

Tissue modeling

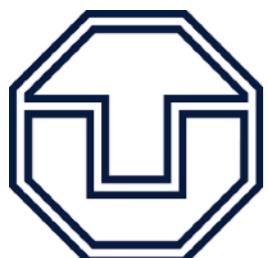
Multi-scale modeling of multicellular systems

Walter de Back

walter.deback@tu-dresden.de

twitter: @wdeback

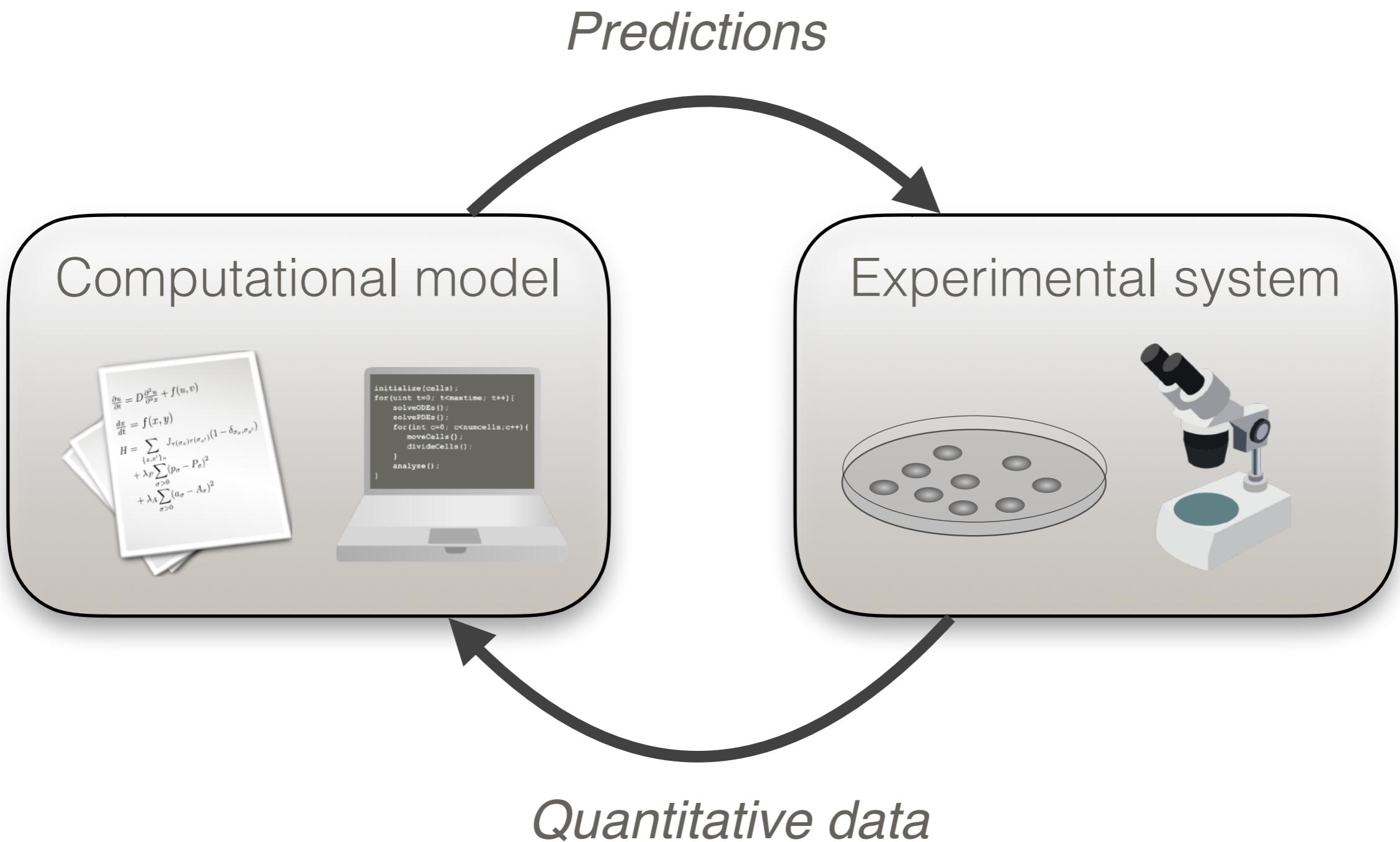
Institute for Medical Informatics and Biometry
“Carl Gustav Carus” Faculty of Medicine
TU Dresden



Systems Biology workshop, HZI Braunschweig, 2017

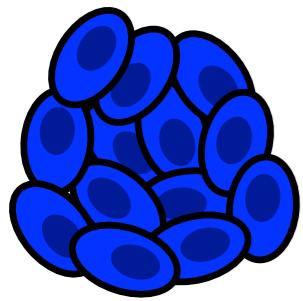


Systems biology cycle



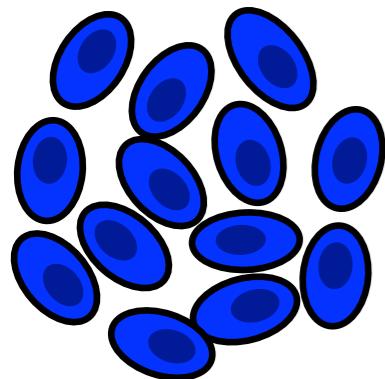
Systems biology

Tissue



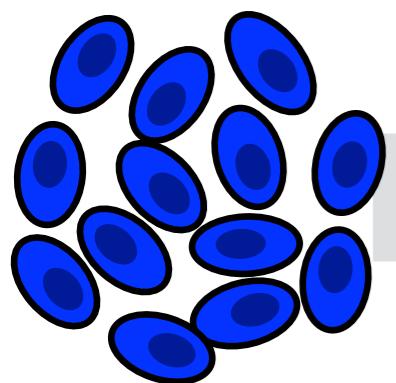
Systems biology

Tissue

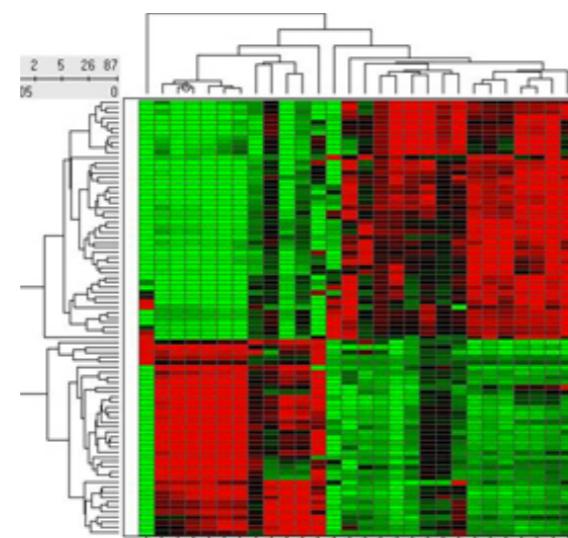


Systems biology

Tissue

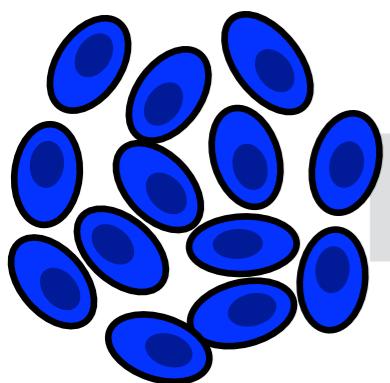


Omics

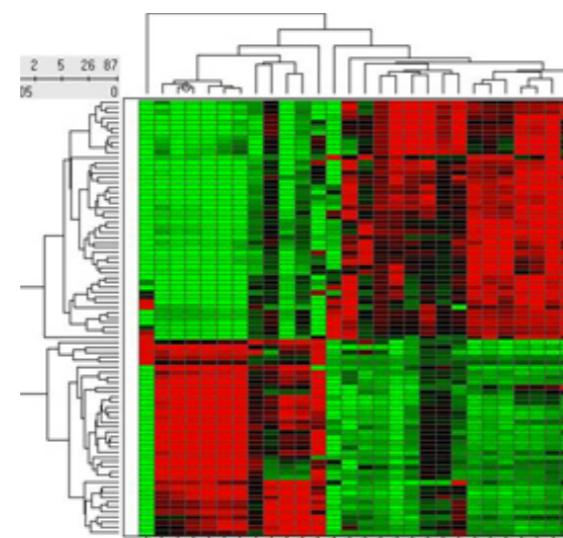


Systems biology

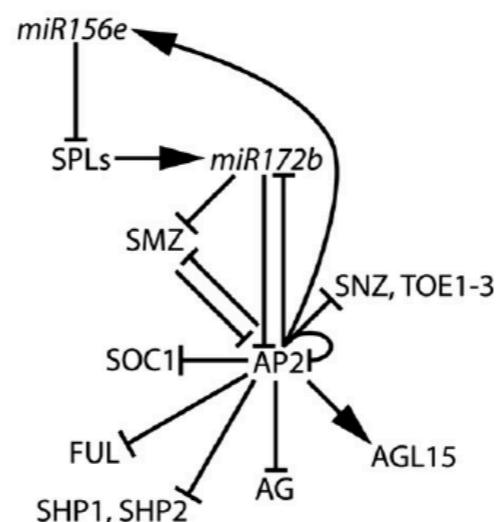
Tissue



Omics

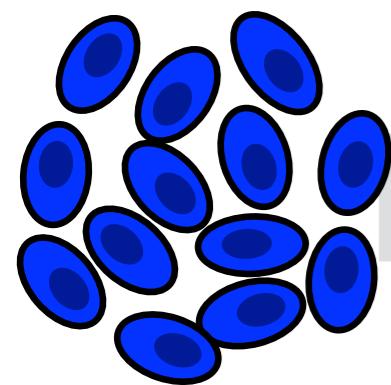


Intracellular network

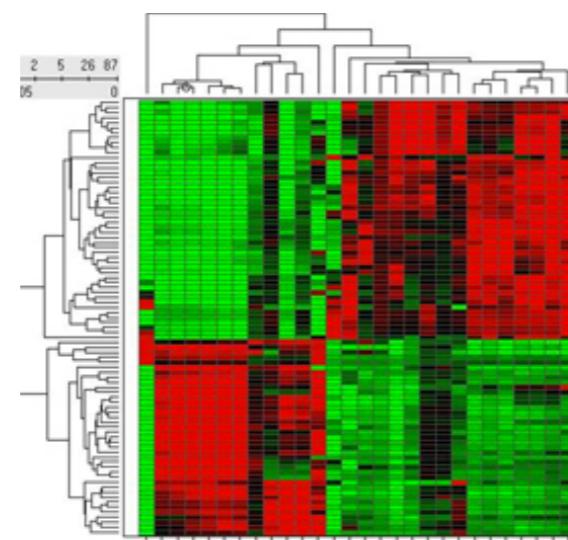


Systems biology

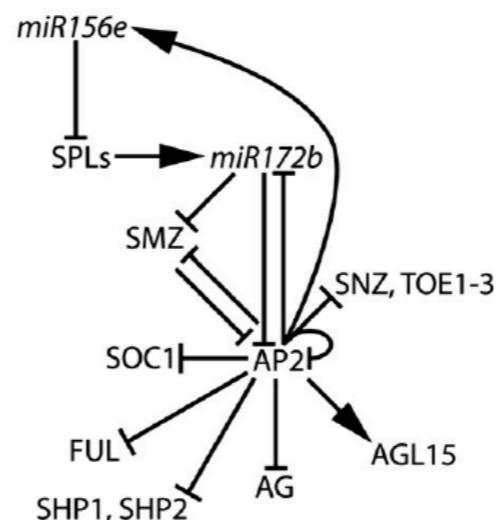
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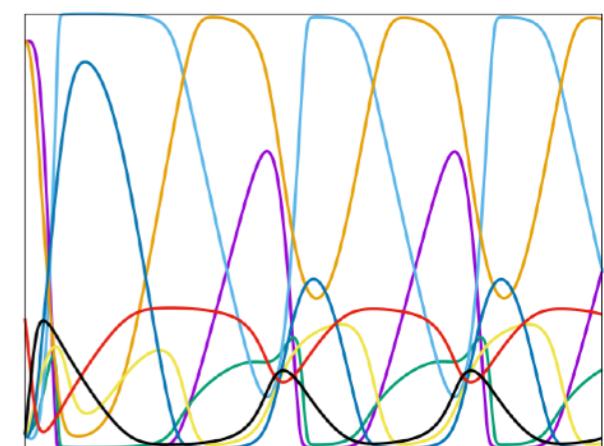
Omics



Intracellular network

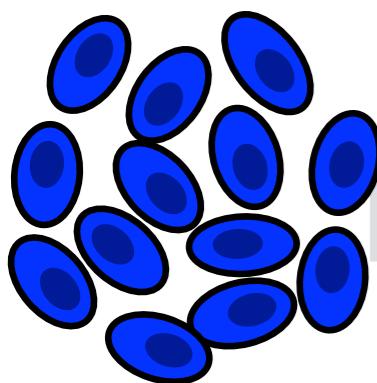


Dynamic simulation

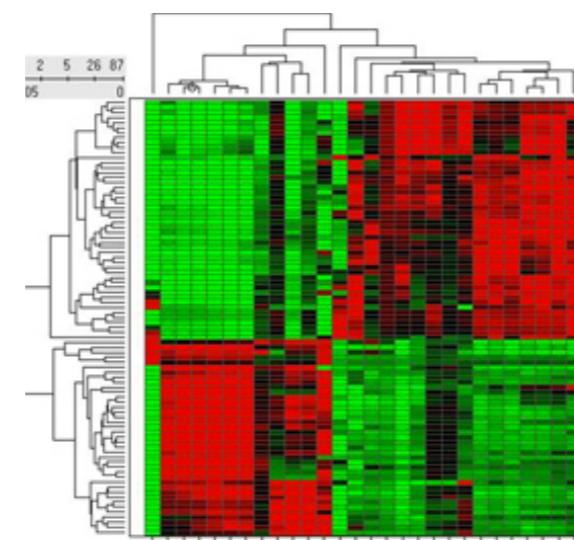


Multicellular Systems biology

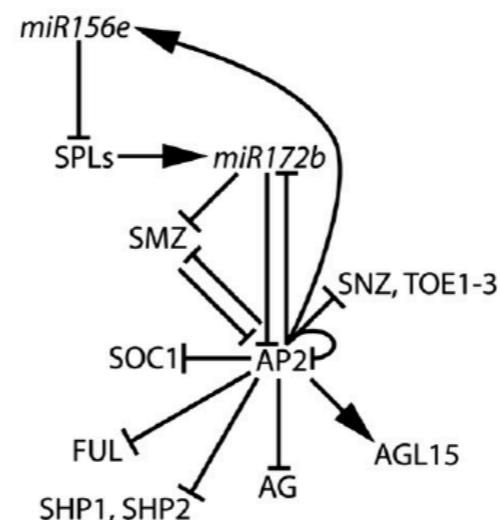
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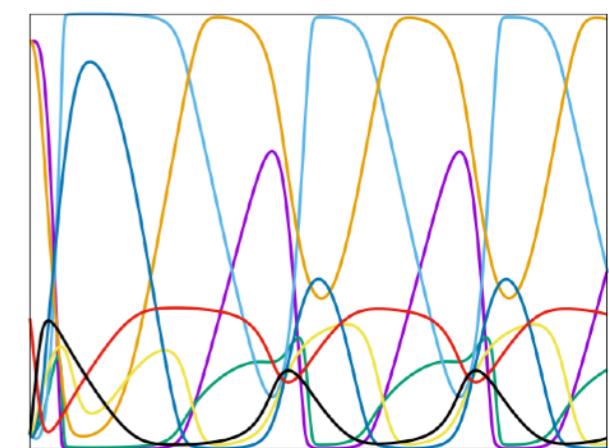
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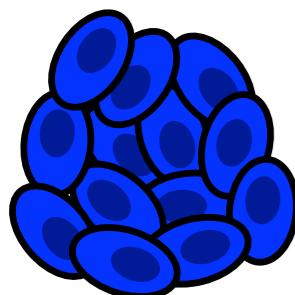
Intracellular network



Dynamic simulation

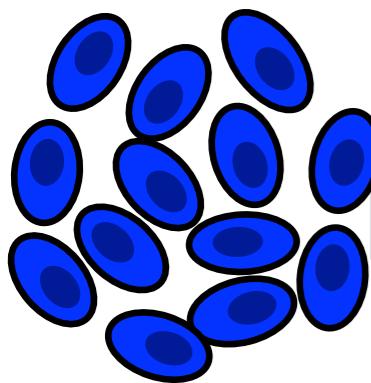


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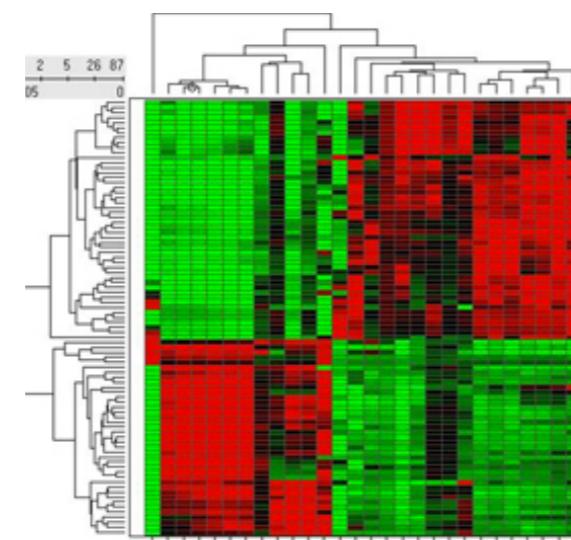


From SysBio to Multicellular SysBio

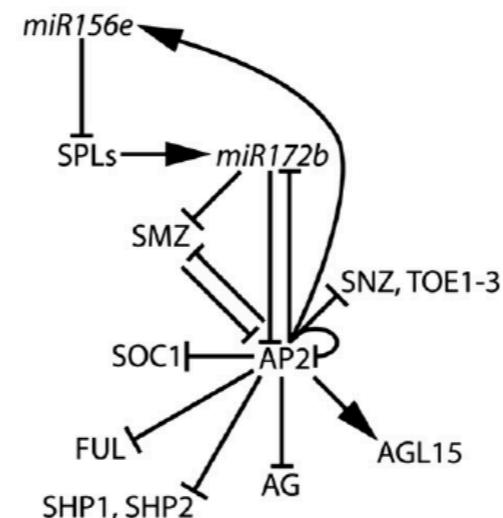
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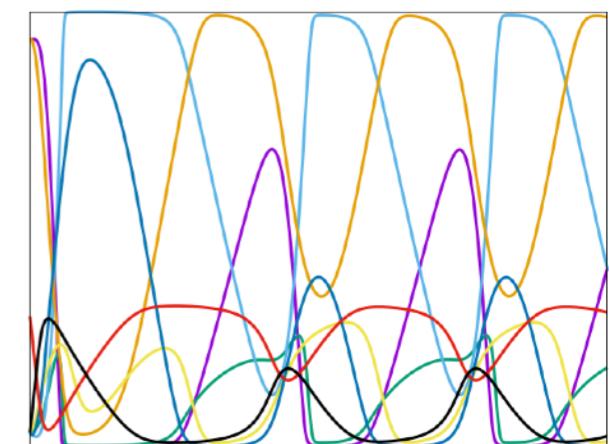
Omics



Intracellular network



Dynamic simulation



Tissue

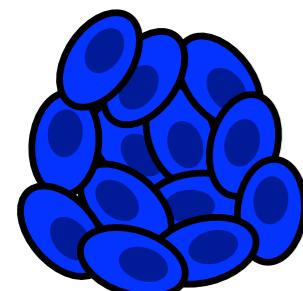
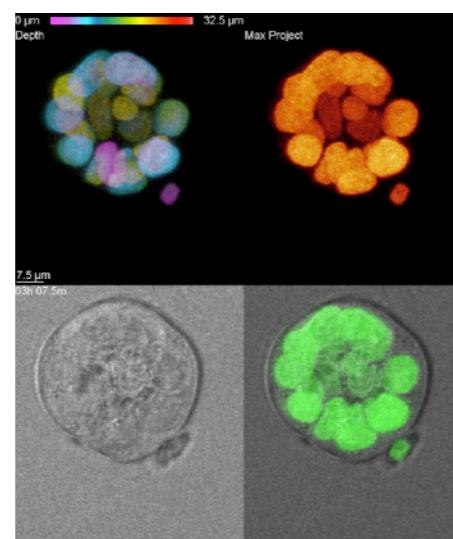


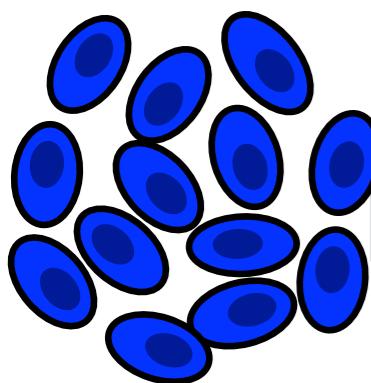
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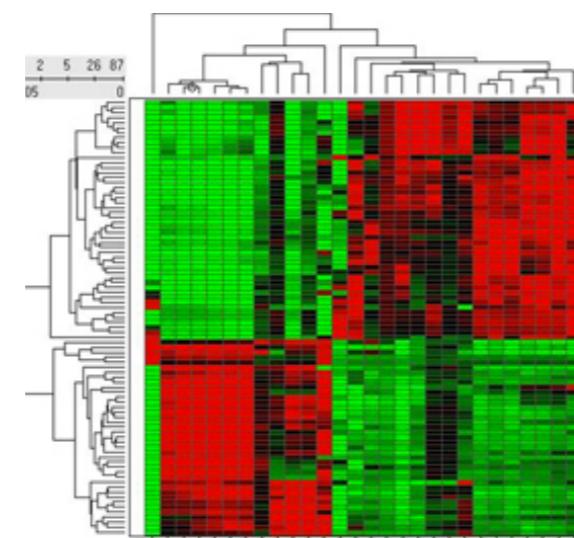
Drost et al, 2015

From SysBio to Multicellular SysBio

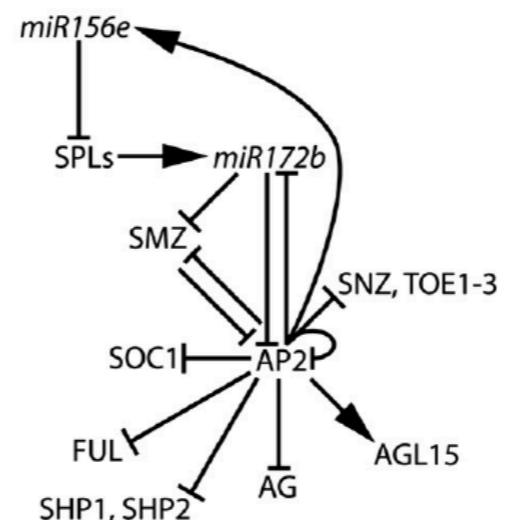
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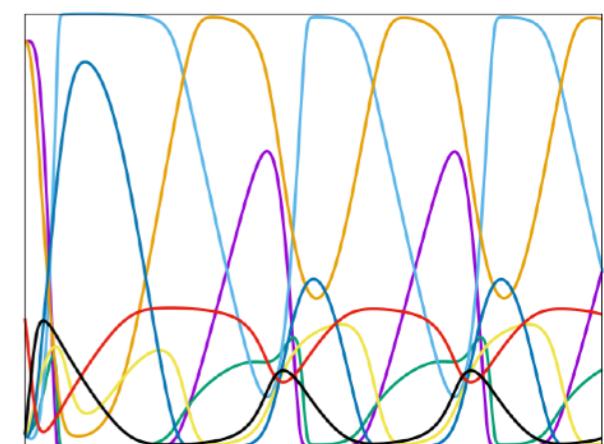
Omics



Intracellular network



Dynamic simulation



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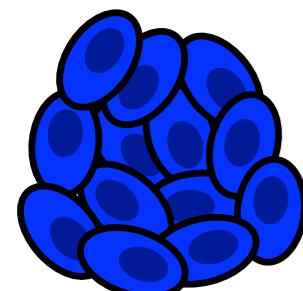
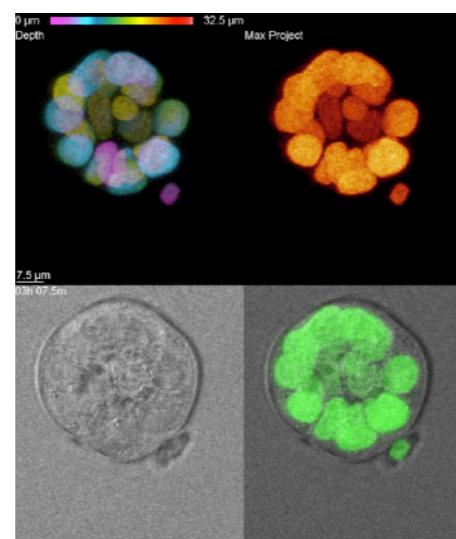


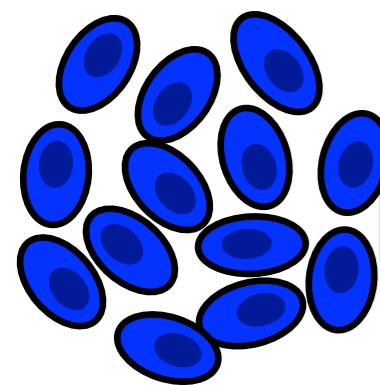
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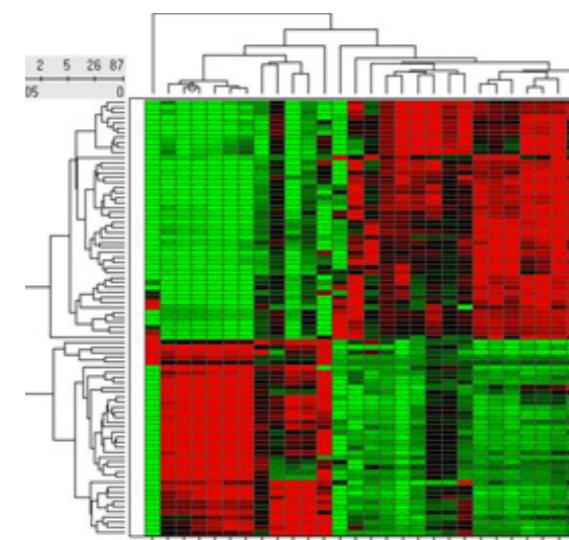
Drost et al, 2015

From SysBio to Multicellular SysBio

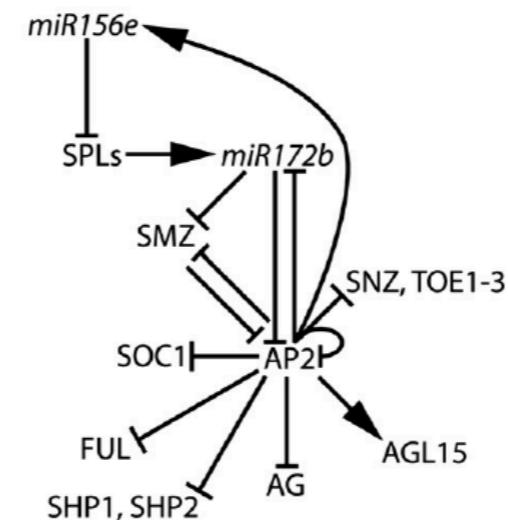
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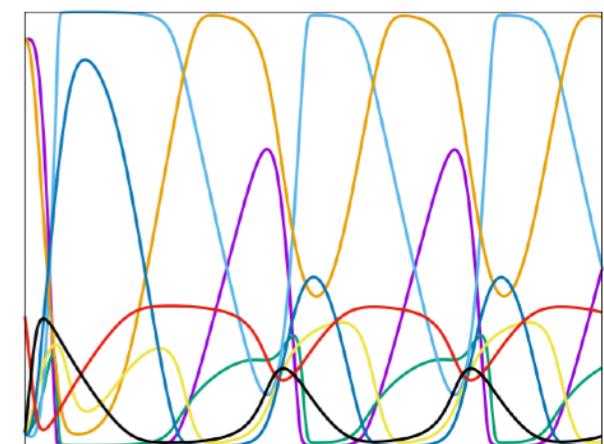
Omics



Intracellular network



Dynamic simulation



Tissue

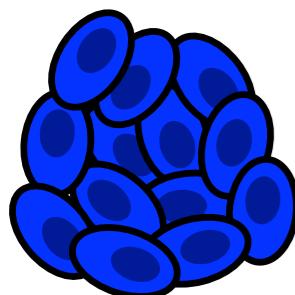
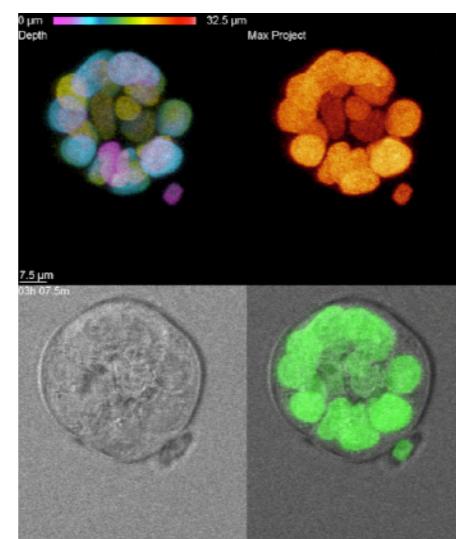
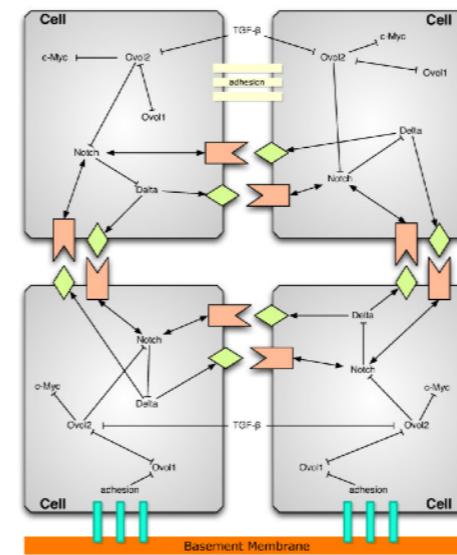


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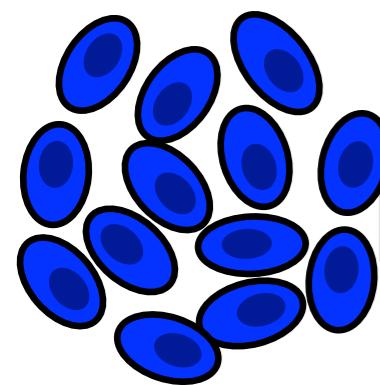
Drost et al, 2015

Intercellular network

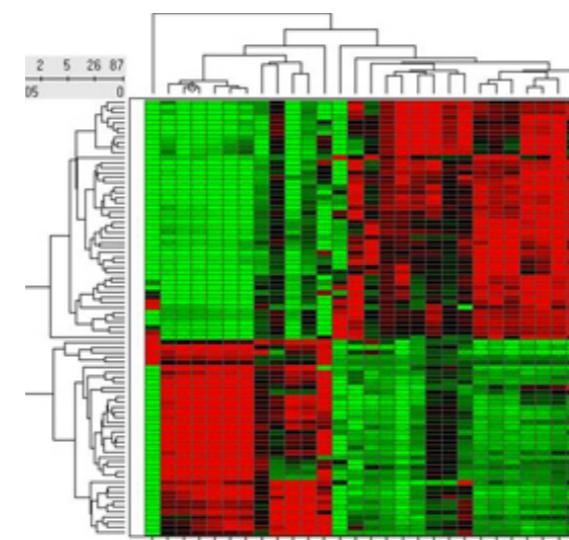


From SysBio to Multicellular SysBio

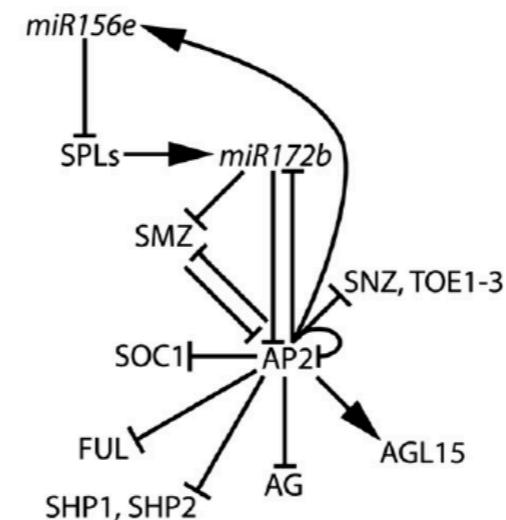
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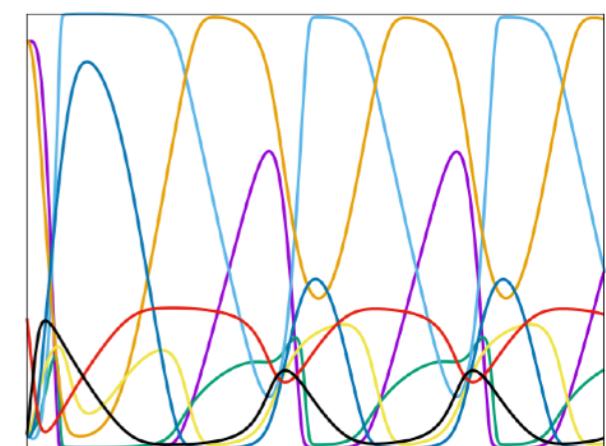
Omics



Intracellular network



Dynamic simulation



Tissue

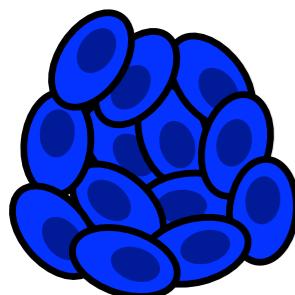
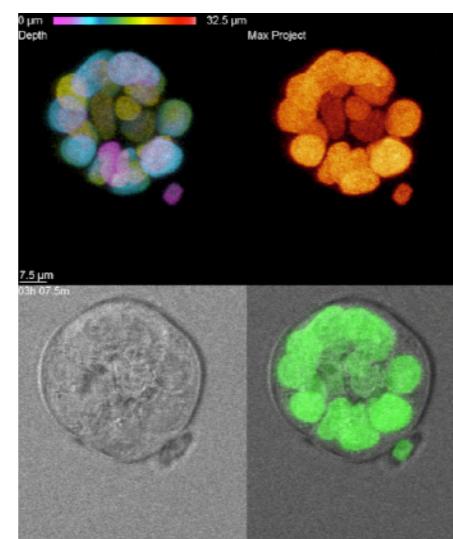
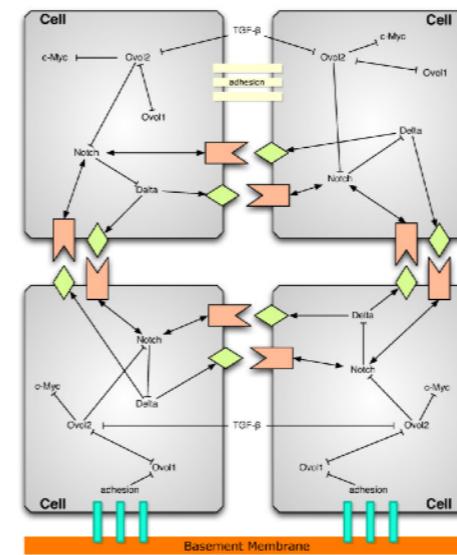


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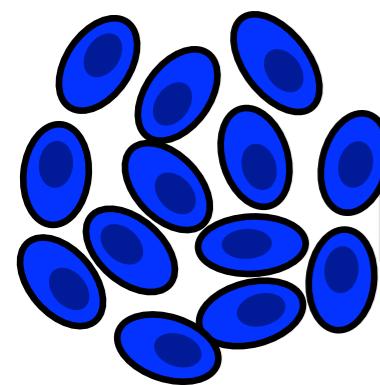
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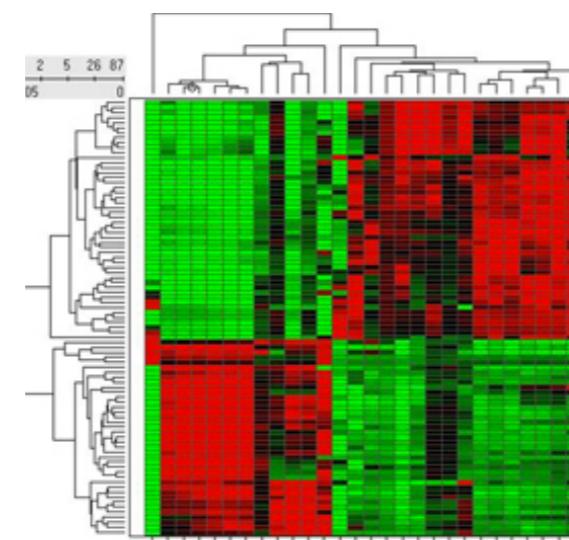


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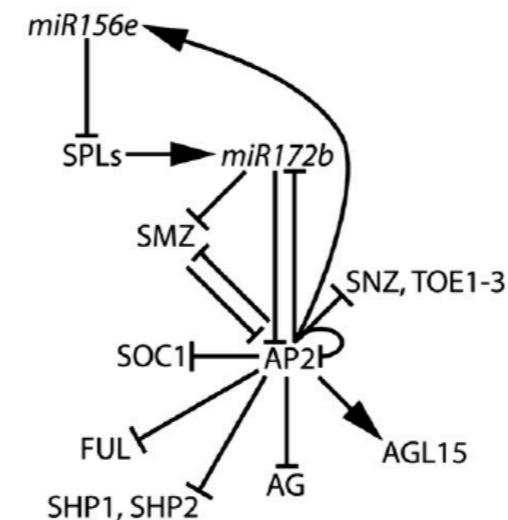
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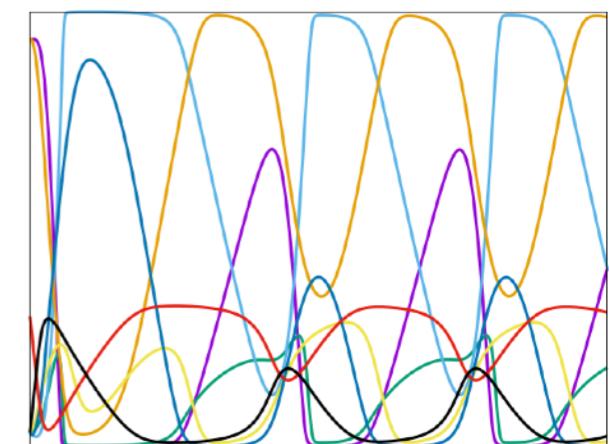
Omics



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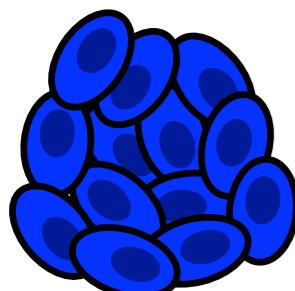
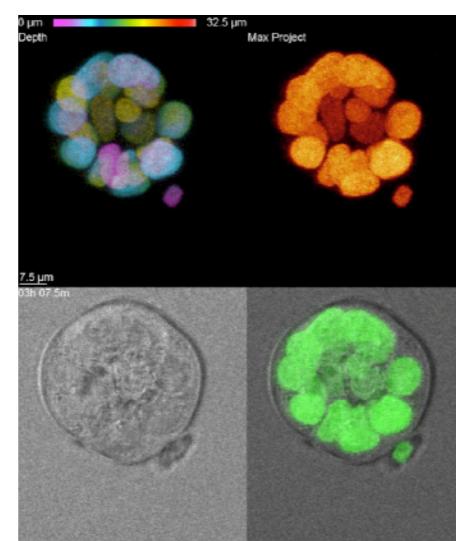
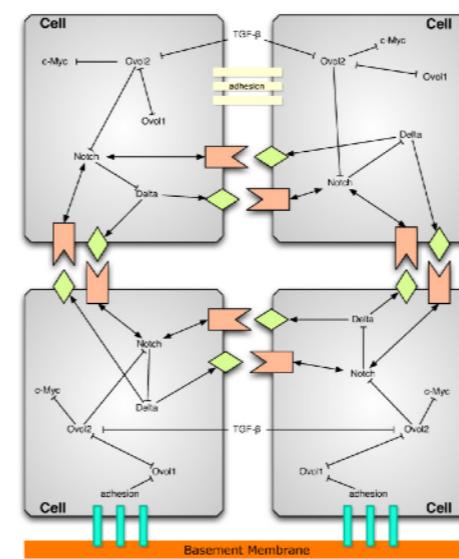


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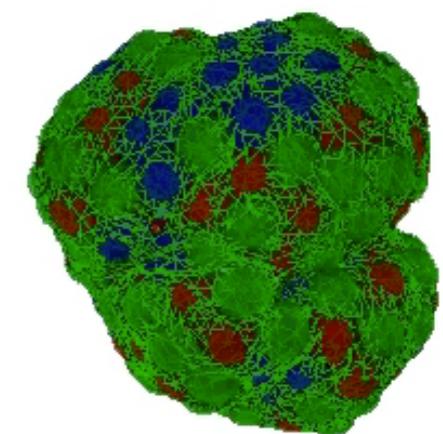


Drost et al., 2015

Intercellular network



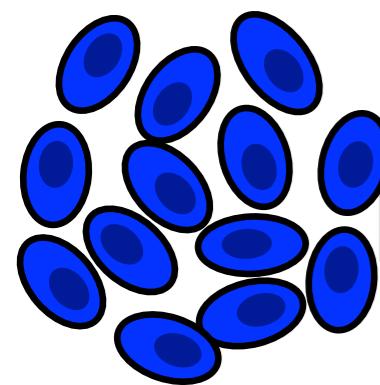
Multicellular simulation



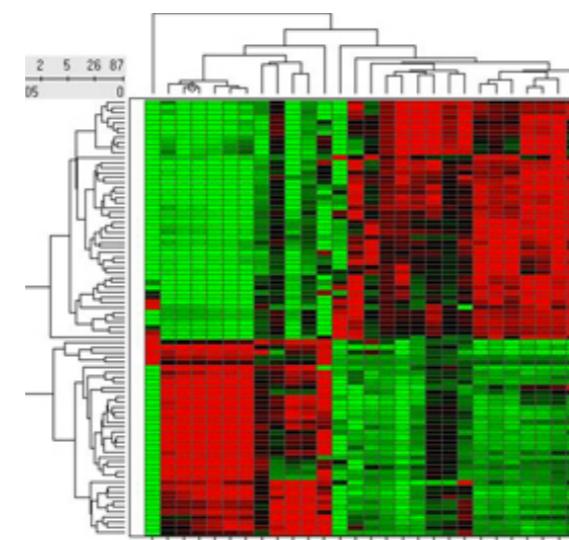
Buske et al., 2012

From SysBio to Multicellular SysBio

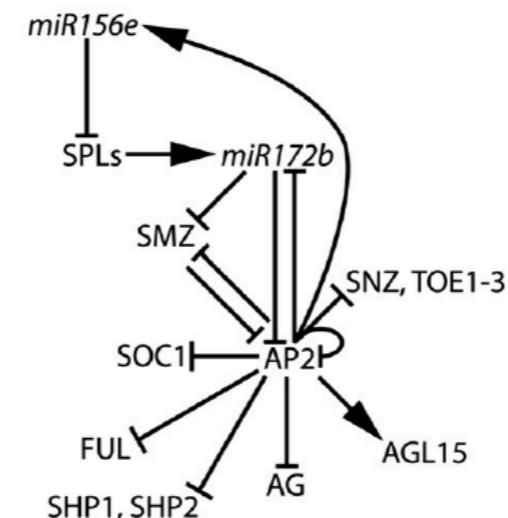
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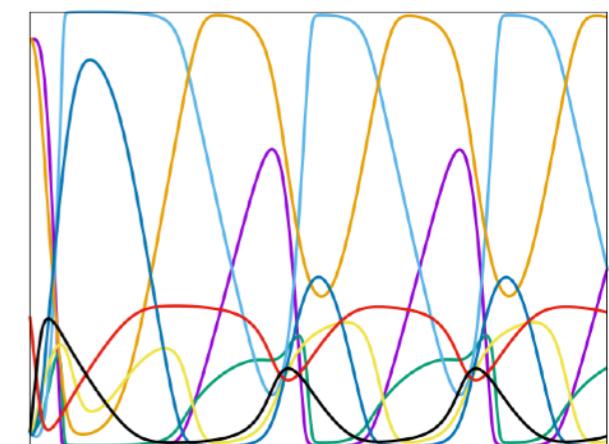
Omics



Intracellular network



Dynamic simulation



Tissue

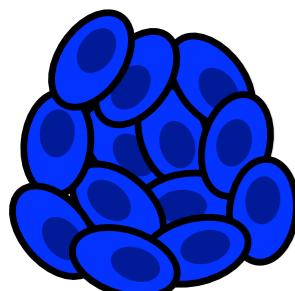
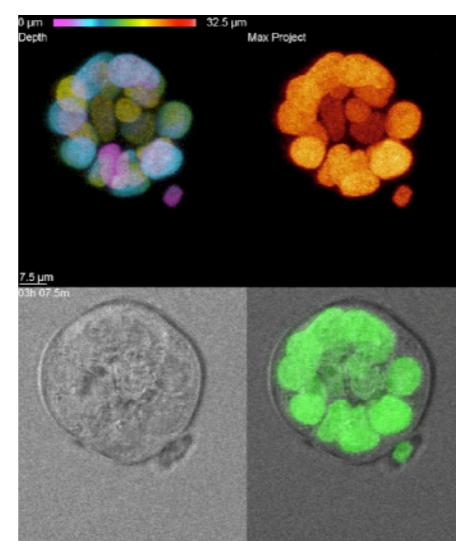
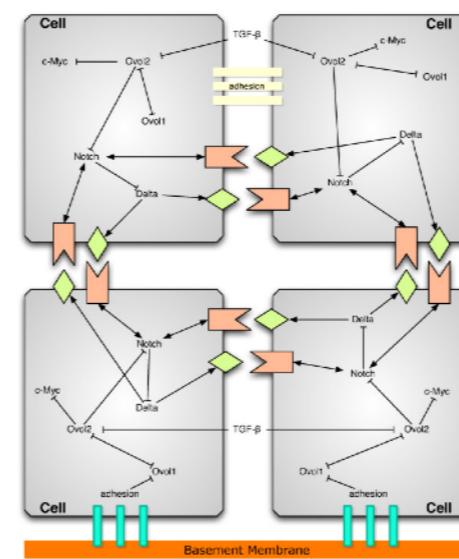


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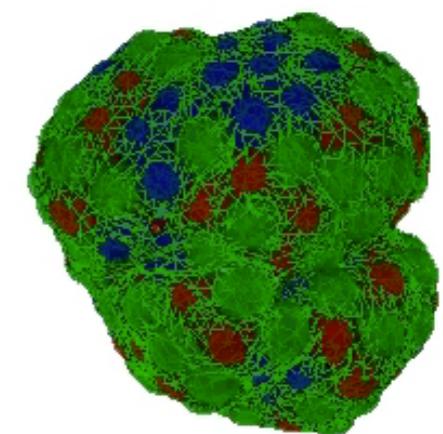


Drost et al., 2015

Intercellular network

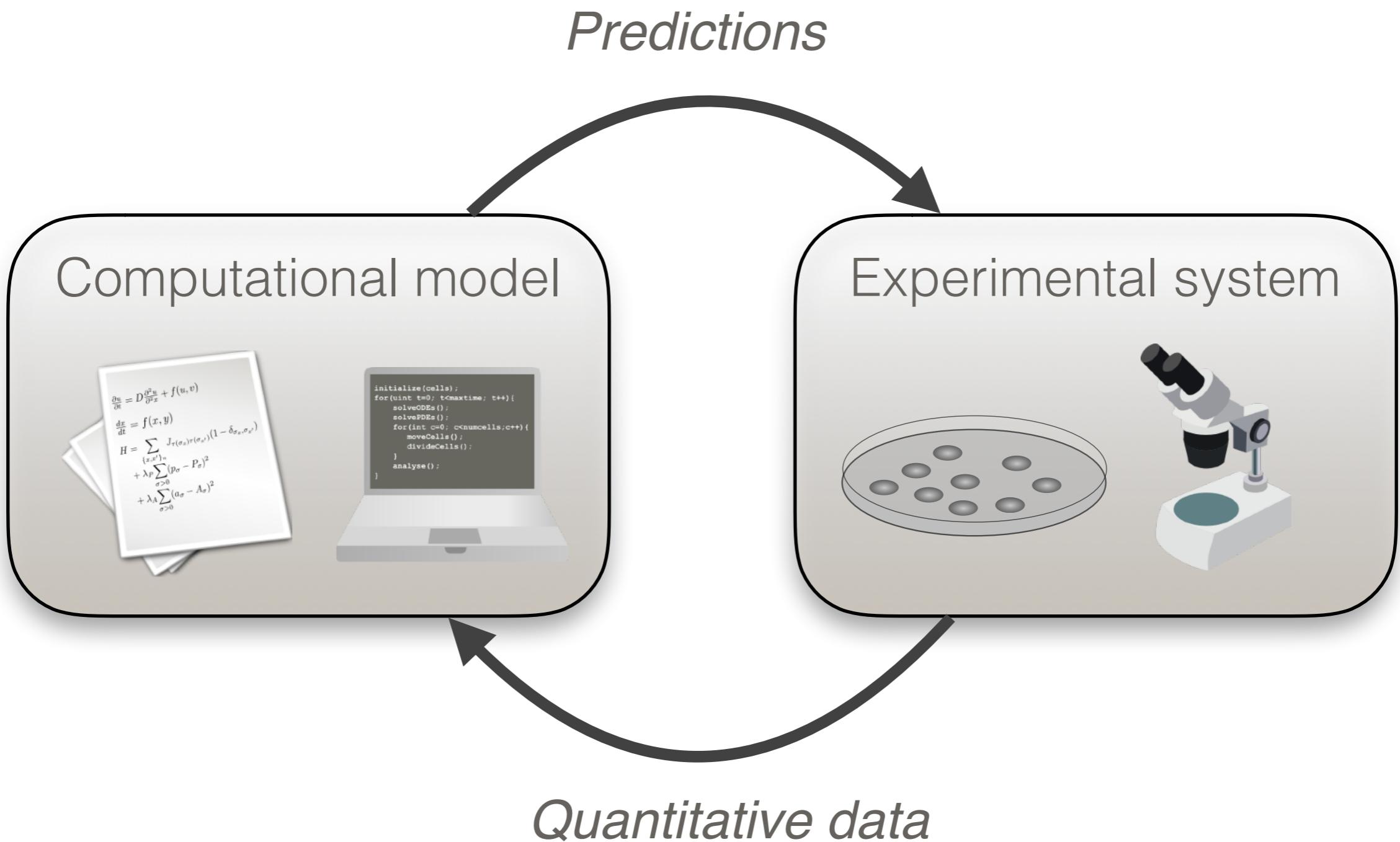


Multicellular simulation



Buske et al., 2012

Systems biology cycle



Content

- ▶ Cell-based modelling
 - ▶ Modeling approaches
 - ▶ Multi-scale modeling
 - ▶ subitem subitem subitem
- ▶ Item
 - ▶ subitem
 - ▶ subitem
 - ▶ subitem
- ▶ Morpheus
 - ▶ Platform for multi-scale multicellular modeling

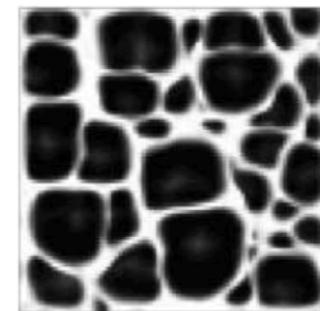
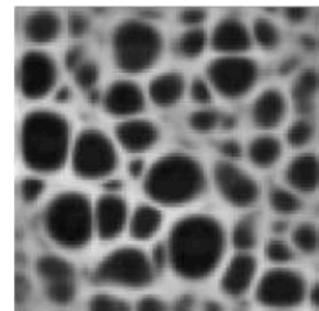
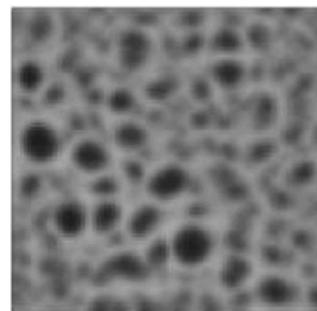


Doe et al., 2017.

Modeling approaches *for tissue modeling*

Tissue modeling: continuous approach

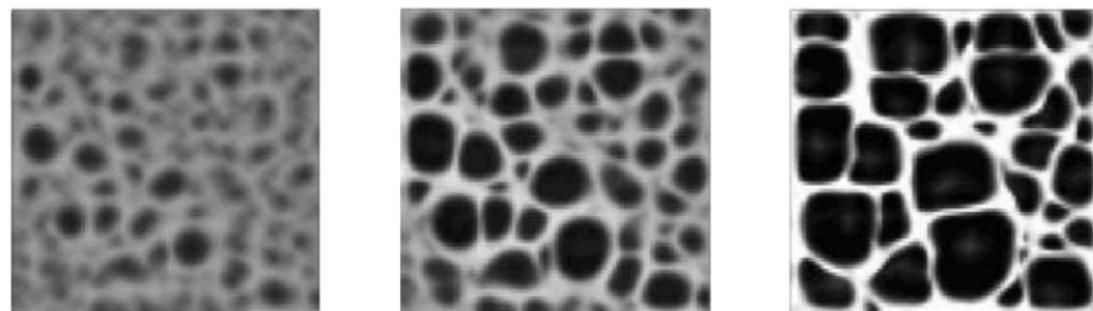
Vascular patterning



Manoussaki et al., 1996

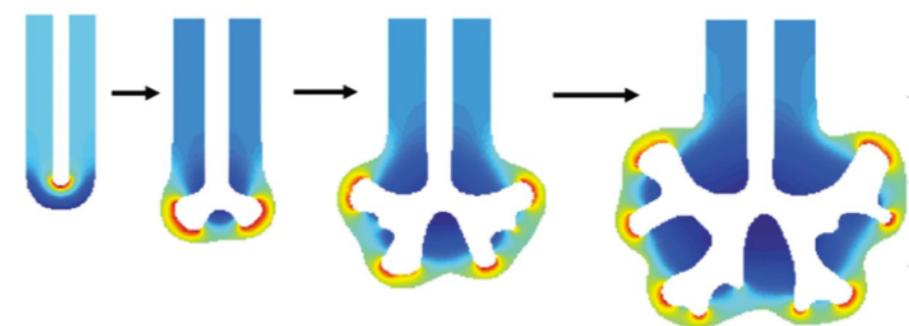
Tissue modeling: continuous approach

Vascular patterning



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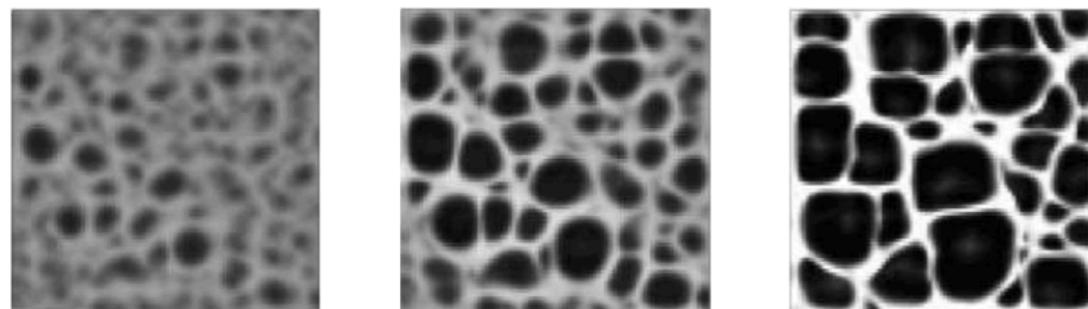
Branching morphogenesis



Iber et al., 2013

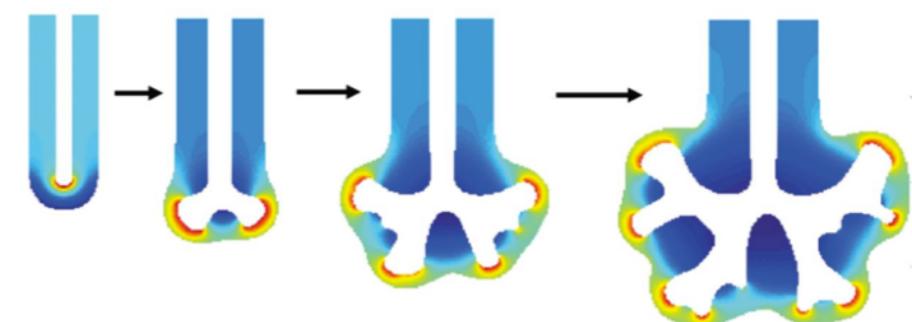
Tissue modeling: continuous approach

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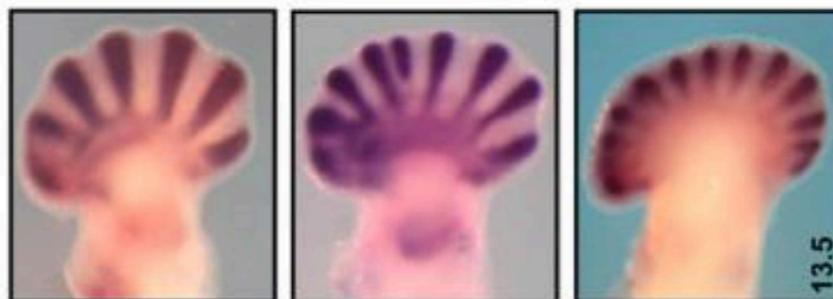
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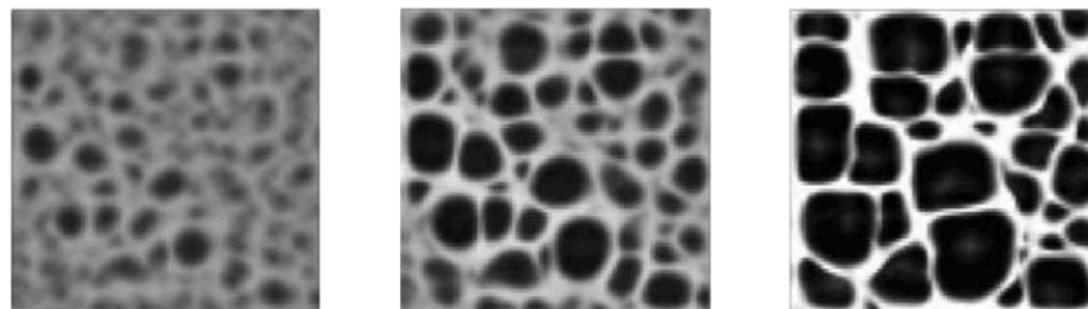
Limb morphogenesis



Sheth et al., 2012

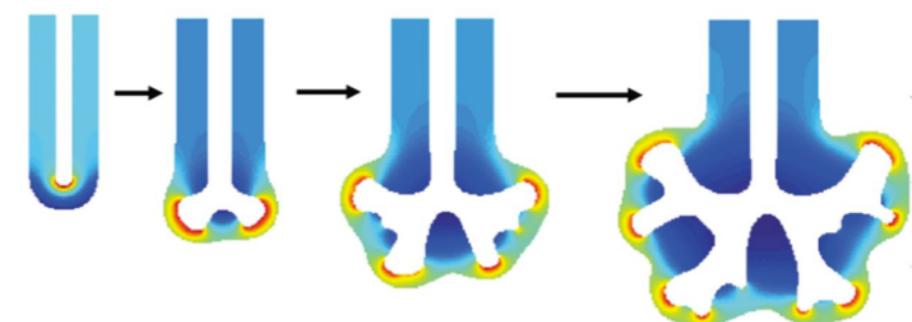
Tissue modeling: continuous approach

Vascular patterning



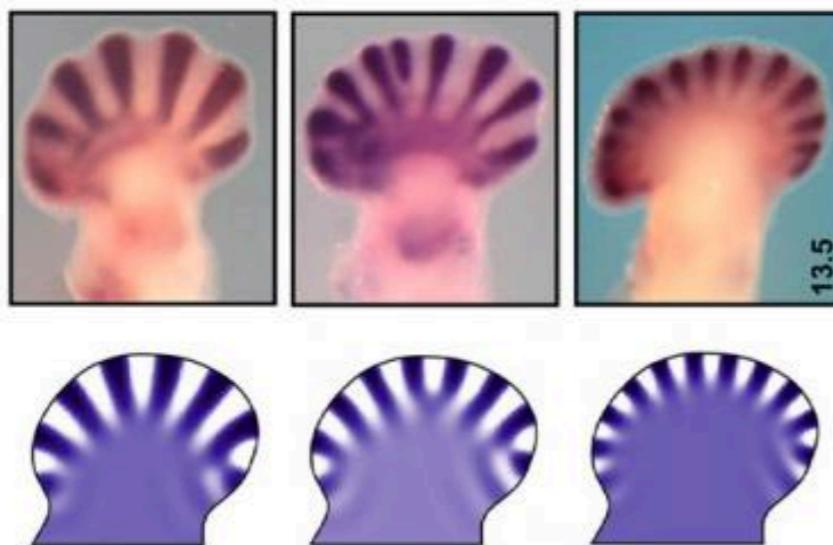
Manoussaki et al., 1996

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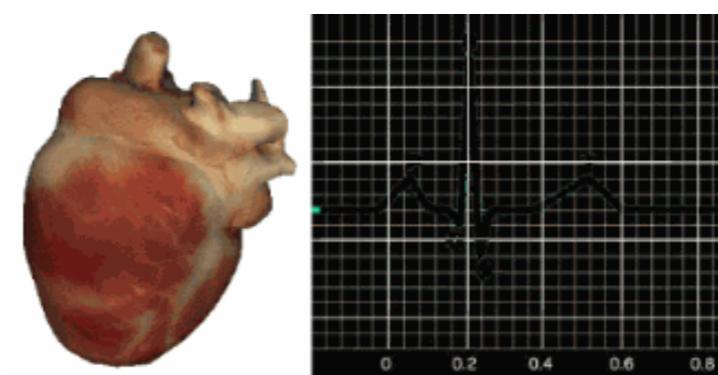
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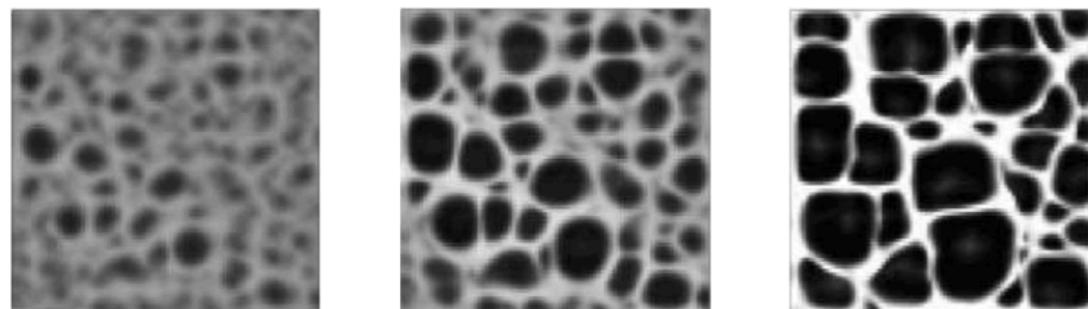
Cardiac physiology



Fenton et al., 2008

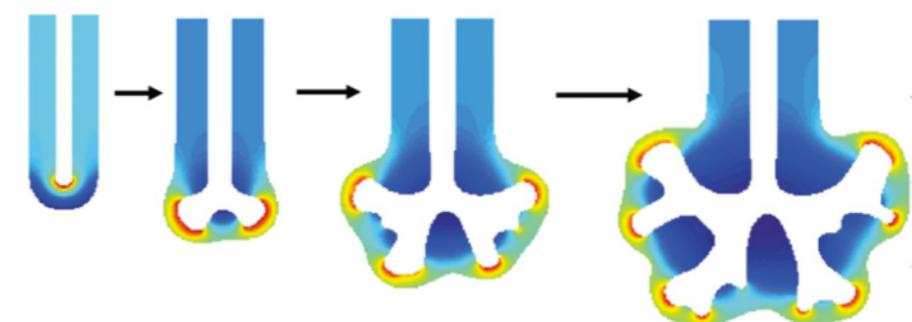
Tissue modeling: continuous approach

Vascular patterning



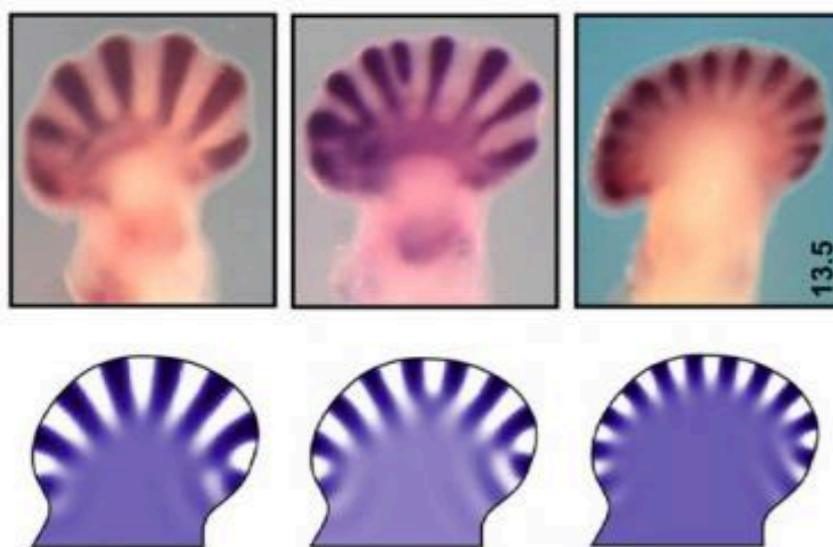
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Branching morphogenesis



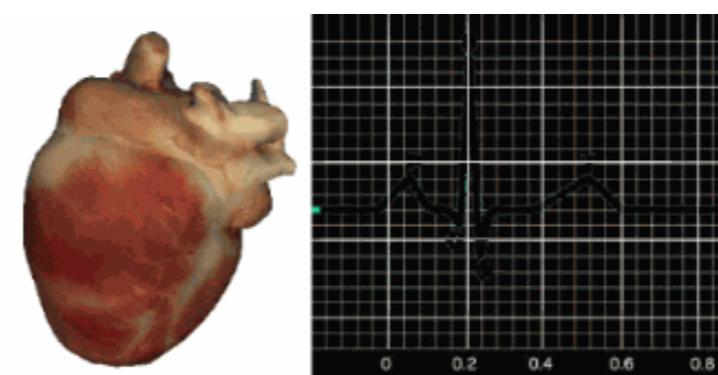
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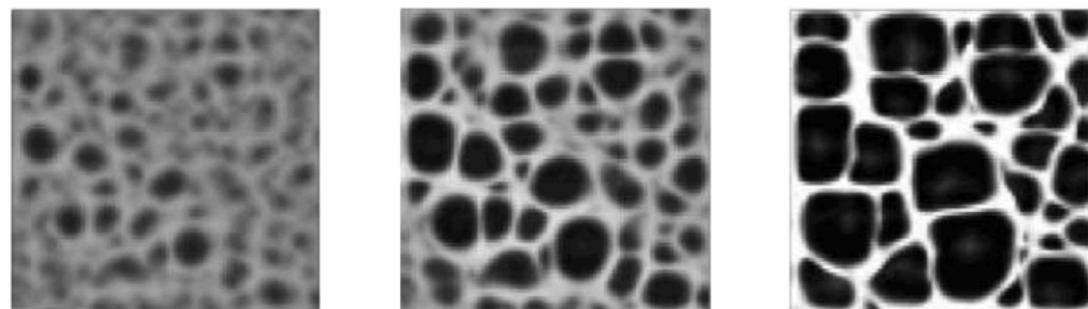
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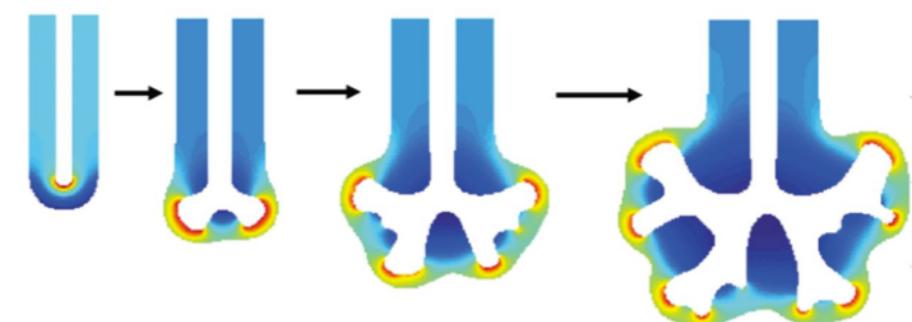
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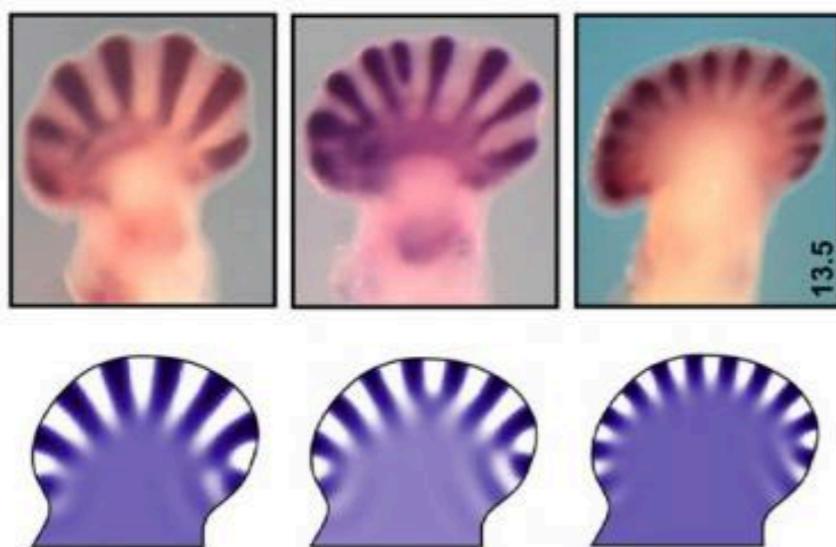
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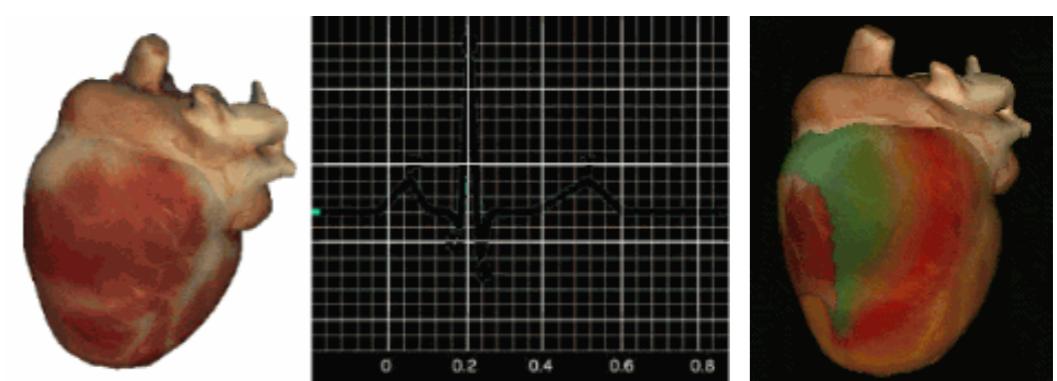
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Fenton et al., 2008

Tissue modeling: discrete approach

Tissue modeling: discrete approach

- ▶ Tissue organization
 - ▶ spatial structure

Tissue modeling: discrete approach

- ▶ Tissue organization

- ▶ spatial structure

- ▶ Cellular behavior

- ▶ cell motility
 - ▶ cell division
 - ▶ cell adhesion
 - ▶ cell shape
 - ▶ etc.

Tissue modeling: discrete approach

- ▶ Tissue organization
 - ▶ spatial structure
- ▶ Cellular behavior
 - ▶ cell motility
 - ▶ cell division
 - ▶ cell adhesion
 - ▶ cell shape
 - ▶ etc.
- ▶ Multi-scale coupling
 - ▶ intracellular processes
 - ▶ extracellular gradients

Tissue modeling: discrete approach

- ▶ Tissue organization
 - ▶ spatial structure
- ▶ Cellular behavior
 - ▶ cell motility
 - ▶ cell division
 - ▶ cell adhesion
 - ▶ cell shape
 - ▶ etc.
- ▶ Small population size
 - ▶ stochasticity
- ▶ Multi-scale coupling
 - ▶ intracellular processes
 - ▶ extracellular gradients

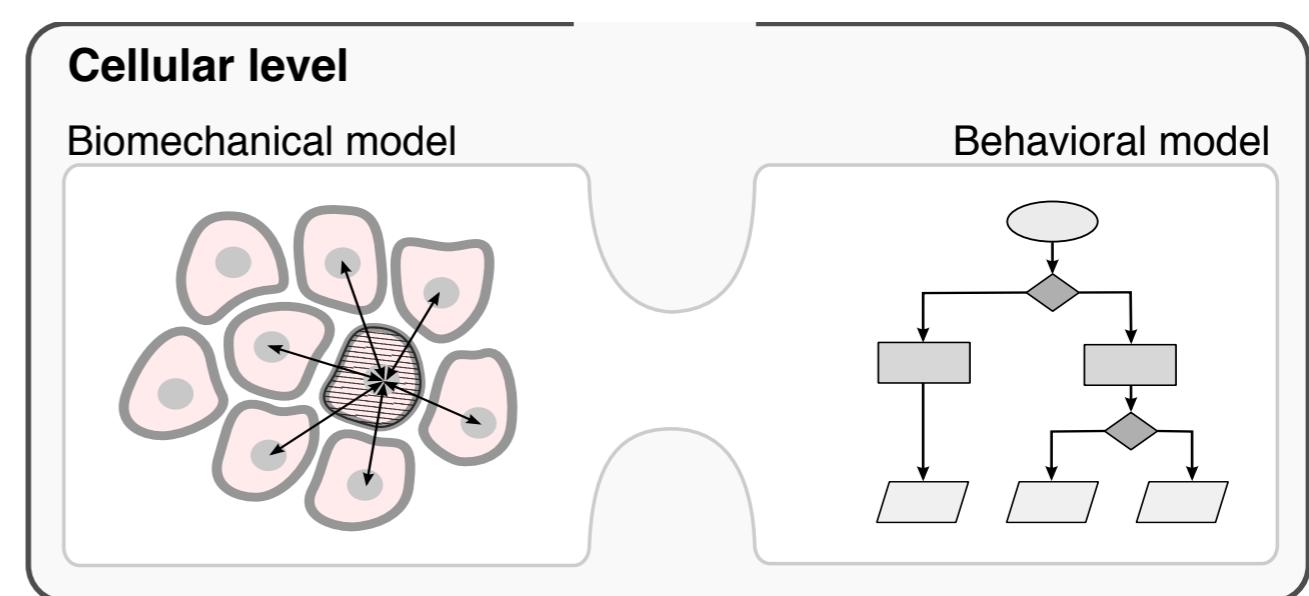
Cell-based modeling

- ▶ Tissue organization
 - ▶ spatial structure

- ▶ Cellular behavior
 - ▶ cell motility
 - ▶ cell division
 - ▶ cell adhesion
 - ▶ cell shape
 - ▶ etc.

- ▶ Small population size
 - ▶ stochasticity

- ▶ Multi-scale coupling
 - ▶ intracellular processes
 - ▶ extracellular gradients



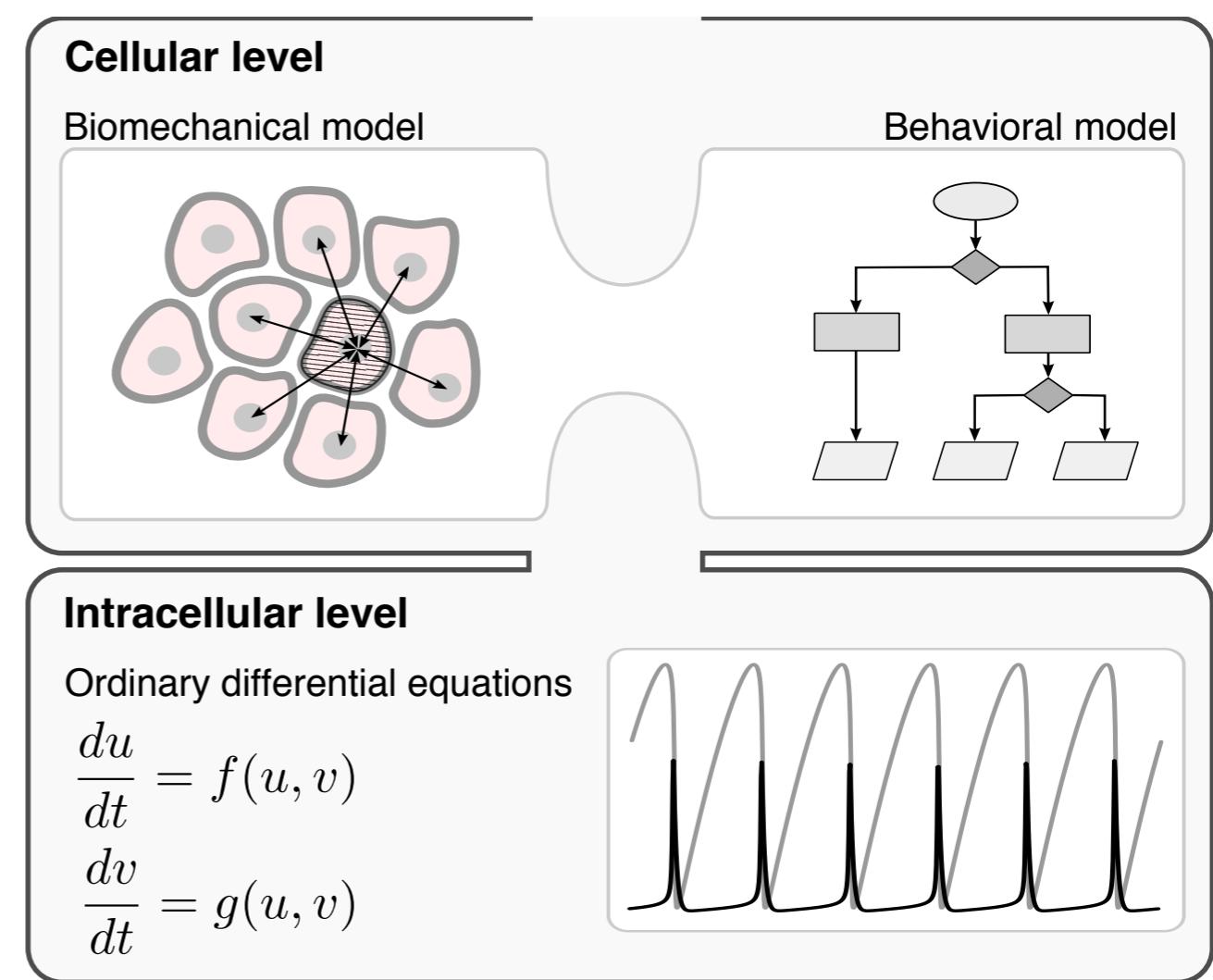
Multi-scale cell-based modeling

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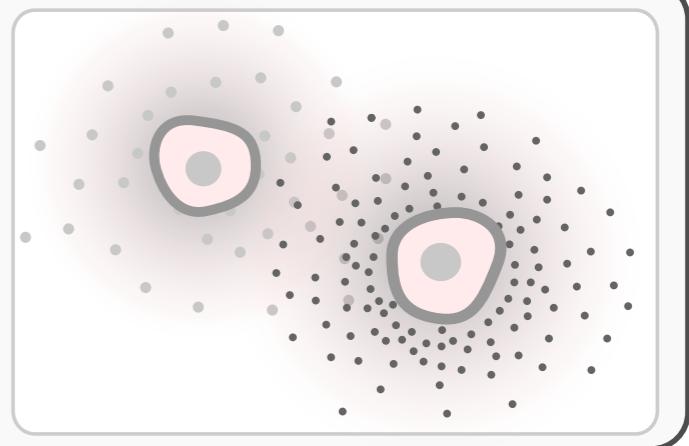
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Extracellular level

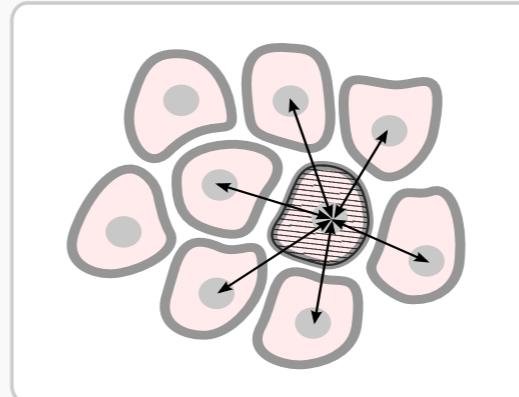
Reaction-diffusion equations

$$\frac{\partial u}{\partial t} = D_u \nabla^2 u + f(u, v)$$
$$\frac{\partial v}{\partial t} = D_v \nabla^2 v + g(u, v)$$

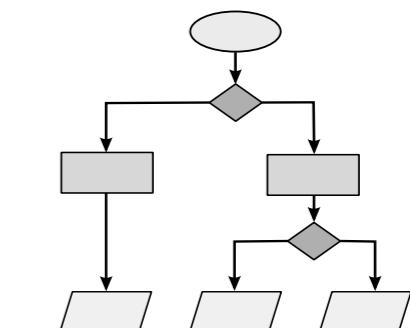


Cellular level

Biomechanical model



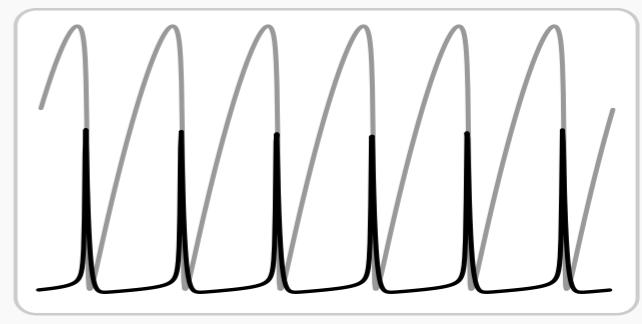
Behavioral model



Intracellular level

Ordinary differential equations

$$\frac{du}{dt} = f(u, v)$$
$$\frac{dv}{dt} = g(u, v)$$



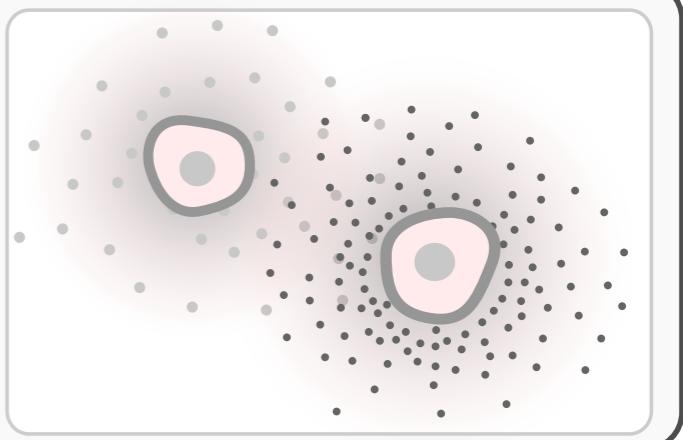
Middle-out multi-scale cell-based modeling

- ▶ Tissue organization
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- ▶ Cellular behavior
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 - ▶ cell adhesion
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Extracellular level

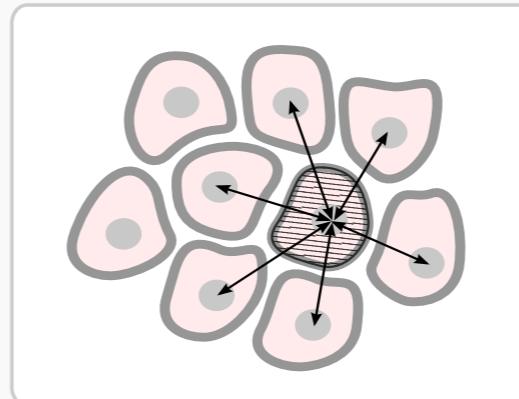
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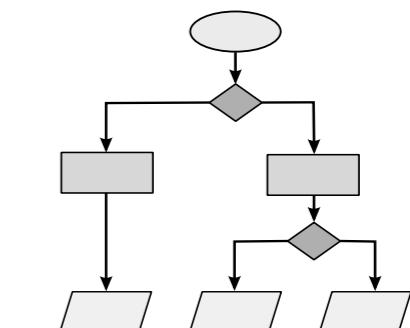


Cellular level

Biomechanical model



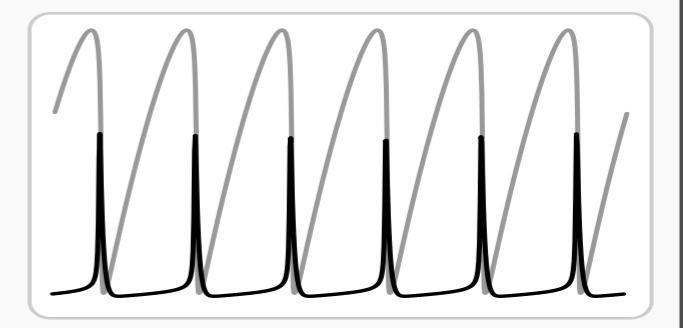
Behavioral model



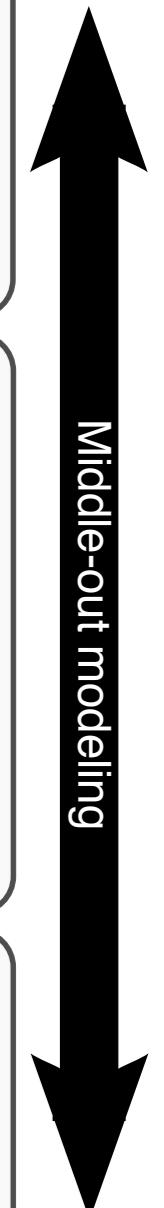
Intracellular level

Ordinary differential equations

$$\frac{du}{dt} = f(u, v)$$
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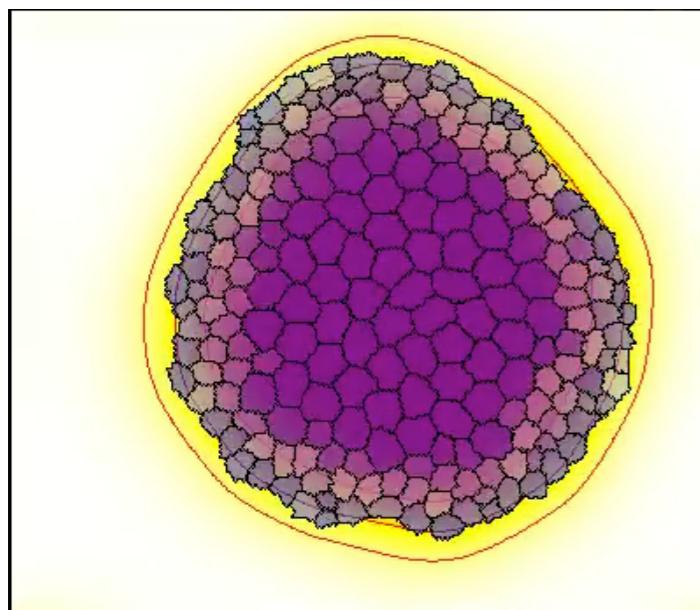


Middle-out modeling

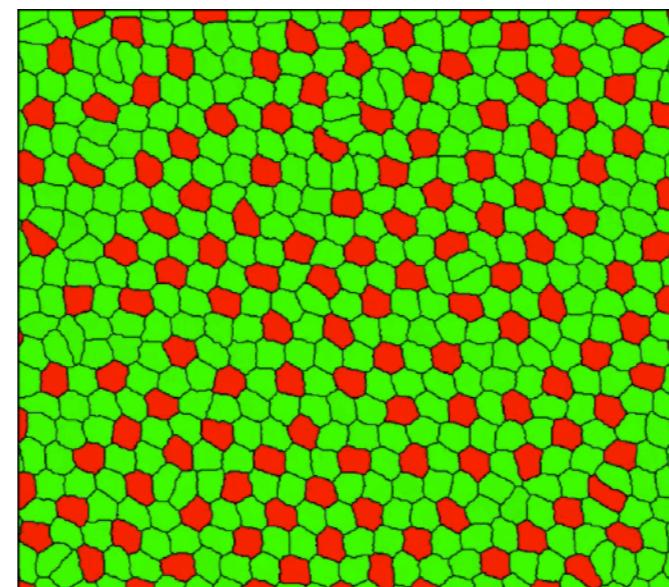


Some examples....

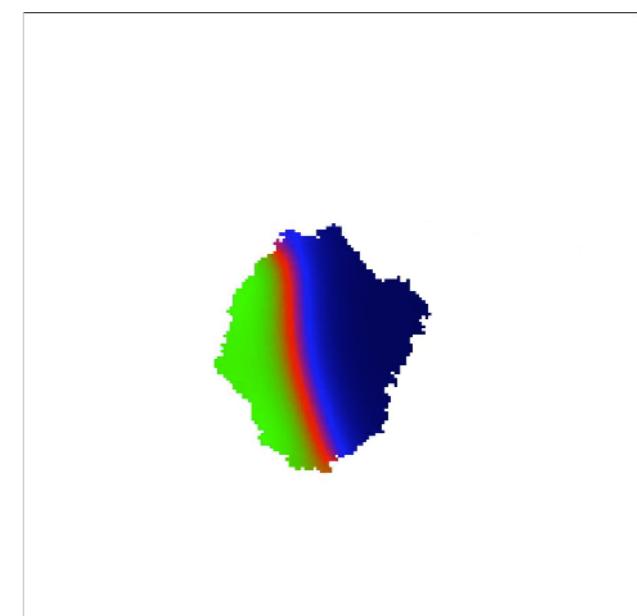
Tissue growth



Lateral inhibition

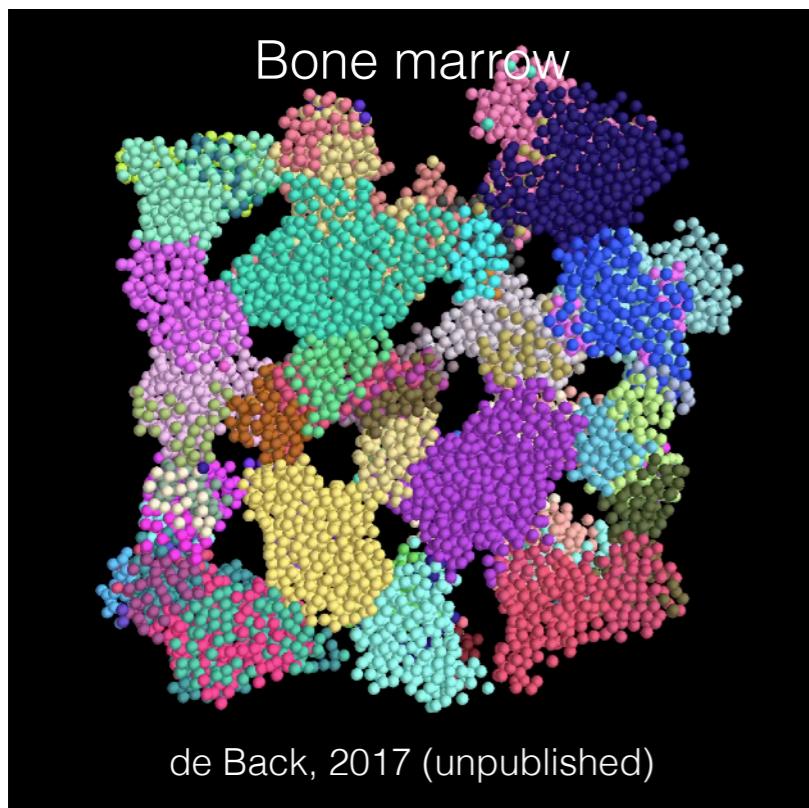


Single cell migration



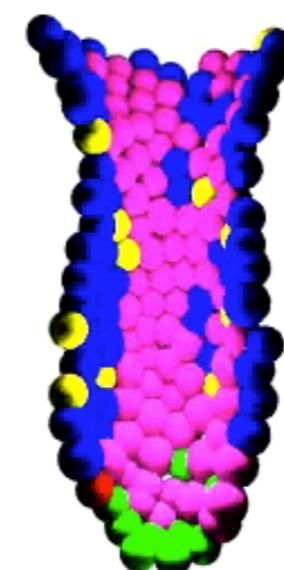
After Maree et al., 2012

Bone marrow



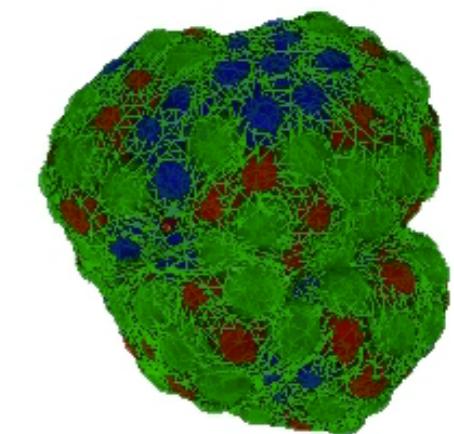
de Back, 2017 (unpublished)

Intestinal crypt



Buske et al., 2011

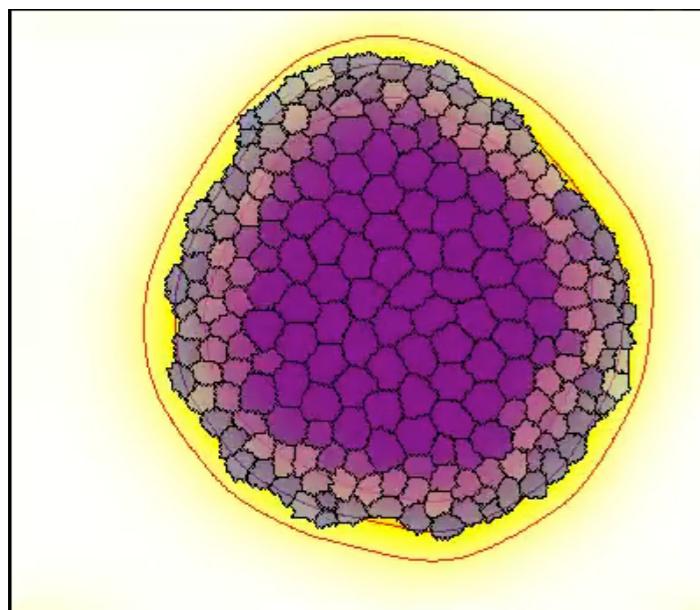
Organoid



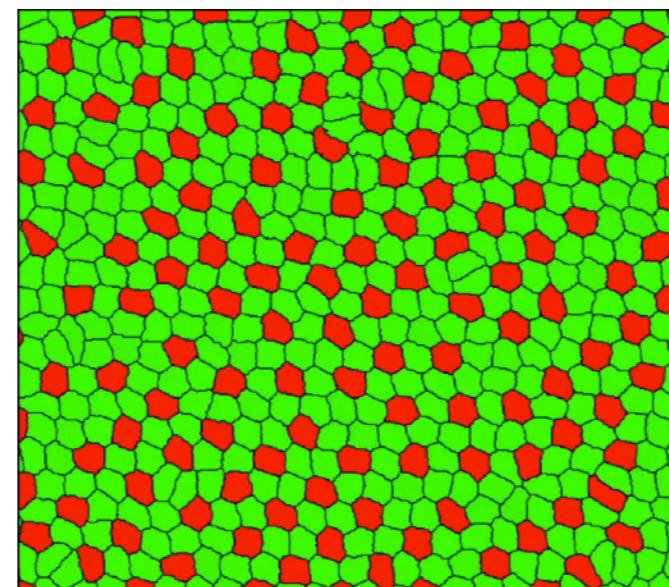
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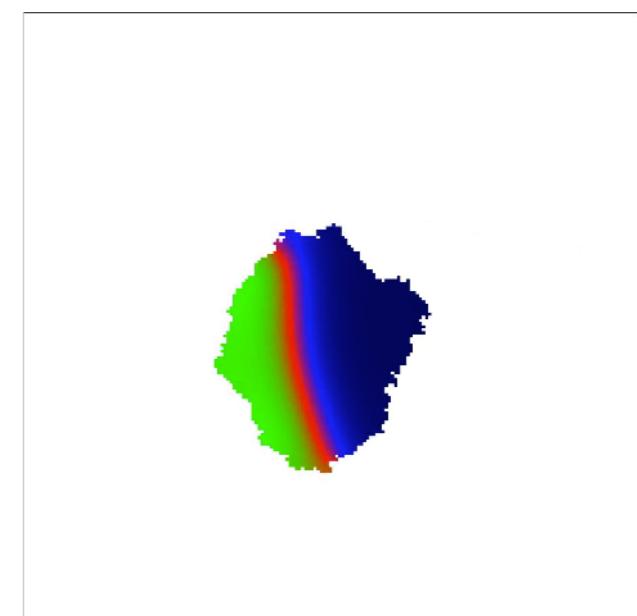
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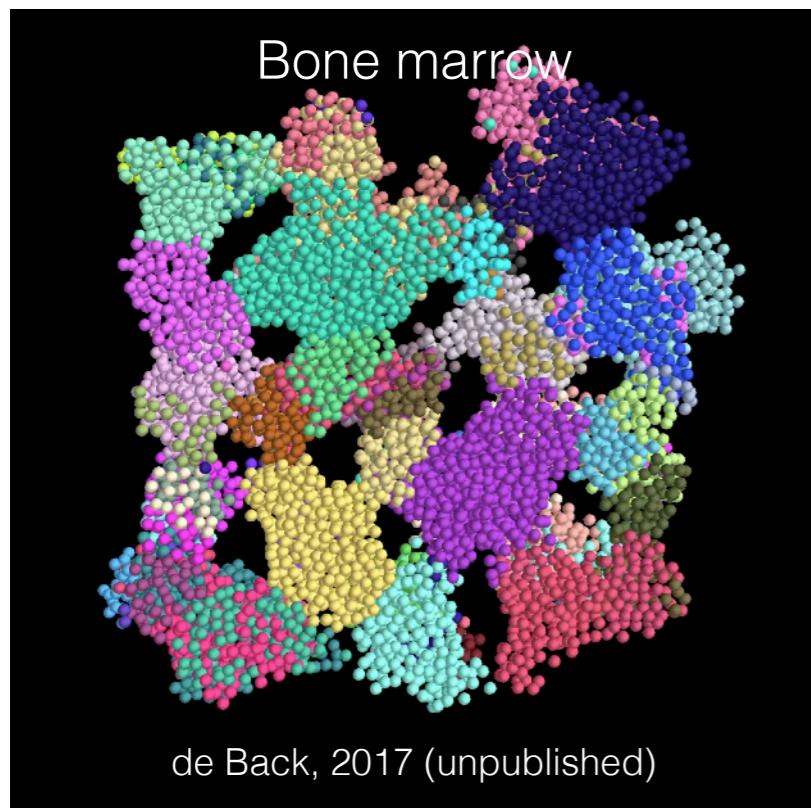


Single cell migration



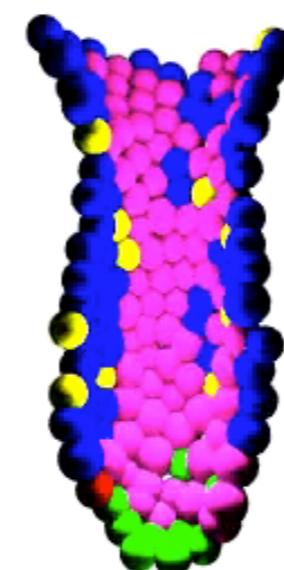
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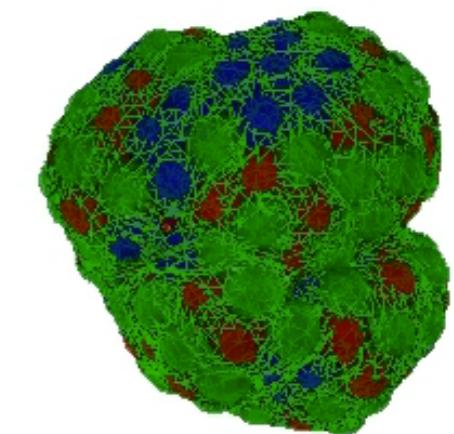
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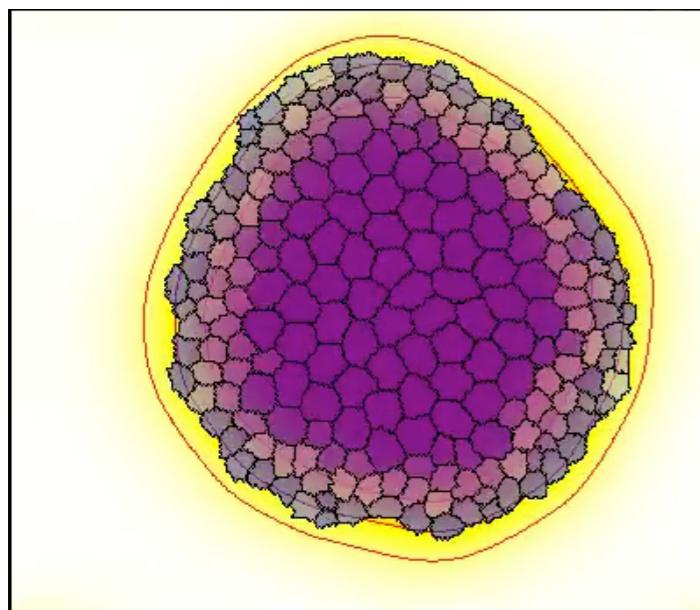
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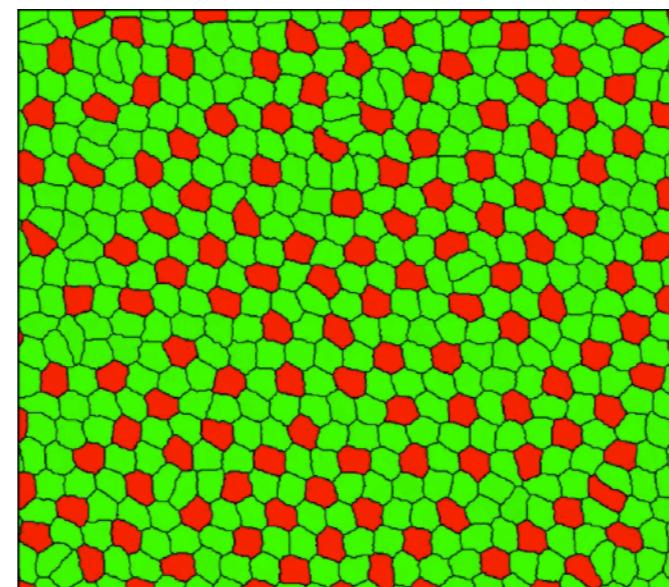
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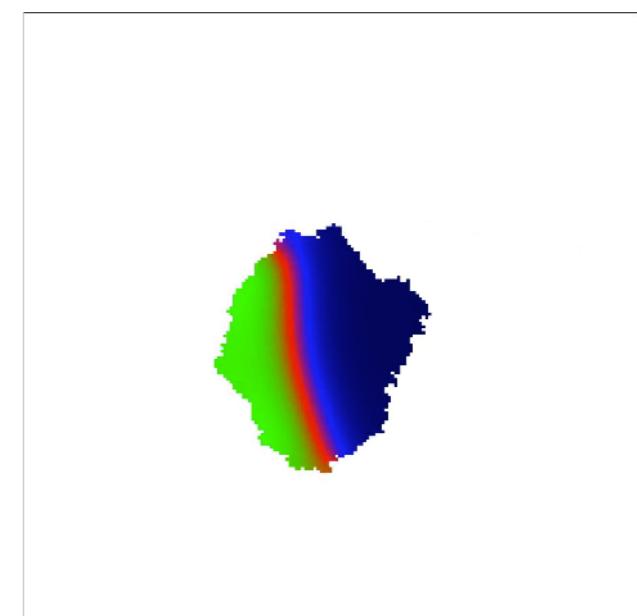
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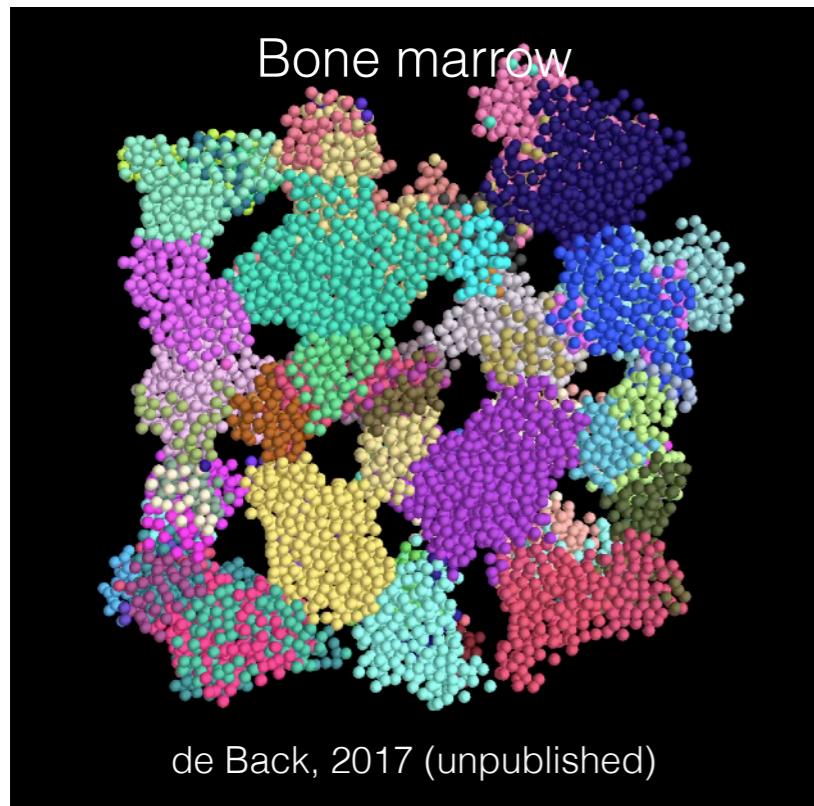


Single cell migration



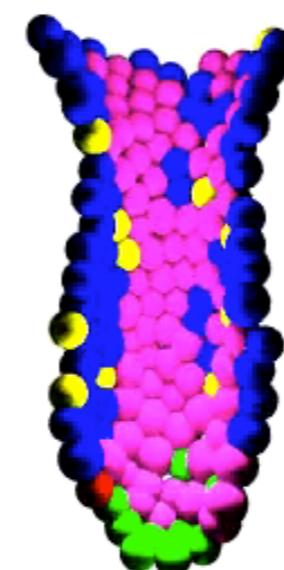
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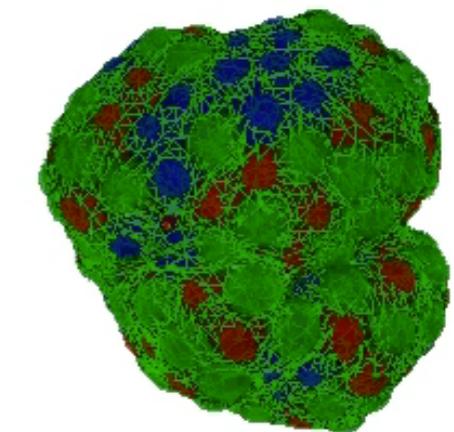
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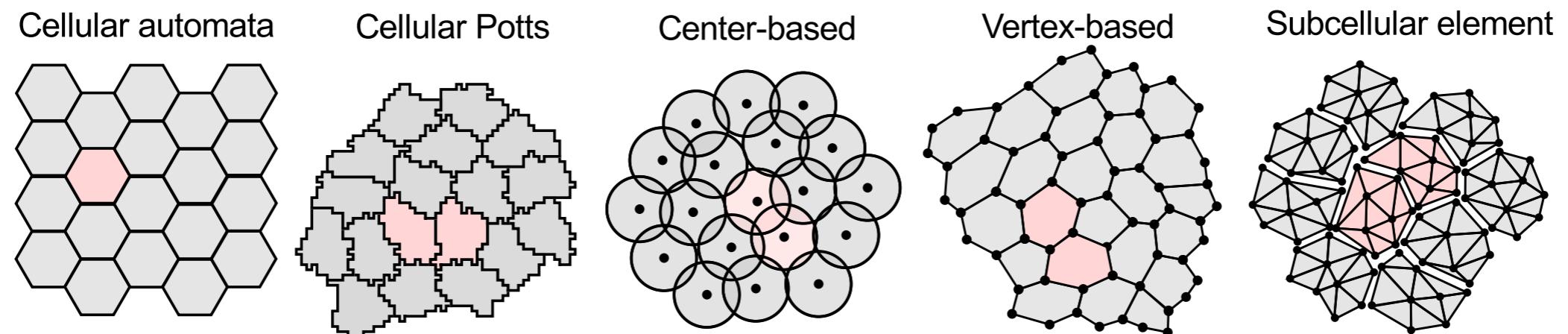
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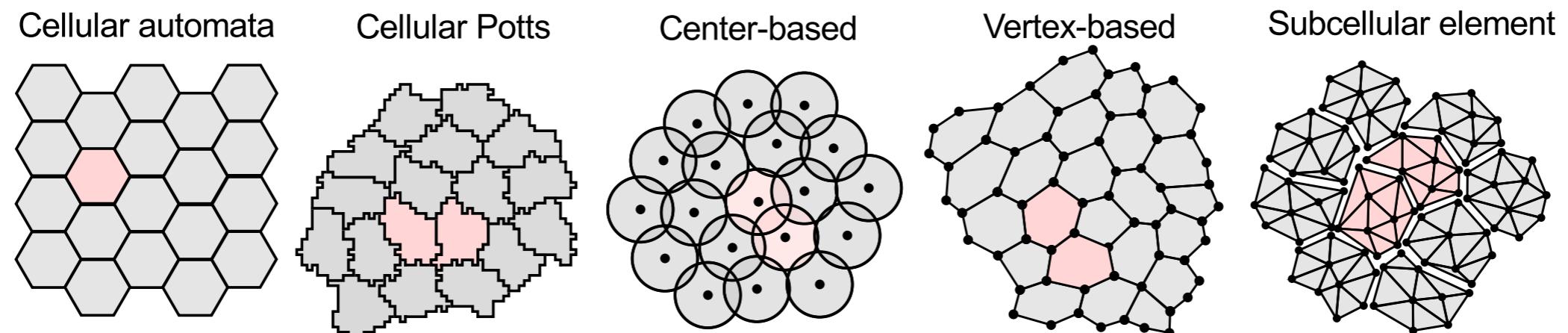
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Computational methods *for cell-based modeling*

Different cell-based modeling approaches



Different cell-based modeling approaches

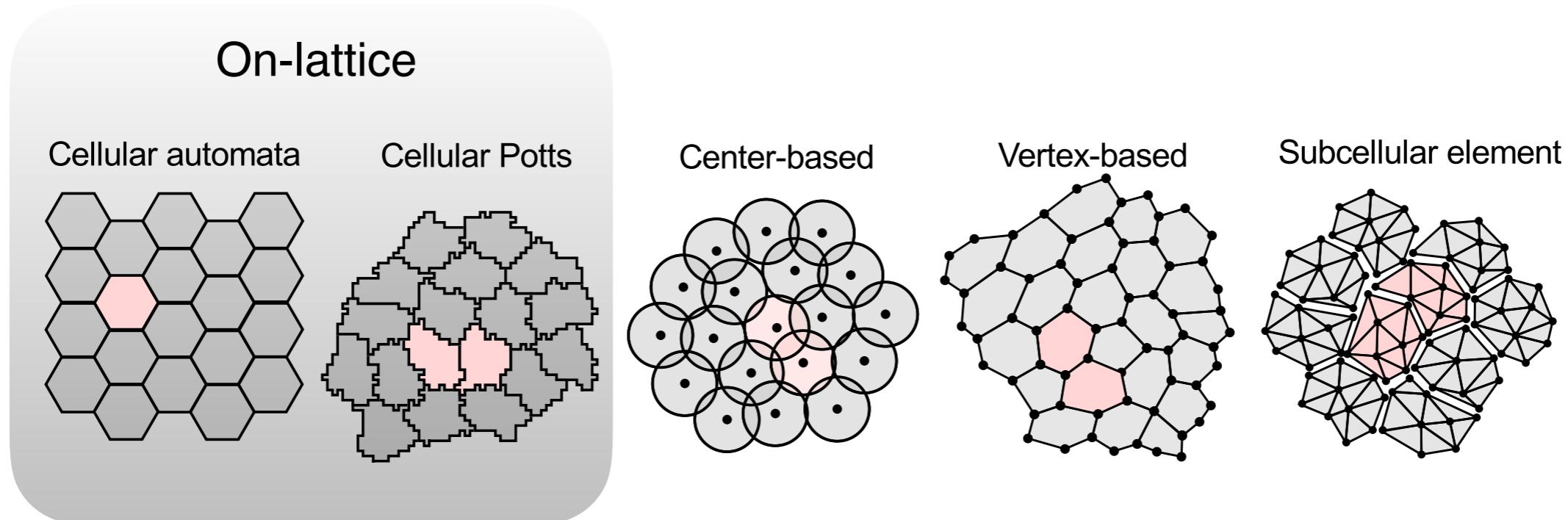


How are cell spatially represented?

On-lattice

Off-lattice

Different cell-based modeling approaches

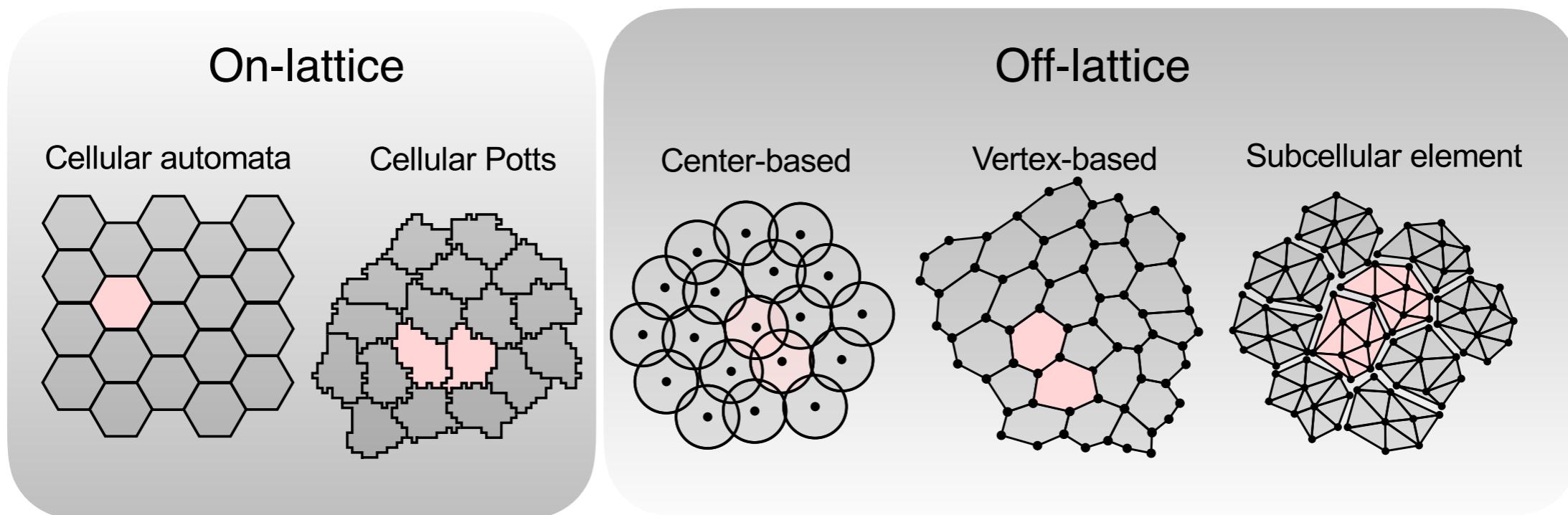


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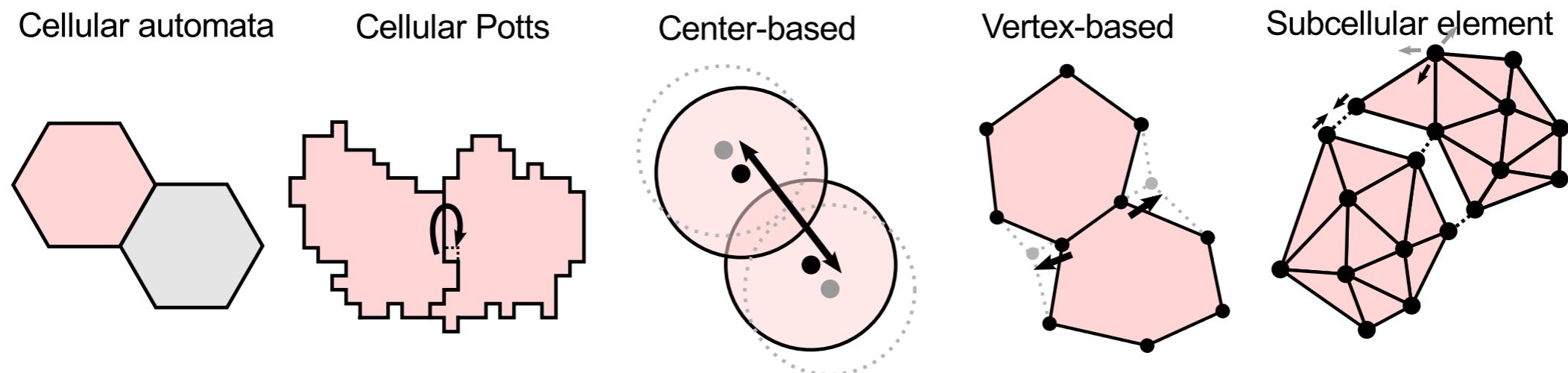


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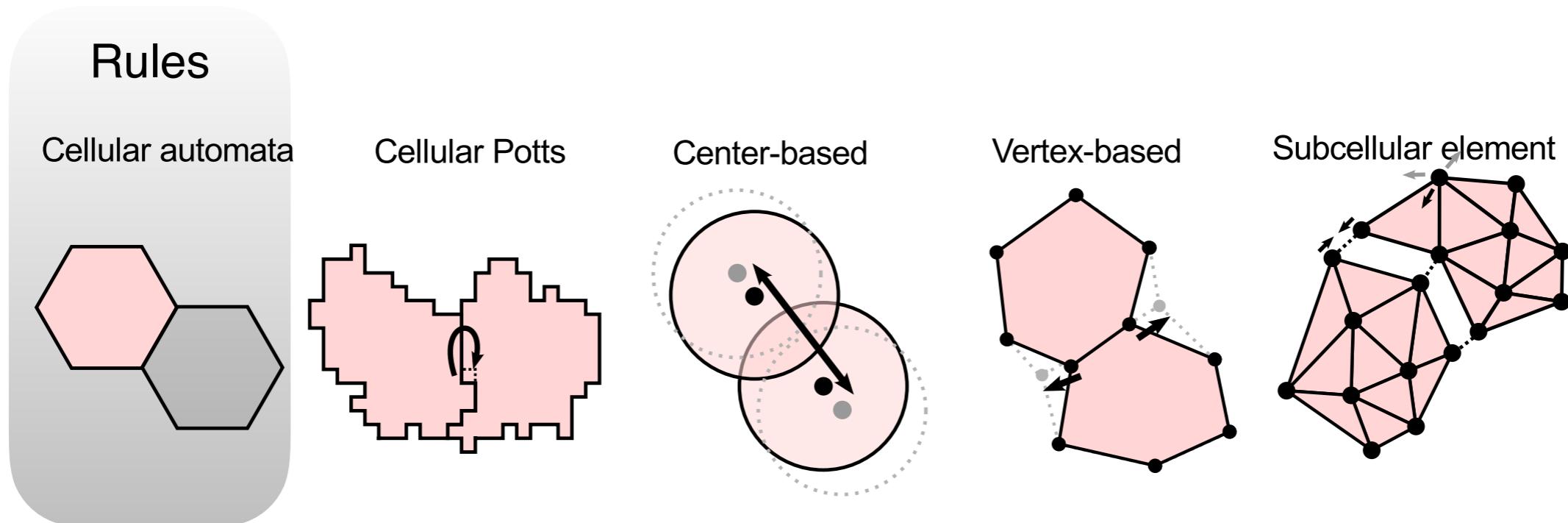
How is cell motility modelled?

Rule-based

Energy-based

Force-based

Different cell-based modeling approaches



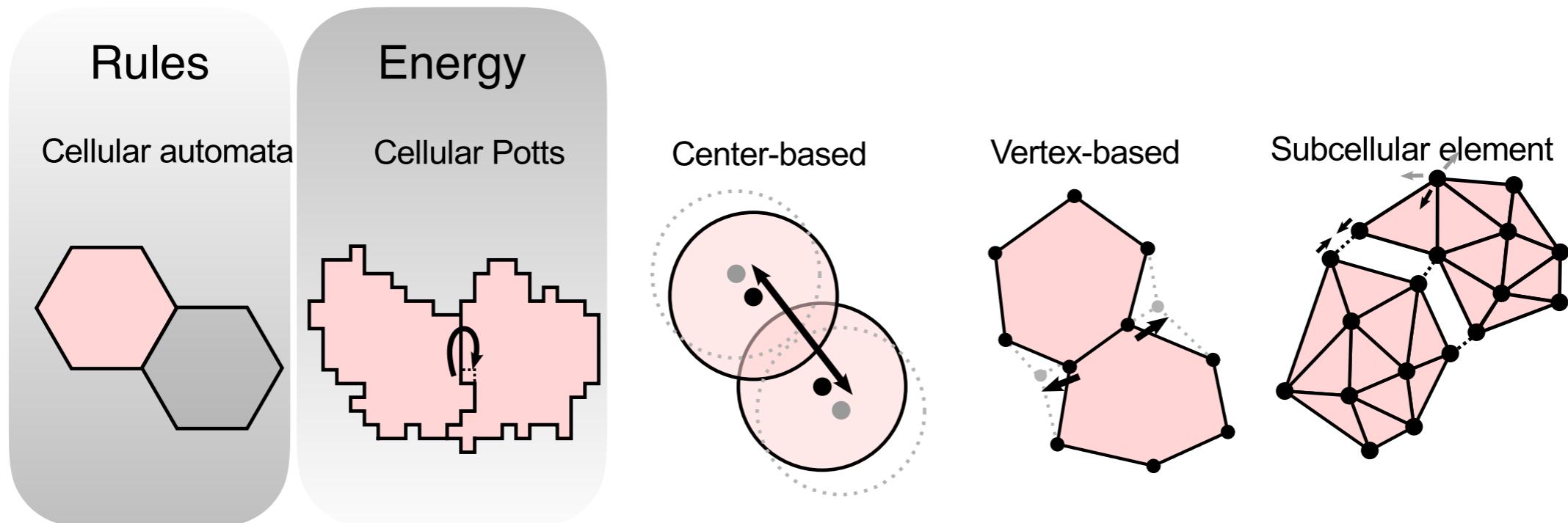
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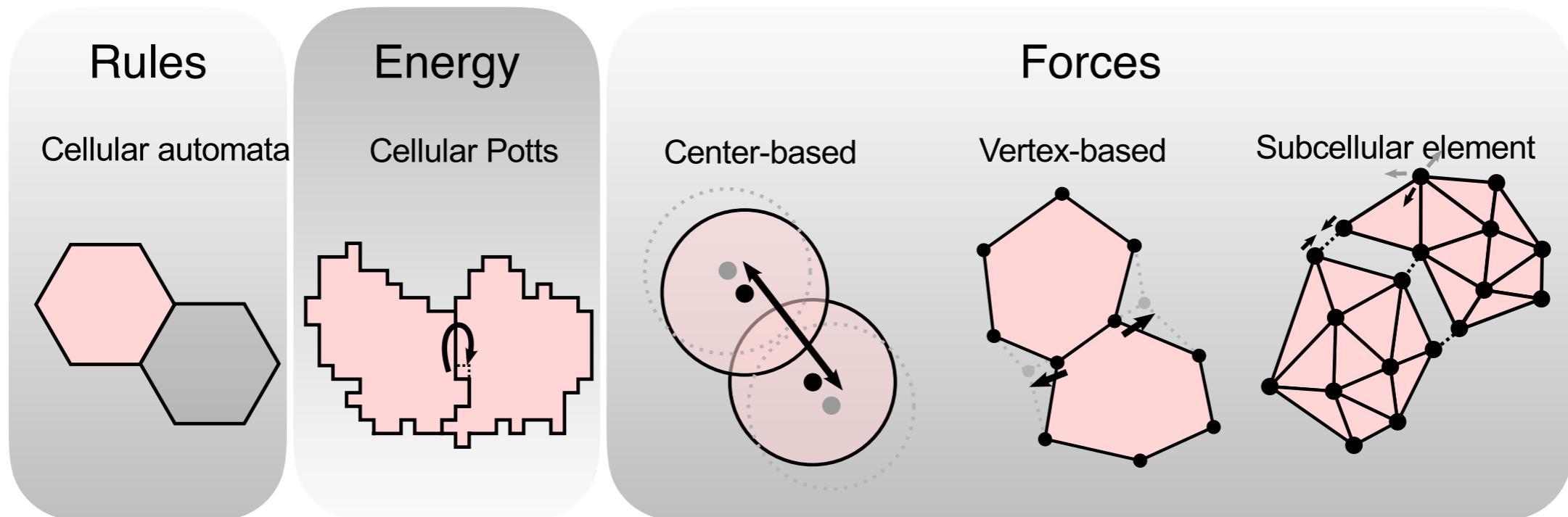
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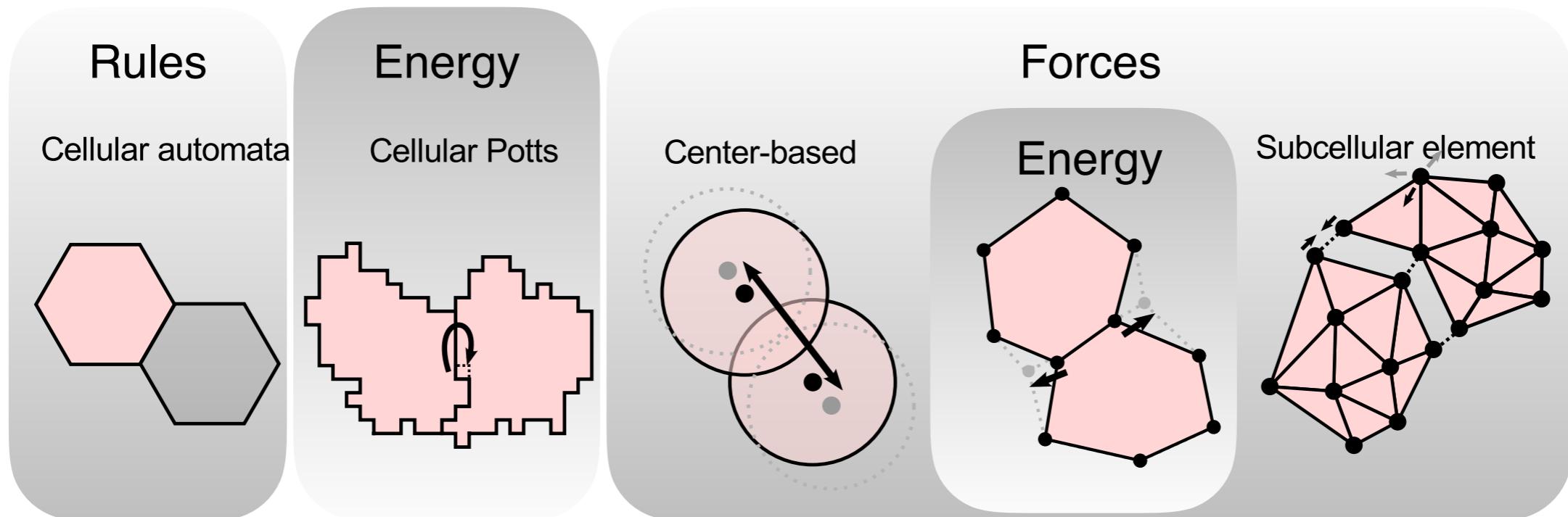
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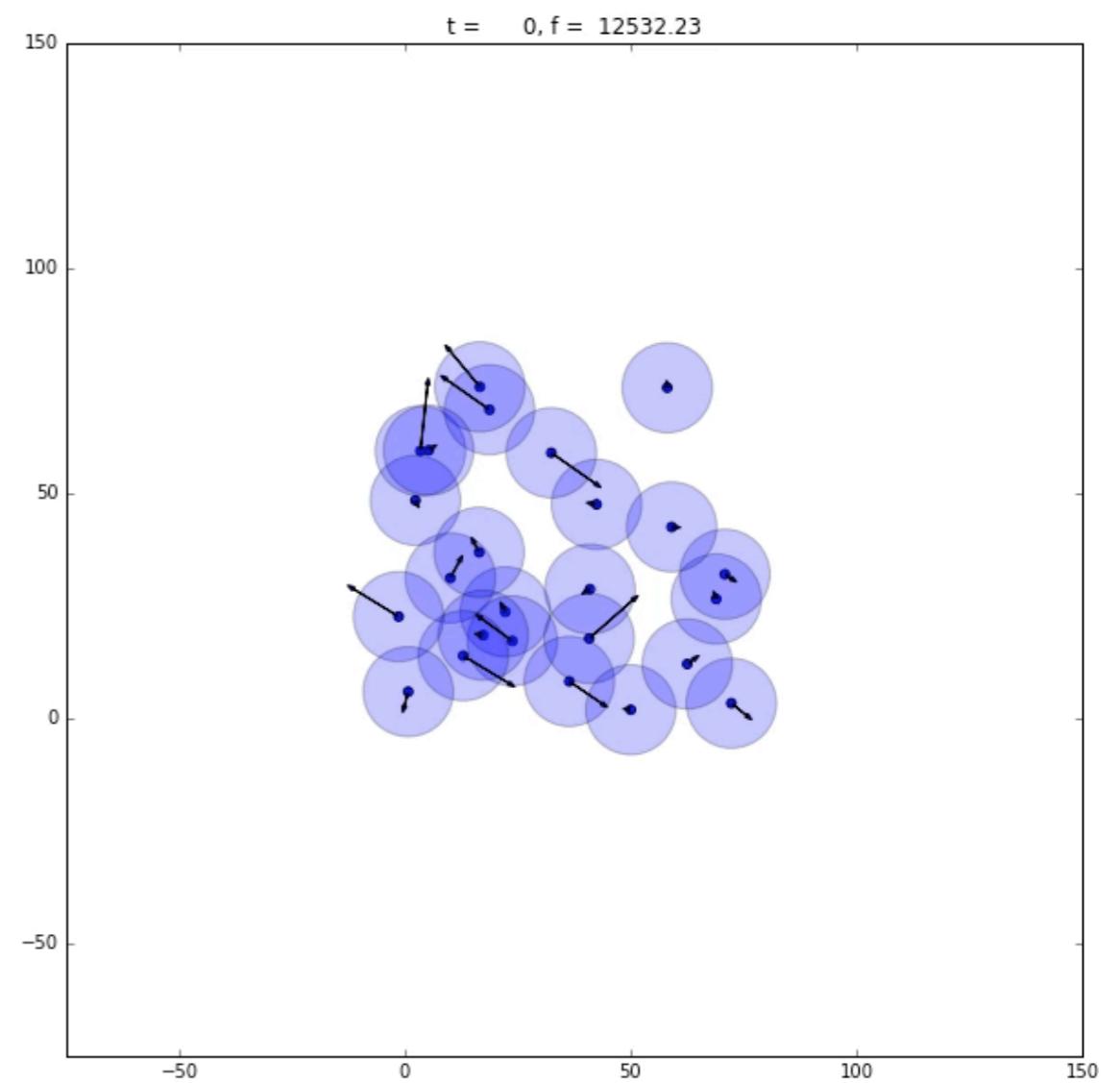
Force-based

Center-based model

Overlapping spheres

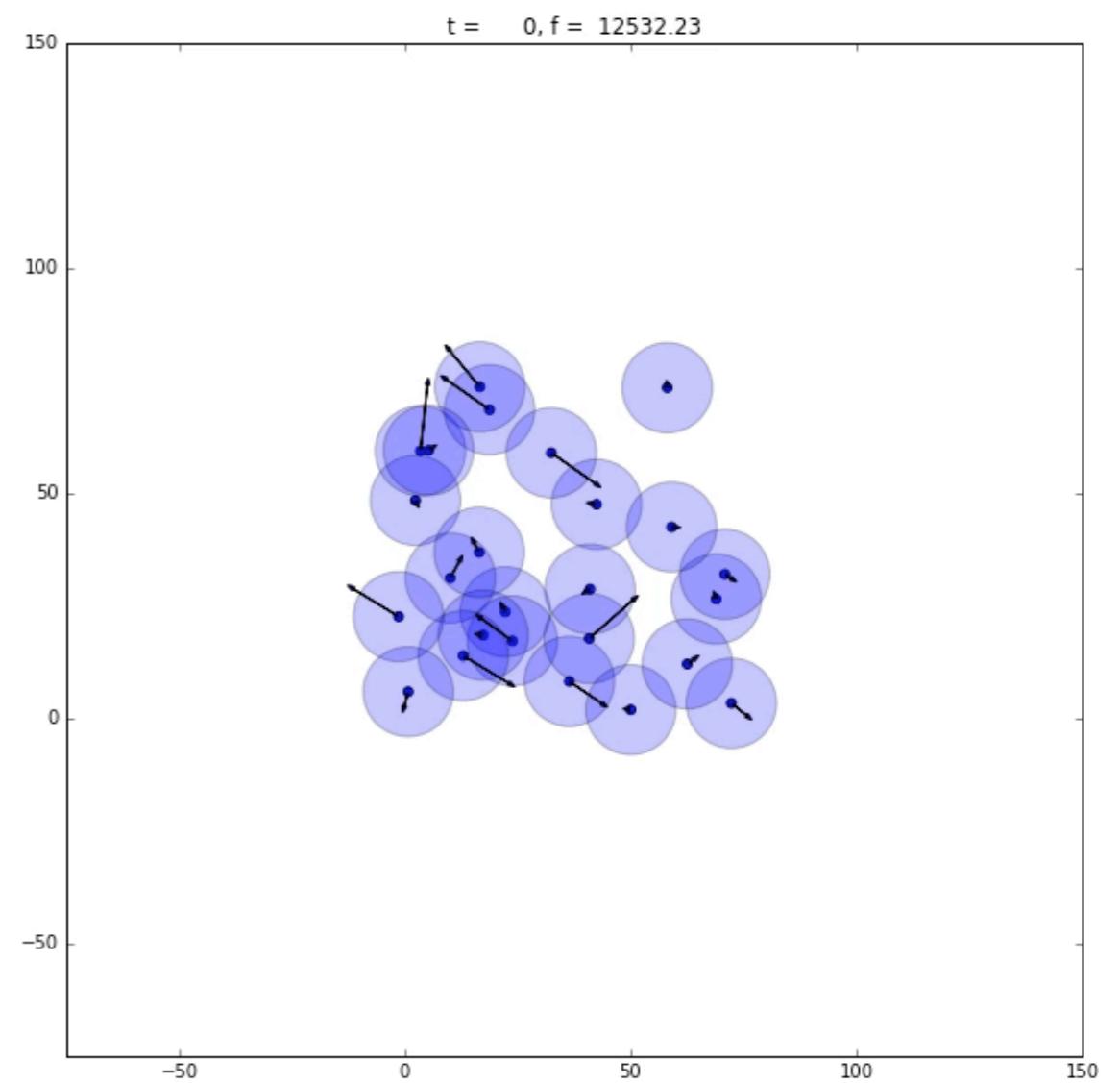
Center based model

- Cell represented as a circles (or spheres)
- Movement controlled by forces
- Interaction between cells:
 - *Adhesion* when close
 - *Repulsion* when too close
 - *No interaction* when too far



Center based model

- Cell represented as a circles (or spheres)
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Center based model - cells

Cell represented as a circles or spheres

Set of cells:

$$\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_{N_{cells}}$$

Interaction radius

$$r_{max}$$

Vector from cell i to cell j

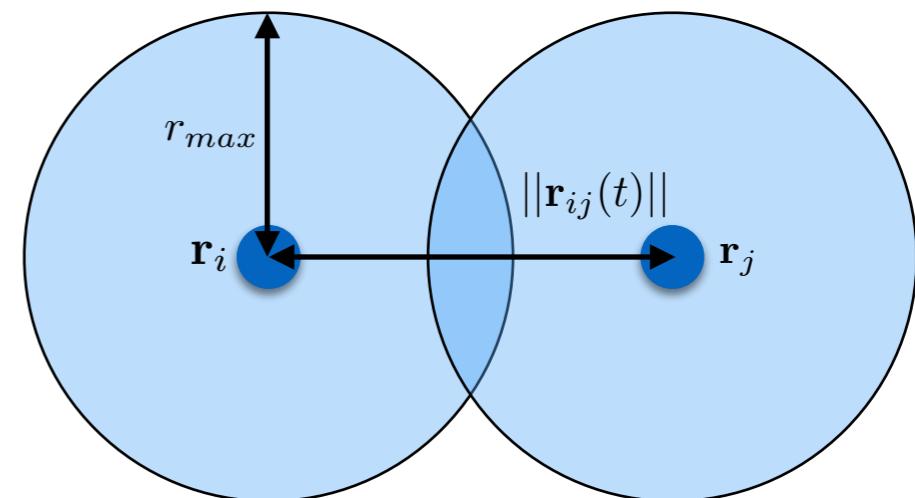
$$\mathbf{r}_{ij}(t) = \mathbf{r}_j(t) - \mathbf{r}_i(t)$$

Distance from cell i to cell j

$$\|\mathbf{r}_{ij}(t)\|$$

Natural separation

$$s_{ij}(t)$$



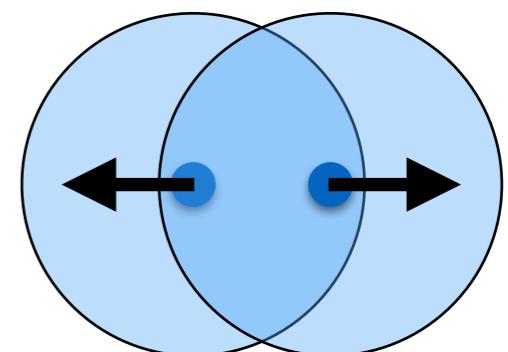
Center based model - forces

Forces on a cell:

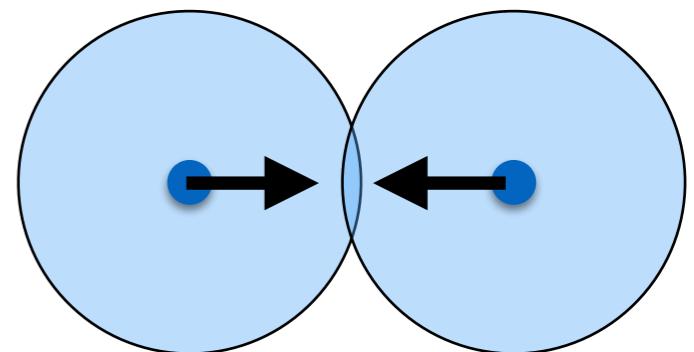
- volume exclusion
- adhesion

$$\|\mathbf{r}_{ij}(t)\| < s_{ij}(t)$$

Repulsion

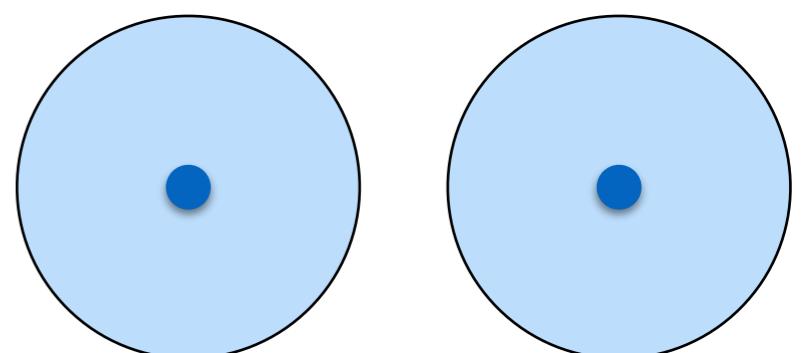


Attraction



$$s_{ij}(t) \leq \|\mathbf{r}_{ij}(t)\| \leq r_{max}$$

No interaction



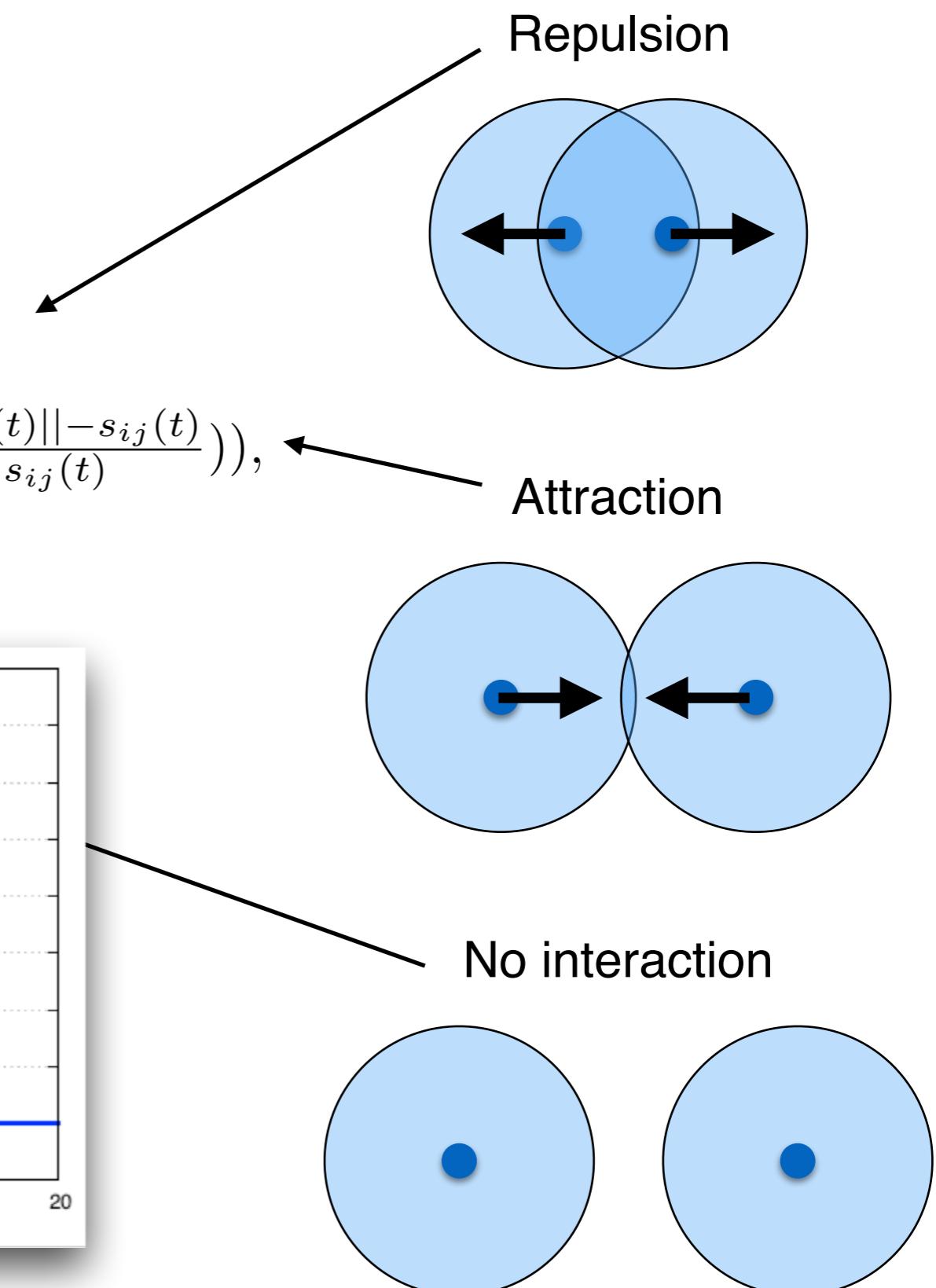
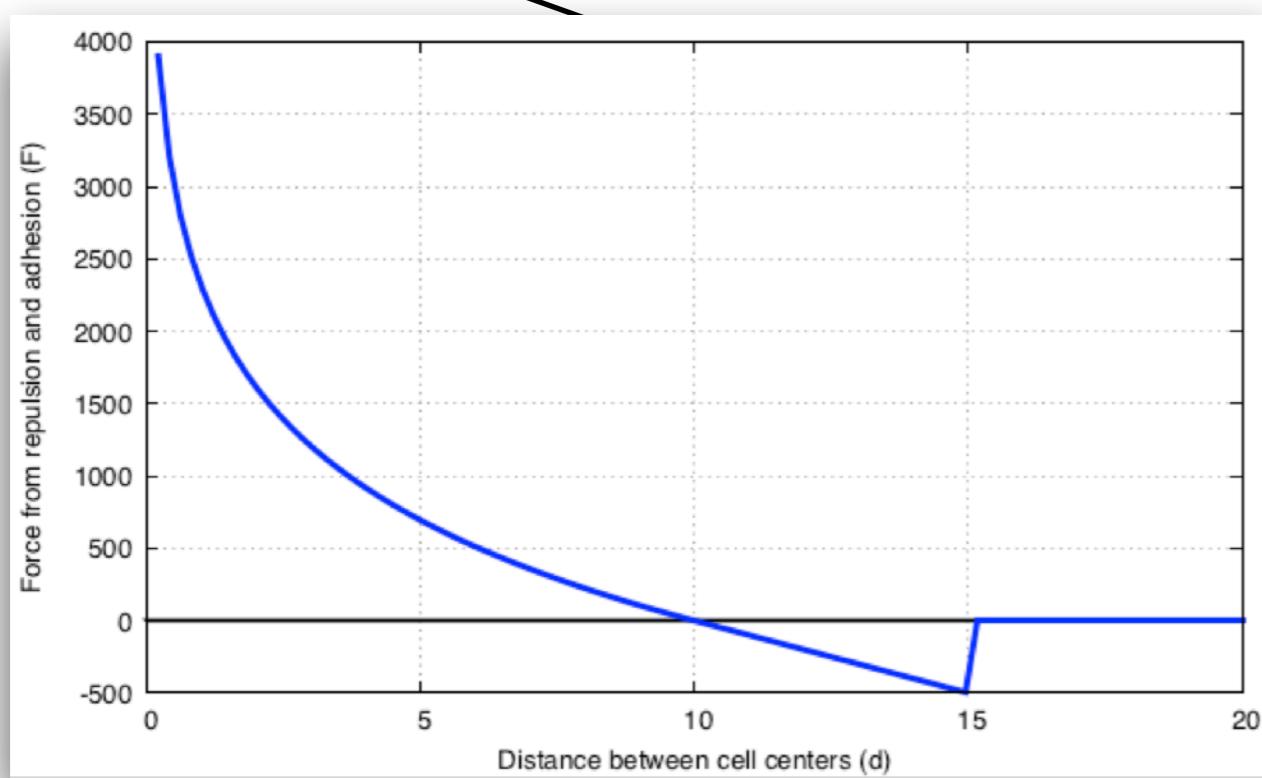
$$\|\mathbf{r}_{ij}(t)\| > r_{max}$$

Center based model - forces

Forces on a cell:

- volume exclusion
- adhesion

$$\mathbf{F}_{ij}(t) = \begin{cases} \mu_{ij} s_{ij}(t) \hat{\mathbf{r}}_{ij}(t) \log\left(1 + \frac{||\mathbf{r}_{ij}(t)|| - s_{ij}(t)}{s_{ij}(t)}\right), \\ \mu_{ij} (||\mathbf{r}_{ij}(t)|| - s_{ij}) \hat{\mathbf{r}}_{ij}(t) \exp\left(-k_c \frac{||\mathbf{r}_{ij}(t)|| - s_{ij}(t)}{s_{ij}(t)}\right), \\ 0, \end{cases}$$

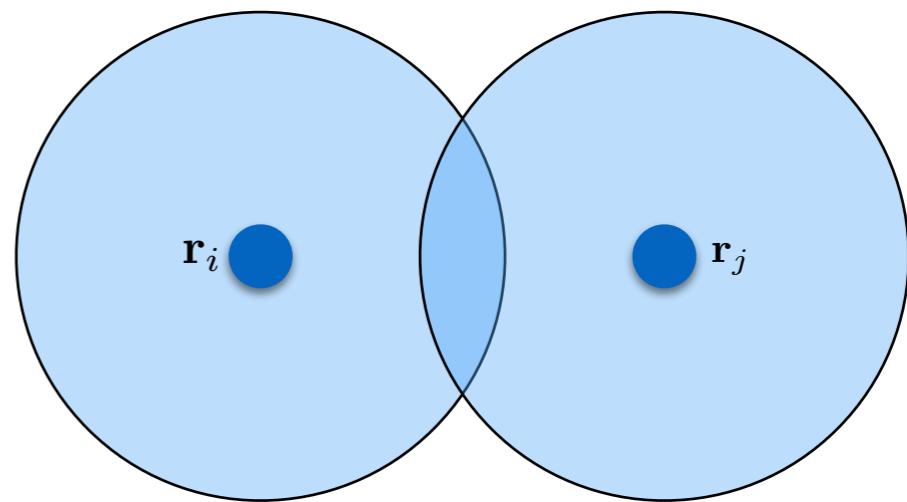


Center based model - motility

Cell represented as a circles or spheres

Update positions according to linear ODEs:

$$\eta \frac{d\mathbf{r}_i}{dt} = \mathbf{F}_i(t) = \sum_{j \in \mathcal{N}_i(t)} \mathbf{F}_{ij}(t)$$



Discretized in time:

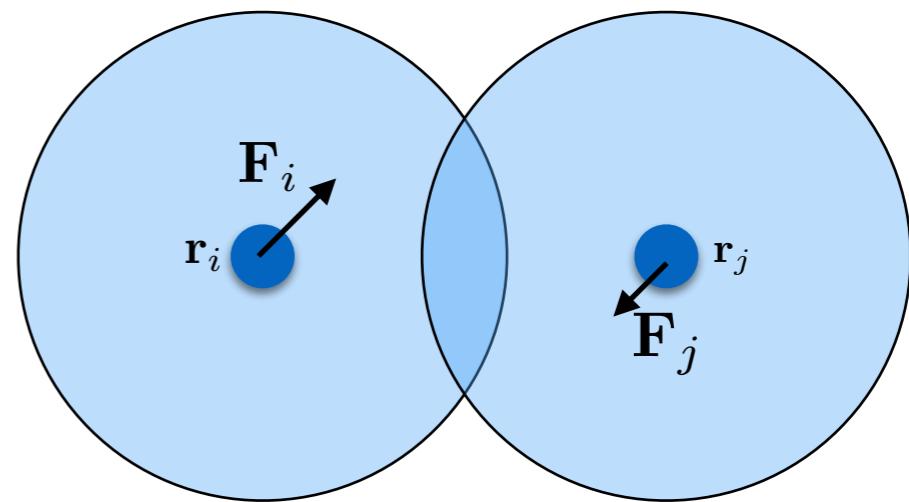
$$\mathbf{r}_i(t + \Delta t) = \mathbf{r}_i + \frac{\Delta t}{\eta} \sum_{j \in \mathcal{N}_i(t)} \mathbf{F}_{ij}(t)$$

Center based model - motility

Cell represented as a circles or spheres

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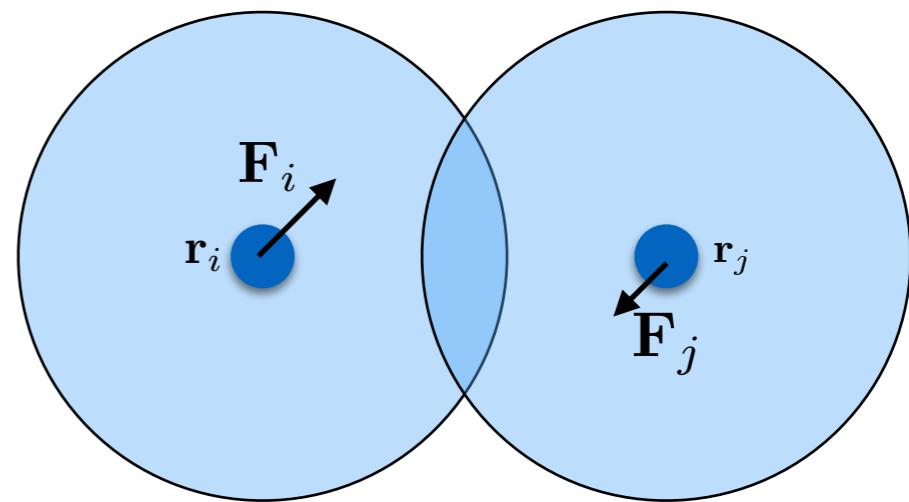
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Center based model - motility

Cell represented as a circles or spheres

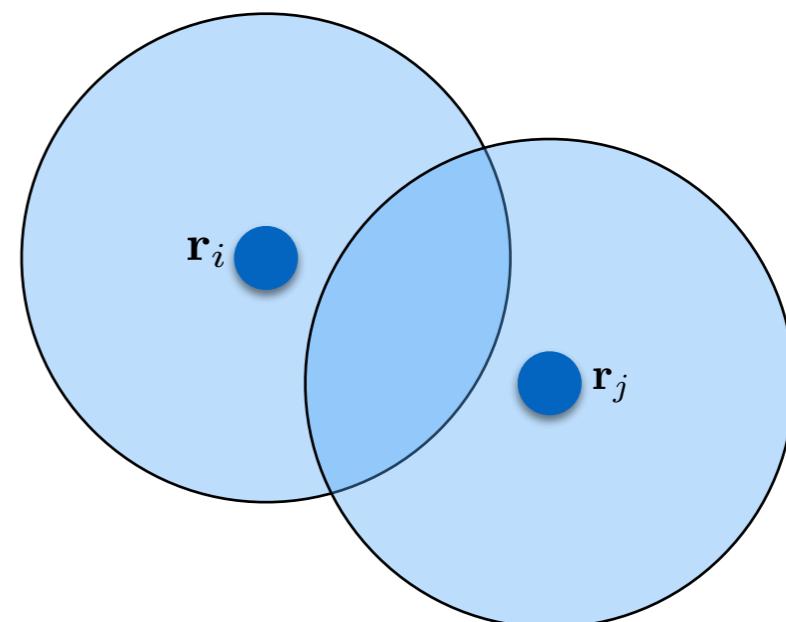
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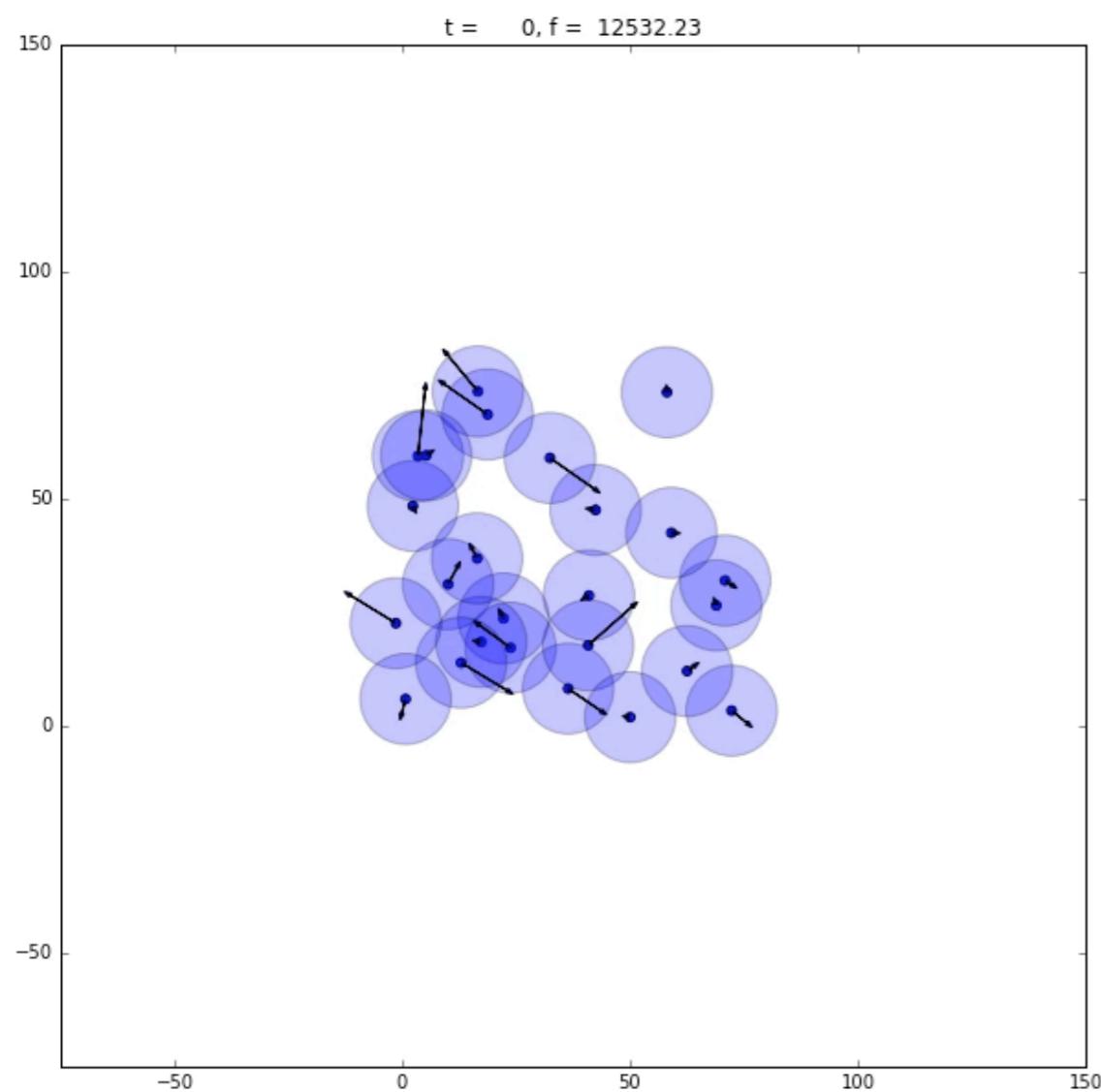


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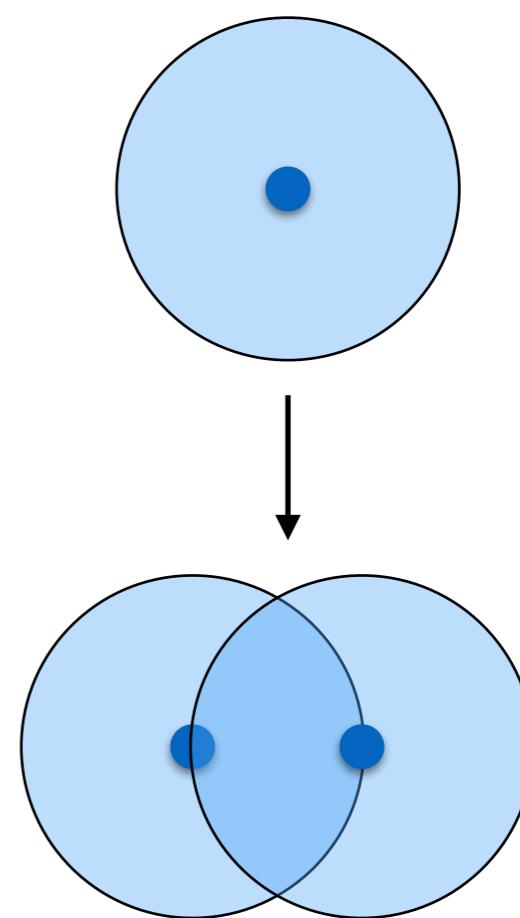
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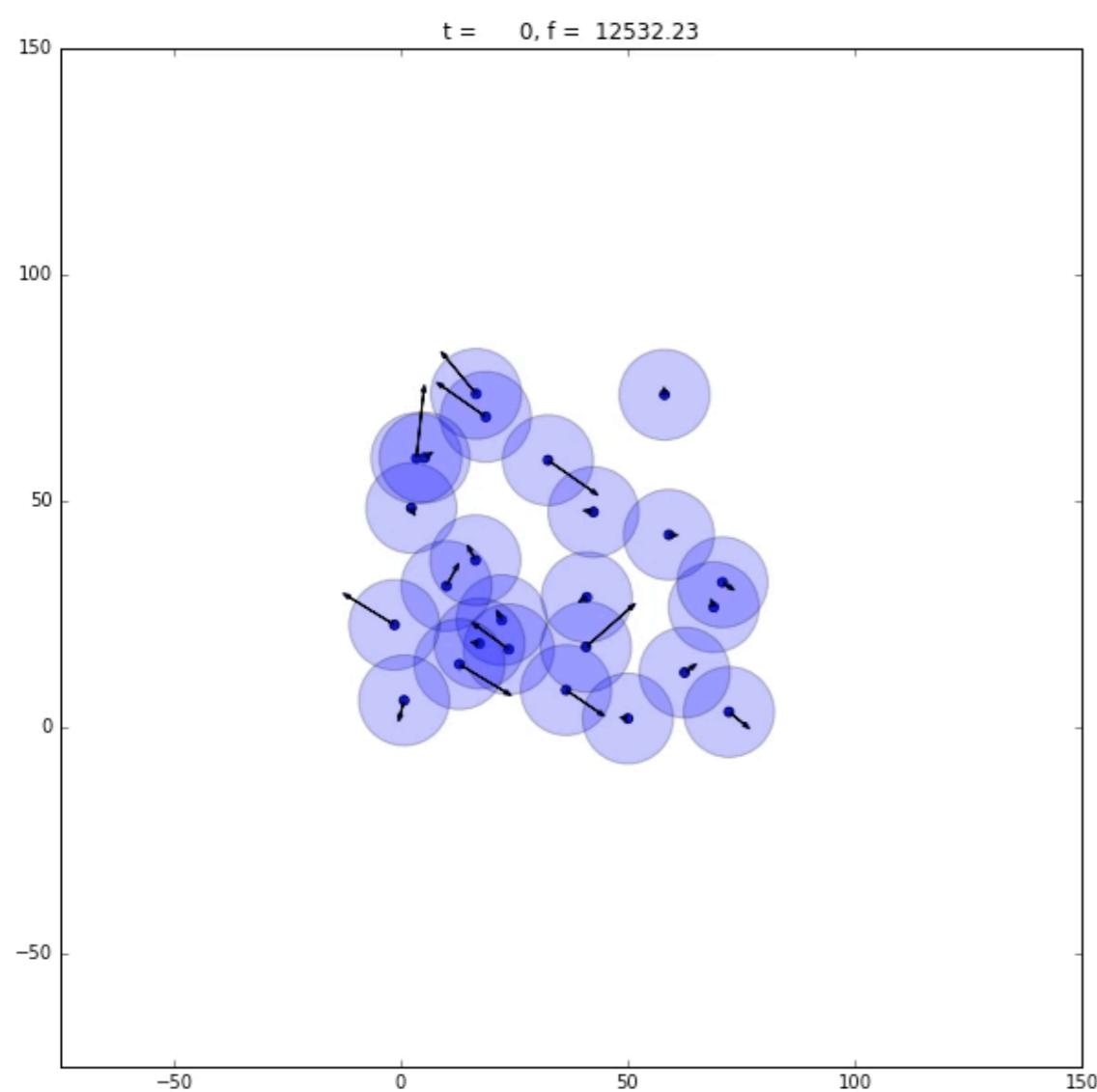
Center based model



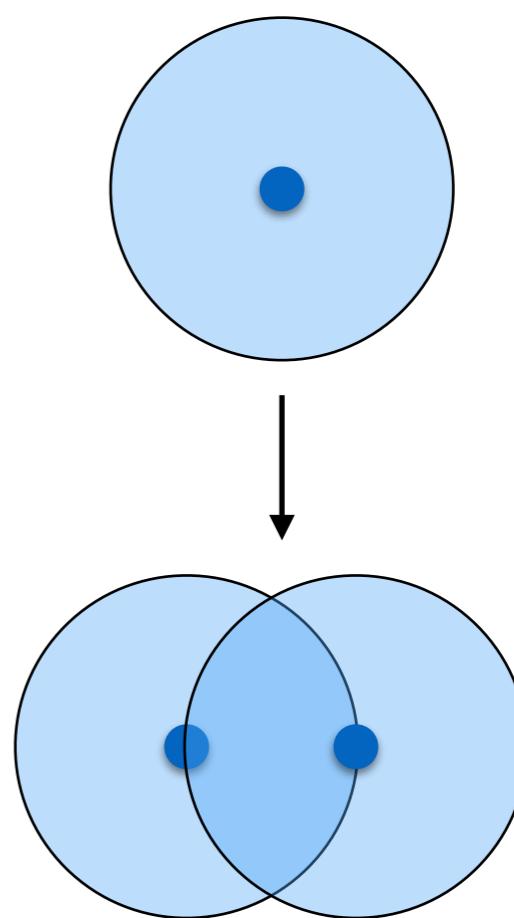
Cell division



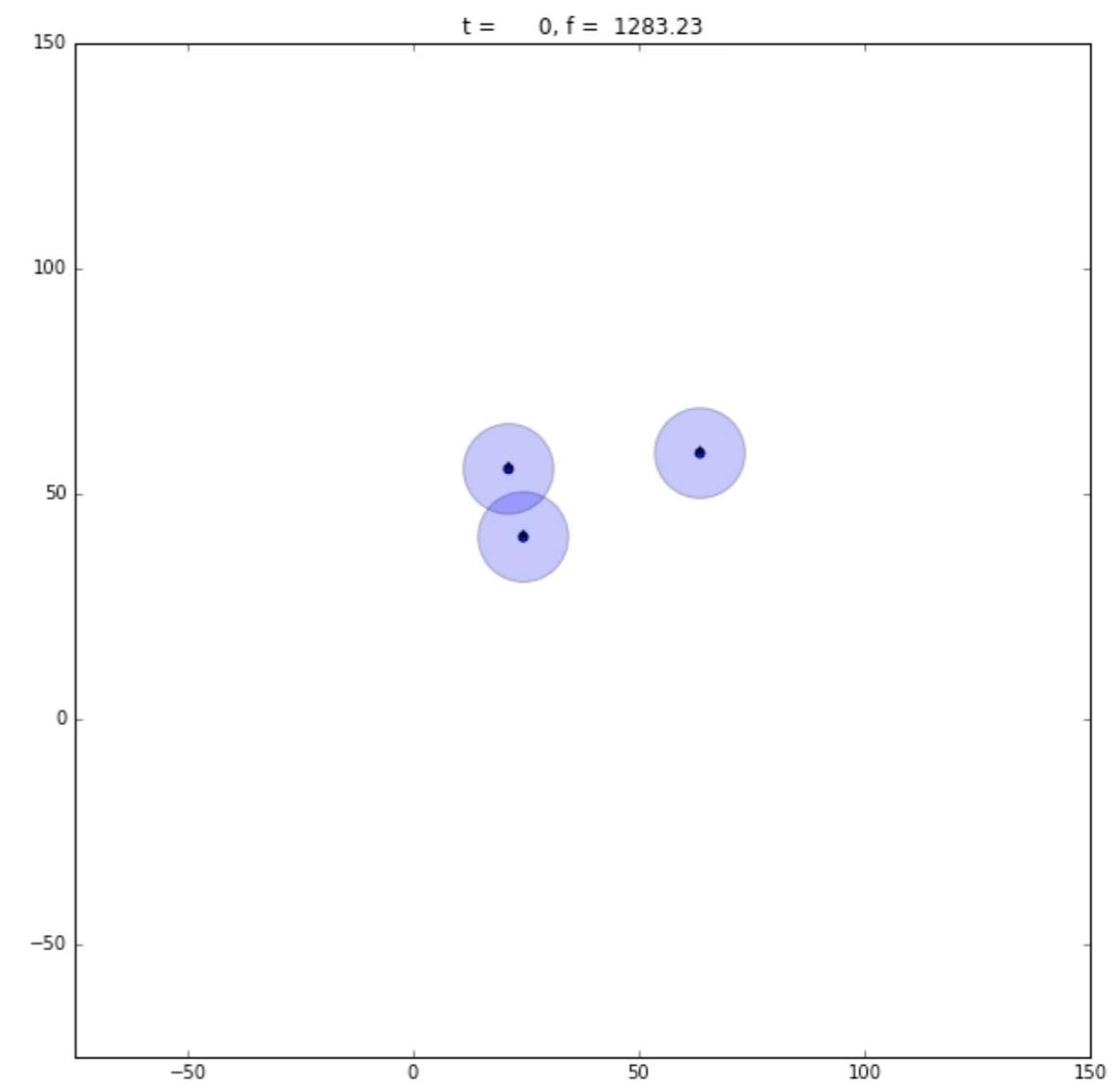
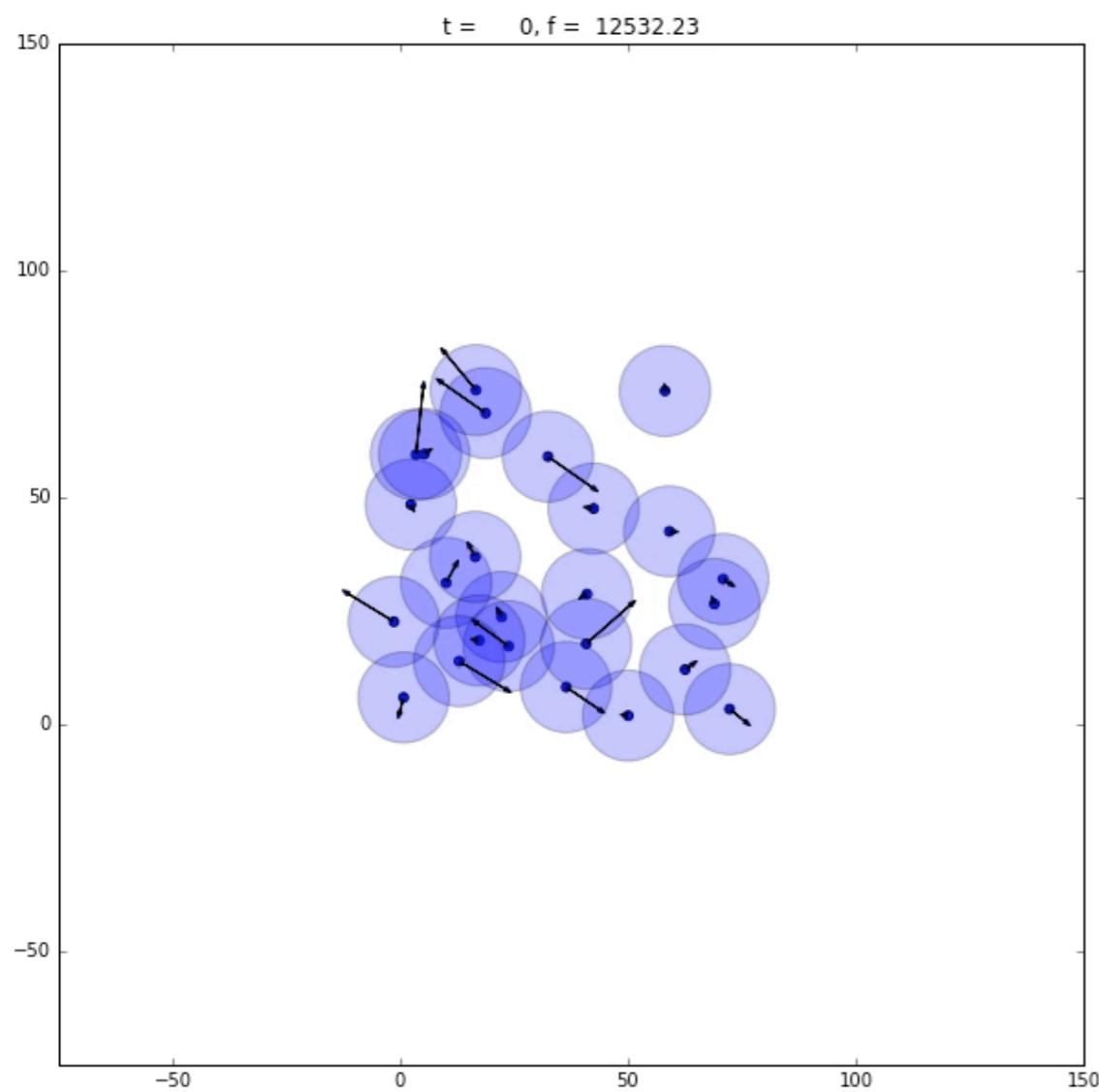
Center based model



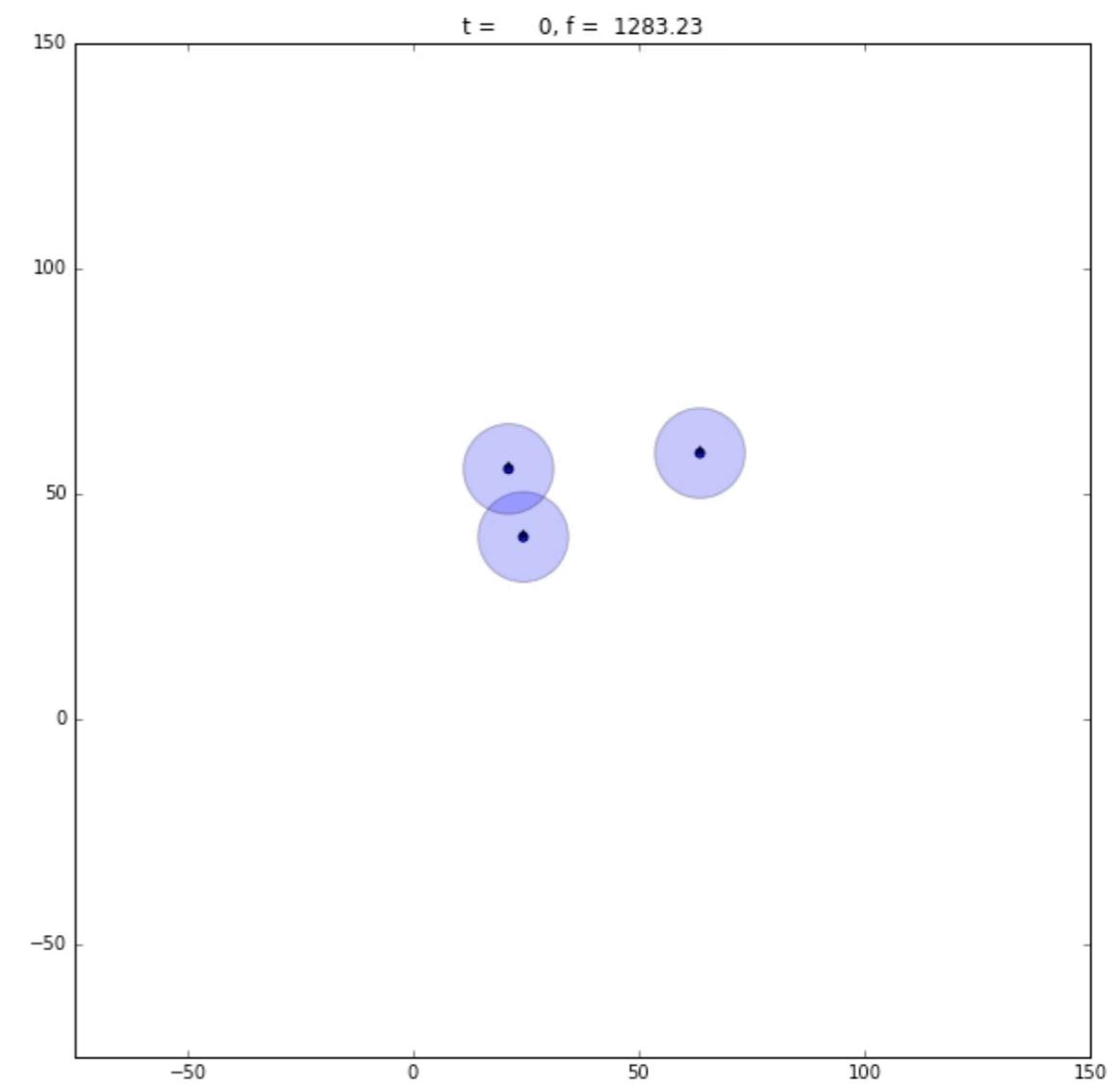
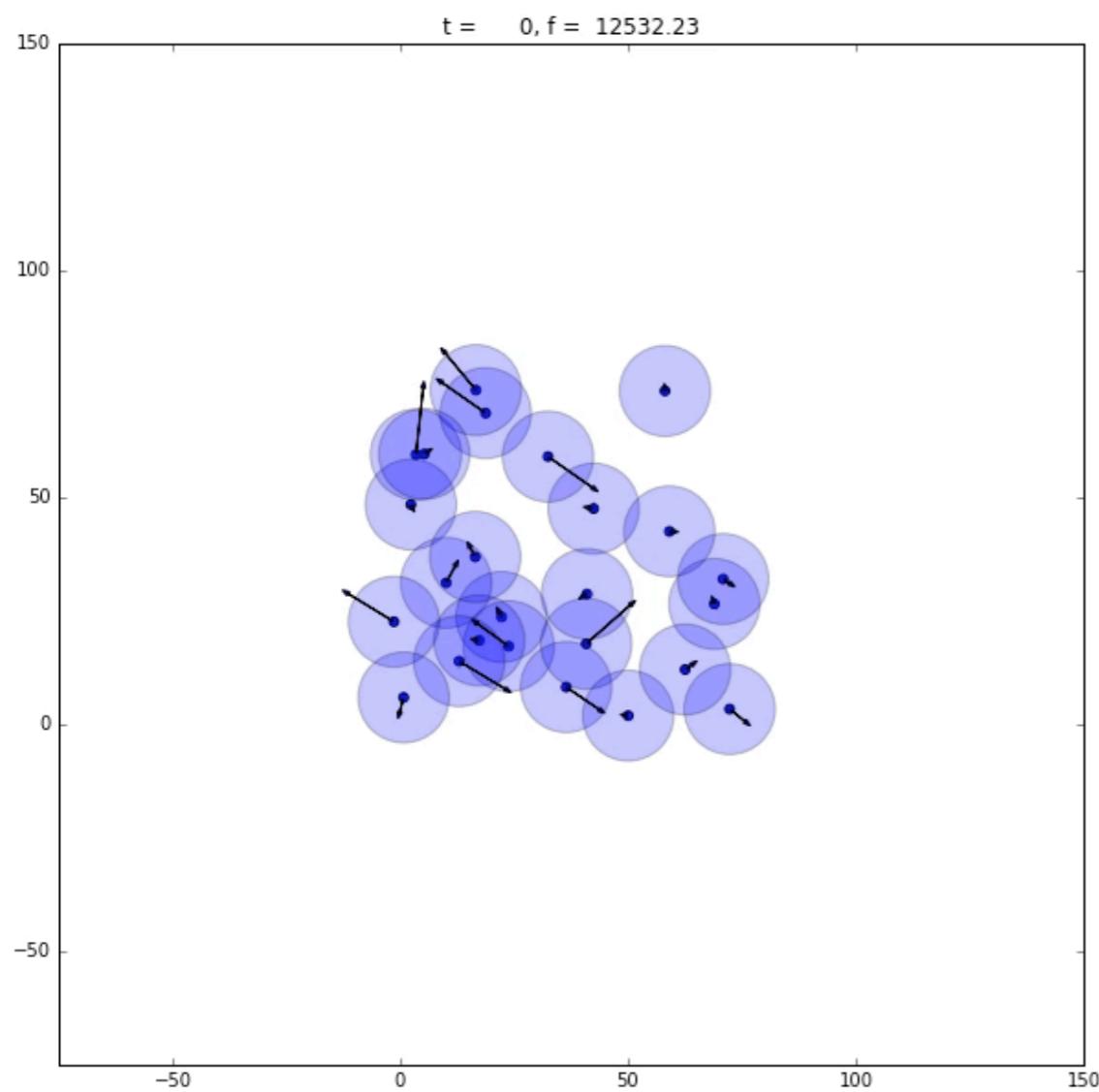
Cell division



Center based model - cell division



Center based model - cell division

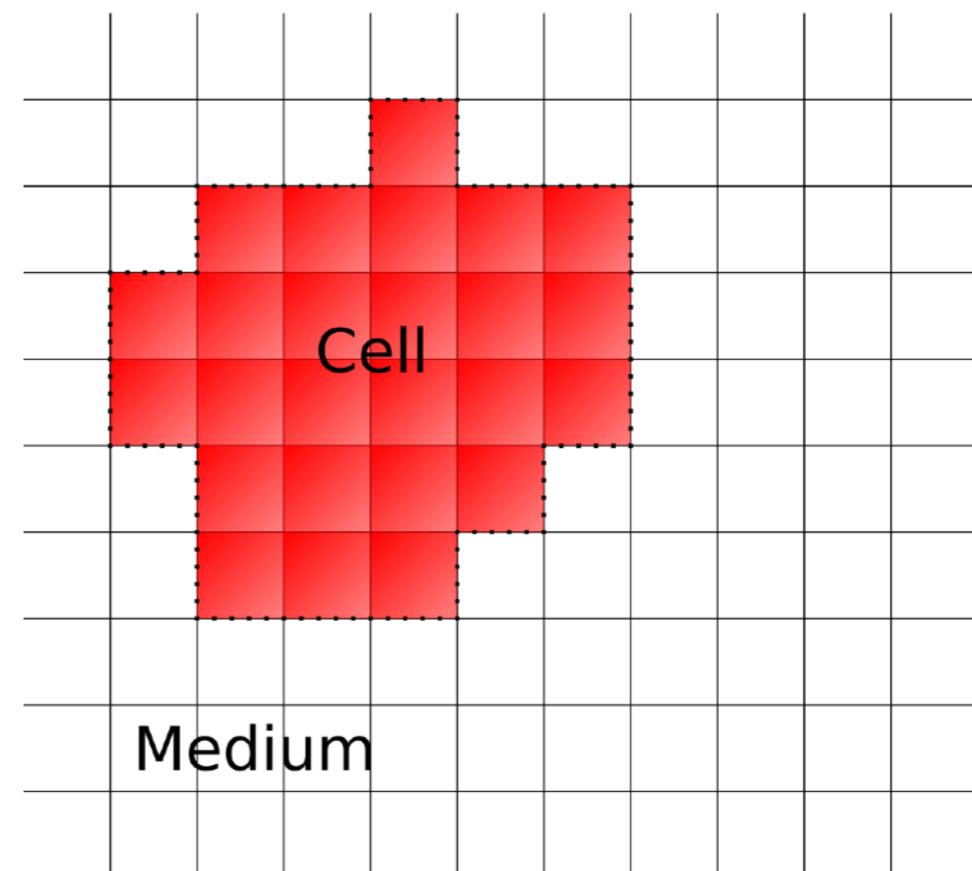


Cellular Potts model

Cellular Potts model - cell size

Cell represented as a lattice domain

$$H = \sum_{\sigma>0} (a_\sigma - A_\sigma)^2$$

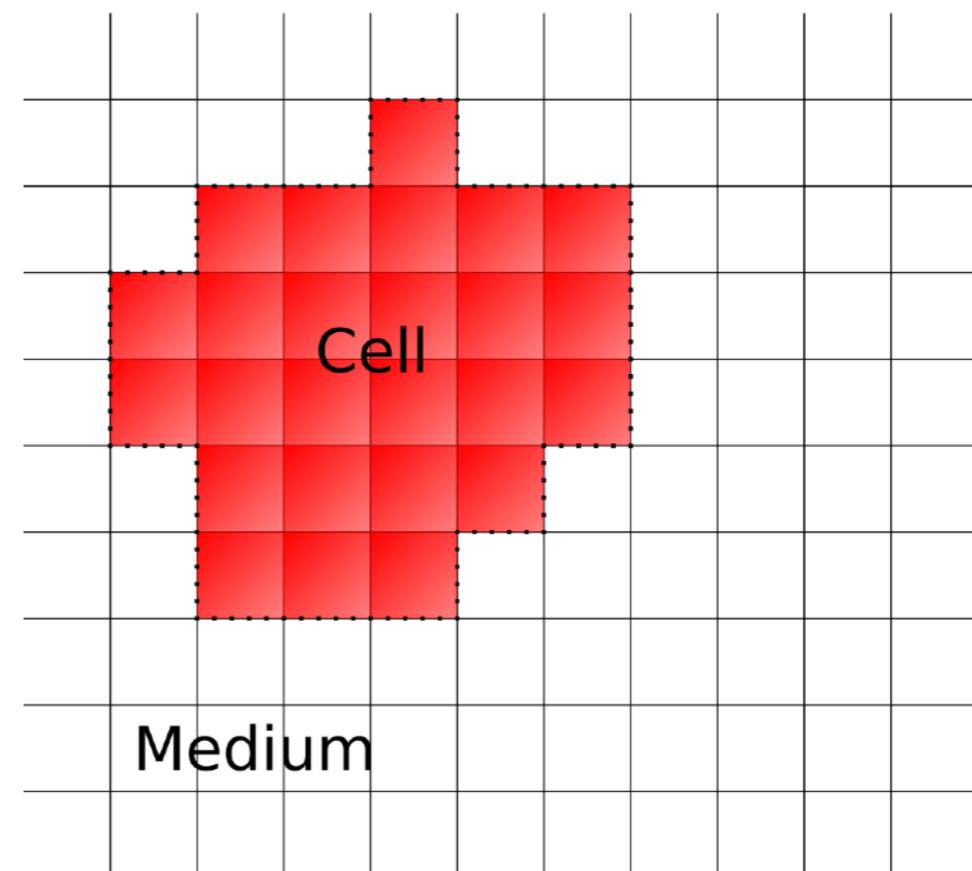


Cellular Potts model - cell size

Cell represented as a lattice domain

energy

$$H = \sum_{\sigma>0} (a_\sigma - A_\sigma)^2$$



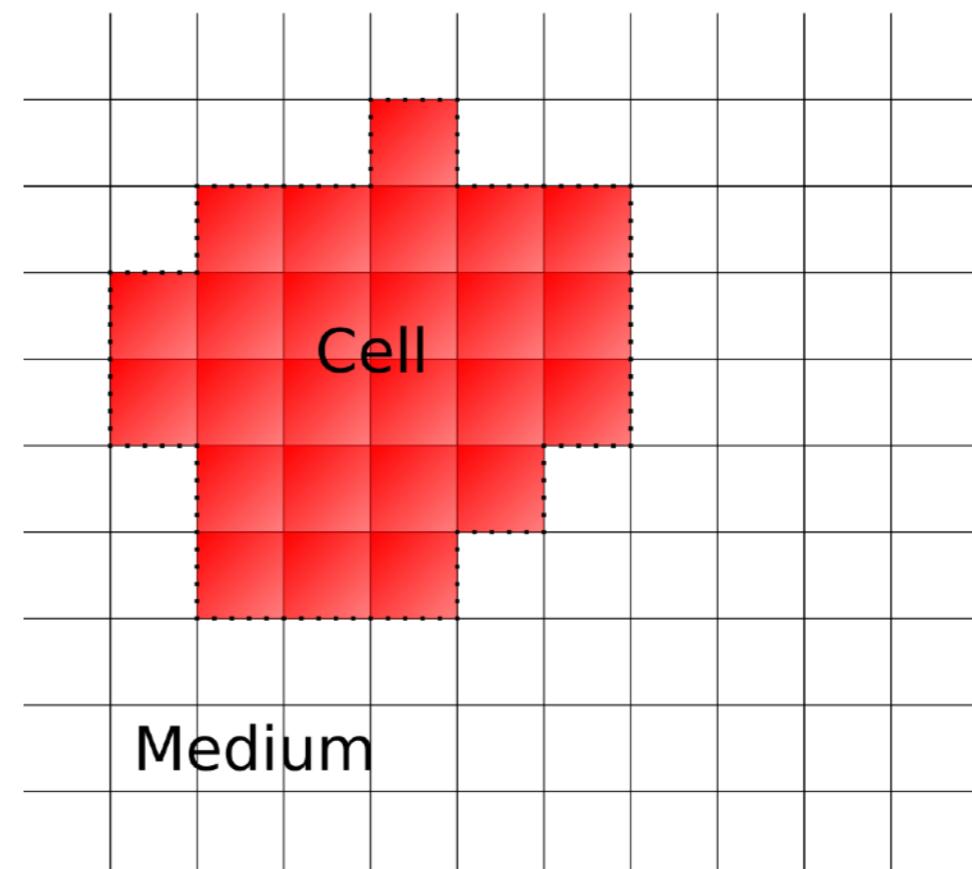
Cellular Potts model - cell size

Cell represented as a lattice domain

energy

$$H = \sum_{\sigma>0} (a_\sigma - A_\sigma)^2$$

sum over cells

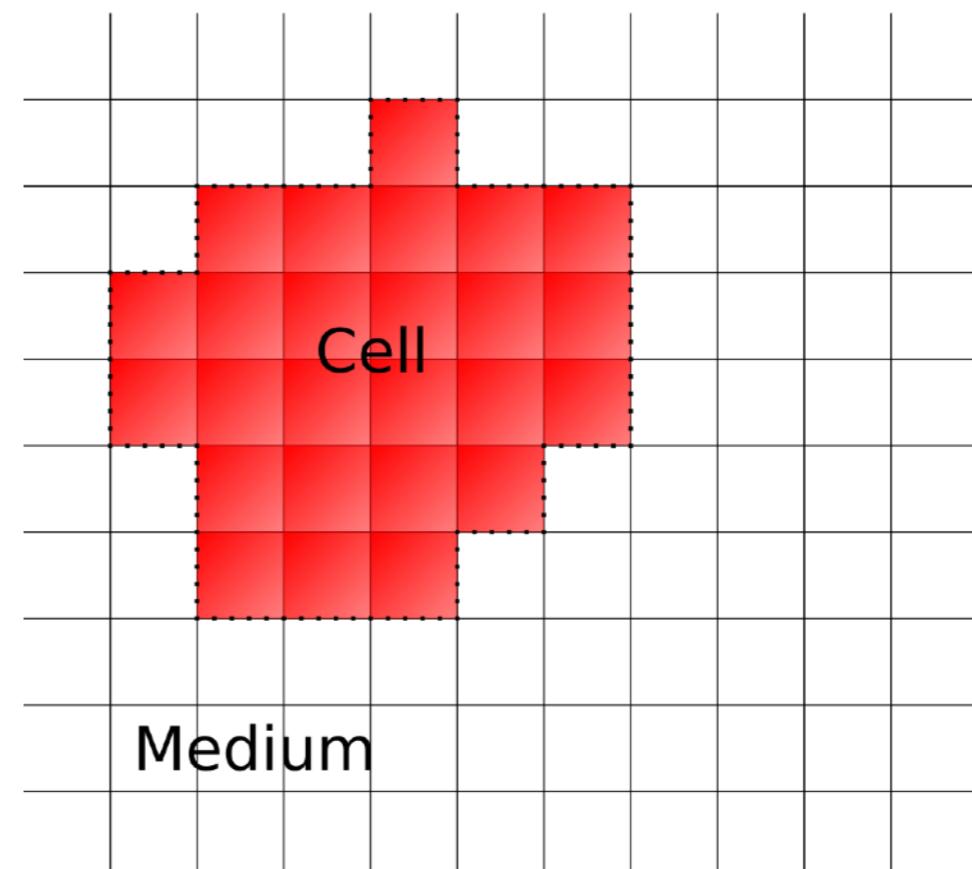


Cellular Potts model - cell size

Cell represented as a lattice domain

$$H = \sum_{\sigma > 0} (a_{\sigma} - A_{\sigma})^2$$

energy actual area
 \ /
 sum over cells

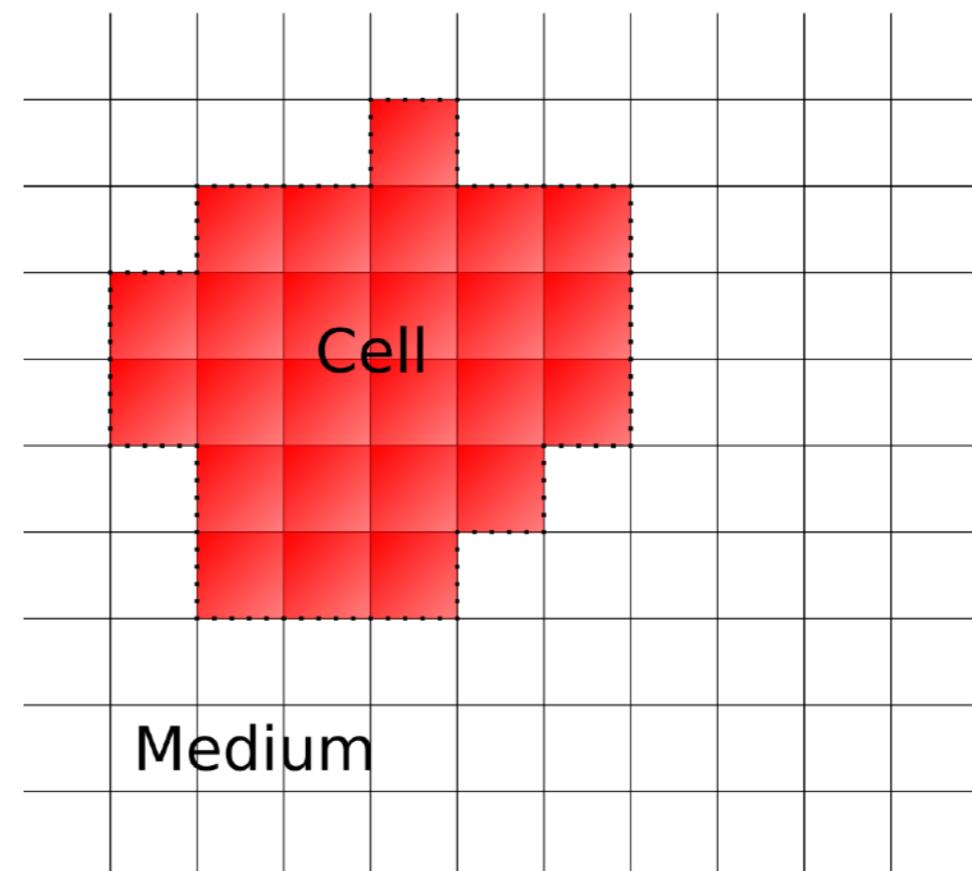


Cellular Potts model - cell size

Cell represented as a lattice domain

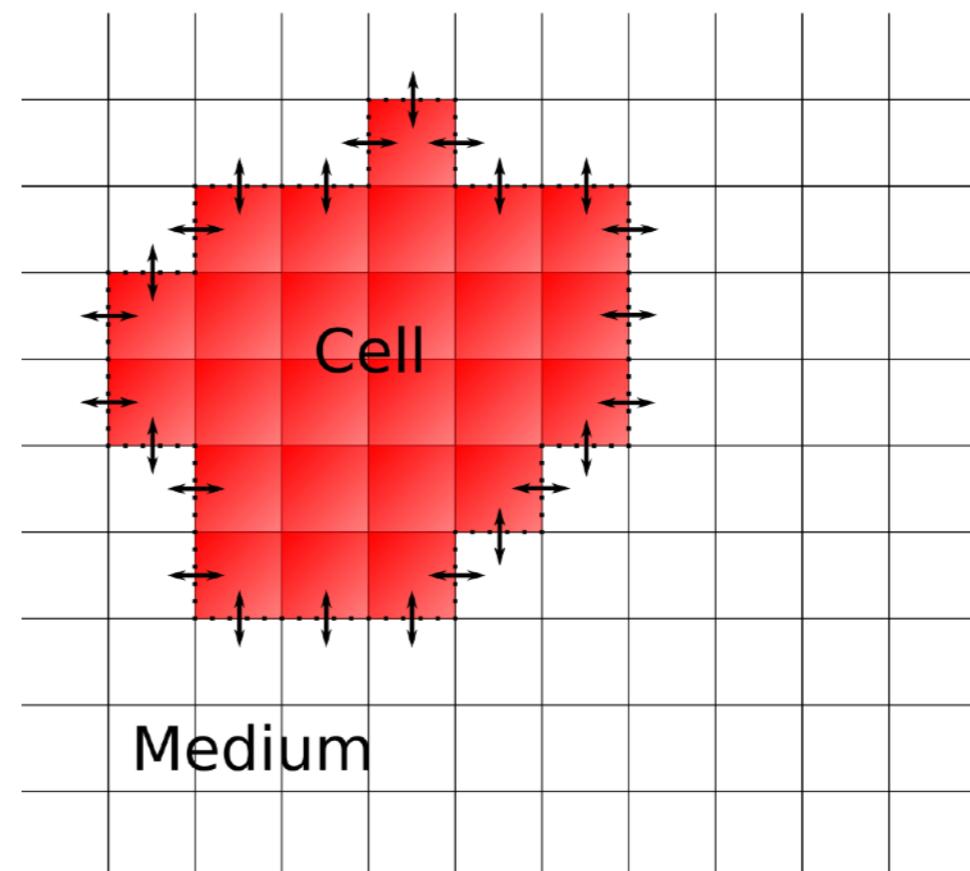
$$H = \sum_{\sigma > 0} (a_{\sigma} - A_{\sigma})^2$$

energy actual area
sum over cells target area



Cellular Potts model - contact energy

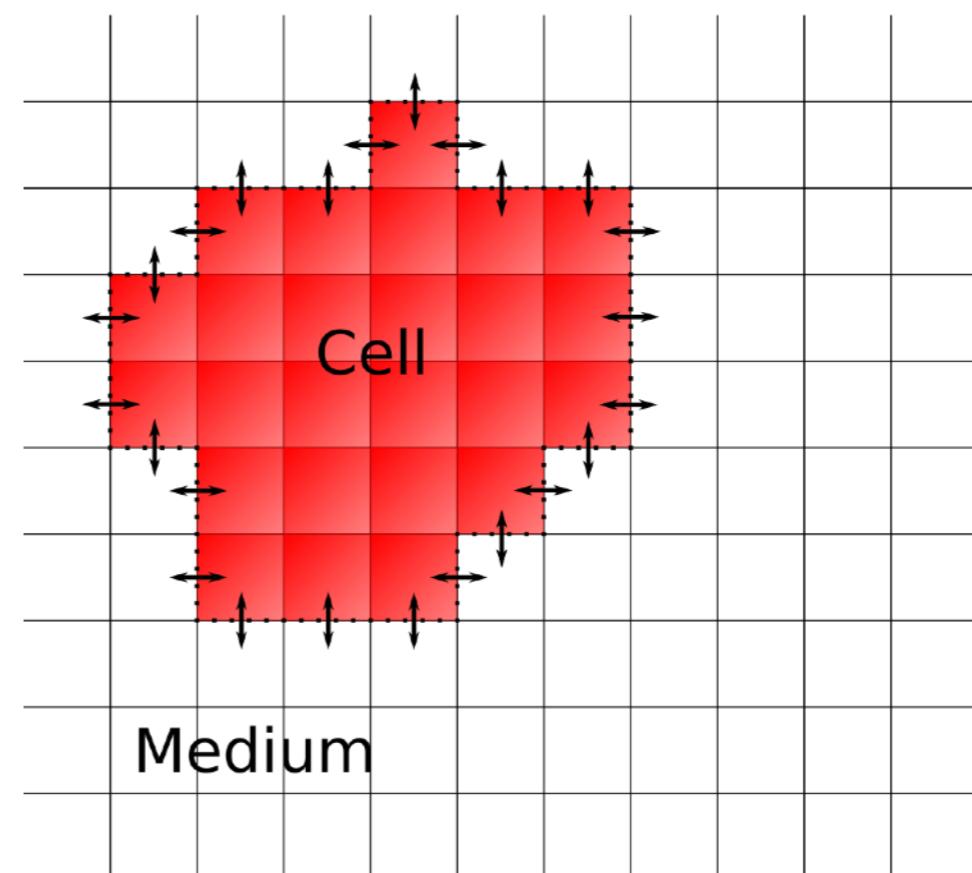
$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y})$$



Cellular Potts model - contact energy

energy

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y})$$

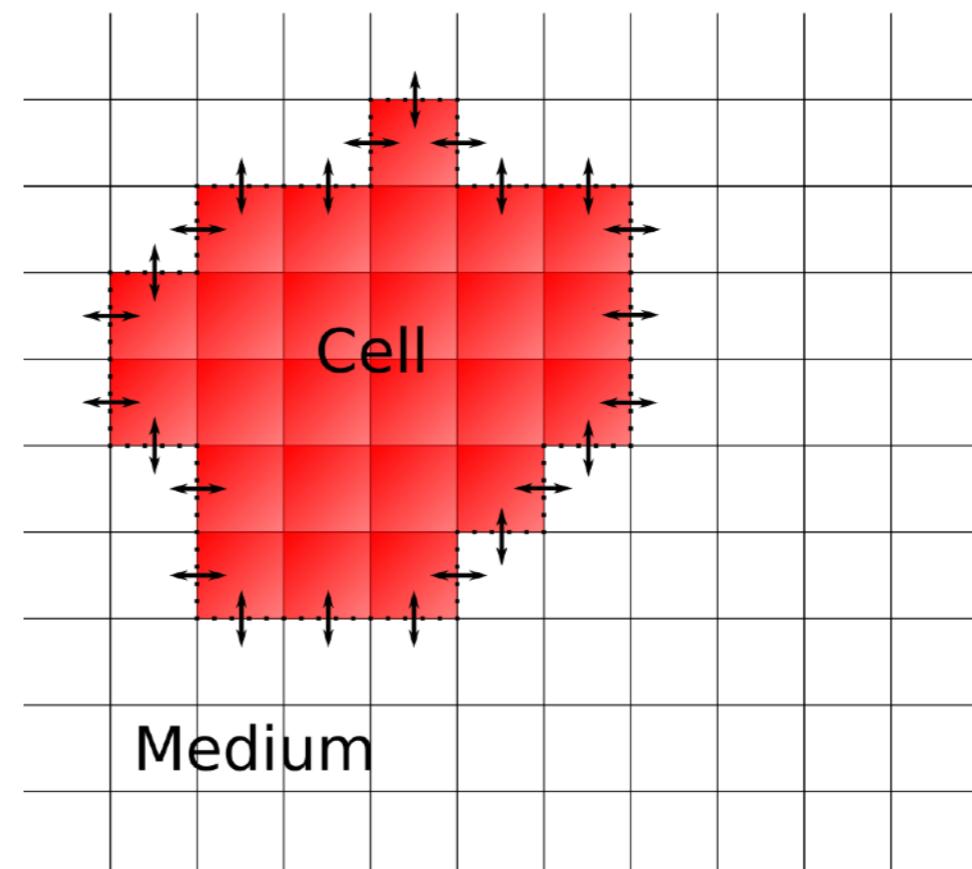


Cellular Potts model - contact energy

energy

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y})$$

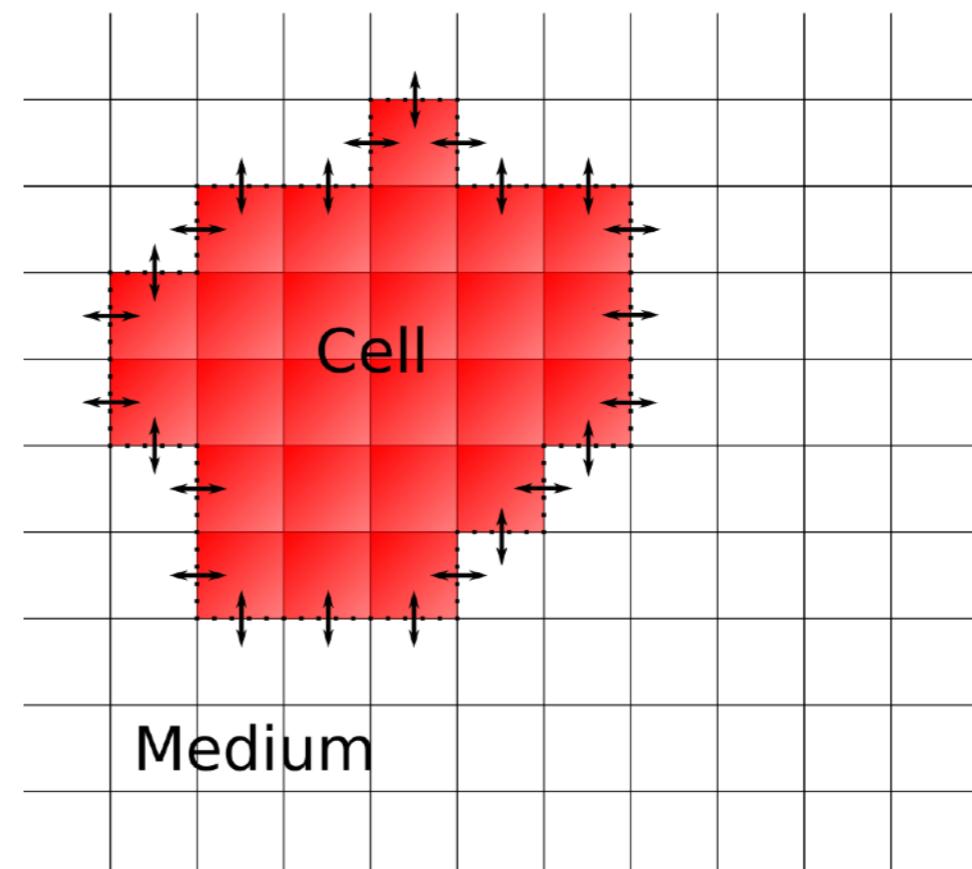
sum over interfaces



Cellular Potts model - contact energy

$$H = \sum_{\text{interfaces}} J_{x,y} (1 - \delta_{x,y})$$

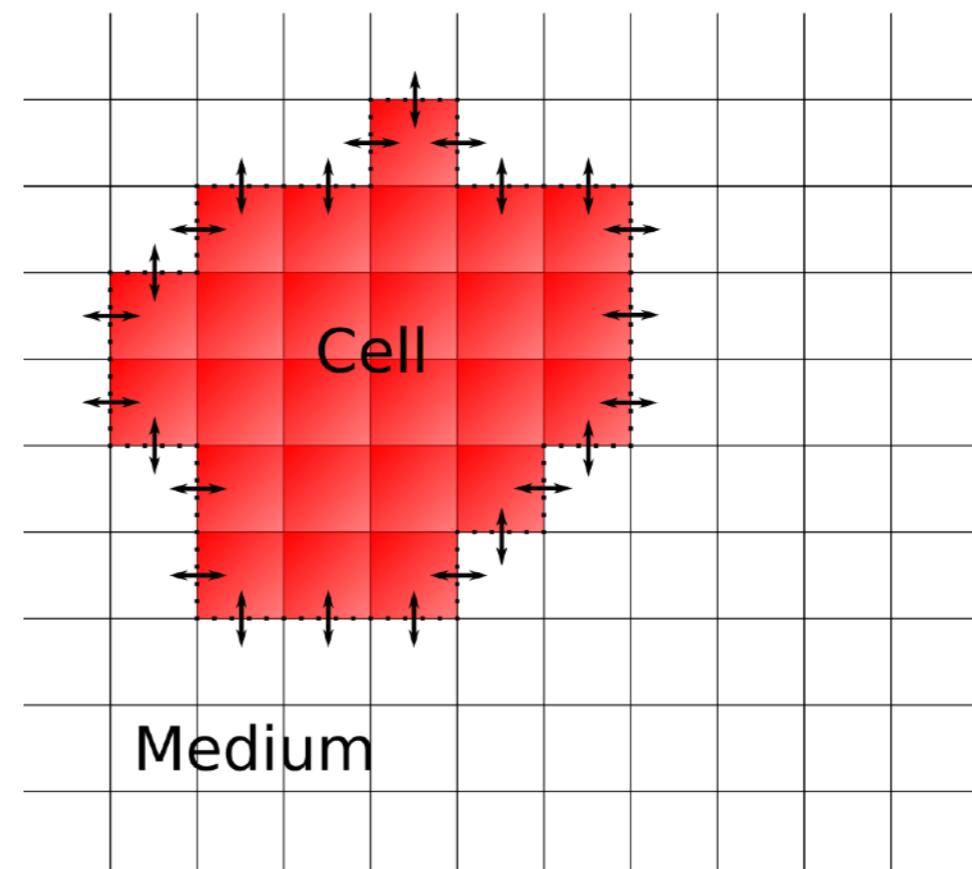
energy \ contact energy
sum over interfaces



Cellular Potts model - contact energy

$$H = \sum_{\text{interfaces}} J_{x,y} (1 - \delta_{x,y})$$

energy
sum over interfaces
contact energy
between domains

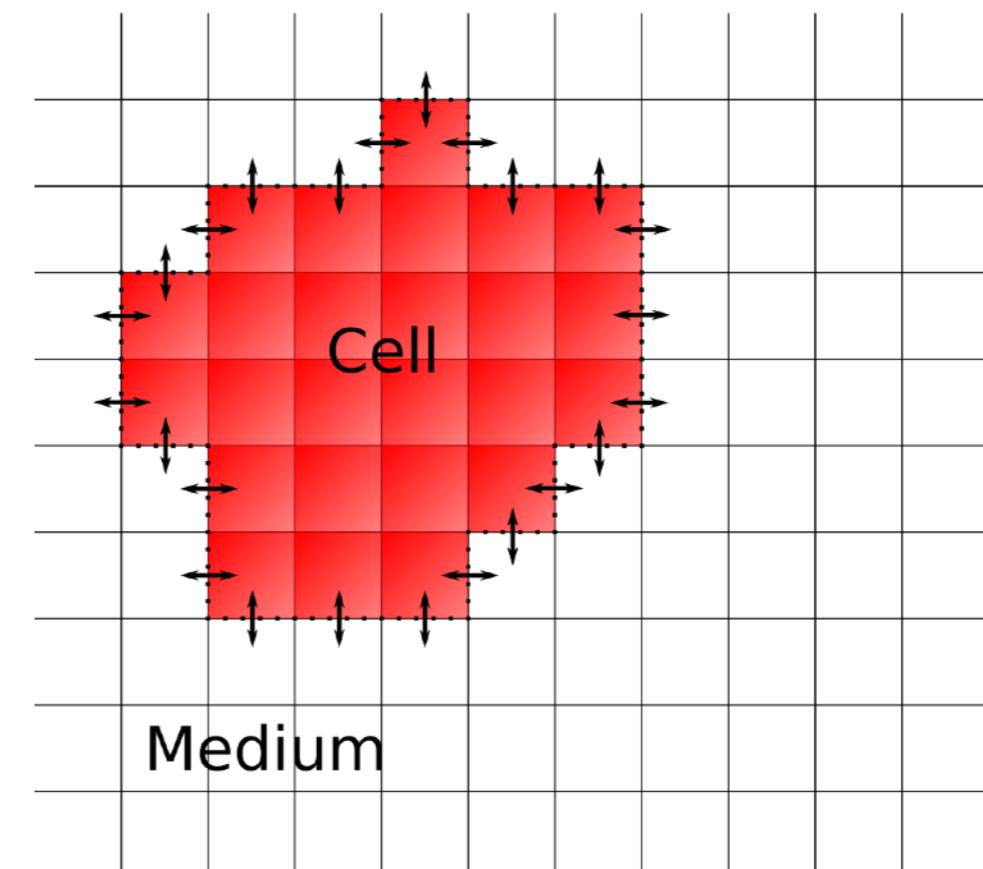


Cellular Potts model - contact energy

$$H = \sum_{\text{interfaces}} J_{x,y} (1 - \delta_{x,y})$$

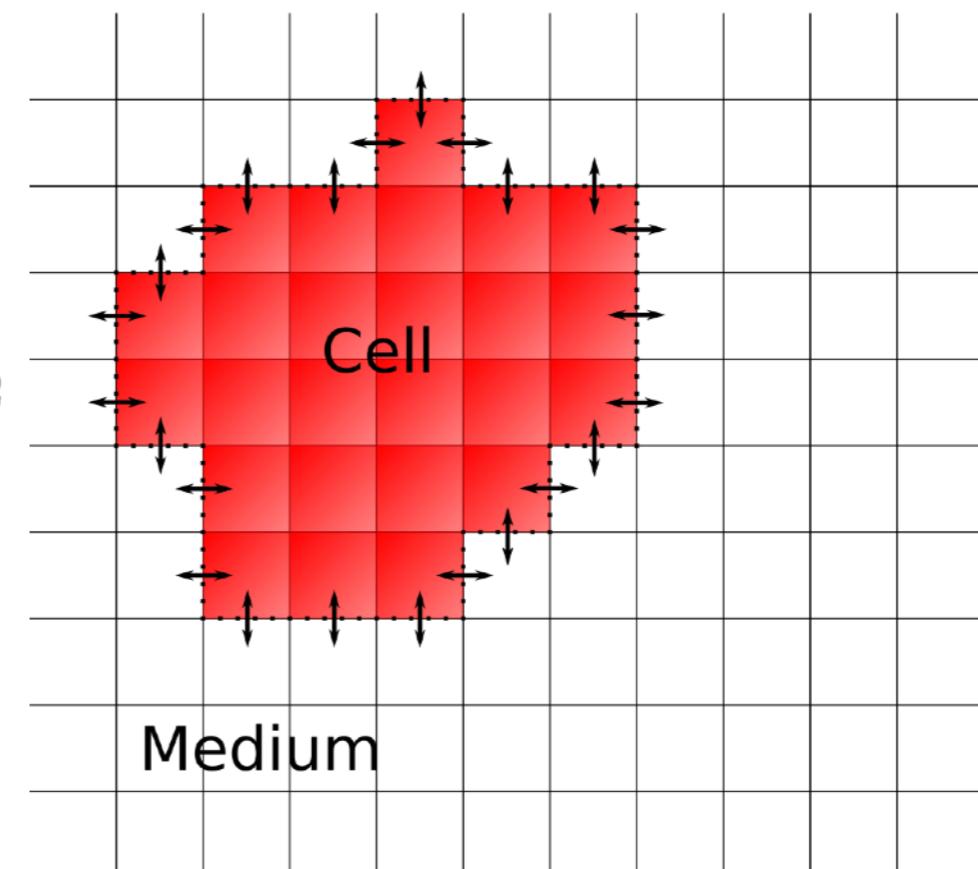
energy
sum over interfaces
contact energy
between domains

Contact	Cell	Medium
Cell	J_{CC}	J_{CM}
Medium	J_{CM}	—



Cellular Potts model - energy function

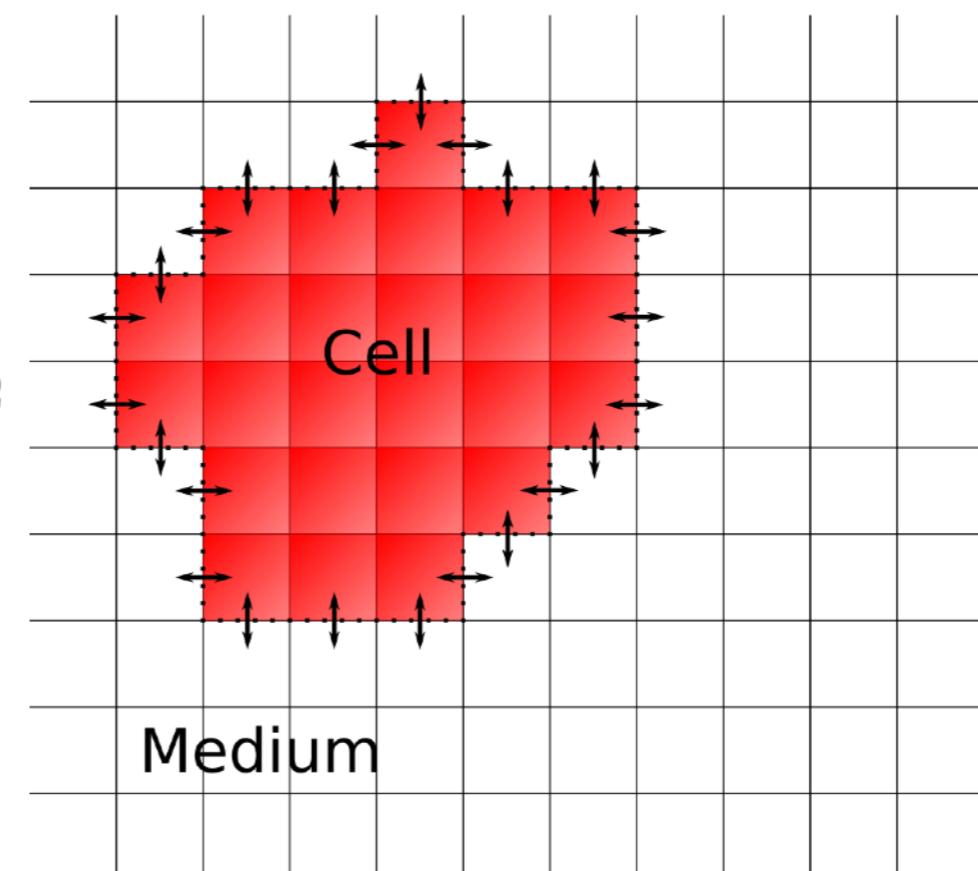
$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$



Cellular Potts model - energy function

energy

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$

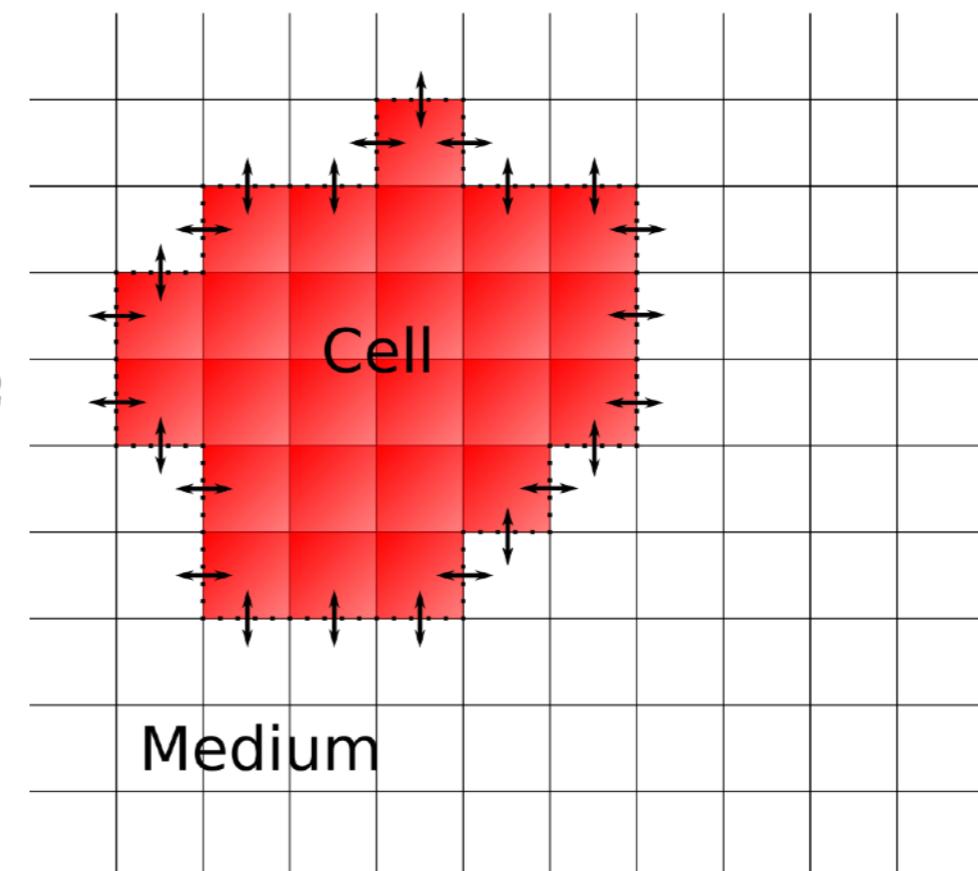


Cellular Potts model - energy function

energy

adhesion

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$



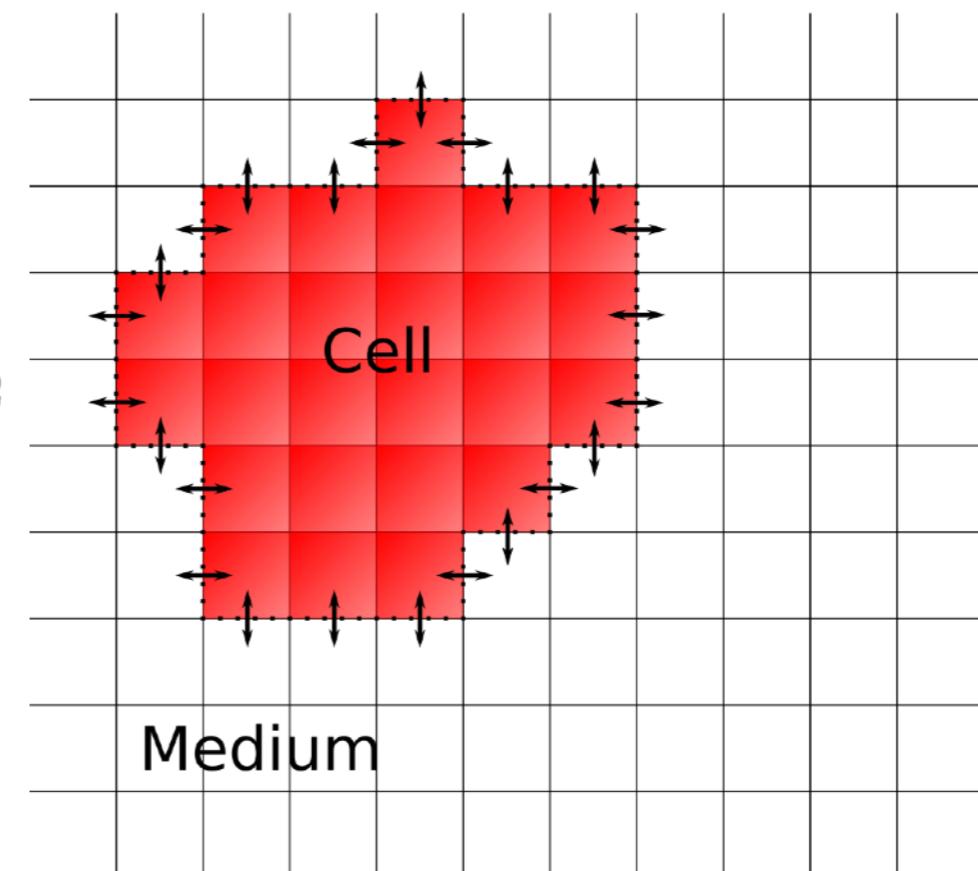
Cellular Potts model - energy function

energy

adhesion

area constraint

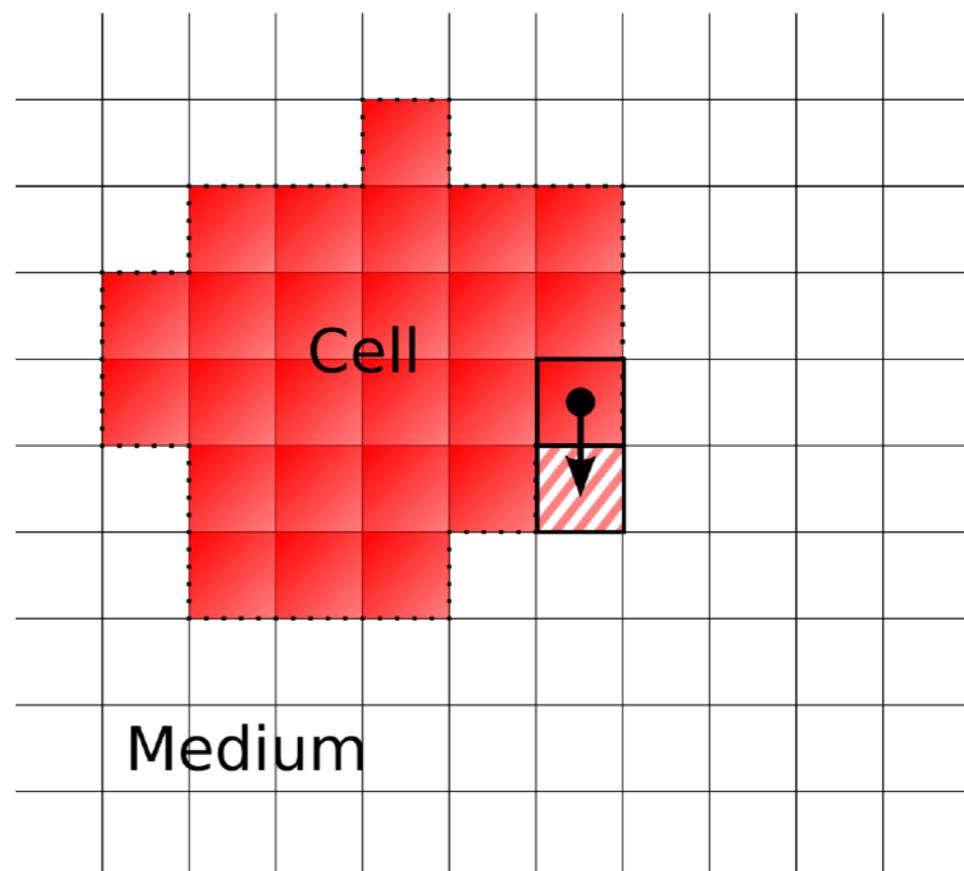
$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$



Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

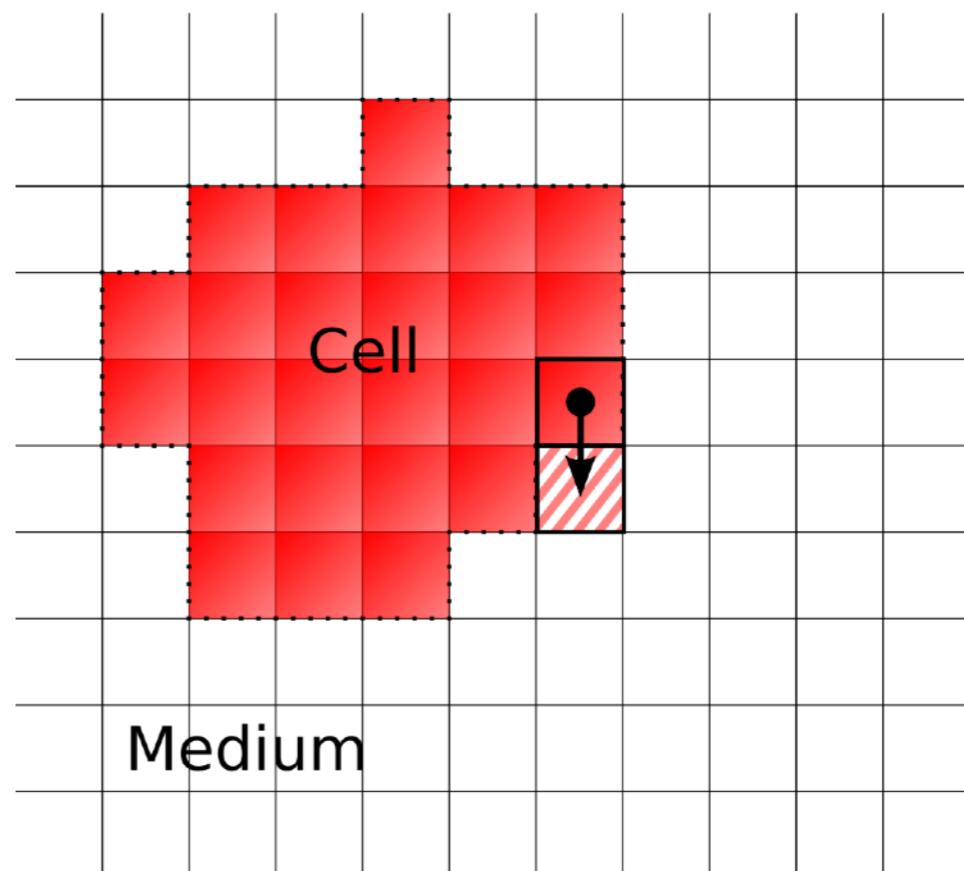


Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

- Pick a random node

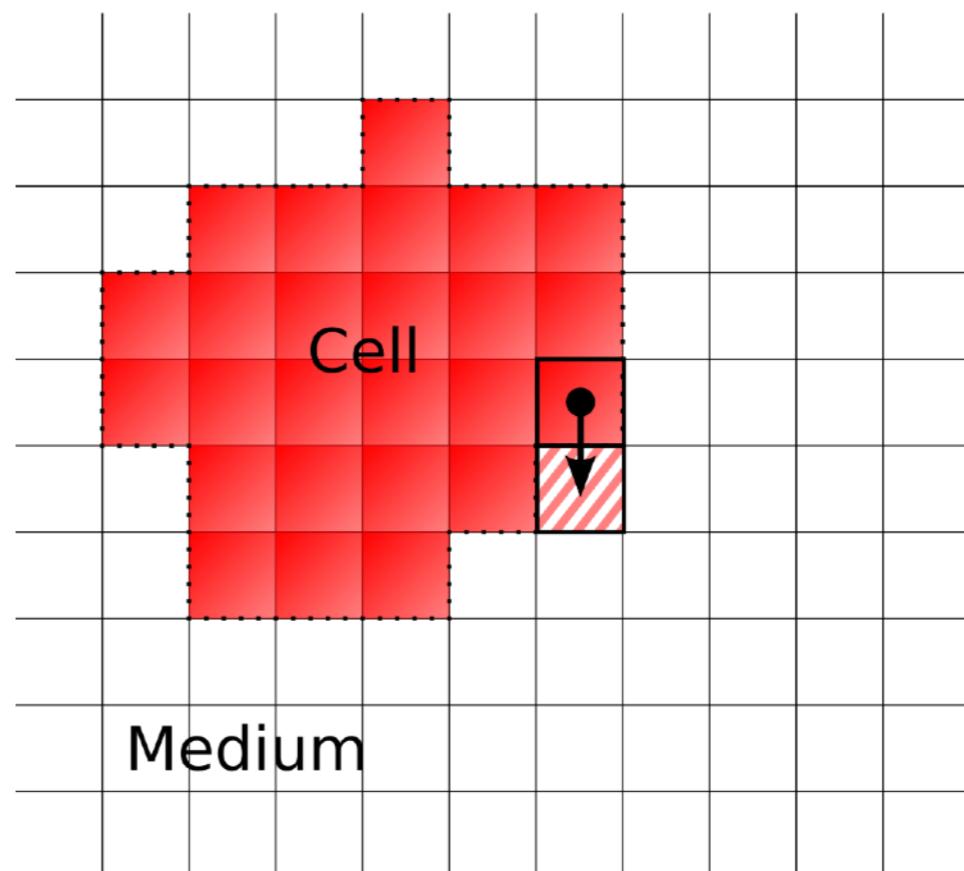


Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

- Pick a random node
- Pick a second random node in neighborhood

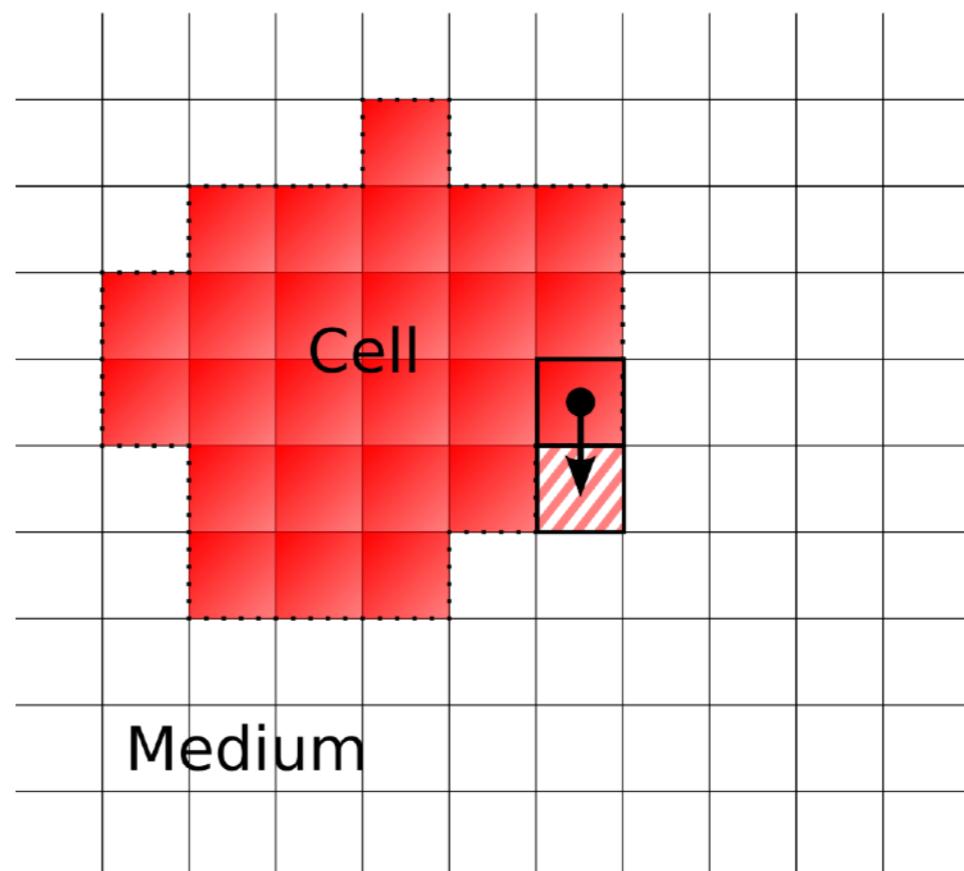


Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

- Pick a random node
- Pick a second random node in neighborhood
- Compute energy difference ΔH if spin is copied:



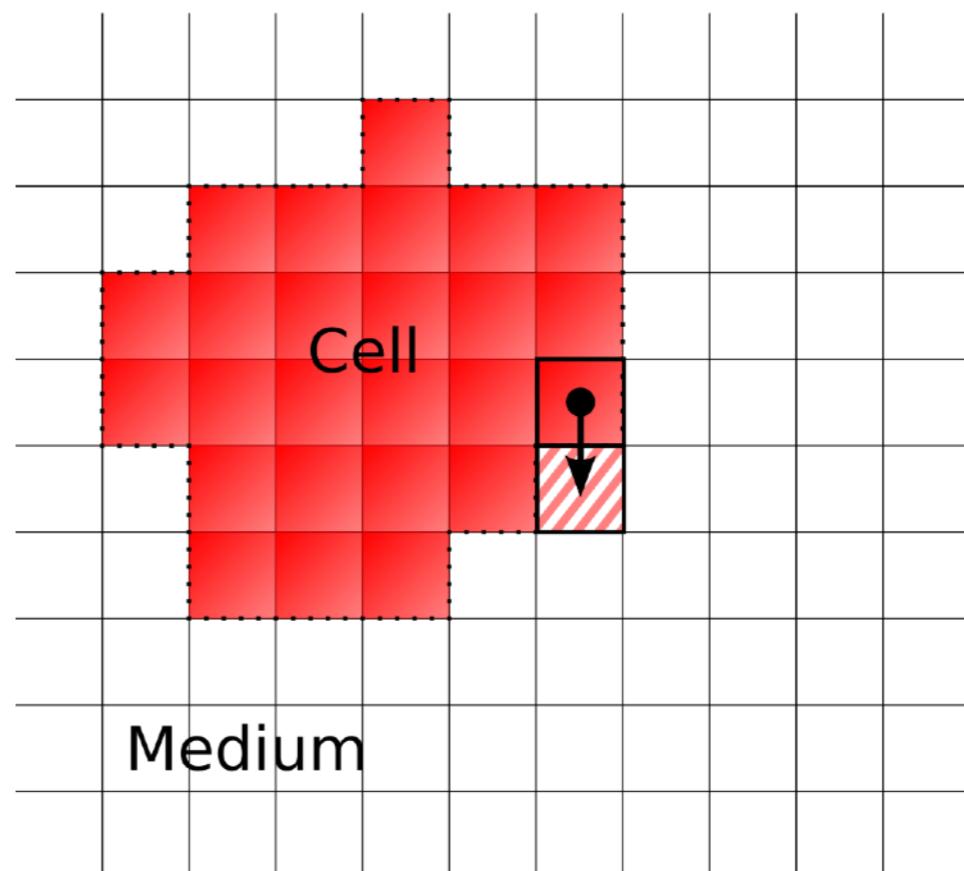
Cellular Potts model - dynamics

Stochastic minimization of energy

Modified Metropolis algorithm:

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$$\Delta H = H_{after} - H_{before}$$



Cellular Potts model - dynamics

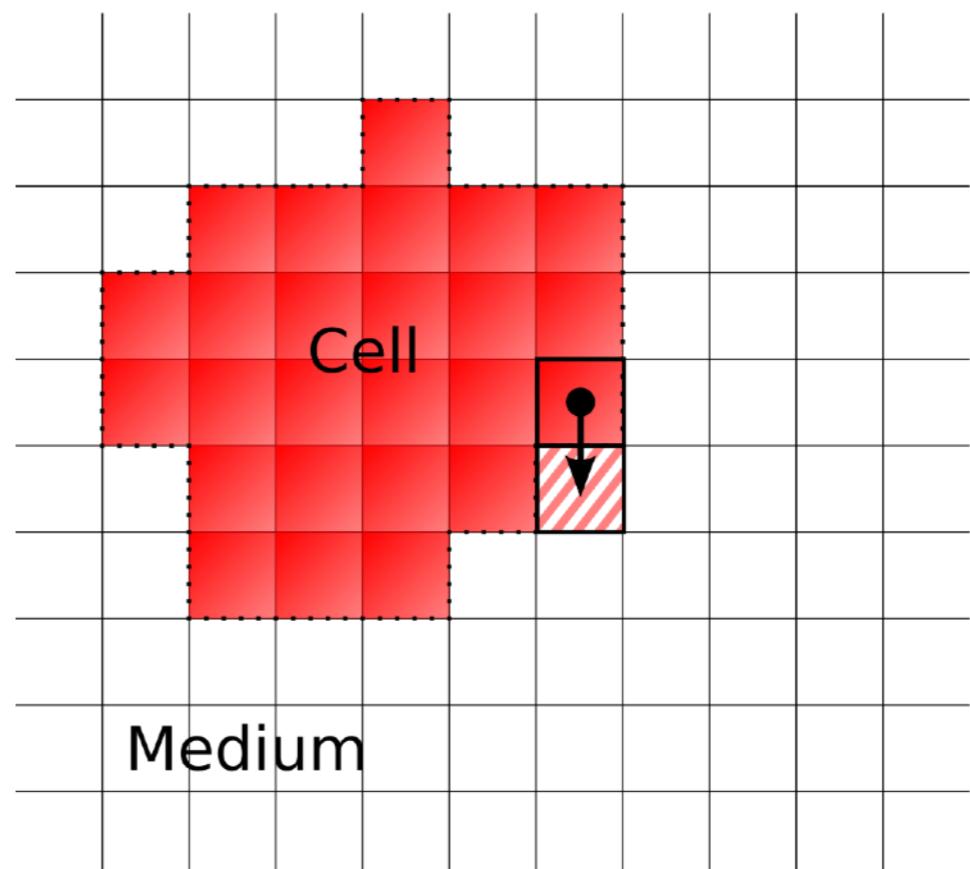
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- Probability to accept copy depends on ΔH :



Cellular Potts model - dynamics

Stochastic minimization of energy

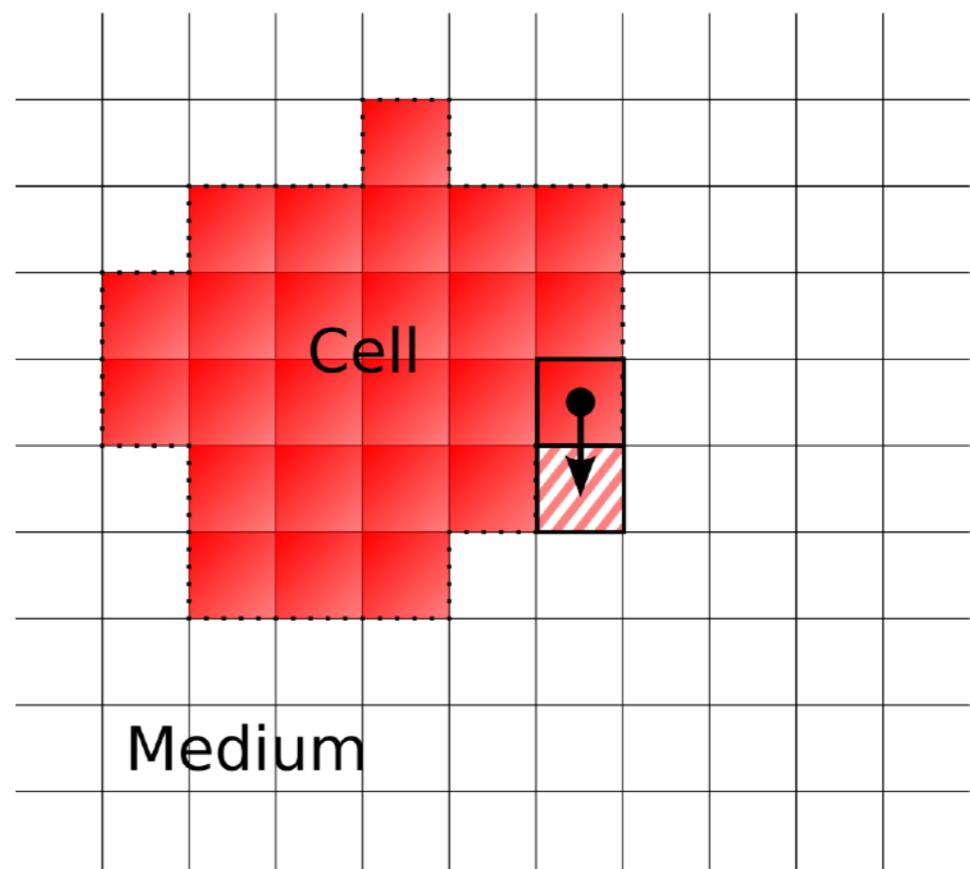
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- Probability to accept copy depends on ΔH :

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0 \\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$



Cellular Potts model - dynamics

Stochastic minimization of energy

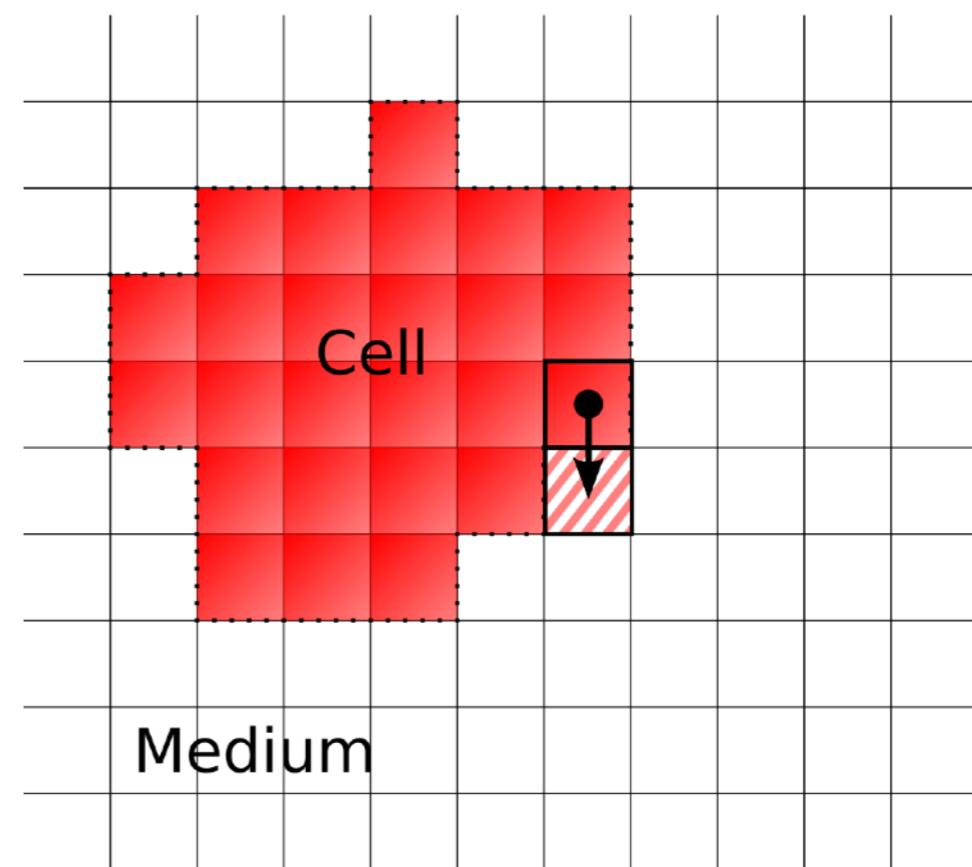
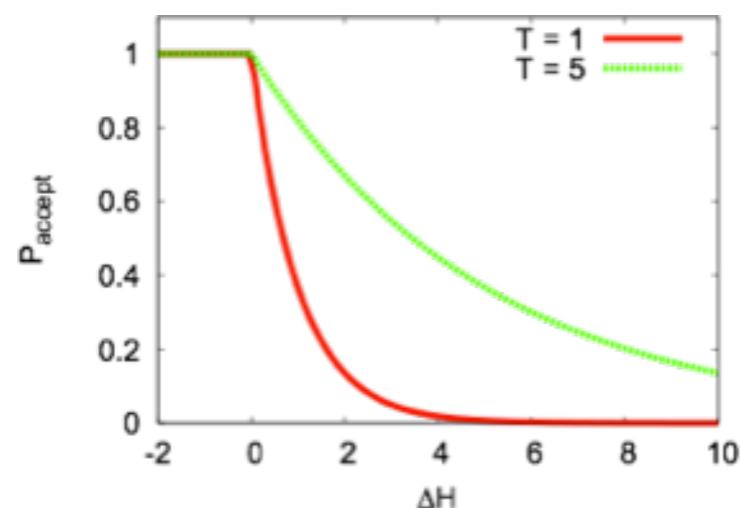
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Cellular Potts model - dynamics

Stochastic minimization of energy

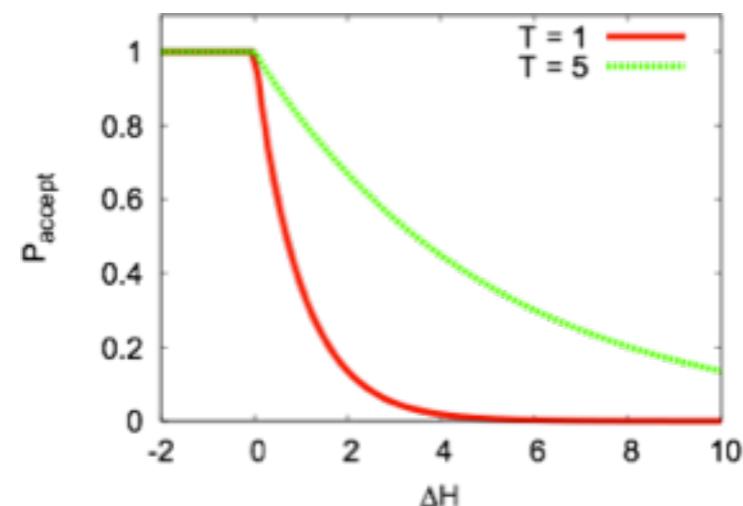
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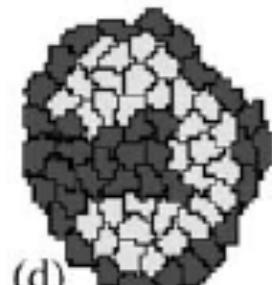
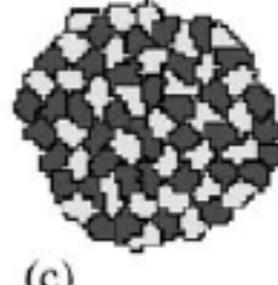
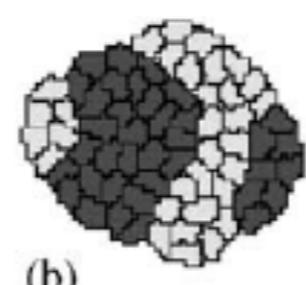
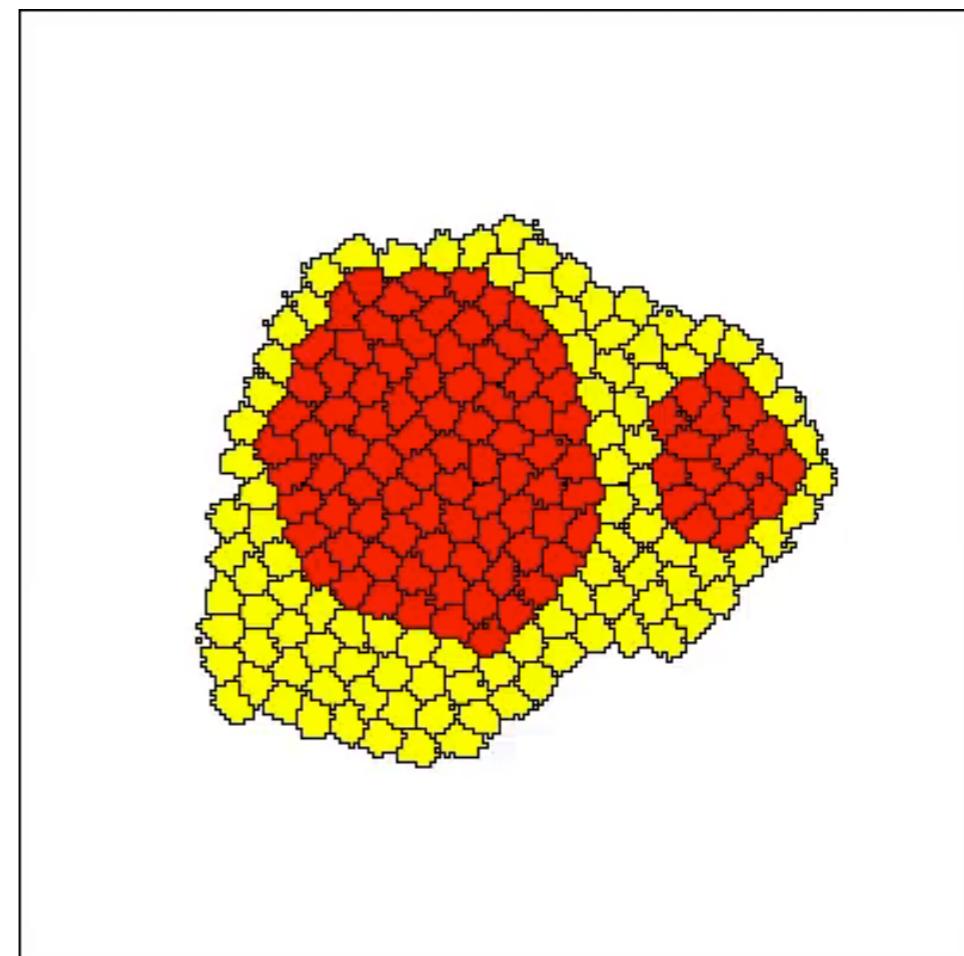
Cellular Potts model

Energy function (Hamiltonian):

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$

Energy minimization:

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0 \\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$



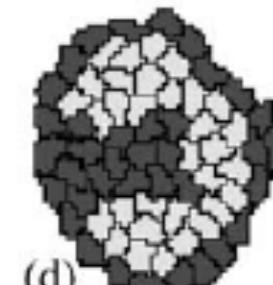
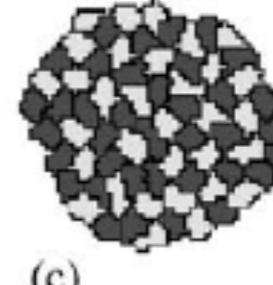
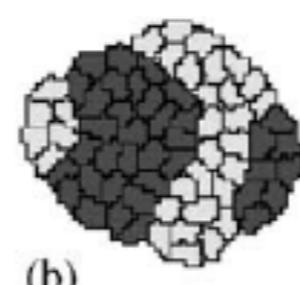
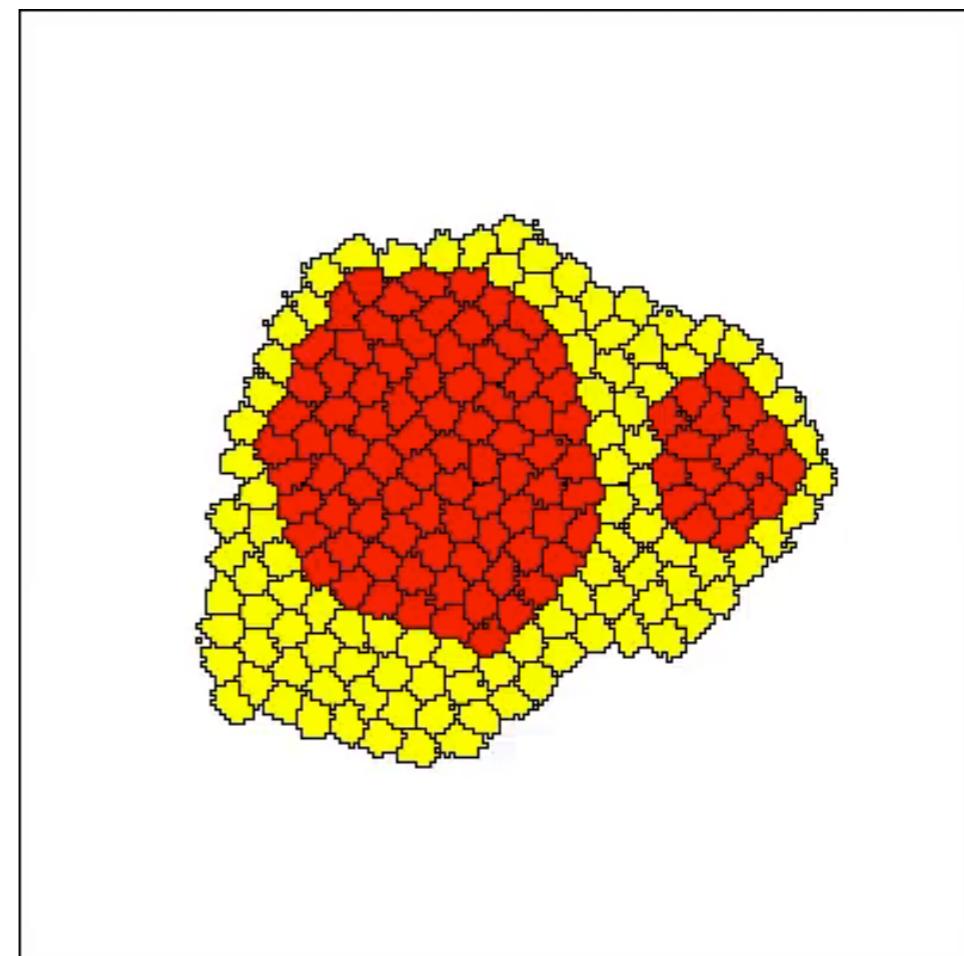
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Cellular Potts model

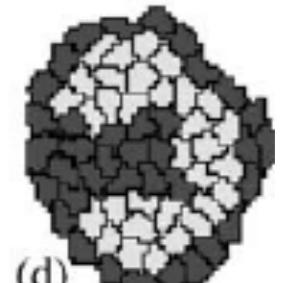
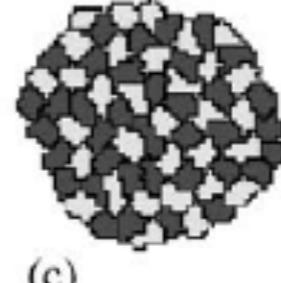
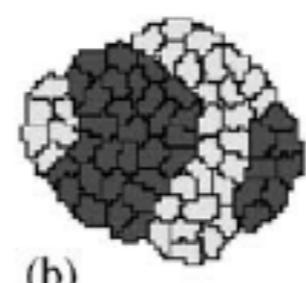
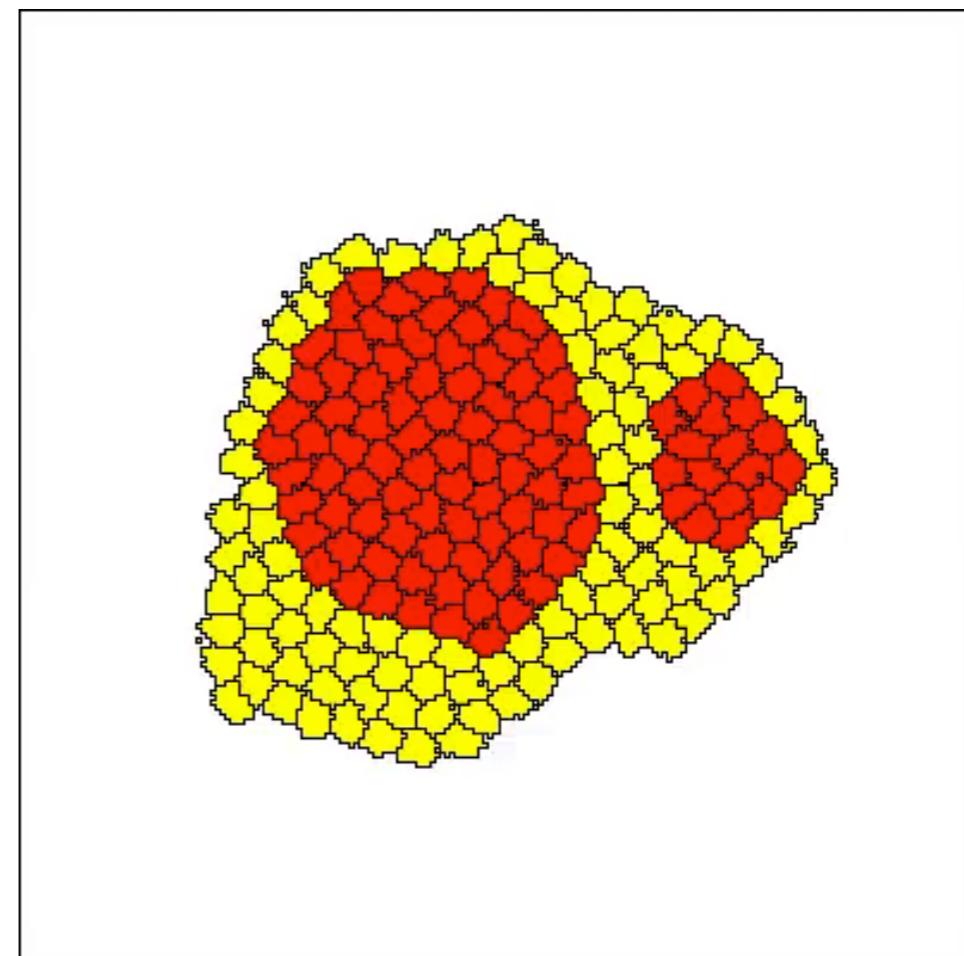
Energy function (Hamiltonian):

energy

$$H = \sum_{interfaces} J_{x,y} (1 - \delta_{x,y}) + \sum_{cells} \lambda_A (a_\sigma - A_\sigma)^2$$

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$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0 \\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$



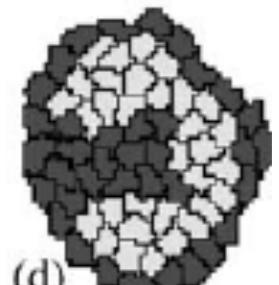
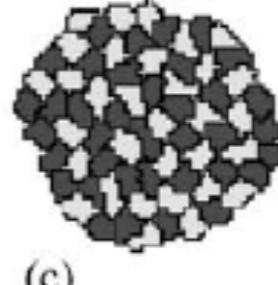
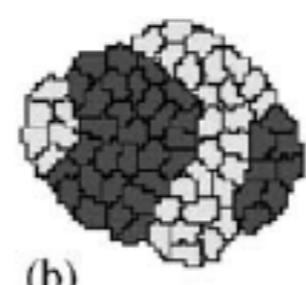
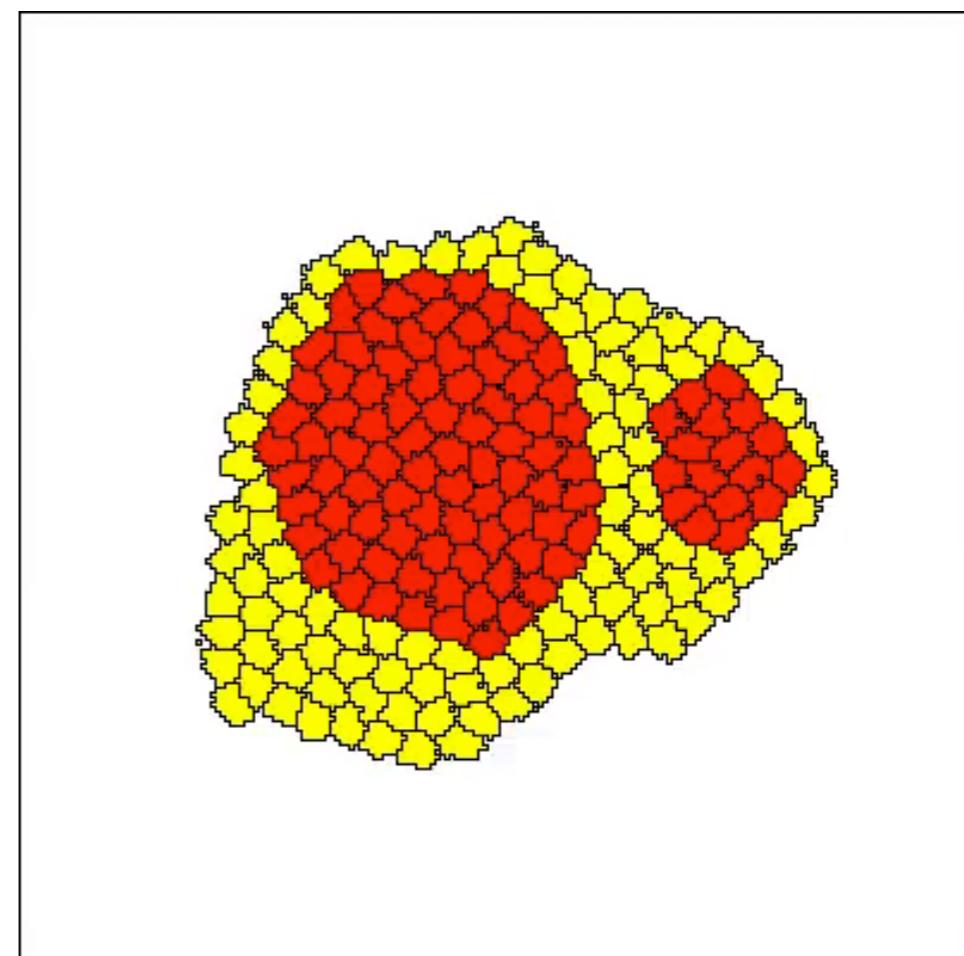
Cellular Potts model

Energy function (Hamiltonian):

$$\text{energy} \quad \text{adhesion}$$
$$H = \sum_{\text{interfaces}} J_{x,y} (1 - \delta_{x,y}) + \sum_{\text{cells}} \lambda_A (a_\sigma - A_\sigma)^2$$

Energy minimization:

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H \leq 0 \\ e^{-\frac{\Delta H}{T}} & \text{otherwise} \end{cases}$$



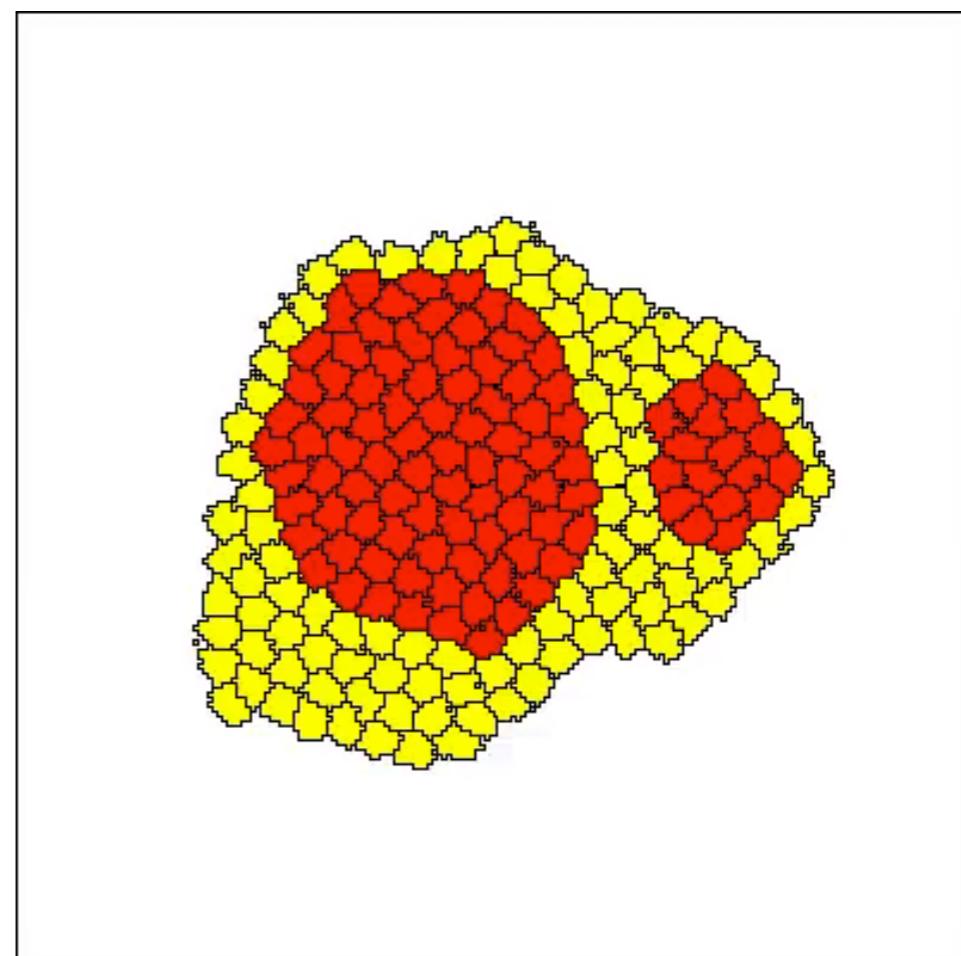
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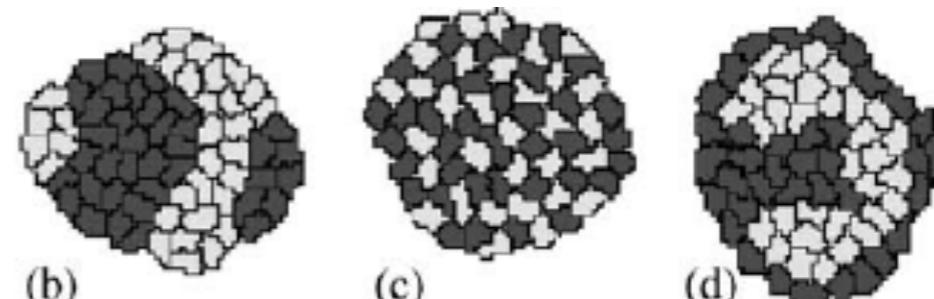
energy adhesion area constraint

| | |

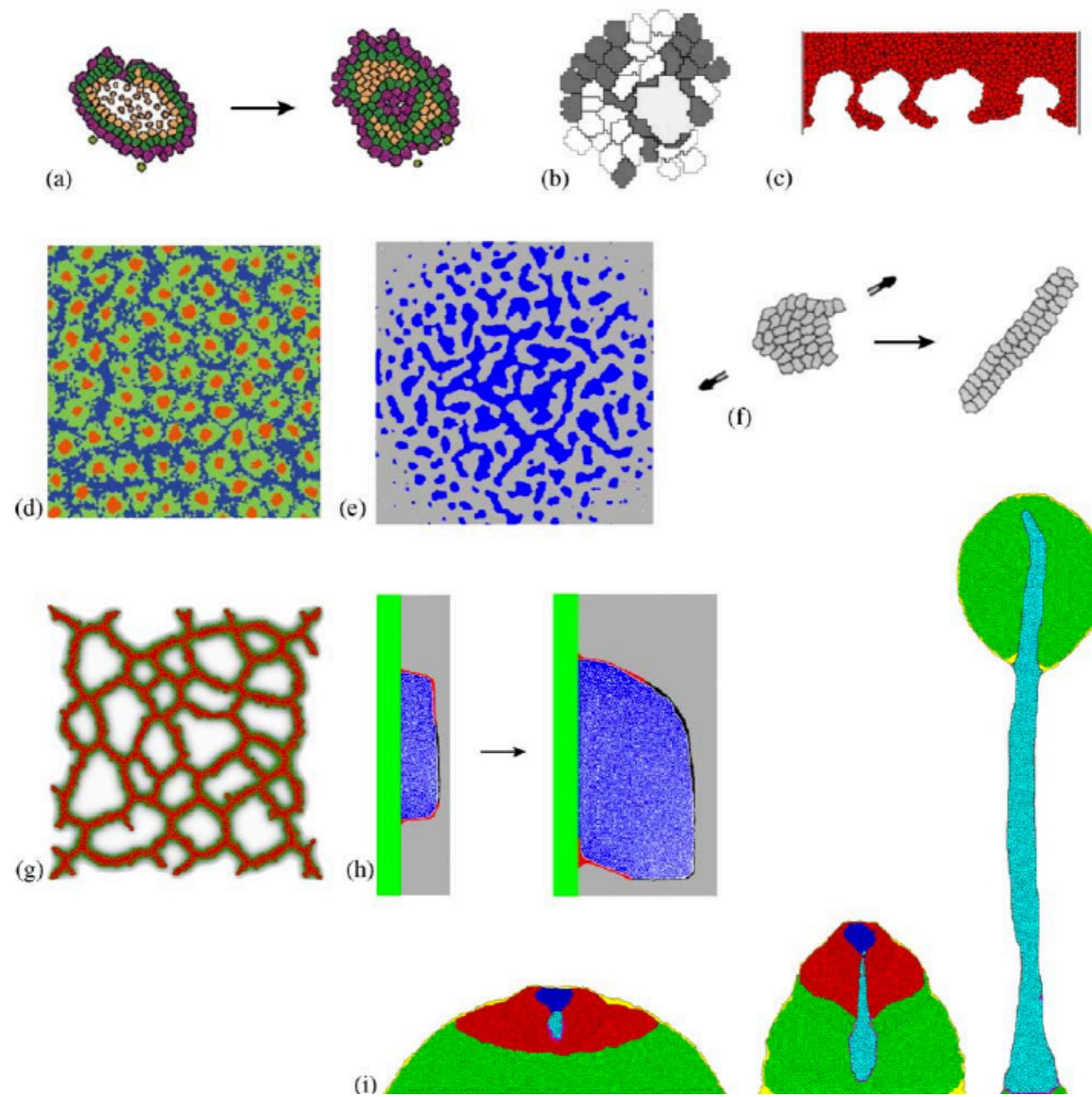


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Cellular Potts model



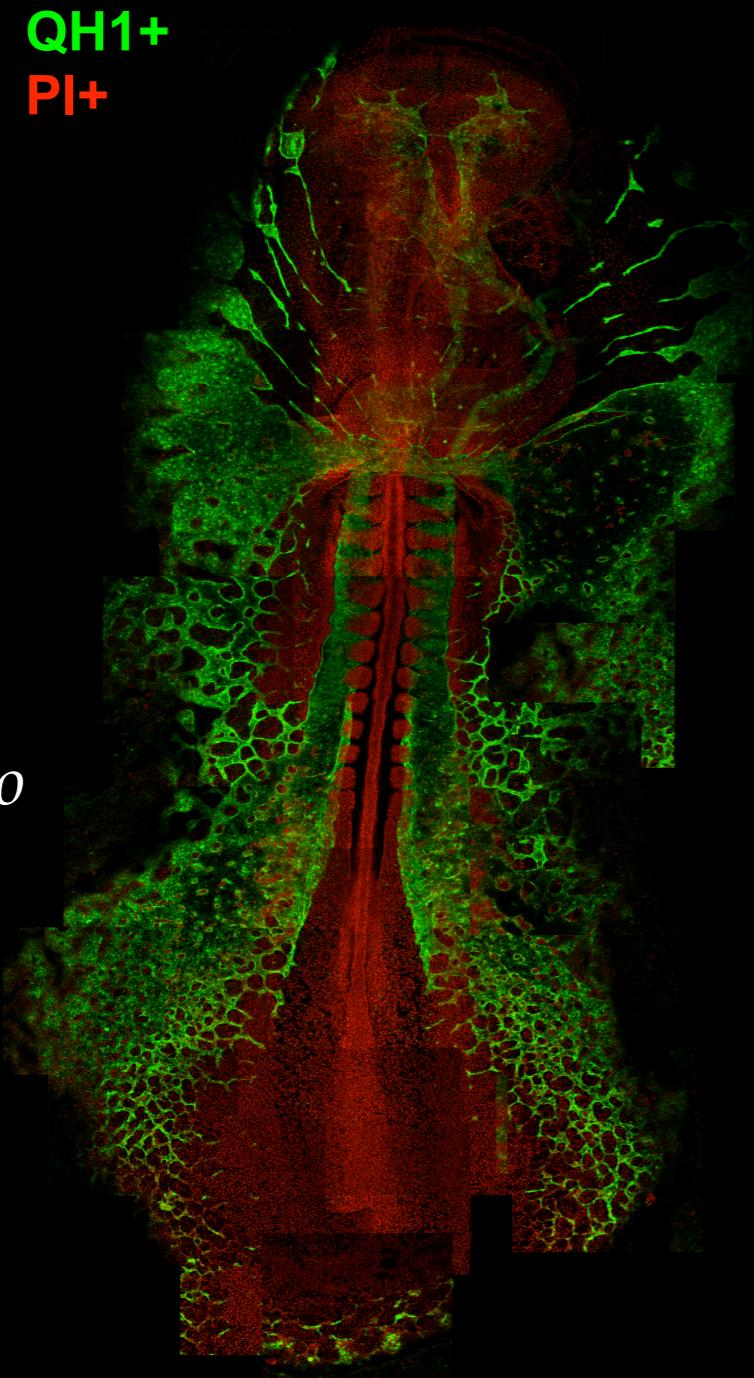
Vascular patterning

Example study

How do cells form a blood vessel network?



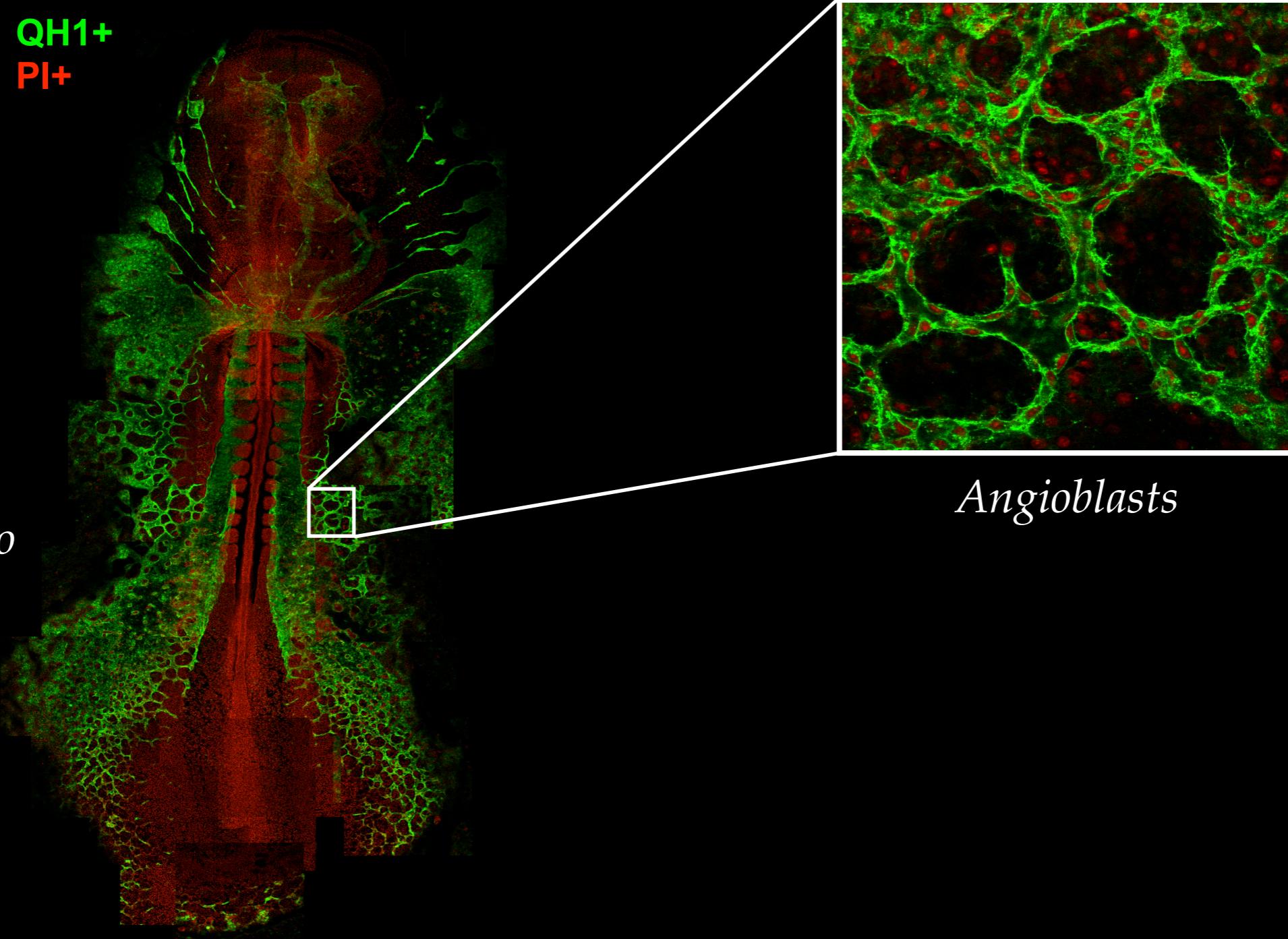
Quail embryo
HH stage 11



How do cells form a blood vessel network?



Quail embryo
HH stage 11

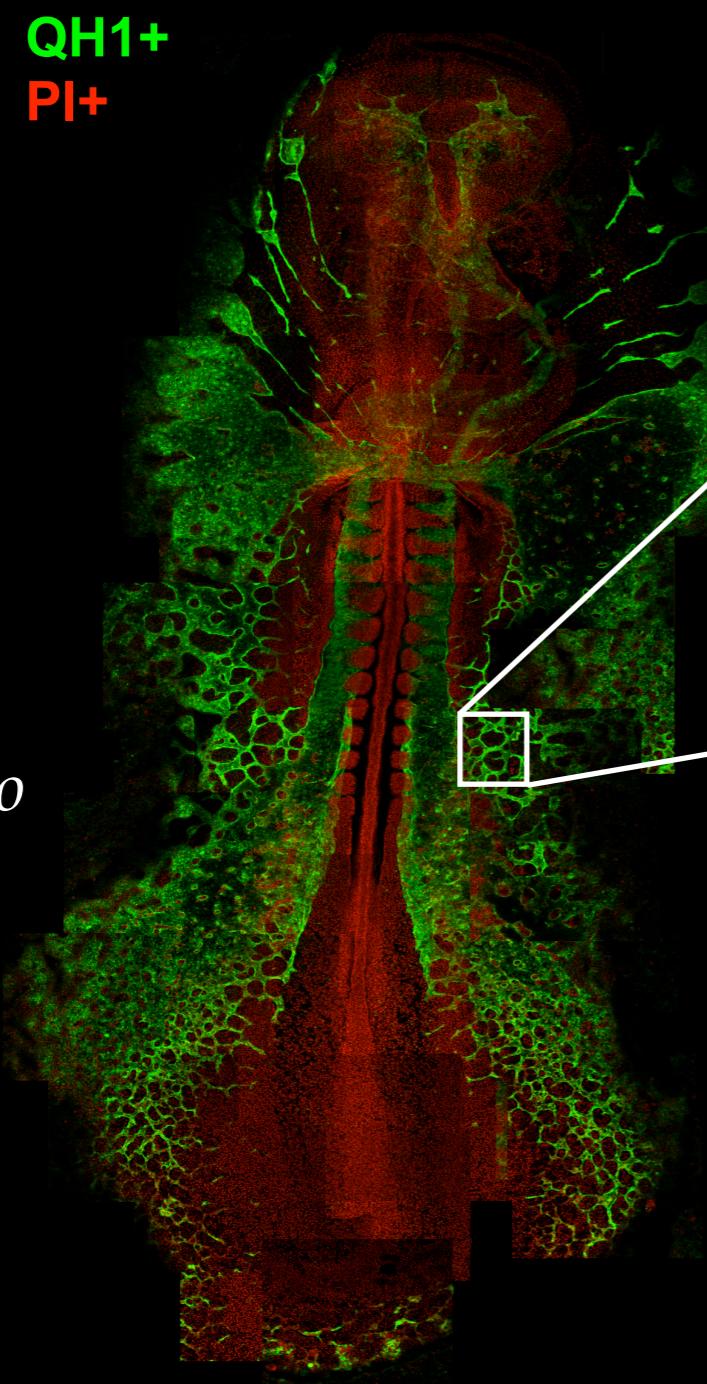


Angioblasts

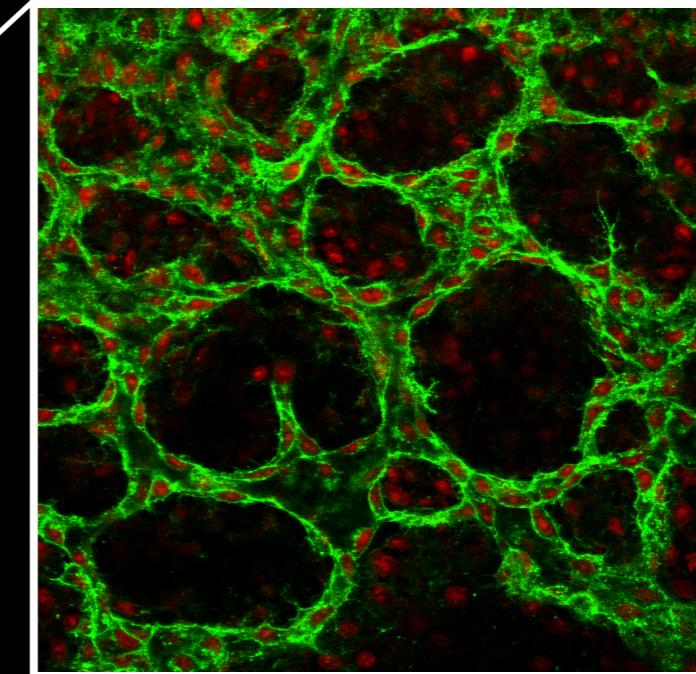
How do cells form a blood vessel network?



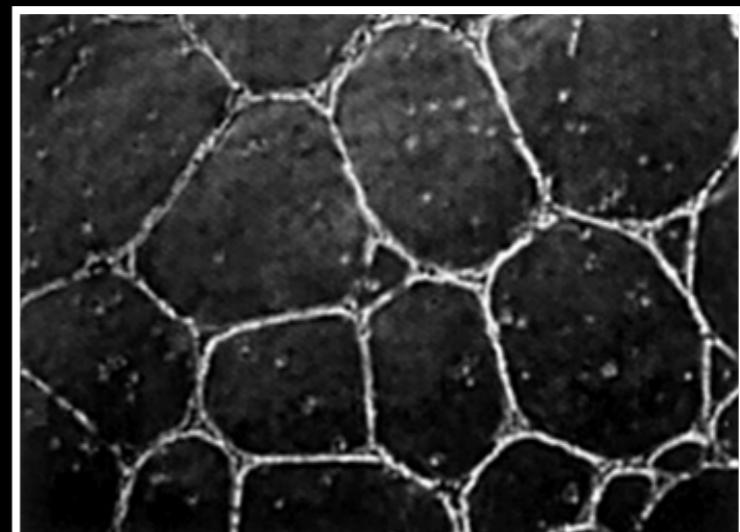
Quail embryo
HH stage 11



QH1+
PI+



Angioblasts

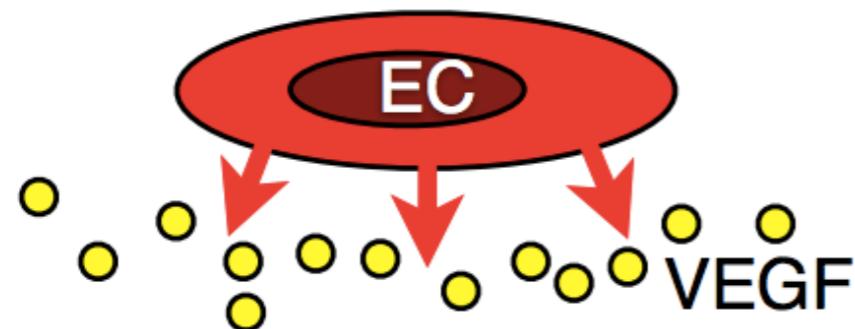


HUVEC in Matrigel

Chemotaxis model of vascular network formation

Autocrine chemotaxis model

VEGF = Vascular endothelial growth factor

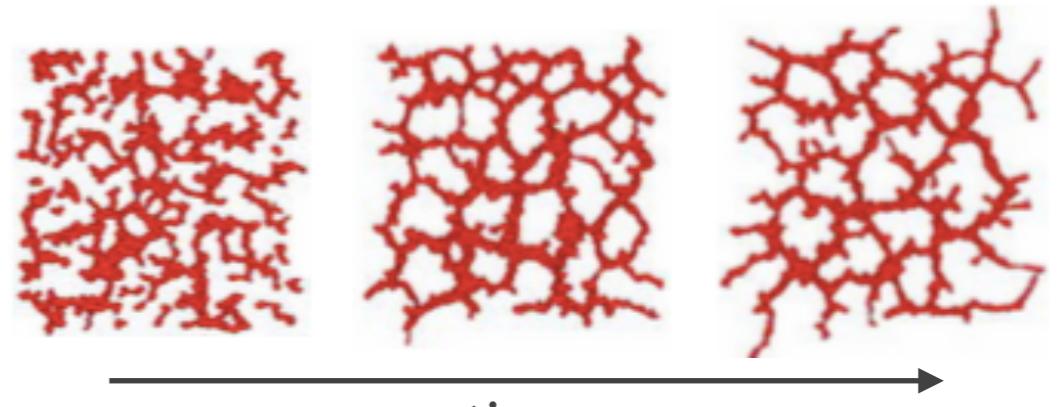
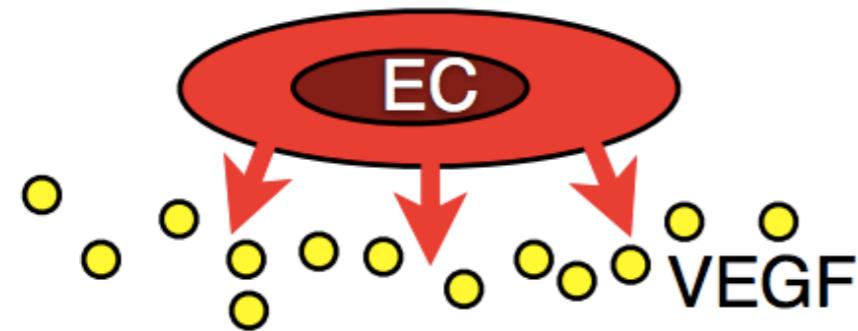


- Angioblasts produce VEGF
- Angioblasts migrate towards VEGF

Chemotaxis model of vascular network formation

Autocrine chemotaxis model

VEGF = Vascular endothelial growth factor

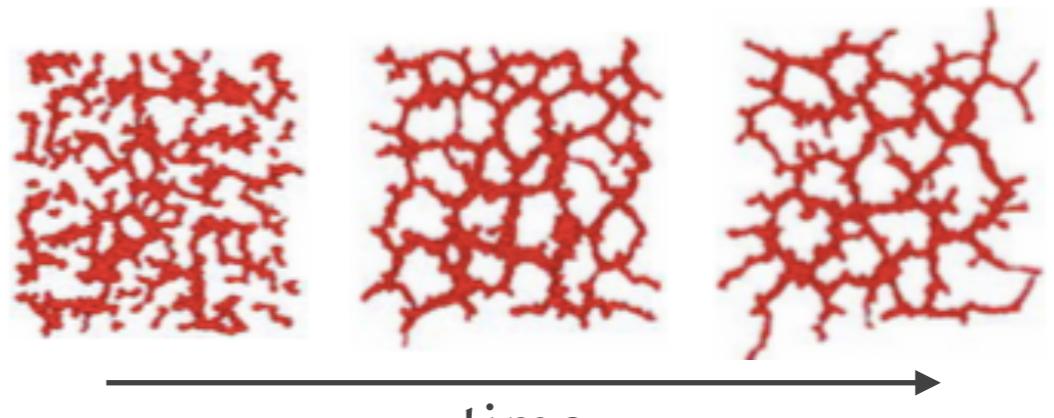
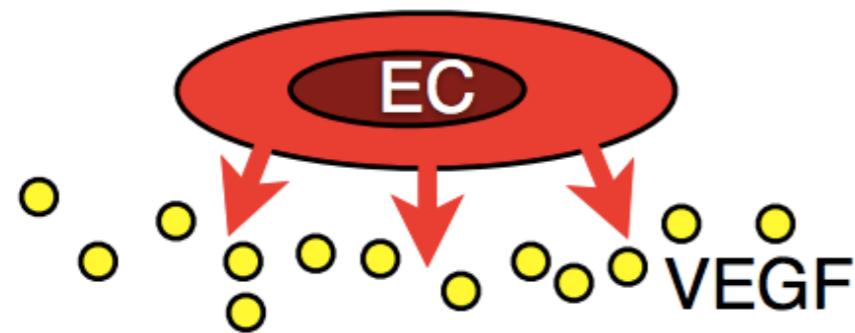


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Chemotaxis model of vascular network formation

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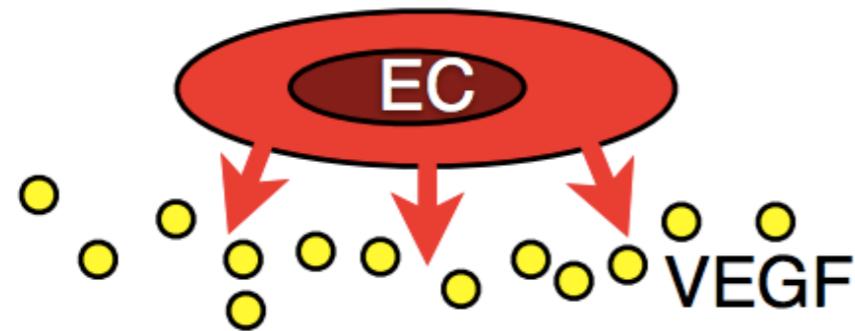
- Angioblasts produce VEGF
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However:

- Little evidence for VEGF production
- Unrealistically low diffusion rate

Chemotaxis model of vascular network formation

Autocrine chemotaxis model



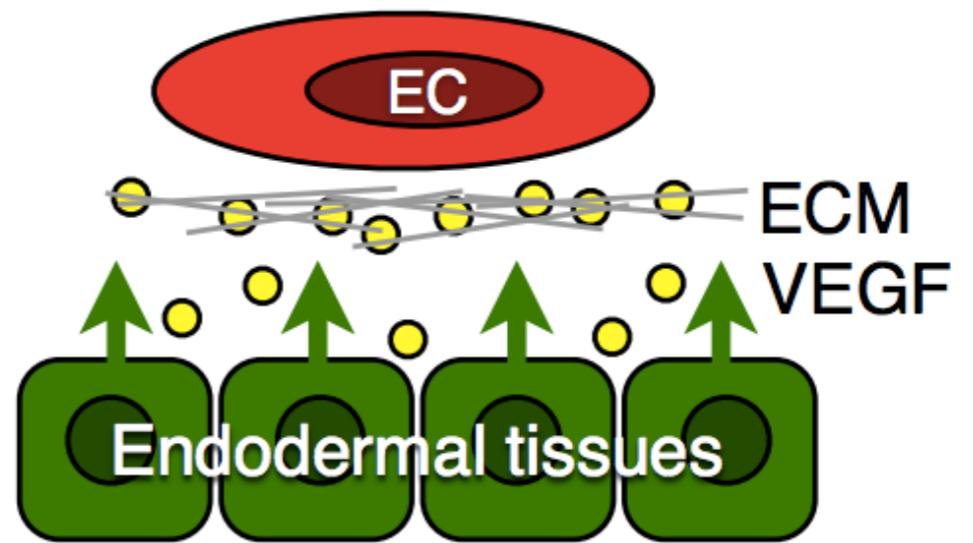
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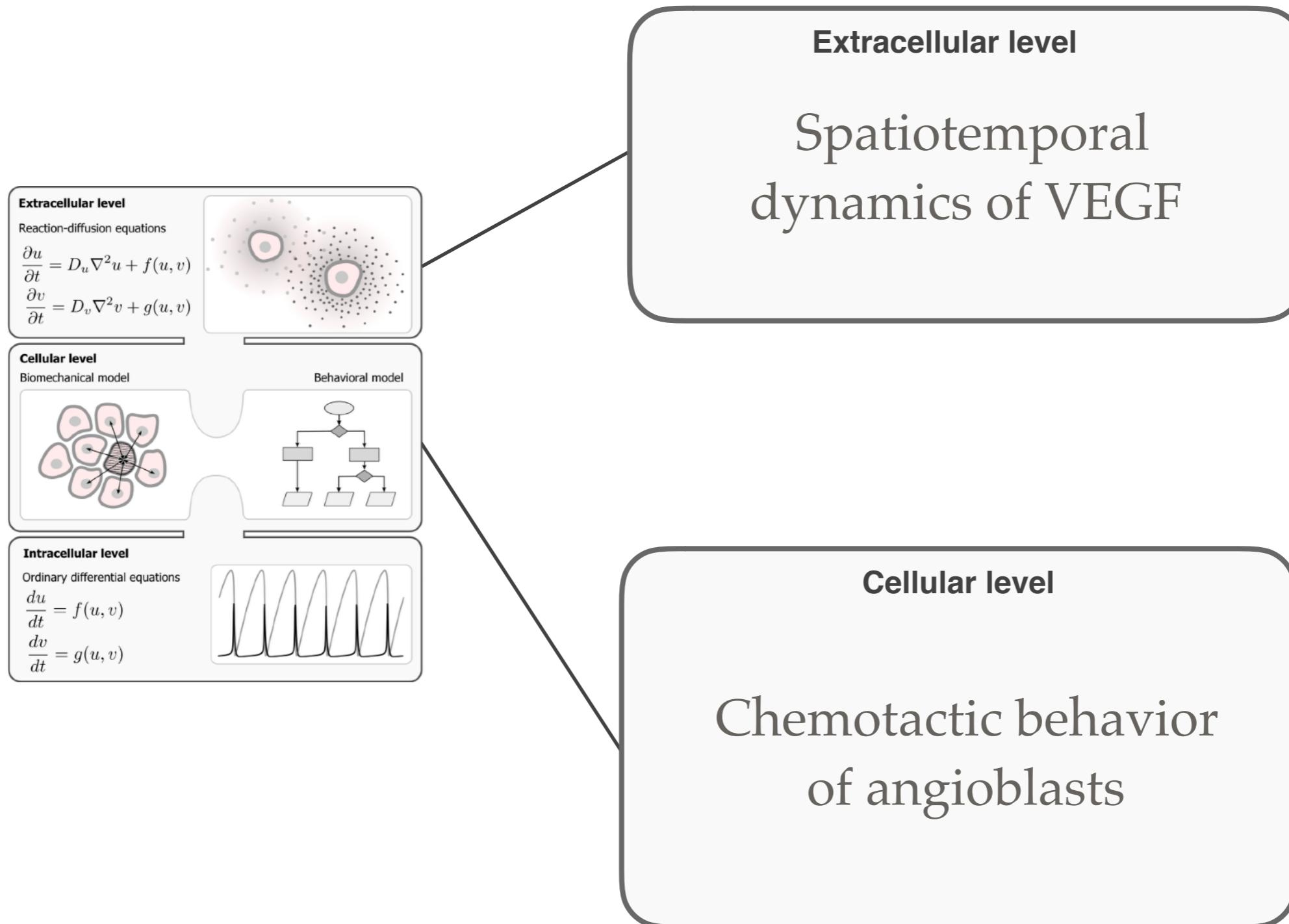
Paracrine chemotaxis model

ECM = Extra-cellular matrix



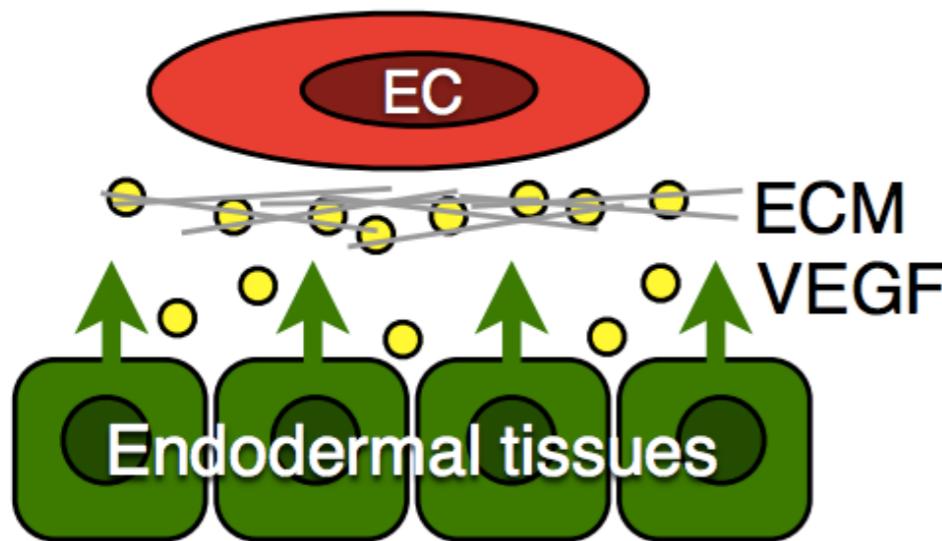
- Endoderm produces VEGF
- Angioblasts modify ECM
- VEGF binds to modified ECM
- Angioblasts migrate to bound VEGF

Modeling approach



Spatiotemporal dynamics of VEGF

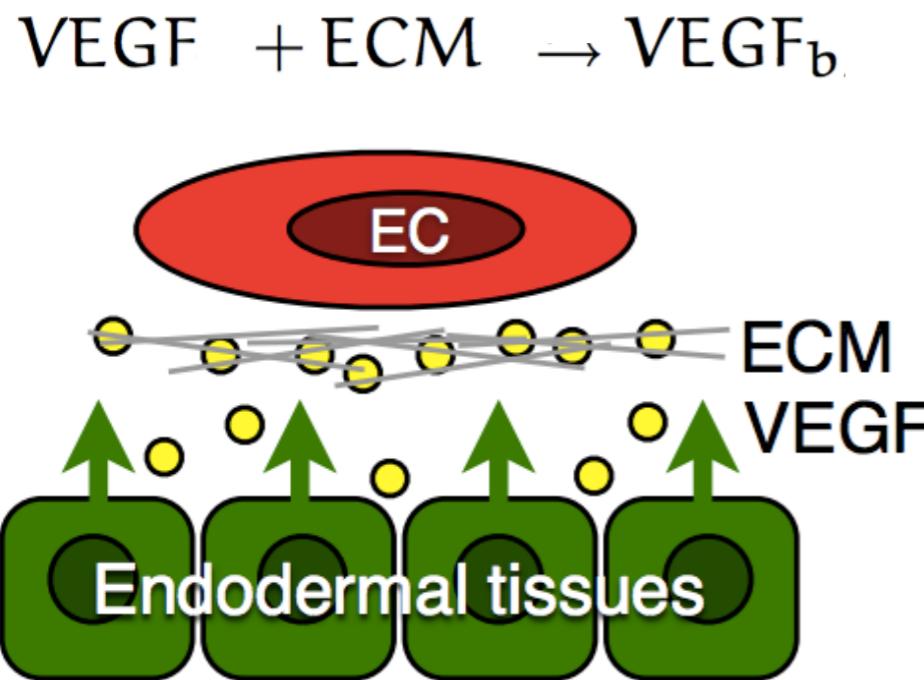
Reaction-diffusion model



$$\begin{aligned}\frac{\partial u}{\partial t} &= D\Delta u + \gamma_1 - f(u, v) - \delta u \\ \frac{\partial v}{\partial t} &= \gamma_2 \delta_{\sigma_{x,0}} - f(u, v) \\ \frac{\partial w}{\partial t} &= f(u, v)\end{aligned}$$

Spatiotemporal dynamics of VEGF

Reaction-diffusion model

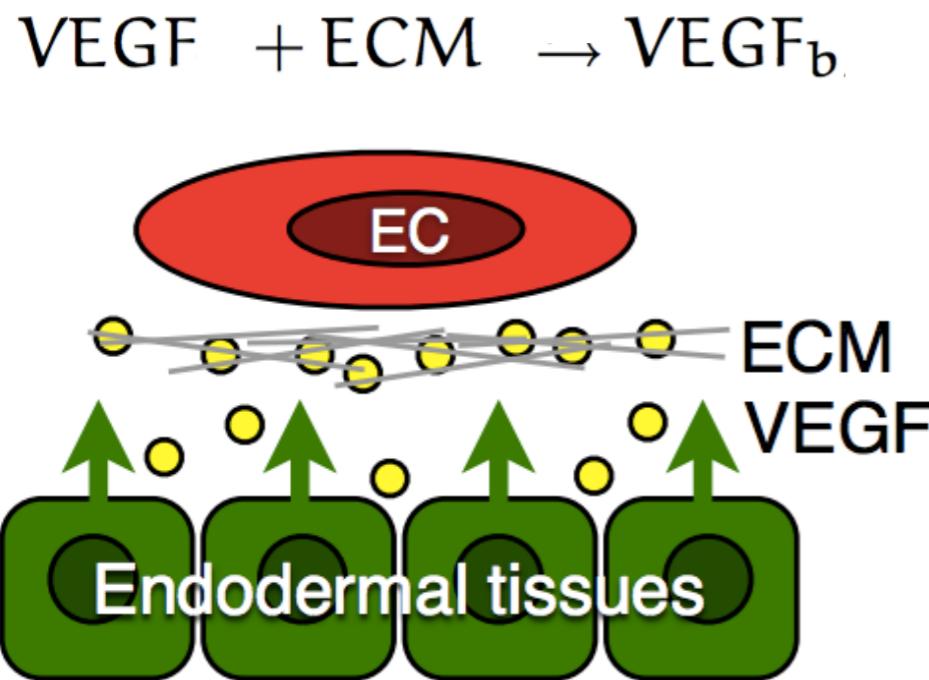


Diffusion

$$\begin{aligned} \text{VEGF}_s & \quad \frac{\partial u}{\partial t} = D \Delta u + \gamma_1 - f(u, v) - \delta u \\ \text{ECM} & \quad \frac{\partial v}{\partial t} = \gamma_2 \delta_{\sigma_{x,0}} - f(u, v) \\ \text{VEGF}_b & \quad \frac{\partial w}{\partial t} = f(u, v) \end{aligned}$$

Spatiotemporal dynamics of VEGF

Reaction-diffusion model



Diffusion

VEGF production by endoderm

VEGF_s

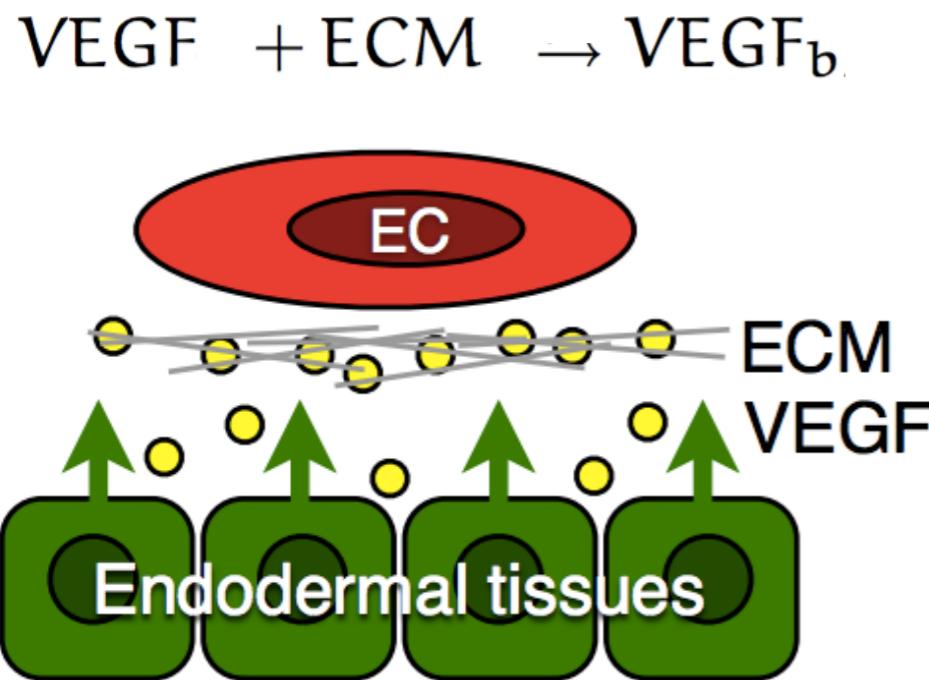
ECM

VEGF_b

$$\frac{\partial u}{\partial t} = D \Delta u + \gamma_1 - f(u, v) - \delta u$$
$$\frac{\partial v}{\partial t} = \gamma_2 \delta_{\sigma_x, 0} - f(u, v)$$
$$\frac{\partial w}{\partial t} = f(u, v)$$

Spatiotemporal dynamics of VEGF

Reaction-diffusion model



VEGF_s $\frac{\partial u}{\partial t} = D\Delta u + \gamma_1 - f(u, v) - \delta u$

ECM $\frac{\partial v}{\partial t} = \gamma_2 \delta_{\sigma_{x,0}} - f(u, v)$

VEGF_b $\frac{\partial w}{\partial t} = f(u, v)$

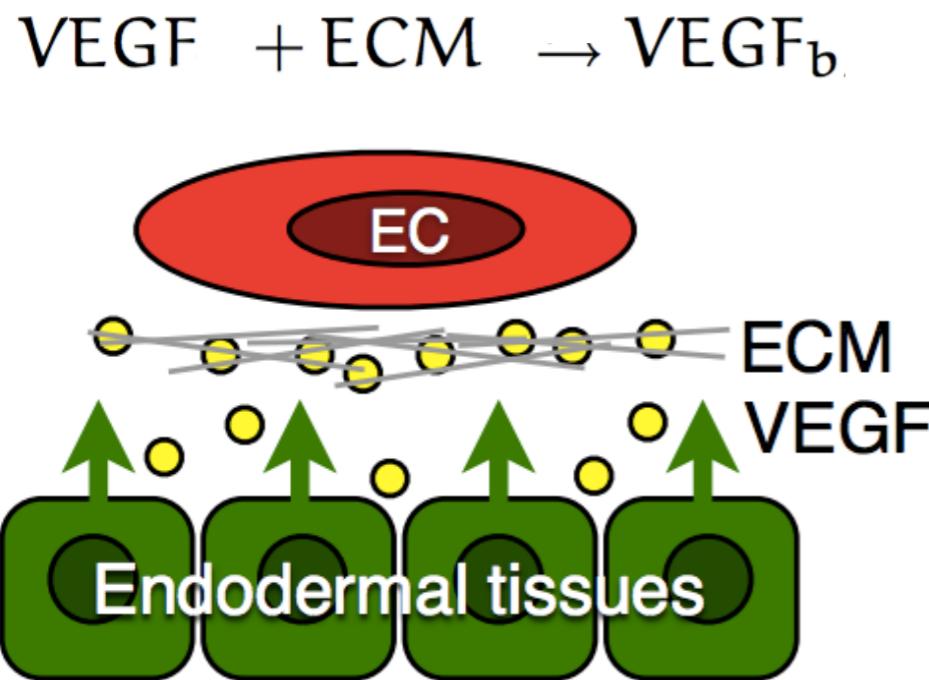
Diffusion

VEGF production by endoderm

Decay

Spatiotemporal dynamics of VEGF

Reaction-diffusion model



Diffusion

VEGF_s

ECM

VEGF_b

VEGF production by endoderm

Decay

$\frac{\partial u}{\partial t} = D \Delta u + \gamma_1 - f(u, v) - \delta u$

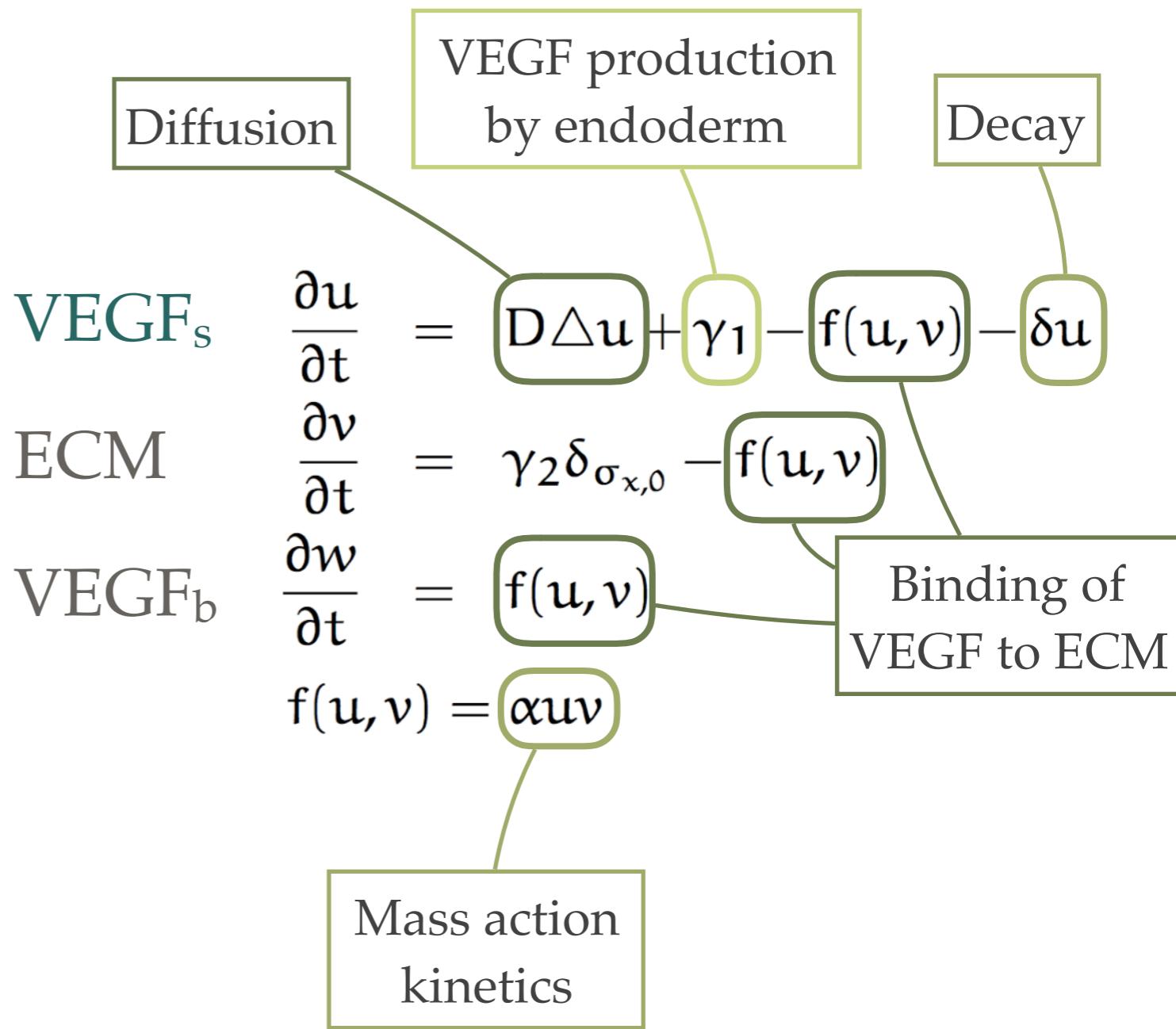
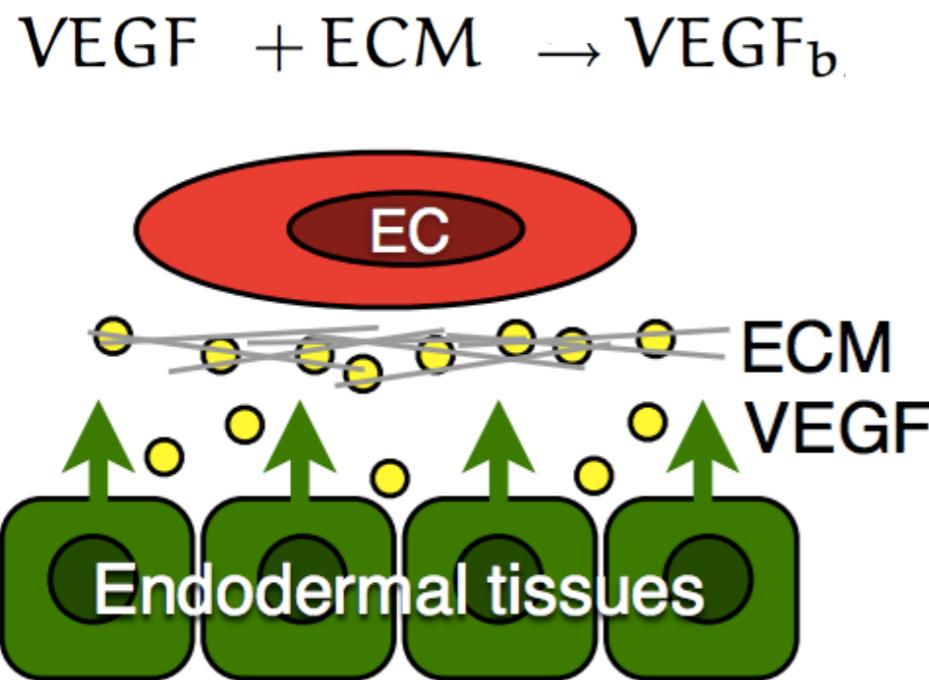
$\frac{\partial v}{\partial t} = \gamma_2 \delta_{\sigma_{x,0}} - f(u, v)$

$\frac{\partial w}{\partial t} = f(u, v)$

Binding of VEGF to ECM

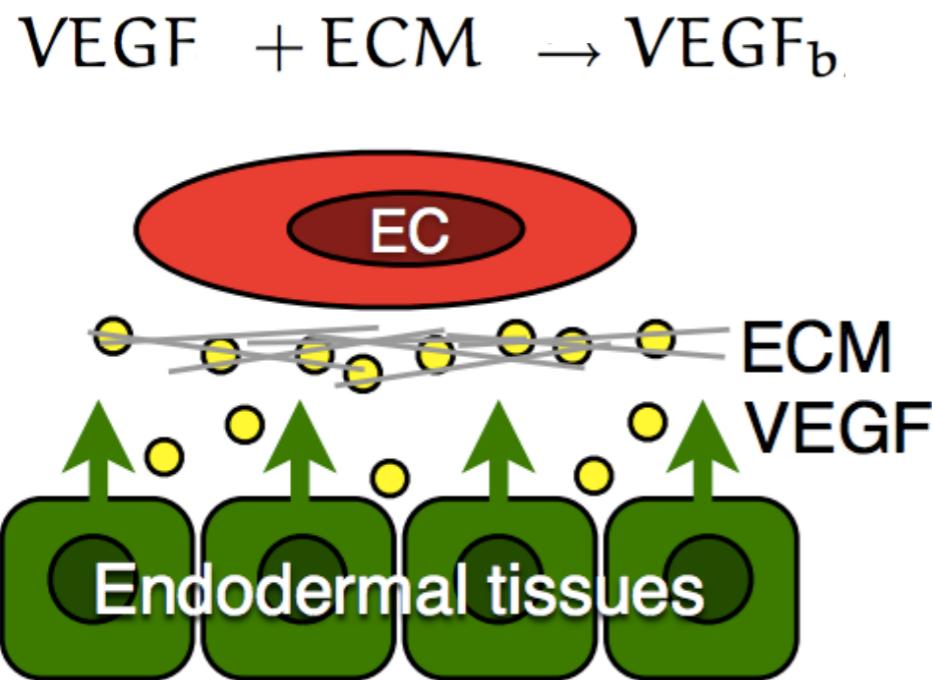
Spatiotemporal dynamics of VEGF

Reaction-diffusion model



Spatiotemporal dynamics of VEGF

Reaction-diffusion model



VEGF_s ECM VEGF_b

Diffusion

$$\frac{\partial u}{\partial t} = D \Delta u + \gamma_1 - f(u, v) - \delta u$$

VEGF production by endoderm

$$\frac{\partial v}{\partial t} = \gamma_2 \delta_{\sigma_x, 0} - f(u, v)$$

Decay

$$\frac{\partial w}{\partial t} = f(u, v)$$

Binding of VEGF to ECM

$$f(u, v) = \alpha u v$$

Mass action kinetics

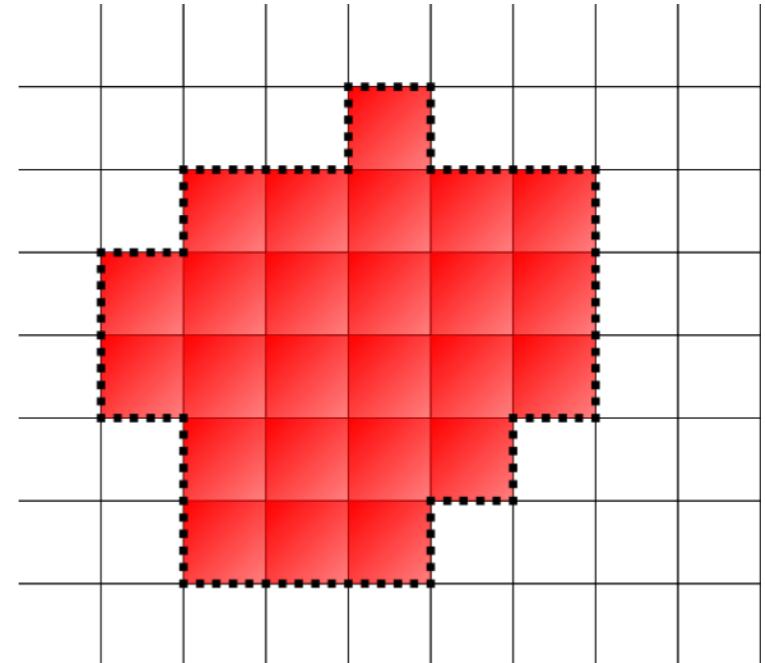
Cell-dependent ECM modification

Chemotaxis of angioblasts

Cellular Potts model

Energy function

$$H = \sum_{\sigma>0} (\lambda_a (a_\sigma - A)^2 + \lambda_p p_\sigma)$$



Chemotaxis of angioblasts

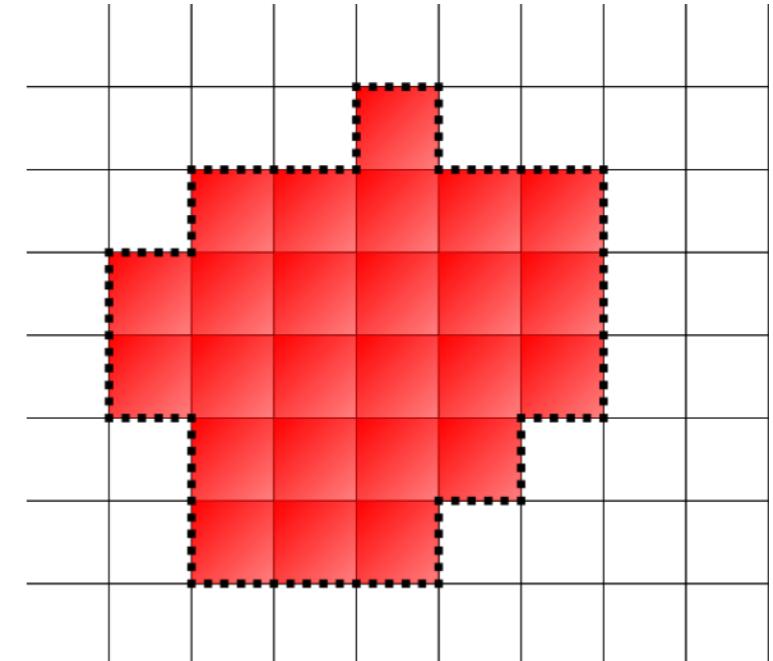
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$$H = \sum_{\sigma > 0} (\lambda_a (a_\sigma - A)^2 + \lambda_p p_\sigma)$$

Number of 

Target number of 



Chemotaxis of angioblasts

Cellular Potts model

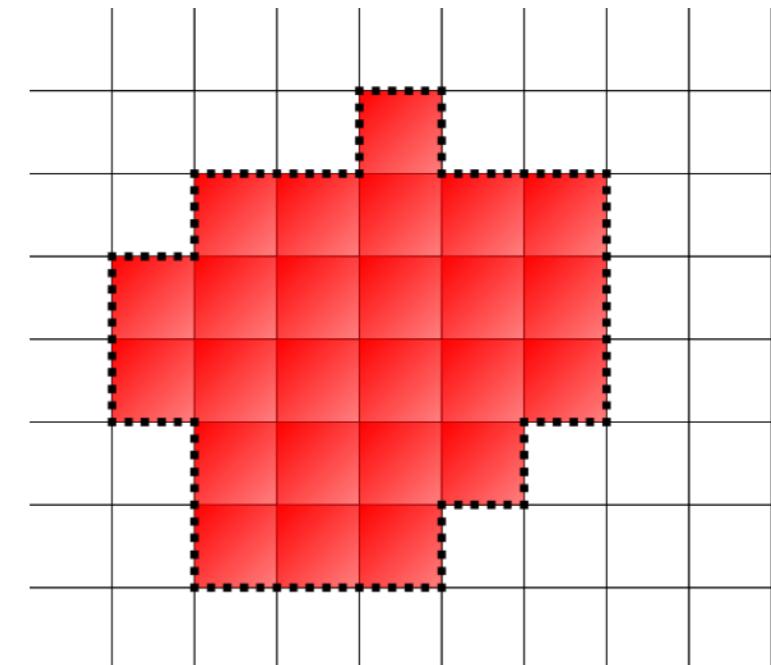
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Number of

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Chemotaxis of angioblasts

Cellular Potts model

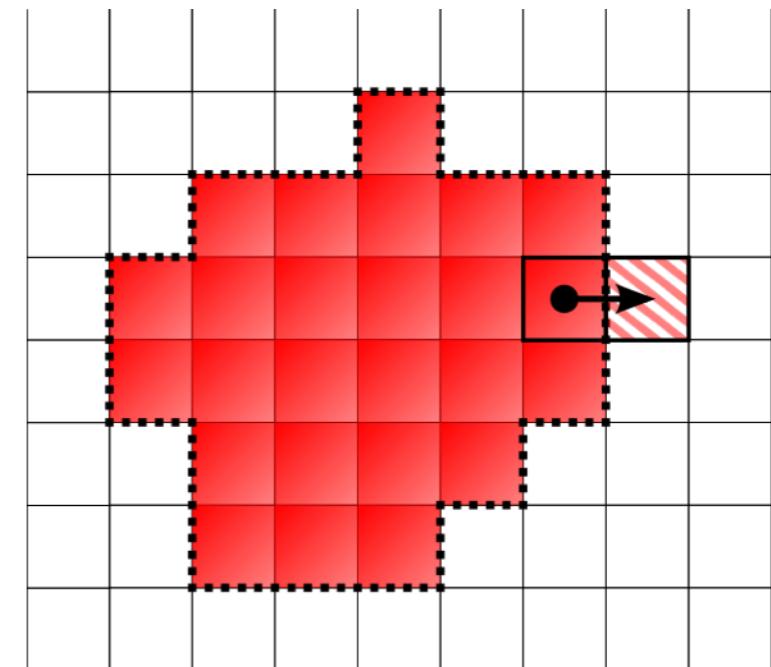
Energy function

$$H = \sum_{\sigma > 0} (\lambda_a (a_\sigma - A)^2 + \lambda_p p_\sigma)$$

Number of :

Number of

Target number of



Chemotaxis of angioblasts

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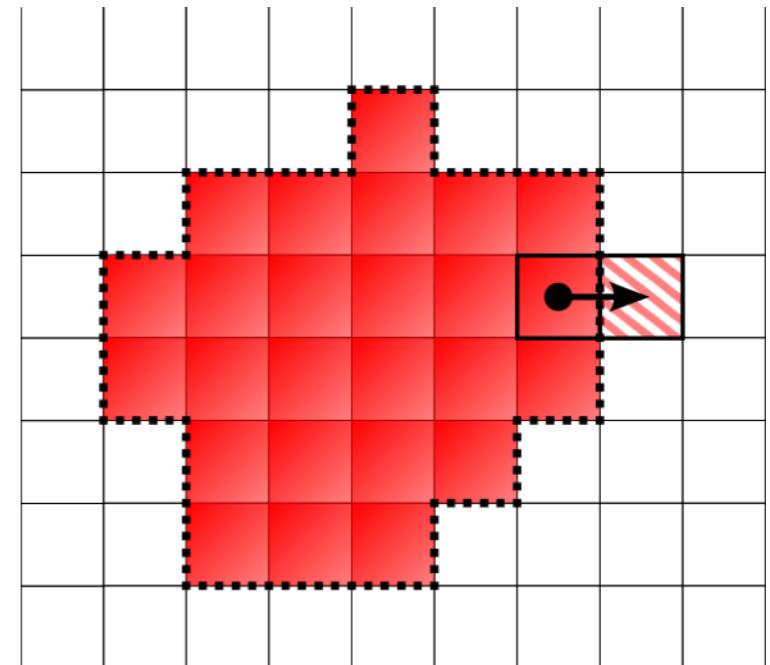
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Number of :

Number of ■

Target number of ■



Metropolis kinetics

$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H < 0 \\ e^{\frac{-(\Delta H)}{T}} & \text{otherwise} \end{cases}$$

Chemotaxis of angioblasts

Cellular Potts model

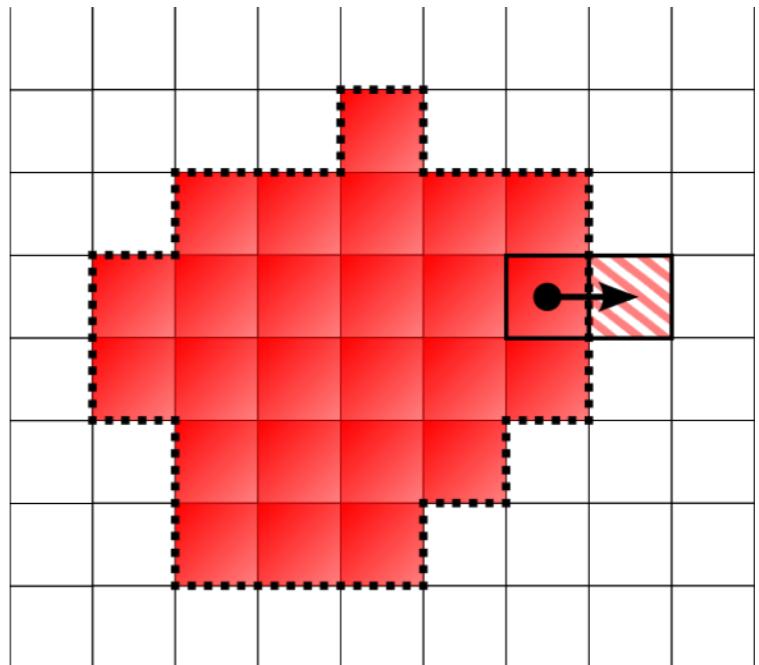
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Number of 

Target number of 

Number of :

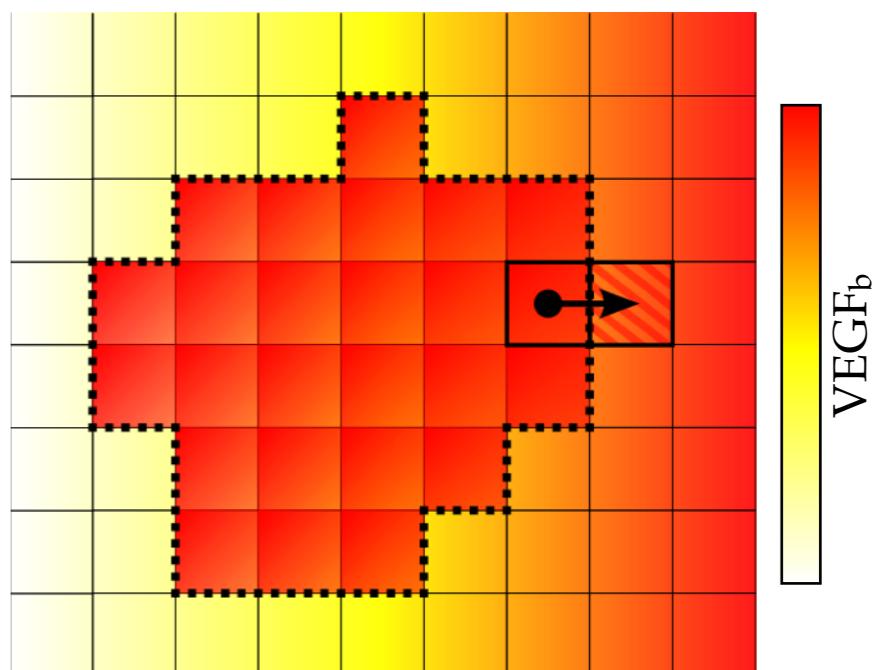


Metropolis kinetics

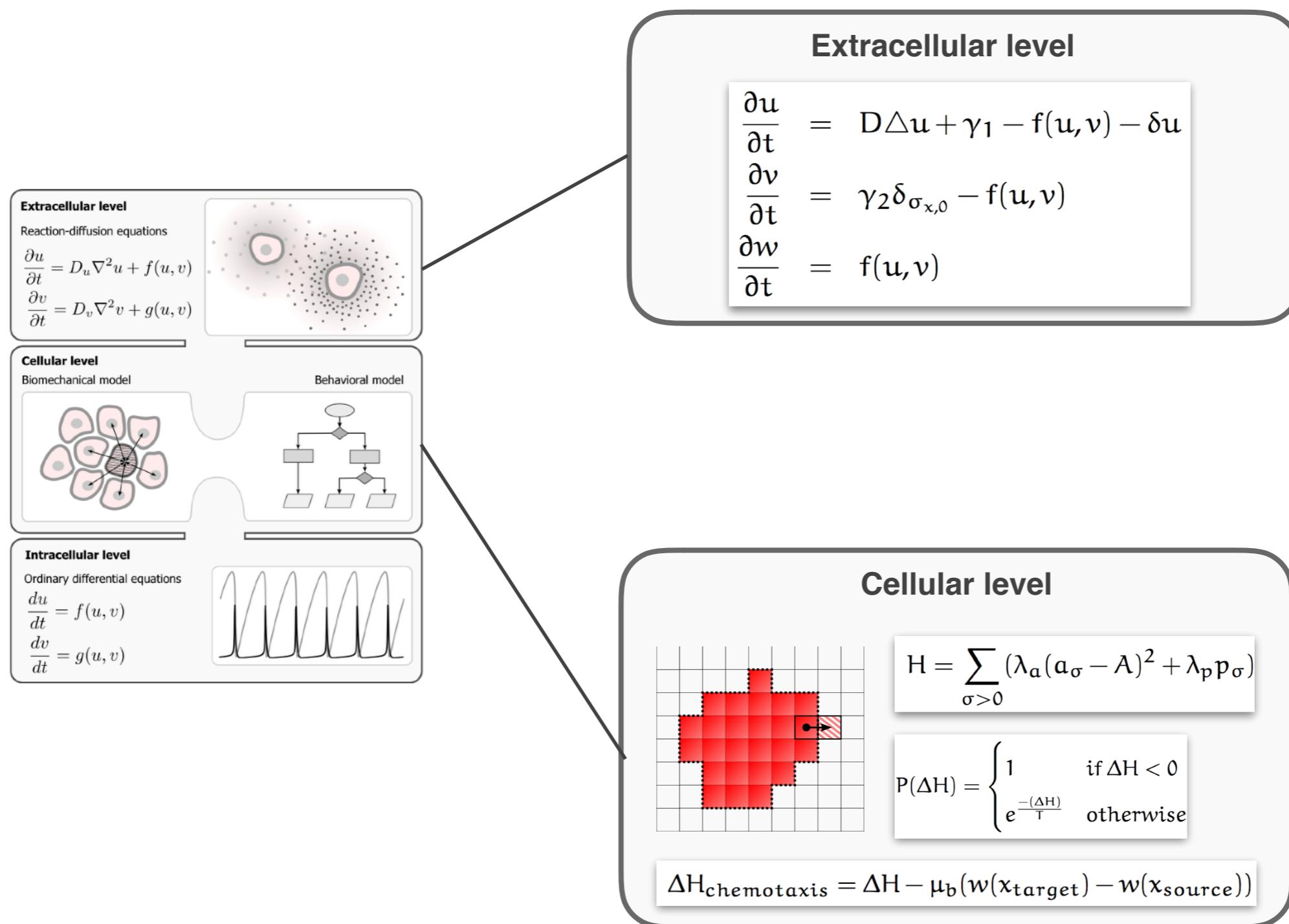
$$P(\Delta H) = \begin{cases} 1 & \text{if } \Delta H < 0 \\ e^{\frac{-(\Delta H)}{T}} & \text{otherwise} \end{cases}$$

Chemotaxis

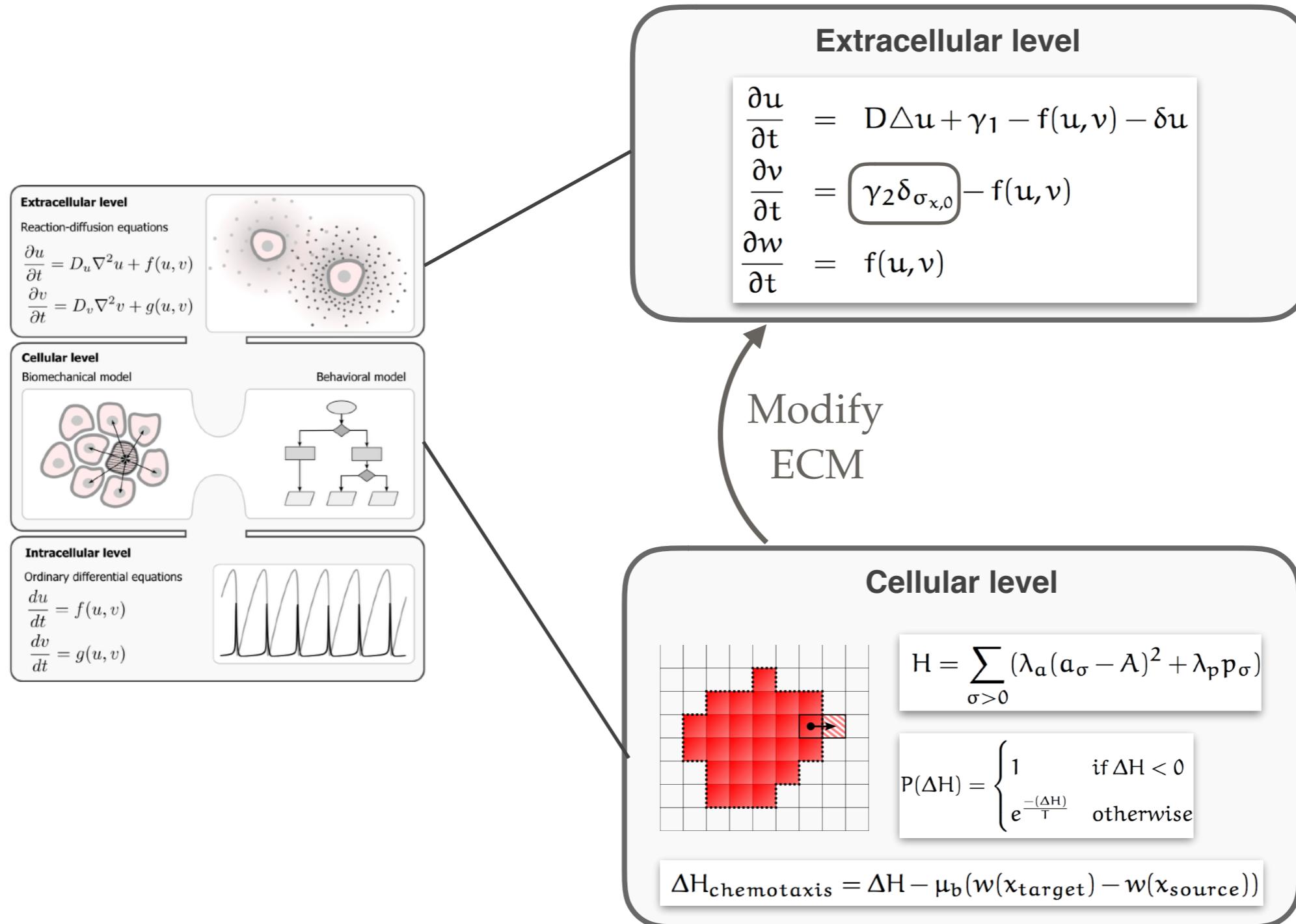
$$\Delta H_{\text{chemotaxis}} = \Delta H - \mu_b (w(x_{\text{target}}) - w(x_{\text{source}}))$$



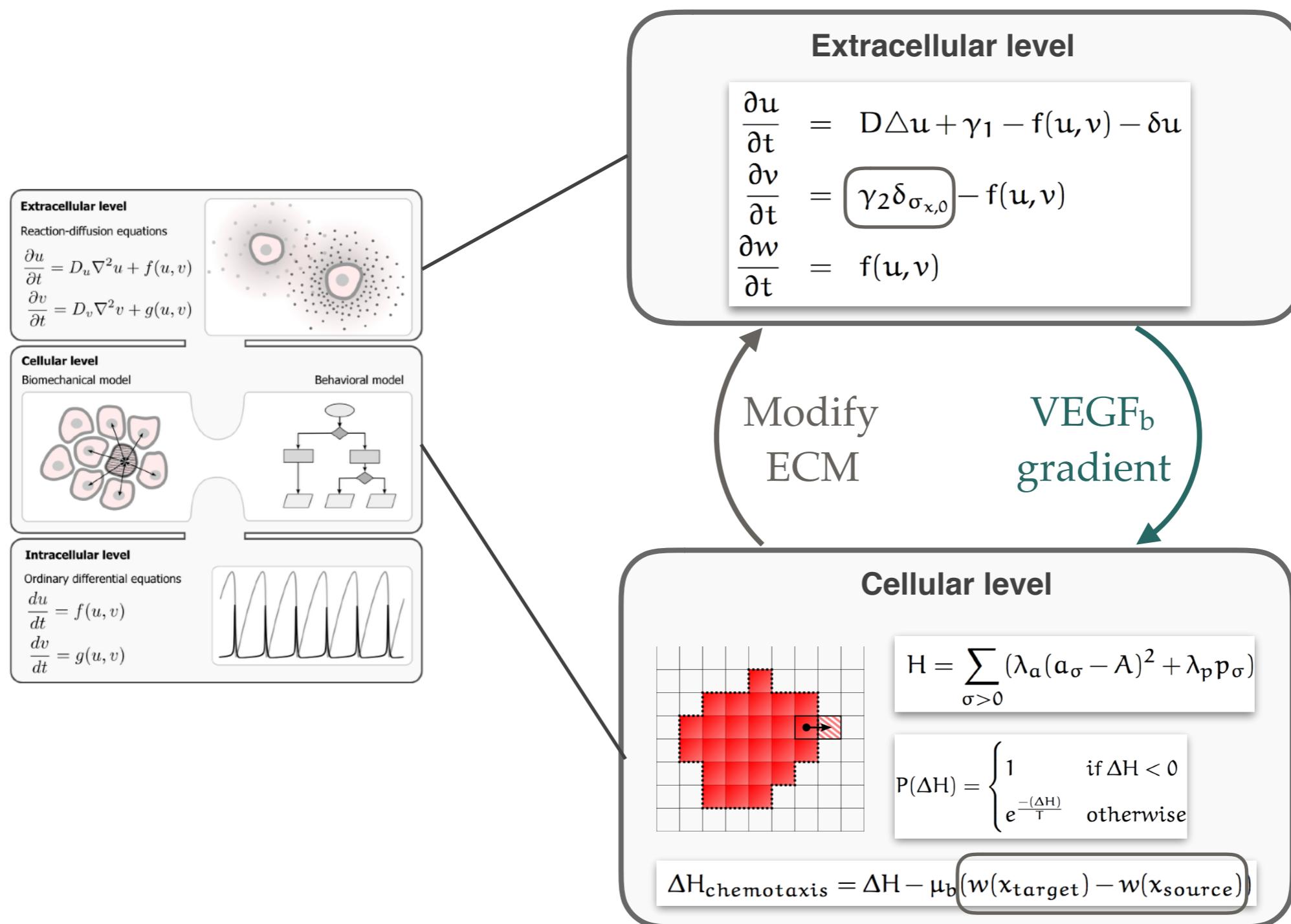
Multi-scale coupling



Multi-scale coupling

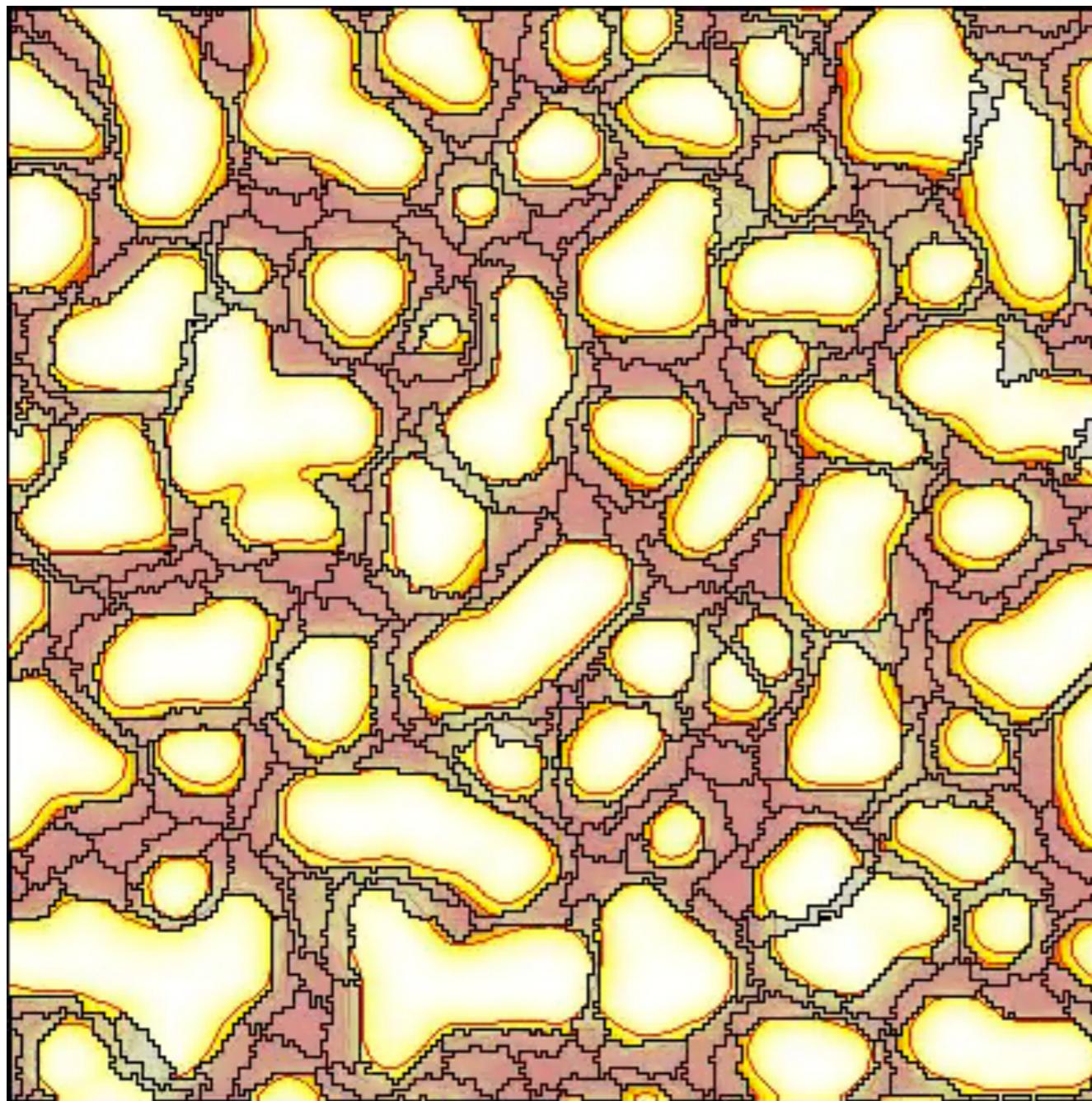


Multi-scale coupling



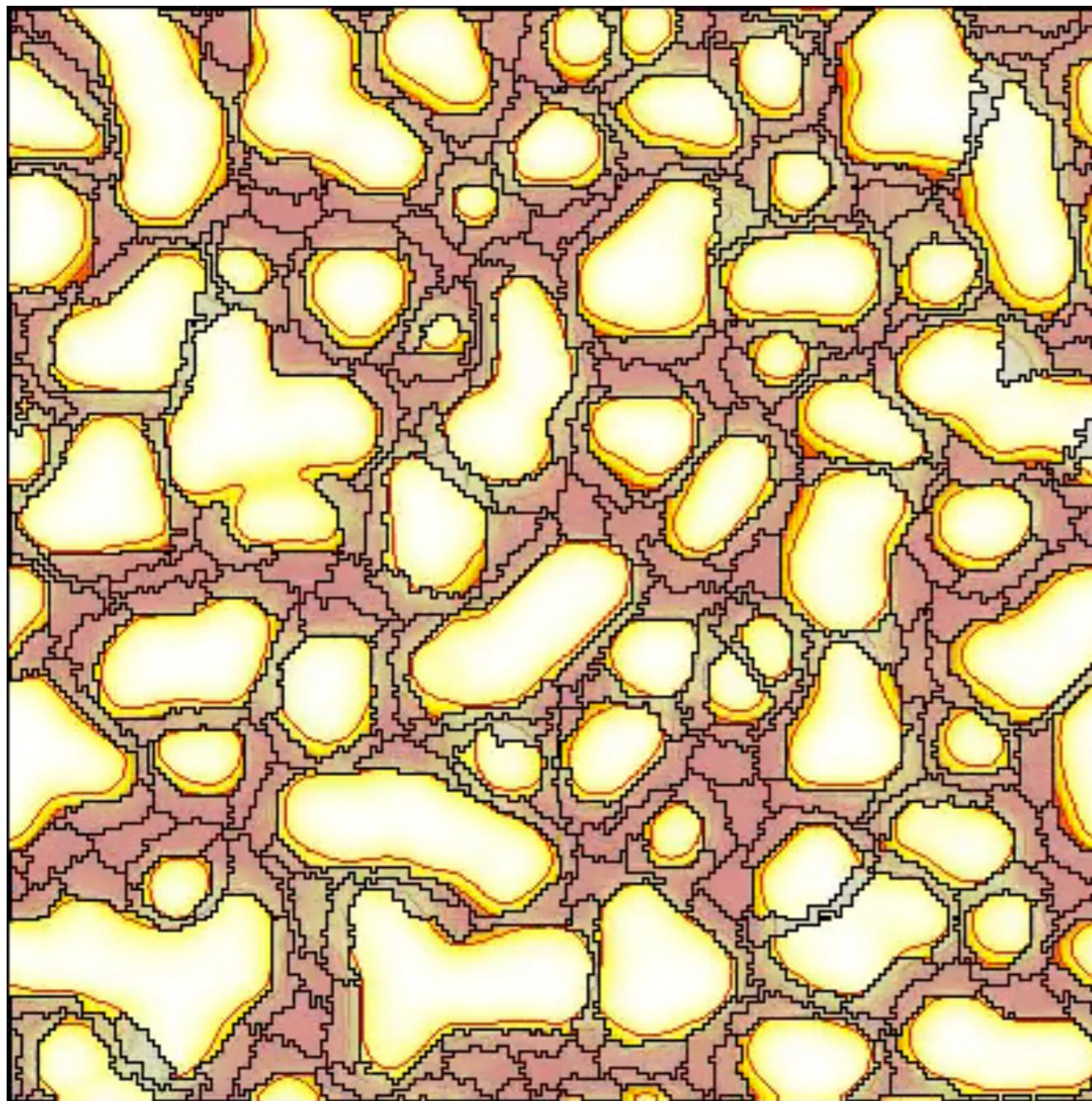
Results

Network formation and morphometric comparison



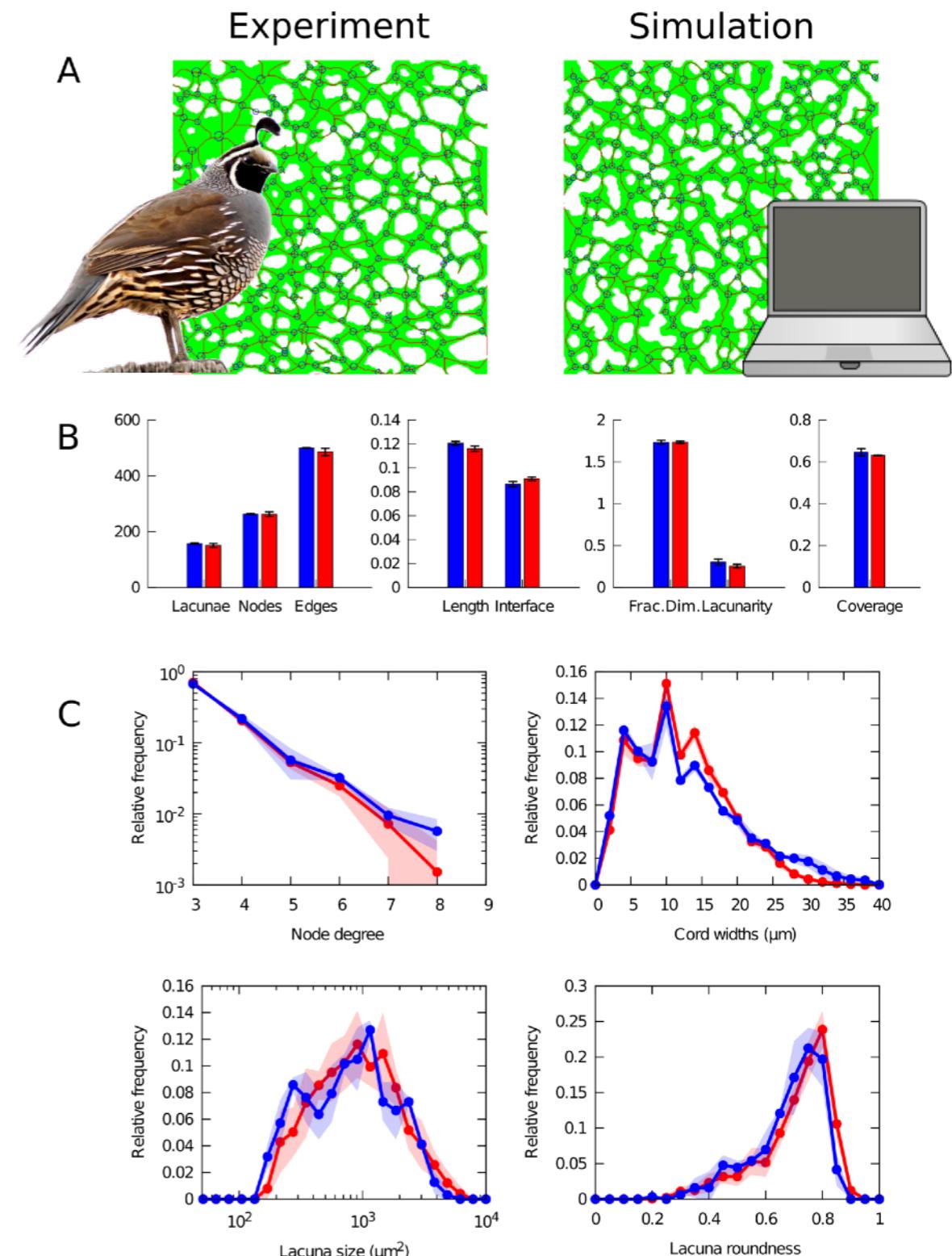
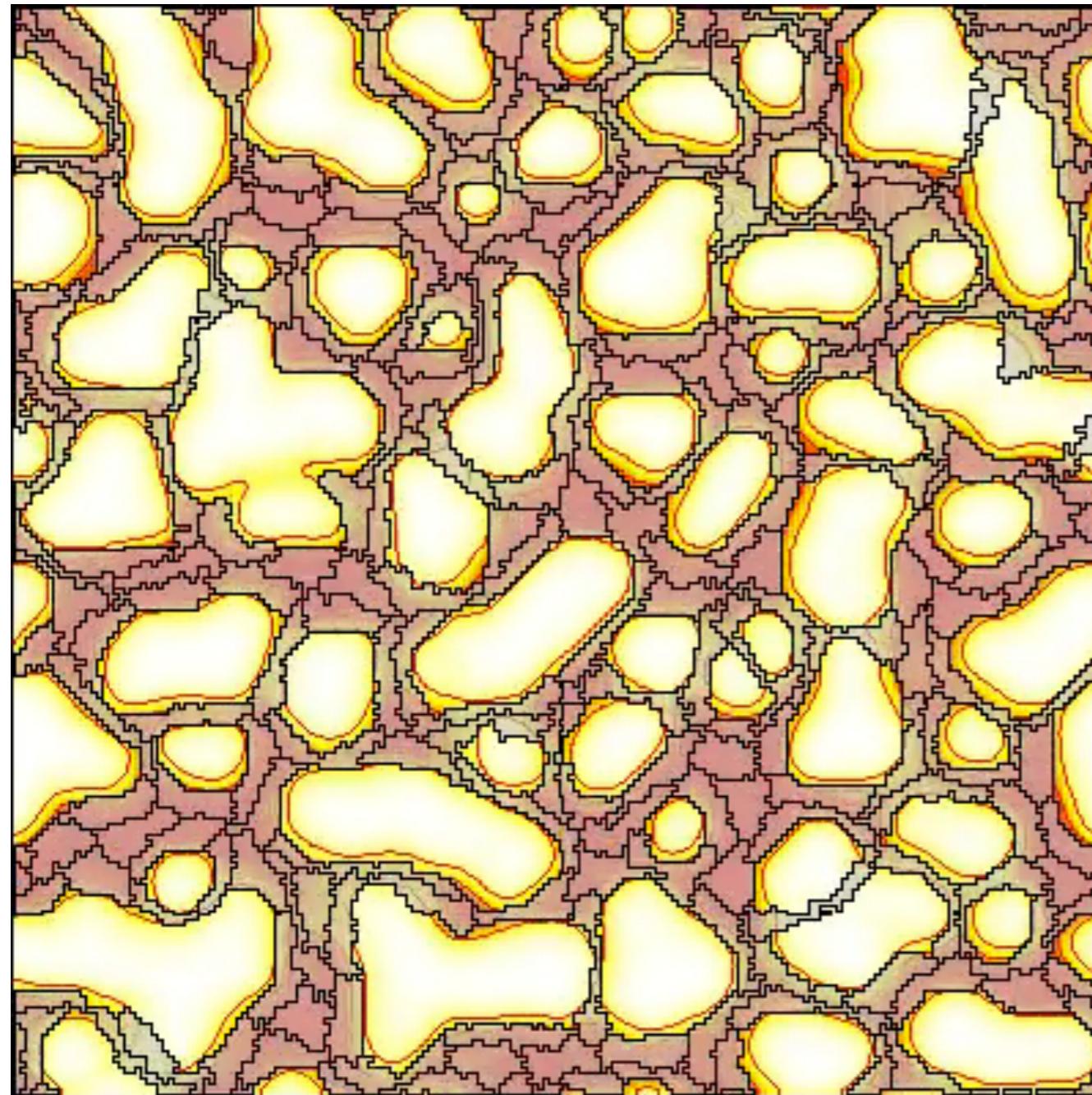
Results

Network formation and morphometric comparison



Results

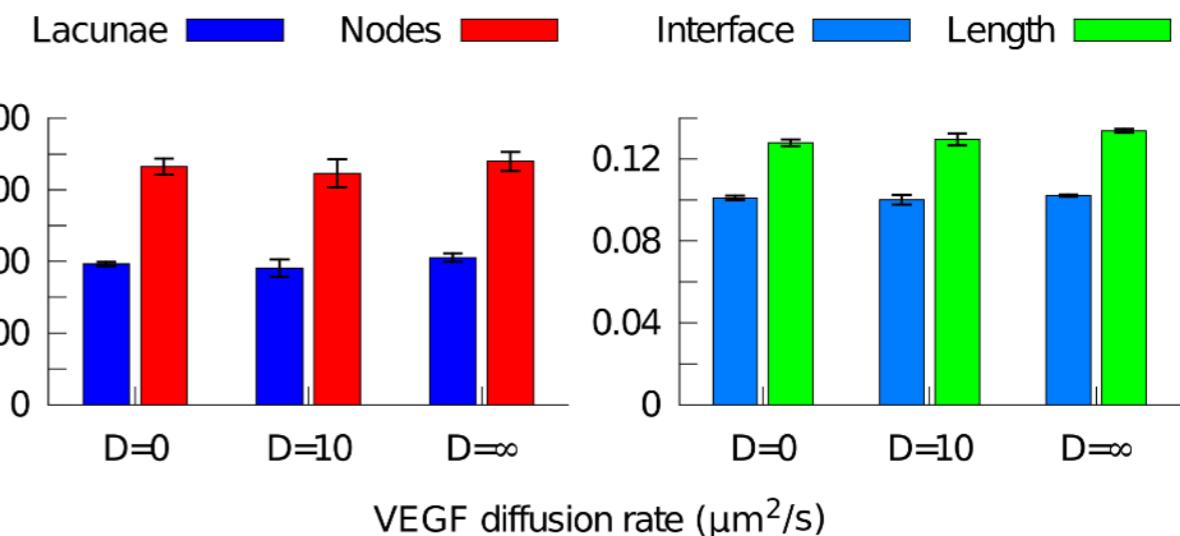
Network formation and morphometric comparison



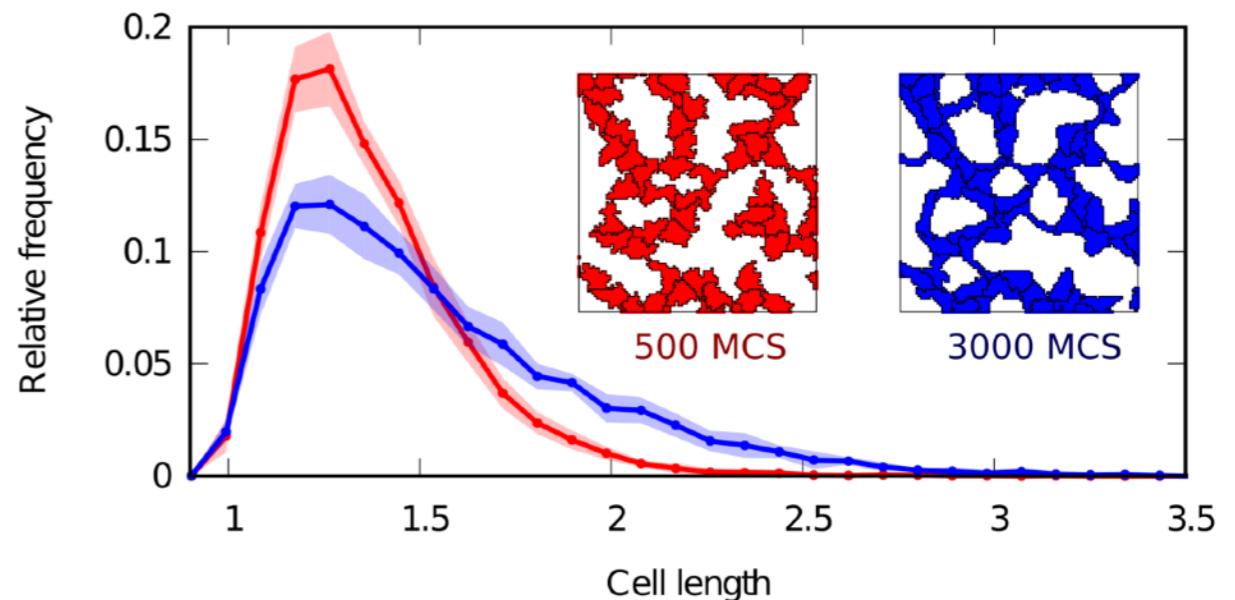
Results

Dynamics of network formation

- Sensitivity analysis
Network formation independent of diffusion coefficient

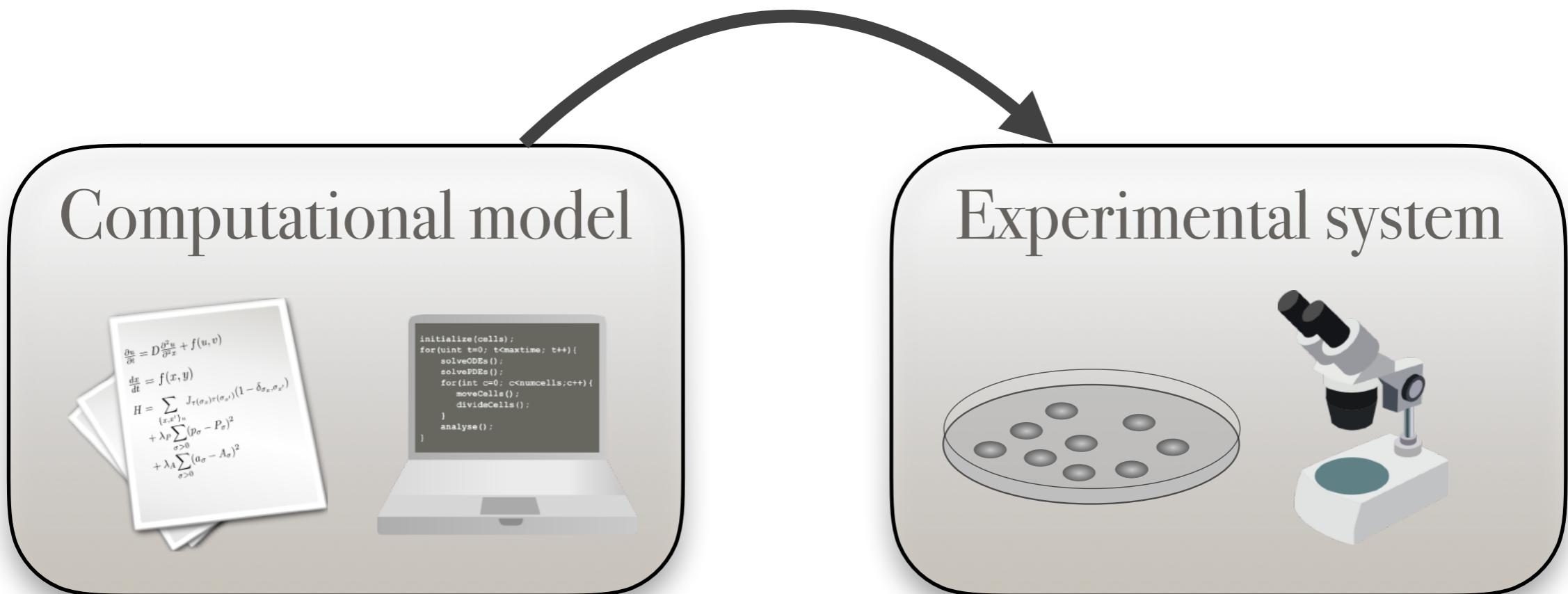


- Cell elongation
Emergent effect rather than cause



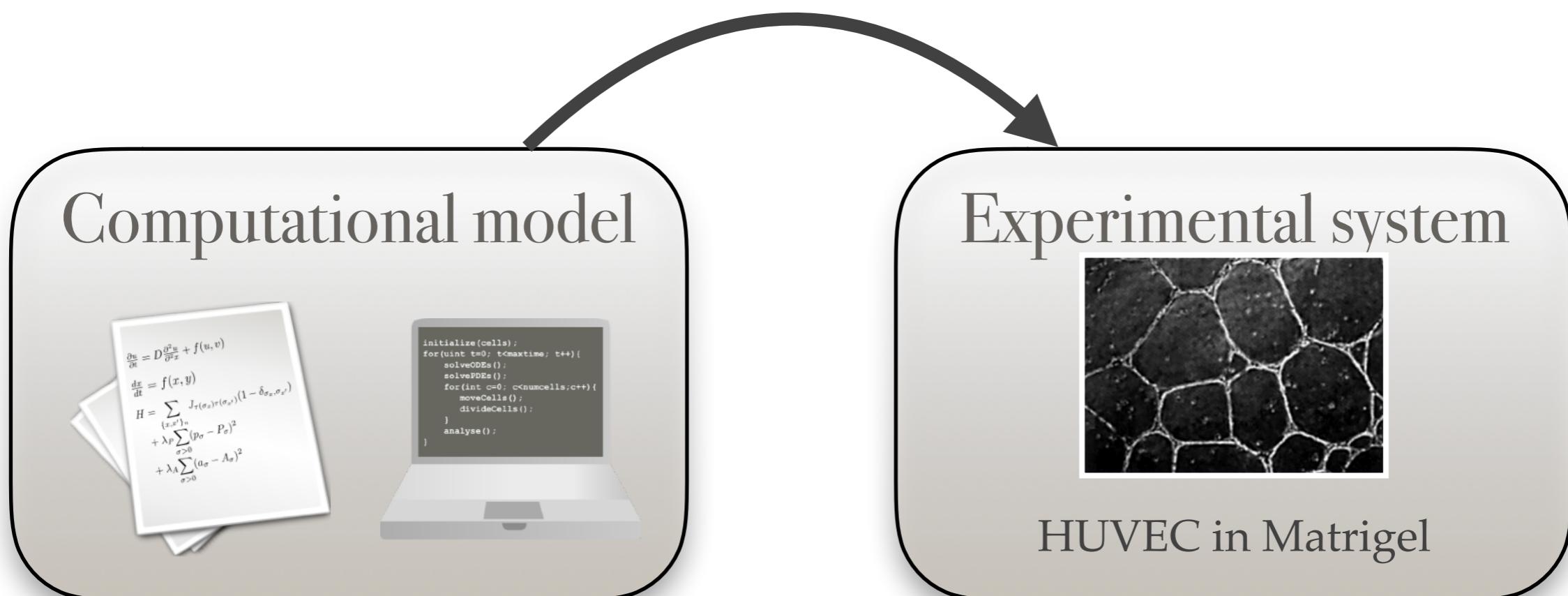
Systems biology

Predictions



Systems biology

Predictions



Prof. Takashi Miura
Kyushu University
Fukuoka, Japan



Dr. Alvaro Köhn-Luque
Complutense University,
Madrid, Spain



Absorption of VEGF

Prediction: VEGF should be absorbed near HUVECs

HUVEC = Human Umbilical Vein Endothelial Cell

Absorption of VEGF

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Experiment:

Add fluorescent VEGF₁₆₅ after normal network formation

Absorption of VEGF

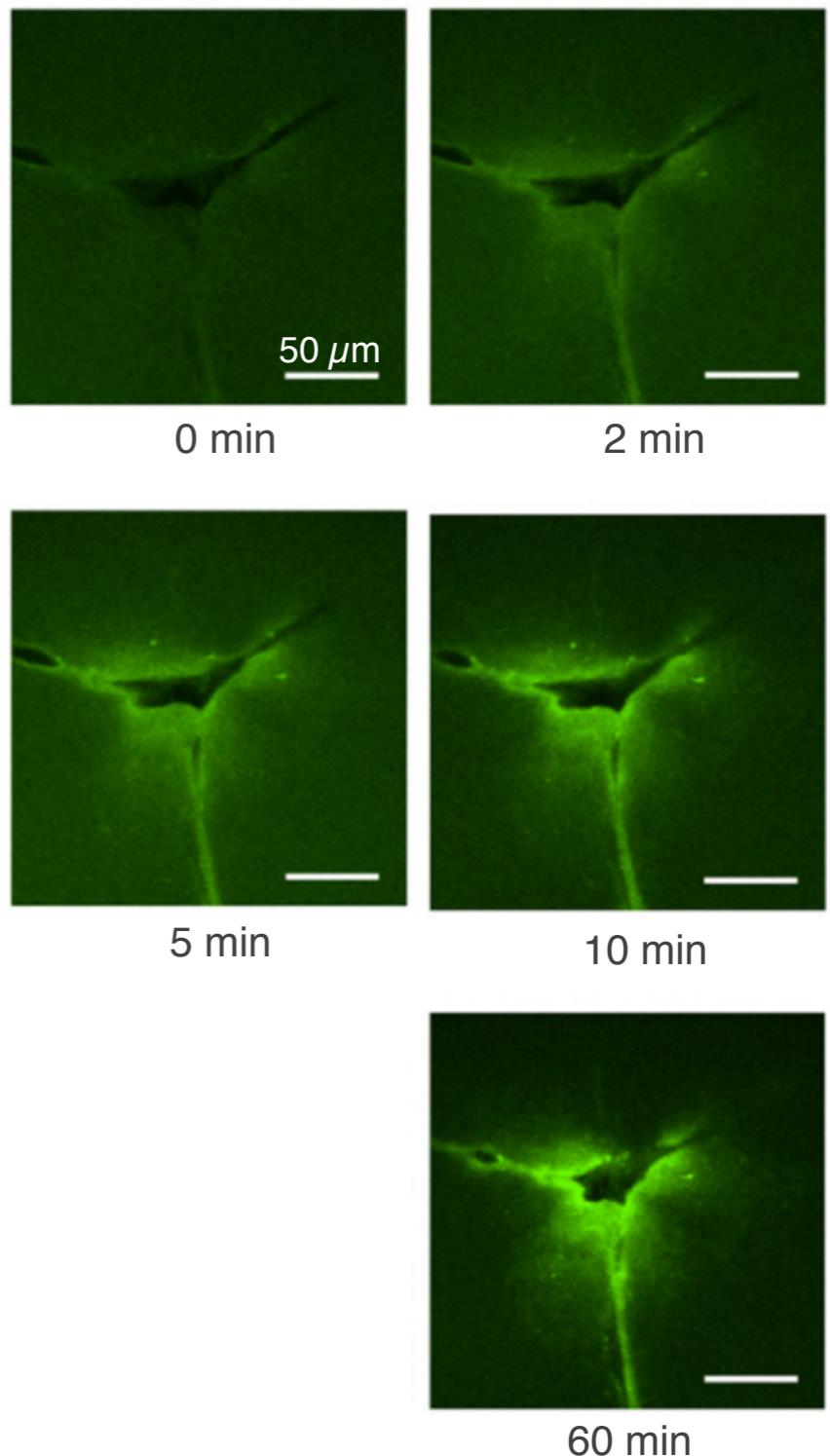
Prediction: VEGF should be absorbed near HUVECs

HUVEC = Human Umbilical Vein Endothelial Cell

Experiment:

Add fluorescent VEGF₁₆₅ after normal network formation

Result: Fluorescent VEGF accumulates near HUVECs



VEGF dynamics

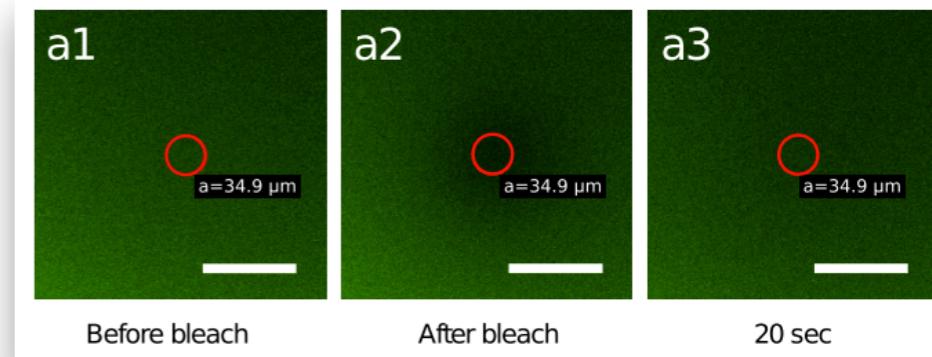
Prediction: Near HUVECs, VEGF is bound rather than diffusing

HUVEC = Human Umbilical Vein Endothelial Cell

VEGF dynamics

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Experiment: FRAP: Fluorescent recovery after photobleaching



VEGF dynamics

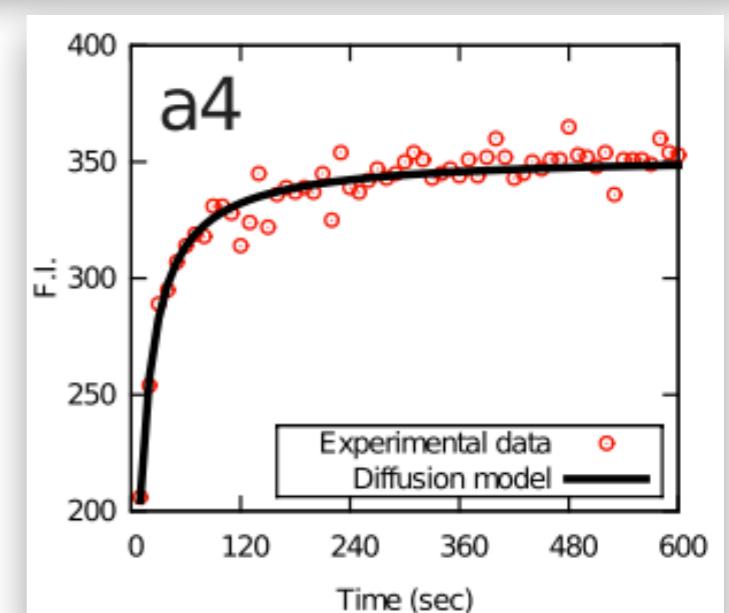
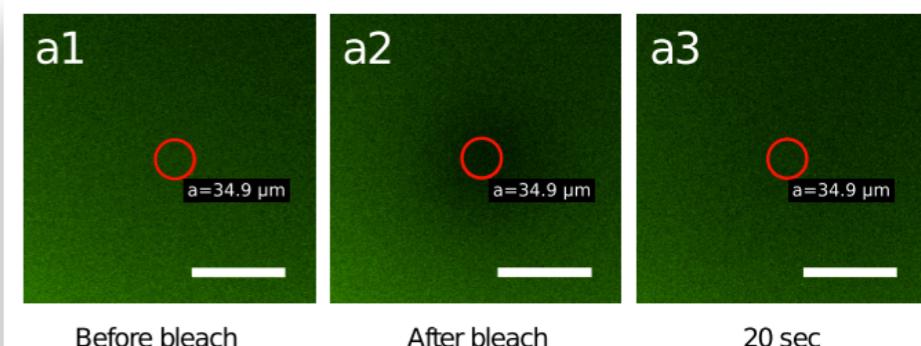
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Result: In absence of cells: Consistent with diffusion

$$frap(t) = F_\infty \exp\left(-\frac{2}{1 + 8Dt/a^2}\right)$$



VEGF dynamics

Prediction: Near HUVECs, VEGF is bound rather than diffusing

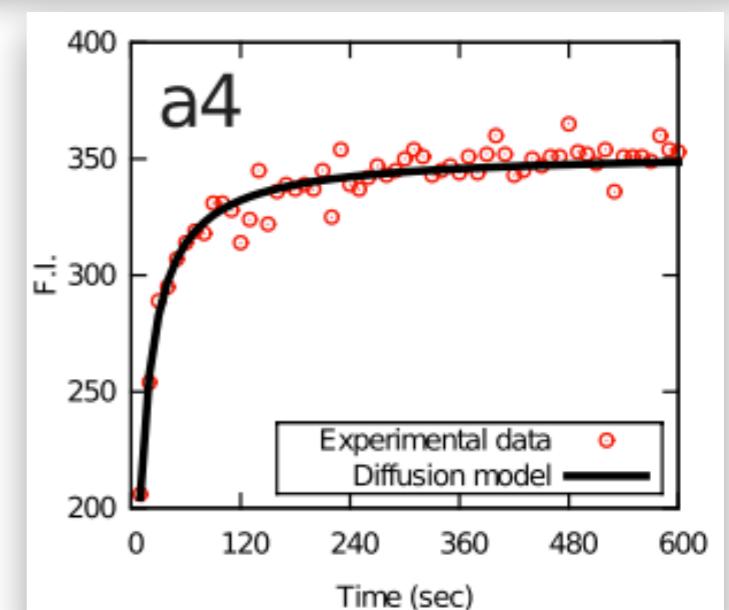
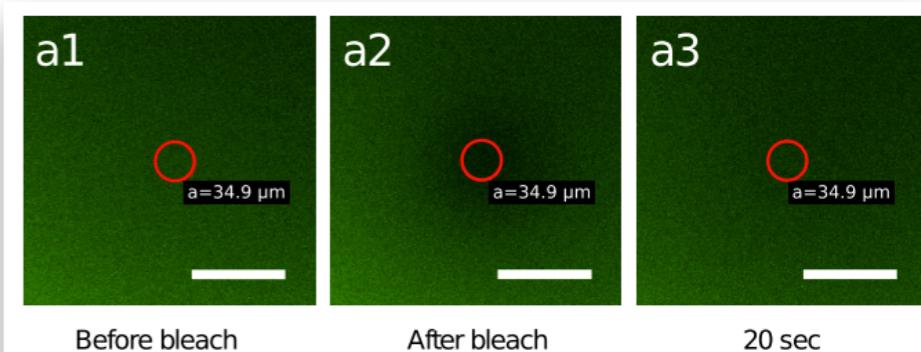
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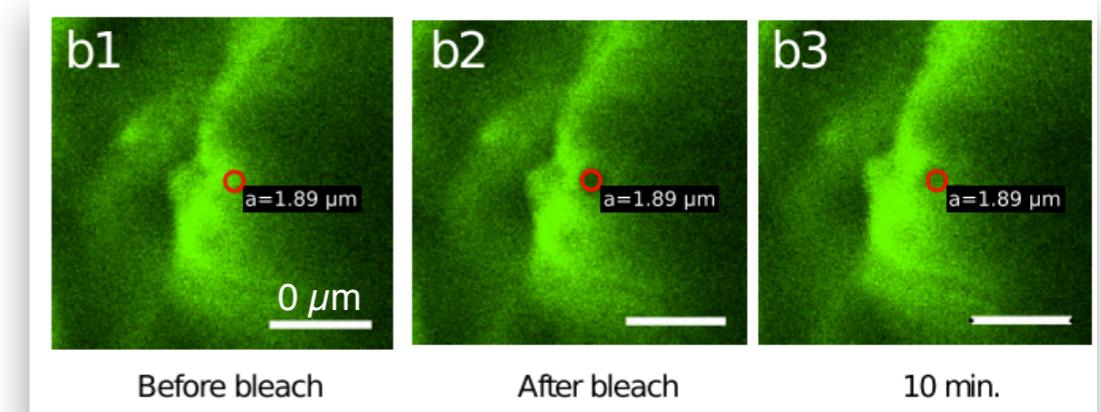
$$frap(t) = F_\infty \exp\left(-\frac{2}{1 + 8Dt/a^2}\right)$$

$$D \approx 5.87 \times 10^{-7} \text{ cm}^2/\text{s}$$



VEGF dynamics

Prediction: Near HUVECs, VEGF is bound rather than diffusing

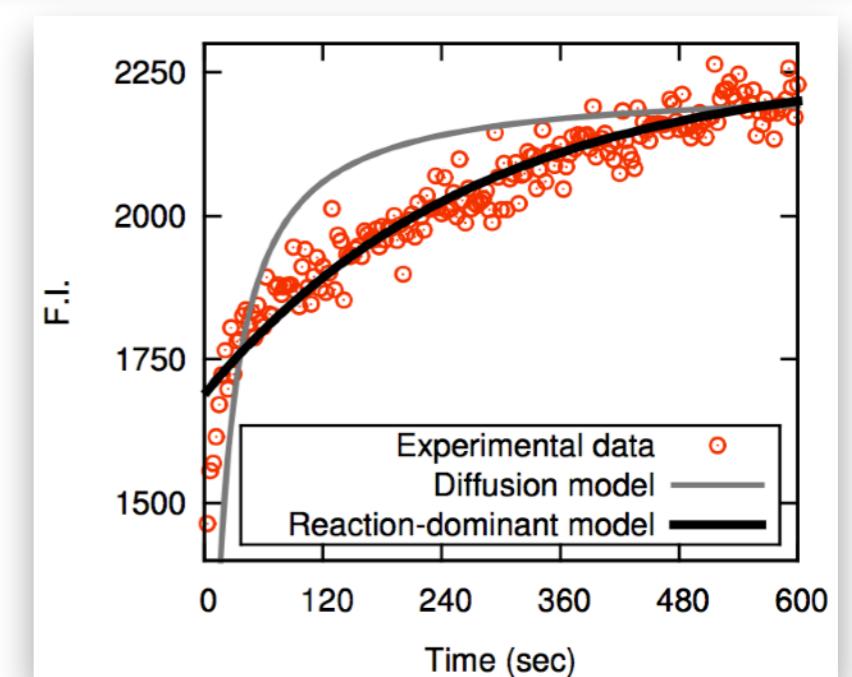
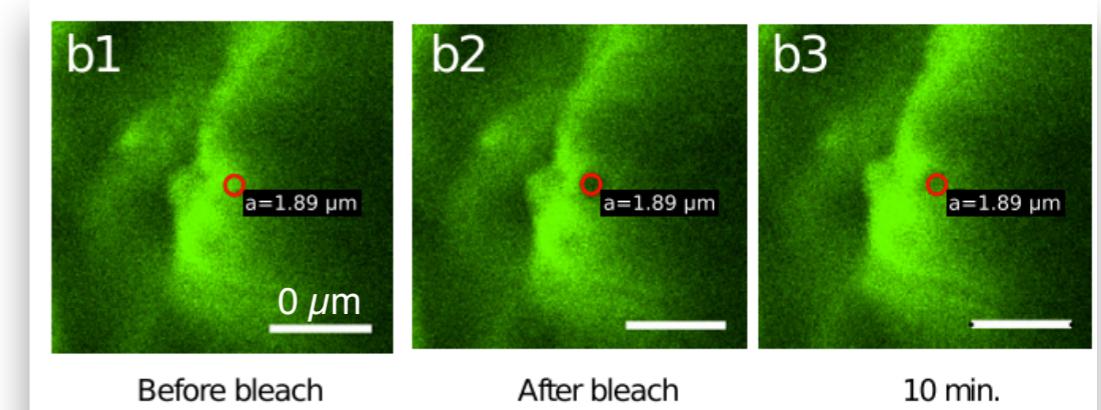


VEGF dynamics

Prediction: Near HUVECs, VEGF is bound rather than diffusing

Result:

Near cells: **Inconsistent** with diffusion



VEGF dynamics

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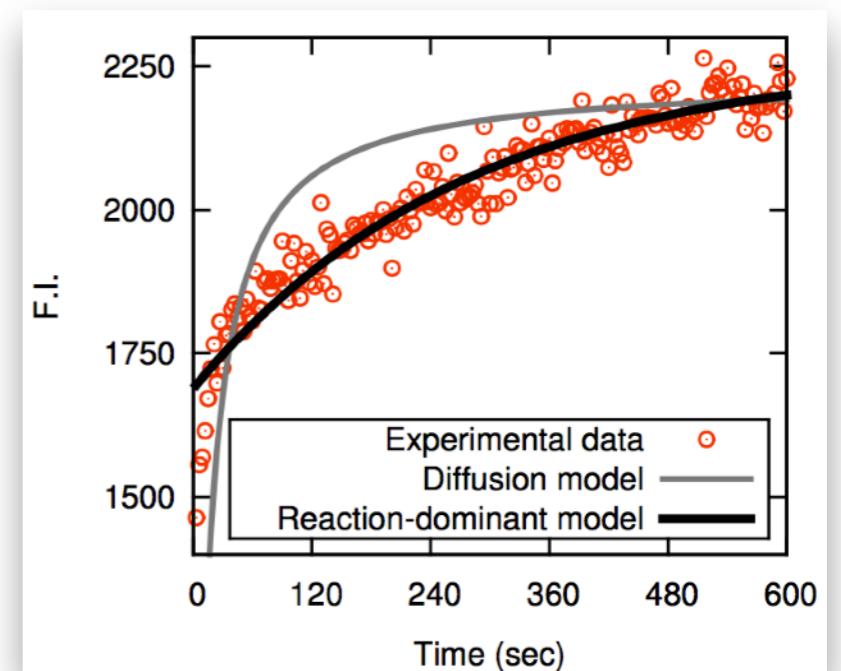
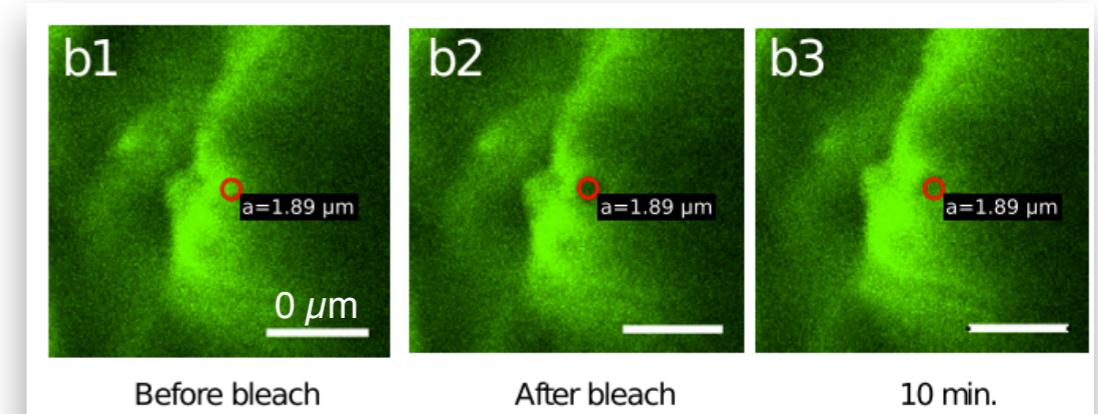
Consistent with **reaction-dominant** model

$$\text{frap}(t) = u(t) + b(t) = 1 - \frac{k_{\text{on}}^*}{k_{\text{on}}^* + k_{\text{off}}} e^{-k_{\text{off}} t}$$

$$k_{\text{on}}^* \approx 1.5 \times 10^{-3} \text{s}^{-1}$$

$$k_{\text{off}} \approx 3.6 \times 10^{-3} \text{s}^{-1}$$

$$k_{\text{on}} = \frac{k_{\text{off}}}{K_d} = 3.6 \times 10^4 \text{M}^{-1} \text{s}^{-1}$$

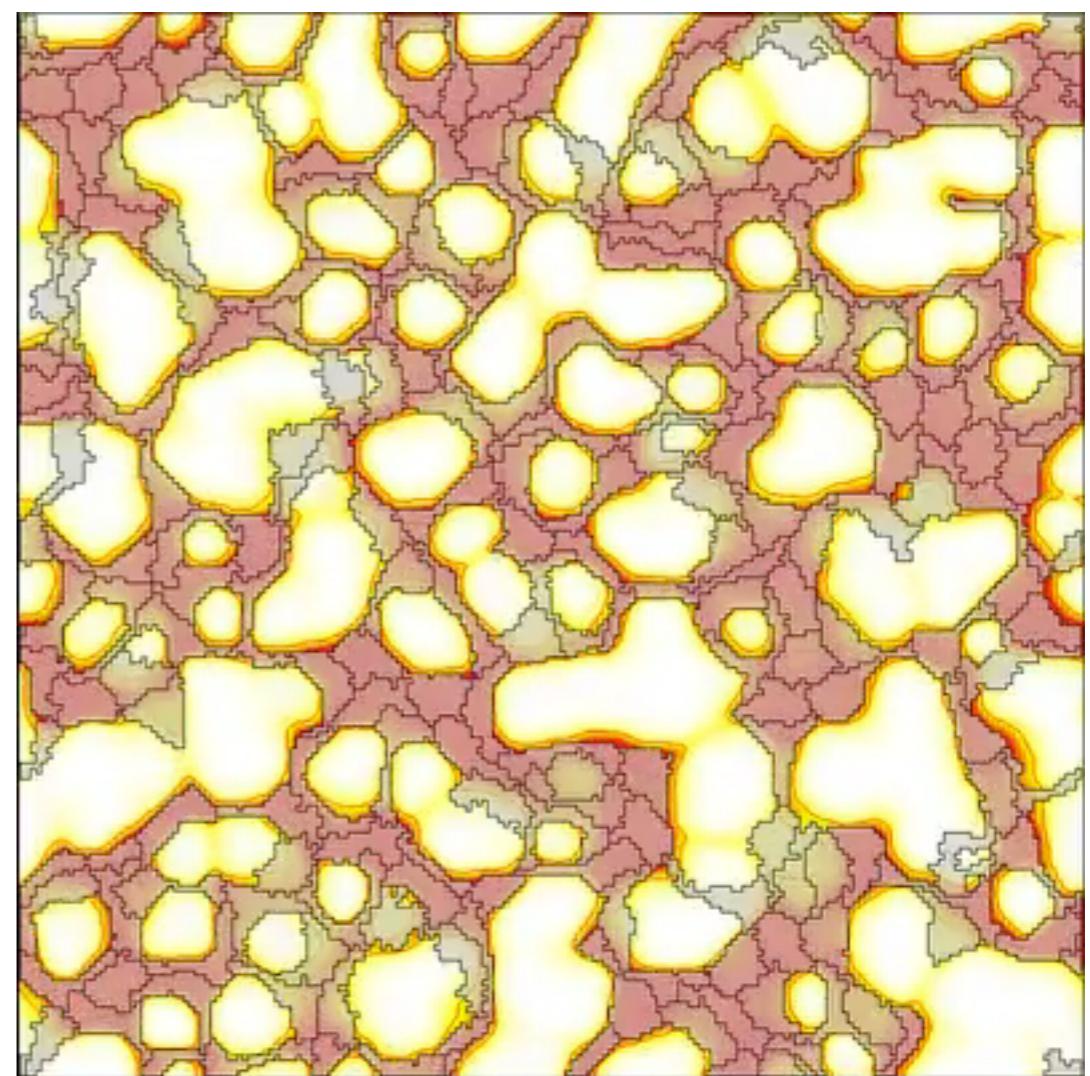


Quantitative modeling

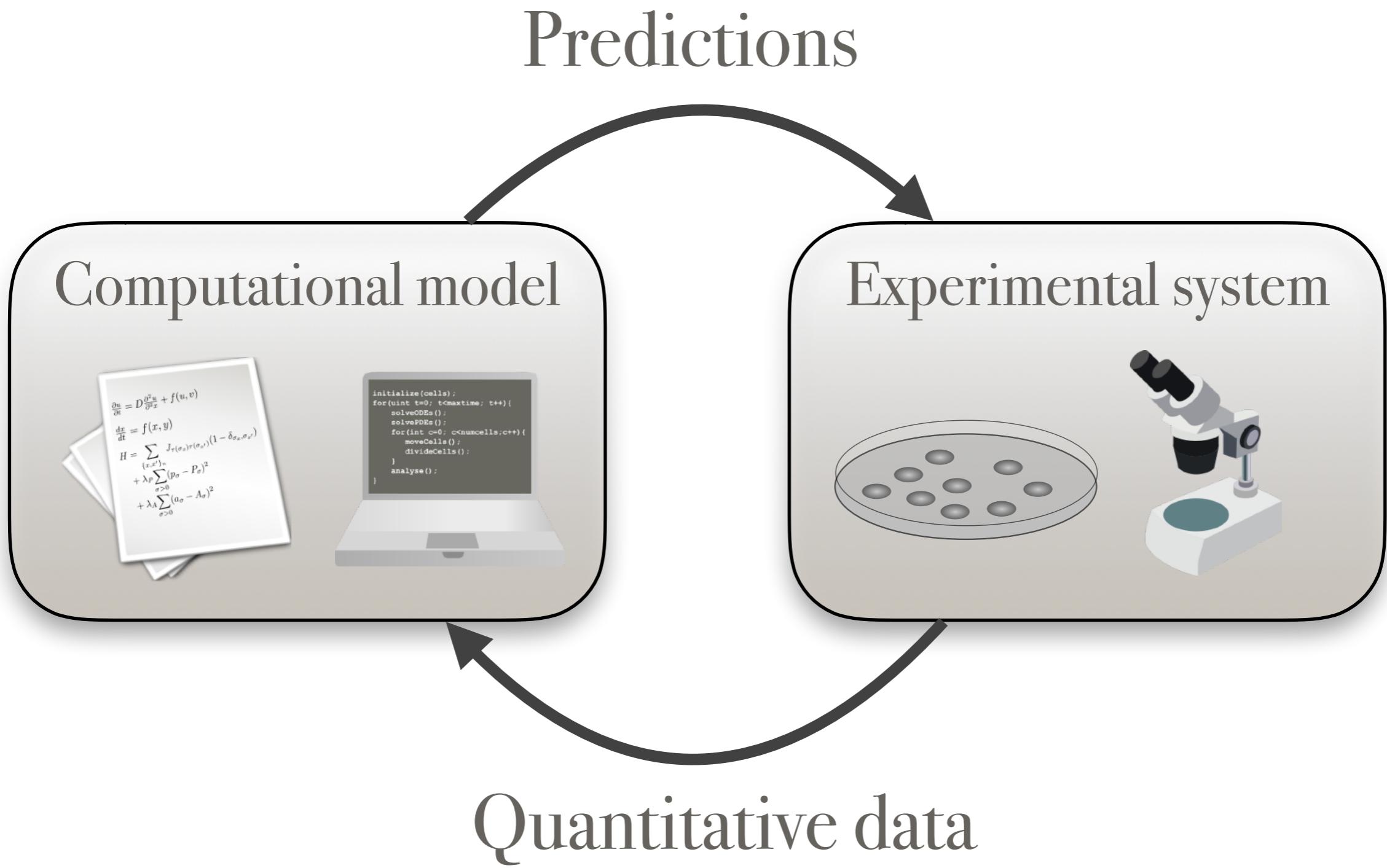
Parameter	Estimate	Method
PDE		
D	$5.87 \cdot 10 \mu\text{m}^2\text{s}^{-1}$	FRAP
k_{on}	$8.57 \cdot 10^{-7} \text{ ng ml}^{-1}\text{s}^{-1}$	FRAP
k_{off}	$3.6 \cdot 10^{-3} \text{ s}^{-1}$	FRAP
ϵ	$2.67 \cdot 10^{-6} \text{ s}^{-1}$	ELISA
γ	$0.5 - 2.0 \text{ ng ml}^{-1}\text{s}^{-1}$	Estimated in this study
CPM		
A	$300 \mu\text{m}^2$	Measured in this study
λ_a	$0.5 \text{ a.u. } \mu\text{m}^{-2}$	^{102,252} rescaled
λ_p	$1.6 \text{ a.u. } \mu\text{m}^{-1}$	^{102,252} rescaled
μ	$40 - 140 \text{ a.u. } \text{ng}^{-1}\text{ml}$	Calibration using data from ²⁶²
Initial condition		
u_0	1.5 ng ml^{-1}	ELISA
s_0	0.0 ng ml^{-1}	Assumed in this study
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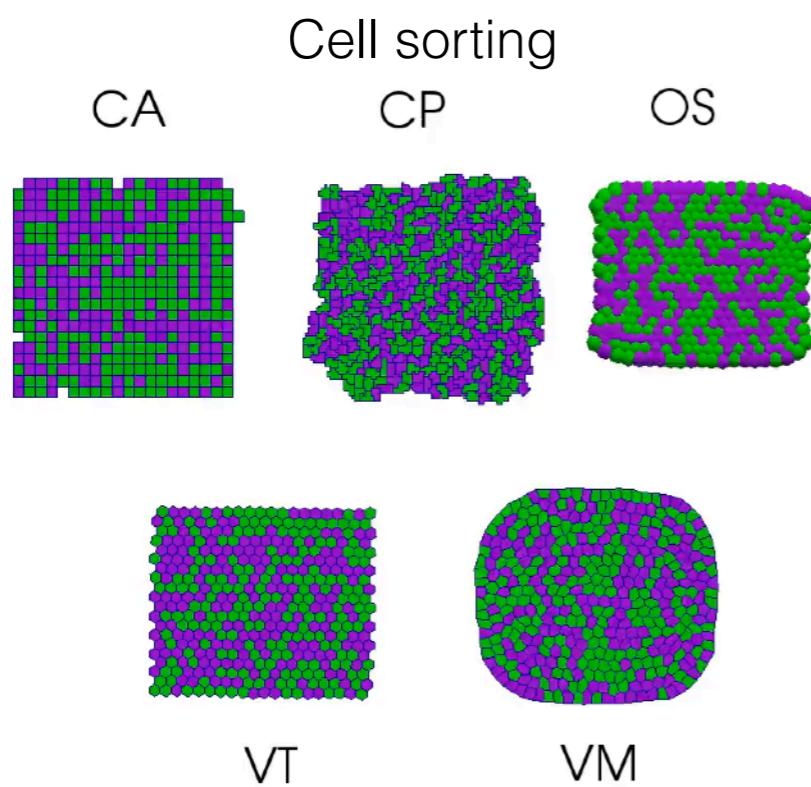
Systems biology cycle



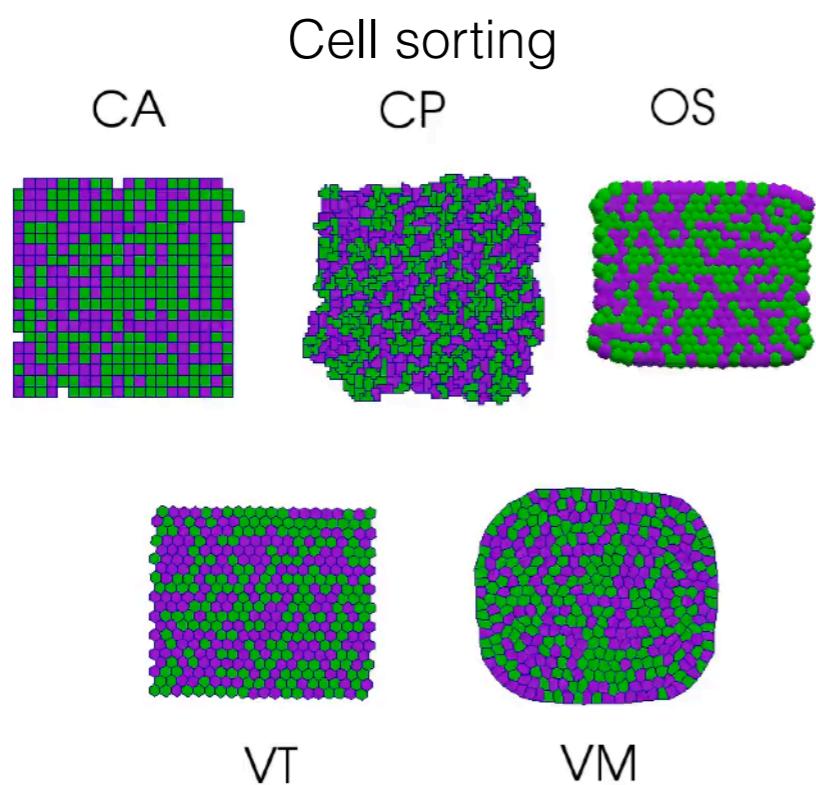
Comparing cell-based models

Osborne et al. 2017

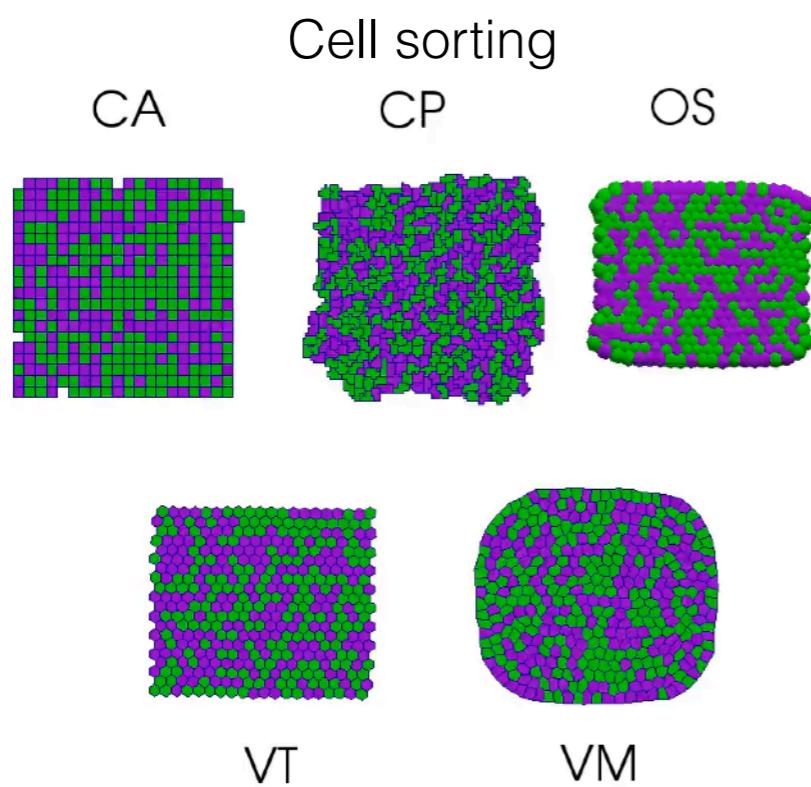
Comparison based on case studies



Comparison based on case studies



Comparison based on case studies

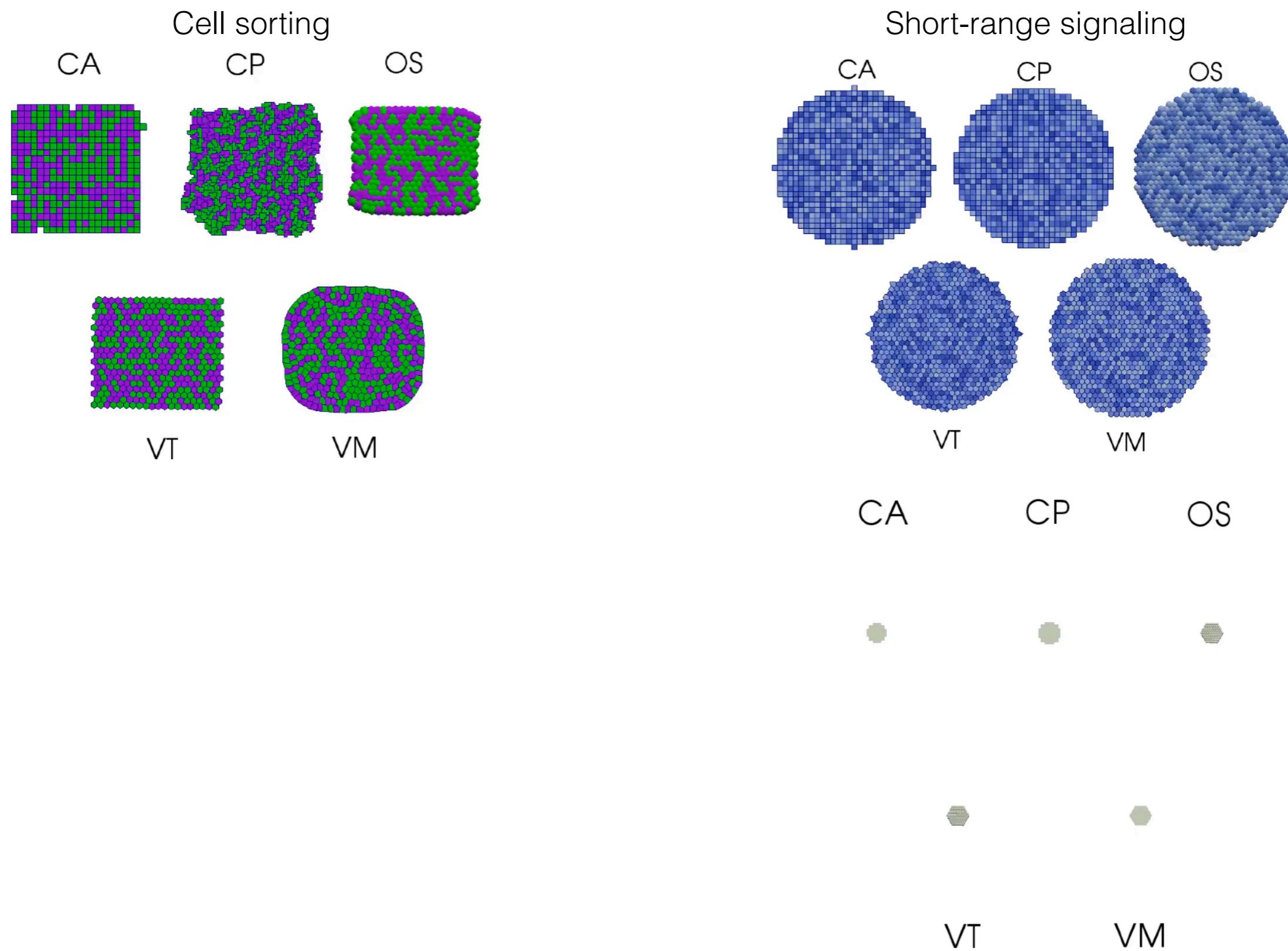


CA CP OS

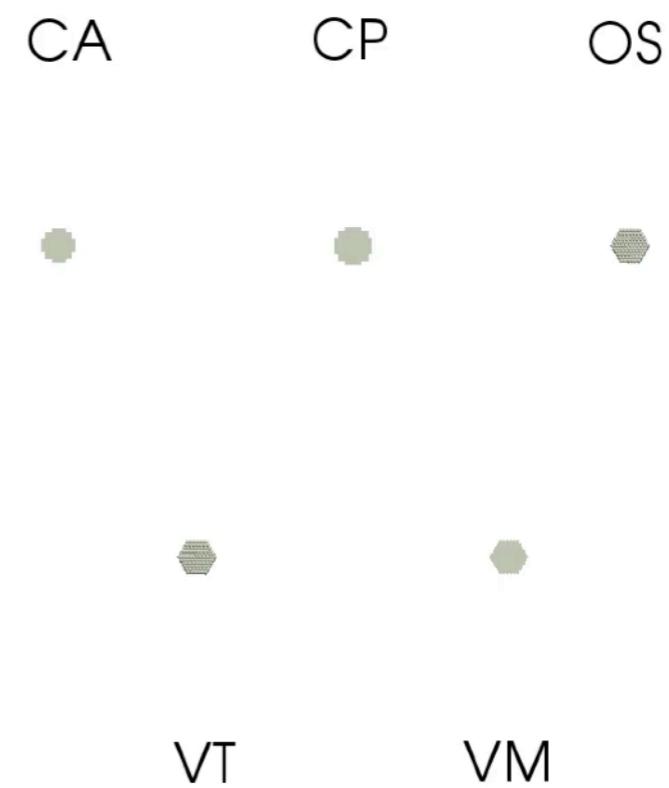
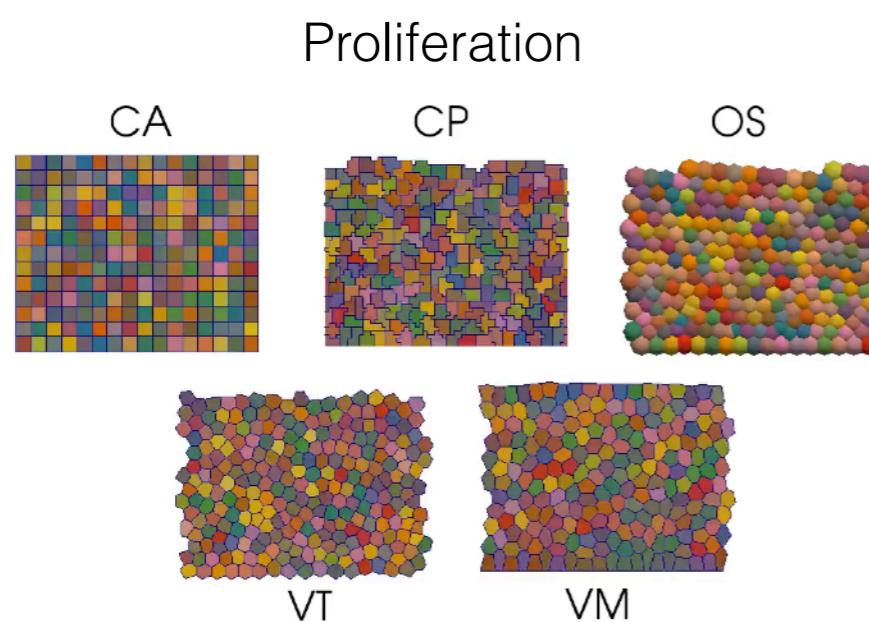
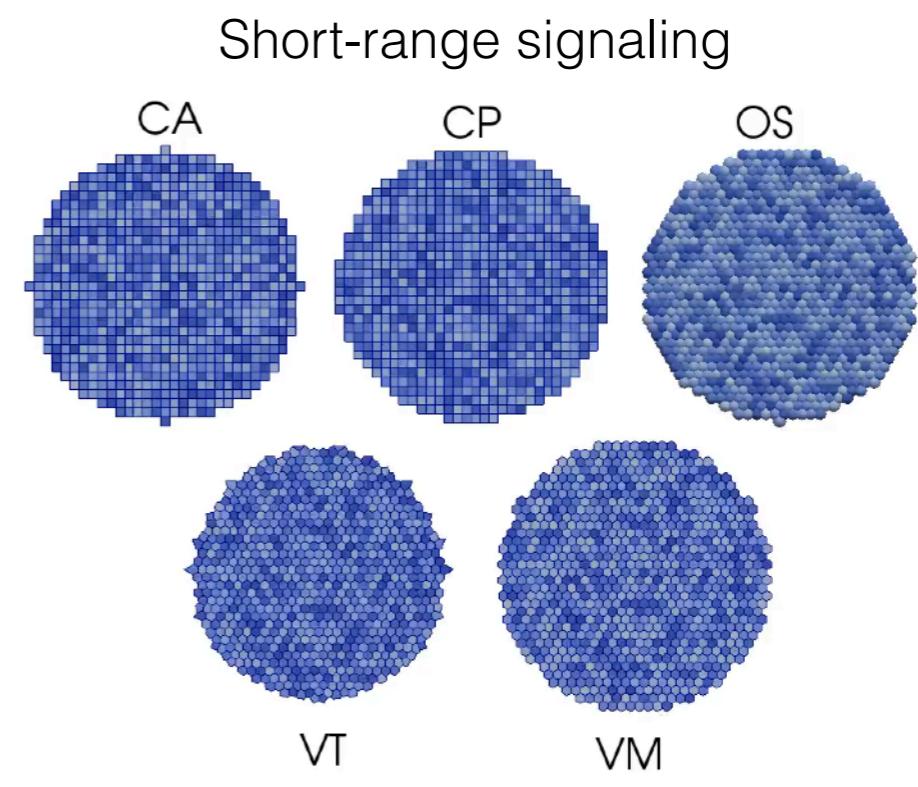
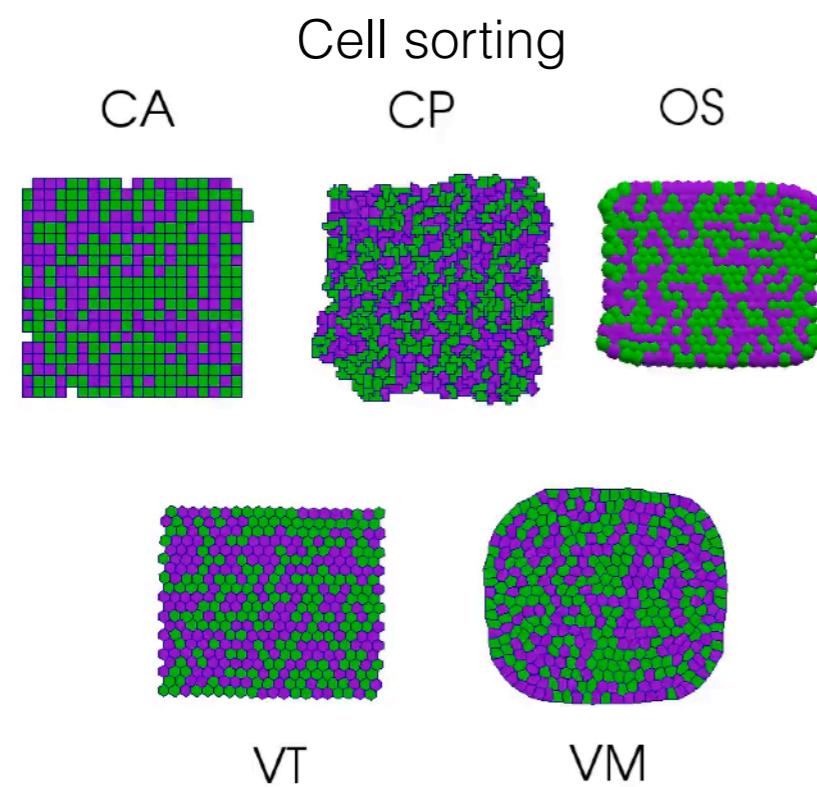


VT VM

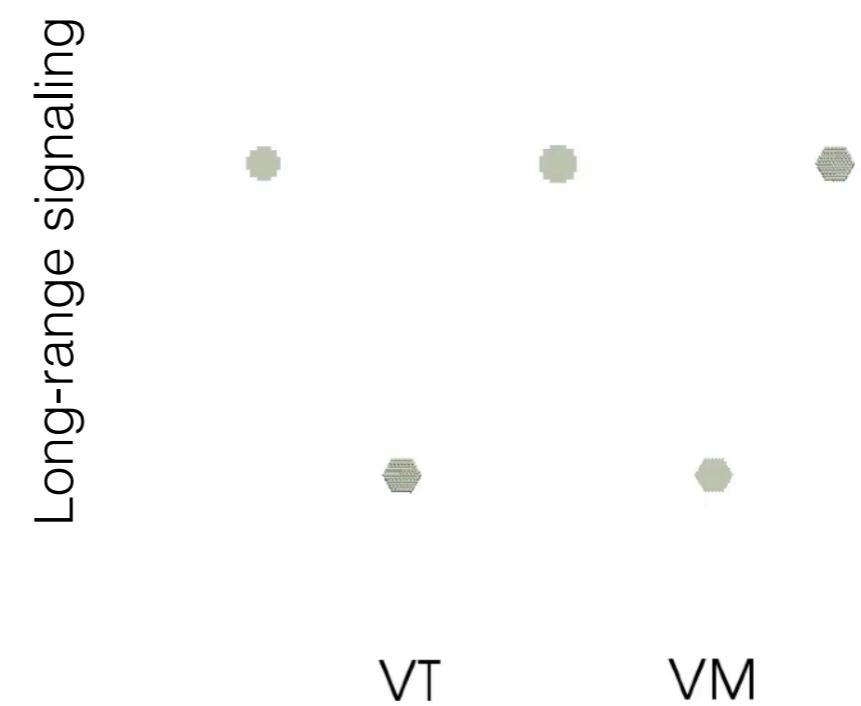
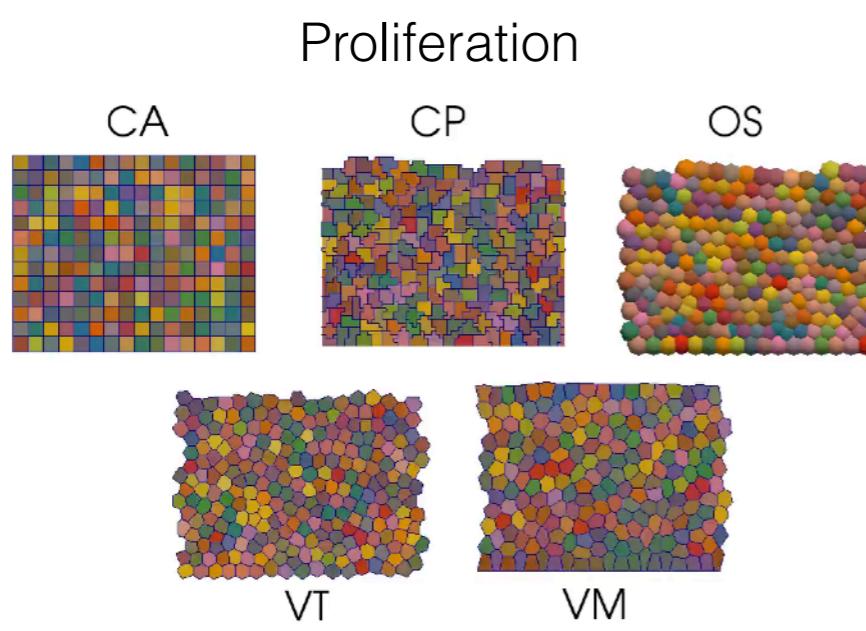
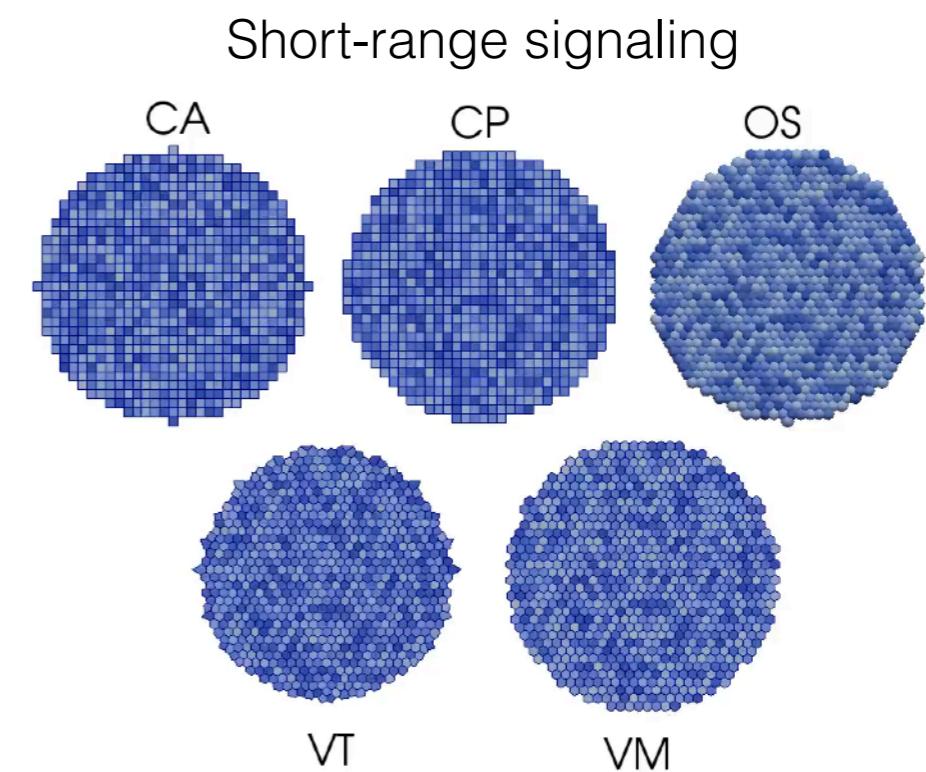
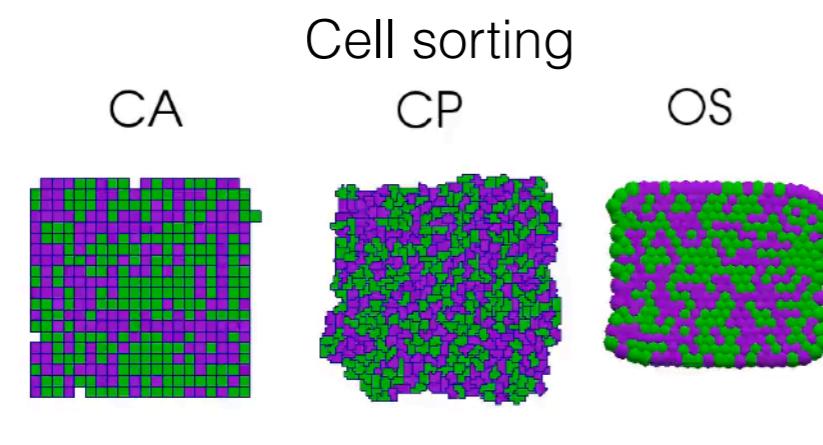
Comparison based on case studies



Comparison based on case studies



Comparison based on case studies



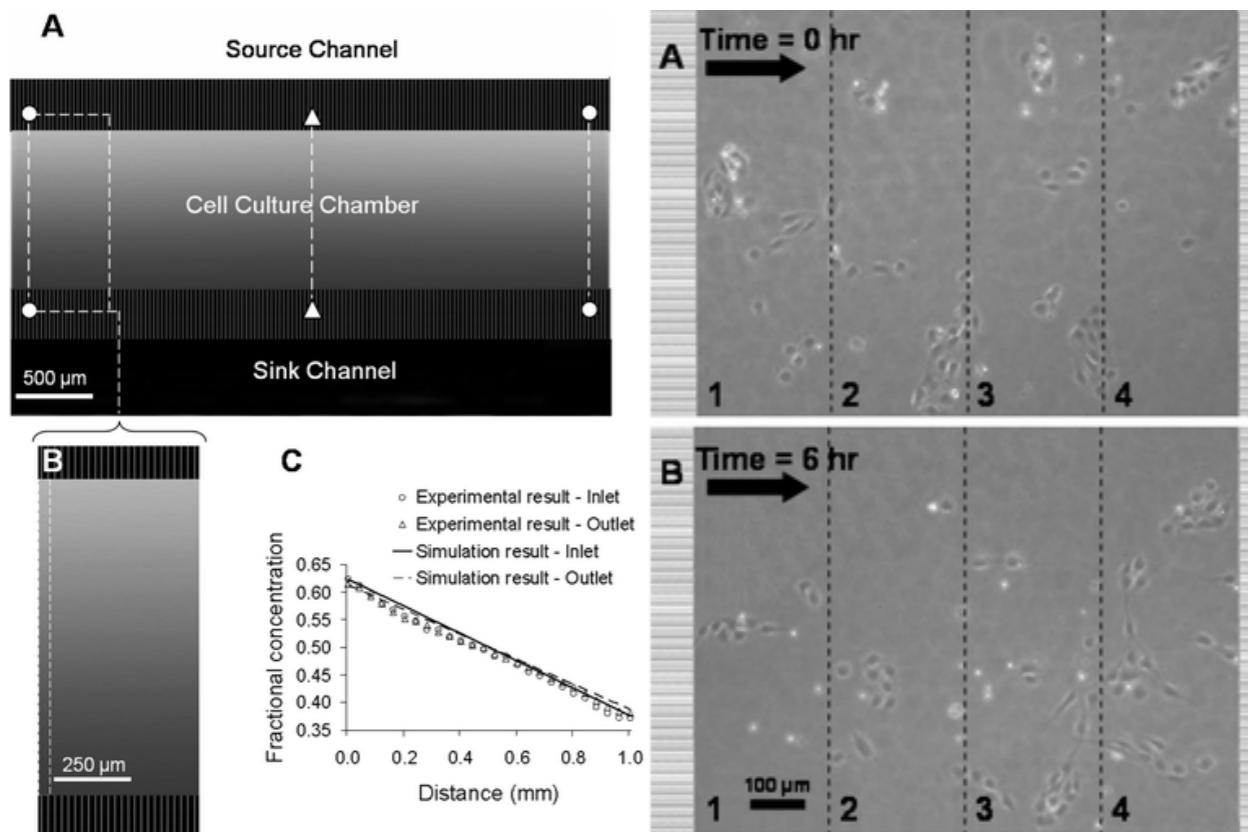
Fitting to experimental data

Approximate Bayesian Computation

Estimating chemotactic sensitivity

► Experiment

- Microfluidic device
- Stable VEGF gradient
- Measure cell movement

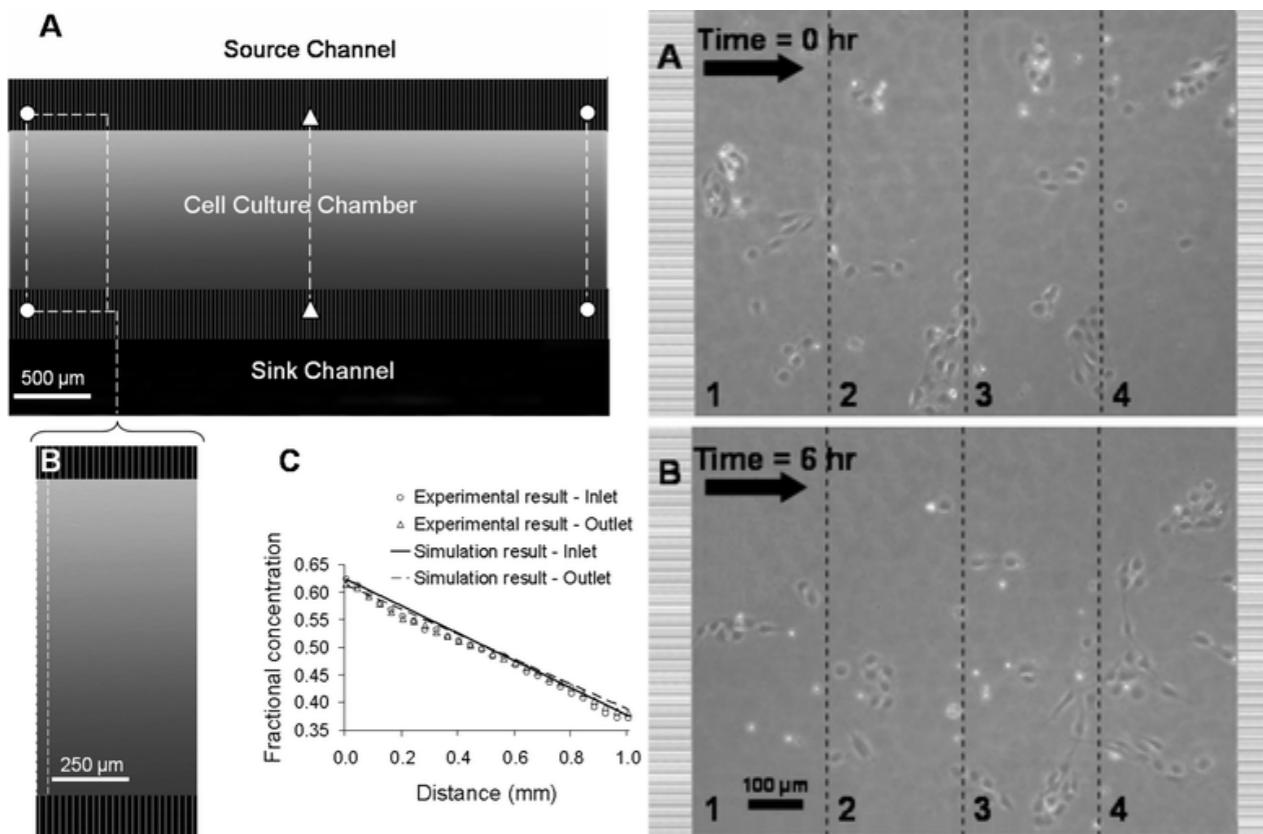


Shamloo et al., 2008

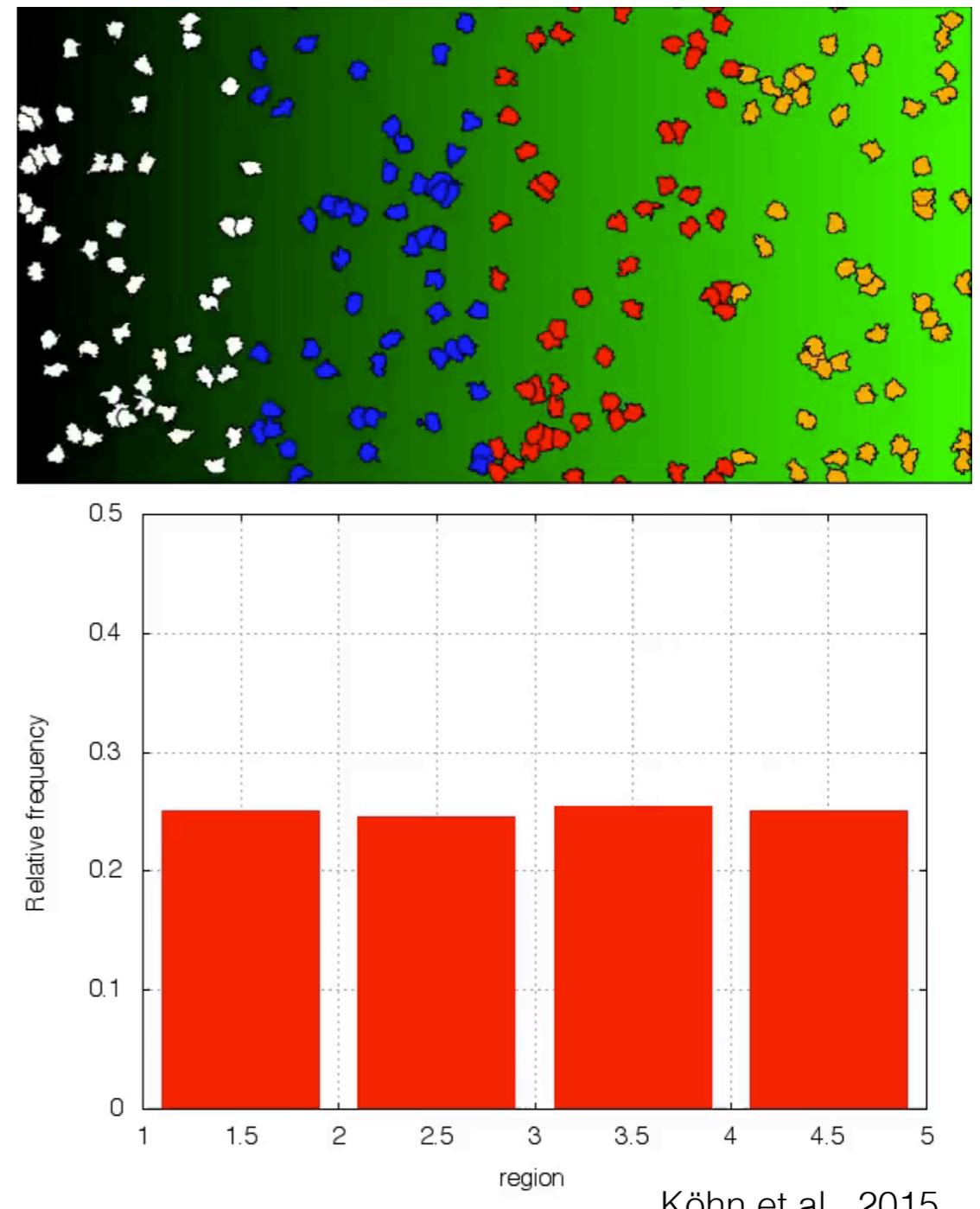
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Shamloo et al., 2008

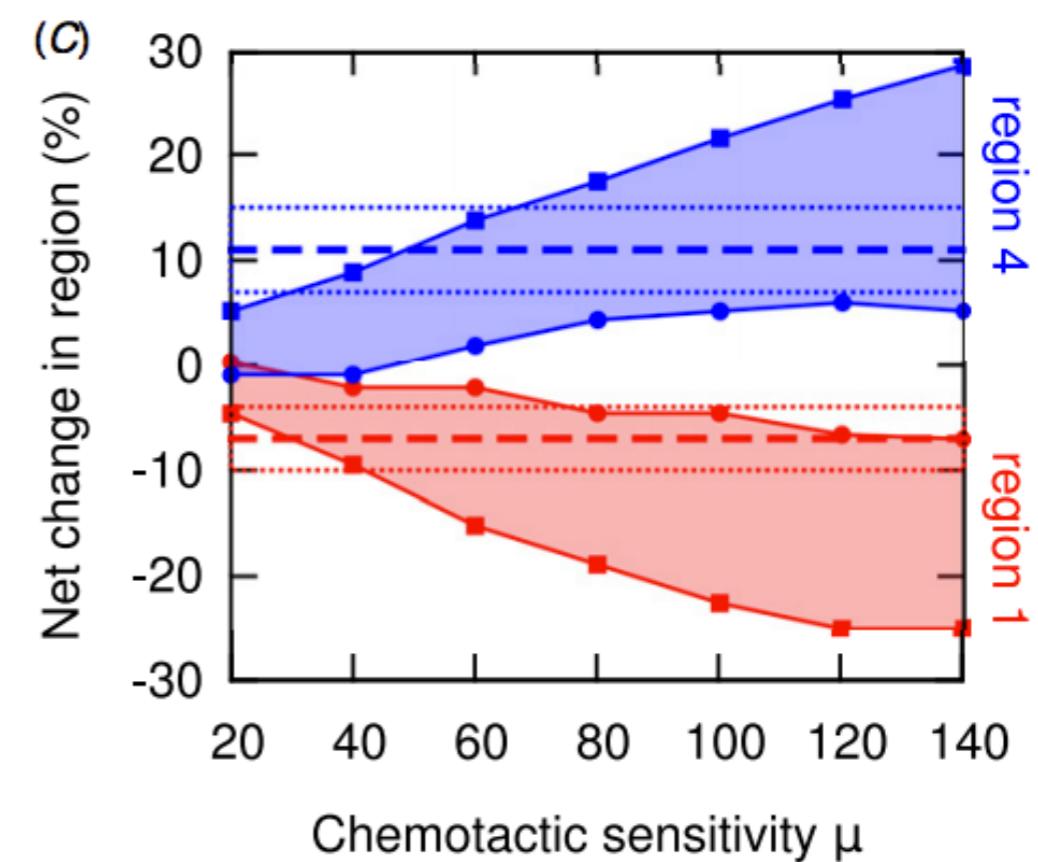
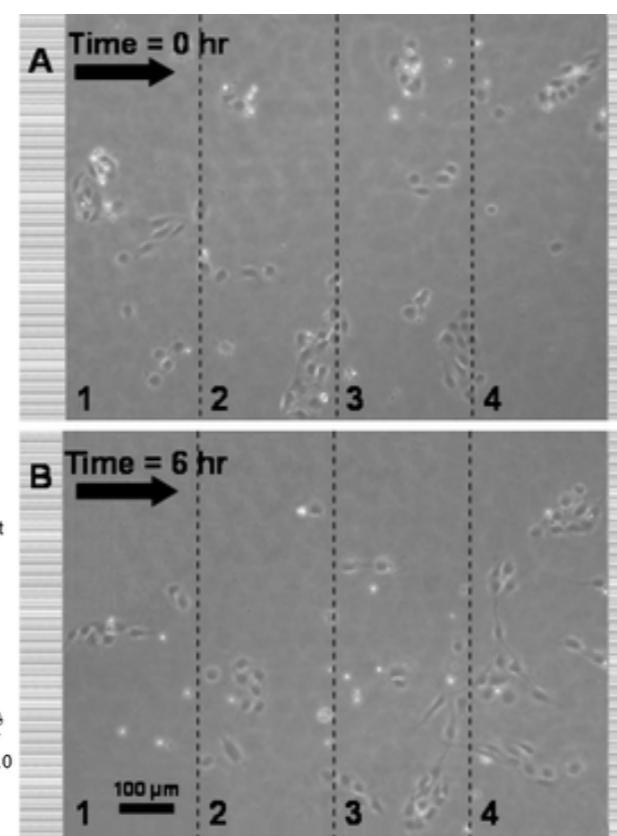
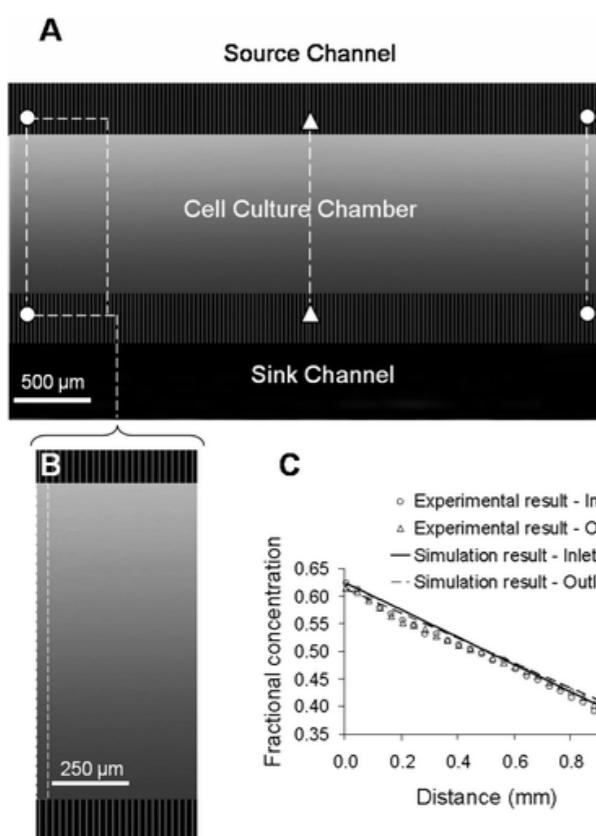


Köhn et al., 2015

Estimating chemotactic sensitivity

► Experiment

- Microfluidic device
- Stable VEGF gradient
- Measure cell movement



Shamloo et al., 2008

Köhn et al., 2015

Parameter sweep in Morpheus

- ▶ “Brute force” grid search
 - ▶ explore parameter space
 - ▶ with fixed intervals

Element	Name/Symbol	Value
CellType	cells	
Property	X =	0.0
Property	Xn =	0.0
NeighborsRepo...		
System		
Property	tau =	-1
Event		
FlipCells		
Condition		
Constant	m =	rand_uni(0,1)<m
Property	label =	0.5
CellType	medium	0.0

Name of the Sweep:

Number of Jobs:

Parameters and Value Sets

Attribute	Type	Values
...me=cells]/Constant[symbol=m]/@value	Double	0:#10:1 0.6;0.7;0.8;0.9;1

Approximate Bayesian Computation

- ▶ Likelihood-free method
 - ▶ for complex models for which an analytic likelihood function cannot be written down
 - ▶ approximate posterior distribution by sampling

- ▶ Requirements

- ▶ Summary statistic
- ▶ Distance measure
- ▶ Tolerance (error)
- ▶ Patience

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{marginal likelihood}}$$

Approximate Bayesian Computation

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Bayes Rule:

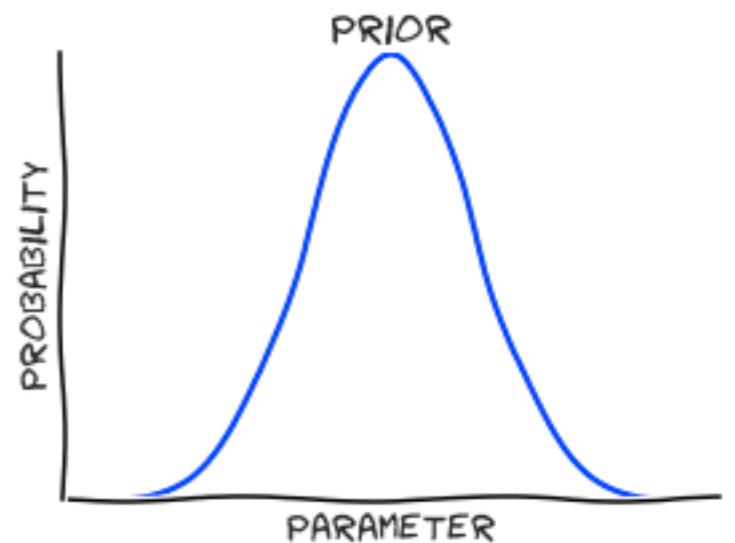
$$p(\theta_s|x) = \frac{p(x|\theta_s) \times p(\theta_s)}{p(x)}$$

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{marginal likelihood}}$$

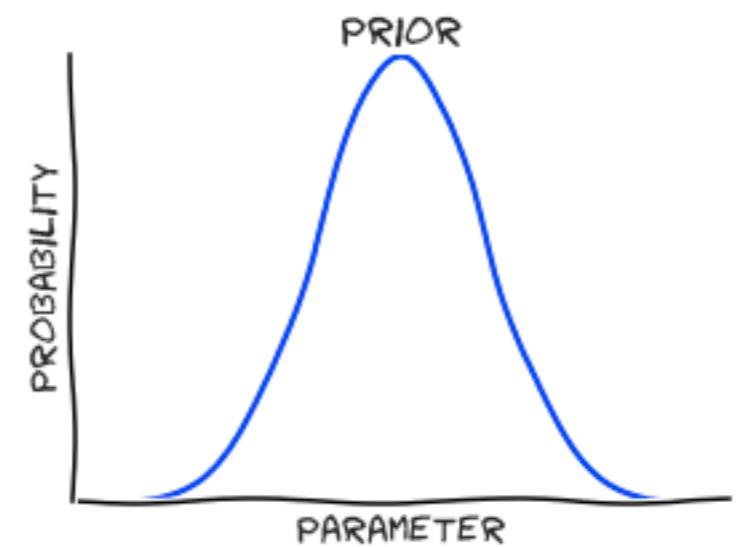
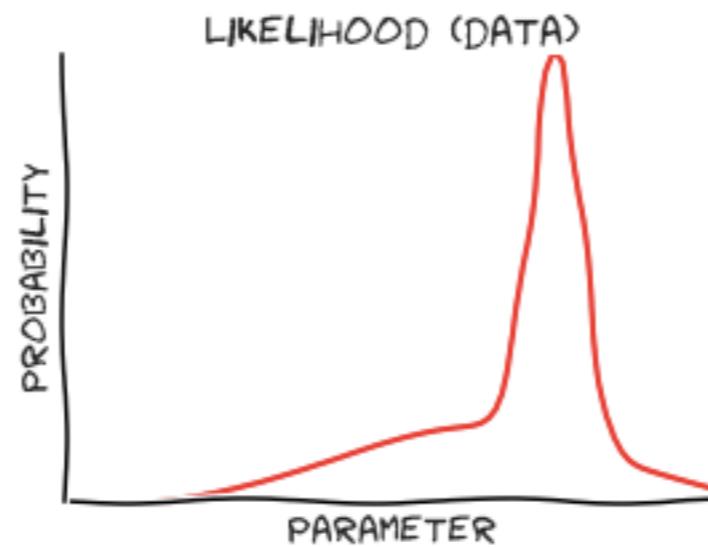
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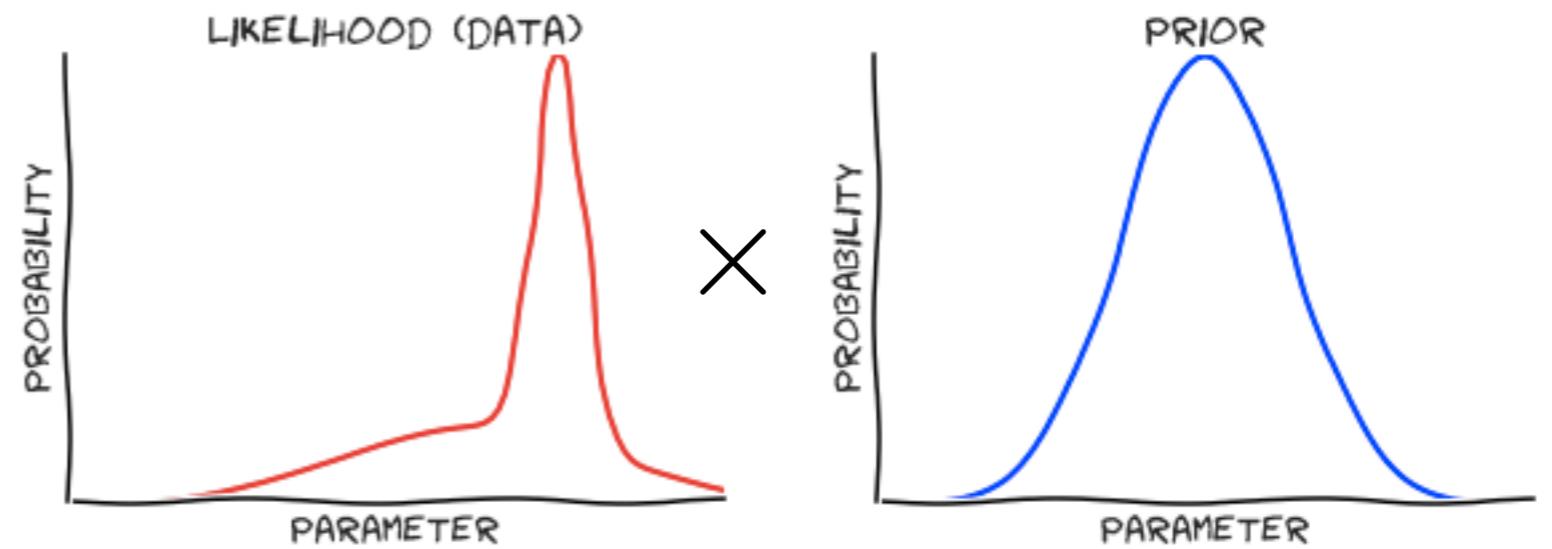
BAYESIAN INFERENCE



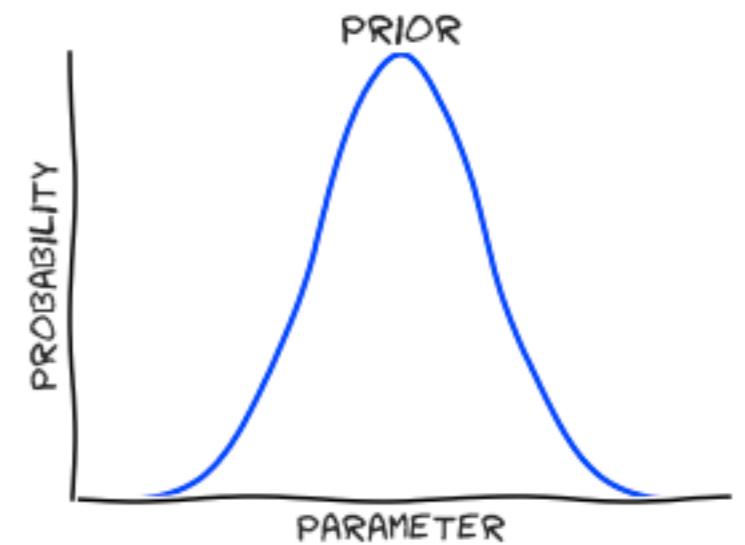
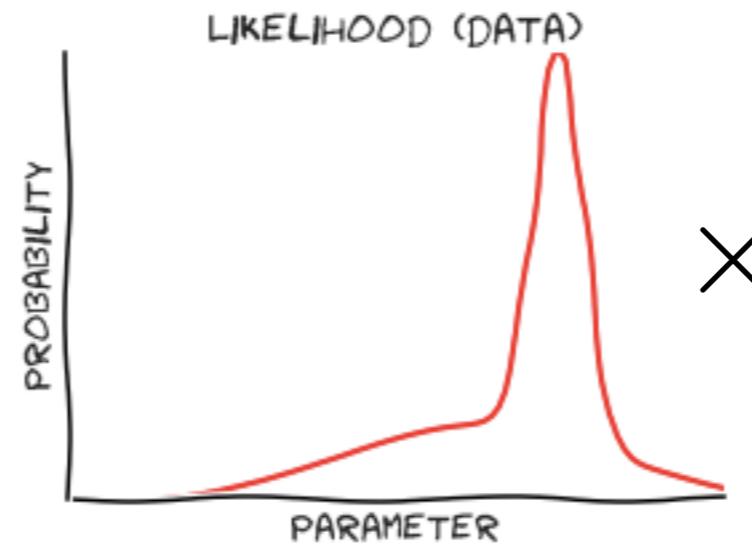
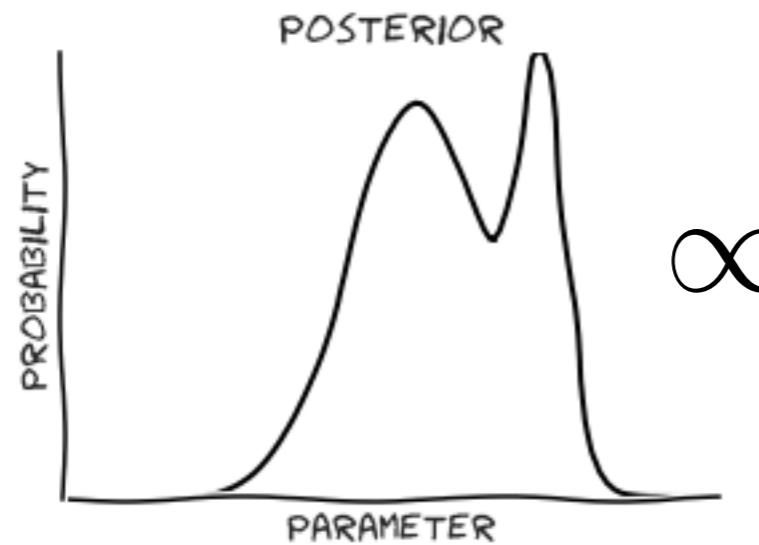
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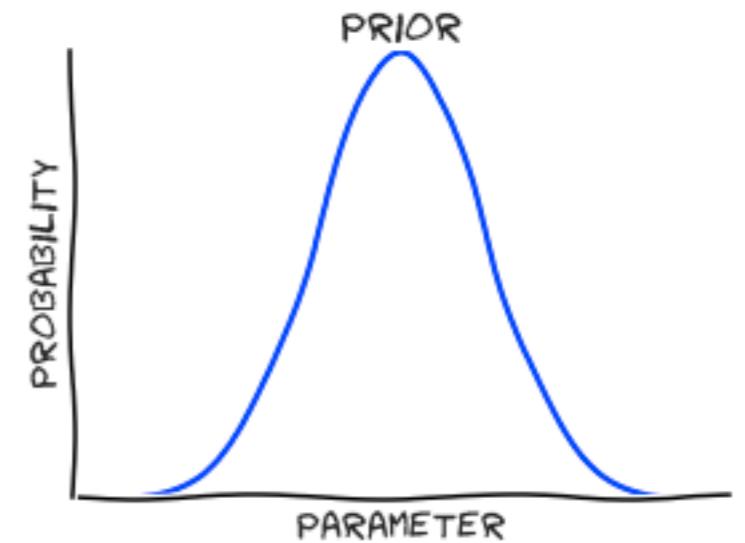
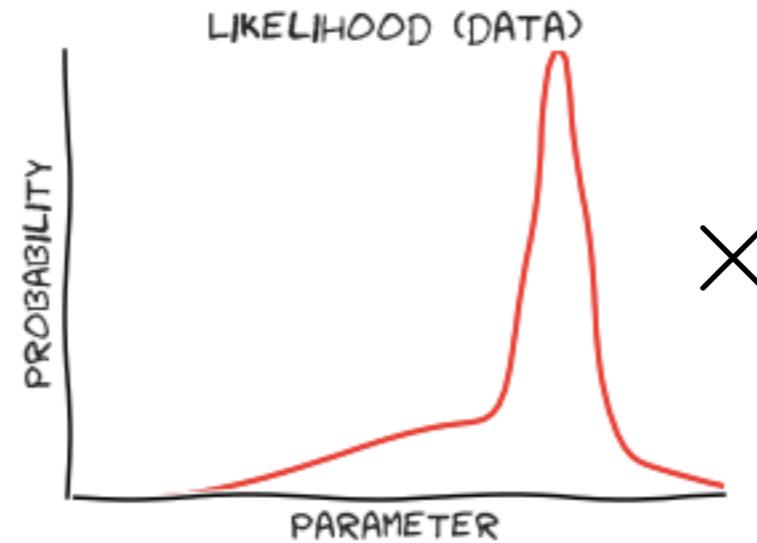
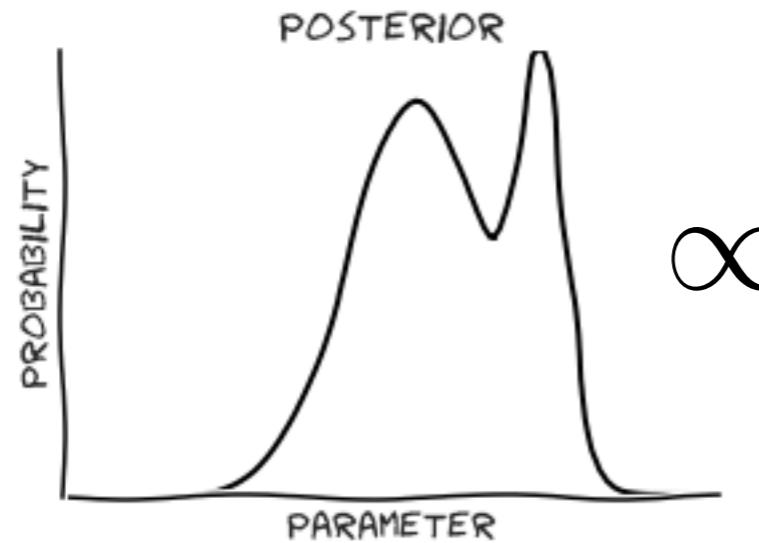
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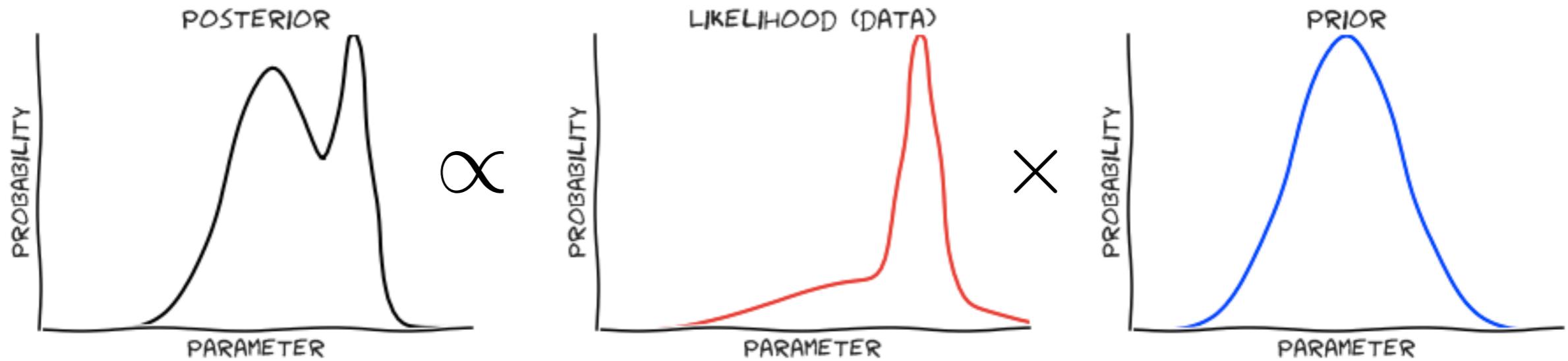


BAYESIAN INFERENCE

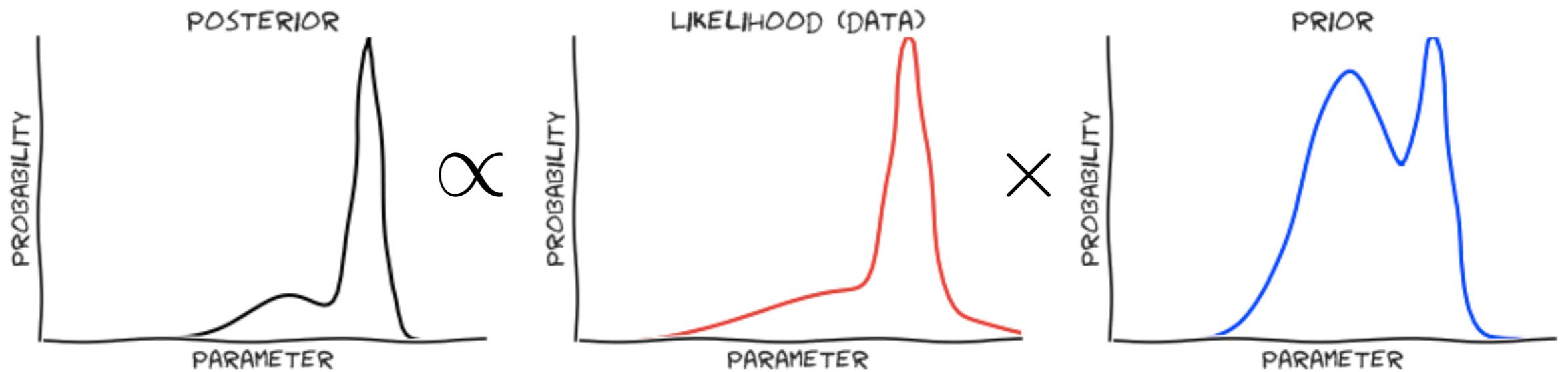


"TODAY'S POSTERIOR IS TOMORROW'S PRIOR" (LINDLEY, 1970)

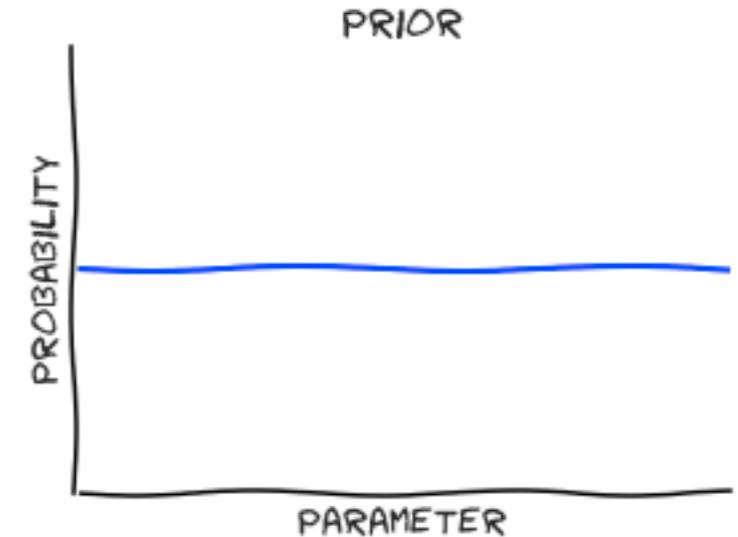
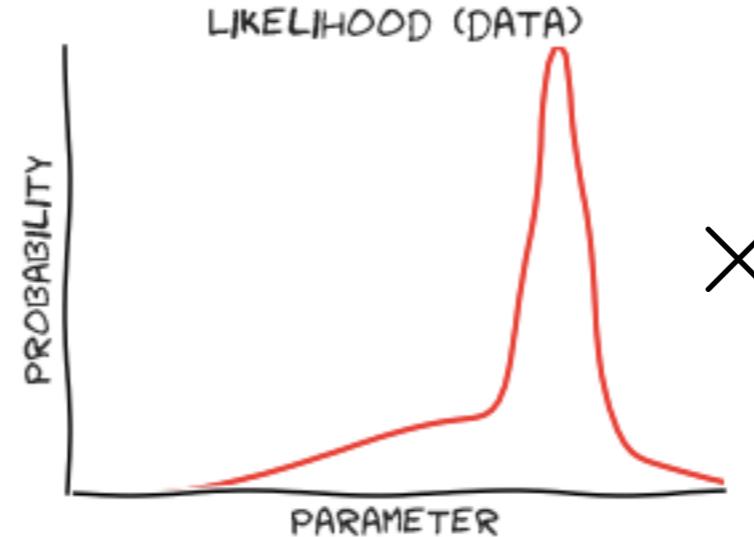
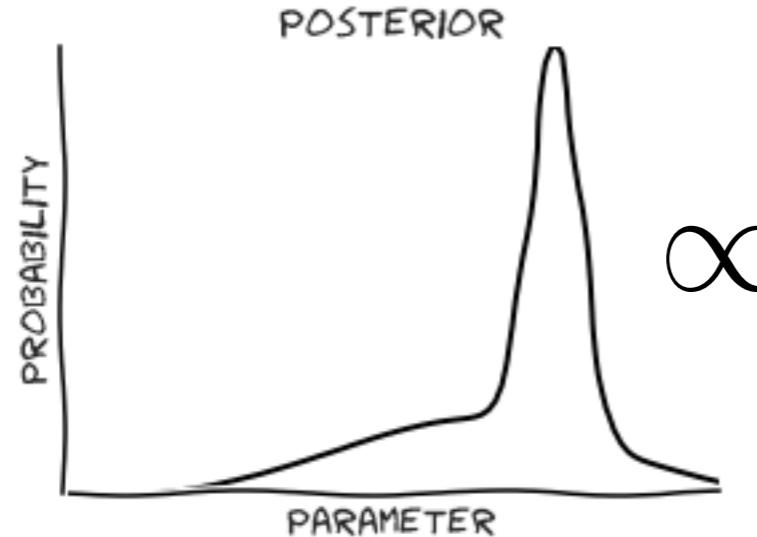
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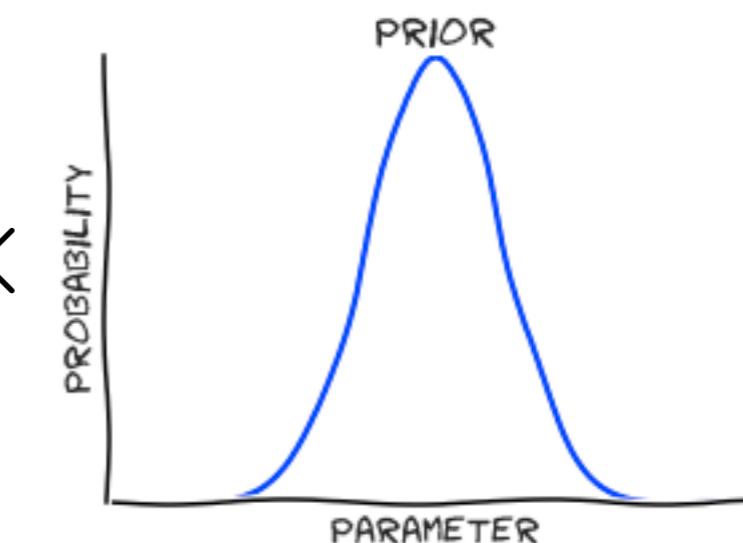
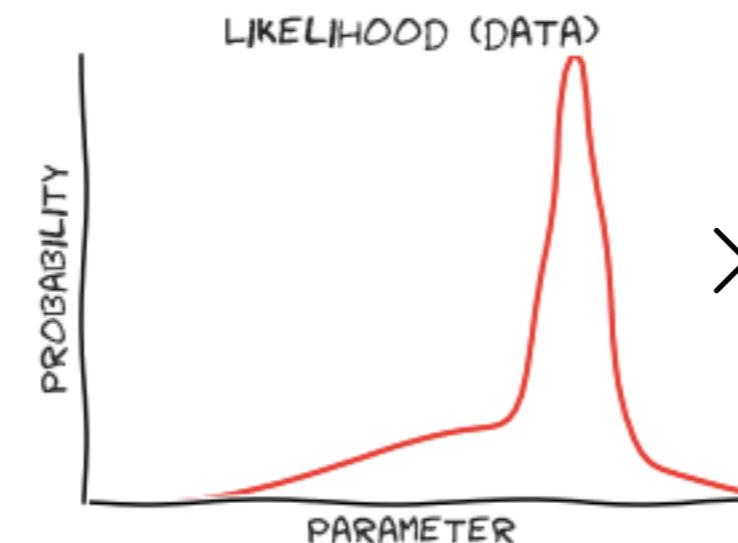
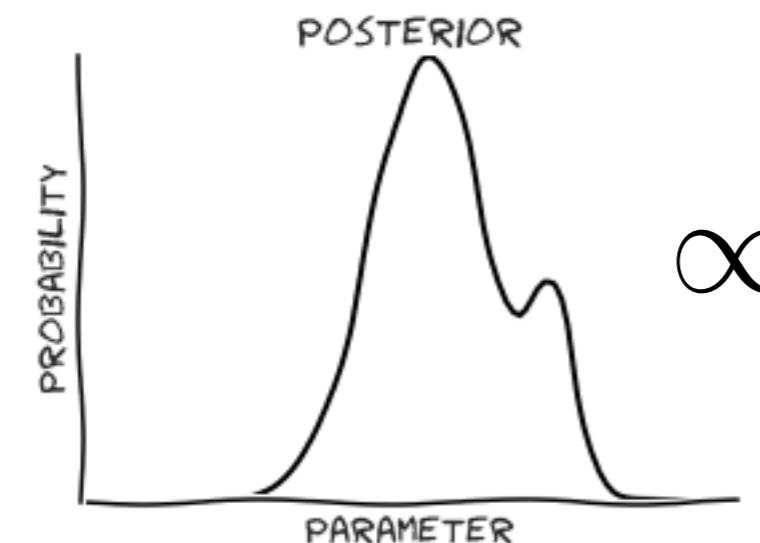
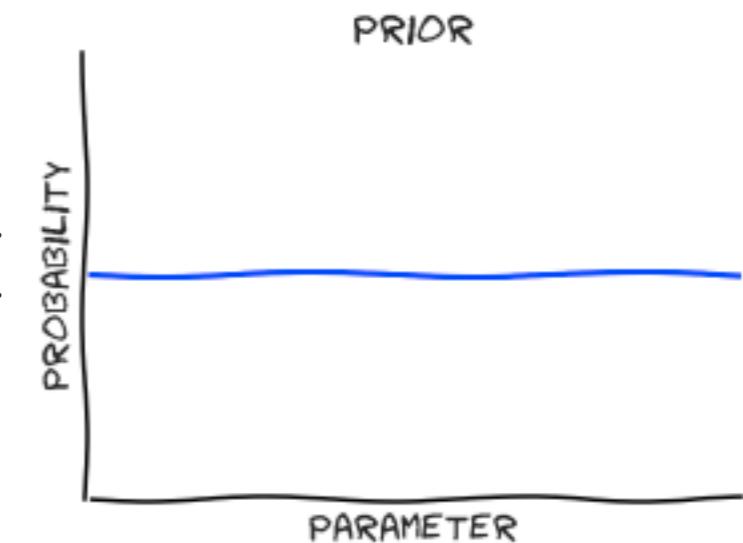
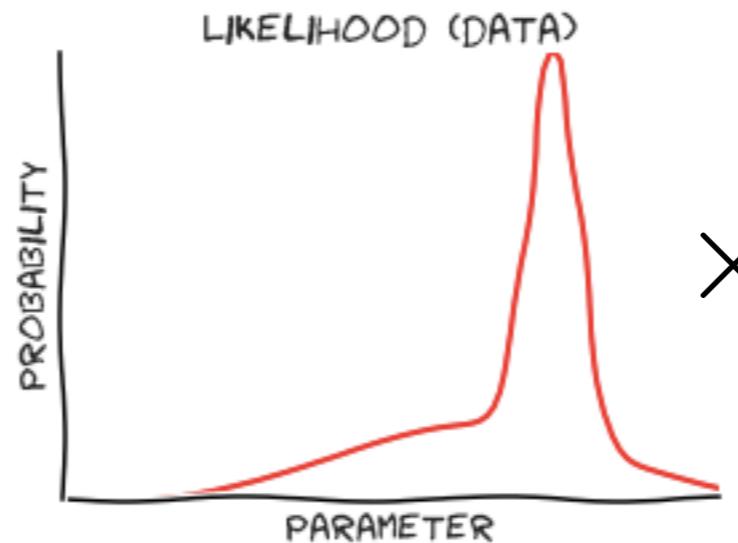
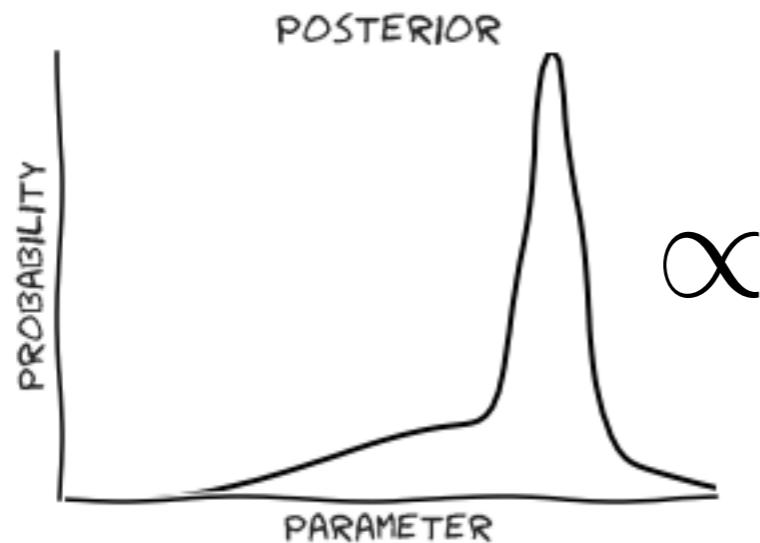
"TODAY'S POSTERIOR IS TOMORROW'S PRIOR" (LINDLEY, 1970)



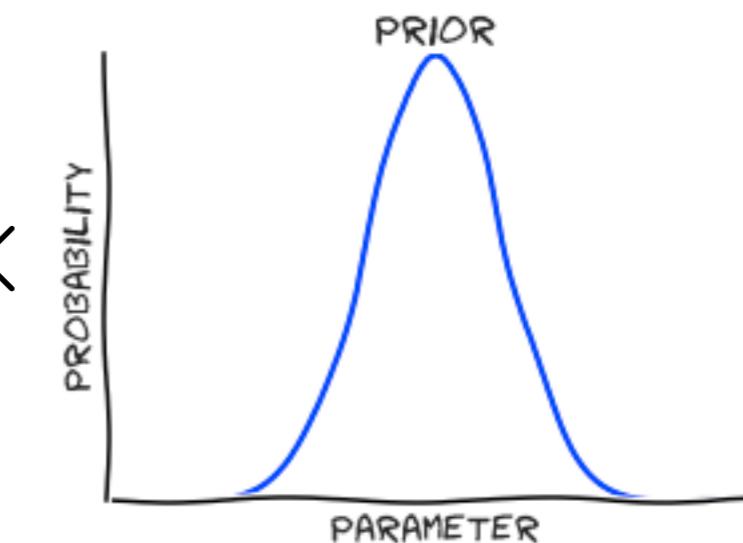
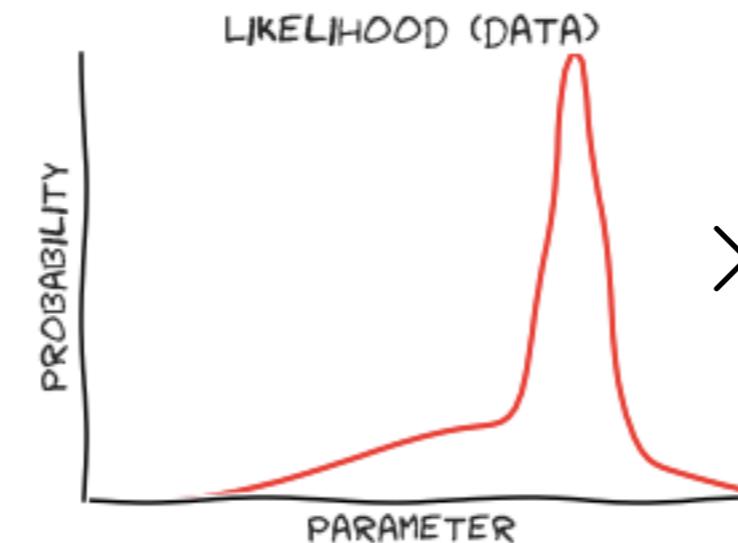
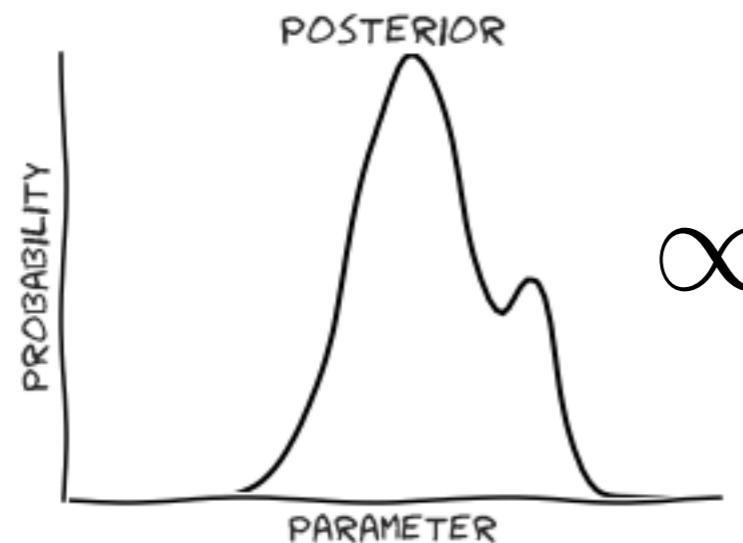
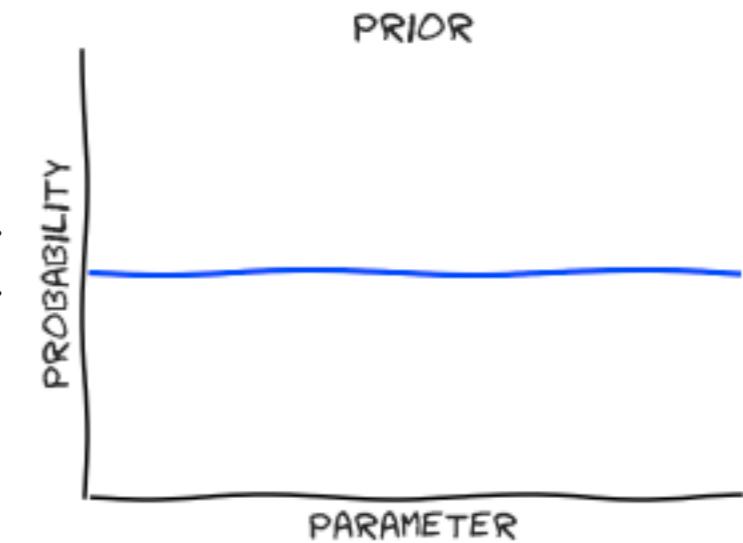
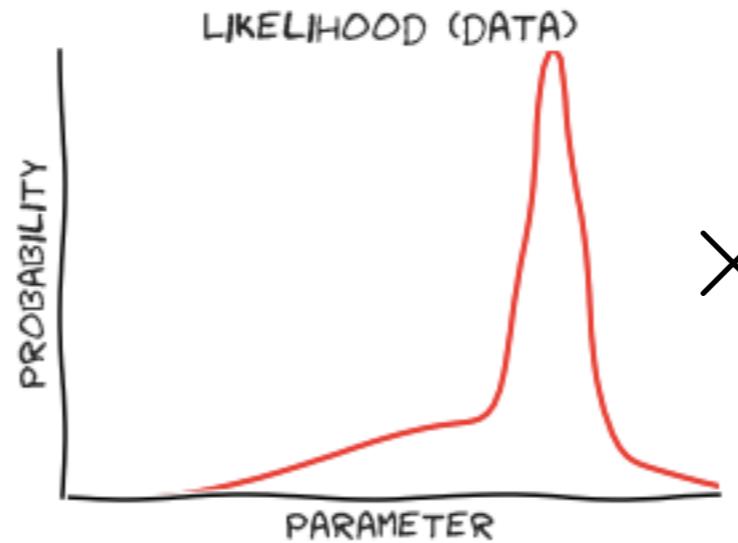
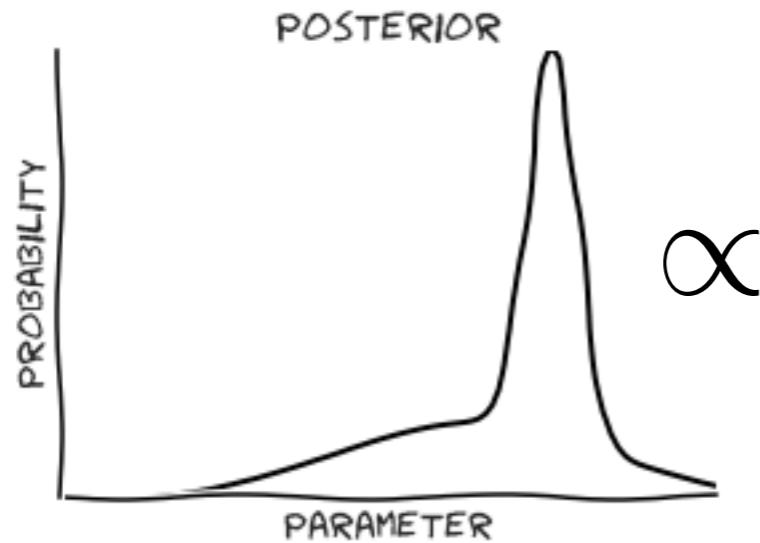
WEAK AND STRONG PRIORS



WEAK AND STRONG PRIORS

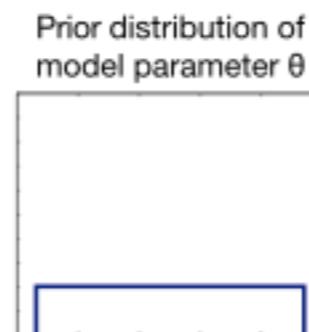
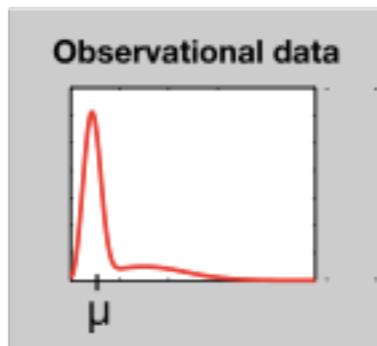


WEAK AND STRONG PRIORS



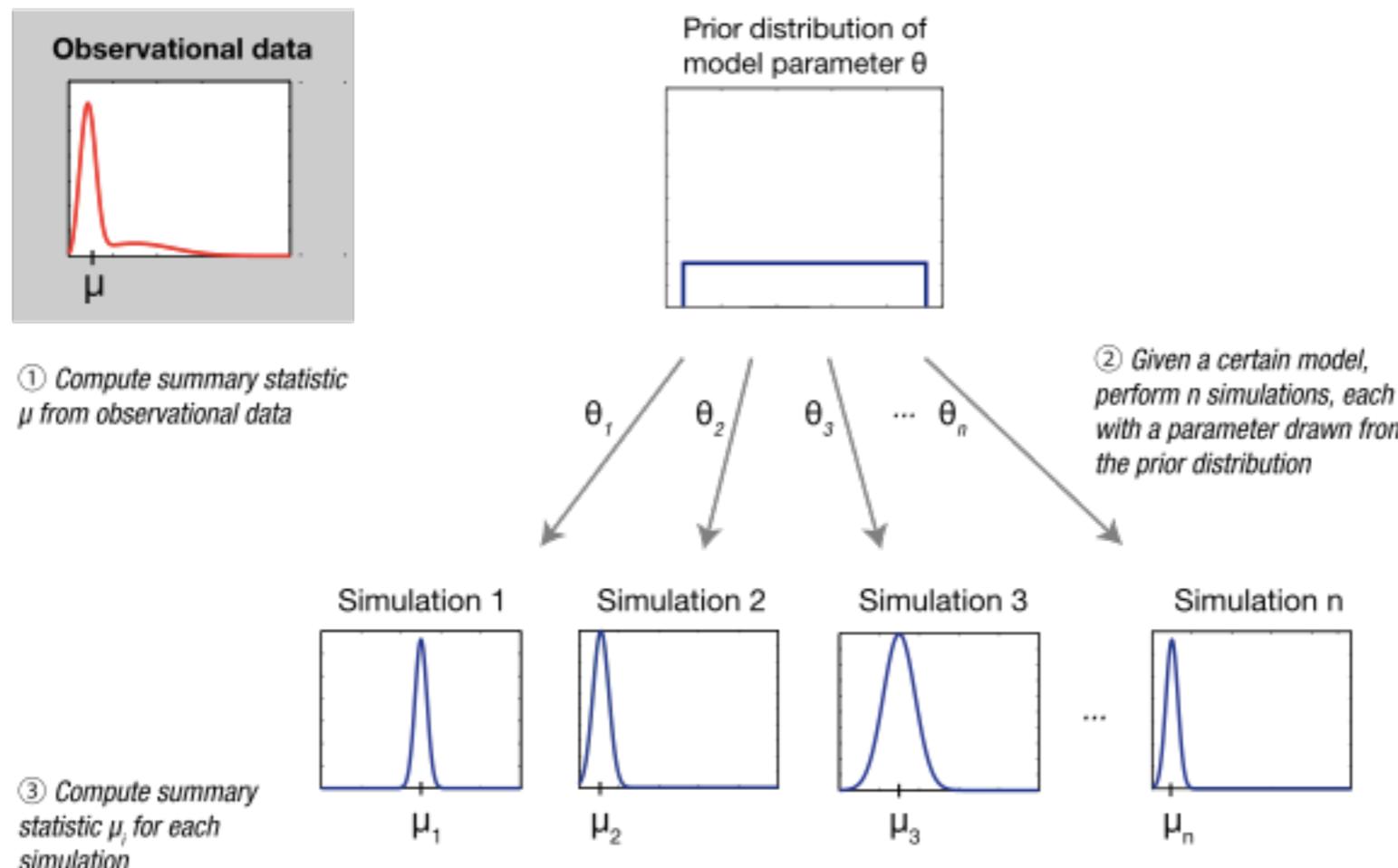
"EXTRA-ORDINARY CLAIMS REQUIRE EXTRA-ORDINARY EVIDENCE"
(CARL SAGAN)

ABC - STEP1 - DEFINE PRIOR & SUMMARY STATISTIC

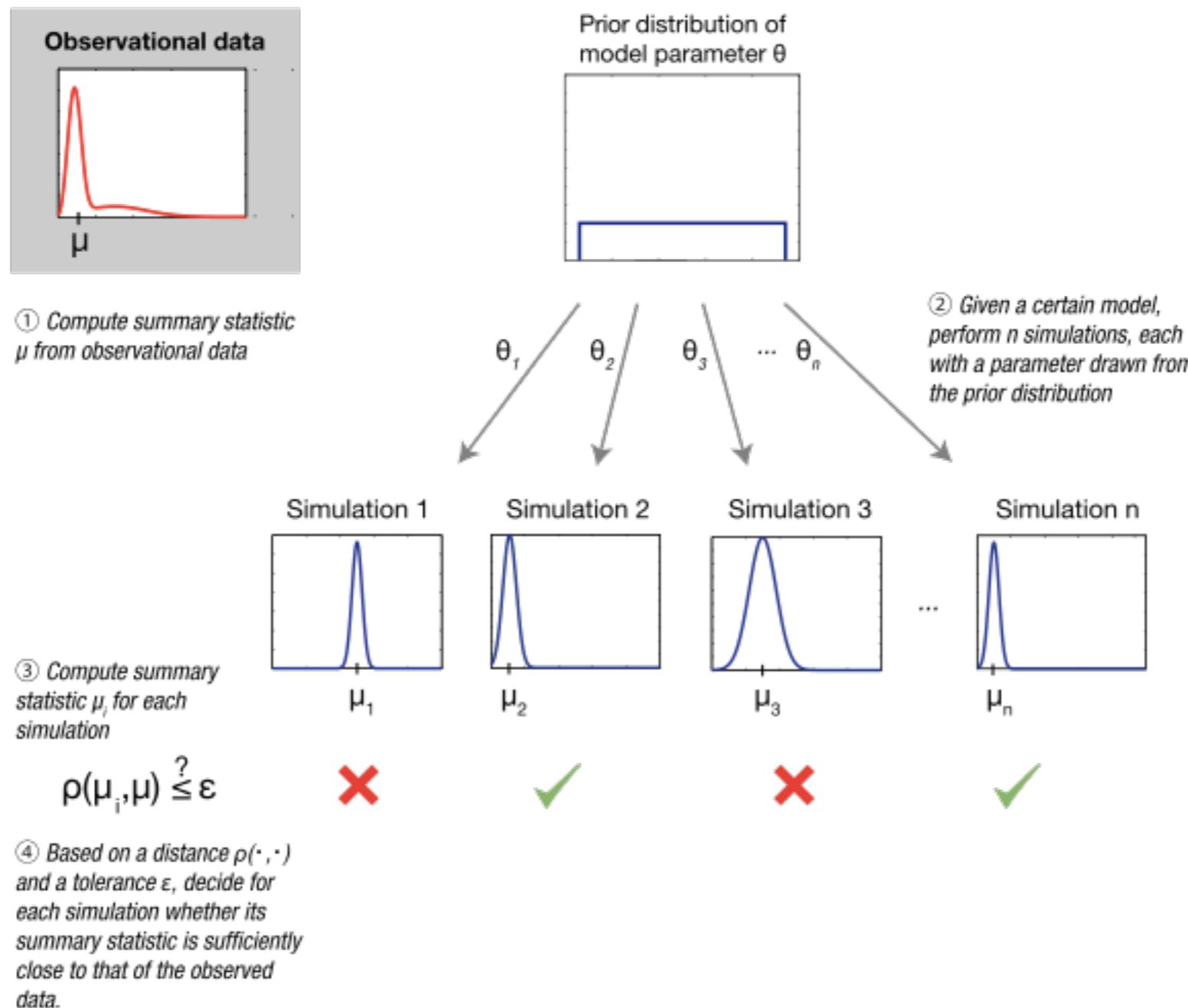


- ① Compute summary statistic μ from observational data

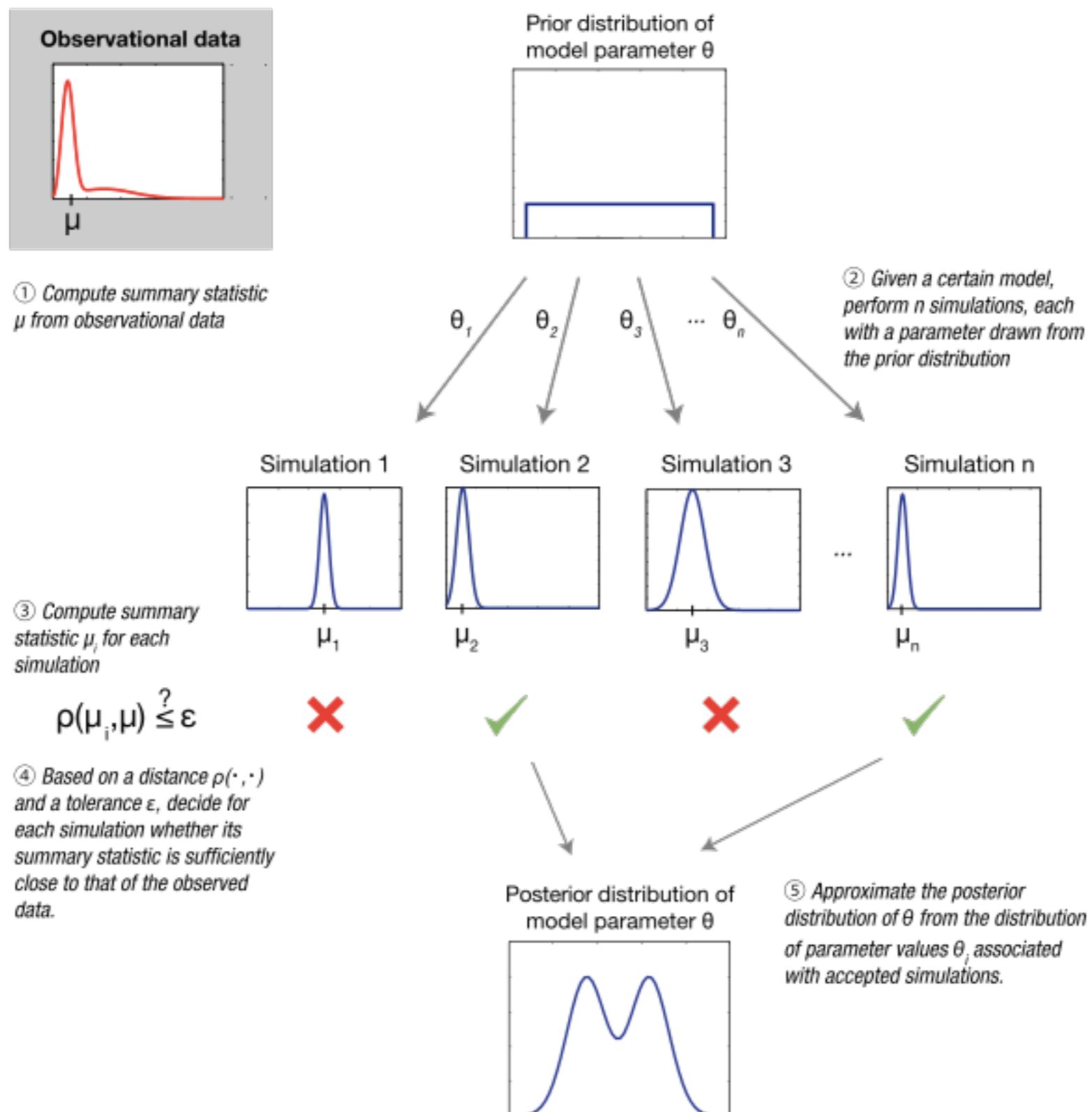
ABC - STEP 2 - SAMPLE FROM PRIOR & RUN SIMULATIONS



ABC - STEP 3 - ACCEPT / REJECT MODELS



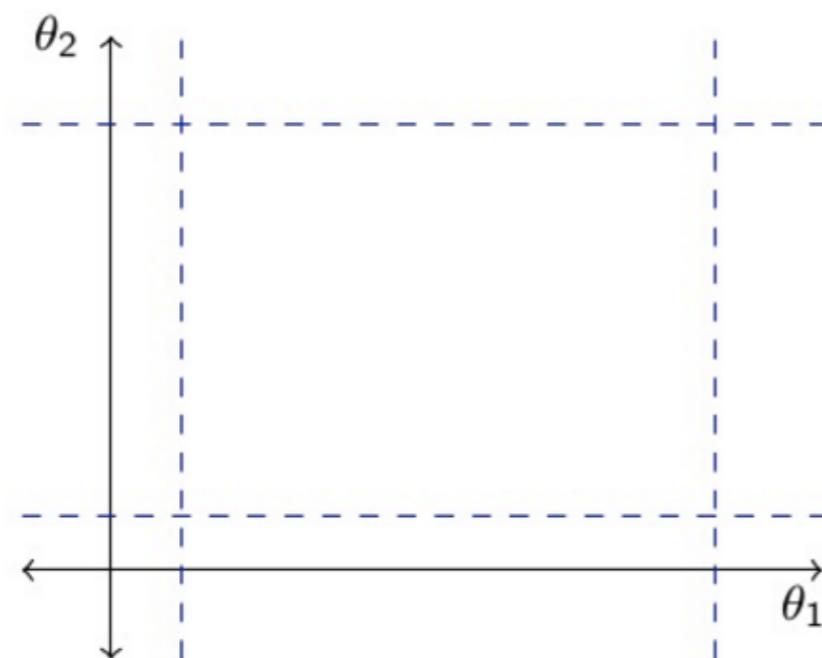
ABC - STEP 4 - APPROXIMATE POSTERIOR DISTRIBUTION



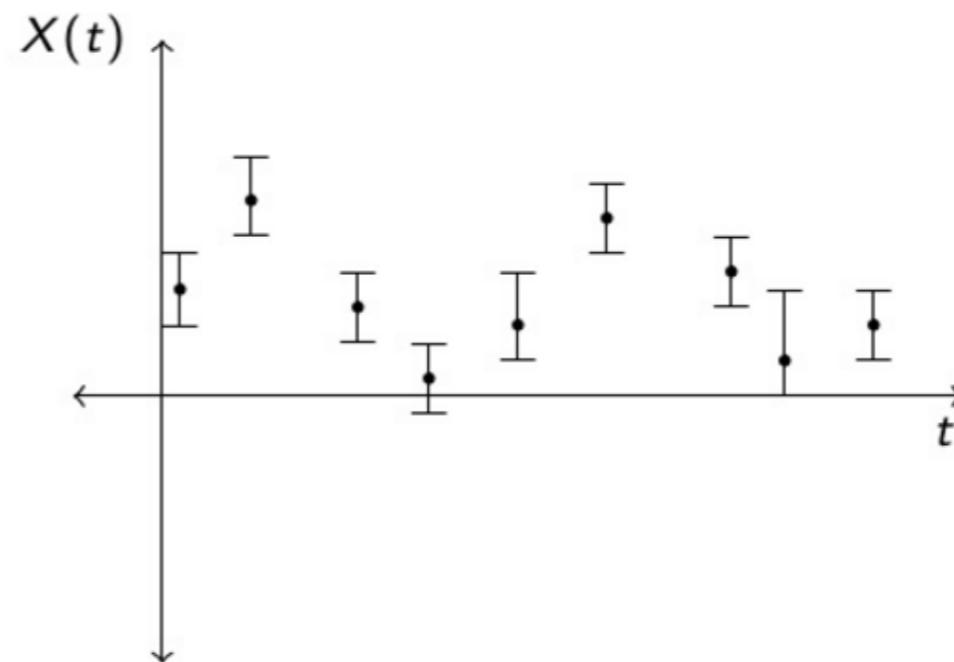
Approximate Bayesian Computation

Clip slide

Model



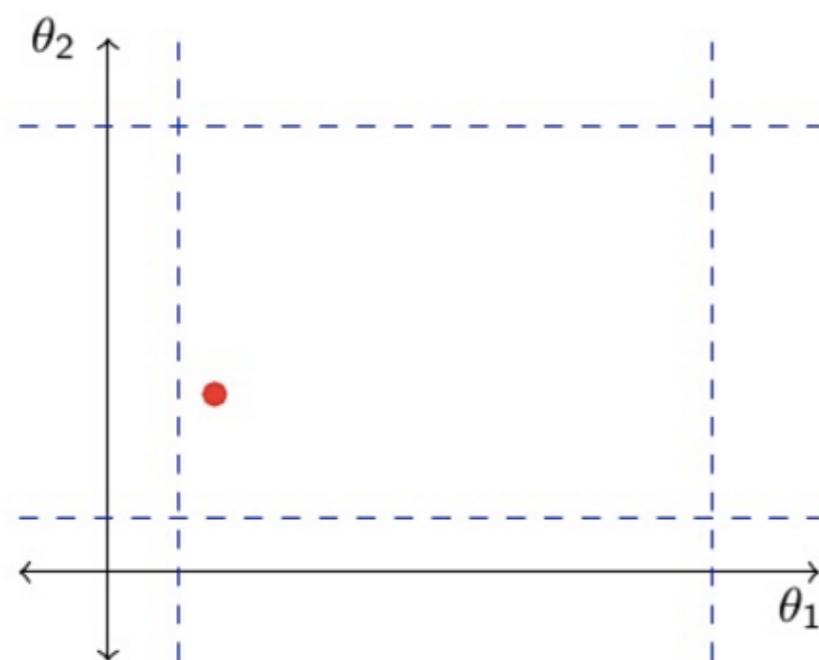
Data, X



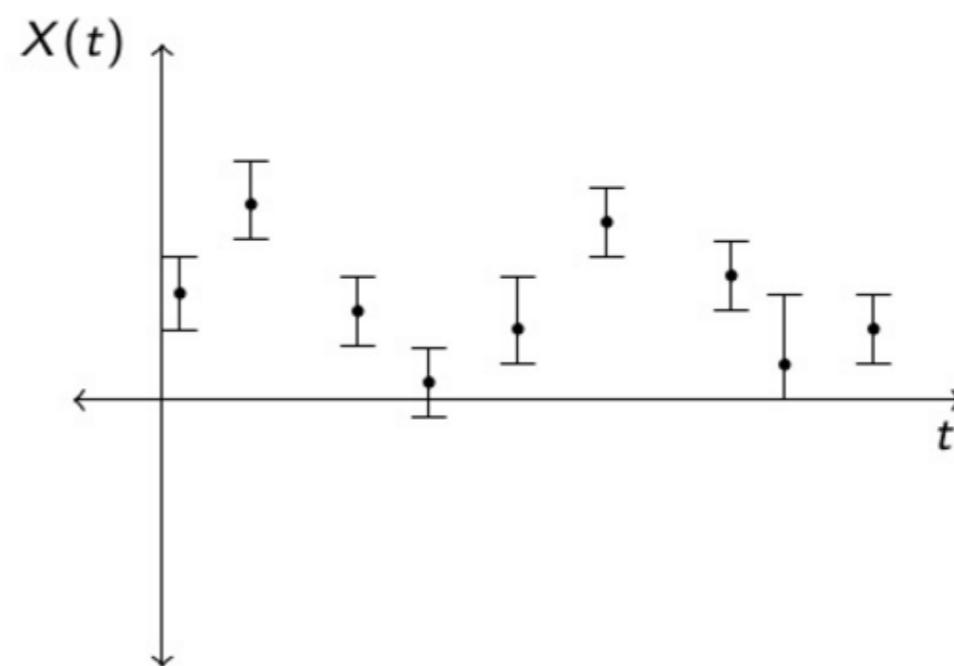
Approximate Bayesian Computation

Clip slide

Model



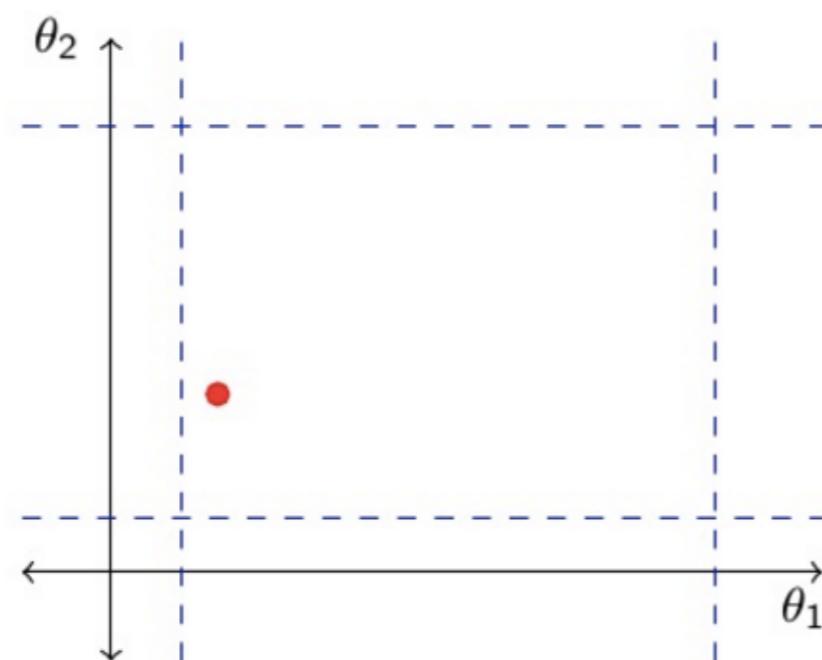
Data, X



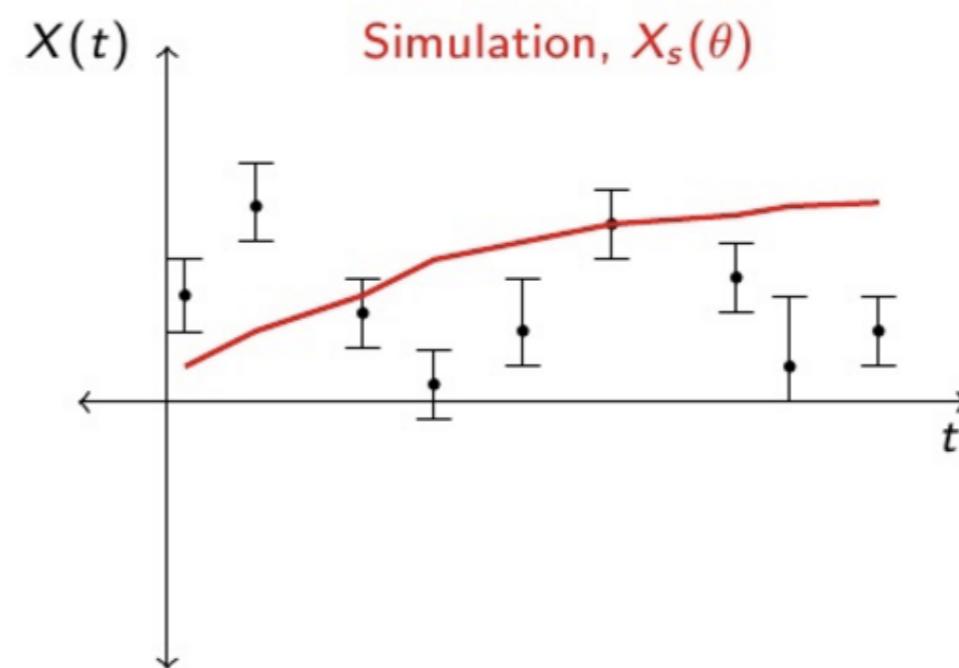
Approximate Bayesian Computation

Clip slide

Model

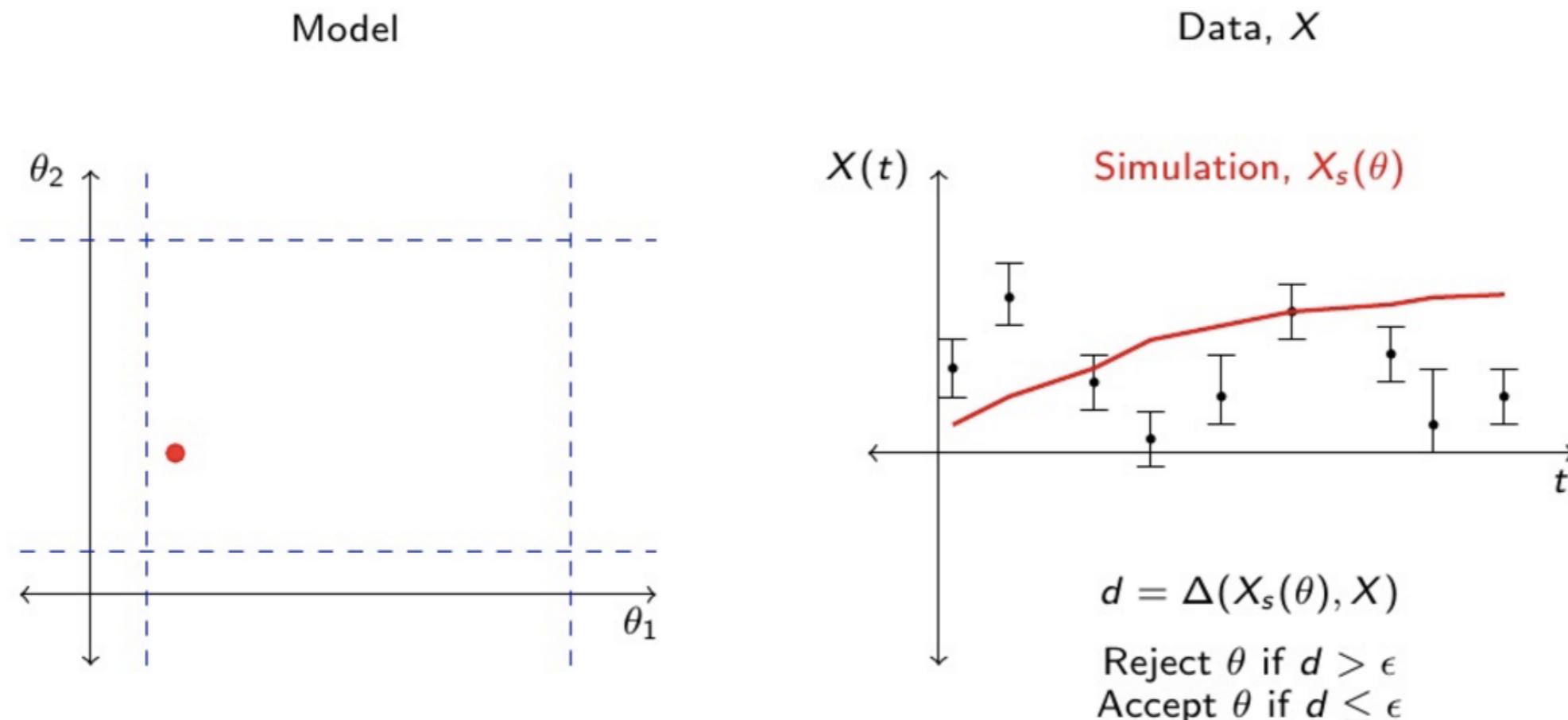


Data, X



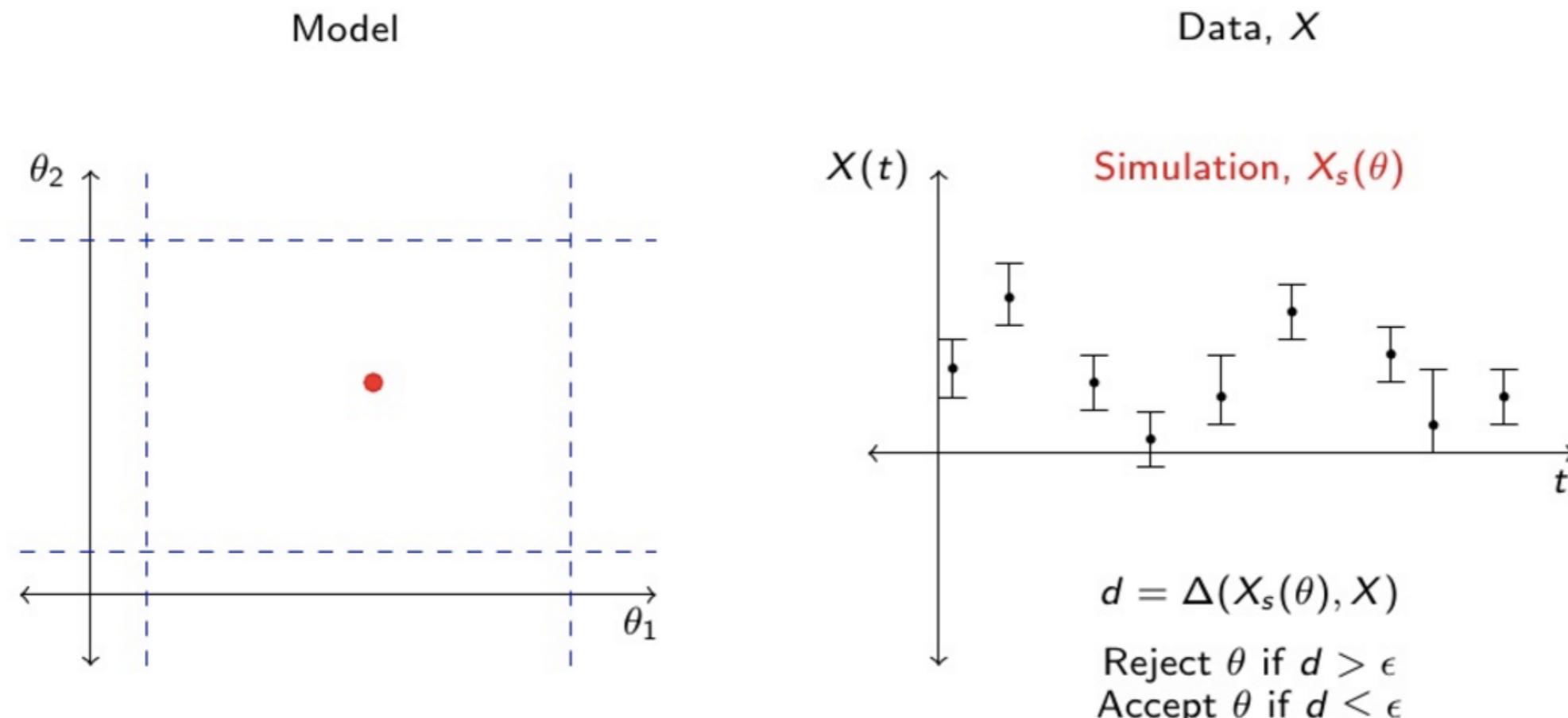
Approximate Bayesian Computation

Clip slide



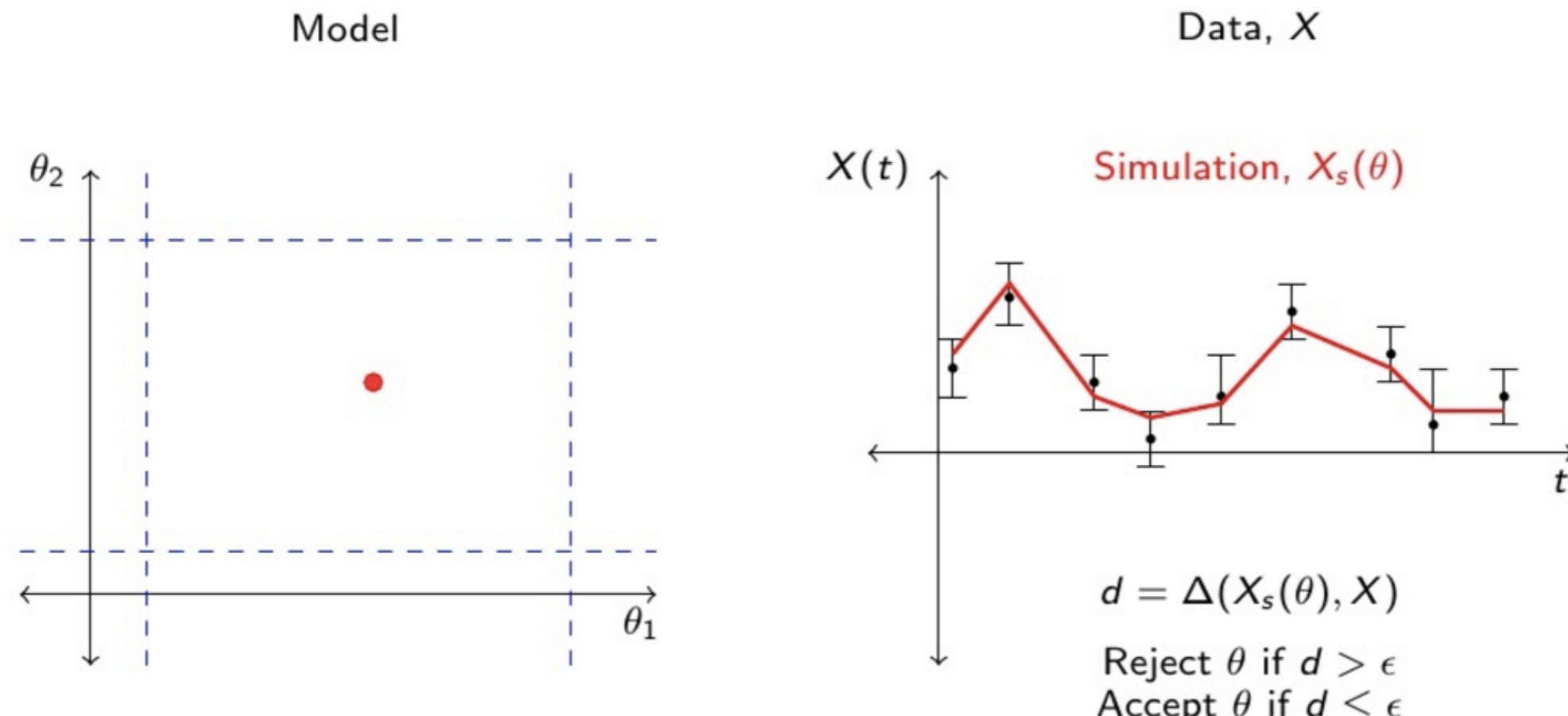
Approximate Bayesian Computation

Clip slide



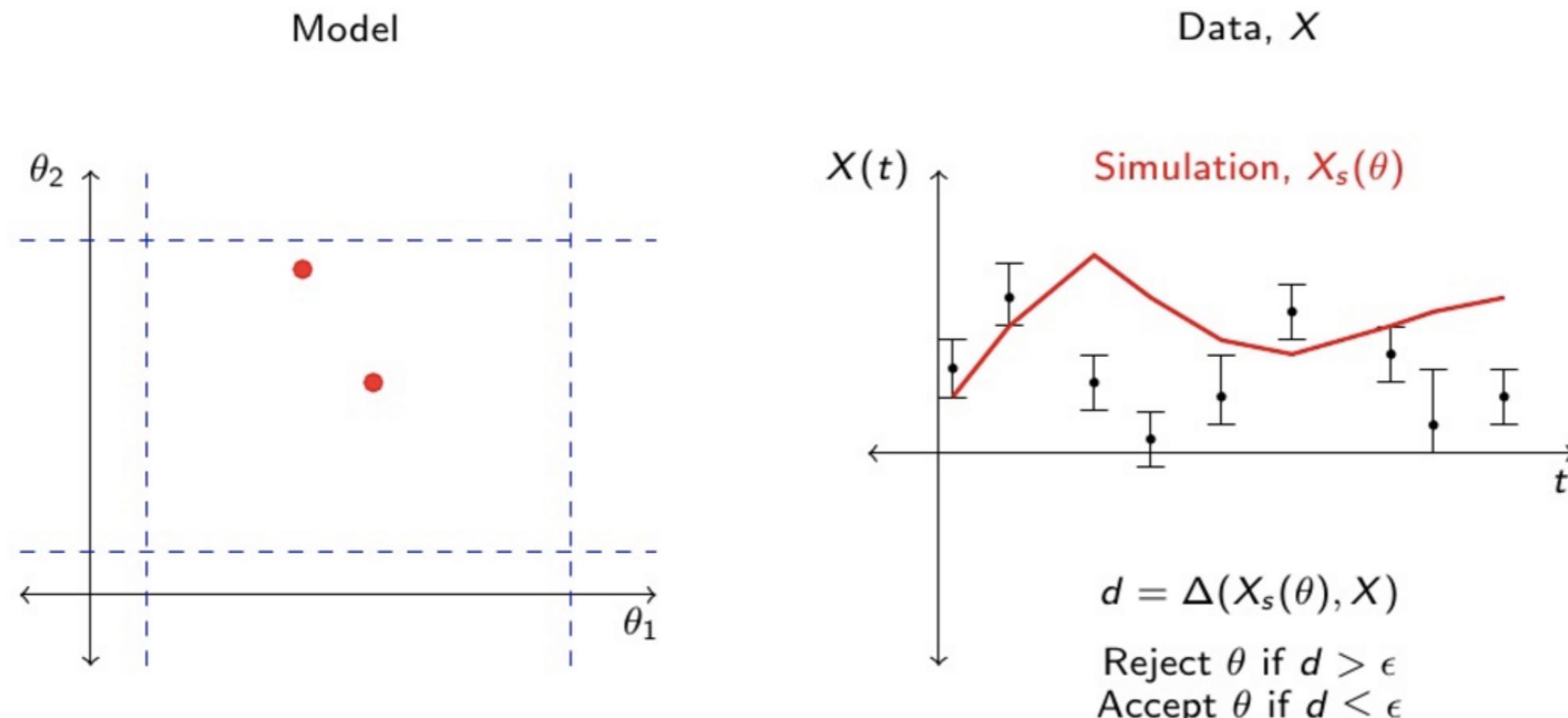
Approximate Bayesian Computation

Clip slide



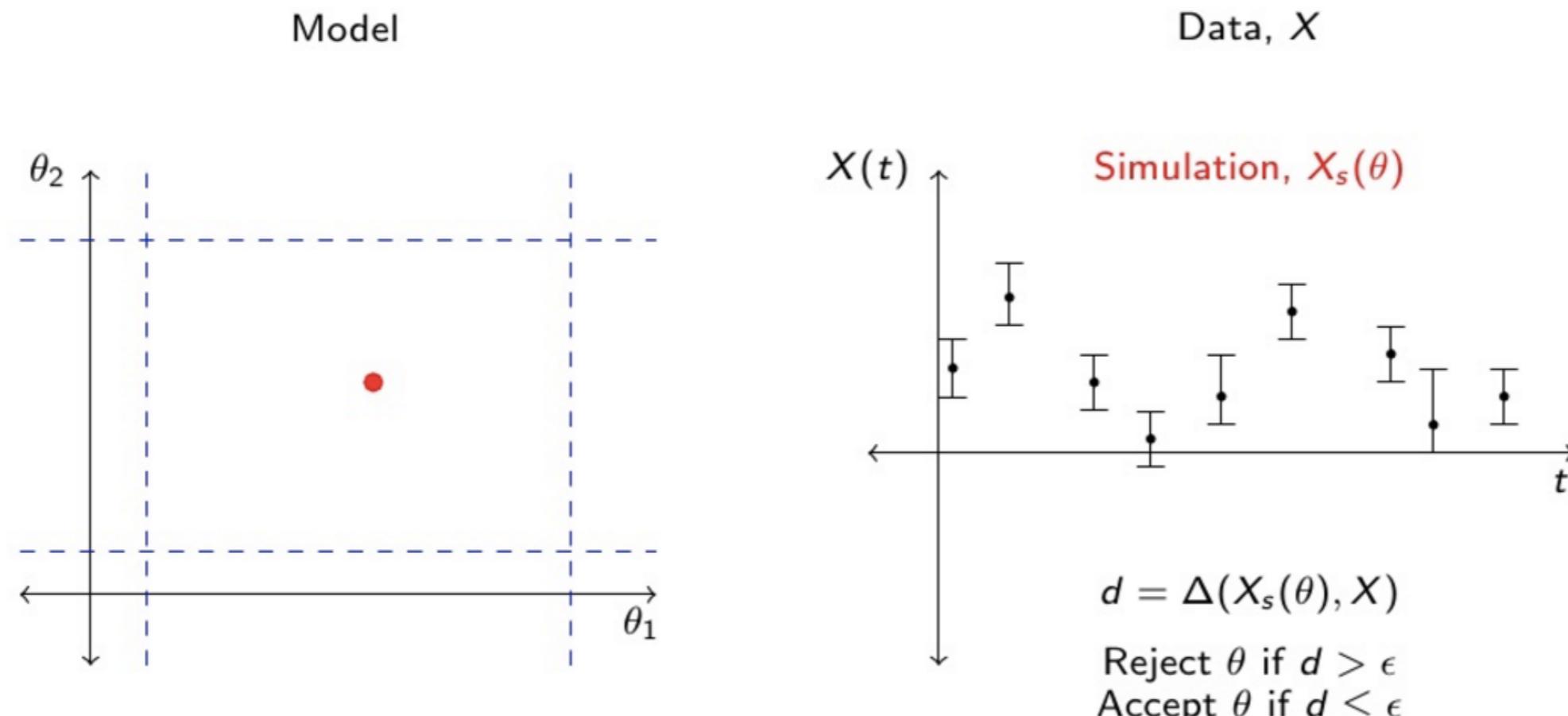
Approximate Bayesian Computation

Clip slide



Approximate Bayesian Computation

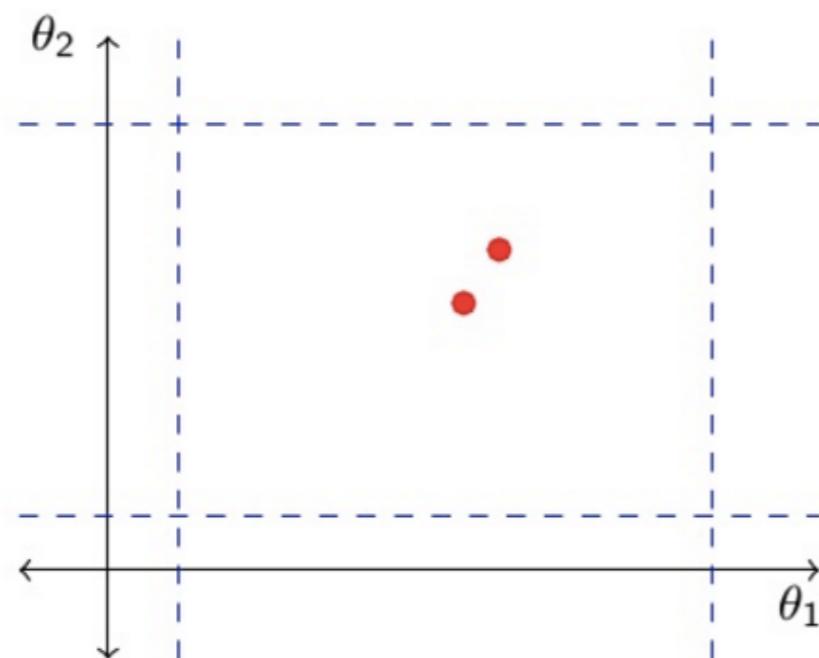
Clip slide



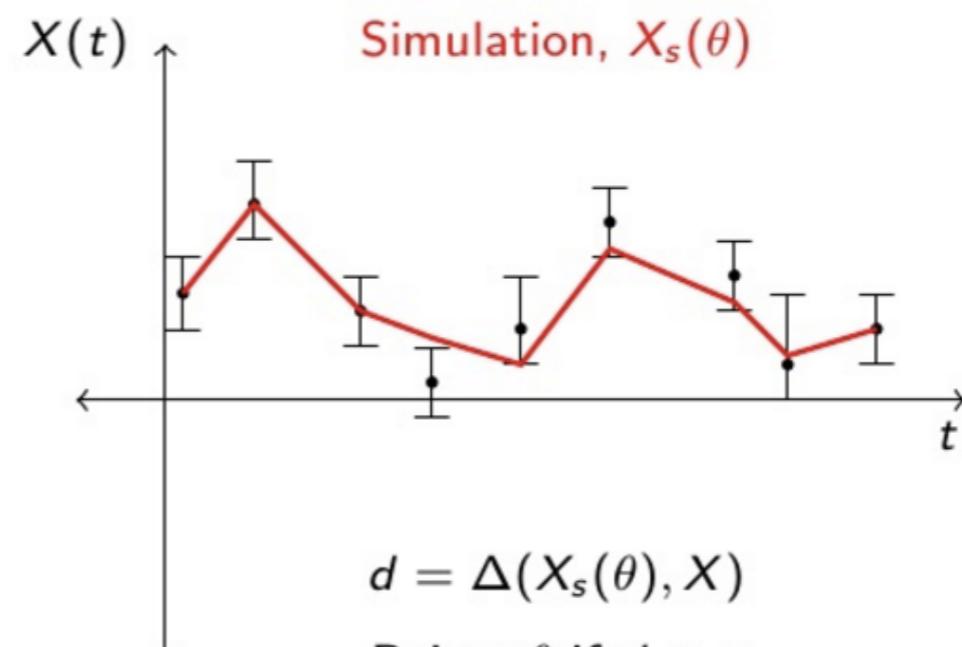
Approximate Bayesian Computation

Clip slide

Model

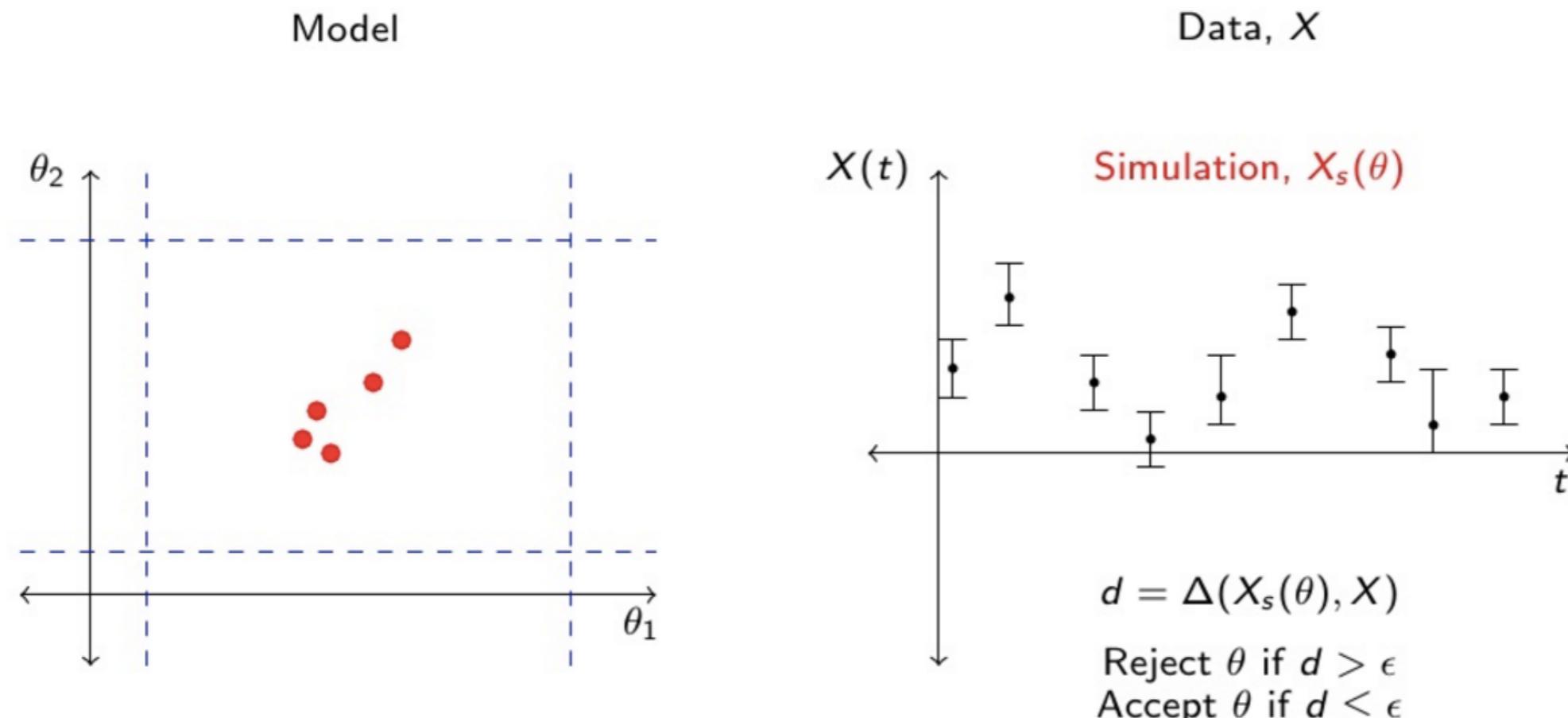


Data, X



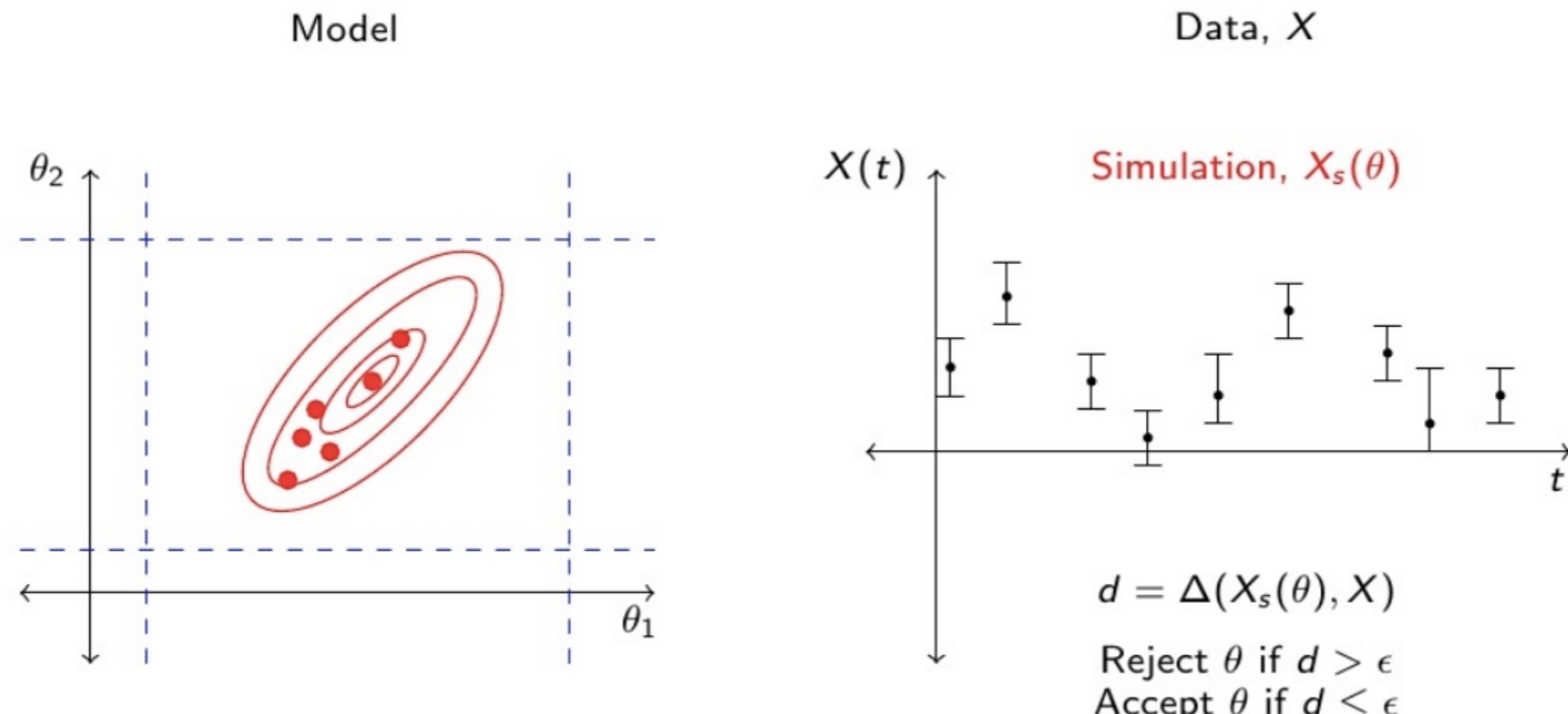
Approximate Bayesian Computation

Clip slide

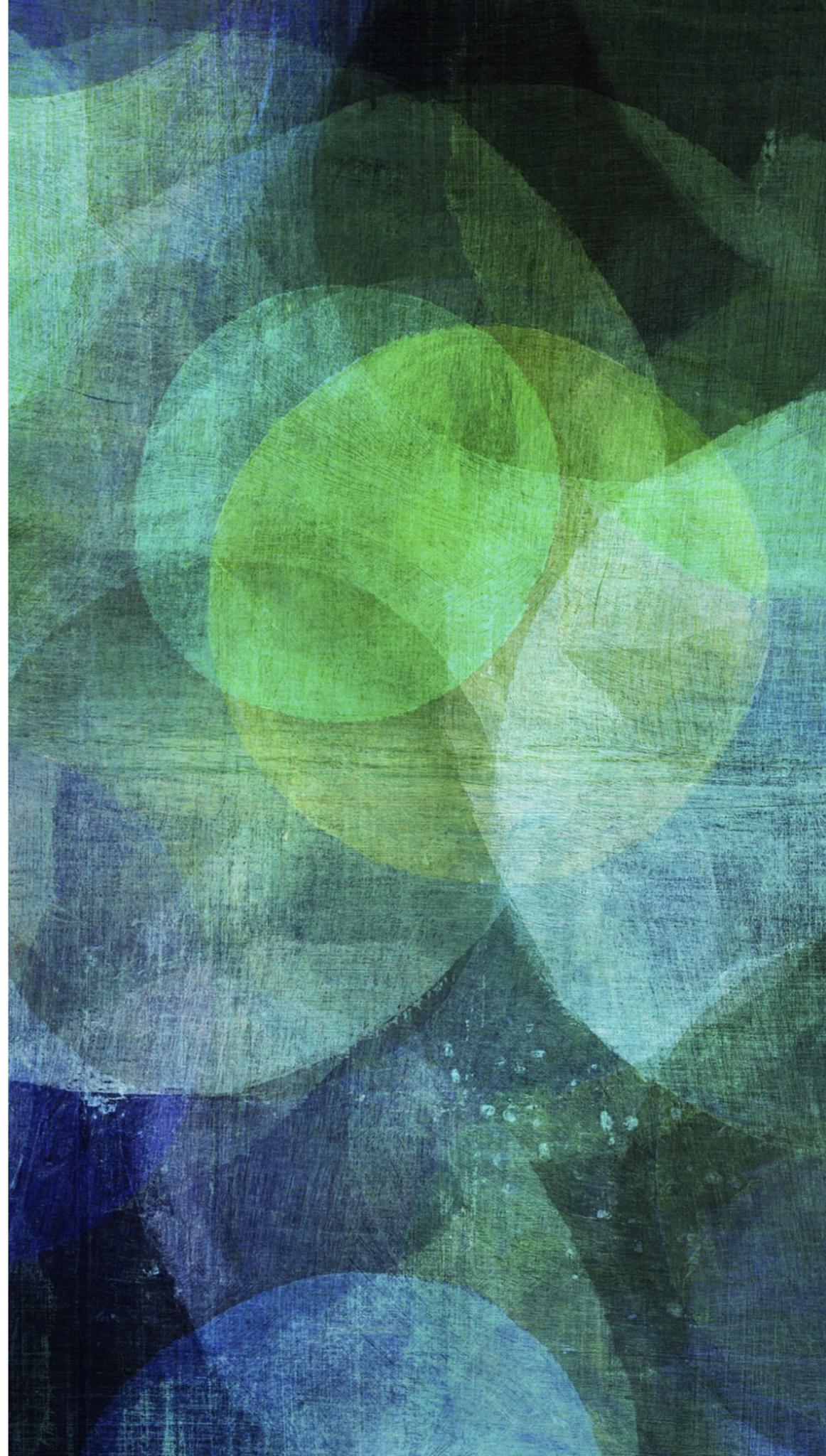


Approximate Bayesian Computation

Clip slide

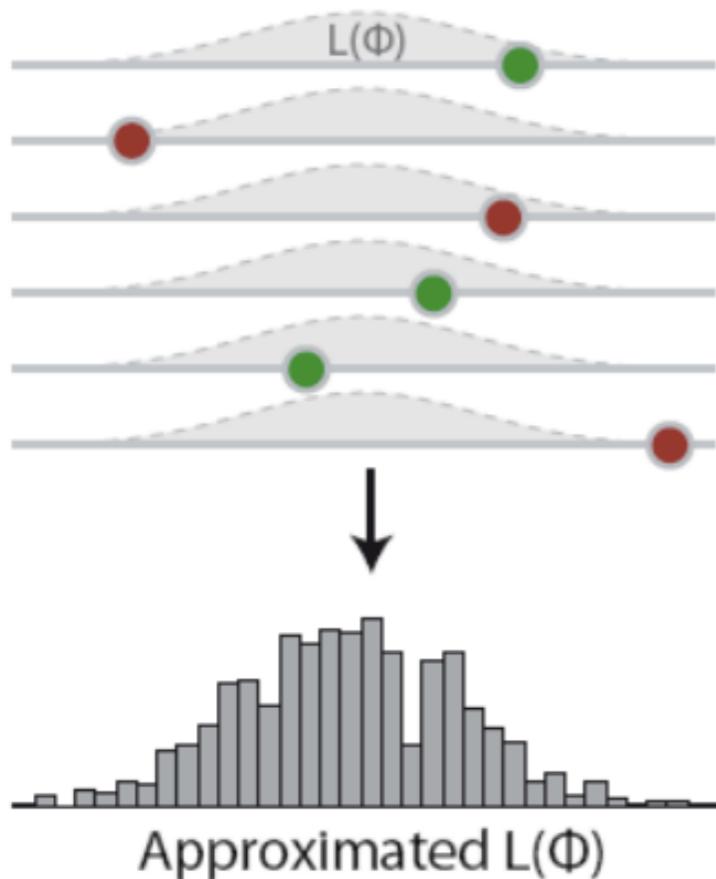


ABC ALGORITHMS



REJECTION SAMPLING

Rejection Sampling (REJ)



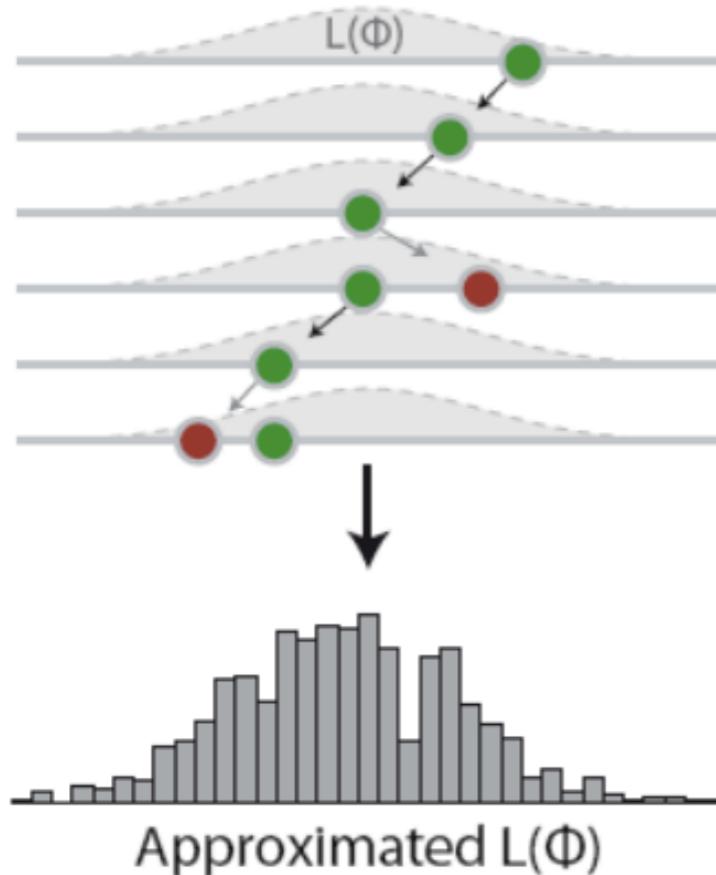
- 1) Draw a parameter Φ
- 2) Calculate $L(\Phi)$
- 3) Accept proportional to $L(\Phi)$

Algorithm 2 ABC-REJ ([Tavare et al. 1997](#); [Fu & Li 1997](#))

- 1: Define metric $d(S, S')$
 - 2: Calculate S_{obs} from the data
 - 3: **repeat**
 - 4: Sample parameter ϕ from prior
 - 5: Obtain simulated value S_{sim} from $M(\phi)$
 - 6: Accept when $d(S_{sim}, S_{obs}) < \epsilon$
 - 7: **until** Convergence criteria met
-

MARKOV CHAIN MONTE CARLO (MCMC)

MCMC Algorithm

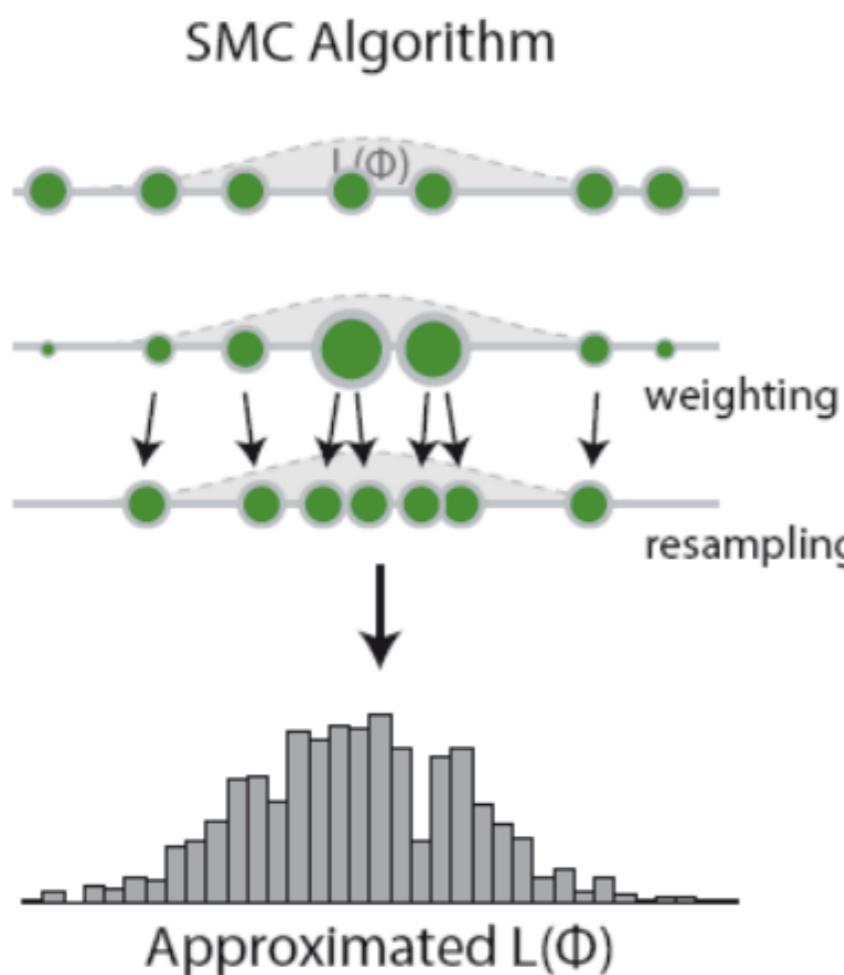


- 1) Draw new parameter Φ' close to the old Φ
- 2) Calculate $L(\Phi')$
- 3) Jump proportional to $L(\Phi')/L(\Phi)$

Algorithm 3 ABC-MCMC ([Marjoram et al. 2003](#))

```
1: Define metric  $d(S, S')$ 
2: Calculate  $S_{obs}$  from the data
3: Draw / choose initial  $\phi$ 
4: repeat
5:   Propose new  $\phi$  according to proposal function  $q(\phi \rightarrow \phi')$ 
6:   Obtain simulated value  $S_{sim}$  from  $M(\phi')$ 
7:   if  $d(S_{sim}, S_{obs}) < \epsilon$  then
8:     Jump to  $\phi'$  with probability  $\frac{p(\phi')q(\phi' \rightarrow \phi)}{p(\phi)q(\phi \rightarrow \phi')}$ 
9:   else
10:    Stay at  $\phi$ 
11:   end if
12: until Convergence criteria met
```

SEQUENTIAL MONTE CARLO (SMC) A.K.A. PARTICLE FILTERING



- 1) Last set of parameters $\{\Phi_i\}$
- 2) Assign weight ω_i proportional to $L(\Phi_i)$
- 3) Draw new $\{\Phi_i\}$ based on the ω_i

Algorithm 4 ABC-SMC ([Sisson et al. 2009](#); [Beaumont et al. 2009](#))

```
1: Define metric  $d(S, S')$ 
2: Set start acceptance distance  $\epsilon_{t=0}$ 
3: repeat
4:   repeat
5:     if  $t = 0$  then
6:       Sample particle  $\phi_i^0$  from initial distribution  $\mu(\phi)$ 
7:       Set  $\omega_i^0 = p(\phi)/\mu(\phi)$ 
8:     else
9:       Pick  $\phi_i^t$  from the  $\phi_j^{t-1}$  with prob  $\omega_j^{t-1}$ 
10:      Perturb  $\phi_i^t$  by Kernel  $K(\phi, \phi')$ 
11:      Set  $\omega_i^t = p(\phi)/\sum_{j=1}^N \omega_j^{t-1} K(\phi_i^t, \phi_j^{t-1})$ 
12:    end if
13:    if  $d(M(\phi_i^t), S) < \epsilon_t$  then
14:      Accept  $\phi_i^t$  for the next generation
15:    end if
16:  until  $N$  particles sampled
17:  Optional: update  $\epsilon_t$  and  $K(\phi, \phi')$ 
18: until Convergence criteria met
```
