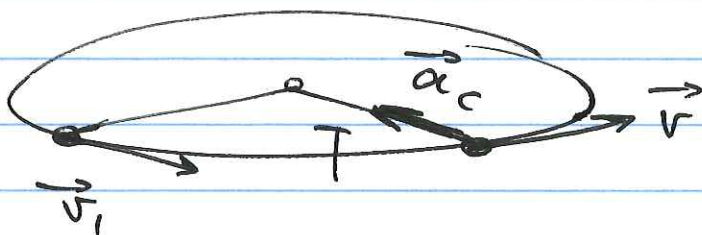
$$\vec{a}_c = \frac{\Delta \vec{v}}{\Delta t} \quad \text{centripetal acceleration}$$

$$\vec{a}_c = \frac{v^2}{R} \quad \text{towards the center of rotation}$$

$$\underline{\underline{a_c = \frac{v^2}{R} = \frac{(\omega R)^2}{R} = \underline{\underline{\omega^2 R}}}}$$

Dynamics : $\vec{F}_{\text{net},c} = m \vec{a}_c$

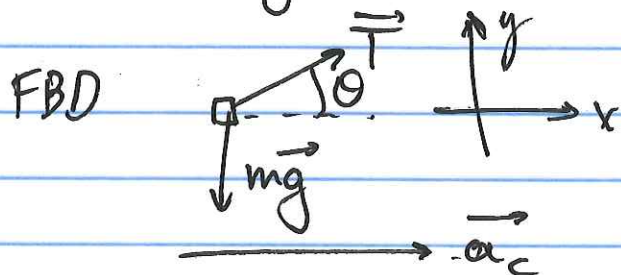
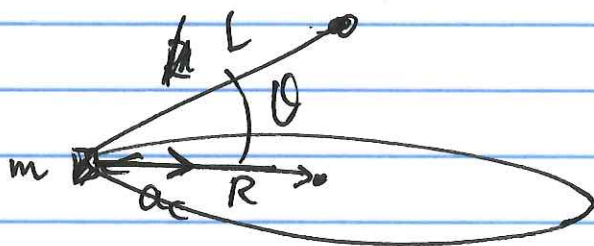
$\vec{F}_{\text{net},c}$ points towards the center



$$a_c = \frac{v^2}{R}$$

$$T = F_{\text{net},c} = m a_c = m \frac{v^2}{R}$$

What is the angle at which the mass spins
? string

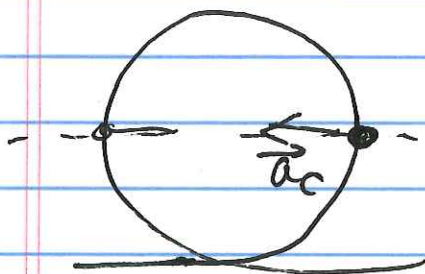


$$\vec{F}_{\text{net}} = m\vec{a} : \begin{cases} x : T \cos \theta = m \frac{v^2}{R} \\ y : T \sin \theta - mg = 0 \end{cases}$$

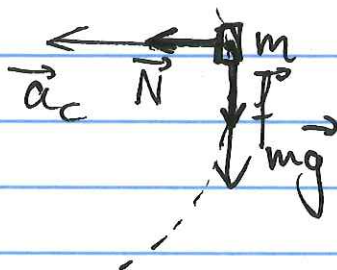
$$T = \frac{mg}{\sin \theta}$$

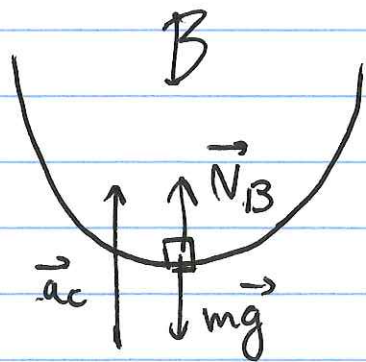
$$\cancel{mg} \frac{\cos \theta}{\sin \theta} = \cancel{m} \frac{v^2}{R}$$

$$\frac{1}{\tan \theta} = \frac{v^2}{Rg} \rightarrow \frac{1}{10} = \frac{1 \text{ m/s}^2}{1 \text{ m}} = \frac{1}{10}$$



FBD

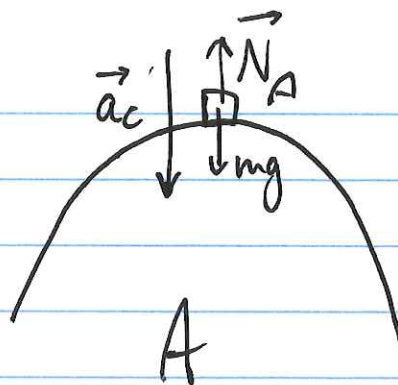




$$N_B - mg > 0$$

$$a_c > 0$$

$$N_B > N_A$$



$$N_A - mg < 0$$

$$a_c < 0$$

