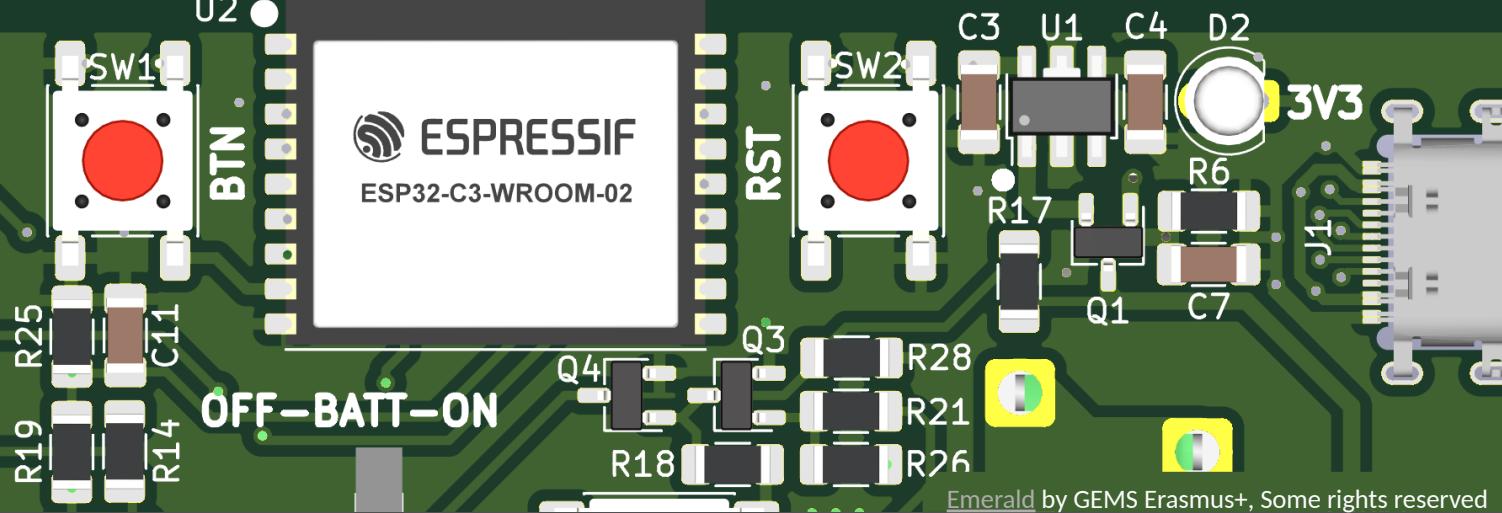


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3D printing - Enabling robot manufacturing technology

Building Robots: System Integration

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About

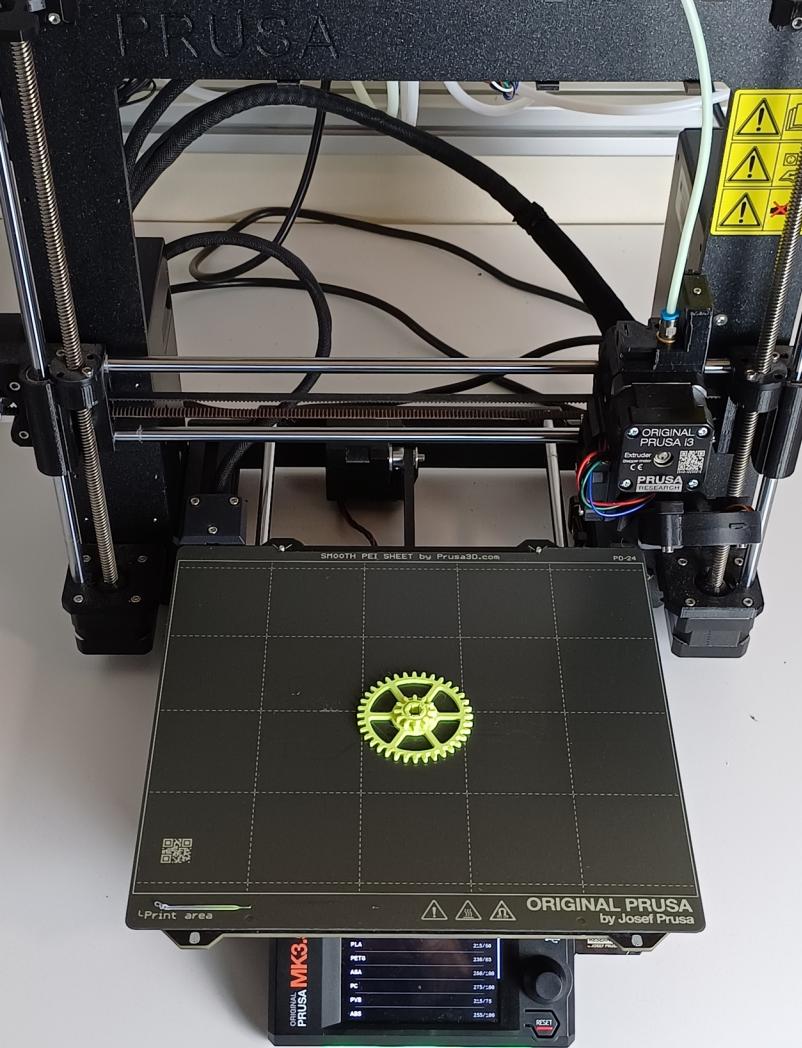
1 Process

2 Workflow

3 Limitations

4 Solutions

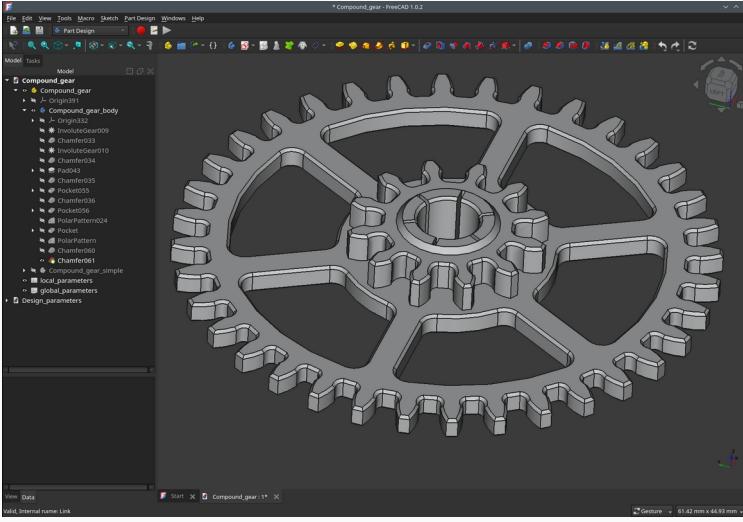
3D printing



FDM 3D Printing process

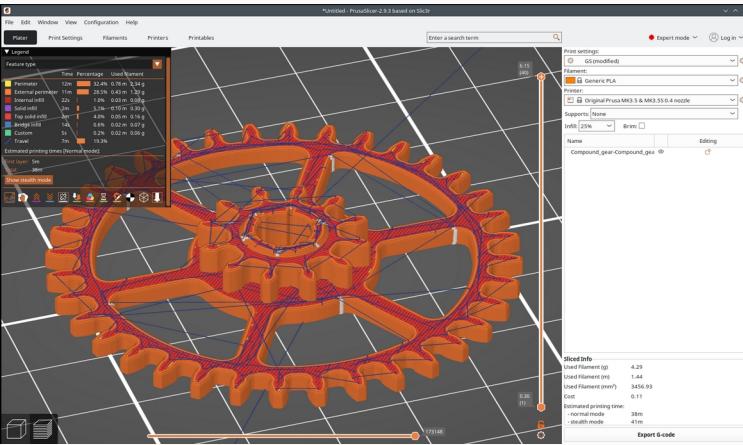
- 1 Thermoplastic filament
- 2 Moving heated nozzle
(melt → extrude → cool)
- 3 Extrusion in layers
(2D + 1D → 3D)

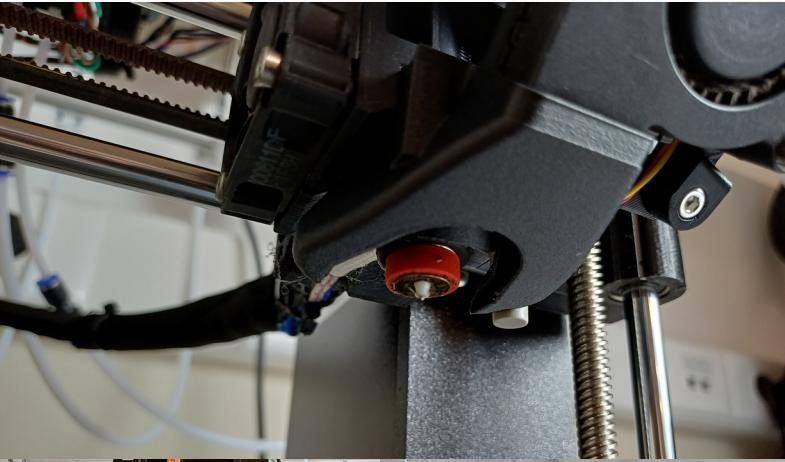
Workflow



Tools

- 1 CAD (FreeCAD)
Part design → export 3D object
- 2 CAM → Slicer (PrusaSlicer)
Nozzle path → save program
- 3 3D printer (Prusa mk3s+)
Final 3D printed part → post-processing

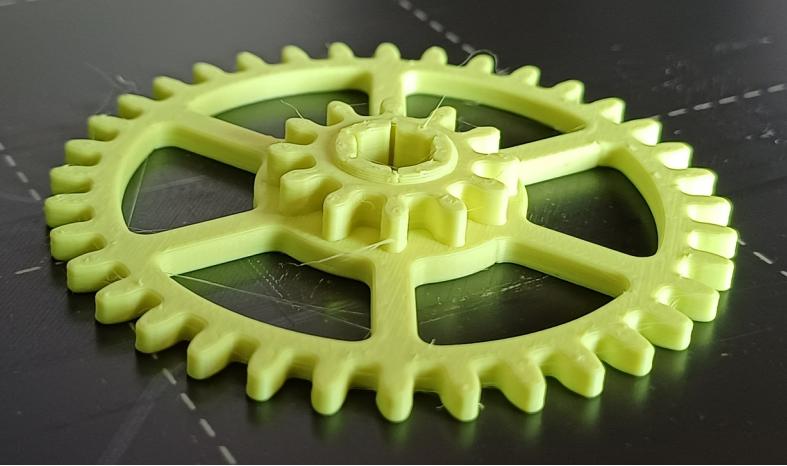
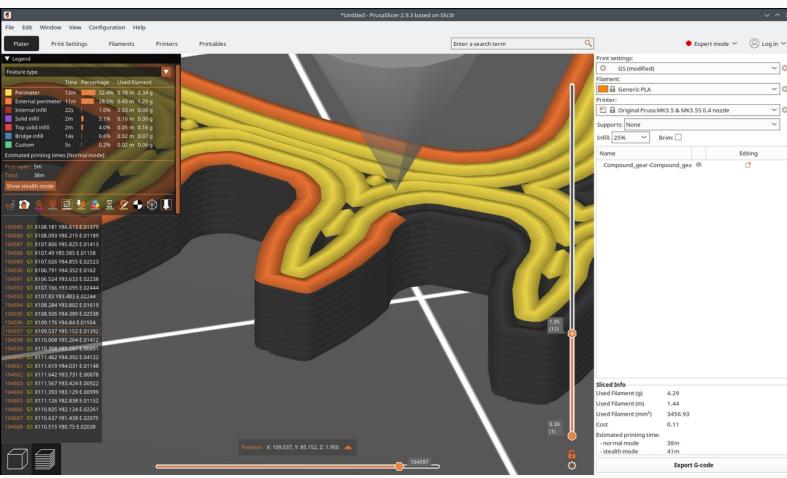




Configuration

- 1 Material → filament diameter, printing temperature
- 2 Nozzle → extrusion diameter, nozzle temperature
- 3 Part → layer height, N outer walls, infill percentage and pattern

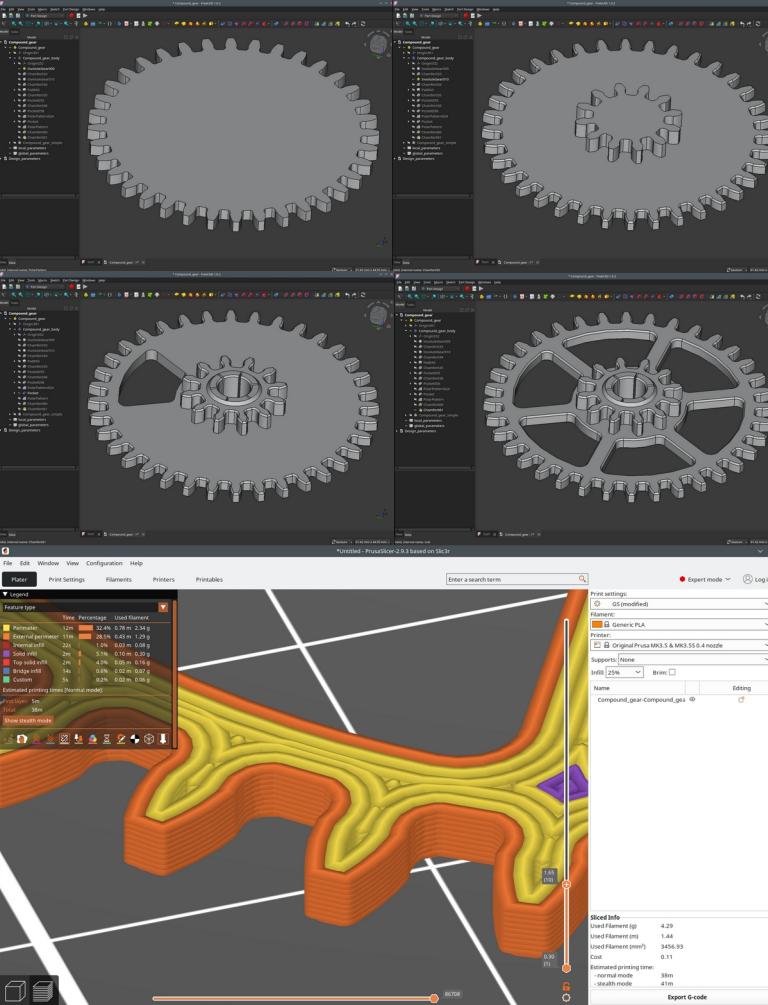
Limitations



Causes

- 1 Layer stacking → lower tensile strength, overhangs with support
- 2 Inconsistent width of extrusion → poor tolerances and surface
- 3 Poor first layer adhesion → print failure

Solutions



Design for manufacturing

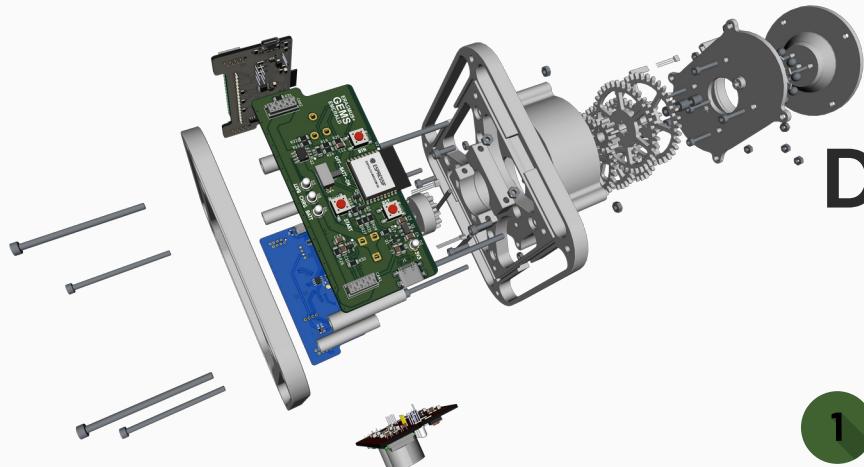
- 1 Part geometry based on layer and load direction
- 2 Nozzle size → defines the geometry of small details
- 3 Minimization of post-processing



Manufacturing process

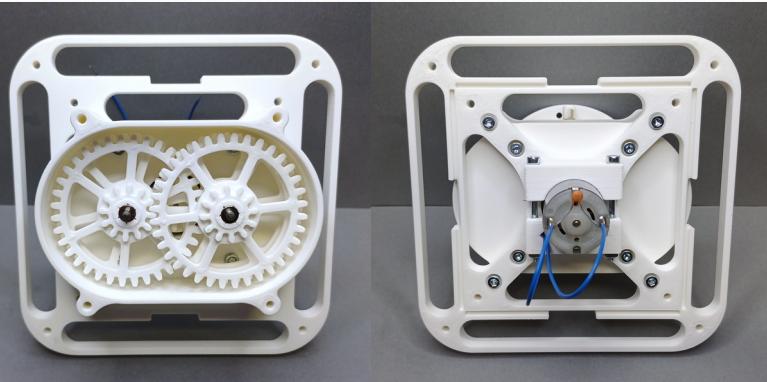
- 1 Dry filament
- 2 Clean and heated build plate
Surface material and texture
- 3 Supervision of first layer

Importance

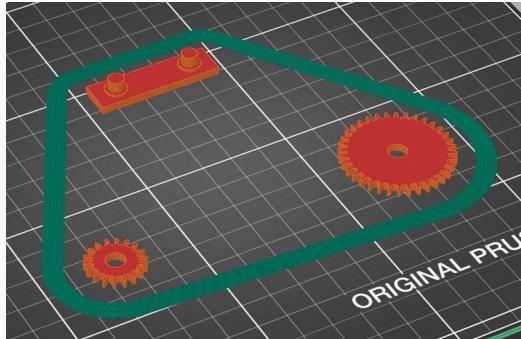
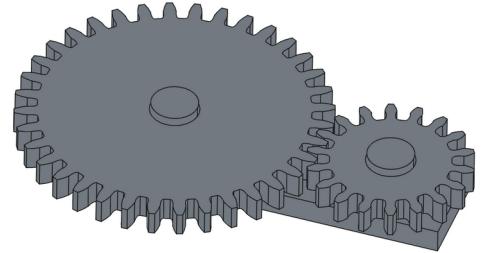


Design flexibility

- 1 Fast and inexpensive design iteration → small steps
- 2 Automated manufacturing process → time
- 3 Assembly driven design



Task



Gear pair

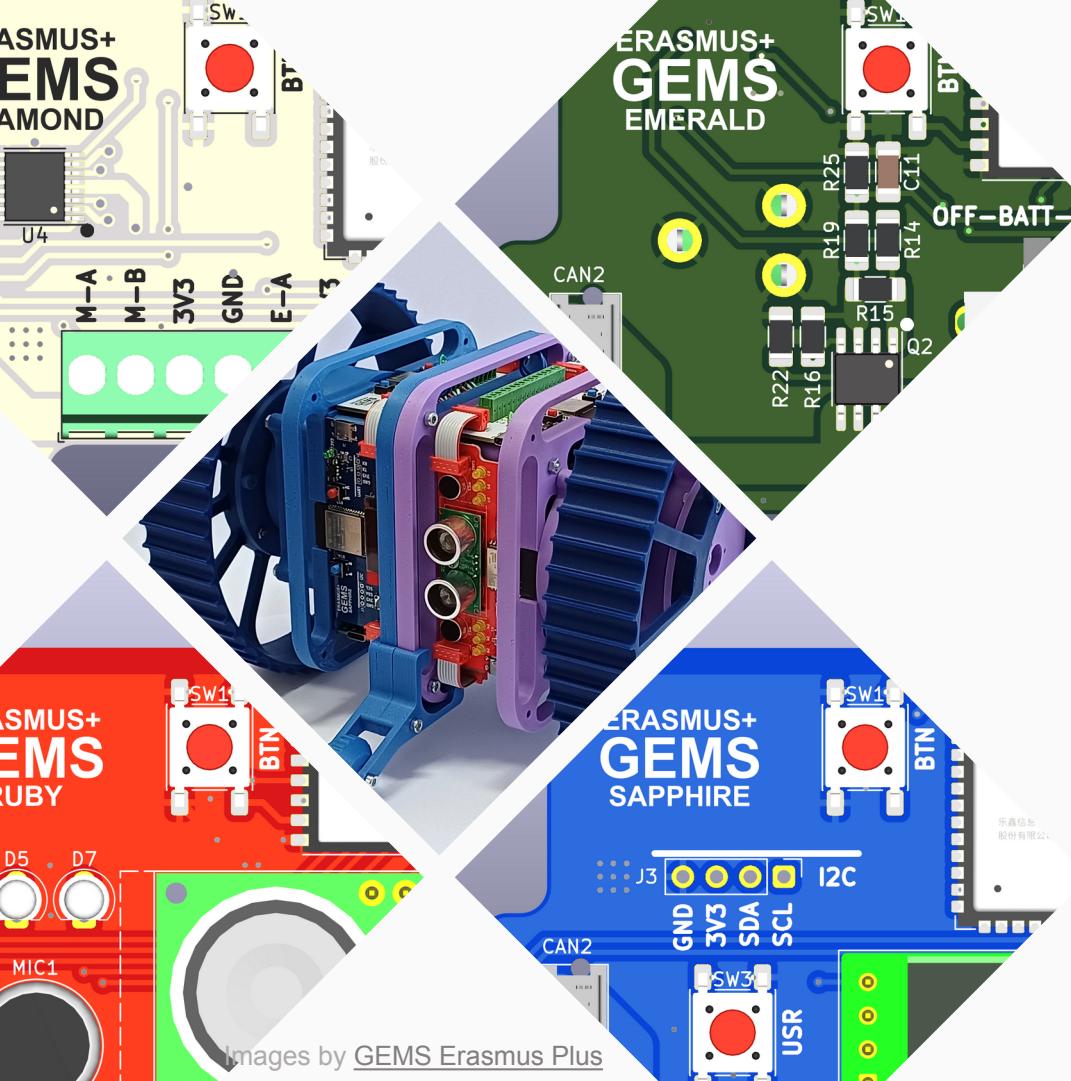
- 1 Reduction ratio: 3:1
- 2 Tooth: module (1.5mm), pressure angle (20°)
- 3 Gears: Number of teeth (20 and 60)
Center distance for meshing gears

Conclusion



3D printing for building robots

- 1 Versatile, but with limitations
- 2 Design for manufacturing process
- 3 Fast development pace



Thank you for watching!

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