

# Internet of Things Practical

## Week 1-2 Manual

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# Preparation for OS: Configure Installation and Basic Setting

## 1. Complete the Box

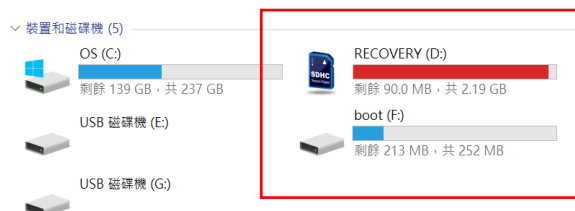
The box has 6 pieces of plastic, one of them is the top. Make up the four surrounding broads and place the mother board in. Place the bottom and the top at last. Be careful with the sides, otherwise The box would look like the pictures below.



## 2. Format SD Card

You would need a SD card formatter, the Windows default formatter cannot return “a SD card that divided into 2 slots” back to one slot. Download at: [https://www.sdcard.org/downloads/formatter\\_4/](https://www.sdcard.org/downloads/formatter_4/).

First you read the raspberry pi, you would see a *recovery slot* and another *boot slot*, using the formatter upon then a clean, newly SD card is here.



← 2 slots initially, make it 1.

**⚠ Notice** The SD card slot on raspberry pi is fragile, pull out carefully.

## 3. Install OS with NOOBs

This resource explains how to install a Raspberry Pi operating system on an SD

card. We recommend most users download [NOOBS](#), which is designed to be very easy to use. *New Out Of Box Software (NOOBS)* is an easy operating system installation manager for the Raspberry Pi.

Unzip the zip file on Windows, copy the files under NOOBS folder into the Raspberry Pi's SD card. Then you can boot the Raspberry Pi. Note that do not copy the root folder directly.

下載 > noobs解壓縮 > NOOBS\_v3\_2\_0

搜尋 NOOBS\_v3\_2\_0

名稱	修改日期	類型
defaults	2019/9/17 下午 01:44	檔案資料夾
os	2019/9/17 下午 01:44	檔案資料夾
overlays	2019/9/17 下午 01:44	檔案資料夾
bcm2708-rpi-b.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2708-rpi-b-plus.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2708-rpi-cm.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2708-rpi-zero.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2708-rpi-zero-w.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2709-rpi-2-b.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2710-rpi-3-b.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2710-rpi-3-b-plus.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2710-rpi-cm3.dtb	2019/6/10 下午 12:18	DTB 檔案
bcm2711-rpi-4-b.dtb	2019/6/10 下午 12:18	DTB 檔案
bootcode.bin	2019/6/10 下午 12:18	BIN 檔案
BUILD-DATA	2019/6/10 下午 12:18	檔案
INSTRUCTIONS-README.txt	2019/6/10 下午 12:18	文字文件

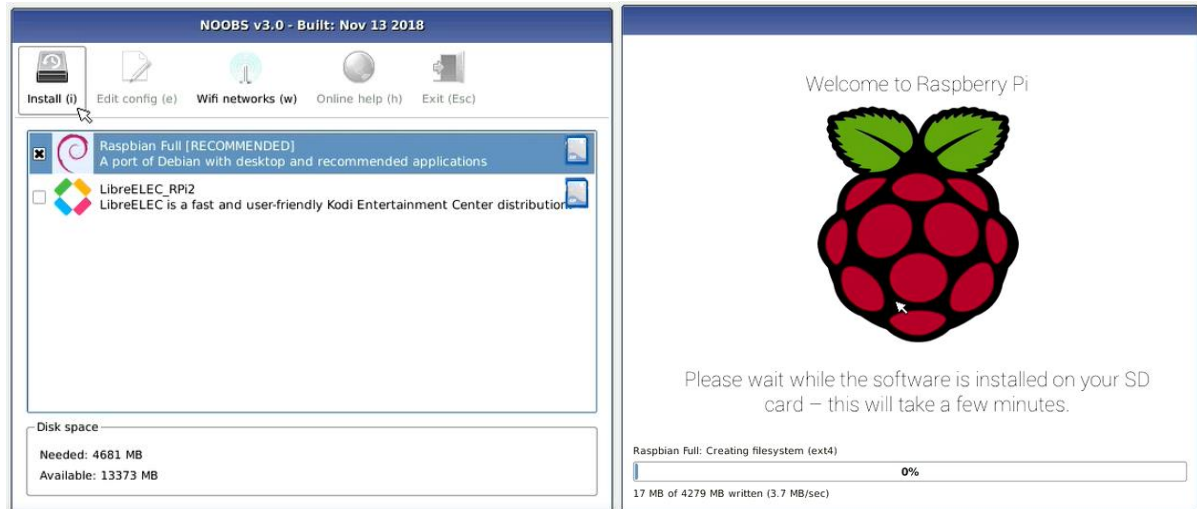
#### 4. First Boot & Basic Setting

**▲ Notice** Your Raspberry Pi doesn't have a power switch, only when you connect it to a power outlet, it will turn on.

You need to prepare an addition set of mouse, key broad, and screen in order to connect the Raspberry Pi. Plug the USB power supply into a socket and connect it to your Raspberry Pi's power port. The steps are as follow:

- Choose raspbian operating system
- Wait for installation
- Have basic settings done, Wi-Fi connection is recommended
- For full info, visit: <https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up/5>
- Settings info for: <https://projects.raspberrypi.org/en/projects/raspberry-pi>

## setting-up/6

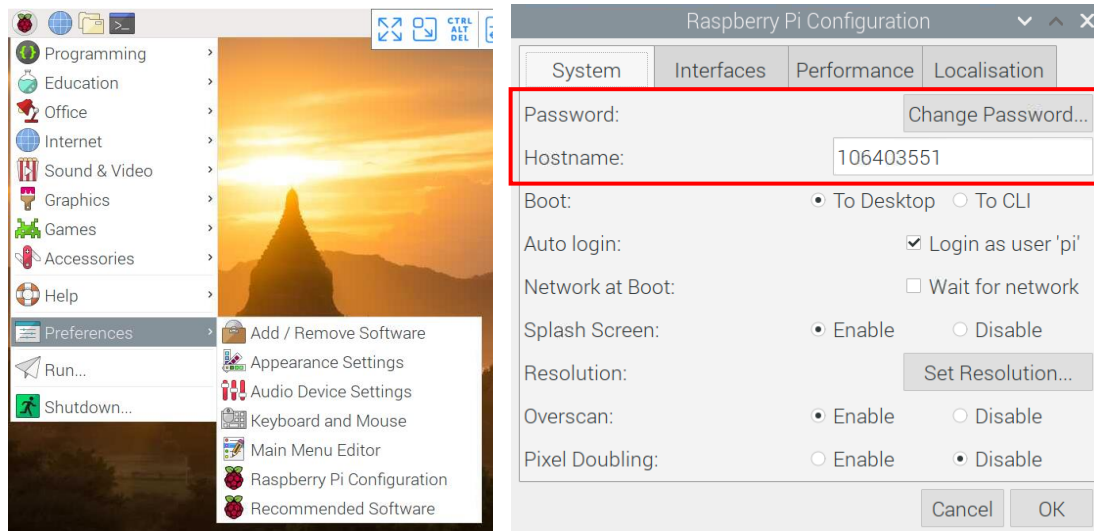


After booting, the Raspbian Desktop will appear.



## 5. First Login

Now you have logged in with root user “pi”, remember to set its password. Go to “Preferences > Raspberry Pi Configuration” or enter `raspi-config` in terminal. See more at <https://www.raspberrypi.org/documentation/linux/usage/users.md> and <https://www.raspberrypi.org/documentation/configuration/raspi-config.md>.



## 6. Remote Raspberry Pi with VNC Viewer

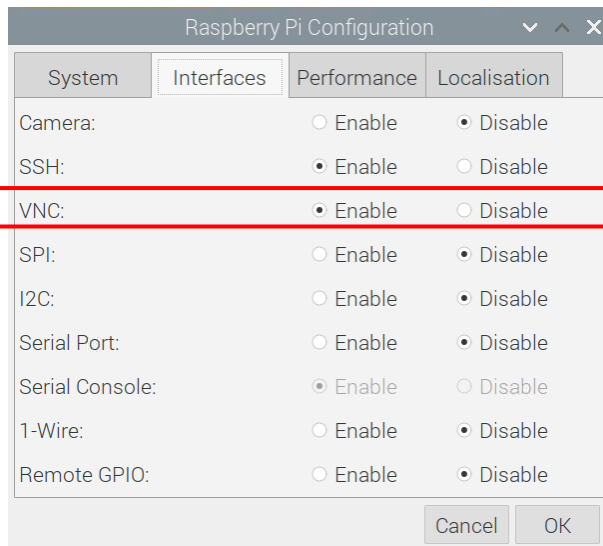
Is it inconvenient to control raspberry pi with an additional mouse and monitor?  
Let's try VNC Viewer, a remote-control application.

To do with VNC viewer, follow the steps below:

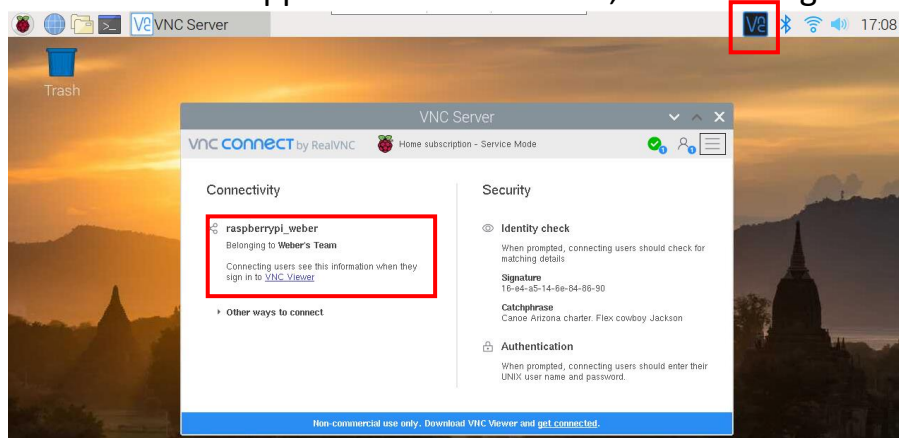
- Register a VNC account
- Enable VNC on raspberry pi
- Login your VNC account on raspberry pi
- Install VNC viewer on PC and login
- Start connecting

Download and register at: <https://www.realvnc.com/en/connect/download/viewer/>.

Go to "Preferences > Raspberry Pi Configuration" or enter `raspi-config` in terminal. Find the VNC setting and make it work.



A VNC icon will appear on the menu bar, click it to login.



Last, login your account on PC's VCN viewer, enter the hostname, the root account "pi" and its root password. Feel free to remote the Raspbian.

**▲ Notice** Make sure your Raspbian Pi has the access to Wi-Fi, or you won't be able to remote it by VNC. It will be definitely a disaster. Insure that it is connected to your smart phone hot spot at least.

## 7. Edit the config.txt for Video Output

Tutor: <https://www.raspberrypi.org/documentation/configuration/config-txt/>

Details: <https://www.raspberrypi.org/documentation/configuration/config-txt/video.md>

Process: <https://www.makeuseof.com/tag/edit-boot-config-file-raspberry-pi/>

The default video output for Raspbian Pi is terrible. Access the *config.txt* file to select a better output. You can have this done via editing config.txt file, or via entering `raspi-config` in terminal by using GUI to change video settings, or via

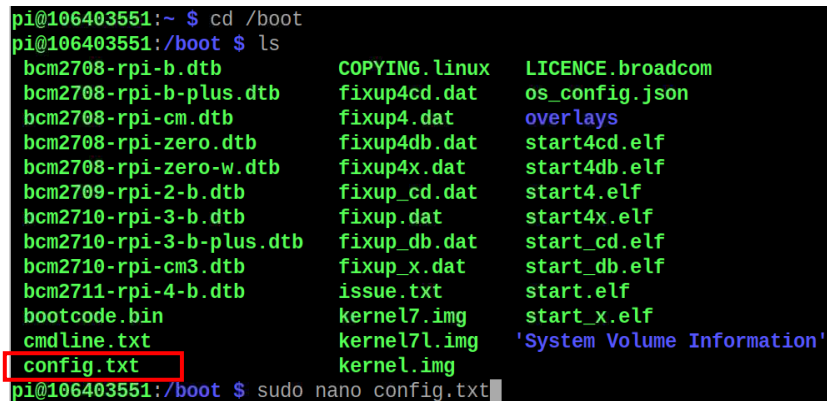
reading the SD card by PC/Mac and edit the file directly.

The Raspberry Pi uses a configuration file instead of the [BIOS](#) you would expect to find on a conventional PC. The system configuration parameters, which would traditionally be edited and stored using a BIOS, are stored instead in an optional text file named *config.txt*.

**▲ Notice** This file is normally accessible as `/boot/config.txt` from Linux, and must be edited as [root](#).

Go to terminal, use nano (a Linux editor) to edit config.txt, tap

```
cd /boot
sudo nano config.txt
```



```
pi@106403551:~ $ cd /boot
pi@106403551:/boot $ ls
bcm2708-rpi-b.dtb      COPYING.linux      LICENCE.broadcom
bcm2708-rpi-b-plus.dtb  fixup4cd.dat      os_config.json
bcm2708-rpi-cm.dtb     fixup4.dat         overlays
bcm2708-rpi-zero.dtb   fixup4db.dat      start4cd.elf
bcm2708-rpi-zero-w.dtb fixup4x.dat        start4db.elf
bcm2709-rpi-2-b.dtb    fixup_cd.dat       start4.elf
bcm2710-rpi-3-b.dtb    fixup.dat          start4x.elf
bcm2710-rpi-3-b-plus.dtb fixup_db.dat       start_cd.elf
bcm2710-rpi-cm3.dtb    fixup_x.dat        start_db.elf
bcm2711-rpi-4-b.dtb    issue.txt          start.elf
bootcode.bin           kernel7.img         start_x.elf
cmdline.txt             kernel7l.img        'System Volume Information'
config.txt              kernel.img
```

Uncomment `hdmi_group` and set it for DMT (Display Monitor Timings) standard

```
# Set monitor mode to DMT
hdmi_group=2
```

Uncomment `hdmi_mode` and set it for 1280x720 in resolution at 60Hz

```
Hdmi_mode=85
```

Uncomment `hdmi_drive` and set it to be normal hdmi mode

```
hdmi_drive=2
```

Once the changes have been made, press **Ctrl + X** to save and exit. Remember to reboot your Raspberry Pi after making changes.

```
Ctrl + O (save)
Enter (edit filename)
```

Ctrl + X

```
# uncomment if hdmi display is not detected and composite is being output
hdmi_force_hotplug=1

# uncomment to force a specific HDMI mode (this will force VGA)
hdmi_group=2
hdmi_mode=85

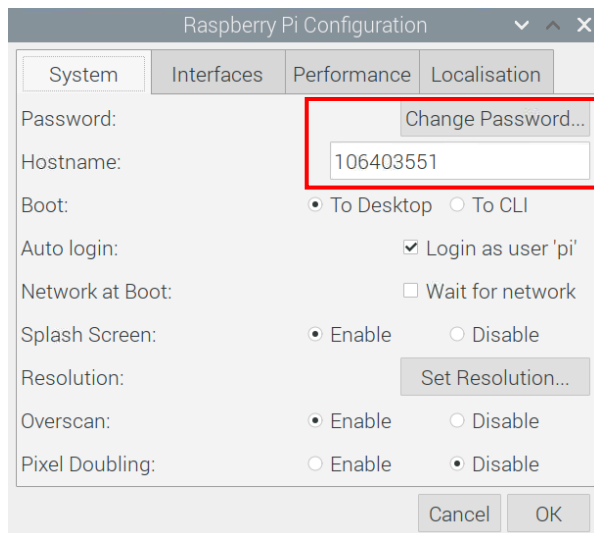
# uncomment to force a HDMI mode rather than DVI. This can make audio work in
# DMT (computer monitor) modes
hdmi_drive=2
```

^G Get Help   ^O Write Out   ^W Where Is   ^K Cut Text   ^J Justify   ^C Cur Pos  
^X Exit   ^R Read File   ^\ Replace   ^U Uncut Text   ^T To Spell   ^\_ Go To Line

## 8. Reset Hostname & Create New Root User

Official document: <https://www.raspberrypi.org/documentation/configuration/raspi-config.md>

Set the host name to an identical name in order not to be hacked, for instance, your student number. Go to “Preferences > Raspberry Pi Configuration” or enter `raspi-config` in terminal.



For security reason, do not use the root account “pi” to often, create a new user with root permission. Next week we’ll use this new user to install python environment.



Full Docs visit <https://www.raspberrypi.org/documentation/linux/usage/users.md>.

## Add user

```
sudo add user weber
```

Switch to the root user, make weber as sudoer

```
sudo su  
sudo visudo
```

Then edit the file in /etc/sudoers

```
# User privilege specification  
root  ALL=(ALL:ALL) ALL  
weber  ALL = NOPASSWD: ALL
```

<b>▲ Notice</b>	Be careful, it's possible to remove your own sudo rights by accident.
-----------------	---

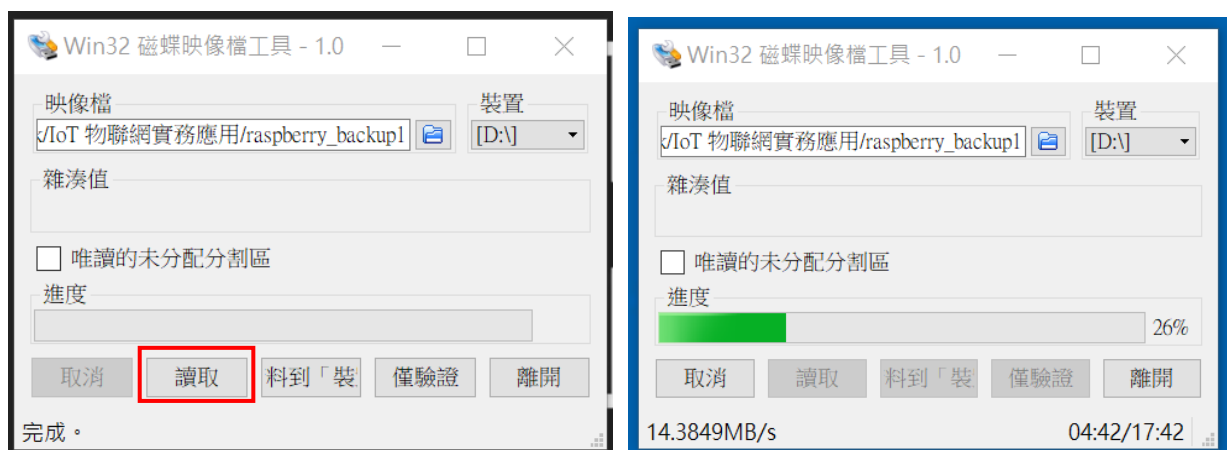
# Preparation for Python: Installing Package Manager Conda & Editor Jupyter Notebook

## 1. Back up your Raspbian OS (Optional)

It might be frustrating when raspberry pi got crashed during your programming time, or the testing phrase. Try to back up the OS, its environment and accounts. You may restore your OS if by any chance.

There are 3 main ways to back up raspberry pi, copying the entire SD card image is the most direct method, you may find other 2 ways at [here](#), or [Chinese ver.](#)

First, take out the SD card. Then download [Win32 Disk Imager](#), enter filename you want to keep, click “read”, and it’s done.



Click “write” to write an image file back to SD card if restore is needed. You have to format the SD card before restoring it.



▲ Notice It might take over 15(30) minutes to copy(restore) the 16G SD card.

## 2. Download & Install Conda with New User

To run python on your raspberry pi, we should have our own python package manager, *pip* or *conda*. Some of the functionality of these two tools overlap, but *pip* has the latest version of python package, *conda* may contain software written in any language. To see more differences between *pip* and *conda*, click [here](#).

Here we choose *conda* as our package manager tool. There are 3 kinds of *condas*: *Anaconda*, *Miniconda*, and *Berryconda* respectively.

- [Anaconda](#): With 150+ packages install at once, but storage costing.
- [Miniconda](#): Only few packages, must download others manually.
- [Berryconda](#): Same as *miniconda*, more suitable for raspberry pi.

After comparing these *condas*, install *Berryconda* by the construction of github site. Visit <https://github.com/jjhelmus/berryconda>.

First download the file using the raspberry terminal, then execute it.

```
chmod +x Berryconda3-2.0.0-Linux-armv7l.sh
```

```
./Berryconda3-2.0.0-Linux-armv7l.sh
```

You can execute the following codes as well. [Reference](#).

```
wget
```

```
https://github.com/jjhelmus/berryconda/releases/download/v2.0.0/Berryconda3-2.0.0-Linux-armv7l.sh
```

```
bash Berryconda3-2.0.0-Linux-armv7l.sh
```

Remember to use default settings and path, please choose “yes” for all the options. The setting processes would be:

▲ Notice	You should complete these processes with the “new user account” created on previous step. And make sure it’s installed under the “new user folder”. Finally, do NOT use “sudo” statement, or you may have to gain root privilege every time while accessing <i>berryconda</i> .
----------	---

\*Switching use by `su - username` (change folder as well), or `su username` (using current folder).

\*Check your python version after installing *conda*, because it’ll automatically change default python path to its python 3.

- Before:

```
weber@106403551:/home/pi $ python -V
Python 2.7.16
weber@106403551:/home/pi $ python3 -V
Python 3.7.3
weber@106403551:/home/pi $ pip -V
^[[A^[[Cpip 18.1 from /usr/lib/python2.7/dist-packages/pip (python 2.7)
weber@106403551:/home/pi $ pip3 -V
pip 18.1 from /usr/lib/python3/dist-packages/pip (python 3.7)
```

- After:

```
weber@106403551:~ $ python -V
Python 3.6.1
```

### 3. Install Jupyter Notebook

As the saying goes, “Good craftsmanship depends on use of the right tools.” Before starting on python programming, we still need an editing tool. It is Jupyter Notebook.

Enter `conda install -c rpi jupyter` to install it. `-c` or `--channel` means select a channel, `rpi` means for raspberry pi.

```
weber@106403551:~ $ conda install -c rpi jupyter
Fetching package metadata .....
Solving package specifications: .

Package plan for installation in environment /home/weber/berryconda3:

The following NEW packages will be INSTALLED:

    backcall:          0.1.0-py_0
    bleach:            2.1.4-py_1
    decorator:         4.3.0-py_0
```

Enter “y” to continue download. As we use berryconda, a kind of mini conda, we should install packages related with Jupyter.

```
The following packages will be UPDATED:

    conda:              4.3.22-py36_0      --> 4.5.11-py36_0
    conda-env:          2.6.0-0            --> 2.6.0-1
    pycosat:            0.6.1-py36_0      --> 0.6.3-py36hdf2a78_1

Proceed ([y]/n)? y

conda-env-2.6. 100% |#####| Time: 0:00:00 269.81 kB/s
libsodium-1.0. 100% |#####| Time: 0:00:03 305.77 kB/s
```

## 4. Create a virtual environment using Conda (Optional 2)

▲ Notice Remember to switch the virtual environment to “ipykernel\_py3”, install these packages in “ipykernel\_py3”.

Using Conda to create a virtual environment, in which you will use conda to install a number of packages. Note that although having a virtual environment is optional, it is recommended for managing different python environments.

Packages required:

- numpy
- scipy
- matplotlib
- pandas
- scikit-learn
- seaborn
- rpi.gpio (This is not available in conda repository. Use pip to install it)

Open the terminal, install packages at once by

```
conda install -c rpi numpy scipy matplotlib pandas scikit-learn seaborn
pip install RPi.GPIO
```

Your terminal will look like:

```
(ipykernel_py3) weber@106403551:~ $ conda env list
# conda environments:
#
base                        /home/weber/berryconda3
ipykernel_py2              /home/weber/berryconda3/envs/ipykernel_py2
ipykernel_py3              * /home/weber/berryconda3/envs/ipykernel_py3
(ipykernel_py3) weber@106403551:~ $ conda install -c rpi numpy scipy matplotlib pandas sci
kit-learn seaborn
Solving environment: / █
```

## 5. Make the kernel in virtual environment available in Jupyter notebook (Optional 3)

Chinese Tutor: <https://medium.com/datainpoint/jupyter-kernels-3151a6408bab>

Ipython docs: [https://ipython.readthedocs.io/en/stable/install/kernel\\_install.html](https://ipython.readthedocs.io/en/stable/install/kernel_install.html)

List all the conda virtual environment and jupyter kernel, there should be python 3 for base environment initially.

```
conda env list
jupyter kernelspec list
```

Create a new conda virtual environment and jupyter kernel, which name is “ipykernel\_py3”.

```
conda create -n ipykernel_py3 python=3 ipykernel
source activate ipykernel_py3
python -m ipykernel install --user
```

If you want to activate an exist virtual environment, just enter

```
source activate envname
```

When you activate a virtual environment, there will be a virtual environment surrounded with parentheses.

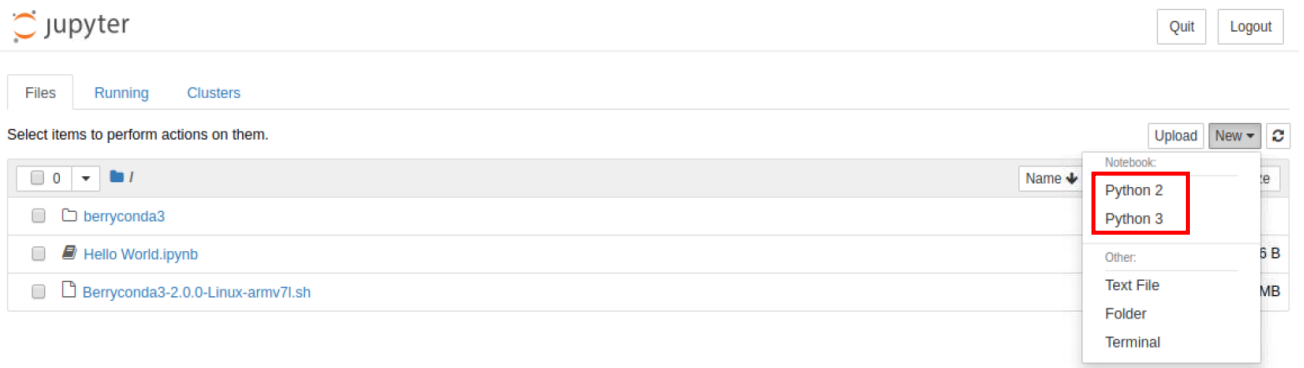
```
pi@106403551:~ $ su - weber
Password:
weber@106403551:~ $ source activate ipykernel_py3
(ipykernel_py3) weber@106403551:~ $
```

Check the environment again, you’ll find a new python 3 environment and new kernel.

```
(ipykernel_py3) weber@106403551:~ $ conda env list
# conda environments:
#
base                /home/weber/berryconda3
ipykernel_py2       /home/weber/berryconda3/envs/ipykernel_py2
ipykernel_py3      * /home/weber/berryconda3/envs/ipykernel_py3
```

```
(ipykernel_py3) weber@106403551:~ $ jupyter kernelspec list
Available kernels:
python2  /home/weber/.local/share/jupyter/kernels/python2
python3  /home/weber/.local/share/jupyter/kernels/python3
```

Now run jupyter notebook again, a python 3 environment is well done.



To deactivate the environment when you want to close the server.

```
source deactivate
```

## 6. Run a Jupyter Notebook with the above installed packages

**▲ Notice** Remember to switch the virtual environment to “ipykernel\_py3”, the required packages are in it.

Full tutor: <https://realpython.com/jupyter-notebook-introduction/#installation>

Once you install jupyter notebook, why not try to run a simple program? Follow the steps on terminal.

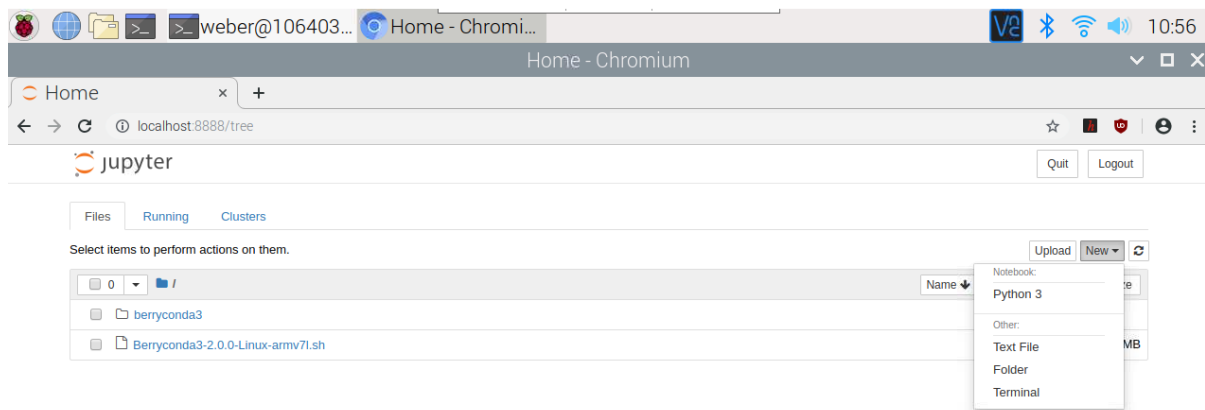
```
jupyter notebook
```

```
weber@106403551:~ $ jupyter notebook
[I 10:53:14.676 NotebookApp] Writing notebook server cookie secret to /home/weber/.local/share/jupyter/runtime/notebook_cookie_secret
[I 10:53:17.043 NotebookApp] Serving notebooks from local directory: /home/weber
[I 10:53:17.043 NotebookApp] The Jupyter Notebook is running at:
[I 10:53:17.044 NotebookApp] http://localhost:8888/?token=b73183373d61d5daccf969745eb246f4cfeaacf0c0b1aa81
[I 10:53:17.044 NotebookApp] Use Control-C to stop this server and shut down all kernels (twice to skip confirmation).
[W 10:53:17.046 NotebookApp] No web browser found: could not locate runnable browser.
[C 10:53:17.047 NotebookApp]

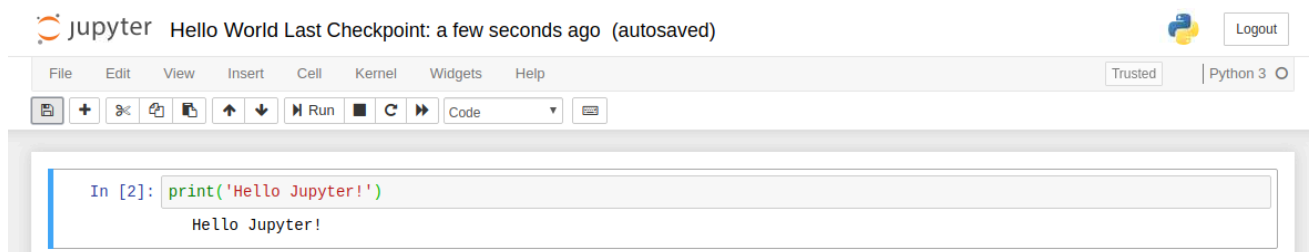
Copy/paste this URL into your browser when you connect for the first time,
to login with a token:
http://localhost:8888/?token=b73183373d61d5daccf969745eb246f4cfeaacf0c0b1aa81
[I 10:54:04.802 NotebookApp] 302 GET /?token=b73183373d61d5daccf969745eb246f4cfeaacf0c0b1aa81 (:::1) 4.22ms
```

This will start up Jupyter and your default browser should start (or open a new tab) to the following URL: <http://localhost:8888/tree>.

Your browser should now look something like this:



A Notebook's cell defaults to using code whenever you first create one, and that cell uses the kernel that you chose when you started your Notebook. Add some python code to run the cell.



Enter CTRL + C to shutdown the notebook. Have fun!

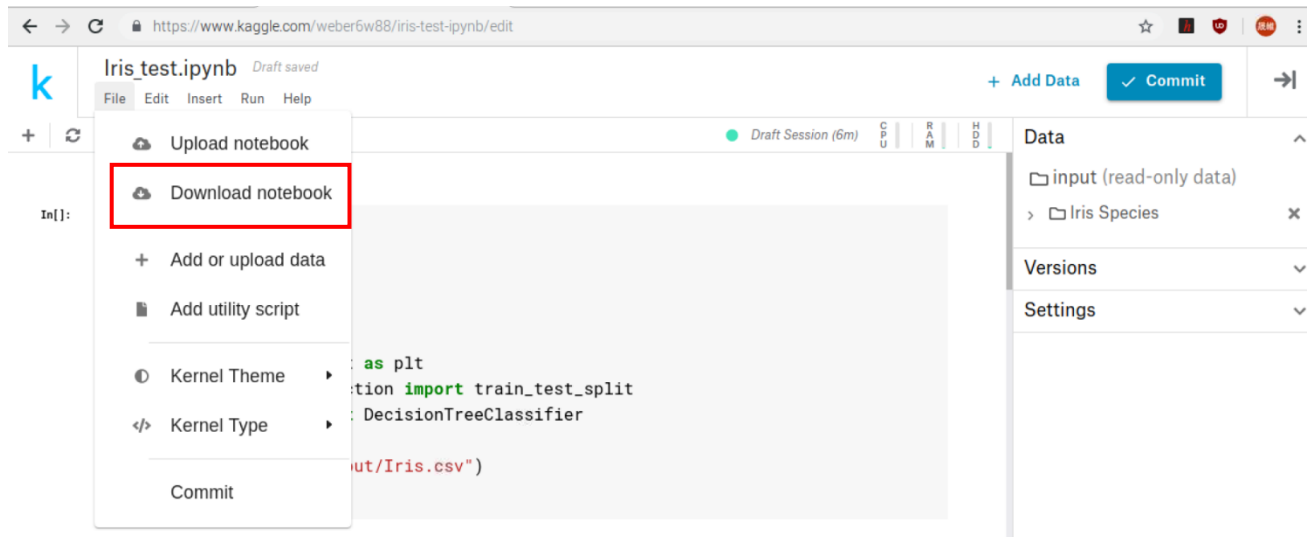
## 7. Fork a Jupyter Note from Kaggle and run it on your RPi (Optional 4)

One of the advantages of jupyter notebook is you could utilize the cloud. As a result, you could download a notebook from the cloud. Let's begin an easy demonstration.

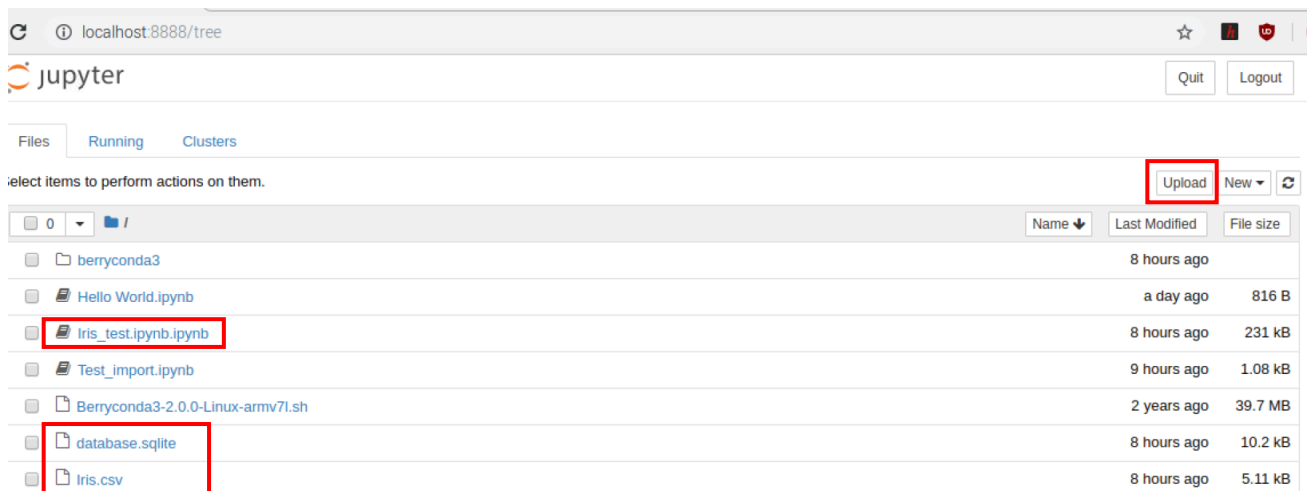
First, we need to sign up a [Kaggle](https://www.kaggle.com/) account. It is a community of data science. Kaggle got its start by offering machine learning competitions and now also offers a public data platform, a cloud-based workbench for data science.

Log in with google chrome on the Raspbian Pi. Then visit the example notebook <https://www.kaggle.com/alexela12345/iris-test-ipynb>. Login Kaggle and click copy and edit to fork the sample codes, the notebook will appear in your Kaggle account, and you can also download the file into the Raspbian Pi.

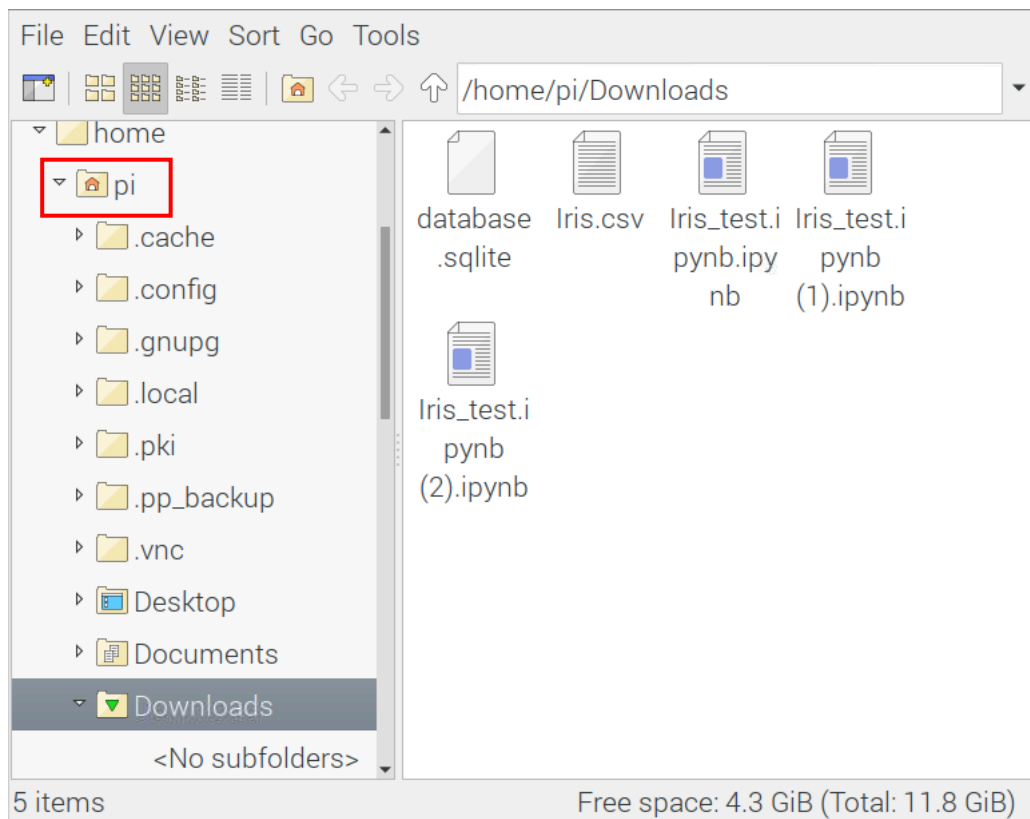




Next, download and update the data as well. Download “Iris.csv” and “database.sqlite” from the sample website. Go back to homepage of Jupyter notebook, click the “upload” button to upload these 2 files and the “Iris\_test.ipynb” notebook file. Congratulate! Here the preparing process ends.



**⚠ Notice** Chrome will download the files in root user “pi” folder. Not in the current “weber” folder.



Now, run the program cell by cell, the result will look like as follow.

```
In [1]: %matplotlib inline

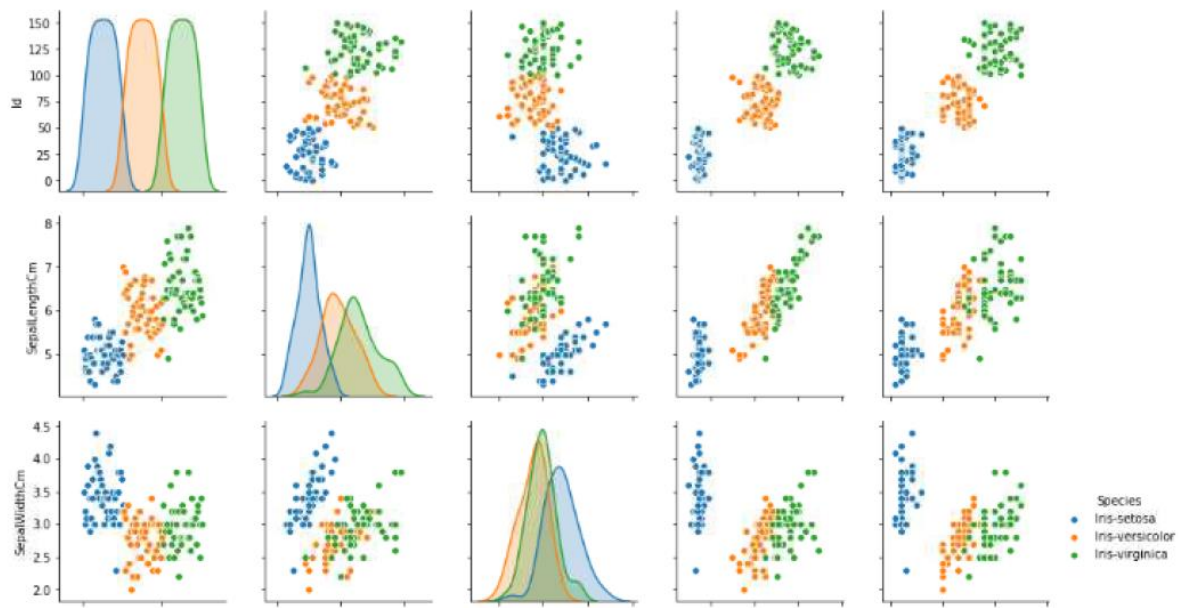
import pandas as pd
import numpy as np
import seaborn as sns
import matplotlib.pyplot as plt
from sklearn.model_selection import train_test_split
from sklearn.tree import DecisionTreeClassifier

df = pd.read_csv("./Iris.csv")

In [3]: df.isnull().any()

Out[3]: Id                False
SepalLengthCm            False
SepalWidthCm              False
PetalLengthCm            False
PetalWidthCm             False
Species                  False
dtype: bool
```

Out[7]: <seaborn.axisgrid.PairGrid at 0x66161030>



▲ Notice You have to change the path of the csv file.  
And you may not have the “seaborn” package installed, if not install it when error occurs.