

Rotational kinematics  $\rightarrow$  description of motion only  
 $\hookrightarrow$  nothing about causes

Rotational dynamics  $\rightarrow$  causes of angular motion  
 velocity  
 acceleration

$$\vec{F} = m\vec{a}$$

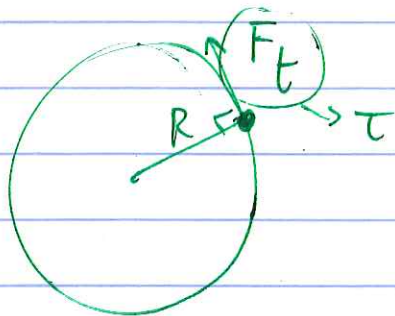
↑ dynamics      ↑ mass (inertial)      ↙ kinematics

force  $\vec{F} \rightarrow$  torque  $\vec{\tau} = F_{\perp} R$

acceleration  $\vec{a} \rightarrow$  angular acceleration

$$a_t = \alpha R$$

$$\frac{a_t}{R} = \alpha$$



mass  $m \rightarrow I$ , moment of inertia

$$\vec{F}_t = m\vec{a}_t$$

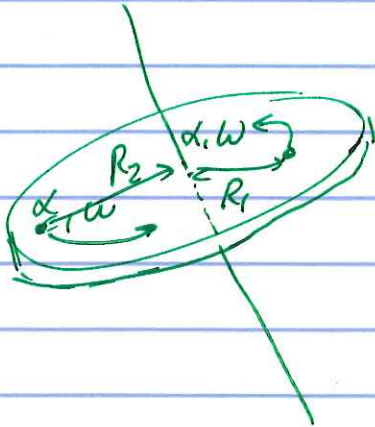
$$F_t R = \tau$$

$$\tau = F_t R = m a_t R = m R^2 \alpha$$

$$\vec{\tau} = (m R^2) \vec{\alpha} = I \vec{\alpha} \quad \text{with } m R^2 = I$$

$\tau$  CCW,  $\tau$  positive  $\rightarrow \alpha$  positive

$\tau$  CW,  $\tau$  negative  $\rightarrow \alpha$  negative



disc consists of many points  
with all same  $\alpha, \omega$

$$\tau_1 = m_1 R_1^2 \alpha$$

$$\tau_2 = m_2 R_2^2 \alpha$$

$\vdots$

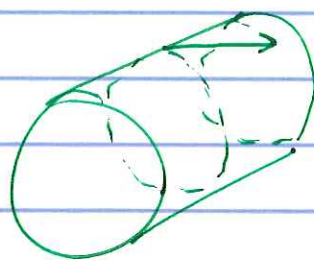
$$+ \frac{\tau_{\text{net}} = (m_1 R_1^2 + m_2 R_2^2 + \dots) \alpha}{\textcircled{I}}$$

$I$  is known for simple geometries (tabulated on pg. 328 of text)

$$I_{\text{disk}} = I_{\text{cylinder}} = \frac{1}{2} M R^2 \quad \begin{array}{l} M = \text{total mass} \\ R = \text{outer radius} \end{array}$$

$$I_{\text{hoop}} = M R^2$$

Example: cylinder of mass 2kg,  $R = 10 \text{ cm}$



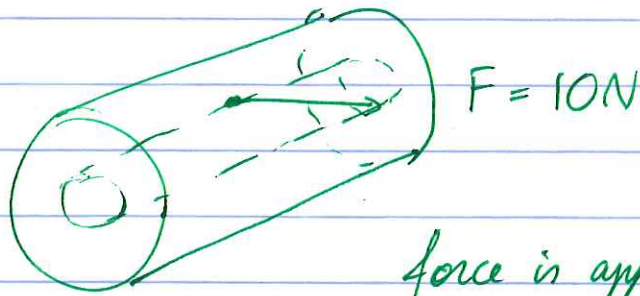
$F = 10 \text{ N}$  on outer diameter

what will  $\alpha$  be?

$$I = \frac{1}{2} M R^2 = 0.01 \text{ kg} \cdot \text{m}^2$$

$$\tau = F_{\perp} R = (10 \text{ N})(10 \text{ cm}) = 1 \text{ N} \cdot \text{m}$$

$$\tau = I \alpha \rightarrow \alpha = \frac{\tau}{I} = 100 \frac{\text{rad}}{\text{s}^2}$$



force is applied at  $\frac{R}{2}$

what will  $\alpha$  be now?

A:  $\alpha = 50 \frac{\text{rad}}{\text{s}^2}$

$$\alpha = \frac{\tau}{I} = \frac{F \frac{R}{2}}{\frac{1}{2} MR^2} = 50 \frac{\text{rad}}{\text{s}^2}$$

B:  $\alpha = 100 \frac{\text{rad}}{\text{s}^2}$

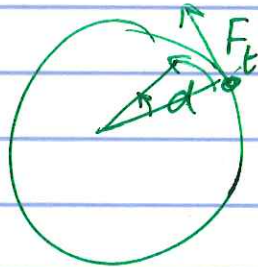
C:  $\alpha = 200 \frac{\text{rad}}{\text{s}^2}$

D:  $\alpha = ?$



Work for rotational dynamics

$$W = F_t d \cos \theta = F_t d = (F_t R) \left( \frac{d}{R} \right)$$



$$\underline{W = \tau \theta}$$

$$KE_{\text{rot}} = \frac{1}{2} m v_t^2 = \frac{1}{2} m R^2 \frac{v^2}{R^2} = \frac{1}{2} I \omega^2$$

$$\frac{v}{R} = \omega$$

$$W = F(d) \rightarrow W_{\text{rot}} = \tau \theta$$

$$KE = \frac{1}{2} (m v^2) \rightarrow \underline{KE_{\text{rot}}} = \frac{1}{2} (I \omega^2)$$

