# PyPy meets Python 3 and Numpy (and other What's New topics)

Armin Rigo

EuroPython 2017

July 2017

# What's New In PyPy

- 1. Python 3.5
- 2. Numpy, Cython, Pandas, ...
- 3. pypy-stm?
- 4. RevDB: reverse debugging
- 5. Others...

### What is PyPy

- PyPy is another implementation of Python
- Mostly, drop-in replacement
- Supports Python 2.7, and almost Python 3.5
- ► Comes with a JIT, good performance

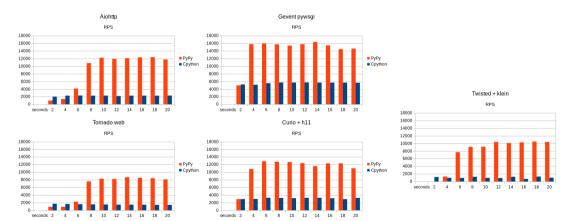
PyPy 3.5

### PyPy 3.5

- Python 3.5 support released in gamma
  - as stable (and mostly as fast) as PyPy 2.7, same JIT/GC/etc.
  - what could be wrong is a few details everywhere
  - please try it and report issues!
- ► Thanks to Mozilla for funding this work!

## PyPy 3.5

#### ► Async HTTP benchmarks:



### PyPy 3.5 status

- ► Roughly complete 3.5 support (plus f-strings!)
- Reasonably good performance
- ► Tested mostly on Linux so far
- ► First "final" to be released soon (i.e. some time in 2017 I guess)
- Python 3.6 to follow

#### Numpy or Numpypy?

- ► Numpy = the standard numpy library
- ► Numpypy = our own partial reimplementation

#### Numpy or Numpypy?

- ► Numpy = the standard numpy library (use this)
- ► Numpypy = our own partial reimplementation (deprecated)

- ► Numpy works (99.9%)
- On both PyPy 2.7 and PyPy 3.5
- ► The rest of the scientific stack mostly works too (Jupyter, Matplotlib, Pandas, etc.)

### Cython, cpyext

- Cython mostly works
- Actually, any CPython C extension module mostly works
- ▶ Thanks to cpyext, our CPython C API emulation layer

#### Performance?

- Numpy/Pandas/etc. are all slow-ish at the Python-C boundary
- Less so than last year but still
- Complex algorithms written inside Numpy in C or Fortran have the same speed, of course
  - lots of ndarray[index]: slow
  - one call to numpy.linalg.eig(): fast
  - ▶ speed hack: p = ffi.cast("double \*", ffi.from\_buffer(ndarray))

#### Performance?

- ► We have plans to improve
- ► Funding help welcome
- For now: try it out on your own code and see

pypy-stm: getting rid of the Global Interpreter Lock

...unfortunately, this approach does not seem to work :-(

#### Unstable performance:

- "Conflicts" between threads are hard to find
- Fix one conflict, usually only to uncover the next one
- As long as there is one, performance is bad
- You may fix enough to get good performance... but:
- Continue developing the program, and you'll often reintroduce conflicts
- (Also, hard to test for, reliably)

### PyPy-nogil?

- ► Thinking instead about a GIL-free but non-STM PyPy
- ► See lightning talk later

# Reverse Debugger

# Reverse Debugger

▶ RevDB: The essential tool you need once a year

### Reverse Debugger

- Debugger with the ability to go forward and backward in time
- ▶ Watchpoints to know when a value changes, while going in either direction
- http://bitbucket.org/pypy/revdb

#### Others

### JIT improvements

- ► Reductions in the warm-up time
- ► Consumes less memory, too

#### **VMProf**

- A good high-performance profiler for Python code
- ▶ pip install vmprof
- Works on CPython and on PyPy
- ▶ The PyPy version shows the machine code generated by the JIT

### **CFFI** improvements

- ► CFFI: calling C from Python or the other way around
- Works identically on CPython and on PyPy
- Biggest improvement of last year is embedding
- Use CFFI to embed Python inside another program---much easier than with the CPython C API, and works identically on CPython or PyPy too

# Next year?

## Next year?

- ▶ Polish PyPy 3.5 / 3.6
- Polish Numpy and the scientific stack
- ► Play with PyPy-nogil
- ► Port RevDB to PyPy 3.5

#### Question & answers

- ▶ Polish PyPy 3.5 / 3.6
- ► Polish Numpy and the scientific stack
- Play with PyPy-nogil
- Port RevDB to PyPy 3.5

Thank you! PyPy main site: http://pypy.org/