Standard Model is best model (working title)

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ABSTRACT

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This is the abstract text.

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Preface

This is the preface. It’s optional, but it’s nice to give some context for the reader and stuff.

Will K. DiClemente
Philadelphia, February 2019

Chapter 1

Introduction

The Standard Model (SM)[1] has been remarkably successful...

[1] Here's a footnote.

Chapter 2

Theoretical Framework

(Some example introductory text for this chapter)...

2.1 Introduction to the Standard Model

Modern particle physics is generally interpreted in terms of the Standard Model (SM). This is a quantum field theory which encapsulates our understanding of the electromagnetic, weak, and strong interactions...

2.2 Electroweak Mixing and the Higgs Field

When the theory of the electroweak interaction was first developed [1, 2], the W and Z bosons were predicted to be massless (a typical mass term in the Lagrangian would violate the SU(2) symmetry). However, these were experimentally observed to have masses...

Chapter 3

LHC and the ATLAS Detector

3.1 The Large Hadron Collider

The Large Hadron Collider (LHC) [3] is...

3.2 The ATLAS Detector

ATLAS is a general-purpose particle detector...

3.2.1 The Inner Detector

The Inner Detector serves the primary purpose of measuring the trajectories of charged particles...

3.2.1.1 Pixel Detector

The Pixel detector consists of four cylindrical barrel layers and three disk-shaped endcap layers...

3.2.1.2 Semiconductor Tracker

The Semiconductor Tracker uses the same basic technology as the Pixels, but the fundamental unit of silicon is a larger “strip”...

3.2.1.3 Transition Radiation Tracker

The Transition Radiation Tracker is the outermost component of the ID...

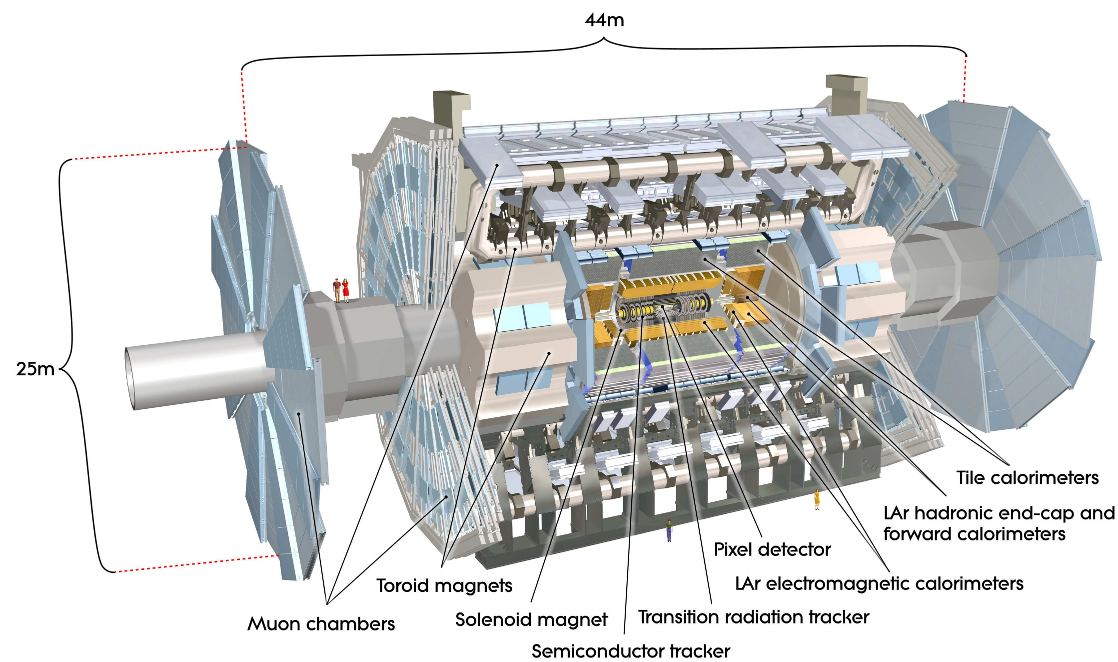

Figure 3.1: General cut-away view of the ATLAS detector [4].

3.2.2 The Calorimeters

ATLAS includes two types of calorimeter system for measuring electromagnetic and hadronic showers. These are the Liquid Argon (LAr) calorimeters and the Tile calorimeters. Together, these cover the region with $|\eta| < 4.9$...

3.2.2.1 Liquid Argon Calorimeters

The Liquid Argon system consists of...

3.2.2.2 Tile Calorimeters

The Tile calorimeter provides coverage for hadronic showers...

Chapter 4

Alignment of the ATLAS Inner Detector

In order for the subdetectors of the ID to operate at their designed precisions, it is essential that the locations of the sensors be known as precisely as possible. Differences between the expected and actual positions of a sensor can result in displaced particle hits and degrade track reconstruction quality. These misalignments can occur for any number of reasons, including but not limited to elemnts shifting during maintenance periods or cycles in ATLAS's magnetic field, or simply small movements during normal detector operations. Since it is not practical to physically realign hundreds of thousands of detector elements to μm precision by hand, an iterative track-based alignment algorithm is used to determine the physical positions and orientations of these elements [5]. The effects of misalignments and the steps taken to correct and monitor them are detailed in this chapter.

4.1 Effects of Misalignment

Hello world!

4.2 The Alignment Method

Hello world!

4.3 Momentum Bias Corrections

Hello world!

4.4 Alignment of the IBL

Hello world!

4.5 Alignment Monitoring

Hello world!

Chapter 5

WZ production @ $\sqrt{s} = 13$ TeV

5.1 Theoretical motivation

Hello world!

5.2 Signal definition

Hello world!

5.3 Background estimations

Hello world!

5.4 Cross section measurement

Hello world!

Chapter 6

Same-sign WW @ $\sqrt{s} = 13$ TeV

6.1 Theoretical motivation

Hello world!

6.2 Signal definition

Hello world!

6.3 Background estimations

Hello world!

6.4 Cross section measurement

Hello world!

Chapter 7

Prospects for same-sign WW at the High Luminosity LHC

On December 3, 2018, Run 2 of the LHC officialy ended, and the collider was shut down to begin the first of two scheduled extended maintenance periods [6]. During these two long shutdowns, the Phase-I and Phase-II upgrades of the LHC and ATLAS will occur in order to prepare for the High-Luminosity LHC (HL-LHC) which is scheduled to begin operation in 2026 [7].

The HL-LHC is planned to run at an instantaneous luminosity of $\mathcal{L} = 5 \times 10^{34}$ cm^{-2}s^{-}1 with an average of 140 collisions per beam-crossing. Over the course of operation, the HL-LHC is expected to collect a total integrated luminosity of $\mathcal{L} = 3000$ fb^{-1} by 2035 [8].

These run conditions are much harsher than what ATLAS has experienced so far, and as a result there are several planned upgrades to the detector. Most notably, the entire ID will be replaced with an all-silicon tracker which will extend the coverage from $|\eta| \leq 2.7$ up to $|\eta| \leq 4.0$. This will allow for reconstruction of charged particle tracks which can in turn be matched to clusters in the calorimeters for electron identification or forward jet tagging [9].

TODO: Why are we studying ssww at the HL-LHC

7.1 Theoretical motivation

The theoretical motivation for studying the ssWW process is detailed in Section 6.1.

7.2 Signal definition

Hello world!

7.2.1 Sensitivity to longitudinal polarization

7.3 Background estimations

Hello world!

7.4 Selection optimization

TODO: Motivation

7.4.1 Random grid search algorithm

The chosen algorithm for optimizing the event selection is known as the Random Grid Search (RGS) [10]. Consider a simple case of two variables x and y chosen to differentiate the signal from the background. In order to be considered a signal event, a given event would be required to pass a *cut point* $\{x > x_c, y > y_c\}$. A simple method to choose the optimal cut point (i.e. the "best" values of the cuts x_c and y_c) would be to construct an $n \times m$ rectangular grid in x and y consisting of points $(x_0, y_0), (x_1, y_1), ..., (x_n, y_m)$, as in Figure 7.1. One can then choose a cut point $\{x > x_i, y > y_j\}$ that maximizes the signal significance as measured by a chosen metric. This would be considered a *regular* or *rectangular* grid search.

The rectangular grid search comes with two major drawbacks:

1. The algorithm does not scale well as the number of variables to be optimized (i.e. the dimensionality of the grid) increases. In the case of a square grid with N bins per dimension d, the number of cut points to be evaluated grows as N^d.

2.

7.4.2 Inputs to the optimization

7.4.3 Results of the optimization

7.5 Cross section measurement

Hello world!

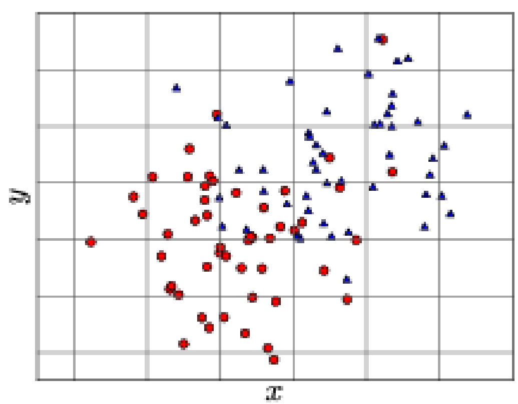

Figure 7.1: TODO: replace with own figure

Chapter 8

Conclusion

Here's where you wrap it up.

Looking Ahead

Here's an example of how to have an "informal subsection".

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