Semantyka i weryfikacja programów

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Program Semantics & Verification

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This course:

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Blocks & declarations

Let's look at declarations of local variables:

$$S \in \mathbf{Stmt} ::= \dots \mid \mathbf{begin} \ D_V \ S \ \mathbf{end}$$

$$D_V \in \mathbf{VDecl} ::= \mathbf{var} \ x; D_V \mid \varepsilon$$

Locations

We have identified two roles of variables:

- identifiers, as used in programs
- names for memory cells, where values are stored

To separate them, the structure of the semantic domains has to be changed.

Splitting states into environments and stores

$$\mathbf{Int} = \{0, 1, -1, 2, -2, \ldots\}_{\perp}$$

$$\mathbf{Bool} = \{\mathbf{tt}, \mathbf{ff}\}_{\perp}$$

$$\mathbf{VEnv} = \mathbf{Var} \to (\mathbf{Loc} + \{??\})$$

$$\mathbf{Store} = \mathbf{Loc} \to (\mathbf{Int} + \{??\})$$

 $combine : \mathbf{VEnv} \times \mathbf{Store} \to \mathbf{State}$

 $combine(\rho_V, s) = \lambda x : \mathbf{Var}.s(\rho_V(x))$

Inaccurate, but right...

Semantic functions

$$\mathcal{N} \colon \mathbf{Num} \to \mathbf{Int}$$

$$\mathcal{E} \colon \mathbf{Exp} \to \mathbf{VEnv} \to \mathbf{Store} \to (\mathbf{Int} + \{??\})$$

$$\mathbf{EXP}$$

$$\mathcal{B} \colon \mathbf{BExp} \to \mathbf{VEnv} \to \mathbf{Store} \to (\mathbf{Bool} + \{??\})$$

$$\mathbf{BEXP}$$

and then for instance

$$\mathcal{E}[\![x]\!] = \lambda \rho_V : \mathbf{VEnv}.\lambda s : \mathbf{Store}.ifte(\rho_V \ x = ??, ??, ifte(s \ (\rho_V \ x) = ??, ??, s \ (\rho_V \ x)))$$

$$\mathcal{E}[\![e_1 + e_2]\!] = \lambda \rho_V : \mathbf{VEnv}.\lambda s : \mathbf{Store}.ifte(\mathcal{E}[\![e_1]\!]) \rho_V \ s = ??, ??,$$

Looks horrible! Reads even worse!

$$ifte(\mathcal{E}\llbracket e_2 \rrbracket \ \rho_V \ s = ??, ??,$$

$$\mathcal{E}\llbracket e_1 \rrbracket \ \rho_V \ s + \mathcal{E}\llbracket e_2 \rrbracket \ \rho_V \ s))$$

Bits of notation

- (re)move lambda-abstraction
- use where-notation, let-notation, explicit if-then-notation, etc
- assume that errors ?? propagate

Then:

$$\begin{split} \mathcal{E}[\![x]\!] & \rho_V \ s = s \ l \ \text{ where } l = \rho_V \ x \\ \mathcal{E}[\![e_1 + e_2]\!] & \rho_V \ s = n_1 + n_2 \ \text{ where } n_1 = \mathcal{E}[\![e_1]\!] \ \rho_V \ s, n_2 = \mathcal{E}[\![e_2]\!] \ \rho_V \ s \end{split}$$

Relate this to the previous semantics using combine

Write down all the other rules for \mathcal{E} and \mathcal{B} . Spell out their exact meaning expanding all the notations in use.

Statements

One could work with "big states"

$$S: \mathbf{Stmt} \to \underbrace{\mathbf{VEnv} \times \mathbf{Store} \to (\mathbf{VEnv} \times \mathbf{Store} + \{??\})}_{\mathbf{STMT}}$$

BUT:

Statements do not modify the environment!

Hence:

$$\mathcal{S} \colon \mathbf{Stmt} \to \underbrace{\mathbf{VEnv} \to \mathbf{Store} \to (\mathbf{Store} + \{??\})}_{\mathbf{STMT}}$$

Semantic clauses

```
\begin{split} \mathcal{S}\llbracket x := e \rrbracket \; \rho_V \; s &= s[l \mapsto n] \; \text{where} \; l = \rho_V \; x, n = \mathcal{E}\llbracket e \rrbracket \; \rho_V \; s \\ \mathcal{S}\llbracket \text{skip} \rrbracket \; \rho_V \; s &= s \\ \mathcal{S}\llbracket S_1; S_2 \rrbracket \; \rho_V \; s &= \mathcal{S}\llbracket S_2 \rrbracket \; \rho_V \; s_1 \; \text{where} \; s_1 = \mathcal{S}\llbracket S_1 \rrbracket \; \rho_V \; s \\ \mathcal{S}\llbracket \text{if} \; b \; \text{then} \; S_1 \; \text{else} \; S_2 \rrbracket \; \rho_V \; s &= \text{let} \; v = \mathcal{B}\llbracket b \rrbracket \; \rho_V \; s \; \text{in} \\ & \text{if} \; v = \text{tt} \; \text{then} \; \mathcal{S}\llbracket S_1 \rrbracket \; \rho_V \; s \\ \mathcal{S}\llbracket \text{while} \; b \; \text{do} \; S \rrbracket \; \rho_V \; s &= \text{let} \; v = \mathcal{B}\llbracket b \rrbracket \; \rho_V \; s \; \text{in} \\ & \text{if} \; v = \text{ff} \; \text{then} \; s \\ & \text{if} \; v = \text{tt} \; \text{then} \; s \\ & \text{if} \; v = \text{tt} \; \text{then} \; \mathcal{S}\llbracket \text{while} \; b \; \text{do} \; S \rrbracket \; \rho_V \; s' \\ & \text{where} \; s' = \mathcal{S}\llbracket S \rrbracket \; \rho_V \; s \end{split}
```

More compact version

Relying on propagation of errors ?? to be also built into composition of functions from Store to Store $+ \{??\}$:

$$\begin{split} \mathcal{S}[\![x := \! e]\!] & \rho_V \, s = s[l \mapsto n] \text{ where } l = \rho_V \, x, n = \mathcal{E}[\![e]\!] \, \rho_V \, s \\ \mathcal{S}[\![s \text{kip}]\!] & \rho_V = i d_{\textbf{Store}} \\ \mathcal{S}[\![S_1; S_2]\!] & \rho_V = \mathcal{S}[\![S_1]\!] \, \rho_V; \mathcal{S}[\![S_2]\!] \, \rho_V \\ \mathcal{S}[\![if \ b \ \textbf{then} \ S_1 \ \textbf{else} \ S_2]\!] & \rho_V = cond(\mathcal{B}[\![b]\!] \, \rho_V, \mathcal{S}[\![S_1]\!] \, \rho_V, \mathcal{S}[\![S_2]\!] \, \rho_V) \\ \mathcal{S}[\![\textbf{while} \ b \ \textbf{do} \ S]\!] & \rho_V = cond(\mathcal{B}[\![b]\!] \, \rho_V, \mathcal{S}[\![S]\!] \, \rho_V; \mathcal{S}[\![\textbf{while} \ b \ \textbf{do} \ S]\!] \, \rho_V, i d_{\textbf{Store}}) \end{split}$$

The missing clause for blocks in a moment

Declarations modify environments

$$\mathcal{D}_V \colon \mathbf{VDecl} o \underbrace{\mathbf{VEnv} o \mathbf{Store} o (\mathbf{VEnv} imes \mathbf{Store} + \{??\})}_{\mathbf{VDECL}}$$

$$\begin{split} \mathcal{D}_V \llbracket \varepsilon \rrbracket \; \rho_V \; s &= \langle \rho_V, s \rangle \\ \mathcal{D}_V \llbracket \mathbf{var} \; x; D_V \rrbracket \; \rho_V \; s &= \mathcal{D}_V \llbracket D_V \rrbracket \; \rho_V' \; s' \\ \text{where} \; l &= newloc(s), \rho_V' = \rho_V [x \mapsto l], s' = s[l \mapsto ??] \end{split}$$

Trouble: We want newloc: **Store** \rightarrow **Loc** to yield a new, unused location. This cannot be defined under the definitions given so far. Solution: more information in stores is needed to determine used and unused locations.

Simple solution

Take:

$$Loc = \{0, 1, 2, \ldots\}$$

Add to each store a pointer to the next unused location:

$$\mathbf{Store} = (\mathbf{Loc} + \{next\}) \rightarrow (\mathbf{Int} + \{??\})$$

Semantic clauses then:

$$\mathcal{D}_{V}\llbracket \varepsilon \rrbracket \; \rho_{V} \; s = \langle \rho_{V}, s \rangle$$

$$\mathcal{D}_{V}\llbracket \mathbf{var} \; x; D_{V} \rrbracket \; \rho_{V} \; s =$$

$$\mathcal{D}_{V}\llbracket D_{V} \rrbracket \; \rho'_{V} \; s' \; \text{ where } l = s \; next, \rho'_{V} = \rho_{V}[x \mapsto l], s' = s[l \mapsto ??, next \mapsto l+1]$$

Semantics of blocks

The scope of a declaration is the block it occurs in with holes resulting from redeclarations of the same variable within it

For instance

begin var y; var x x := 1; begin var x y := 2; x := 5 end; y := x end may be marked as follows to indicate the relevant declarations:

$$\mathbf{begin} \ \boxed{\mathbf{var} \ y}; \boxed{\mathbf{var} \ x} \ \boxed{x} := 1; \mathbf{begin} \ \boxed{\mathbf{var} \ x} \ \boxed{y} := 2; \boxed{x} := 5 \ \mathbf{end}; \boxed{y} := \boxed{x} \ \mathbf{end}$$

Procedures

$$TINY^{++}$$

```
S \in \mathbf{Stmt} ::= \dots \mid \mathbf{begin} \ D_V \ D_P \ S \ \mathbf{end} \mid \mathbf{call} \ p
D_V \in \mathbf{VDecl} ::= \mathbf{var} \ x; D_V \mid \varepsilon
D_P \in \mathbf{PDecl} ::= \mathbf{proc} \ p \ \mathbf{is} \ (S); D_P \mid \varepsilon
```

- binding of global variables
- recursion

Binding of global variables

Static binding

```
begin var y;
   var x;
   proc p is (x := 1);
   begin var x;
   x := 3;
   call p;
   y := x
   end
end
```

Dynamic binding

```
begin var y;
   var x;
   proc p is (x := 1);
   begin var x;
   x := 3;
   call p; %%% with x
   y := x
   end
end
```

Semantic domains and functions

Dynamic binding

$$\begin{aligned} \mathbf{PEnv} &= \mathbf{IDE} \rightarrow (\mathbf{PROC}_0 + \{??\}) \\ \mathbf{PROC}_0 &= \mathbf{VEnv} \rightarrow \mathbf{PEnv} \rightarrow \mathbf{Store} \rightarrow (\mathbf{Store} + \{??\}) \end{aligned}$$

$$\mathcal{S} \colon \mathbf{Stmt} o \mathbf{VEnv} o \mathbf{PEnv} o \mathbf{Store} o (\mathbf{Store} + \{??\})$$

$$\mathcal{D}_P \colon \mathbf{PDecl} o \mathbf{PEnv} o (\mathbf{PEnv} + \{??\})$$
PDECL

Semantic clauses

```
\mathcal{S}[x := e] \rho_V \rho_P s = s[l \mapsto n] where l = \rho_V x, n = \mathcal{E}[e] \rho_V s
S[\mathbf{skip}] \rho_V \rho_P = id_{\mathbf{Store}}
\mathcal{S}[S_1; S_2] \rho_V \rho_P = \mathcal{S}[S_1] \rho_V \rho_P; \mathcal{S}[S_2] \rho_V \rho_P
\mathcal{S}[[b]]  then S_1 else S_2[[\rho_V \rho_P] = cond(\mathcal{B}[[b]][\rho_V, \mathcal{S}[[S_1]][\rho_V \rho_P, \mathcal{S}[[S_2]][\rho_V \rho_P)])
S while b do S \rho_V
         cond(\mathcal{B}[\![b]\!] \rho_V, \mathcal{S}[\![S]\!] \rho_V \rho_P; \mathcal{S}[\![\mathbf{while}\ b\ \mathbf{do}\ S]\!] \rho_V \rho_P, id_{\mathbf{Store}})
 \mathcal{S}[[call \ p]] \rho_V \rho_P = P \rho_V \rho_P \text{ where } P = \rho_P p
S[begin D_V D_P S end] \rho_V \rho_P s =
         \mathcal{S}[S][\rho'_V \rho'_P s'] where \langle \rho'_V, s' \rangle = \mathcal{D}_V[D_V][\rho_V s, \rho'_P = \mathcal{D}_P[D_P][\rho_P]]
\mathcal{D}_P[\![\varepsilon]\!] = id_{\mathbf{PEnv}}
 \mathcal{D}_P[\mathbf{proc}\ p\ \mathbf{is}\ (S); D_P] \rho_P = \mathcal{D}_P[D_P] \rho_P[p \mapsto \mathcal{S}[S]]
```

Recursion

Semantic domains and functions

Static binding

$$\mathbf{PEnv} = \mathbf{IDE} \rightarrow (\mathbf{PROC}_0 + \{??\})$$
$$\mathbf{PROC}_0 = \mathbf{Store} \rightarrow (\mathbf{Store} + \{??\})$$

$$\mathcal{S} \colon \mathbf{Stmt} o \mathbf{VEnv} o \mathbf{PEnv} o \mathbf{Store} o (\mathbf{Store} + \{??\})$$

$$\mathcal{D}_P \colon \mathbf{PDecl} o \mathbf{VEnv} o \mathbf{PEnv} o (\mathbf{PEnv} + \{??\})$$
PDECL

Semantic clauses

```
\mathcal{S}[x := e] \rho_V \rho_P s = s[l \mapsto n] where l = \rho_V x, n = \mathcal{E}[e] \rho_V s
S[\mathbf{skip}] \rho_V \rho_P = id_{Store}
\mathcal{S}[S_1; S_2] \rho_V \rho_P = \mathcal{S}[S_1] \rho_V \rho_P; \mathcal{S}[S_2] \rho_V \rho_P
\mathcal{S}[[b]]  then S_1 else S_2[[\rho_V \rho_P] = cond(\mathcal{B}[[b]][\rho_V, \mathcal{S}[[S_1]][\rho_V \rho_P, \mathcal{S}[[S_2]][\rho_V \rho_P)])
S while b do S \rho_V \rho_P =
          cond(\mathcal{B}[\![b]\!] \rho_V, \mathcal{S}[\![S]\!] \rho_V \rho_P; \mathcal{S}[\![\mathbf{while}\ b\ \mathbf{do}\ S]\!] \rho_V \rho_P, id_{\mathbf{Store}})
 \mathcal{S}[[call \ p]] \rho_V \rho_P = P \text{ where } P = \rho_P p
S[begin D_V D_P S end] \rho_V \rho_P s =
          \mathcal{S}\llbracket S 
Vert 
ho_V' 
ho_P' s' where \langle 
ho_V', s' 
angle = \mathcal{D}_V \llbracket D_V 
Vert 
ho_V s, \ 
ho_P' = \mathcal{D}_P \llbracket D_P 
Vert 
ho_V' 
ho_P
\mathcal{D}_P \llbracket \varepsilon \rrbracket \; \rho_V = id_{\mathbf{PEnv}}
 \mathcal{D}_P \llbracket \mathbf{proc} \ p \ \mathbf{is} \ (S); D_P \rrbracket \ \rho_V \ \rho_P =
            \mathcal{D}_P \llbracket D_P \rrbracket \rho_V \rho_P [p \mapsto P] where P = \mathcal{S} \llbracket S \rrbracket \rho_V \rho_P [p \mapsto P]
```