

Algorithms for the Constrained Longest Common Subsequence Problem with t -length Substrings *

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Abstract

The longest common subsequence (LCS) problem and its variants, such as the constrained LCS (CLCS) problem, and the LCS with t -length substrings (LCS_t) problem, are well-studied problems as the similarity measurement for strings or biosequences. In this paper, we first define the new variant, which is the constrained longest common subsequence with t -length substrings (CLCS _{t}) problem. Then, we propose three algorithms for solving the problem. The time complexity of the dynamic programming algorithm is $O(mnr)$, where m , n , and r are the lengths of the two target sequences and the constraint sequence, respectively. The row-wise algorithm is our second method, with $O(r \times \min\{mL + R, R \log L\} + m + n)$ time, where L denotes the answer length, and R denotes the number of t -match pairs between the two target sequences. Our third method is the diagonal algorithm with $O(rL(m - L) + R)$ time. As experimental results show, the diagonal algorithm is the most efficient.

Keywords: longest common subsequence (LCS), constrained LCS, LCS_t , dynamic programming, diagonal

1 Introduction

The goal of the LCS problem is to measure the similarity of two or more given sequences by the LCS length. In the past decades, many algorithms have been proposed for solving the LCS

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problem [1–5].

Given two sequences A and B with a constraint sequence P , the *constrained longest common subsequence* (CLCS) problem aims to find the LCS of A and B containing P as a subsequence of the answer. The CLCS problem was first introduced and solved by Tsai [6], who presented a *dynamic programming* (DP) algorithm with $O(m^2n^2r)$ time and space, where $|A| = m$, $|B| = n$ and $|P| = r$. Chin *et al.* [7] proposed a DP-based method reducing both time and space complexities to $O(mnr)$. In 2018, Hung *et al.* [8] presented a diagonal-based [4] algorithm with $O(rL(m - L))$ time and $O(mr)$ space, where L denotes the CLCS length.

In 2013, Benson *et al.* [9] first defined a new variant of LCS, the *LCS with t -length substrings* (LCS_t), aiming to find the LCS answer consisting of common t -length substrings. They proposed a DP algorithm to solve the LCS_t problem, with $O(mnt)$ time and $O(mt)$ space. In 2014, Deorowicz and Grabowski [10] proposed an improved algorithm, reducing the time complexity to $O(mn)$. In 2020, Huang *et al.* [11] proposed a diagonal-based algorithm with $O(n(m - L))$ time and $O(n)$ space.

The summary of the above CLCS and LCS_t algorithms, including our algorithms, is presented in Table 1.

In this paper, we first define the *constrained LCS with t -length substrings* (CLCS _{t}) problem, a new variant combined from the CLCS problem and the LCS_t problem. In the CLCS _{t} problem, we are given two sequences A and B with a constraint sequence P . The answer is the LCS of A and B with containing P as a subsequence, and it is composed of common t -length substrings of A and B . We propose three algorithms for solving the CLCS _{t} problem. The first is a DP algorithm with $O(mnr)$ time, the second is a row-wise algorithm with $O(r \times \min\{mL + R, R \log L\} + m + n)$

Table 1: The time and space complexities of the CLCS and LCS_t algorithms. t : length of each common substring; L : length of the answer; R : number of t -match pairs between A and B ; $r = |P| \leq m = |A| \leq n = |B|$; M, N, R' : numbers of runs in the two target sequences and constraint sequence, respectively, with the run-length encoded format.

CLCS				
Year	Author(s)	Time complexity	Space complexity	Note
2003	Tsai [6]	$O(m^2n^2r^2)$	$O(m^2n^2)$	All components
2004	Chin <i>et al.</i> [7]	$O(mnr)$	$O(mnr)$	DP
2012	Ann <i>et al.</i> [12]	$O(nmR' + nMr + Nmr)$		Run-length encoded
2018	Hung <i>et al.</i> [8]	$O(rL(m - L))$ $O(mnr)$	$O(mr)$ $O(mnr)$	Diagonal DP CLCS _t
2021	Ours	$O(r \times \min\{mL + R, R \log L\} + m + n)$ $O(rL(m - L) + R)$	$O(r(L + m + n))$ $O(rL + R)$	Row-wise CLCS _t Diagonal CLCS _t

LCS_t				
Year	Author(s)	Time complexity	Space complexity	Note
2013	Benson <i>et al.</i> [9]	$O(mnt)$	$O(mt)$	DP
2014	Deorowicz and Grabowski [10]	DP: $O(mn)$	DP: $O(mt)$	Sparse DP, van Emde Boas tree
		Sparse: $O(n + R \log L)$	Sparse: $O(n + \min\{R, mL\})$	
		Dense: $O(mn/t + m(t \log n)^{2/3})$	Dense: $O(m)$	
		Dense-vEB: $O(mn \log \log m/t)$	Dense-vEB: $O(m \log \log m)$	
2018	Pavetić <i>et al.</i> [13]	DP-4R: $O(mn/\log m)$	DP-4R: $O(n + nt/\log n)$	Match pair
		$O(m + n + R + \min(R \log L, R + mL))$	$O(m + n)$	
		$O(n(m - L))$		
2020	Huang <i>et al.</i> [11]	$O(n + L(m - L) \log n)$	$O(n)$	Diagonal
		$O(n + L(m - L) + R)$		

time, where L denotes the answer length, and R denotes the number of t -match pairs between A and B , and the third is a diagonal algorithm with $O(rL(m - L) + R)$ time. Theoretically and practically, the diagonal algorithm is the most efficient.

The organization of this paper is given as follows. Section 2 introduces some preliminaries of the CLCS_t problem. Then, in Sections 3 through 5, we propose three algorithms for solving the CLCS_t problem. Section 6 shows the experimental results. Finally, the conclusion is given in Section 7.

2 Preliminaries

A sequence $S = s_1s_2 \dots s_m$ consists of characters over a finite alphabet set Σ . $S_{i..j}$ represents the substring of S from positions i to j . $S_{i..j} = \emptyset$ if $i > j$. A subsequence of S is obtained by deleting an arbitrary number, or zero, of characters from S with the order-preserving.

Definition 1. (CLCS_t problem) Given two sequences $A = a_1a_2 \dots a_m$ and $B = b_1b_2 \dots b_n$, with

a constraint sequence $P = p_1p_2p_3 \dots p_r$ and a constant positive integer t , the CLCS_t problem is to find the LCS with common t -length substrings of A and B that contains P as a subsequence.

Suppose the answer length is $l \times t$, then there exists a common subsequence $C = A_{i_1-t+1..i_1} A_{i_2-t+1..i_2} \dots A_{i_l-t+1..i_l} = B_{j_1-t+1..j_1} B_{j_2-t+1..j_2} \dots B_{j_l-t+1..j_l}$, where $i_g \leq i_{g+1} - t$ and $j_g \leq j_{g+1} - t$ for $1 \leq g \leq l - 1$, and C contains P as a subsequence. Note that each common substring is of length t .

3 The Dynamic Programming Algorithm

Definition 2. [9] For sequences A and B , there is a t -match pair at (i, j) , denoted as $\text{match}_t(i, j) = 1$, if and only if $A_{i-t+1..i} = B_{j-t+1..j}$.

Definition 3. For a sequence A and a constraint sequence P , let $\text{suf}_t(i, k)$ denote the length of the maximum suffix of $P_{1..k}$ contained in $A_{i-t+1..i}$ as a subsequence. That is, if $\text{suf}_t(i, k) = h$, then

$P_{k-h+1..k}$ is a subsequence of $A_{i-t+1..i}$, but $P_{k-h..k}$ is not.

Definition 4. Let $M_t(i, j, k)$ denote the CLCS_t length for $A_{1..i}$ and $B_{1..j}$ with a constraint sequence $P_{1..k}$ contained as a subsequence in the CLCS_t answer.

Note that $suf_t(i, k) = 0$ if p_k is not in $A_{i-t+1..i}$. With the above definitions, the DP method for CLCS_t is presented in Equation 1. The idea of Equation 1 is simple. Since $M_t(i, j, k)$ could only come from the vertical, horizontal or diagonal direction, it solves the problem by considering these 3 directions and finding the maximum. Moreover, Table 2 shows an example of this algorithm.

$$M_t(i, j, k) = \max \begin{cases} M_t(i-1, j, k) & \text{if } i \geq 1, \\ M_t(i, j-1, k) & \text{if } j \geq 1, \\ M_t(i-t, j-t, k) & \text{if } match_t(i, j) = 1 \\ k-h + t & \text{and } suf_t(i, k) = h, \end{cases} \quad (1)$$

with boundary condition:

$$M_t(i, 0, 0) = M_t(0, j, 0) = 0,$$

$$M_t(i, 0, k) = M_t(0, j, k) = -\infty,$$

for $0 \leq i \leq m$, $0 \leq j \leq n$, and $1 \leq k \leq r$.

Table 2: An example of the DP algorithm for CLCS_t with $A = \text{aactccacta}$, $B = \text{aaccccactcta}$, $P = \text{ctt}$ and $t = 3$. '-' denotes $-\infty$.

	0	1	2	3	4	5	6	7	8	9	10	11
0	-	-	-	-	-	-	-	-	-	-	-	-
1 a	0	0	0	0	0	0	0	0	0	0	0	0
2 a	0	0	0	0	0	0	0	0	0	0	0	0
3 c	0	0	0	3	3	3	3	3	3	3	3	3
4 t	0	0	0	3	3	3	3	3	3	3	3	3
5 c	0	0	0	3	3	3	3	3	3	3	3	3
6 c	0	0	0	3	3	3	3	3	3	3	3	3
7 a	0	0	0	3	3	6	6	6	6	6	6	6
8 c	0	0	0	3	3	6	6	6	6	6	6	6
9 c	0	0	0	3	3	6	6	6	6	6	6	6
10 a	0	0	0	3	3	6	6	6	6	6	6	9

	0	1	2	3	4	5	6	7	8	9	10	11
0	-	-	-	-	-	-	-	-	-	-	-	-
1 a	-	-	-	-	-	-	-	-	-	-	-	-
2 a	-	-	-	-	-	-	-	-	-	-	-	-
3 c	-	-	-	-	-	-	-	-	-	-	-	-
4 t	-	-	-	-	-	-	-	-	-	-	-	-
5 c	-	-	-	-	-	-	-	-	-	-	-	-
6 c	-	-	-	-	-	-	-	-	-	-	-	-
7 a	-	-	-	-	-	-	-	-	-	-	-	-
8 c	-	-	-	-	-	-	-	-	-	-	-	-
9 c	-	-	-	-	-	-	-	-	-	-	-	-
10 a	-	-	-	-	-	-	-	-	-	-	-	-

	0	1	2	3	4	5	6	7	8	9	10	11
0	-	-	-	-	-	-	-	-	-	-	-	-
1 a	-	-	-	-	-	-	-	-	-	-	-	-
2 a	-	-	-	-	-	-	-	-	-	-	-	-
3 c	-	-	-	-	-	-	-	-	-	-	-	-
4 t	-	-	-	-	-	-	-	-	-	-	-	-
5 c	-	-	-	-	-	-	-	-	-	-	-	-
6 c	-	-	-	-	-	-	-	-	-	-	-	-
7 a	-	-	-	-	-	-	-	-	-	-	-	-
8 c	-	-	-	-	-	-	-	-	-	-	-	-
9 c	-	-	-	-	-	-	-	-	-	-	-	-
10 a	-	-	-	-	-	-	-	-	-	-	-	-

	0	1	2	3	4	5	6	7	8	9	10	11
0	-	-	-	-	-	-	-	-	-	-	-	-
1 a	-	-	-	-	-	-	-	-	-	-	-	-
2 a	-	-	-	-	-	-	-	-	-	-	-	-
3 c	-	-	-	-	-	-	-	-	-	-	-	-
4 t	-	-	-	-	-	-	-	-	-	-	-	-
5 c	-	-	-	-	-	-	-	-	-	-	-	-
6 c	-	-	-	-	-	-	-	-	-	-	-	-
7 a	-	-	-	-	-	-	-	-	-	-	-	-
8 c	-	-	-	-	-	-	-	-	-	-	-	-
9 c	-	-	-	-	-	-	-	-	-	-	-	-
10 a	-	-	-	-	-	-	-	-	-	-	-	-

The time and space complexities of the DP algorithm are both $O(mnr)$ time. With the monotonicity of $M_t(i, j, k)$, as given as follows, we can easily show the correctness of Equation 1.

Property 1. Each of the following holds.

- (1) $M_t(i, j, k_1) \geq M_t(i, j, k_2)$ if $k_1 < k_2$.
- (2) $M_t(i_1, j_1, k) \leq M_t(i_2, j_2, k)$ if $i_1 \leq i_2$ and $j_1 \leq j_2$.

(3) $M_t(i_1, j_1, k) < M_t(i_2, j_2, k)$ if $i_1 \leq i_2 - t$, $j_1 \leq j_2 - t$, $match_t(i_2, j_2) = 1$ and $M_t(i_2, j_2, k) \neq -\infty$.

(4) $M_t(i_1, j_1, k-h) < M_t(i_2, j_2, k)$ if $i_1 \leq i_2 - t$, $j_1 \leq j_2 - t$, $match_t(i_2, j_2) = 1$, $M_t(i_2, j_2, k) \neq -\infty$ and $h = suf_t(i_2, k)$.

(5) $M_t(i_1, j_1, k-h) + t \leq M_t(i_2, j_2, k)$ if $i_1 \leq i_2 - t$, $j_1 \leq j_2 - t$, $match_t(i_2, j_2) = 1$, $M_t(i_2, j_2, k) \neq -\infty$ and $h = suf_t(i_2, k)$.

4 The Row-wise Algorithm

In the DP algorithm, we observe that the computation of most cells in $M_t(i, j, k)$ is not needed because the CLCS_t length depends on only the t -match pairs. Accordingly, we propose the row-wise method for solving the CLCS_t problem, which calculates the answer length only at t -match pairs with the row by row manner (increasing values of index i of A).

For implementing the row-wise concept, we formally define $d_{i,s,k}$ as follows.

Definition 5. For two input sequences A and B with a constraint sequence P , let $d_{i,s,k} = \min\{j | M_t(i, j, k) \geq s\}$. In other words, $d_{i,s,k}$ records the smallest index j of B for $M_t(i, j, k) \geq s$.

Then, the row-wise algorithm for calculating $d_{i,s,k}$ is given as follows.

$$d_{i,s,k} = \min \begin{cases} 0 & \text{if } s = 0 \text{ and } k = 0, \\ \infty & \text{if } s \geq 1 \text{ or } k \geq 1, \\ d_{i-1,s,k} & \text{if } i \geq 1, \\ j & \text{if } match_t(i, j) = 1 \text{ and } suf_t(i, k) = h \text{ and } d_{i-t,s-t,k-h} \leq j - t. \end{cases} \quad (2)$$

According to Equation 2, the pseudocode of the row-wise algorithm for solving the CLCS_t problem is presented in Algorithm 1. Table 3 shows an example of the row-wise CLCS_t algorithm with Equation 2. The first two items in Equation 2 are boundary conditions and the third item is for the cases without matching, while the last item is for matching cases.

Theorem 1. Algorithm 1 solves the CLCS_t problem with $O(r \times \min\{mL + R, R \log L\} + m + n)$ time and $O(r(L + m + n))$ space, where $r = |P| \leq m = |A| \leq n = |B|$, L denotes the CLCS_t length and R denotes the number of t -match pairs between A and B .

Algorithm 1 Row-wise algorithm for CLCS_t

Input: two sequences $A = a_1a_2\dots a_m$ and $B = b_1b_2\dots b_n$, a constraint sequence $P = p_1p_2\dots p_r$, and a positive integer t for the substring length in the solution, where $r = |P| \leq m = |A| \leq n = |B|$.
Output: length of CLCS_t(A, B, P)

- 1: $d_{i,0,0} \leftarrow 0$ for $0 \leq i \leq m$
- 2: $d_{0,0,k} \leftarrow \infty$ for $1 \leq k \leq r$
- 3: **for** $k = 0 \rightarrow r$ **do**
- 4: $d_{0,s,k} \leftarrow \infty$ for $1 \leq s \leq n$
- 5: **for** $i = 1 \rightarrow m$ **do**
- 6: $h \leftarrow \text{suf}_t(i, k)$
- 7: $s \leftarrow 0$
- 8: **while** $d_{i,s-t,k} < \infty$ or $s \leq t$ **do**
- 9: $s \leftarrow s + t$
- 10: $d_{i,s,k} \leftarrow d_{i-1,s,k}$
- 11: **for** $j = 1 \rightarrow n$ **do**
- 12: **if** $\text{match}_t(i, j) = 1$ **then**
- 13: **if** $d_{i-t,s-t,k-h} \leq j - t$ **then**
- 14: $d_{i,j,k} \leftarrow \min\{d_{i,j,k}, j\}$
- 15: **break**
- 16: **return** $\max_{d_{i,s,r} \leq n, 1 \leq i \leq m} \{s\}$

5 The Diagonal Algorithm

Our diagonal algorithm for solving the CLCS_t problem is inspired by the diagonal LCS algorithm of Nakatsu *et al.* [4]. The diagonal algorithm also calculates the CLCS_t length only at t -match pairs. But, the calculation of the diagonal algorithm is done along the diagonal direction (not row by row). Thus, the diagonal algorithm is very efficient in dealing with highly similar sequences.

To solve the CLCS_t problem with the diagonal algorithm, we first define $\text{NextMatch}_t(i, j)$.

Definition 6. For two sequences A and B , $\text{NextMatch}_t(i, j)$ denotes the smallest j' such that $j' \geq j + t$ and $A_{i-t+1..i} = B_{j'-t+1..j'}$. If there is no such j' , then $\text{NextMatch}_t(i, j) = \infty$.

The diagonal algorithm for calculating $d_{i,s,k}$ is given as follows.

$$d_{i,s,k} = \min \begin{cases} 0 & \text{if } s = 0 \text{ and } k = 0, \\ \infty & \text{if } s \geq 1 \text{ or } k \geq 1, \\ d_{i-1,s,k} & \text{if } i \geq 1, \\ \text{NextMatch}_t(i, & \text{if } i \geq s \geq t \\ d_{i-t,s-t,k-h}) & \text{and } \text{suf}_t(i, k) = h. \end{cases} \quad (3)$$

Accordingly, the pseudocode of the diagonal algorithm for solving the CLCS_t problem is presented in Algorithm 2. Table 4 shows an example of the diagonal CLCS_t algorithm with Equation 3.

Table 3: An example of $d_{i,s,k}$ calculated by the row-wise method with $A = \text{aactccacta}$, $B = \text{aaccccactcta}$, $P = \text{ctt}$ and $t = 3$.

i	Length	s	0	3	6	9	12
0			0	∞	∞	∞	∞
1	a	0	∞	∞	∞	∞	∞
2	a	0	∞	∞	∞	∞	∞
3	c	0	3	∞	∞	∞	∞
4	t	0	3	∞	∞	∞	∞
5	c	0	3	∞	∞	∞	∞
6	c	0	3	∞	∞	∞	∞
7	a	0	3	6	∞	∞	∞
8	c	0	3	6	∞	∞	∞
9	t	0	3	6	∞	∞	∞
10	a	0	3	6	11	∞	∞

(a) $k = 0$
(b) $k = 1$

i	Length	s	0	3	6	9	12
0			∞	∞	∞	∞	∞
1	a		∞	∞	∞	∞	∞
2	a		∞	∞	∞	∞	∞
3	c		∞	∞	∞	∞	∞
4	t		∞	8	∞	∞	∞
5	c		∞	8	∞	∞	∞
6	c		∞	8	∞	∞	∞
7	a		∞	8	∞	∞	∞
8	c		∞	8	∞	∞	∞
9	t		∞	8	8	∞	∞
10	a		∞	8	8	11	∞

(c) $k = 2$
(d) $k = 3$

Table 4: An example of the diagonal algorithm for the CLCS_t problem with $A = \text{aactccacta}$, $B = \text{aaccccactcta}$, $P = \text{ctt}$ and $t = 3$.

Length	s	0	3	6	9
i = 3	$d_{0,0,k}$	$d_{3,3,k}$	$d_{6,6,k}$	$d_{9,9,k}$	
k = 0	0	3	∞	∞	
k = 1	∞	3	∞	∞	
k = 2	∞	∞	∞	∞	
k = 3	∞	∞	∞	∞	

(a) Round 1
(b) Round 2

Length	s	0	3	6	9
i = 6	$d_{3,0,k}$	$d_{6,3,k}$	$d_{9,6,k}$	$d_{12,9,k}$	
k = 0	0	3	6	11	
k = 1	∞	3	6	11	
k = 2	∞	8	8	11	
k = 3	∞	∞	∞	∞	

(c) Round 4
(d) Round 5

Theorem 2. Algorithm 2 solves the CLCS_t problem in $O(rL(m-L) + R)$ time, and its space complexity is $O(rL + R)$.

6 Experimental Results

In the experiments, we compare the execution time of the DP, row-wise, and diagonal CLCS_t algorithms. The execution time is obtained from the average of ten testing cases for each parameter combination. The pseudorandom datasets used in our experiments are generated with $|A| = 500$, $|B| = 500$, constraint ratio $\frac{|P|}{\min\{|A|, |B|\}} = 0.05$, alphabet size $|\Sigma| \in \{4, 20\}$, substrings length $t \in \{2, 5\}$, and various similarities $SI \in \{0.1, 0.2, \dots, 0.9\}$. The following algorithms are compared in our

Algorithm 2 The diagonal algorithm for CLCS_t

Input: two sequences $A = a_1a_2 \dots a_m$ and $B = b_1b_2 \dots b_n$, a constraint sequence $P = p_1p_2 \dots p_r$, and a positive integer t for the substring length in the solution, where $r = |P| \leq m = |A| \leq n = |B|$.
Output: length of $CLCS_t(A, B, P)$

```

1:  $L \leftarrow 0$ 
2: for  $i = t \rightarrow m$  do ▷ round  $i - t + 1$ 
3:    $d_{i-t,0,0} \leftarrow 0$ 
4:    $d_{i-t,0,k} \leftarrow \infty$  for  $1 \leq k \leq r$ 
5:    $i' \leftarrow i$ 
6:   while  $i' \leq m$  do
7:      $s \leftarrow i' - i + t$ 
8:     for  $k = 0 \rightarrow r$  do
9:        $h \leftarrow suf_t(i', k)$ 
10:       $j \leftarrow NextMatch_t(i', d_{i'-t,s-t,k-h})$ 
11:       $d_{i',s,k} \leftarrow \min\{d_{i'-t,s,k}, j\}$ 
12:      if  $d_{i',s,k} = \infty$  then break
13:    end for
14:    if  $d_{i',s,0} = \infty$  then break
15:    if  $d_{i',s,r} \leq n$  then  $L \leftarrow \max\{d_{i',s,r}, L\}$ 
16:     $i' \leftarrow i' + t$ 
17:   end while
18:   if  $m - i \leq L$  then return  $L$ 
19: end for
20: return  $L$ 

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experiments:

- **DP:** our DP algorithm for the CLCS_t problem;
- **R-Linear:** our row-wise algorithm with the linear scan for the CLCS_t problem.
- **R-Binary:** our row-wise algorithm with the binary search for the CLCS_t problem.
- **R-Hybrid:** our row-wise algorithm choosing the linear or binary strategy based on the current number of t -match pairs for the CLCS_t problem.
- **DIA:** our diagonal algorithm for the CLCS_t problem.

Figures 1, 2 and 3 show the average execution time of the above algorithms. We use the 7-tuple $(|A|, |B|, |P|, t, |\Sigma|, similarity, algo)$ to represent the parameters in the title of each line chart. For example, in Figure 1, $(500, 500, 25, 2, 4, *, *)$ means that $|A| = |B| = 500$, $|P| = 25$, $t = 2$, $|\Sigma| = 4$. Then the first wildcard '*' means that all similarities are tested in the experiment, and the second wildcard '*' indicates that all algorithms are executed.

As the experimental results show, the efficiency of the diagonal algorithm is always superior to the others with various parameter combinations. When $t \times |\Sigma|$ is relatively small (Figure 1), the

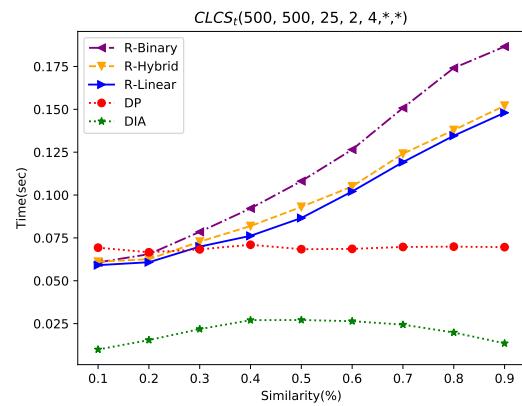


Figure 1: The average execution time for $|A| = 500$, $|B| = 500$, $|P| = 25$, $t = 2$ and $|\Sigma| = 4$.

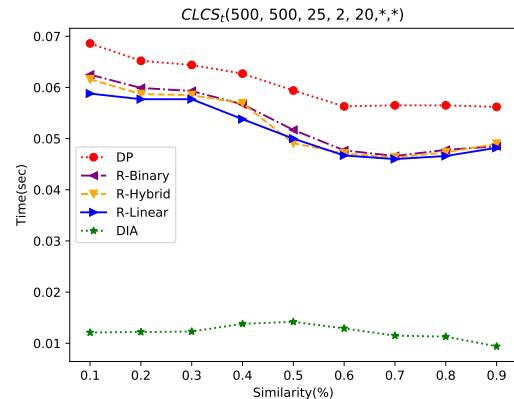


Figure 2: The average execution time for $|A| = 500$, $|B| = 500$, $|P| = 25$, $t = 2$ and $|\Sigma| = 20$.

row-wise algorithms are worse than DP if the similarity is high. The reason is that the number of t -match pairs becomes more in such situation. Thus, the row-wise algorithms are slightly better than DP when $t \times |\Sigma|$ is relatively large (Figures 2 and 3), since the number of t -match pairs is relatively small.

7 Conclusion

In this paper, we define the CLCS_t problem, a new variant of the CLCS problem. Then, we propose the DP, row-wise, and diagonal algorithms for solving the problem. As the experimental results show, the diagonal algorithm is the most efficient with various parameter combinations.

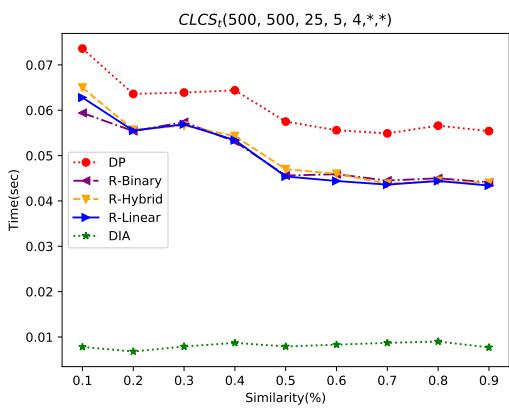


Figure 3: The average execution time for $|A| = 500$, $|B| = 500$, $|P| = 25$, $t = 5$ and $|\Sigma| = 4$.

In the future, we may apply our methods to more applications, especially for biosequences measurement. We may also generalize the problem to the CLCS_{t+} problem, in which each common substring is of length t or more (not exactly t). This new variant becomes more complicated since the length of each common substring becomes more flexible.

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