

seamCarving

June 5, 2020

```
[32]: import cv2
import numpy as np
import math
import time
import matplotlib.pyplot as plt
from scipy.ndimage.filters import convolve
```

```
[2]: # resize the image proportionally

def img_resize(image, new_cols):
    row, col = image.shape[0], image.shape[1]

    ratio = new_cols / col

    new_rows = ratio * row

    img_new = cv2.resize(image, (int(new_cols), int(new_rows)))
    return img_new
```

```
[3]: # def normalization_e(data):
#     _range = np.max(data) - np.min(data)
#     return (data - np.min(data)) / _range
```

```
[4]: # compute gradient of image

def compute_sobel(im):
    filter_du = np.array([
        [1.0, 2.0, 1.0],
        [0.0, 0.0, 0.0],
        [-1.0, -2.0, -1.0],
    ])
    filter_dv = np.array([
        [1.0, 0.0, -1.0],
        [2.0, 0.0, -2.0],
        [1.0, 0.0, -1.0],
    ])
    im = im.astype('float32')
```

```

        convolved = np.absolute(convolve(im, filter_du)) + np.absolute(convolve(im,
↪filter_dv))
    return convolved

```

[5]: *# compute gradient of image and construct energy image*

```

def compute_importance(image):
    eI = compute_sobel(image)
    return eI

```

[6]: *# compute the accumulation of energy*

```

def compute_M(importances):
    [row, column] = importances.shape
    M = np.zeros((row, column))
    track = np.zeros((row, column))

    for i in range(row):
        for j in range(column):
            if (i == 0):
                M[i][j] = importances[i][j]
                track[i][j] = 0
            else:
                if (j == 0):
                    M[i][j] = importances[i][j] + np.min(M[i - 1, j: j + 2])
                    track[i][j] = j + np.argmin(M[i - 1, j: j + 2])
                elif (j == column - 1):
                    M[i][j] = importances[i][j] + np.min(M[i - 1, j - 1: j + 1])
                    track[i][j] = j - 1 + np.argmin(M[i - 1, j - 1: j + 1])
                else:
                    M[i][j] = importances[i][j] + np.min(M[i - 1, j - 1: j +
↪2])
                    track[i][j] = j - 1 + np.argmin(M[i - 1, j - 1: j + 2])

    return M, track

```

[7]: *# delete a column path*

```

def delete_column(img):
    image = img.copy()
    im = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY)

    [row, column, channel] = image.shape
    mask = np.ones((row, column), dtype=np.bool)

    importances = compute_importance(im)
    [M, btrack] = compute_M(importances)

```

```

pos = np.argmin(M[row - 1, :])
mask_im = image.copy()
for i in reversed(range(row)):
    mask[i, pos] = 0
    pos = int(btrack[i, pos])
    mask_im[i, pos] = 255

mask = np.stack([mask] * 3, axis=2)

image = image[mask].reshape((row, column - 1, channel))

#     plt.imshow(mask_im)
return image

```

[8]: *# crop the image to new size*

```

def crop_image(im, newrow, newcol):
    image = im.copy()
    [row, col, channel] = image.shape
    crop_row_times = row - newrow
    crop_col_times = col - newcol
    for i in range(crop_col_times):
        #         print(i)
        image = delete_column(image)

    image = np.rot90(image, 1, (0, 1))
    for i in range(crop_row_times):
        #         print(i)
        image = delete_column(image)
    image = np.rot90(image, 3, (0, 1))
    return image

```

[9]: *# retarget the image to new size*

```

def retarget_image(im, newrow, newcol):
    image = im.copy()
    [row, col, channel] = image.shape
    row_ratio = row / newrow
    col_ratio = col / newcol
    print (row_ratio, col_ratio)
    if (newrow > row and newcol > col):
        if (row_ratio < col_ratio):
            thecol = int(col / row_ratio)
            image = img_resize(image, thecol)
        else:
            image = img_resize(image, newcol)
    elif (newrow > row and newcol <= col):

```

```

        thecol = int(col / row_ratio)
        image = img_resize(image, thecol)
    elif (newrow <= row and newcol > col):
        image = img_resize(image, newcol)

    print (image.shape)
    image = crop_image(image, newrow, newcol)
    return image

```

[10]: *# remove a column path of the signed rect*

```

def remove_line(img, a, b, c ,d):
    im = img.copy()
    image = cv2.cvtColor(im,cv2.COLOR_RGB2GRAY)

    [row, column, channel] = im.shape
    mask = np.ones((row, column), dtype=np.bool)

    importances = compute_importance(image)
    for i in range(b - a):
        for j in range(d - c):
            importances[i + a][j + c] = -100000
    [M, btrack] = compute_M(importances)
    #     plt.imshow(M, cmap = plt.cm.gray)

    pos = np.argmin(M[row - 1, :])
    mask_im = image.copy()
    for i in reversed(range(row)):
        mask[i, pos] = 0
        pos = int(btrack[i, pos])
        mask_im[i, pos] = 255

    mask = np.stack([mask] * 3, axis=2)

    im = im[mask].reshape((row, column - 1, channel))
    #     plt.imshow(im, cmap = plt.cm.gray)
    return im

```

[11]: *# remove the signed rect vertically*

```

def remove_rect(im, a, b, c ,d):
    image = im.copy()
    m = d
    for i in range(d - c - 1):
        #         print (i)
        image = remove_line(image, a, b, c, m)
        m = m - 1

```

```
return image
```

```
[12]: # remove the signed rect horizontally
```

```
def remove_rect_horizon(im, a, b, c ,d):  
    [row, col, channel] = im.shape  
    image = im.copy()  
    newc = col - d  
    newd = col - c  
    image = np.rot90(image, 1, (0, 1))  
    m = b  
    for i in range(b - a - 1):  
        # print (i)  
        image = remove_line(image, newc, newd, a, m)  
        m = m - 1  
    image = np.rot90(image, 3, (0, 1))  
    return image
```

```
[13]: # display the signed rectangle
```

```
def draw_rect(im, a, b, c ,d):  
    [row, col, channel] = im.shape  
    image = im.copy()  
    for i in range(row):  
        for j in range(col):  
            if (i >= a and i < b and j >= c and j < d):  
                image[i, j][2] = 255  
    return image
```

```
[50]: # remove multiple paths at once 1
```

```
def delete_multi_column(img, cols, is_show = False):  
  
    image = img.copy()  
  
    im = cv2.cvtColor(image,cv2.COLOR_RGB2GRAY)  
  
    [row, column, channel] = image.shape  
    mask = np.ones((row, column), dtype=np.bool)  
  
    importances = compute_importance(im)  
    [M, btrack] = compute_M(importances)  
  
    bottom = M[row - 1, :]  
  
    # print(bottom)  
    pos = np.argmin(M[row - 1, :])
```

```

#     print(pos)
#     print(min(M[row - 1, :]))
pos = np.argmin(M[row - 1, :])
mask_im = image.copy()

min_width = cols // 2
for i in reversed(range(row)):
    if (pos - 0 < min_width):
        min_width = pos
    if (column - 1 - pos < min_width):
        min_width = column - 1 - pos
    pos = int(btrack[i, pos])

#     print(min_width)

pos = np.argmin(M[row - 1, :])

for i in reversed(range(row)):
    for mm in range(2 * min_width + 1):
        mask[i, pos - min_width + mm] = 0
    for mm in range(2 * min_width + 1):
        mask_im[i, pos - min_width + mm] = (0, 255, 150)
    pos = int(btrack[i, pos])

mask = np.stack([mask] * 3, axis=2)

image = image[mask].reshape((row, column - (2 * min_width + 1), channel))

if (is_show == True):
    plt.imshow(mask_im)

return image

```

```

[49]: # remove multiple paths at once 2

def delete_multi_column2(img, cols, is_show = False):
    image = img.copy()

    im = cv2.cvtColor(image, cv2.COLOR_RGB2GRAY)

    [row, column, channel] = image.shape
    mask = np.ones((row, column), dtype=np.bool)

    importances = compute_importance(im)
    [M, btrack] = compute_M(importances)

    sort = np.argsort(M[row - 1, :])

```

```

count1 = 0
count2 = 0
able_update = 0

mask_im = image.copy()

while(1):
    if (count1 == cols or count2 == column - 1):
        break

    pos = sort[count2]
    pos1 = pos

    for i in reversed(range(row)):
        # print(np.where(mask[i,:] == 0), pos1)
        if (mask[i, pos1] == 0):
            break
        if (i == 0):
            able_update = 1
            pos1 = int(btrack[i, pos1])

    if (able_update == 1):
        count1 = count1 + 1
        for i in reversed(range(row)):
            mask[i, pos] = 0
            pos = int(btrack[i, pos])
            mask_im[i, pos] = (0, 255, 0)

    able_update = 0

    count2 = count2 + 1

mask = np.stack([mask] * 3, axis=2)
#
image = image[mask].reshape((row, column - count1, channel))

if (is_show == True):
    plt.imshow(mask_im)

return image

```

[16]: *# only remove background pixels*

```

def delete_bg_column(img):

    image = img.copy()

```

```

im = cv2.cvtColor(image,cv2.COLOR_RGB2GRAY)

[row, column, channel] = image.shape
mask = np.ones((row, column), dtype=np.bool)

importances = compute_importance(im)

grab_image = image.copy()

rows, cols = im_re.shape[0], im_re.shape[1]
mask_t = np.zeros(grab_image.shape[:2],np.uint8)
bgdModel = np.zeros((1,65),np.float64)
fgdModel = np.zeros((1,65),np.float64)
rect = (50, 50, rows - 50, cols - 50)#
cv2.grabCut(grab_image, mask_t,rect,bgdModel,fgdModel,5,cv2.
→GC_INIT_WITH_RECT)
mask2 = np.where((mask_t==2)|(mask_t==0),0,1).astype('uint8')#0 2

#     importances[mask2] = 10000
for i in range(row):
    for j in range(column):
        if (mask2[i][j] == 1):
            importances[i][j] = 10000

[M, btrack] = compute_M(importances)

pos = np.argmin(M[row - 1, :])
mask_im = image.copy()
for i in reversed(range(row)):
    mask[i, pos] = 0
    pos = int(btrack[i, pos])
    mask_im[i, pos] = 255

mask = np.stack([mask] * 3, axis=2)

image = image[mask].reshape((row, column - 1, channel))

#     plt.imshow(mask_im)
return image

```

[57]: *# read the image file and resize it*

```

filename = './test1.jpeg'
im_bgr = cv2.imread(filename)
b,g,r = cv2.split(im_bgr)
im_rgb = cv2.merge([r,g,b])

```



```
im_rgb = img_resize(im_rgb, 500)

[row, col, channel] = im_rgb.shape

im = cv2.imread(filename, 0)

im = img_resize(im, 500)
plt.figure(figsize=(6, 6))
plt.imshow(im_rgb)
```

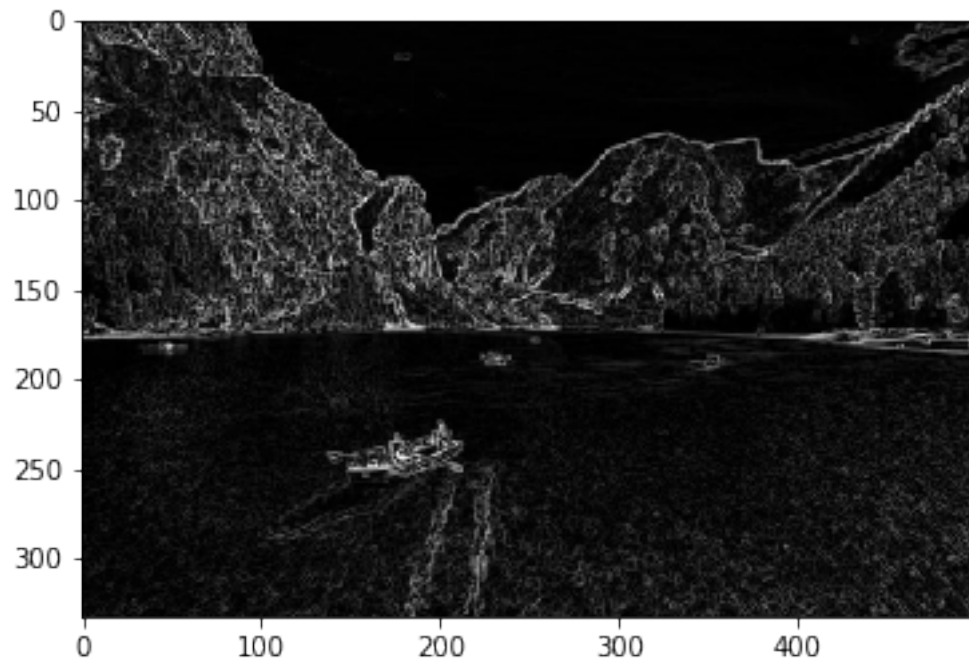
[57]: <matplotlib.image.AxesImage at 0x7f612c53db00>



```
[58]: # show energy image

eI1 = compute_importance(im)
plt.figure(figsize=(6, 6))
plt.imshow(eI1, cmap = plt.cm.gray)
```

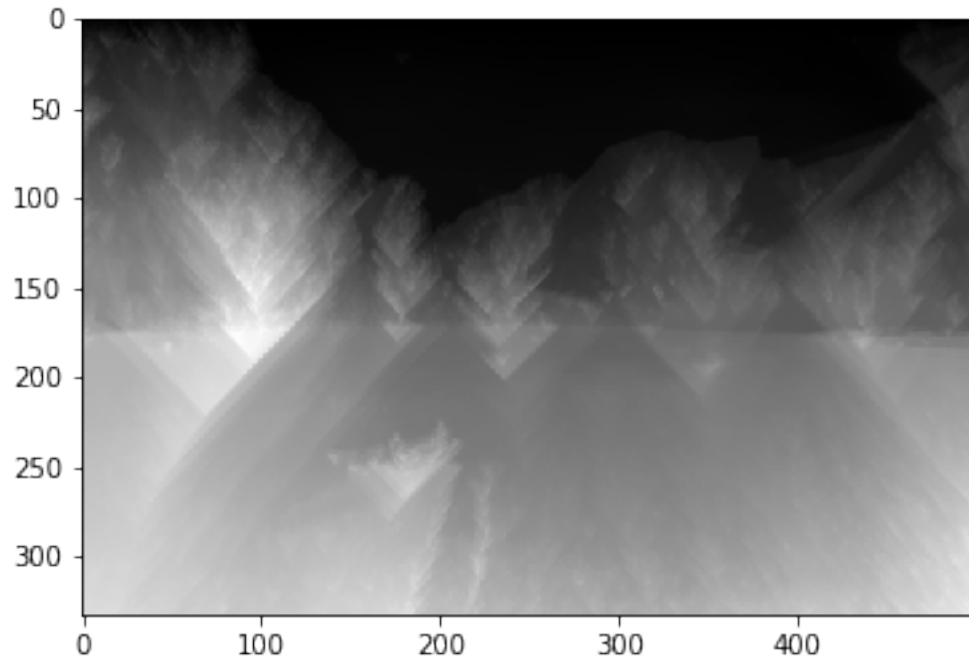
[58]: <matplotlib.image.AxesImage at 0x7f612dff6208>



```
[59]: # show accumulation of energy image
```

```
M, track = compute_M(eI1)
plt.figure(figsize=(6, 6))
plt.imshow(M, cmap = plt.cm.gray)
```

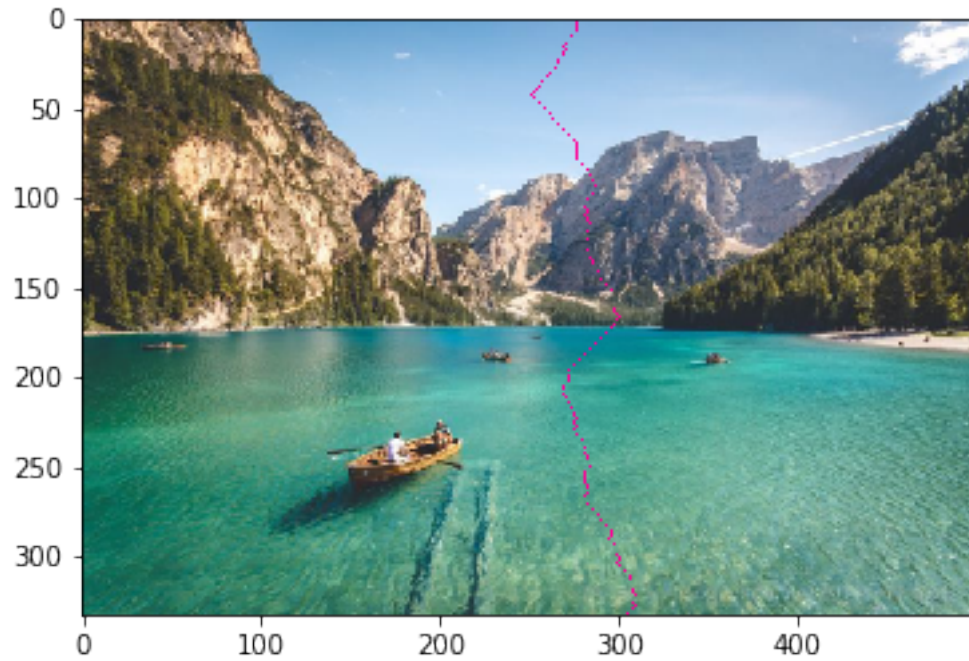
```
[59]: <matplotlib.image.AxesImage at 0x7f612c36b278>
```



```
[61]: # show energy minimum path

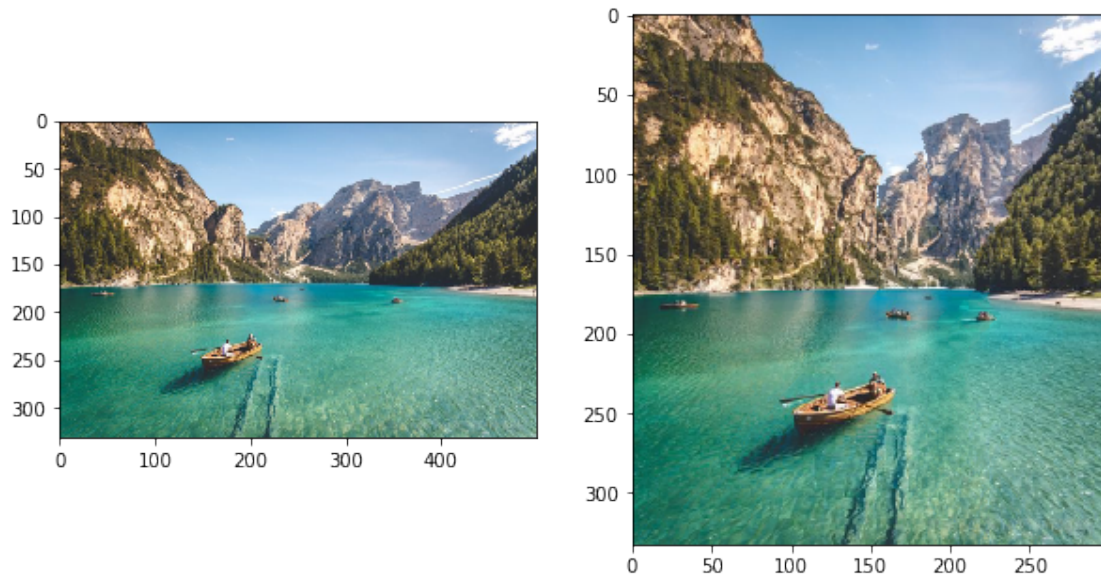
pos = np.argmin(M[row - 1, :])
mask_im = im_rgb.copy()
for i in reversed(range(row)):
    pos = int(track[i, pos])
    mask_im[i, pos] = (255, 0, 150)
plt.figure(figsize=(6, 6))
plt.imshow(mask_im)
```

```
[61]: <matplotlib.image.AxesImage at 0x7f612dfa5d30>
```



```
[68]: # crop the image

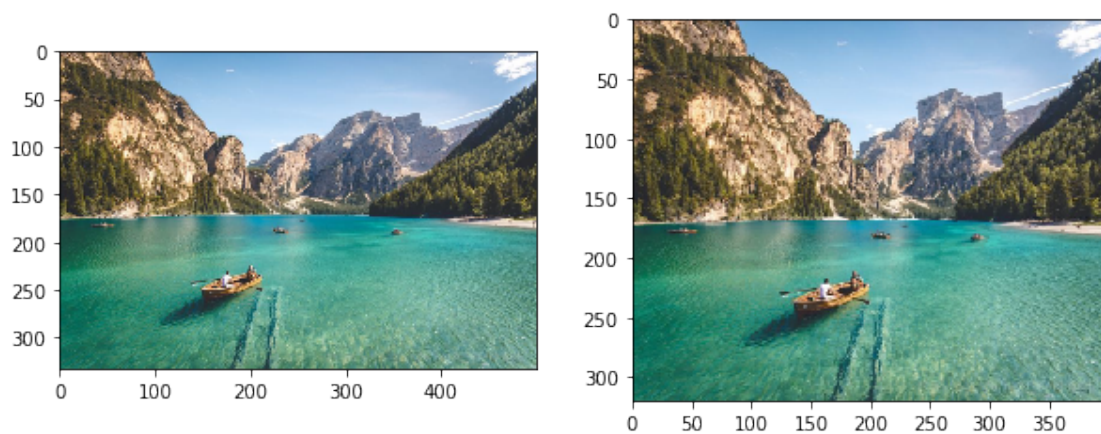
im_crop = crop_image(im_rgb, 320, 300)
plt.figure(figsize=(10, 10))
ax = plt.subplot(121)
plt.imshow(im_rgb)
ax = plt.subplot(122)
plt.imshow(im_crop)
plt.show()
```



[70]: *# retarget the image*

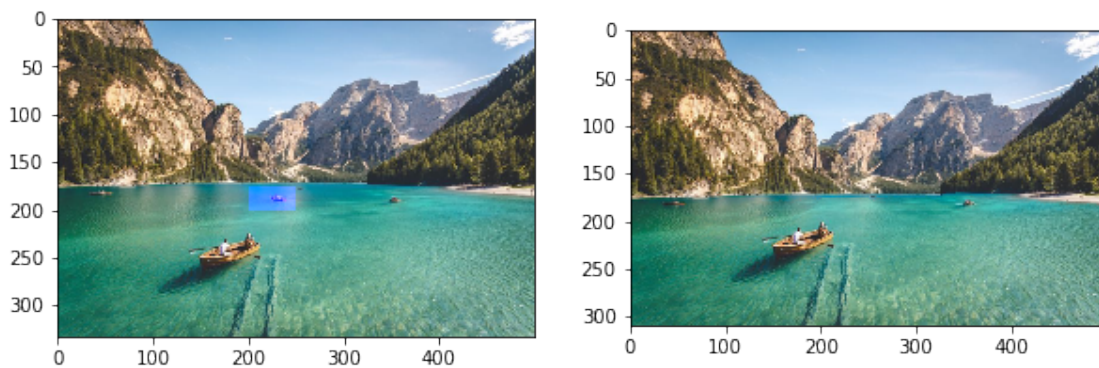
```
im_retar = retarget_image(im_rgb, 320, 400)
plt.figure(figsize=(10, 10))
ax = plt.subplot(121)
plt.imshow(im_rgb)
ax = plt.subplot(122)
plt.imshow(im_retar)
plt.show()
```

1.040625 1.25
(333, 500, 3)



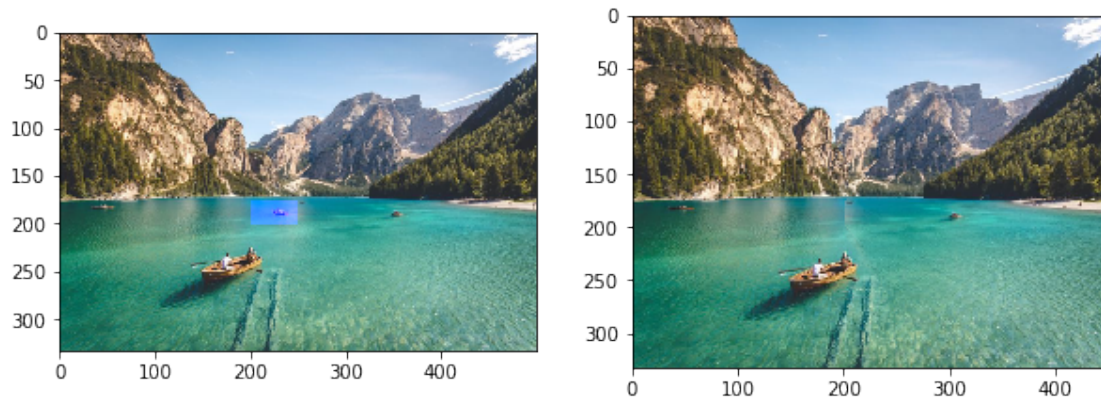

```
[71]: # remove the specified rectangular area

# rect = draw_rect(im_rgb, 350, 358, 270, 310)
# result = remove_rect_horizon(im_rgb, 350, 358, 270, 310)
rect = draw_rect(im_rgb, 175, 200, 200, 250)
result = remove_rect_horizon(im_rgb, 175, 200, 200, 250)
plt.figure(figsize=(10, 10))
ax = plt.subplot(121)
plt.imshow(rect)
ax = plt.subplot(122)
plt.imshow(result)
plt.show()
```



```
[74]: # remove the specified rectangular area

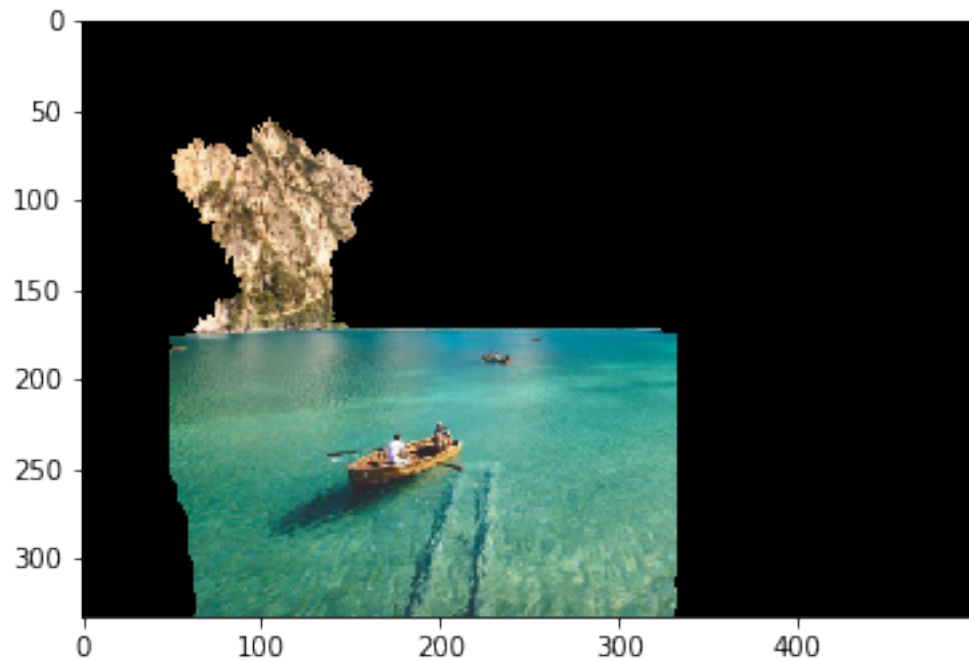
# rect1 = draw_rect(im_rgb, 350, 358, 270, 310)
# result1 = remove_rect(im_rgb, 350, 358, 270, 310)
rect1 = draw_rect(im_rgb, 175, 200, 200, 250)
result1 = remove_rect(im_rgb, 175, 200, 200, 250)
plt.figure(figsize=(10, 10))
ax = plt.subplot(121)
plt.imshow(rect1)
ax = plt.subplot(122)
plt.imshow(result1)
plt.show()
```



[75]: *# show the foreground isolated by grab cut*

```
im_cut = im_rgb.copy()
rows, cols = im_cut.shape[0], im_cut.shape[1]
mask = np.zeros(im_cut.shape[:2], np.uint8)
bgdModel = np.zeros((1, 65), np.float64)
fgdModel = np.zeros((1, 65), np.float64)
rect = (50, 50, rows - 50, cols - 50) #
cv2.grabCut(im_cut, mask, rect, bgdModel, fgdModel, 10, cv2.GC_INIT_WITH_RECT)
mask2 = np.where((mask==2) | (mask==0), 0, 1).astype('uint8') #0 2
im_re = im_cut * mask2[:, :, np.newaxis] #
plt.figure(figsize=(6, 6))
plt.imshow(im_re, cmap = plt.cm.gray)
```

[75]: <matplotlib.image.AxesImage at 0x7f612c3ff240>

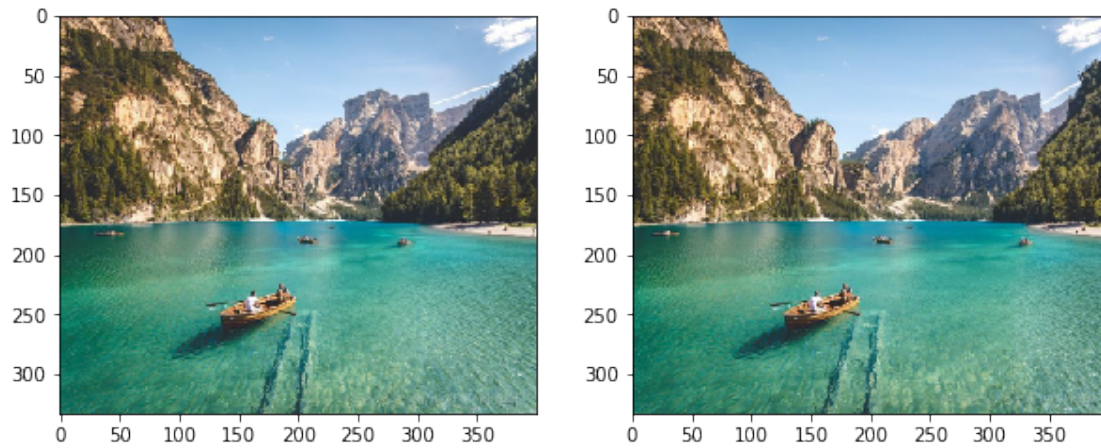


```
[76]: # improved seam carving

im_cc = im_rgb.copy()
for i in range(100):
    im_cc = delete_column(im_cc)

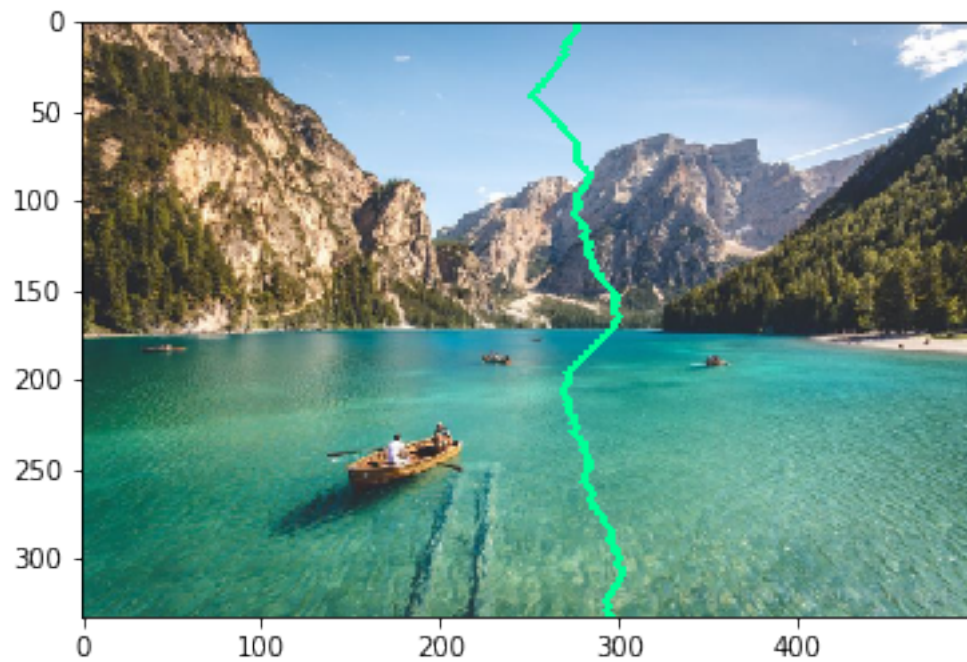
im_bg = im_rgb.copy()
for i in range(100):
    im_bg = delete_bg_column(im_bg)

plt.figure(figsize=(10, 10))
ax = plt.subplot(121)
plt.imshow(im_cc)
ax = plt.subplot(122)
plt.imshow(im_bg)
plt.show()
```

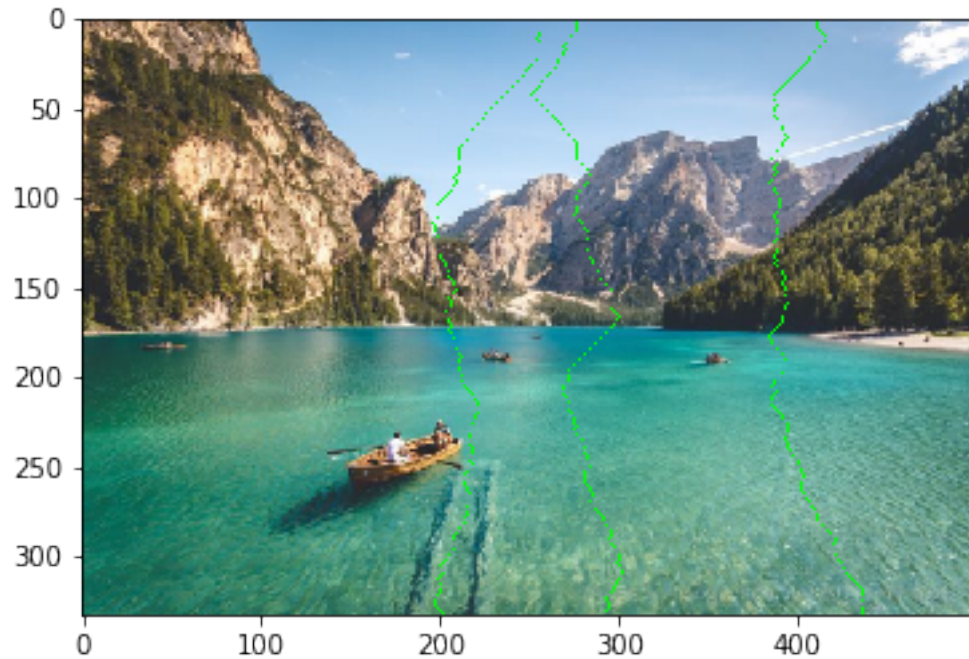
```
[77]: # show multiple path 1

plt.figure(figsize=(6, 6))
m1_im = delete_multi_column(im_rgb, 5, True)
```



```
[78]: # show multiple path 2

plt.figure(figsize=(6, 6))
m2_im = delete_multi_column2(im_rgb, 3, True)
```



```
[79]: start1 = time.clock()
mc1_im = im_rgb.copy()
for i in range(25):
    mc1_im = delete_multi_column(mc1_im, 3)

start2 = time.clock()
mc2_im = im_rgb.copy()
for i in range(25):
    mc2_im = delete_multi_column2(mc2_im, 3)

start3 = time.clock()
mc3_im = im_rgb.copy()
for i in range(75):
    mc3_im = delete_column(mc3_im)

end = time.clock()

print ('multi_column1: ', start2 - start1, 's')
print ('multi_column2: ', start3 - start2, 's')
print ('single_column: ', end - start3, 's')

plt.figure(figsize=(10, 10))
ax = plt.subplot(131)
plt.imshow(mc3_im)
ax = plt.subplot(132)
```

```
plt.imshow(mc1_im)
ax = plt.subplot(133)
plt.imshow(mc2_im)
plt.show()
```

multi_column1: 32.065685000000003 s
multi_column2: 33.166760999999995 s
single_column: 95.752762999999996 s

