

PHYS 107 - Week 3 - Friday

* From kinematics to dynamics

kinematics = treatment of motion without consideration of its causes



dynamics = what causes the motion

"Forces" cause dynamics

Force = intuitive notion of "push" or "pull"
= vector quantity with both direction and magnitude

Historically: Aristotle : - the natural state of an object is at rest.

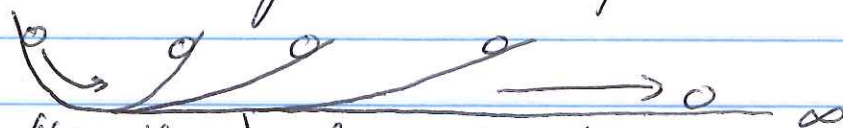


- any motion requires a force, and an object will come to rest when no force is applied

Galileo (1609) : objects in motion stay in motion unless acted upon by an external force



Newton (1685-1686) : laws of motion



* Newton's first law: (based on Galileo's work)

Objects have a constant velocity \vec{v}
unless acted upon by a force \vec{F}

Note: $\vec{v} = 0$ is a perfectly allowed state of motion but
not a special case

Moving reference frames with constant velocity \rightarrow all
laws of physics are still valid
 \rightarrow classical relativity (ball bouncing on
a train)

* Newton's second law:

Acceleration of an object that is acted upon by an
external force \vec{F}_{net} is directly proportional to that
force, and inversely proportional to its mass m .

$$\vec{F}_{\text{net}} = m\vec{a} \quad \text{or} \quad \vec{a} = \frac{\vec{F}_{\text{net}}}{m}$$

$$\vec{F}_{\text{net}} = \text{sum of all external forces (vector sum)} \\ = \sum_i \vec{F}_i$$

$$\underbrace{\vec{F}_{\text{net}}}_{\text{dynamics}} = m \underbrace{\vec{a}}_{\text{kinematics}}$$

inertial mass

Note: first law is a consequence of second law
 $\vec{F} = 0 \rightarrow \vec{a} = 0 \rightarrow \vec{v} = \text{constant}$
 $\hookrightarrow \text{slope is zero}$

* Newton's Third law:

If an object A exerts a force on object B, then object B exerts an equal and opposite force on object A
 $\left\{ \begin{array}{l} \text{magnitude} \\ \text{direction} \end{array} \right.$

$$\vec{F}_{BA} = - \vec{F}_{AB}$$

Examples: - person on floor \rightarrow floor on person
- gravity on mass \rightarrow mass on earth

Q Apple-earth

after
units

* ~~Units~~:

Mass vs.
Height

mass $m \rightarrow$ units kg

- = measure of inertia of an object
(reluctance to change its motion)
- ↳ intrinsic property of an object
(number and type of atoms)
- scalar quantity

weight $\vec{W} = -mg$ = force due to gravity
- vector quantity

* Units of force: ~~units~~ ~~units~~ $m\vec{a} \rightarrow \text{kg m/s}^2 = N$

1 N = force of 1 apple in your hand

$$(100g)(9.80 \text{ m/s}^2) \approx 1 N$$

* Force is a vector: $\vec{F}_{\text{net}} = m\vec{a} \rightarrow \begin{cases} F_x = ma_x \\ F_y = ma_y \\ F_z = ma_z \end{cases}$

Q Forces 3a

* Examples of forces:

- Weight = force due to gravity

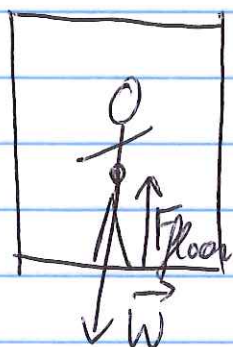
$$\vec{F}_g = \vec{W} = m\vec{a} = m\vec{g} \rightarrow -g, \text{ downward} \\ |\vec{g}| = 9.80 \text{ m/s}^2$$

$$m = 1 \text{ kg} \rightarrow \vec{W} = -9.80 \text{ N}, \text{ downward}$$

On the moon, $\vec{g} = 1.67 \text{ m/s}^2$, downward

$$\hookrightarrow \vec{W}' = -1.67 \text{ N}, \text{ downward} \approx \frac{1}{6} \vec{W}$$

* Person in elevator



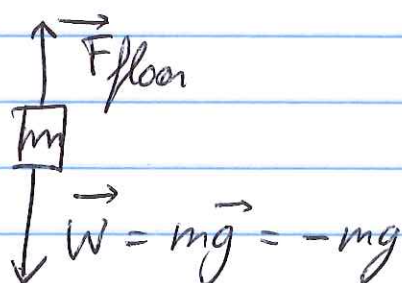
going at constant velocity
standing still $\rightarrow m\vec{a} = 0 = \vec{F}_{\text{net}}$

$$\vec{F}_{\text{net}} = \vec{F}_{\text{floor}} + \vec{W} = 0 \\ \text{(upward)} \quad \text{(downward)}$$

$$\vec{F}_{\text{floor}} = +mg, \text{ upwards}$$

Free-body diagram:

diagram with all
forces exerting on
object (not an
accurate picture with details!)



* Falling elevator $\rightarrow \vec{a} = \vec{g}$

$$\hookrightarrow \vec{F}_{\text{net}} = m\vec{a} = m\vec{g} = \vec{W} + \vec{F}_{\text{floor}}$$

$$\hookrightarrow \vec{F}_{\text{floor}} = \cancel{m\vec{g}} - \vec{W} = 0$$

\rightarrow no force from floor on person

* Rising, accelerating elevator $\rightarrow \vec{a}$ positive, upward

$$\hookrightarrow \vec{F}_{\text{net}} = m\vec{a} = \vec{W} + \vec{F}_{\text{floor}}$$

$$\vec{F}_{\text{floor}} = m\vec{a} - \vec{W} = m(a + g)$$

\parallel
 $-mg$

\hookrightarrow feel heavier

* Downward accelerating elevator $\rightarrow \vec{a}$ negative, downward
but $|\vec{a}| < |\vec{g}|$

$$\hookrightarrow \vec{F}_{\text{floor}} = m\vec{a} - \vec{W} = m(-a + g)$$

\hookrightarrow feel lighter