

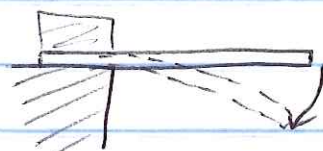
PHYS 107 - Week 12 - Friday

* Waves and periodic motion, oscillations

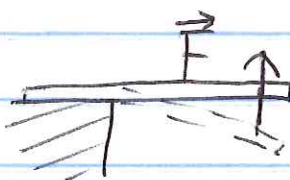
What is periodic motion? - grandfather clock with pendulum,
- guitar string, water waves,
- sound, light, electrical phenomena etc
- vibrations in molecules
- earthquakes, waves on earth
- oscillations in brightness of stars

Simplest oscillations and waves: caused by restoring force around equilibrium

Example: meter stick



give stick some deviation from equilibrium



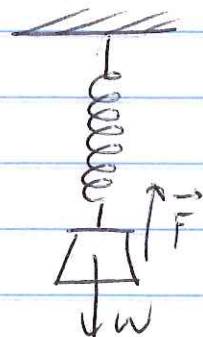
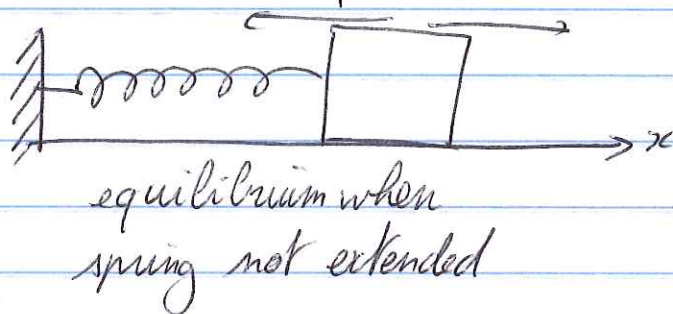
→ force wants to bring system back to equilibrium

Features:

- stable equilibrium position
- restoring force tries to bring system back to equilibrium
- system builds up kinetic energy and overshoots
- now the restoring force is on the opposite side

Q & Restoring force

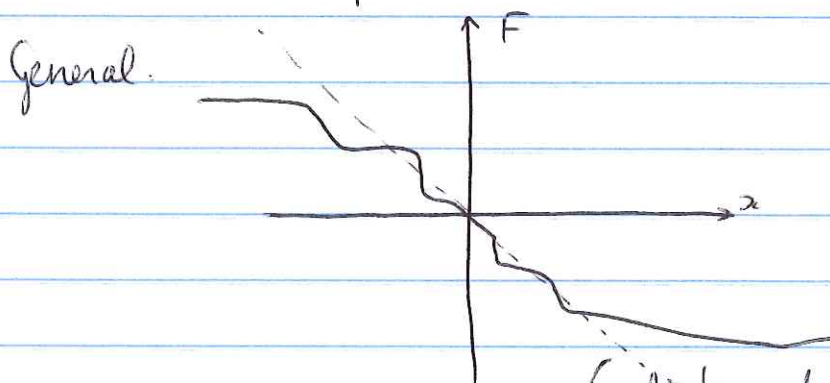
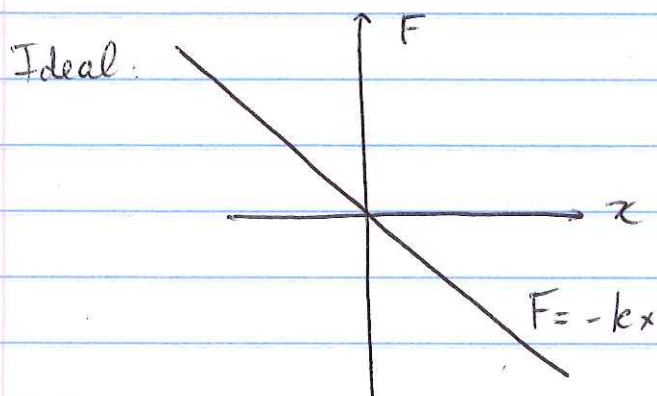
* Spring as the prototypical oscillating system



equilibrium when $F = W$
 Hooke's law $F = -k\Delta L$ is the restoring force
 equilibrium at $x = 0 \rightarrow F = -kx$

Q 9a, b Spring Max Acceleration/Energy

* Other types of springs: compression/expansion, shearing



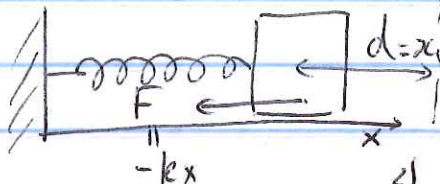
(, just order approximation
 \rightarrow there is always a small enough region where $F = -kx$

* Energy

$$PE \rightleftharpoons KE \rightleftharpoons PE$$

Potential energy for elastic system:

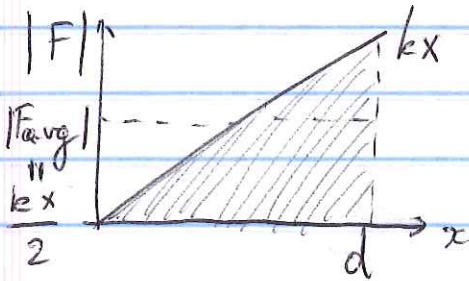
1) naive approximation:



$$W = F \cdot d \cos \theta = Fx \cos 180^\circ$$

$$= -kx \cos 180^\circ = kx^2$$

2) but F is not constant



$$\rightarrow W = F_{\text{avg}} x = \frac{1}{2} kx^2$$

$$PE = \frac{1}{2} k X^2, \text{ with } X = \text{maximum value of } x$$

* Frequency and period

T = period = time needed for 1 oscillation (unit: s)

$f = \frac{1}{T}$ = frequency = number of oscillations in 1 second
(units: $s^{-1} = \text{Hz}$)

piano playing note A: $440 \text{ Hz} \rightarrow T = \frac{1}{f} = 2.27 \text{ ms}$

WCWM: $90.3 \text{ MHz} \rightarrow T = 1.1 \times 10^{-8} \text{ s}$
 $= 11 \text{ ns}$

* Simple harmonic motion (SHM)

↳ name for any oscillation that follows Hooke's law like a mass and spring system, pendulum, ruler, but much more broadly applicable

Amplitude A = maximum displacement from equilibrium

In SHM : f, T are independent from A

→ same frequency for large and small amplitude (example: guitar string has same frequency regardless of amplitude)

What does the frequency depend on in SHM? m, k

$$T = 2\pi \sqrt{\frac{m}{k}} \quad \text{or} \quad f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \text{frequency}$$
$$\omega = 2\pi f = \sqrt{\frac{k}{m}} = \text{angular frequency}$$

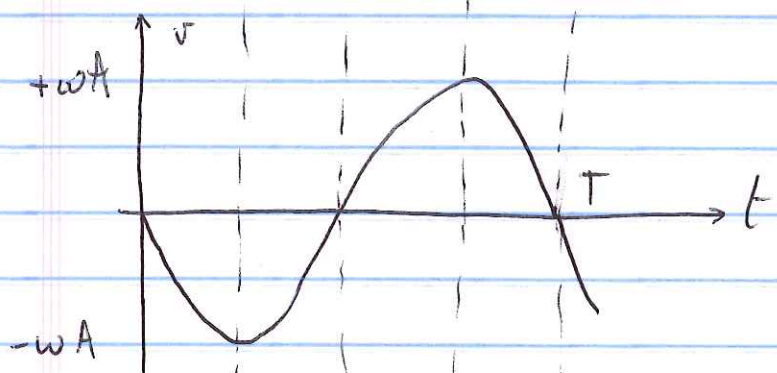
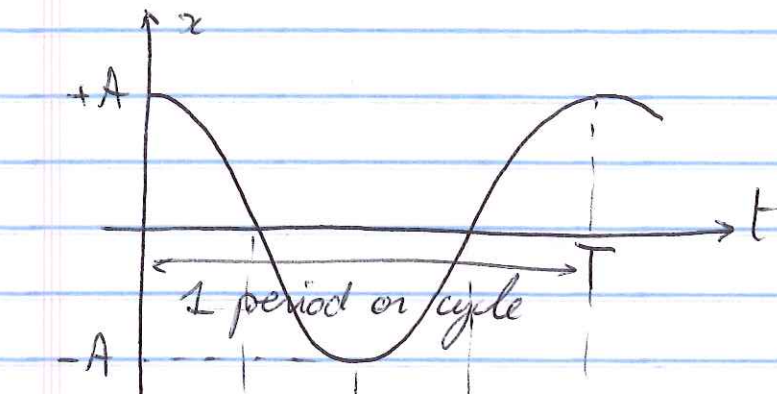
Why? $\left. \begin{array}{l} m \text{ in units } \text{kg} \\ k \text{ in units } \frac{\text{N}}{\text{m}} = \frac{\text{kg}}{\text{s}^2} \end{array} \right\} \text{ only way to get units of } \text{s}^{-1} \text{ is as } \sqrt{\frac{k}{m}}$

Example: shock absorbers on a car with $m = 2500 \text{ kg}$
 $k = 10^6 \text{ N/m}$

$$\hookrightarrow T = 2\pi \sqrt{\frac{m}{k}} = 0.3 \text{ s}$$

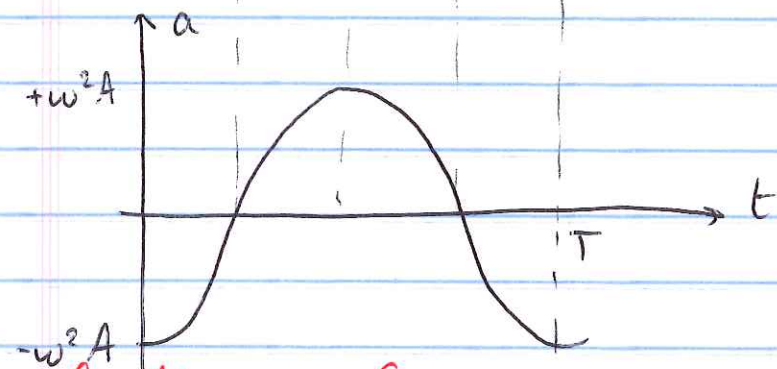
* How does x change over time?

$$x = A \cos(\omega t) = A \cos(2\pi f t) = A \cos\left(2\pi \frac{t}{T}\right)$$



$$v = -\sqrt{\frac{k}{m}} A \sin(2\pi f t)$$

$$= -\omega A \sin(\omega t)$$



$$a = -\omega^2 A \cos(\omega t)$$

Q 10a, b Mass on a Spring

$$\rightarrow v_{\max} = \omega A = \sqrt{\frac{k}{m}} A$$

$$a_{\max} = \omega^2 A = \frac{k}{m} A$$

$$F = ma? \text{ yes: } F = -kx = -k(A \cos(\omega t)) = -m \omega^2 A \cos(\omega t)$$

+ Energy conservation : $KE + PE = \text{constant}$

$$E_{\text{total}} = \frac{1}{2} m v^2 + \frac{1}{2} k x^2$$

$$= \frac{1}{2} m (-\omega A \sin \omega t)^2 + \frac{1}{2} k (A \cos \omega t)^2$$

$$= \frac{1}{2} m (\omega^2 A^2 \sin^2 \omega t) + \frac{1}{2} k (A^2 \cos^2 \omega t)$$

"k/m"

$$= \frac{1}{2} k A^2 (\sin^2 \omega t + \cos^2 \omega t) = \underline{\underline{\frac{1}{2} k A^2}}$$

= constant

$$E_{\text{total}} = \frac{1}{2} k A^2 = \frac{1}{2} k x_{\text{max}}^2 = \frac{1}{2} m v_{\text{max}}^2$$

$$PE_{\text{max}} = KE_{\text{max}}$$