

Semantyka i weryfikacja programów

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Program Semantics & Verification

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This course:

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Direct semantics

begin ... ; ... ; ... **end**

$s^\emptyset \xrightarrow{\mathcal{S}[\dots]} s_i \xrightarrow{\mathcal{S}[\dots]} s_j \xrightarrow{\mathcal{S}[\dots]} s' \rightsquigarrow \text{"overall result"}$

Continuation semantics

begin ... ; ... ; ... **end**

$\kappa' : \rightsquigarrow \text{"overall result"}$

$\xleftarrow{\mathcal{S}[\dots]} \kappa_i : \rightsquigarrow \text{"overall result"}$

$\xleftarrow{\mathcal{S}[\dots]} \kappa_j : \rightsquigarrow \text{"overall result"}$

$\xleftarrow{\mathcal{S}[\dots]} \kappa^\emptyset : \rightsquigarrow \text{"overall result"}$

Continuations

$$\text{Cont} = \text{State} \rightarrow \text{Ans}$$

Now:

- states do not include outputs
- answers are outputs (or errors)
- these are continuations for statements; semantics for statements is given by:

$$\begin{aligned}\text{State} &= \text{Store} \times \text{Input} \\ \text{Ans} &= \text{Output}\end{aligned}$$

$$\mathcal{S}: \text{Stmt} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont} \rightarrow \text{Cont}}_{\text{STMT}}$$

That is:

$$\text{STMT} = \text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont} \rightarrow \text{State} \rightarrow \text{Ans}$$

Expression and declaration continuations

- continuations for other syntactic categories should be additionally parameterised by whatever these pass on:
 - expressions pass on values, so

$$\begin{aligned}\text{Cont}_E &= \text{Int} \rightarrow \text{State} \rightarrow \text{Ans} \\ \text{Cont}_B &= \text{Bool} \rightarrow \text{State} \rightarrow \text{Ans}\end{aligned}$$

- declarations pass on environments, so

$$\begin{aligned}\text{Cont}_{D_V} &= \text{VEnv} \rightarrow \text{State} \rightarrow \text{Ans} \\ \text{Cont}_{D_P} &= \text{PEnv} \rightarrow \text{State} \rightarrow \text{Ans}\end{aligned}$$

$$N \in \mathbf{Num} ::= 0 \mid 1 \mid 2 \mid \dots$$

$$x \in \mathbf{Var} ::= \dots$$

$$p \in \mathbf{IDE} ::= \dots$$

$$e \in \mathbf{Exp} ::= N \mid x \mid e_1 + e_2 \mid e_1 * e_2 \mid e_1 - e_2$$

$$b \in \mathbf{BExp} ::= \mathbf{true} \mid \mathbf{false} \mid e_1 \leq e_2 \mid \neg b' \mid b_1 \wedge b_2$$

$$\begin{aligned} S \in \mathbf{Stmt} ::= & x := e \mid \mathbf{skip} \mid S_1; S_2 \mid \mathbf{if} \ b \ \mathbf{then} \ S_1 \ \mathbf{else} \ S_2 \mid \mathbf{while} \ b \ \mathbf{do} \ S' \\ & \mid \mathbf{begin} \ D_V \ D_P \ S \ \mathbf{end} \mid \mathbf{call} \ p \mid \mathbf{call} \ p(\mathbf{vr} \ x) \\ & \mid \mathbf{read} \ x \mid \mathbf{write} \ e \end{aligned}$$

$$D_V \in \mathbf{VDecl} ::= \mathbf{var} \ x; D_V \mid \varepsilon$$

$$D_P \in \mathbf{PDecl} ::= \mathbf{proc} \ p \ \mathbf{is} \ (S); D_P \mid \mathbf{proc} \ p(\mathbf{vr} \ x) \ \mathbf{is} \ (S); D_P \mid \varepsilon$$

$$\mathbf{Prog} ::= \mathbf{prog} \ S$$

Semantic domains

$\text{Int} = \dots$
 $\text{Bool} = \dots$
 $\text{Loc} = \dots$
 $\text{Store} = \dots$
 $\text{VEnv} = \dots$

$\text{Input} = \text{Int} \times \text{Input} + \{\text{eof}\}$
 $\text{State} = \text{Store} \times \text{Input}$
 $\text{Output} = \text{Int} \times \text{Output} + \{\text{eof}, ??\}$

$\text{PROC}_0 = \text{Cont} \rightarrow \text{Cont}$
 $\text{PROC}_1^{\text{vr}} = \text{Loc} \rightarrow \text{PROC}_0$
 $\text{PEnv} =$
 $\text{IDE} \rightarrow (\text{PROC}_0 + \text{PROC}_1^{\text{vr}} + \{??\})$

$\text{Cont} = \text{State} \rightarrow \text{Output}$
 $\text{Cont}_E = \text{Int} \rightarrow \text{Cont}$
 $\text{Cont}_B = \text{Bool} \rightarrow \text{Cont}$
 $\text{Cont}_{D_V} = \text{VEnv} \rightarrow \text{Cont}$
 $\text{Cont}_{D_P} = \text{PEnv} \rightarrow \text{Cont}$

Semantic functions

$$\mathcal{E}: \text{Exp} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_E \rightarrow \text{Cont}}_{\text{EXP}}$$

$$\mathcal{B}: \text{BExp} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_B \rightarrow \text{Cont}}_{\text{BEXP}}$$

$$\mathcal{S}: \text{Stmt} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont} \rightarrow \text{Cont}}_{\text{STMT}}$$

$$\mathcal{D}_V: \text{VDecl} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_{D_V} \rightarrow \text{Cont}}_{\text{VDECL}}$$

$$\mathcal{D}_P: \text{PDecl} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont}_{D_P} \rightarrow \text{Cont}}_{\text{PDECL}}$$

$$\mathcal{P}: \text{Prog} \rightarrow \underbrace{\text{Input} \rightarrow \text{Output}}_{\text{PROG}}$$

Sample semantic clauses

Programs:

$$\mathcal{P}[\text{prog } S] i = \mathcal{S}[S] \rho_V^\emptyset \rho_P^\emptyset \kappa^\emptyset \langle s^\emptyset, i \rangle$$

where $\rho_V^\emptyset x = ??, \rho_P^\emptyset p = ??, \kappa^\emptyset s = \text{eof}, s^\emptyset \text{ next} = 0, s^\emptyset l = ??$

Declarations:

$$\begin{aligned} \mathcal{D}_P[\varepsilon] \rho_V \rho_P \kappa_P &= \kappa_P \rho_P \\ \mathcal{D}_P[\text{proc } p \text{ is } (S); D_P] \rho_V \rho_P &= \\ &\mathcal{D}_P[D_P] \rho_V \rho_P[p \mapsto P] \text{ where } P = \mathcal{S}[S] \rho_V \rho_P[p \mapsto P] \\ \mathcal{D}_V[\text{var } x; D_V] \rho_V \kappa_V \langle s, i \rangle &= \\ &\mathcal{D}_V[D_V] \rho'_V \kappa_V \langle s', i \rangle \text{ where } l = s \text{ next}, \rho'_V = \rho_V[x \mapsto l], \\ &s' = s[l \mapsto ??, \text{next} \mapsto l + 1] \end{aligned}$$

Continuations not really used here, just passed around

Sample semantic clauses

Expressions:

$$\mathcal{E}[[x]] \rho_V \kappa_E = \lambda \langle s, i \rangle : \mathbf{State}. \kappa_E n \langle s, i \rangle \text{ where } l = \rho_V x, n = s l$$

this means: ?? if $\rho_V x = ??$ or $s l = ??$

$$\mathcal{E}[[e_1 + e_2]] \rho_V \kappa_E =$$

$$\mathcal{E}[[e_1]] \rho_V \lambda n_1 : \mathbf{Int}. \mathcal{E}[[e_2]] \rho_V \lambda n_2 : \mathbf{Int}. \kappa_E (n_1 + n_2)$$

check the types!

Boolean expressions:

$$\mathcal{B}[[\mathbf{true}]] \rho_V \kappa_B = \kappa_B \mathbf{tt}$$

$$\mathcal{B}[[e_1 \leq e_2]] \rho_V \kappa_B =$$

$$\mathcal{E}[[e_1]] \rho_V \lambda n_1 : \mathbf{Int}. \mathcal{E}[[e_2]] \rho_V \lambda n_2 : \mathbf{Int}.$$

$$\kappa_B \text{ ifte}(n_1 \leq n_2, \mathbf{tt}, \mathbf{ff})$$

Back to declarations

Recall:

$$\begin{aligned} \mathcal{D}_V[\mathbf{var} \ x; D_V] \rho_V \kappa_V \langle s, i \rangle = \\ \mathcal{D}_V[D_V] \rho'_V \kappa_V \langle s', i \rangle \text{ where } l = s \text{ next}, \rho'_V = \rho_V[x \mapsto l], \\ s' = s[l \mapsto ??, \text{next} \mapsto l + 1] \end{aligned}$$

What would happen if variable declarations included initializing expressions?

$$\begin{aligned} \mathcal{D}_V[\mathbf{var} \ x = e; D_V] \rho_V \kappa_V \langle s, i \rangle = \\ \mathcal{E}[e] \rho_V (\lambda n:\mathbf{Int}. \mathcal{D}_V[D_V] \rho'_V \kappa_V \langle s', i \rangle) \text{ where } l = s \text{ next}, \rho'_V = \rho_V[x \mapsto l], \\ s' = s[l \mapsto n, \text{next} \mapsto l + 1] \end{aligned}$$

Statements

$$\mathcal{S}[\mathbf{x} := e] \rho_V \rho_P \kappa = \mathcal{E}[e] \rho_V (\lambda n:\mathbf{Int}.\lambda \langle s, i \rangle:\mathbf{State}.\kappa \langle s[l \mapsto n], i \rangle) \\ \text{where } l = \rho_V x$$

$$\mathcal{S}[\mathbf{skip}] \rho_V \rho_P = id_{\mathbf{Cont}}$$

$$\mathcal{S}[S_1; S_2] \rho_V \rho_P \kappa = \mathcal{S}[S_1] \rho_V \rho_P (\mathcal{S}[S_2] \rho_V \rho_P \kappa)$$

$$\mathcal{S}[\mathbf{if } b \mathbf{ then } S_1 \mathbf{ else } S_2] \rho_V \rho_P \kappa = \\ \mathcal{B}[b] \rho_V \lambda v:\mathbf{Bool}.\text{ifte}(v, \mathcal{S}[S_1] \rho_V \rho_P \kappa, \mathcal{S}[S_2] \rho_V \rho_P \kappa)$$

$$\mathcal{S}[\mathbf{while } b \mathbf{ do } S] \rho_V \rho_P \kappa = \\ \mathcal{B}[b] \rho_V \lambda v:\mathbf{Bool}.\text{ifte}(v, \mathcal{S}[S] \rho_V \rho_P (\mathcal{S}[\mathbf{while } b \mathbf{ do } S] \rho_V \rho_P \kappa), \kappa)$$

$$\mathcal{S}[\mathbf{call } p] \rho_V \rho_P = P \text{ where } P = \rho_P p$$

$$\mathcal{S}[\mathbf{call } p(\mathbf{vr } x)] \rho_V \rho_P = P l \text{ where } P = \rho_P p \in \mathbf{PROC}_1^{\text{vr}}, l = \rho_V x$$

$$\mathcal{S}[\mathbf{read } x] \rho_V \rho_P \kappa \langle s, i \rangle = \kappa \langle s[l \mapsto n], i' \rangle \text{ where } l = \rho_V x, \langle n, i' \rangle = i$$

$$\mathcal{S}[\mathbf{write } e] \rho_V \rho_P \kappa = \mathcal{E}[e] \rho_V \lambda n:\mathbf{Int}.\lambda \langle s, i \rangle:\mathbf{State}.\langle n, \kappa \langle s, i \rangle \rangle$$

Blocks

$$\mathcal{S}[\text{begin } D_V \ D_P \ S \ \text{end}] \ \rho_V \ \rho_P \ \kappa = \\ \mathcal{D}_V[D_V] \ \rho_V \ \lambda \rho'_V : \mathbf{VEnv} . \mathcal{D}_P[D_P] \ \rho'_V \ \rho_P \ \lambda \rho'_P : \mathbf{PEnv} . \mathcal{S}[S] \ \rho'_V \ \rho'_P \ \kappa$$

This got separated, because we will want to add jumps. . .

Abrupt termination

Let us forget input/output for now, fall back to the language TINY^{++} with (parameterless) procedures.

Extend it with:

$$S \in \mathbf{Stmt} ::= \dots \mid \mathbf{abort}$$

*The killer application of continuations is non-local control flow.
This is the simplest example.*

Semantic domains

$$\mathbf{Ans} = \mathbf{Store}$$

$$\mathbf{Cont} = \mathbf{Store} \rightarrow \mathbf{Ans}$$

$$\mathbf{Cont}_E = \mathbf{Int} \rightarrow \mathbf{Ans}$$

$$\mathbf{Cont}_B = \mathbf{Bool} \rightarrow \mathbf{Ans}$$

$$\mathbf{Cont}_{D_V} = \mathbf{VEnv} \rightarrow \mathbf{Cont}$$

$$\mathbf{Cont}_{D_P} = \mathbf{PEnv} \rightarrow \mathbf{Ans}$$

$$\mathbf{PROC} = \mathbf{Cont} \rightarrow \mathbf{Cont}$$

$$\mathbf{PEnv} = \mathbf{IDE} \rightarrow (\mathbf{PROC} + \{??\})$$

Most continuation types got simplified, since expressions or procedure declarations do not produce new **Store**'s. We could have done that previously, too.

Semantic functions

As before:

$$\mathcal{E}: \text{Exp} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_E \rightarrow \text{Cont}}_{\text{EXP}}$$

$$\mathcal{B}: \text{BExp} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_B \rightarrow \text{Cont}}_{\text{BEXP}}$$

$$\mathcal{S}: \text{Stmt} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont} \rightarrow \text{Cont}}_{\text{STMT}}$$

$$\mathcal{D}_V: \text{VDecl} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{Cont}_{D_V} \rightarrow \text{Cont}}_{\text{VDECL}}$$

$$\mathcal{D}_P: \text{PDecl} \rightarrow \underbrace{\text{VEnv} \rightarrow \text{PEnv} \rightarrow \text{Cont}_{D_P} \rightarrow \text{Cont}}_{\text{PDECL}}$$

Sample semantic clauses

Roughly as before. A few get simpler because of simpler continuation types, e.g.:

$$\mathcal{E}[[x]] \rho_V \kappa_E s = \kappa_E n \text{ where } l = \rho_V x, n = s l$$

But a few get more complicated because the simpler types require more explicit state passing, e.g.:

$$\mathcal{E}[[e_1 + e_2]] \rho_V \kappa_E s = \mathcal{E}[[e_1]] \rho_V (\lambda n_1:\mathbf{Int}.\mathcal{E}[[e_2]] \rho_V (\lambda n_2:\mathbf{Int}.\kappa_E (n_1 + n_2)) s) s$$

One new clause:

$$\mathcal{S}[\mathbf{abort}] \rho_V \rho_P \kappa = id_{\mathbf{Store}}$$

Compare it to:

$$\mathcal{S}[\mathbf{skip}] \rho_V \rho_P = id_{\mathbf{Cont}}$$

Exceptions

Exception throwing is a more fancy kind of abrupt termination, where only part of a program gets terminated.

We will throw and catch named exceptions without parameters.

$$\begin{aligned} S \in \mathbf{Stmt} &::= \dots \mid \mathbf{try} \ S_1 \ \mathbf{catch}(\chi) \ S_2 \mid \mathbf{throw} \ \chi \\ \chi \in \mathbf{EXN} &::= \dots \end{aligned}$$

- A thrown exception may erase a part of the procedure-call stack, but it does not erase changes to the store.

Semantic domains

- A new kind of environment:

$$\mathbf{XEnv} = \mathbf{EXN} \rightarrow (\mathbf{Cont} + \{??\})$$

- The appropriate semantic functions get another environment parameter:

$$\begin{array}{l} \mathcal{S}: \mathbf{Stmt} \rightarrow \underbrace{\mathbf{VEnv} \rightarrow \mathbf{PEnv} \rightarrow \mathbf{XEnv} \rightarrow \mathbf{Cont} \rightarrow \mathbf{Cont}}_{\text{STMT}} \\ \mathcal{D}_P: \mathbf{PDecl} \rightarrow \underbrace{\mathbf{VEnv} \rightarrow \mathbf{PEnv} \rightarrow \mathbf{XEnv} \rightarrow \mathbf{Cont}_{\mathbf{D}_P} \rightarrow \mathbf{Cont}}_{\text{PDECL}} \end{array}$$

Semantic clauses

- Semantic clauses for declarations and statements of the “old” forms take the extra environment parameter and disregard it (passing it “down”).
- New clauses:

$$\mathcal{S}[\text{try } S_1 \text{ catch}(\chi) S_2] \rho_V \rho_P \rho_X \kappa =$$

$$\mathcal{S}[S_1] \rho_V \rho_P \rho_X [\chi \mapsto \kappa'] \kappa \text{ where } \kappa' = \mathcal{S}[S_2] \rho_V \rho_P \rho_X \kappa$$

$$\mathcal{S}[\text{throw } \chi] \rho_V \rho_P \rho_X \kappa = \rho_X \chi$$