### Chapter ML:II (continued)

### II. Machine Learning Basics

- Concept Learning: Search in Hypothesis Space
- □ Concept Learning: Version Space
- □ From Regression to Classification
- Evaluating Effectiveness

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#### Simple Classification Problems

### Setting:

- $\Box$  X is a multiset of feature vectors.
- $C = \{\text{no, yes}\}\$ is a set of two classes. Similarly:  $\{0,1\}, \{-1,1\}, \{\ominus, \oplus\},$  "belongs to a concept or not", etc.
- $D = \{(\mathbf{x}_1, c_1), \dots, (\mathbf{x}_n, c_n)\} \subseteq X \times C$  is a multiset of examples.

#### Learning task:

 $\Box$  Fit D using a filter function y() for feature value combinations.

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#### Example Learning Task

X contains vectors encoding the weather in the six dimensions "Sky", "Temperature", "Humidity", "Wind", "Water", and "Forecast". D contains examples of weather conditions  $\mathbf{x} \in X$  along with a statement whether or not our friend will enjoy her favorite sport (surfing):

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
1	sunny	warm	normal	strong	warm	same	yes 1
2	sunny	warm	high	strong	warm	same	yes 1
3	rainy	cold	high	strong	warm	change	no 0
4	sunny	warm	high	strong	cool	change	yes 1

What is the extensional definition of the concept (class) "EnjoySport"?

- → What is an intensional definition of the concept (class) "EnjoySport"?
- → What are hypotheses that capture the concept (class) "EnjoySport"?

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#### Remarks (concept):

- □ A concept (a class) can be described by an intensional or an extensional definition, which gives meaning to the concept (the class). [Wikipedia]
   An intensional definition gives meaning by specifying necessary and sufficient conditions for the concept. An extensional definition gives meaning to a concept by specifying its extension,
- $\Box$  Within a learning task, a concept is (usually incompletely) defined by means of D, which contains examples from which a subset falls under the definition of the concept in question. I.e., D gives us an incomplete, extensional definition of the concept.

that is, every object that falls under the definition of the concept in question.

In the exemplary learning task the population is comprised of the combinations of possible weather conditions in the six dimension (see the feature domains below). The concept is the subset of the population that contains exactly those weather conditions when surfing is enjoyed.

Domains of the features in the learning task:

Sky	Temperature	Humidity	Wind	Water	Forecast
sunny	warm	normal	strong	warm	same
rainy	cold	high	light	cool	change
cloudy					

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#### Remarks (hypothesis):

- Recap. A hypothesis is a proposed explanation for a phenomenon. [Wikipedia] Here, a hypothesis "explains" (= fits) the data D. Hence, a concrete model function y(), y(), or, if the function type is clear from the context, its parameters w or  $\theta$  are called "hypothesis". The variable name h (similarly:  $h_1$ ,  $h_2$ ,  $h_i$ , h', etc.) may be used to refer to a specific instance of a model function or its parameters.
- □ A hypothesis is expected to "capture a (target) concept", to "explain a (target) concept", or to "predict a (target) concept" in terms of the feature expressions of the objects.
- □ The "quality", the "persuasiveness", or the "power" of a hypothesis depends on its capability to represent (= to fit) a given set of observations, which are called examples here.
- □ In our learning setting, a hypothesis cannot be inferred or proven by deductive reasoning. Rather, a hypothesis is a finding or an insight gained by *inductive reasoning*.

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Simple Classification Problems (continued)

#### **Definition 1 (Concept, Hypothesis, Hypothesis Space)**

Let O be a set of objects,  $\mathbf{X}$  the feature space constructed with a model formation function  $\alpha: O \to \mathbf{X}$ , and  $X = \{\mathbf{x} \mid \mathbf{x} = \alpha(o), o \in O\}$  be a multiset of feature vectors.

A concept is a subset of O and hence induces a subset  $X' \subseteq X$ . Concept learning means learning the indicator function for X', which returns 1 if  $\mathbf{x} \in X'$  and 0 otherwise, from an example set D.

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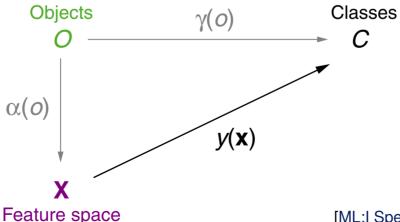
Simple Classification Problems (continued)

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Here, a hypothesis is a filter function  $y: X \to \{0, 1\}$ . The set H of possible hypotheses (filter functions) is called hypothesis space.



[ML:I Specification of Learning Problems]

Simple Classification Problems (continued)

The example set D,  $D = \{(\mathbf{x}_1, c_1), \dots, (\mathbf{x}_n, c_n)\}$ , contains usually both positive (c = 1) and negative (c = 0) examples. [learning task]

#### **Definition 2 (Classified as Positive, Consistent)**

Let y() be a concrete model function (hypothesis).

An example  $(\mathbf{x}, c)$  is classified as positive by y() iff  $y(\mathbf{x}) = 1$ .

y() is consistent with an example  $(\mathbf{x},c)$  iff  $y(\mathbf{x})=c$ .

y() is consistent with a set D of examples, denoted as consistent(y(),D), iff:

$$\forall (\mathbf{x}, c) \in D : y(\mathbf{x}) = c$$



- □ The string "Iff" or "iff" is an abbreviation for "If and only if", which means "necessary and sufficient". It is a textual representation for the logical biconditional, also known as material biconditional or iff-connective. The respective symbol is "↔". [Wolfram] [Wikipedia]
- The fact that a hypothesis is consistent with an example can also be described the other way round: an example is consistent with a hypothesis.
- Given an example  $(\mathbf{x}, c)$ , notice the difference between (1) classified as positive and (2) being consistent with a hypothesis. The former asks for  $y(\mathbf{x}) = 1$ , disregarding the actual target concept value c. The latter asks for the identity between the target concept c and  $y(\mathbf{x})$ .
- The consistency of  $y(\mathbf{x})$  can be analyzed for a single example as well as for a set D of examples. Given the latter, consistency requires that  $y(\mathbf{x}) = 1$  iff c = 1, for all  $(\mathbf{x}, c) \in D$ . This is equivalent with the condition that  $y(\mathbf{x}) = 0$  iff c = 0, for all  $(\mathbf{x}, c) \in D$ .
- Learning means to determine a model function  $y() \in H$  that is consistent with D. Similarly: Machine learning means to systematically search the hypothesis space.

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Simple Classification Problems (continued)

### Structure of the model function y():

- a propositional logic conjunction of feature value matches
- $\Box$  three kinds of parameter values  $\theta$ : literal, ? (wildcard),  $\bot$  (contradiction)

$$y(\mathbf{x}) = \mathcal{I}(\theta_1 \doteq x_1 \land \theta_2 \doteq x_2 \land \dots \land \theta_6 \doteq x_6)$$

$\mathcal{I}(\theta \doteq x)$	$\theta$	x
1	$literal_{ heta} =$	$=$ literal $_x$
0	literal $_{ heta}$ $ eq$	$\neq$ literal $_x$
1	?	$literal_x$
0	Т	$literal_x$

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Simple Classification Problems (continued)

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$\mathcal{I}(\theta \doteq x)$	$\theta$	x
1	$ $ literal $_{ heta}$ =	$=$ literal $_x$
0	$ $ literal $_{ heta}$ $=$	$ \neq$ literal $_x$
1	?	$literal_x$
0		$literal_x$

A hypothesis for EnjoySport [learning task]:  $\theta = (sunny, ?, ?, strong, ?, same)$ 

$$\rightarrow \forall (\mathbf{x}, c) \in D : y(\mathbf{x}) = c$$

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#### Remarks:

- $\square$   $\mathcal{I}$  denotes the standard interpretation function, which returns for a propositional formula  $\alpha$  its truth value:  $\alpha \mapsto \mathcal{I}(\alpha), \ \mathcal{I}(\alpha) \in \{0,1\}.$
- □ Depending on the learning task—more specifically: on the structure of the feature space—a hypothesis (the model function, the model) can take different forms. Examples:
  - rules (as done here)
  - analytical functions (typical for regression settings)
  - decision trees (typical for categorical domains)
  - probability mass functions (in Bayesian learning)

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Simple Classification Problems (continued)

#### **Definition 3 (Maximally Specific / General Hypothesis)**

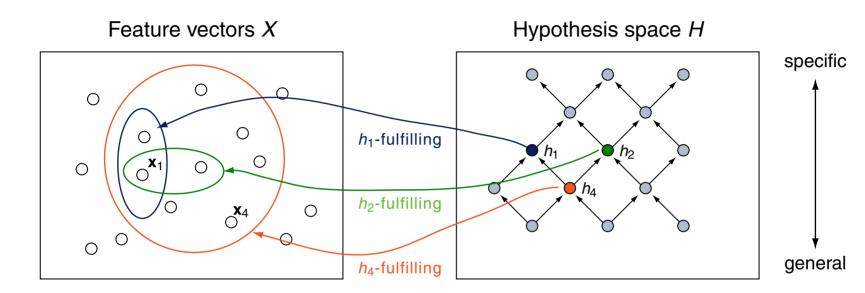
The special filter functions  $y_{s_0}() \equiv 0$  and  $y_{g_0}() \equiv 1$  are called maximally specific and maximally general hypothesis respectively. No  $\mathbf{x} \in X$  is classified as positive by  $y_{s_0}()$ , and all  $\mathbf{x} \in X$  are classified as positive by  $y_{g_0}()$ .

Parameters of maximally specific / general hypothesis in the example [learning task]:

- $h_{g_0}: \theta = (?, ?, ?, ?, ?, ?)$  (always enjoy sport)

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### Order of Hypotheses



$$\mathbf{x}_1 = (\textit{sunny, warm, normal, strong, warm, same})$$

$$\mathbf{x}_4 = (\textit{sunny, warm, high, strong, cool, change})$$

$$h_1: y_1()$$
 with  $\theta = (sunny, ?, normal, ?, ?, ?)$ 

$$h_2: y_2()$$
 with  $\theta = (sunny, ?, ?, ?, warm, ?)$ 

$$h_4: y_4()$$
 with  $\theta = (sunny, ?, ?, ?, ?, ?)$ 

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Order of Hypotheses (continued)

#### **Definition 4 (More General Relation)**

Let X be a multiset of feature vectors and let  $y_1()$  and  $y_2()$  be two boolean-valued model functions with domain X. Then  $y_1()$  is called more general than  $y_2()$ , denoted as  $y_1() \ge_g y_2()$ , iff:

$$\forall \mathbf{x} \in X : (y_2(\mathbf{x}) = 1 \text{ implies } y_1(\mathbf{x}) = 1)$$

 $y_1()$  is called strictly more general than  $y_2()$ , denoted as  $y_1()>_q y_2()$ , iff:

$$y_1() \ge_g y_2()$$
 and  $y_2() \not\ge_g y_1()$ 

In the illustration:  $y_2(\mathbf{x}) = 1$  implies that  $y_4(\mathbf{x}) = 1$ . I.e.,  $y_4()$  is more general than  $y_1()$ .

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#### Remarks:

- $\Box$  If  $y_1()$  is more general than  $y_2()$ , then  $y_2()$  can also be called being more specific than  $y_1()$ .
- The relations  $\geq_g$  and  $>_g$  are independent of a target concept. They depend only on the fact that examples are classified as positive by a hypothesis, i.e., whether  $y(\mathbf{x}) = 1$ ,  $(\mathbf{x}, c) \in D$ . It is not required that c = 1.
- $\ \square$   $h_{s_0}$  is minimum and  $h_{g_0}$  is maximum with regard to  $\ge_g$ : no hypothesis is more specific than  $h_{s_0}$ , and no hypothesis is more general than  $h_{g_0}$ .
  - We will consider only hypothesis spaces that contain  $h_{s_0}$  and  $h_{g_0}$ .
- The  $\geq_g$ -relation defines a partial order on the hypothesis space  $H:\geq_g$  is reflexive, anti-symmetric, and transitive. The order is *partial* since (unlike in a total order) not all hypothesis pairs stand in the relation. [Wikipedia partial, total]
  - I.e., we are given hypotheses  $y_i()$ ,  $y_j()$ , for which neither  $y_i() \ge_g y_j()$  nor  $y_j() \ge_g y_i()$  holds, such as the hypotheses  $h_1$  and  $h_2$  in the illustration.

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#### Remarks (entailment):

- The semantics of the implication, in words "a implies b", denoted as  $a \to b$ , is as follows.  $a \to b$  is true if either (1) a is true and b is true, or (2) if a is false and b is true, or (3) if a is false and b is false—in short: "if a is true then b is true as well", or, "the truth of a implies the truth of b".
- " $\rightarrow$ " can be understood as "causality connective": Let a and b be two events where a is a cause for b. If we interpret the occurrence of an event as true and its non-occurrence as false, we will observe only occurrence combinations such that the formula  $a \rightarrow b$  is true. The connective is also known as material conditional, material implication, material consequence, or simply, implication or conditional.
- Note in particular that the connective " $\rightarrow$ " does not mean "entails", which would be denoted as either  $\Rightarrow$  or  $\models$ . Logical entailment (synonymously: logical inference, logical deduction, logical consequence) allows to infer or to prove a formula  $\beta$  given a formula  $\alpha$ .
  - Consider for instance the More-General-Definition: From the formula  $\alpha = "y_2(\mathbf{x}) = 1"$  we cannot infer or prove the formula  $\beta = "y_1(\mathbf{x}) = 1"$ .
- In the More-General-Definition the implication specifies a condition that is to be fulfilled by the definiendum (= the thing to be defined). The implication is used to check whether or not a thing belongs to the set of things specified by the definiens (= the expression that defines): Each pair of functions,  $y_1()$ ,  $y_2()$ , is a thing that belongs to the set of things specified by the definition of the  $\geq_q$ -relation (i.e., stands in the  $\geq_q$ -relation) if and only if the implication

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 $y_2()=1 \rightarrow y_1()=1$  is true for all  $\mathbf{x} \in X$ .

#### Remarks (entailment): (continued)

- In a nutshell: distinguish carefully between " $\alpha$  requires  $\beta$ ", denoted as  $\alpha \to \beta$ , on the one hand, and "from  $\alpha$  follows  $\beta$ ", denoted as  $\alpha \Rightarrow \beta$ , on the other hand.  $\alpha \to \beta$  is considered as a sentence from the *object language* (language of discourse) and stipulates a computing operation, whereas  $\alpha \Rightarrow \beta$  is a sentence from the *meta language* and makes an assertion *about* the sentence  $\alpha \to \beta$ , namely: " $\alpha \to \beta$  is a tautology".
- □ Finally, consider the following sentences from the object language, which are synonymous:

```
"\alpha \rightarrow \beta"
```

" $\alpha$  implies  $\beta$ "

"if  $\alpha$  then  $\beta$ "

" $\alpha$  causes  $\beta$ "

" $\alpha$  requires  $\beta$ "

" $\alpha$  is sufficient for  $\beta$ "

" $\beta$  is necessary for  $\alpha$ "

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Inductive Learning Hypothesis

"Any hypothesis found to approximate the target function well over a sufficiently large set of training examples will also approximate the target function well over other unobserved examples."

[p.23, Mitchell 1997]

#### Find-S Algorithm

```
1. y()=h_{s_0} // y() is a maximally specific hypothesis in H.

2. FOREACH (\mathbf{x},c)\in D DO

IF c=1 THEN // Learn only from positive examples.

IF y(\mathbf{x})=0 DO

y()=\min_{}generalization(y(),\mathbf{x}) // Relax y() wrt.x.

ENDIF

ENDIF

ENDOO

3. return(y())
```

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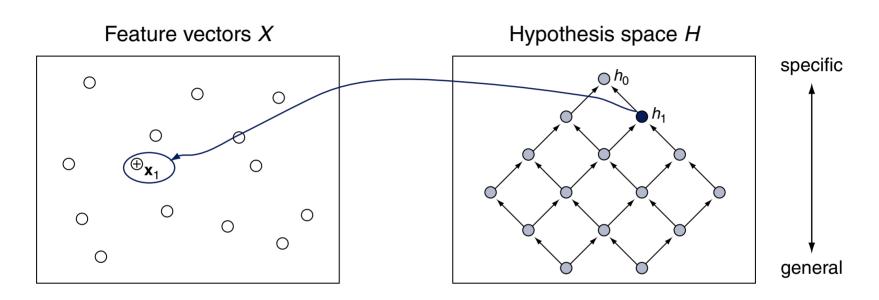
#### Remarks:

- □ Except for the first step, generalization means to substitute question marks (wildcards) for literals. Another term for "generalization" is "relaxation".
- oxdots  $min\_generalization(y(), \mathbf{x})$  returns a function y'() that is minimally generalized wrt. y() and that is consistent with  $(\mathbf{x}, 1)$ . Denoted formally:
  - $y'() \ge_g y()$  and  $y'(\mathbf{x}) = 1$ , and there is no y''() with  $y'(\mathbf{x}) >_g y''() \ge_g y()$  with  $y''(\mathbf{x}) = 1$ .
- $\Box$  For more complex hypothesis structures the relaxation of y(),  $min\_generalization(y(), \mathbf{x})$ , may not be unique. In such a case one of the alternatives has to be chosen.
- If a function y() needs to be relaxed towards some y'() with  $y'() \notin H$ , the maximally general hypothesis  $h_{q_0}$  can be added to H.
- $\Box$  Similar to  $min\_generalization(y(), \mathbf{x})$ , a function  $min\_specialization(y(), \mathbf{x})$  can be defined, which returns a minimally specialized, consistent hypotheses for negative examples.

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Find-S Algorithm (continued)

See the example set *D* for the concept *EnjoySport*.



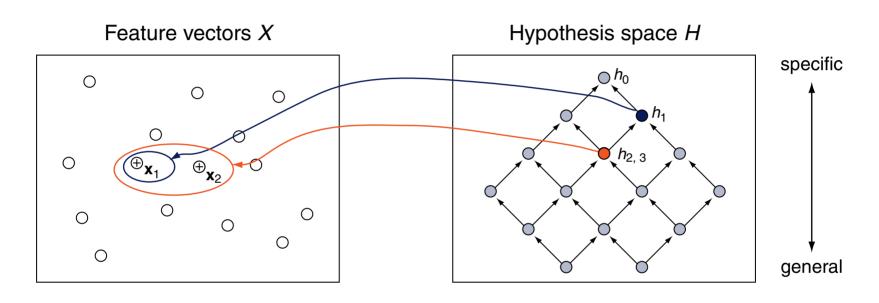
$$h_0 = h_{s_0}$$
:  $(\bot, \bot, \bot, \bot, \bot, \bot)$ 

 $\mathbf{x}_1 = (\textit{sunny}, \textit{warm}, \textit{normal}, \textit{strong}, \textit{warm}, \textit{same}) \quad h_1 : (\textit{sunny}, \textit{warm}, \textit{normal}, \textit{strong}, \textit{warm}, \textit{same})$ 

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Find-S Algorithm (continued)

See the example set *D* for the concept *EnjoySport*.



$$h_0 = h_{\underline{s_0}} : (\bot, \bot, \bot, \bot, \bot, \bot)$$

 $\mathbf{x}_1 = (\textit{sunny, warm, normal, strong, warm, same})$ 

 $\mathbf{x}_2 = (\textit{sunny, warm, high, strong, warm, same})$ 

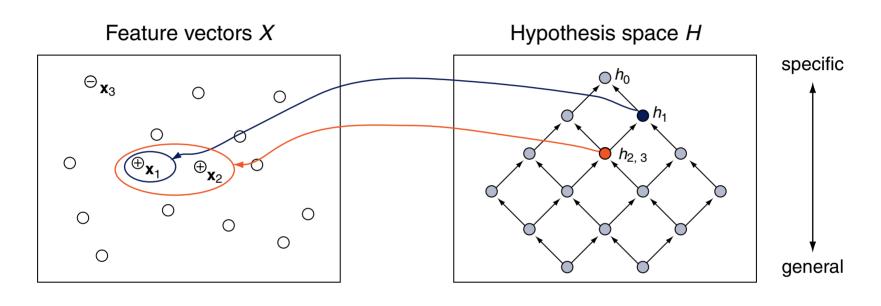
 $h_1$ : (sunny, warm, normal, strong, warm, same)

 $h_2$ : (sunny, warm, ?, strong, warm, same)

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Find-S Algorithm (continued)

See the example set *D* for the concept *EnjoySport*.



$$h_0 = h_{s_0}$$
:  $(\bot, \bot, \bot, \bot, \bot, \bot)$ 

 $\mathbf{x}_1 = (sunny, warm, normal, strong, warm, same)$ 

 $\mathbf{x}_2 = (sunny, warm, high, strong, warm, same)$ 

 $\mathbf{x}_3 = (rainy, cold, high, strong, warm, change)$   $h_3 : (sunny, warm, ?, strong, warm, same)$ 

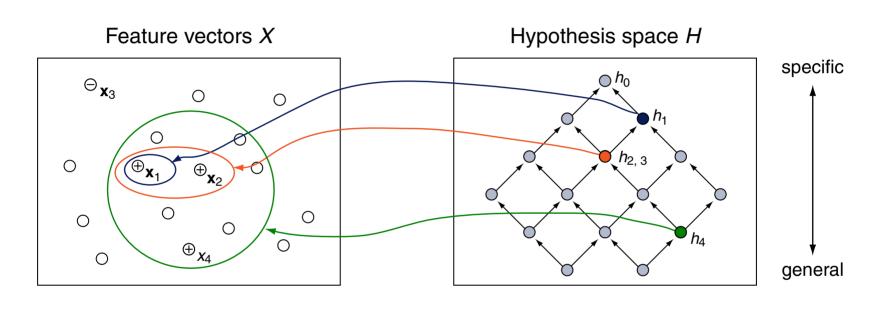
 $h_1$ : (sunny, warm, normal, strong, warm, same)

 $h_2$ : (sunny, warm, ?, strong, warm, same)

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Find-S Algorithm (continued)

See the example set *D* for the concept *EnjoySport*.



$$h_0 = h_{s_0}$$
:  $(\bot, \bot, \bot, \bot, \bot, \bot)$ 

 $\mathbf{x}_1 = (\textit{sunny}, \textit{warm}, \textit{normal}, \textit{strong}, \textit{warm}, \textit{same})$ 

 $\mathbf{x}_2 = (\textit{sunny, warm, high, strong, warm, same})$ 

 $\mathbf{x}_3 = (\textit{rainy, cold, high, strong, warm, change})$ 

 $\mathbf{x}_4 = (\textit{sunny, warm, high, strong, cool, change})$ 

 $h_1$ : (sunny, warm, normal, strong, warm, same)

 $h_2$ : (sunny, warm, ?, strong, warm, same)

 $h_3$ : (sunny, warm, ?, strong, warm, same)

 $h_4$ : (sunny, warm, ?, strong, ?, ?)

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#### Discussion of the Find-S Algorithm

- 1. Did we learn the only concept—or are there others?
- 2. Why should one pursuit the maximally specific hypothesis?
- 3. What if several maximally specific hypotheses exist?
- 4. Inconsistencies in the example set *D* remain undetected.
- 5. An inappropriate hypothesis structure or space H remains undetected.

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# **Concept Learning: Version Space**

#### **Definition** 5 (Version Space)

The version space  $H_D$ ,  $H_D \subseteq H$ , of a hypothesis space H and a example set D is comprised of all model functions  $y() \in H$  that are consistent with the set D of examples:

$$H_D = \{ y() \mid y() \in H \land (\forall (\mathbf{x}, c) \in D : y(\mathbf{x}) = c ) \}$$

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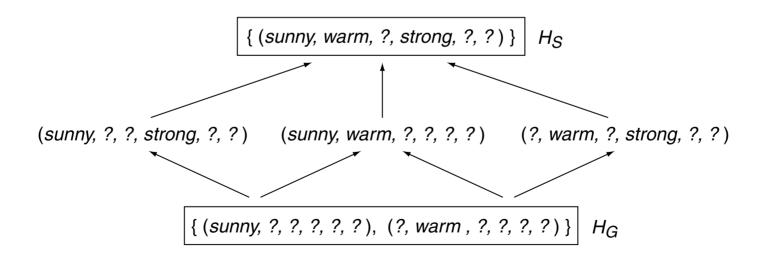
# **Concept Learning: Version Space**

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$$H_D = \{ y() \mid y() \in H \land (\forall (\mathbf{x}, c) \in D : y(\mathbf{x}) = c ) \}$$

Illustration of  $H_D$  for the example set D:



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#### Remarks:

- $\Box$  The term "version space" reflects the fact that  $H_D$  represents the set of all consistent versions of the target concept that are encoded in D.
- A naive approach for the construction of the version space is the following: (1) enumeration of all members of H, and, (2) elimination of those  $y() \in H$  where  $y(\mathbf{x}) \neq c$  for some  $(\mathbf{x},c) \in D$  holds. This approach presumes a finite hypothesis space H and is feasible only for toy problems.

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# **Concept Learning: Version Space**

#### **Definition** 6 (Boundary Sets of a Version Space)

Let H be hypothesis space and let D be set of examples. Then, based on the  $\geq_g$ -relation, the set of maximally general hypotheses,  $\underline{H}_G$ , is defined as follows:

$$H_G = \{ \ y() \mid \ y() \in H \land \ \textit{consistent}(y(), D) \land$$
  
 $(\not\exists y'() : y'() \in H \land \ y'() >_g y() \land \ \textit{consistent}(y'(), D) \ ) \ \}$ 

Similarly, the set of maximally specific (i.e., minimally general) hypotheses,  $H_S$ , is defined as follows:

$$H_S = \{y() \mid y() \in H \land consistent(y(), D) \land (\not\exists y'() : y'() \in H \land y() >_q y'() \land consistent(y'(), D) \}$$

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# **Concept Learning: Version Space**

#### **Theorem 7** (Version Space Representation)

Let X be a multiset of feature vectors,  $C = \{0,1\}$  be a set of classes, and H be a set of boolean-valued functions with domain X. Moreover, let  $D \subseteq X \times C$  be a multiset of examples.

Then, based on the  $\geq_g$ -relation, each member of the version space  $H_D$  lies between two members of  $H_G$  and  $H_S$  respectively:

$$H_D = \{ y() \mid y() \in H \land (\exists y_q() \in H_G \ \exists y_s() \in H_S : y_q() \ge_q y() \ge_q y_s() ) \}$$

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#### Remarks:

 $\Box$  The correctness of Theorem 7 is not obvious. The theorem allows us to characterize the set of all consistent hypotheses by the two boundary sets  $H_G$  and  $H_S$ .

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# **Concept Learning: Version Space**

### Candidate Elimination Algorithm [Mitchell 1997]

- 1. Initialization:  $H_G = \{h_{g_0}\}, H_S = \{h_{s_0}\}$
- 2. If x is a positive example
  - $\square$  Remove from  $H_G$  any hypothesis that is not consistent with  $\mathbf{x}$
  - fill For each hypothesis  $y_s()$  in  $H_S$  that is not consistent with f x
    - $\square$  Remove  $y_s()$  from  $H_S$
    - $\Box$  Add to  $H_S$  all minimal generalizations y() of  $y_s()$  such that
      - 1. y() is consistent with x and
      - 2. some member of  $H_G$  is more general than y()
    - $\square$  Remove from  $H_S$  any hypothesis that is less specific than another hypothesis in  $H_S$

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# **Concept Learning: Version Space**

Candidate Elimination Algorithm [Mitchell 1997] (continued)

- 1. Initialization:  $H_G = \{h_{g_0}\}, H_S = \{h_{s_0}\}$
- 2. If x is a positive example
  - $\square$  Remove from  $H_G$  any hypothesis that is not consistent with  $\mathbf{x}$
  - $\Box$  For each hypothesis  $y_s()$  in  $H_S$  that is not consistent with  $\mathbf{x}$ 
    - $\square$  Remove  $y_s()$  from  $H_S$
    - $\Box$  Add to  $H_S$  all minimal generalizations y() of  $y_s()$  such that
      - 1. y() is consistent with x and
      - 2. some member of  $H_G$  is more general than y()
    - $lue{}$  Remove from  $H_S$  any hypothesis that is less specific than another hypothesis in  $H_S$
- 3. If x is a negative example
  - $\square$  Remove from  $H_S$  any hypothesis that is not consistent with  $\mathbf{x}$
  - $oldsymbol{\Box}$  For each hypothesis  $y_g()$  in  $H_G$  that is not consistent with  ${f x}$ 
    - $\square$  Remove  $y_g()$  from  $H_G$
    - $\Box$  Add to  $H_G$  all minimal specializations y() of  $y_g()$  such that
      - 1. y() is consistent with x and
      - 2. some member of  $H_S$  is more specific than y()
    - $lue{}$  Remove from  $H_G$  any hypothesis that is less general than another hypothesis in  $H_G$

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#### Remarks:

- $\square$  All hypothesis "between" the sets  $H_G$  and  $H_S$  are consistent with all examples seen so far; i.e., they accept the positive examples and reject the negative examples.
- The basic idea of Candidate Elimination is as follows:
  - Deal with false positives. A maximally general hypothesis  $y_g() \in H_G$  tolerates the negative examples in first instance. Hence,  $y_g()$  needs to be constrained (= specialized) with regard to each negative example that is not consistent with  $y_g()$ .
  - Deal with false negatives. A maximally specific hypothesis  $y_s() \in H_S$  restricts the positive examples in first instance. Hence,  $y_s()$  needs to be relaxed (= generalized) with regard to each positive example that is not consistent with  $y_s()$ .
- The boundary set  $H_G$  of the version space summarizes the information from the previously encountered negative examples. The boundary set  $H_S$  forms a summary of the previously encountered positive examples.

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# **Concept Learning: Version Space**

Illustration of the Candidate Elimination Algorithm

$$\{(\bot,\bot,\bot,\bot,\bot,\bot)\}$$
  $H_{S_0}$ 

$$\{(?,?,?,?,?,?)\}\ H_{G_0},$$

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Illustration of the Candidate Elimination Algorithm (continued)

$$\{(?,?,?,?,?,?)\}\ H_{G_0},H_{G_1},$$

 $\mathbf{x}_1 = (sunny, warm, normal, strong, warm, same)$ 

 $EnjoySport(\mathbf{x}_1) = 1$ 

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Illustration of the Candidate Elimination Algorithm (continued)

$$\{(?,?,?,?,?,?)\}\ H_{G_0},H_{G_1},H_{G_2}$$

```
\mathbf{x}_1 = (sunny, warm, normal, strong, warm, same)
\mathbf{x}_2 = (sunny, warm, high, strong, warm, same)
```

$$EnjoySport(\mathbf{x}_1) = 1$$
  
 $EnjoySport(\mathbf{x}_2) = 1$ 

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Illustration of the Candidate Elimination Algorithm (continued)

```
 \{ (sunny, ?, ?, ?, ?), (?, warm, ?, ?, ?, ?), (?, ?, ?, ?, ?, same) \} 
 \{ (?, ?, ?, ?, ?, ?) \} 
 H_{G_0}, H_{G_1}, H_{G_2}
```

```
\mathbf{x}_1 = (sunny, warm, normal, strong, warm, same)
\mathbf{x}_2 = (sunny, warm, high, strong, warm, same)
\mathbf{x}_3 = (rainy, cold, high, strong, warm, change)
```

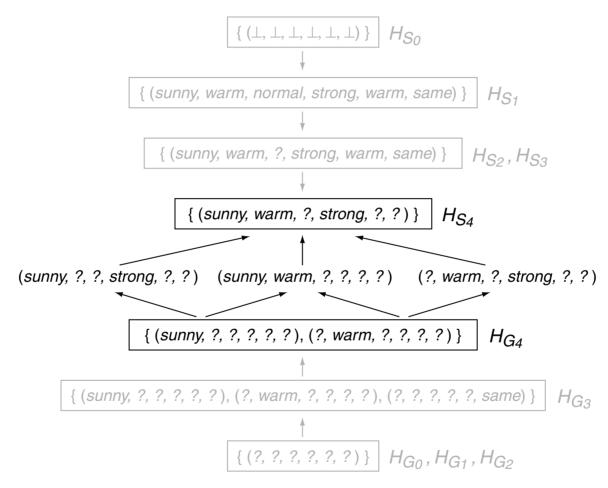
$$EnjoySport(\mathbf{x}_1) = 1$$

$$EnjoySport(\mathbf{x}_2) = 1$$

EnjoySport( $\mathbf{x}_3$ ) = 0 [feature domains] [algorithm]

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Illustration of the Candidate Elimination Algorithm (continued)



```
\mathbf{x}_1 = (\textit{sunny, warm, normal, strong, warm, same})
\mathbf{x}_2 = (\textit{sunny, warm, high, strong, warm, same})
```

$$\mathbf{x}_3 = (\textit{rainy, cold, high, strong, warm, change})$$

$$\mathbf{x}_4 = (\textit{sunny, warm, high, strong, cool, change})$$

EnjoySport(
$$\mathbf{x}_1$$
) = 1  
EnjoySport( $\mathbf{x}_2$ ) = 1  
EnjoySport( $\mathbf{x}_3$ ) = 0  
EnjoySport( $\mathbf{x}_4$ ) = 1

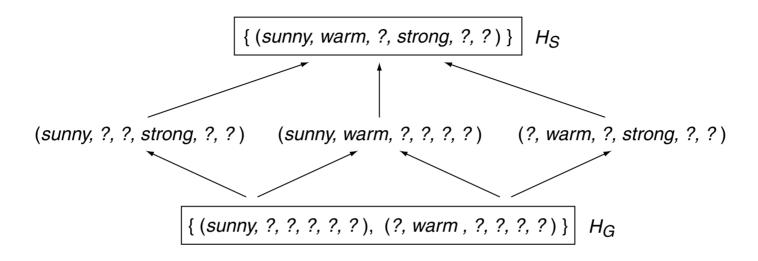
[feature domains] [algorithm]

#### Discussion of the Candidate Elimination Algorithm

- What about selecting examples from D according to a certain strategy?
   Keyword: active learning
- 2. What are partially learned concepts and how to exploit them? Keyword: ensemble classification
- 3. The version space as defined here is "biased". What does this mean? Keywords: representation bias, search bias
- 4. Will Candidate Elimination converge towards the correct hypothesis?
- 5. When does one end up with an empty version space?

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Question 1: Selecting Examples from *D* 

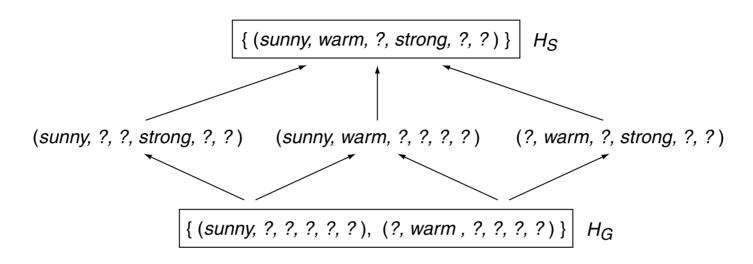


An example from which we can "maximally" learn:

 $\mathbf{x}_7 = (\textit{sunny, warm, normal, light, warm, same})$ 

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Question 1: Selecting Examples from D (continued)



#### An example from which we can "maximally" learn:

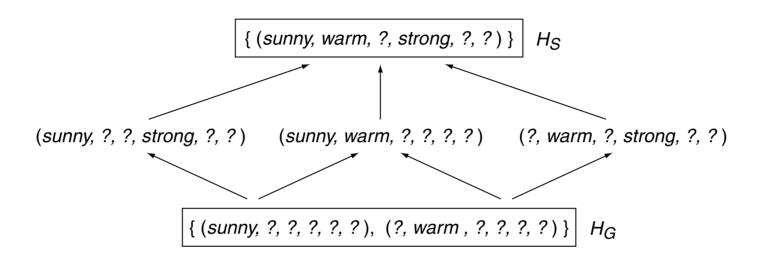
 $\mathbf{x}_7 = (\textit{sunny, warm, normal, light, warm, same})$ 

### Irrespective the value of c, $(\mathbf{x}_7, c)$ is consistent with 3 of the 6 hypotheses:

- $\Box$  If  $EnjoySport(\mathbf{x}_7) = 1$   $H_S$  can be further generalized.
- $\Box$  If  $EnjoySport(\mathbf{x}_7) = \mathbf{0}$   $H_G$  can be further specialized.

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Question 2: Partially Learned Concepts

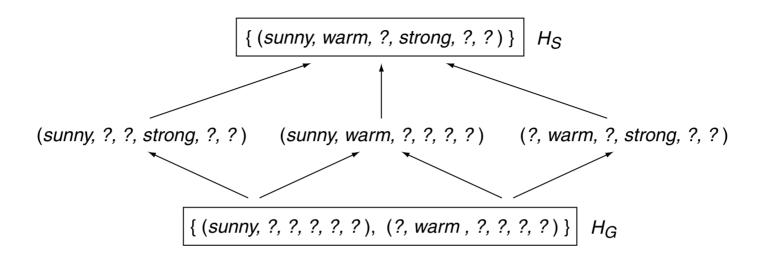


Combine the 6 classifiers in the version space to decide about new examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
5	sunny	warm	normal	strong	cool	change	
6	rainy	cold	normal	light	warm	same	
7	sunny	warm	normal	light	warm	same	
8	sunny	cold	normal	strong	warm	same	

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Question 2: Partially Learned Concepts (continued)

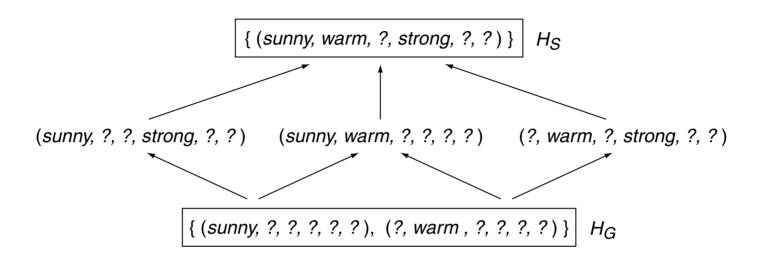


Combine the 6 classifiers in the version space to decide about new examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
5	sunny	warm	normal	strong	cool	change	6+:0-
6	rainy	cold	normal	light	warm	same	
7	sunny	warm	normal	light	warm	same	
8	sunny	cold	normal	strong	warm	same	

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Question 2: Partially Learned Concepts (continued)

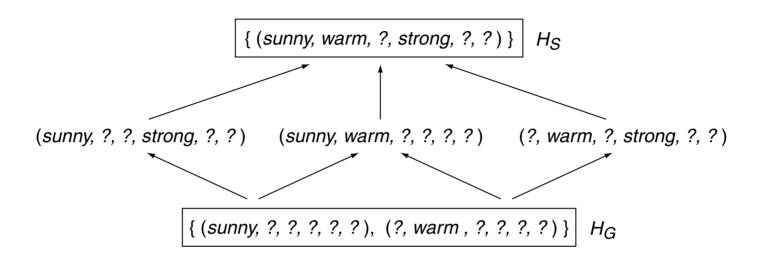


Combine the 6 classifiers in the version space to decide about new examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
5	sunny	warm	normal	strong	cool	change	6+:0-
6	rainy	cold	normal	light	warm	same	0+:6-
7	sunny	warm	normal	light	warm	same	
8	sunny	cold	normal	strong	warm	same	

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Question 2: Partially Learned Concepts (continued)

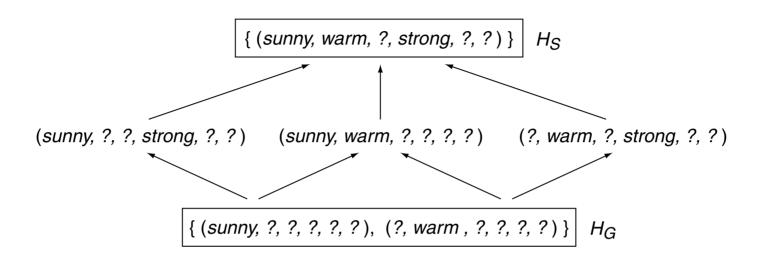


Combine the 6 classifiers in the version space to decide about new examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
5	sunny	warm	normal	strong	cool	change	6+:0-
6	rainy	cold	normal	light	warm	same	0+:6-
7	sunny	warm	normal	light	warm	same	3+:3-
8	sunny	cold	normal	strong	warm	same	

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Question 2: Partially Learned Concepts (continued)



Combine the 6 classifiers in the version space to decide about new examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
5	sunny	warm	normal	strong	cool	change	6+:0-
6	rainy	cold	normal	light	warm	same	0+:6-
7	sunny	warm	normal	light	warm	same	3+:3-
8	sunny	cold	normal	strong	warm	same	2+:4-

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Question 3: Inductive Bias

## Additional training examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
9	sunny	warm	normal	strong	cool	change	yes
10	cloudy	warm	normal	strong	cool	change	yes

 $\rightarrow$   $H_S = \{ (?, warm, normal, strong, cool, change) \}$ 

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Question 3: Inductive Bias (continued)

### Additional training examples:

9 sunny warm normal strong cool change yes 10 cloudy warm normal strong cool change yes	Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
10 cloudy warm normal strong cool change yes	9	sunny	warm	normal	strong	cool	change	yes
	10	cloudy	warm	normal	strong	cool	change	yes

$$\rightarrow$$
  $H_S = \{ (?, warm, normal, strong, cool, change) \}$ 

i

11 rainy warm normal strong cool change	no
---	----

$$\rightarrow$$
  $H_S = \{ \}$ 

#### Discussion:

What assumptions about the target concept are met by the learner a-priori?

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Question 3: Inductive Bias (continued)

## Additional training examples:

Example	Sky	Temperature	Humidity	Wind	Water	Forecast	EnjoySport
9	sunny	warm	normal	strong	cool	change	yes
10	cloudy	warm	normal	strong	cool	change	yes
	<b>→</b> H	$I_S=\{\;( extit{?, wa}$	ırm, norn	nal, stro	ng, co	ol, change	e) }
			:				
11	rainv	warm	normal	strona	cool	change	no

$$\rightarrow$$
  $H_S = \{ \}$ 

#### Discussion:

- □ What assumptions about the target concept are met by the learner a-priori?
- $\rightarrow$  *H* may be designed to contain more elaborate model functions: (sunny, ?, ?, ?, ?, ?)  $\lor$  (cloudy, ?, ?, ?, ?)

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Question 3: Inductive Bias (continued)

"The policy by which a [learning] algorithm generalizes from observed training examples to classify unseen instances is its inductive bias. [...]

Inductive bias is the set of assumptions that,
together with the training data,
deductively justify the classification by the learner to future instances."

[p.43, Mitchell 1997]

Question 3: Inductive Bias (continued)

- □ In a binary classification problem the unrestricted (= unbiased) hypothesis space contains  $|\mathcal{P}(X)| = 2^{|X|}$  elements.
- A learning algorithm that considers all possible hypotheses as equally likely makes no a-priori assumption with regard to the target concept.
- A learning algorithm without a-priori assumptions has no "inductive bias".

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Question 3: Inductive Bias (continued)

- In a binary classification problem the unrestricted (= unbiased) hypothesis space contains  $|\mathcal{P}(X)| = 2^{|X|}$  elements.
- A learning algorithm that considers all possible hypotheses as equally likely makes no a-priori assumption with regard to the target concept.
- □ A learning algorithm without a-priori assumptions has no "inductive bias".
- → A learning algorithm without inductive bias has no directive to classify unseen examples. Put another way: the learner cannot generalize.
- → A learning algorithm without inductive bias can only memorize.

Which algorithm (Find-S, Candidate Elimination) has a stronger inductive bias?

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