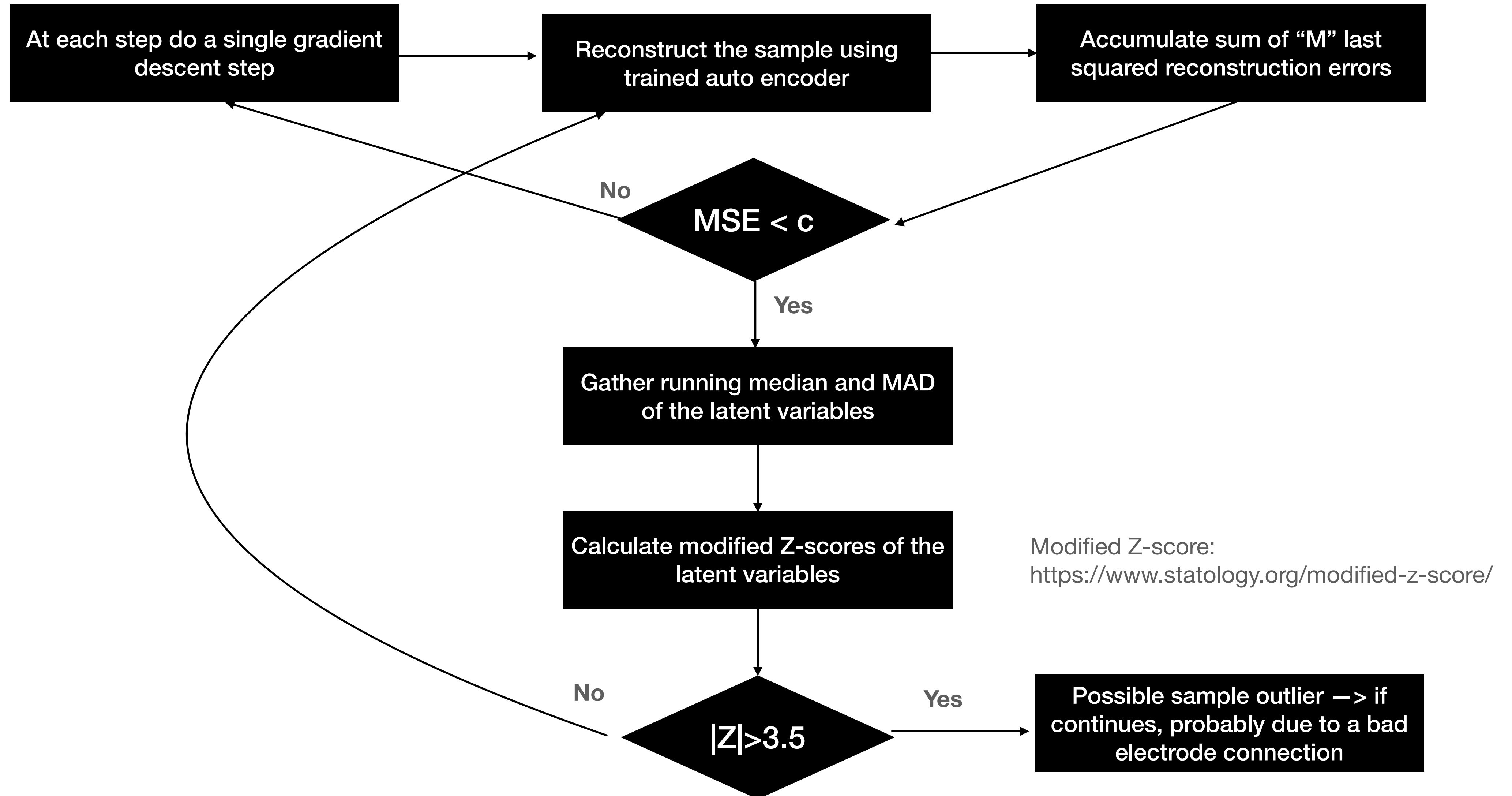


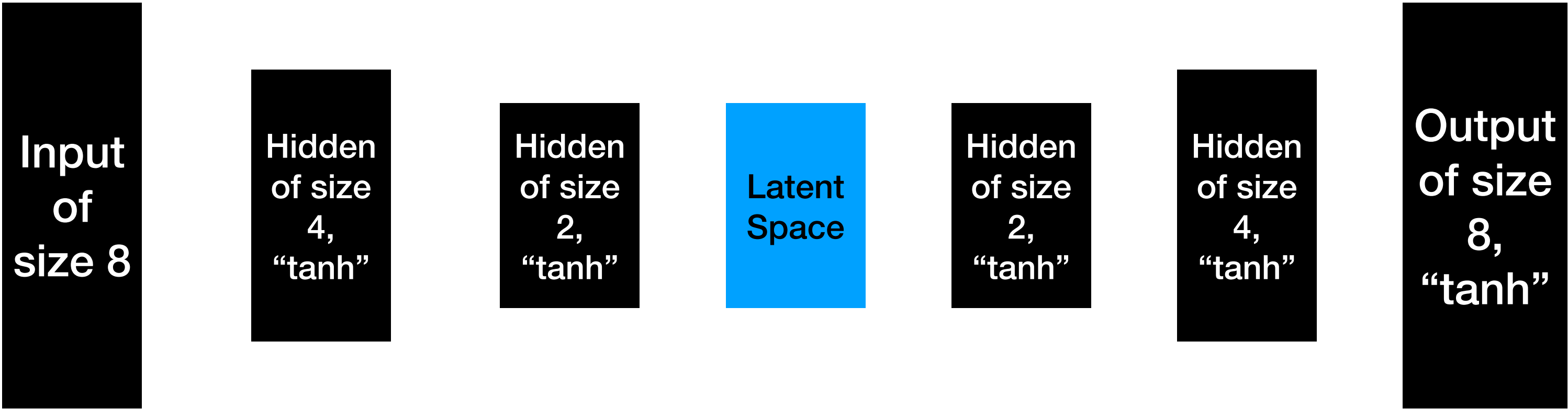
RT Data-Driven Detection of Bad Electrodes Connection

Anton Cooper

For each SNC sensor take windows of 8 consecutive samples, then at each time step do the following logic



Simple autoencoder architecture

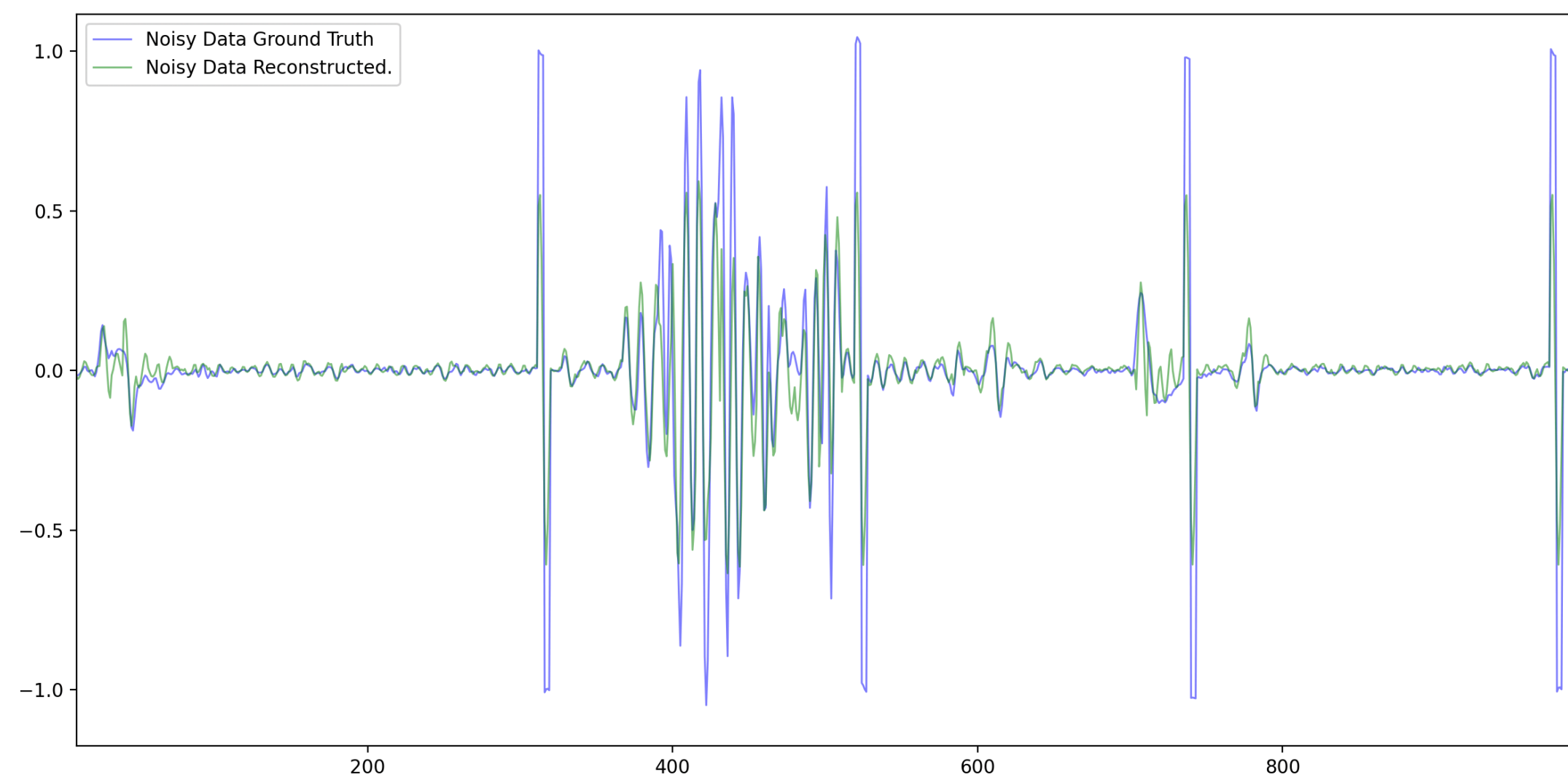


```
-----  
Layer (type)           Output Shape          Param #  
-----  
input_1 (InputLayer)    [(None, 8)]           0  
  
model (Functional)      (None, 2)             52  
  
model_1 (Functional)    (None, 8)             58  
  
-----  
Total params: 110 (440.00 Byte)  
Trainable params: 110 (440.00 Byte)  
Non-trainable params: 0 (0.00 Byte)
```

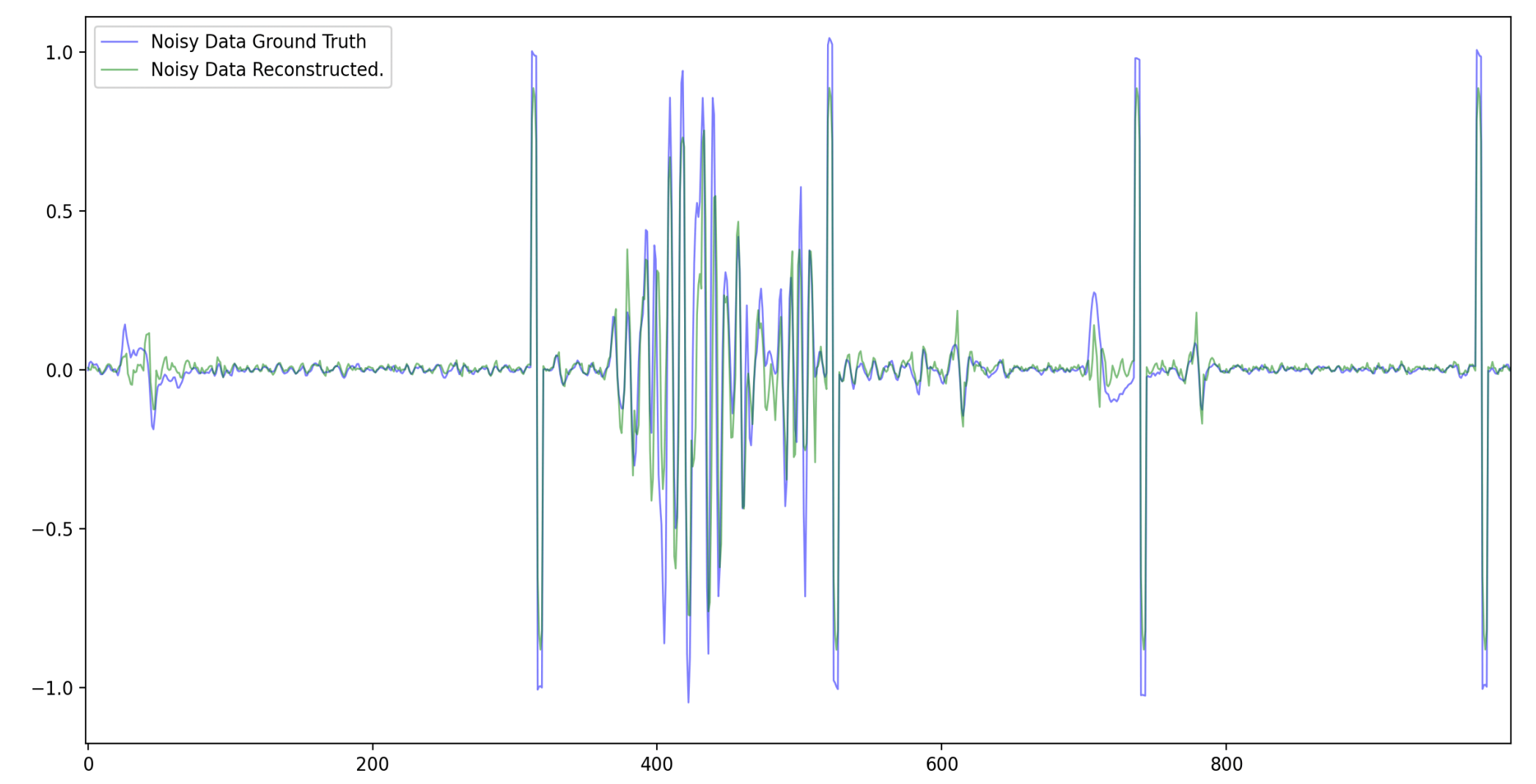
Only, 110 parameters - should work in mobile and might be suitable even for embedded

Example Doublet Noise

Autoencoder **trained on clean data**



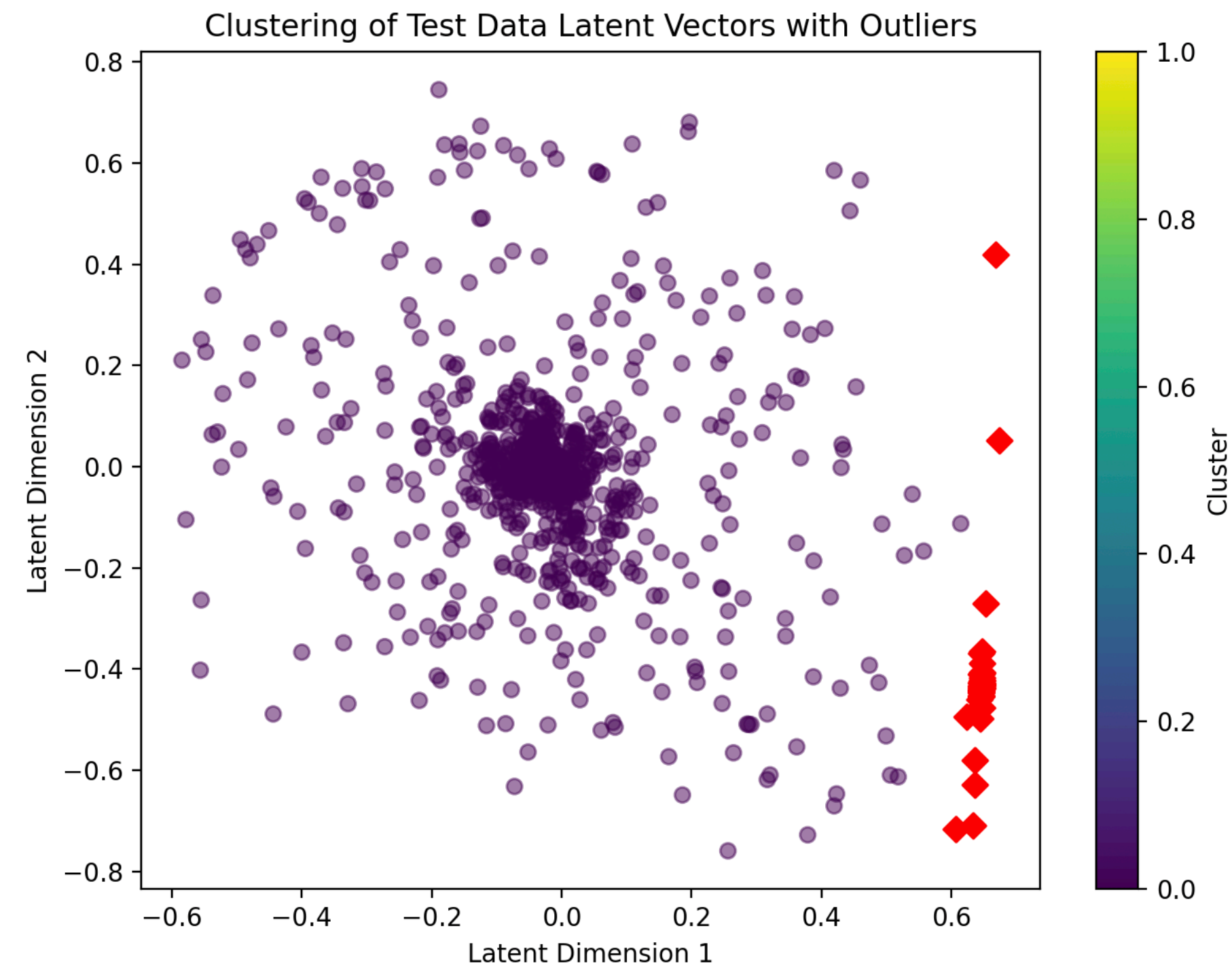
Autoencoder **trained on noisy data**



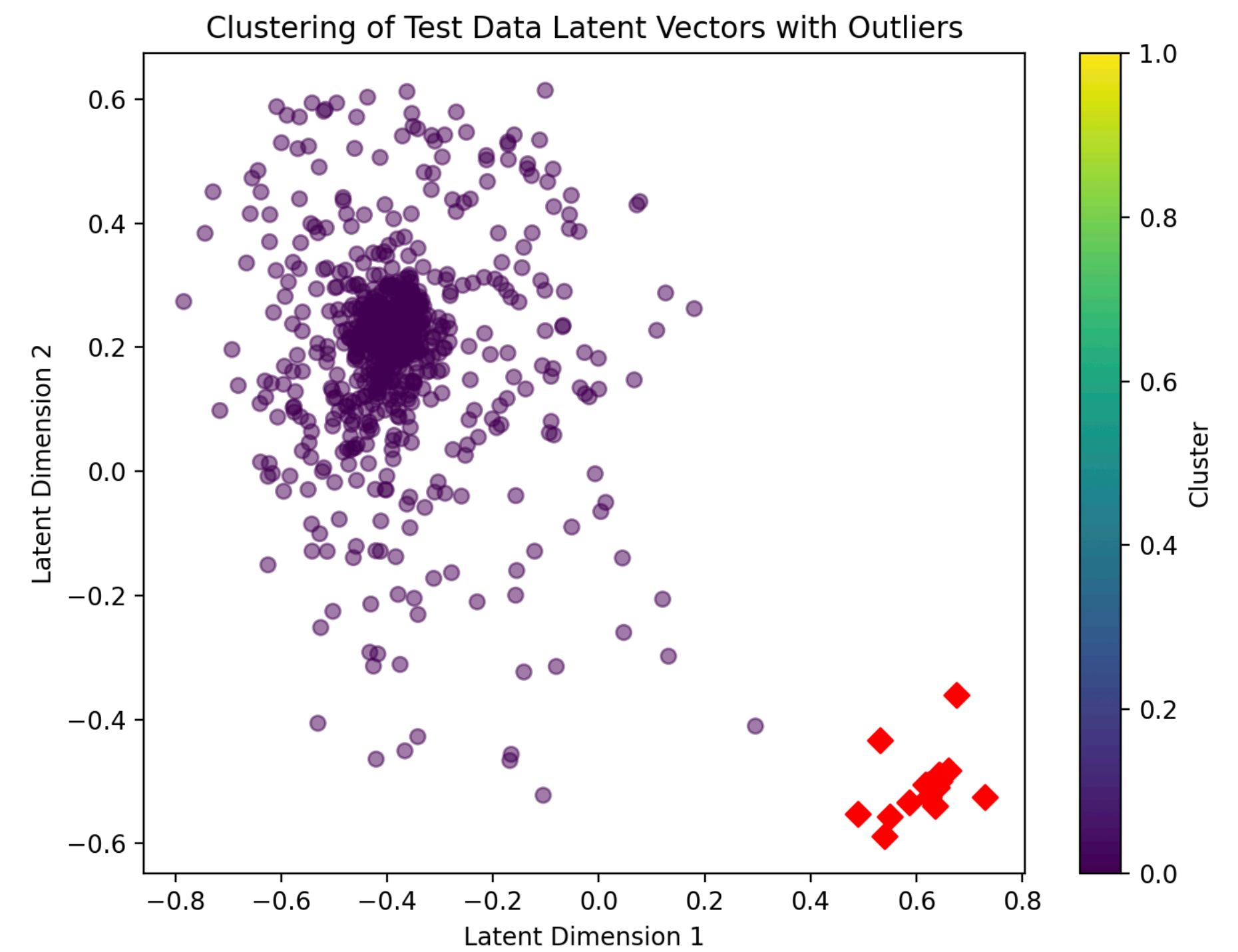
Reconstruction error is much smaller when trained on noisy train set, thus RT anomaly detection is better doing in the latent space.

Example Doublet Noise

Autoencoder and K-means **trained on clean data**

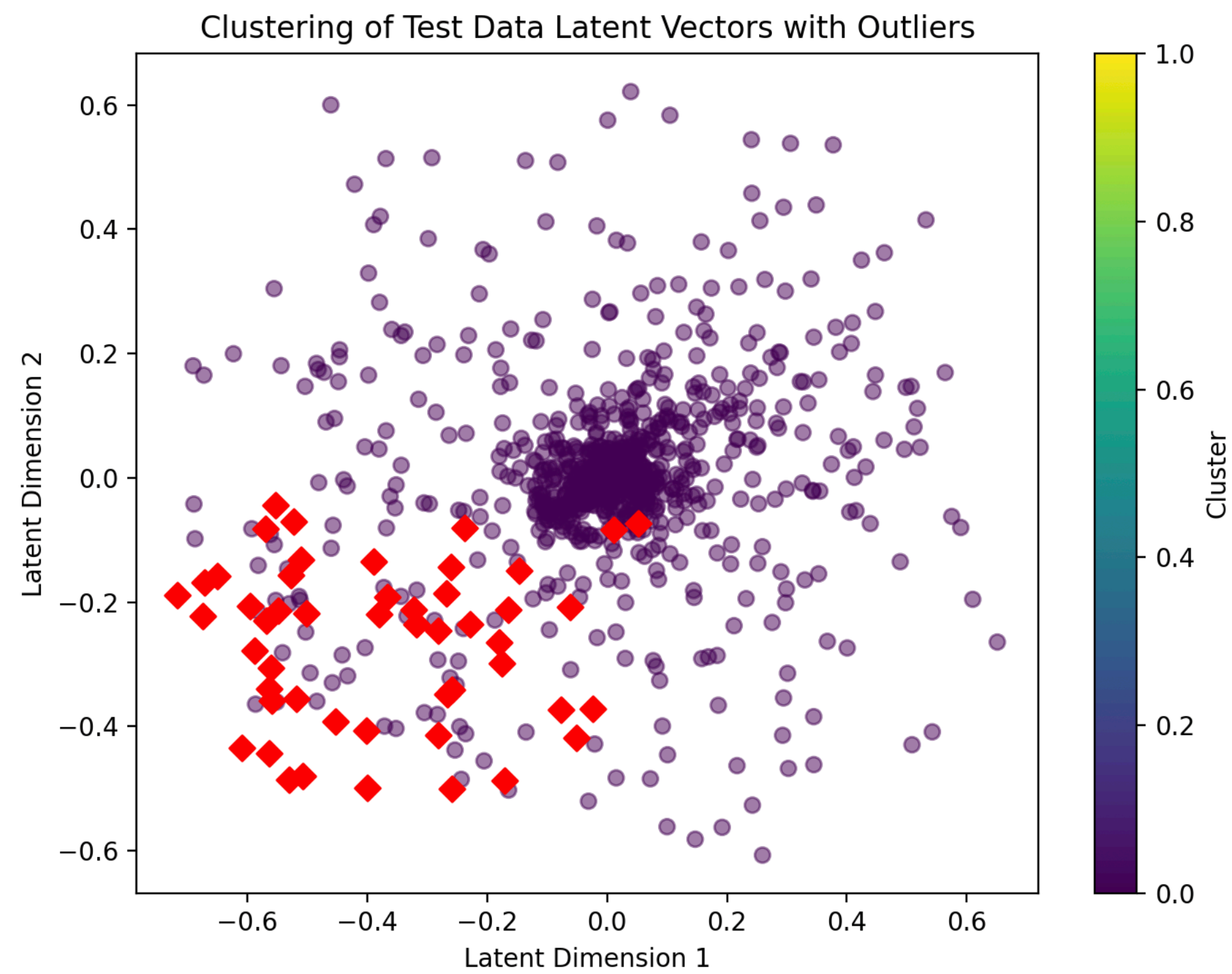


Autoencoder and K-means **trained on noisy data**

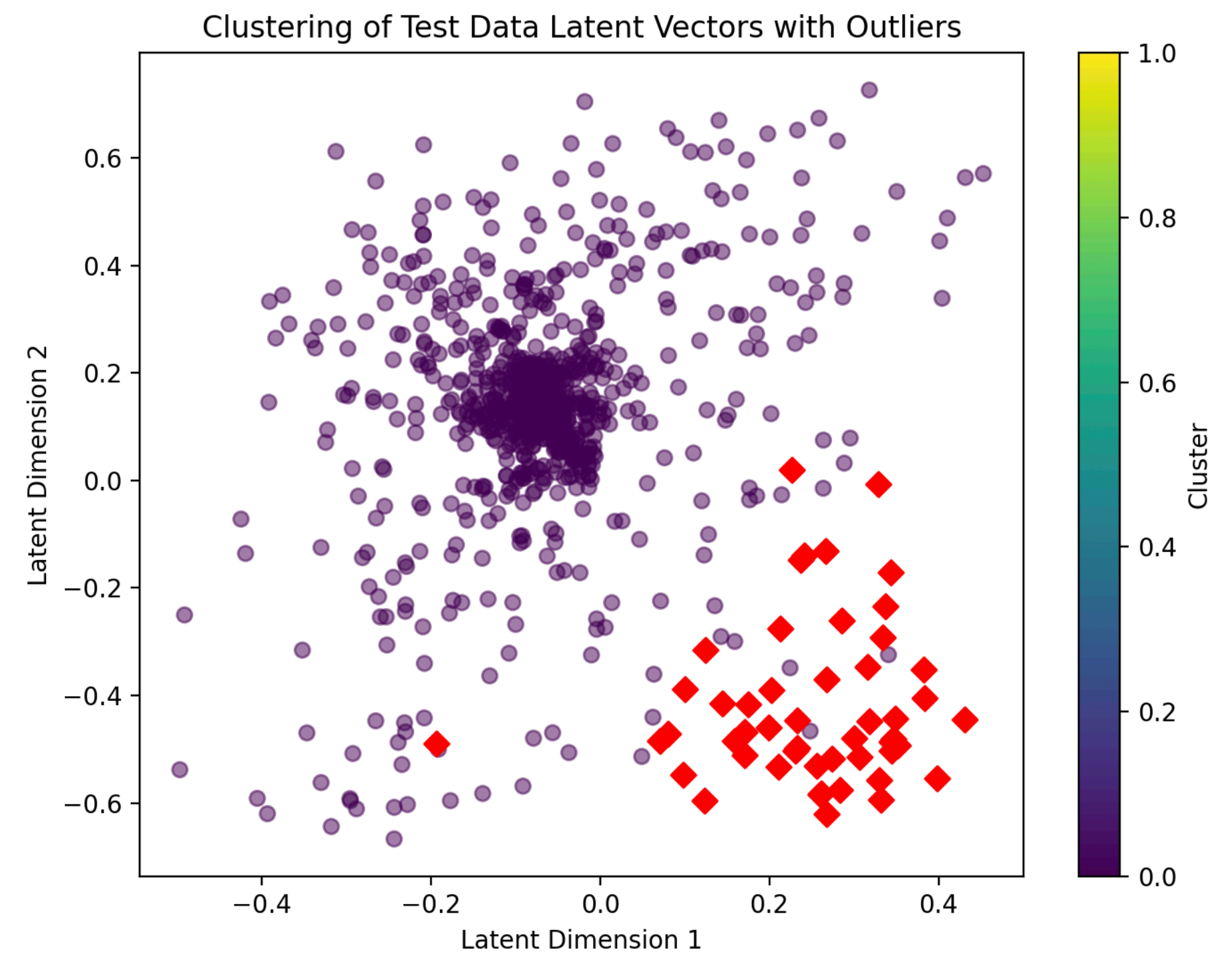


Example White Noise

Autoencoder and K-means trained on clean data



Autoencoder and K-means trained on noisy data



Here separability is worse than in a doublet case, probably because noise is a continuous value between (0, 1), while in doublet it is either 1, either -1. In addition doublet is more representative to electrode disconnection than white noise.