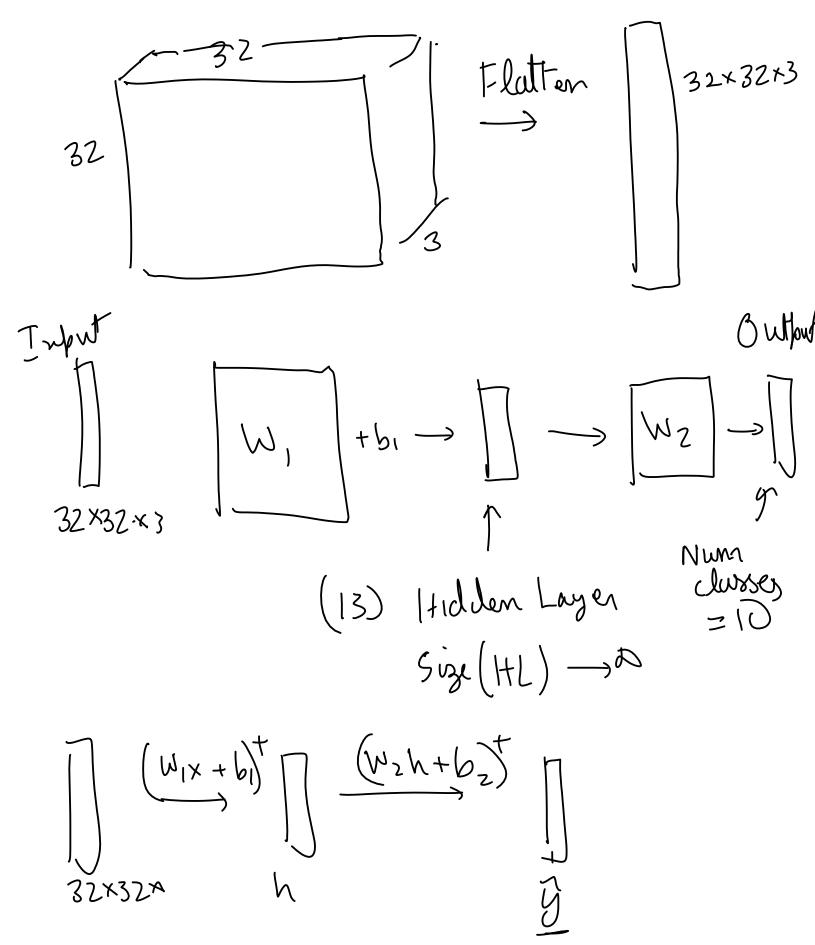
Supervised Learning + NN 1 Dataset {(1.1.7) Model - MLP model 3) LOSS = Perceptoron Los Cross entroly G 5 optimisation methods. out features MWIST now redto Woce IR'S

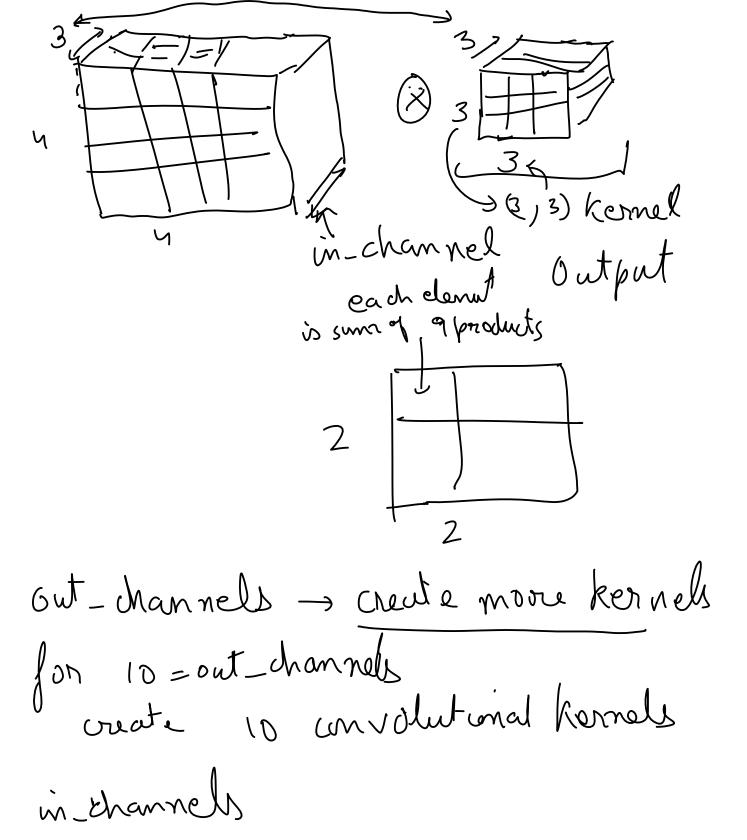
CIFARID



Cross entropy loss  $L(\gamma, \hat{y}) = \frac{9}{2} - P(\gamma = y) \log \left(\frac{\exp(\gamma - y)}{2}\right)$  $\Omega_{V} = \{6, 1,$ of mode coft max Z10/(g) ١٥

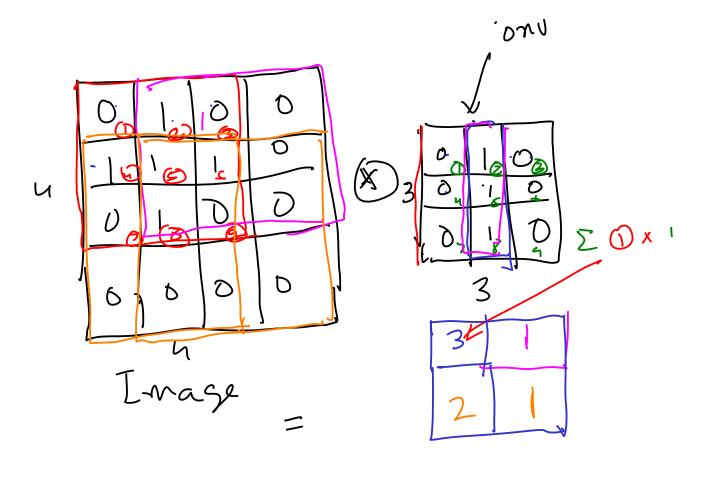
250memn= 1024 109 x 4 bytes = 46B Imases Position of the tree in mage classification problem does not no.thom This property is called translation mvari'ance

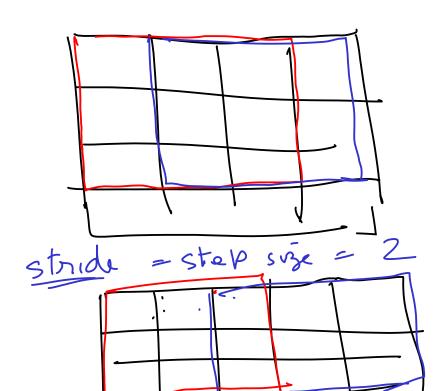
Convolution operation thatis translation invariant Convolution Kernel O E Ox O +(2) D  $\bigcirc$ I-mage



kornel size-

Size is shape of cont Kernel along image dimensions





padding

(4x4) \* (3x3) = (2x2)

wage 

(4x4) 

pudding = !

(4x4) 

wage 

(4x4) 

output)

(3x3) = 
$$[10+[3]x2, 10-[3]x2$$

wage 

(8x8) 

=  $[8 \times 8]$ 

output)

cyc

```
In [1]: # Adapted from: Chapter 7 and 8 of Deep Learning with Pytorch by Eli Stevens
        try:
            import torch as t
            import torch.nn as tnn
        except ImportError:
            print("Colab users: pytorch comes preinstalled. Select Change Ru")
            print("Local users: Please install pytorch for your hardware using instal
            print("ACG users: Please follow instructions here: https://vikasdhiman.i
            raise
        if t.cuda.is available():
            DEVICE="cuda"
        elif t.mps.is available():
            DEVICE="mps"
        else:
            DEVICE="cpu"
        DTYPE = t.get default dtype()
In [2]: ## Doing it the Pytorch way without using our custom feature extraction
        import torch
        import torch.nn
        import torch.optim
        import torchvision
        from torchvision.transforms import ToTensor, Compose, Normalize
        from torch.utils.data import DataLoader
        torch.manual seed(17)
        DATASET MEAN = [0.4914, 0.4822, 0.4465]
        DATASET STD = [0.2470, 0.2435, 0.2616]
        # Getting the dataset, the Pytorch way
        all training data = torchvision.datasets.CIFAR10(
            root="data",
            train=True.
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                          DATASET STD)]) # dataset std
        test data = torchvision.datasets.CIFAR10(
            root="data",
            train=False.
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                          DATASET STD)]) # dataset std
```

Files already downloaded and verified Files already downloaded and verified

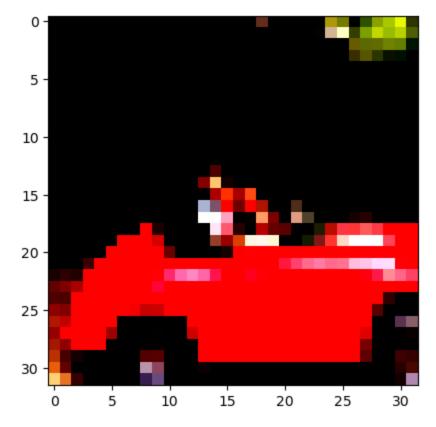
```
In [4]: img, label = all_training_data[99]
  img.shape, label
```

Out[4]: (torch.Size([3, 32, 32]), 1)

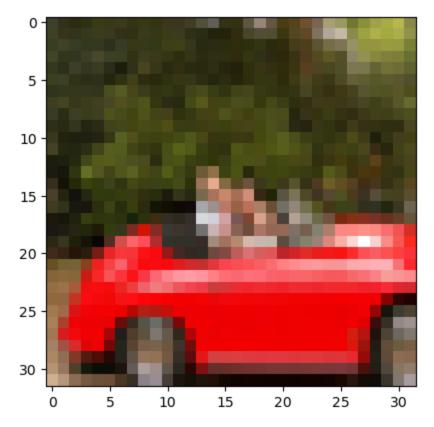
```
In [5]: import matplotlib.pyplot as plt
plt.imshow(img.permute(1, 2, 0))
```

Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).

Out[5]: <matplotlib.image.AxesImage at 0x7efdecbcb5b0>



Out[6]: <matplotlib.image.AxesImage at 0x7efdecb04940>



```
In [7]: imgs = torch.stack([img_t for img_t, _ in all_training_data], dim=3)
        imgs.reshape(3, -1).mean(dim=-1), imgs.reshape(3, -1).std(dim=-1)
Out[7]: (tensor([-1.2762e-06, -1.7074e-04, 1.1819e-04]),
         tensor([1.0001, 0.9999, 1.0000]))
In [8]: import pickle
        cifar meta = pickle.load(open("data/cifar-10-batches-py/batches.meta", "rb")
        class names = [c.decode('utf-8') for c in cifar meta[b'label names']]
        class names
Out[8]: ['airplane',
         'automobile',
         'bird',
         'cat',
         'deer',
         'dog',
         'frog',
         'horse',
         'ship',
         'truck']
In [9]: # Hyper parameters
        learning rate = 1e-3 # controls how fast the gradient descent goes
        batch size = 64
        epochs = 5
        momentum = 0.9
        training dataloader = DataLoader(training data, shuffle=True, batch size=bat
        validation dataloader = DataLoader(validation data, batch size=batch size)
```

test dataloader = DataLoader(test data, batch size=batch size)

```
X, y = next(iter(training_dataloader))
X.shape
```

Out[9]: torch.Size([64, 3, 32, 32])

In [10]: !pip install tensorboard

Requirement already satisfied: tensorboard in /home/vdhiman/.local/minicond a3/envs/ece490/lib/python3.10/site-packages (2.12.0)

Requirement already satisfied: google-auth-oauthlib<0.5,>=0.4.1 in /home/vd himan/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tens orboard) (0.4.6)

Requirement already satisfied: grpcio>=1.48.2 in /home/vdhiman/.local/minic onda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (1.53.0) Requirement already satisfied: tensorboard-data-server<0.8.0,>=0.7.0 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (0.7.0)

Requirement already satisfied: requests<3,>=2.21.0 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (2.2 8.1)

Requirement already satisfied: markdown>=2.6.8 in /home/vdhiman/.local/mini conda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (3.4.3) Requirement already satisfied: tensorboard-plugin-wit>=1.6.0 in /home/vdhim an/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorb oard) (1.8.1)

Requirement already satisfied: google-auth<3,>=1.6.3 in /home/vdhiman/.loca l/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (2.17.0)

Requirement already satisfied: wheel>=0.26 in /home/vdhiman/.local/minicond a3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (0.37.1) Requirement already satisfied: setuptools>=41.0.0 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (65.6.3)

Requirement already satisfied: werkzeug>=1.0.1 in /home/vdhiman/.local/mini conda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (2.2.3) Requirement already satisfied: numpy>=1.12.0 in /home/vdhiman/.local/minico nda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (1.23.5) Requirement already satisfied: protobuf>=3.19.6 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (4.22.1)

Requirement already satisfied: absl-py>=0.4 in /home/vdhiman/.local/minicon da3/envs/ece490/lib/python3.10/site-packages (from tensorboard) (1.4.0) Requirement already satisfied: rsa<5,>=3.1.4 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from google-auth<3,>=1.6.3-> tensorboard) (4.9)

Requirement already satisfied: cachetools<6.0,>=2.0.0 in /home/vdhiman/.loc al/miniconda3/envs/ece490/lib/python3.10/site-packages (from google-auth<3, >=1.6.3->tensorboard) (5.3.0)

Requirement already satisfied: pyasn1-modules>=0.2.1 in /home/vdhiman/.loca l/miniconda3/envs/ece490/lib/python3.10/site-packages (from google-auth<3,>=1.6.3->tensorboard) (0.2.8)

Requirement already satisfied: six>=1.9.0 in /home/vdhiman/.local/miniconda 3/envs/ece490/lib/python3.10/site-packages (from google-auth<3,>=1.6.3->ten sorboard) (1.16.0)

Requirement already satisfied: requests-oauthlib>=0.7.0 in /home/vdhiman/.l ocal/miniconda3/envs/ece490/lib/python3.10/site-packages (from google-authoauthlib<0.5,>=0.4.1->tensorboard) (1.3.1)

Requirement already satisfied: certifi>=2017.4.17 in /home/vdhiman/.local/m iniconda3/envs/ece490/lib/python3.10/site-packages (from requests<3,>=2.21. 0->tensorboard) (2022.12.7)

Requirement already satisfied: urllib3<1.27,>=1.21.1 in /home/vdhiman/.loca l/miniconda3/envs/ece490/lib/python3.10/site-packages (from requests<3,>=2. 21.0->tensorboard) (1.26.14)

Requirement already satisfied: charset-normalizer<3,>=2 in /home/vdhiman/.l ocal/miniconda3/envs/ece490/lib/python3.10/site-packages (from requests<3,>=2.21.0->tensorboard) (2.0.4)

Requirement already satisfied: idna<4,>=2.5 in /home/vdhiman/.local/minicon da3/envs/ece490/lib/python3.10/site-packages (from requests<3,>=2.21.0->ten sorboard) (3.4)

Requirement already satisfied: MarkupSafe>=2.1.1 in /home/vdhiman/.local/miniconda3/envs/ece490/lib/python3.10/site-packages (from werkzeug>=1.0.1->tensorboard) (2.1.1)

Requirement already satisfied: pyasn1<0.5.0,>=0.4.6 in /home/vdhiman/.loca l/miniconda3/envs/ece490/lib/python3.10/site-packages (from pyasn1-modules> =0.2.1->google-auth<3,>=1.6.3->tensorboard) (0.4.8)

Requirement already satisfied: oauthlib>=3.0.0 in /home/vdhiman/.local/mini conda3/envs/ece490/lib/python3.10/site-packages (from requests-oauthlib>=0.7.0->google-auth-oauthlib<0.5,>=0.4.1->tensorboard) (3.2.2)

## In [17]: %tensorboard --logdir=runs

Reusing TensorBoard on port 6006 (pid 543069), started 0:05:49 ago. (Use '! kill 543069' to kill it.)

```
In [22]: from torch.utils.tensorboard import SummaryWriter
import os
writer = SummaryWriter()

loss = torch.nn.CrossEntropyLoss()
# TODO:
# Define model = ?
```

```
model = tnn.Sequential(
   torch.nn.Flatten(),
    tnn.Linear(3*32*32, 100),
    tnn.ReLU(),
    tnn.Linear(100, 10))
# Define optimizer
optimizer = torch.optim.SGD(model.parameters(), lr=learning rate, momentum=m
def loss and accuracy(model, loss, validation dataloader, device=DEVICE):
        # Validation loop
        validation size = len(validation dataloader.dataset)
        num batches = len(validation dataloader)
        test loss, correct = 0, 0
        with torch.no grad():
            model.eval() # Put model in eval mode, affects layers like dropd
            for X, y in validation dataloader:
                X = X.to(device)
                y = y.to(device)
                pred = model(X)
                test loss += loss(pred, y)
                correct += (pred.argmax(dim=-1) == y).type(DTYPE).sum()
        test loss /= num batches
        correct /= validation size
        return test loss, correct
def train(model, loss, training dataloader, validation dataloader, device=DE
    model.to(device)
    t0 = 0
    if os.path.exists("runs/model ckpt.pt"):
        checkpoint = torch.load("runs/model ckpt.pt")
        model.load state dict(checkpoint['model state dict'])
        optimizer.load state dict(checkpoint['optimizer state dict'])
        t0 = checkpoint['epoch']
    for t in range(t0, epochs):
        # Train loop
        training size = len(training dataloader.dataset)
        nbatches = len(training dataloader)
        model.train() # Put model in train mode, affects layers like dropout
        for batch, (X, y) in enumerate(training dataloader):
            X = X.to(device)
            y = y.to(device)
            # Compute prediction and loss
            pred = model(X)
            loss t = loss(pred, y)
            # Backpropagation
            optimizer.zero grad()
            loss t.backward()
            optimizer.step()
            if batch % 100 == 0:
```

```
writer.add scalar("Train/loss batch", loss t, t*nbatches +
                loss t, current = loss t.item(), (batch + 1) * len(X)
                print(f"loss: {loss t:>7f} [{current:>5d}/{training size:>5
        writer.add scalar("Train/loss", loss t, t)
        valid_loss, correct = loss_and_accuracy(model, loss, validation_data
        writer.add scalar("Valid/loss", valid loss, t)
        writer.add scalar("Valid/accuracy", correct, t)
        print(f"Validation Error: \n Accuracy: {(100*correct):>0.1f}%, Avg l
        if t % 3 == 0:
            torch.save({
                'epoch': t,
                'model state dict': model.state dict(),
                'optimizer state dict': optimizer.state dict()
                }, "runs/model ckpt.pt")
    return model
trained model = train(model, loss, training dataloader, validation dataloade
test loss, correct = loss and accuracy(model, loss, test dataloader)
print(f"Test Error: \n Accuracy: {(100*correct):>0.1f}%, Avg loss: {test los
Validation Error: 4864/45000]
Accuracy: 48.4%, Avg loss: 1.453683
Validation Error: 4864/45000]
Accuracy: 49.2%, Avg loss: 1.440753
Test Error:
Accuracy: 50.3%, Avg loss: 1.427571
```

## Limits of fully connected layers

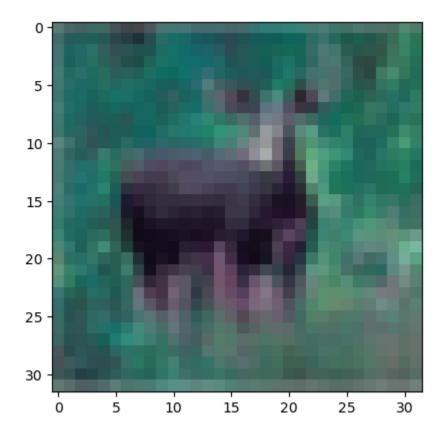
## Convolutions bring translation invariance

```
In [32]: conv = torch.nn.Conv2d(3, 1, kernel_size=3)
conv

Out[32]: Conv2d(3, 1, kernel_size=(3, 3), stride=(1, 1))

In [33]: img, label = training_data[99]
   plt.imshow(img.permute(1, 2, 0) * t.Tensor(DATASET_STD) + t.Tensor(DATASET_N)

Out[33]: <matplotlib.image.AxesImage at 0x7efd51214ee0>
```



Learning with Convolutions

## Maxpooling

In [ ]: