(15i)

APPENDIX

A. Tractable Reformulation of the Multi-Stage Chance-Constrained Investment Problem (4)

Using uncertainty model (2), linear decision rules (5), and following the derivations in Section III, the multi-stage chance-

Constrained investment problem (4) takes the following second-order cone programming form:

$$\min_{\overline{V}} \sum_{t=1}^{T} \left(\text{Tr}\left[S_{t} \hat{\Sigma} S_{t} (Q_{t}^{\parallel T} \overline{V}_{t} + Q_{t}^{\parallel T} \overline{\Theta}_{t} + Q_{t}^{\parallel T} \overline{\Theta}_{t}) \right] + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + \sum_{\tau=1}^{t} \left(o_{t}^{\parallel T} \overline{V}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} \right) S_{\tau} 1 \right) \\
+ \sum_{w=1}^{W} w_{w} \prod_{h=1}^{W} \text{Tr}\left[S_{t}^{\parallel L} \hat{S}_{t} (C_{t}^{\parallel T} P_{t} + Q_{t}^{\parallel T} \overline{\Theta}_{t}) \right] + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + \sum_{\tau=1}^{t} \left(o_{t}^{\parallel T} \overline{V}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} \right) S_{\tau} 1 \right) \\
+ \sum_{w=1}^{W} w_{w} \prod_{h=1}^{W} \text{Tr}\left[S_{t}^{\parallel L} \hat{S}_{t} (C_{t}^{\parallel T} P_{t} + Q_{t}^{\parallel T} \overline{\Theta}_{t}) \right] + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + \sum_{\tau=1}^{t} \left(o_{t}^{\parallel T} \overline{V}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} \right) S_{\tau} 1 \right) \\
+ \sum_{w=1}^{W} w_{w} \prod_{h=1}^{W} \text{Tr}\left[S_{t}^{\parallel L} \hat{S}_{t} (C_{t}^{\parallel T} P_{t} + Q_{t}^{\parallel T} \overline{\Theta}_{t}) \right] + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + \sum_{\tau=1}^{t} \left(o_{t}^{\parallel T} \overline{V}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} + o_{t}^{\parallel T} \overline{\Theta}_{\tau} \right) S_{\tau} 1 \right) \\
+ \sum_{h=1}^{W} w_{w} \prod_{h=1}^{W} \text{Tr}\left[S_{t}^{\parallel L} \hat{S}_{t} (C_{t}^{\parallel T} P_{t} + Q_{t}^{\parallel T} P_{t}) \right] + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + o_{t}^{\parallel T} \overline{P}_{t} S_{t} + o_{t}^{\parallel T} \overline{P}_{t} S_{t} 1 + o_{t}^{\parallel T} \overline$$

 $\left\|\overline{\Sigma}\left[\sum_{\tau=1}^{t}\overline{\Phi}_{\tau wh}S_{\tau}-(\Phi_{twh}^{\scriptscriptstyle +}+\Phi_{twh}^{\scriptscriptstyle -})S_{t}\right]_{i}^{\scriptscriptstyle \top}\right\|\leqslant \frac{1}{\sqrt{(1-\overline{\varepsilon}^{\scriptscriptstyle 8})/\overline{\varepsilon}^{\scriptscriptstyle 8}}}\left[\sum_{\tau=1}^{t}\overline{\Phi}_{\tau wh}S_{\tau}-(\Phi_{twh}^{\scriptscriptstyle +}+\Phi_{twh}^{\scriptscriptstyle -})S_{t}\right]_{i}^{\scriptscriptstyle \top}\right\|$

in variables $\overline{\mathcal{V}}=\{\overline{Y},\overline{\Theta},\overline{\Phi},P,Y,\Theta,\Phi^{\circ},z^{\circ},x^{\circ}\}$, plus emission and investment limits as in (4g) and (4h), respectively. Here, the double-sided entries in power flow constraint (4c) are reformulated into (15d) with $\overline{\varepsilon}^f=\varepsilon^f/E$. The double-sided existing generation limits in (4d) are reformulated into (15e), and single-sided candidate generation limits in (4d) are reformulated into (15f), while fixing $\overline{\varepsilon}^g=\varepsilon^g/(3N)$. Similarly, the double-sided ramping limits on existing generation in (4e) are reformulated into (15g) and the single-sided ramping limits on candidate generation in (4e) are reformulated into (15h). Here, we set $\overline{\varepsilon}^r=\varepsilon^r/(3N)$. All entries in the operational storage constraint (4f) are single-sided and reformulated into (15i) with $\overline{\varepsilon}^s=\varepsilon^s/(7N)$.

B. The Dual Stochastic Problem Formulation

The dual problem of the chance-constrained program (4) takes the following form:

where the optimization variables are denoted by the Greek letter λ . Here, the expected value of the dual objective function is maximized subject to the series of joint chance constraints, where the subscript \odot in ε° denotes the primal variables to which the dual constraints correspond. Note, that the tractable second-order cone programming form of problem (16) is achieved similarly to problem (15) and omitted in the interest of space.