VENGATESAN G

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EDUCATION

 ${\it PhD~Candidate}, \, {\it Mechanical~Engineering} \quad \, ({\it Jan~2013-April~2017})$

National University of Singapore

CAP: 4.67 / 5

Thesis Title: Visual Coverage Path Planning of Unmanned Aerial Vehicles in Cluttered Environments

Modules completed: Advanced Robotics \cdot Machine Vision \cdot Visual Computing \cdot Evolutionary Computation \cdot Soft Robotics \cdot Discrete Events Systems

Graduate Certificate in Management-of-Technology (Aug 2015 - May 2016) Dept. of Engg. Technology and Management, National University of Singapore.

Modules completed: Intellectual Property Management · Management of Industrial R&D · Techlaunch: Experiential Entrepreneurship · Analyzing Hi-Technology Opportunities

Bachelor of Technology, Mechanical Engineering (2007 - 2011)

National Institute of Technology - Trichy

CAP: 8.97 / 10

National level School Board Exams:

Class XII (CBSE) 2007 R.S.K. Hr. Sec. School, Trichy, India 95.4% Class X (CBSE) 2005 R.S.K. Hr. Sec. School, Trichy, India 91.8%

EXPERIENCE

Aviation Officer, at Mumbai International Airport, (Sept 2011 - Nov 2012) Indian Oil Corporation Ltd.

In-charge of electrical maintenance of PLC, pumping equipments and Aircraft Refuelling Operations.

Teaching Assistant for modules EG1109 - Statics and Mechanics of Materials and ME3112 - Mechanics of machines. (Spring 2014, Fall 2015 resp.)

Lab Demonstrator for Vibration Measurement experiment for ME3112 - Mechanics of machines.

PUBLICATIONS Conferences

- 1. Vengatesan G, Gerard Leng, Zhang Qian, Visibility-based UAV path planning for surveillance in cluttered environments, 12th IEEE International Symposium on Safety, Security, and Rescue Robotics, Toyako Japan (Oct 2014)
- Vengatesan G, Gerard Leng, Zhang Qian, Visibility Maximization for Multi-UAV Surveillance over Urban Regions, Singapore Airforce Technology Exhibition and Conference, Singapore (April - 2014)

Journals

 Vengatesan G, Gerard Leng, Zhang Qian, Multi-UAV Surveillance over Forested Regions , Photogrammetric Engineering and Remote Sensing, Number 12, pp. 1129-1137(9) (Dec - 2014)

ACADEMIC ACHIEVEMENTS

Image Processing Robotics:

• Won the **Second Prize** in **IIT-Bombay TechFest - 09** in the GOAL Event for building an autonomous Image Processing Soccer playing robot.

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 Won the Second prize in an obstacles avoiding IP robot competition in IIT Madras Shaastra - 09. Won prizes for similar events in PSG College of Technology, Coimbatore and SRM University, Chennai.

BAJA - SAE All Asia: Participated in SAE-Baja All Asia 2010 All terrain vehicle design and fabrication competition held at NATRIP facility, Pithampur, Indore and achieved 17th position out of 80 teams.

PROJECT WORKS

Projects:

- Successfully completed the Final Year Project on **Design and Control of Stew**art Gough Platform using MATLAB, SimMechanics and SimHydraulics under the guidance of Prof. Dr. M. Udayakumar, at **NIT Trichy**, (Jan - May 2011).
- Successfully completed a project on Stereo Camera Calibration and 3D coordinate measurement using Stereovision at Engineering Design Dept, IIT Madras under the guidance of Dr. Sankara J. Subramanian and Dr. G. Saravana Kumar for the Summer Fellowship Programme (SFP IITM) 2010 (May 17th July 17th 2010).
- Successfully completed a project on Optimization of Magnetic Abrasive Finishing Process using Breeding Swarm Optimization at Mechanical Engg Dept, IIT Kanpur under the guidance of Dr. J. Ramkumar, for the Summer Undergraduate Research Grant for Excellence (SURGE IITK) 2009 (May 5th July 5th, 2009).

TRAINING

- Attended a one week **Summer School on Multi-Robot Systems** (June 2016) conducted by IEEE Robotics & Automation Society and also presented a poster.
- Attended a workshop on Digital Radiography during Non Destructive Evaluation Conference (NDE-2009). Attended a foundation course on Heat Treatment Processes and Welding Technology for Fresh Engineers conducted by the Indian Institute of Metals, Indian Welding Society Trichy.
- Completed an In-Plant Training in Bharat Heavy Electricals Ltd, Trichy.

COMPUTER SKILLS

- Operating Systems: Linux, Windows
- Languages : C++, Python
- Packages: Robot Operating System (ROS), Gazebo, MATLAB, Simulink, AutoCAD, Origin, PRO/E, Solidworks, LATEX

EXTRA-CURRICULAR ACTIVITIES

Positions of Responsibility:

- Manager of a hands-on robotics workshop for building an autonomous 'Sumo-Robot's which had around 250 participants.
- Event Manager of an Image Processing Robotics event 'Snakes and Ladders' in a national level technical festival.
- Organized a science exhibition for students from rural schools and exhibited an Image Processing Robot to motivate the students to continue their studies.

Sports / Cultural Activities:

- Awarded the 'Best Firer' in the rifle firing competition, and Second Best Cadet at the NCC Combined Annual Training Camp held at Karur.
- Parade Commander at the inter-college NCC drill competition.