

About Emittance Grow in SIMULINAC Simulations

To understand the influence of non-linearities from different cavity-models in SIMULINAC on transverse and longitudinal emittances, simulations with identical lattices but different cavity-mappings have been done.

All simulations have been done with [git repository](#) version v11.0.2.3 and input file TT29.yml from that repository.

Cavity-Model with Mapping **t3d**.

Mapping t3d is a linear model. It uses the matrices defined in the code [Trace 3-D](#). The cavities are modeled as Drift-Kick-Drift (DKD) triplets. It does not use any field distribution table. This simulation is the fastest one.

Cavity-Model with mapping **oxal**.

Mapping oxal is a linear model. It uses matrices defined in the [article](#) by A.Shishlo and Jeff Holmes section 4.6 OpenXAL RF Gap Model. It does need a table (from SuperFish) for the field distribution E_{0z} on axis. The cavities are modeled as DKD triplets. This simulation is a bit slower than the t3d simulation.

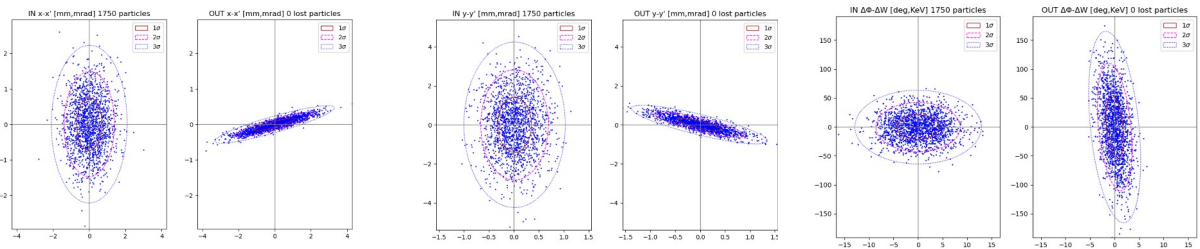
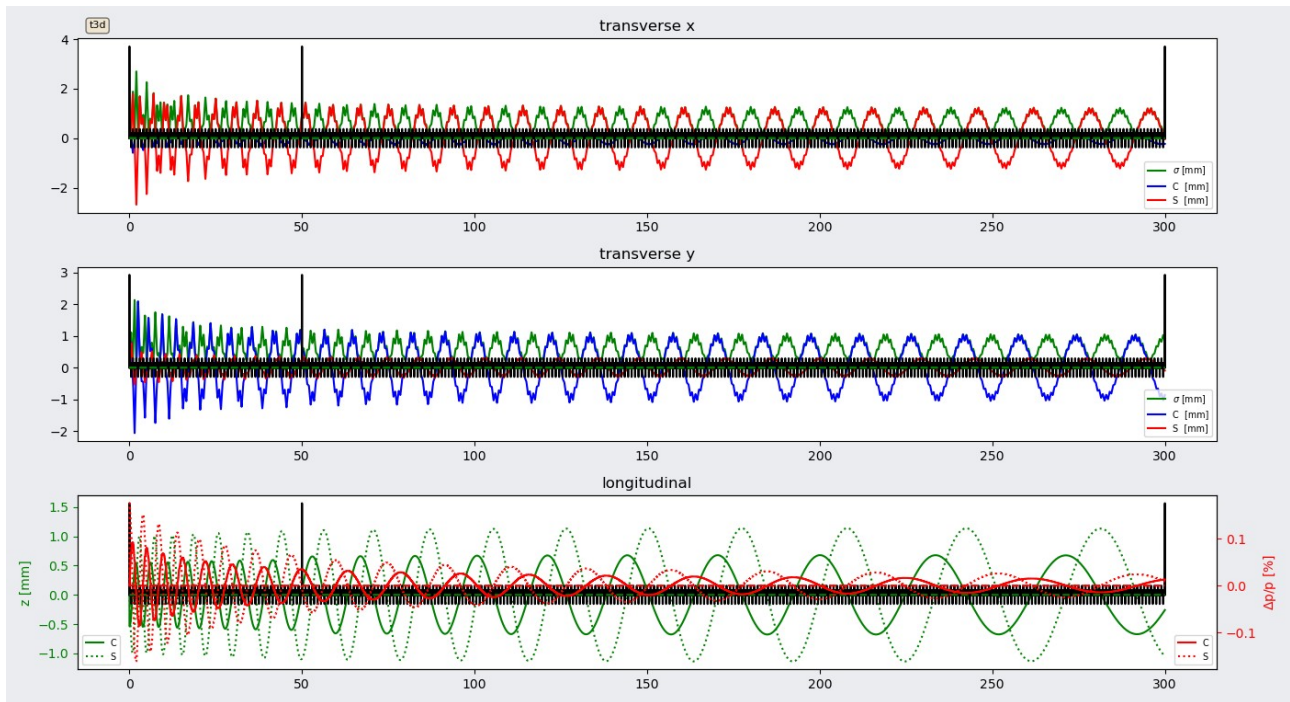
Cavity-Model with mapping **base**.

Mapping base is a non-linear model. It uses mappings defined in the [article](#) by A.Shishlo and Jeff Holmes section 4.2 Base RF Gap Model. It does need a table (from SuperFish) for the field distribution E_{0z} on axis. The cavities are modeled as DKD triplets. Comparing the results from this model with those from t3d allows to estimate the contributions of non-linearities arising from this more realistic approach. This simulation is the fastest non-linear simulation.

Cavity-Model with mapping **tff**.

Mapping tff is a non-linear model. It uses mappings defined in the [article](#) by A.Shishlo and Jeff Holmes section 4.4 Three Point TFF Model. It does need a table (from SuperFish) for the field distribution E_{0z} on axis. The cavities are modeled as DKD triplets. This model is the most realistic one of all but very compute intensive and thus the slowest one.

Results for t3d



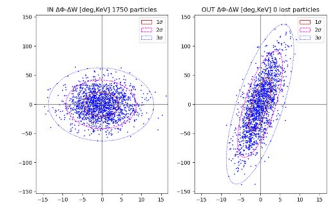
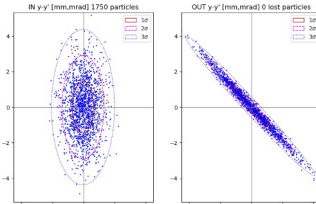
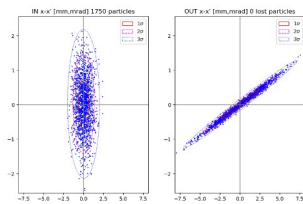
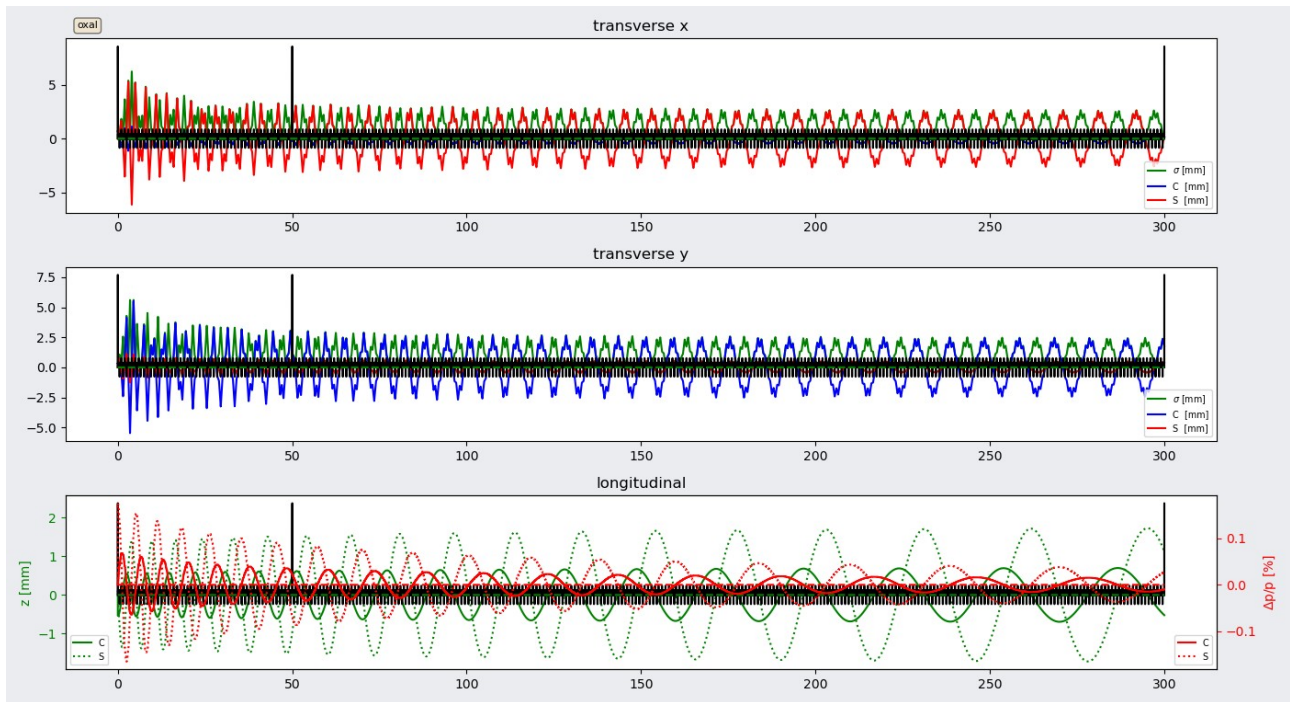
'(W-IN,W-OUT)=(6.0, 192.46754897632235)'

'3-sigma longitudinal RMS-emittances $\Delta\phi-\Delta W$ [deg,KeV]: IN=7.90e+02 OUT=7.90e+02'

"3-sigma transverse RMS-emittances x-x' [mm,mrad]: IN=4.29e+00 OUT=7.30e-01"

"3-sigma transverse RMS-emittances y-y' [mm,mrad]: IN=4.35e+00 OUT=7.41e-01"

Results for **oxal**



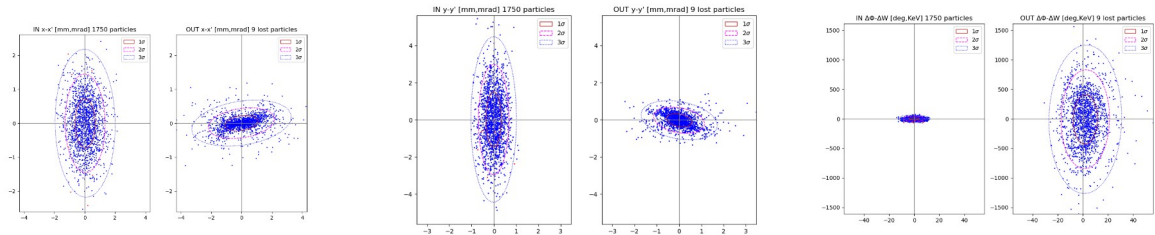
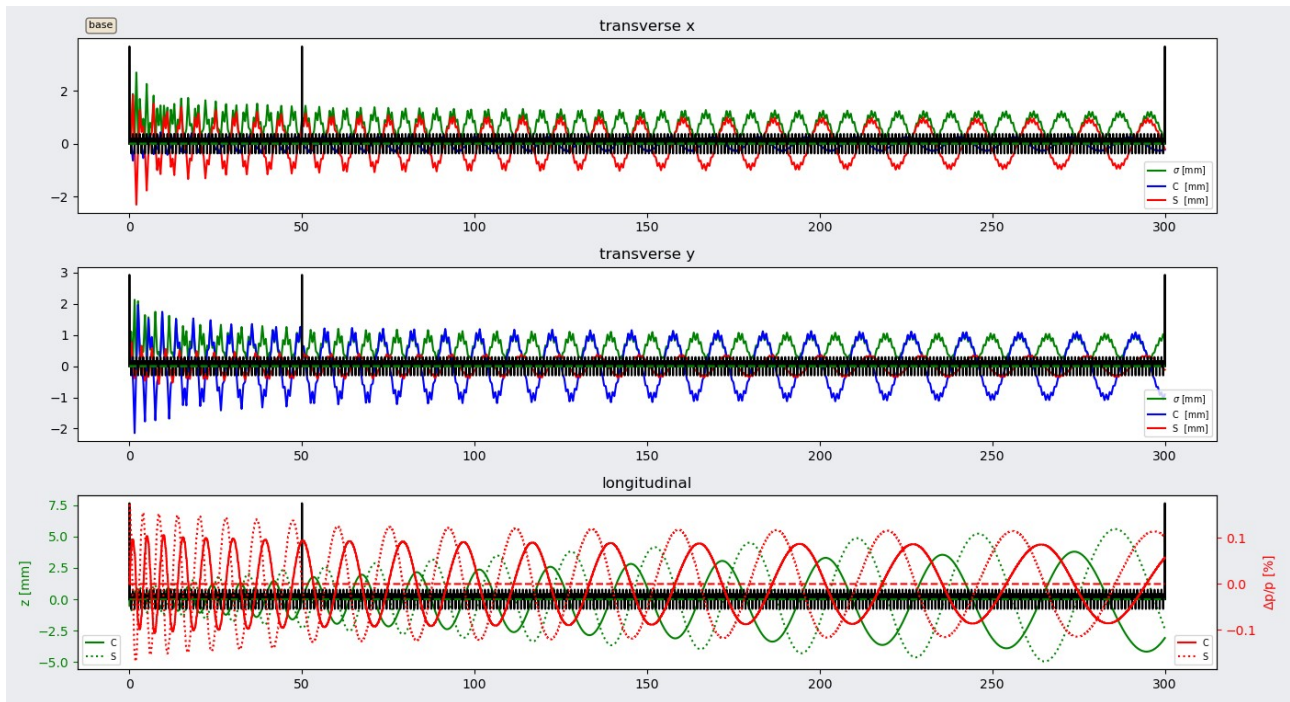
```
'(W-IN,W-OUT)=(6.0, 80.64132828981144)'
```

```
'3-sigma longitudinal RMS-emittances  $\Delta\phi-\Delta W$  [deg,KeV]: IN=8.33e+02 OUT=8.33e+02'
```

```
"3-sigma transverse RMS-emittances x-x' [mm,mrad]: IN=4.53e+00 OUT=1.23e+00"
```

```
"3-sigma transverse RMS-emittances y-y' [mm,mrad]: IN=4.52e+00 OUT=1.23e+00"
```

Results for **base**



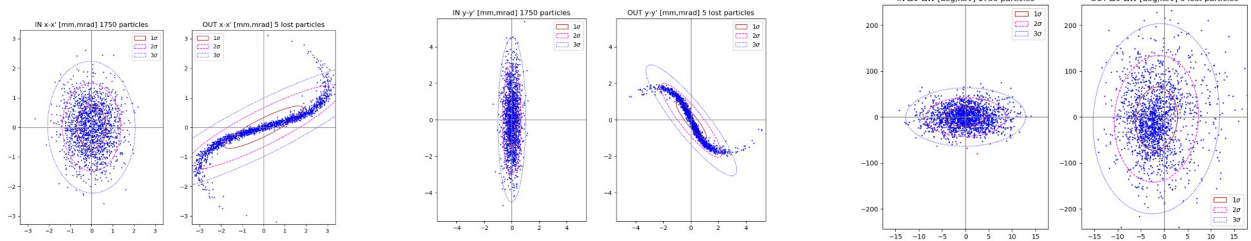
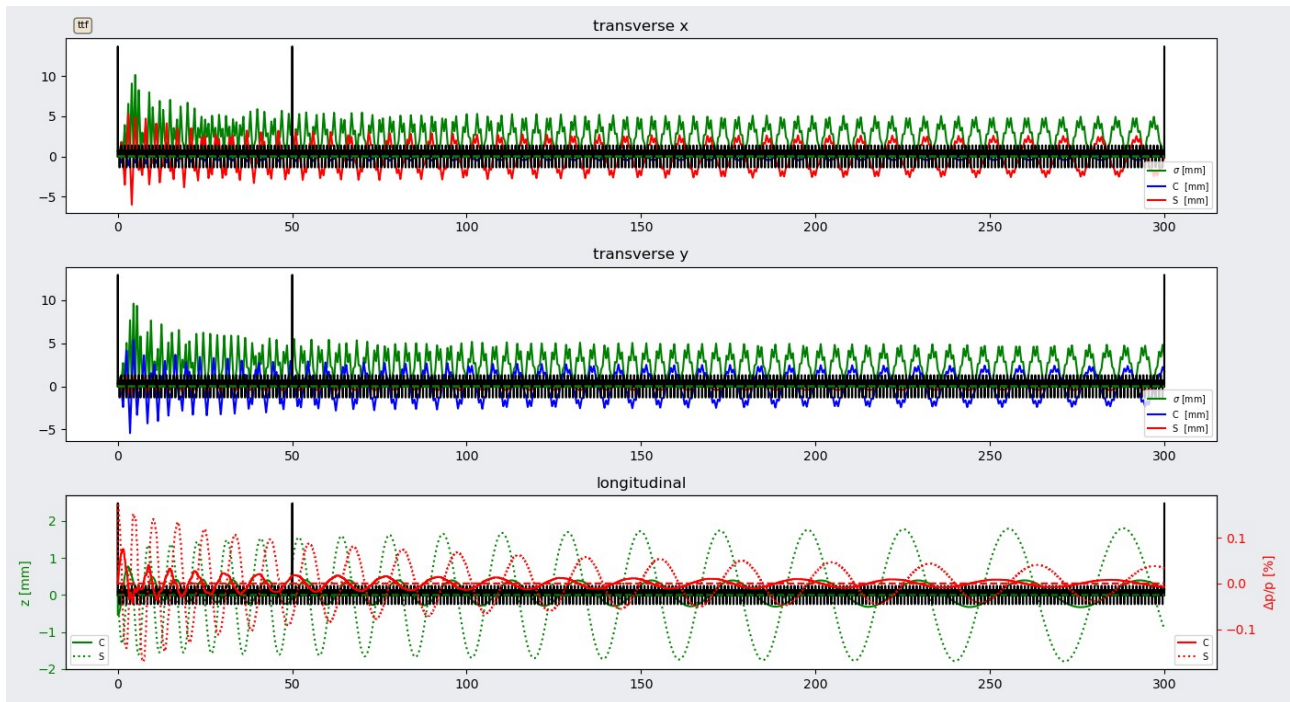
```
'(W-IN,W-OUT)=(6.0, 192.46754897632235)'
```

```
'3-sigma longitudinal RMS-emittances  $\Delta\theta-\Delta W$  [deg,KeV]: IN=8.12e+02 OUT=3.52e+04'
```

```
"3-sigma transverse RMS-emittances  $x-x'$  [mm,mrad]: IN=4.45e+00 OUT=2.20e+00"
```

```
"3-sigma transverse RMS-emittances  $y-y'$  [mm,mrad]: IN=4.58e+00 OUT=1.77e+00"
```


Results for ttf



```
'(W-IN,W-OUT)=(6.0, 80.64132461246324)'
```

```
'3-sigma longitudinal RMS-emittances  $\Delta\Phi$ - $\Delta W$  [deg,KeV]: IN=8.00e+02 OUT=2.76e+03'
```

```
"3-sigma transverse RMS-emittances x-x' [mm,mrad]: IN=4.29e+00 OUT=4.93e+00"
```

```
"3-sigma transverse RMS-emittances y-y' [mm,mrad]: IN=4.47e+00 OUT=4.40e+00"
```

Discussion

For linear mappings the longitudinal rms-emittances stay constant and the transverse rms-emittances get smaller by a factor ~ 5.9 for **t3d** and ~ 3.7 for **oxal**.

For non-linear mappings the longitudinal rms-emittances increase by about a factor ~ 43 (strange?) for **base** and 3.4 for **tff**. The horizontal scatterplots show filamentation for non-linear mappings. Not very much for **base** but very strong for **tff**.

For the base mapping for instance the longitudinal kick ΔW in kinetic energy and the transverse angles x' and y' have a radial dependency as can be seen by the formulae from Shishlo's article :

$$W_{out} - W_{in} = q \cdot E_0 TL \cdot I_0 \left(\frac{\omega}{c(\gamma\beta)_{in}} r \right) \cdot \cos(\varphi_{in}) \quad (4.2.3)$$

$$\varphi_{out} = \varphi_{in} \quad (4.2.4)$$

$$\tilde{z}^{(out)} = \frac{\beta_s^{(out)}}{\beta_s^{(in)}} \tilde{z}^{(in)} \quad (4.2.5)$$

$$\begin{aligned} x'_{out} &= \frac{(\gamma\beta)_{in}}{(\gamma\beta)_{out}} \cdot x'_{in} - \frac{1}{(\gamma\beta)_{out}} \cdot \frac{x}{r} \cdot \frac{q \cdot E_0 TL}{mc^2 (\beta\gamma)_{in}} \cdot I_1 \left(\frac{\omega}{c \cdot (\gamma\beta)_{in}} \cdot r \right) \cdot \sin(\varphi_{in}) \\ y'_{out} &= \frac{(\gamma\beta)_{in}}{(\gamma\beta)_{out}} \cdot y'_{in} - \frac{1}{(\gamma\beta)_{out}} \cdot \frac{y}{r} \cdot \frac{q \cdot E_0 TL}{mc^2 (\beta\gamma)_{in}} \cdot I_1 \left(\frac{\omega}{c \cdot (\gamma\beta)_{in}} \cdot r \right) \cdot \sin(\varphi_{in}) \end{aligned} \quad (4.2.6)$$