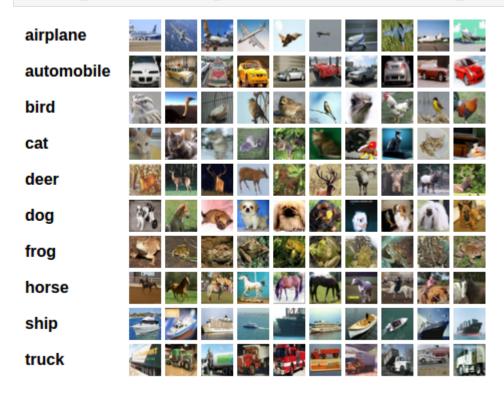
```
In [ ]: # Adapted from: Chapter 7 and 8 of Deep Learning with Pytorch by Eli Stevens
        try:
            import torch as t
            import torch.nn as tnn
        except ImportError:
            print("Colab users: pytorch comes preinstalled. Select Change Ru")
            print("Local users: Please install pytorch for your hardware using instr
            print("ACG users: Please follow instructions here: https://vikasdhiman.i
            raise
        if t.cuda.is available():
            DEVICE="cuda"
        elif t.mps.is available():
            DEVICE="mps"
        else:
            DEVICE="cpu"
        DTYPE = t.get default dtype()
In [ ]: | ## Doing it the Pytorch way without using our custom feature extraction
        import torch
        import torch.nn
        import torch.optim
        import torchvision
        from torchvision.transforms import ToTensor, Compose, Normalize
        from torch.utils.data import DataLoader
        torch.manual seed(17)
        DATASET MEAN = [0.4914, 0.4822, 0.4465]
        DATASET STD = [0.2470, 0.2435, 0.2616]
        # Getting the dataset, the Pytorch way
        all training data = torchvision.datasets.CIFAR10(
            root="data",
            train=True.
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                          DATASET STD)]) # dataset std
        )
        test data = torchvision.datasets.CIFAR10(
            root="data",
            train=False.
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                          DATASET STD)]) # dataset std
```

Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to data/cifar-10-python.tar.gz

In []: training_data, validation_data = torch.utils.data.random_split(all_training_



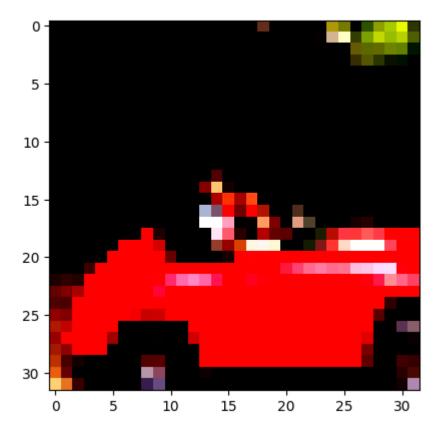
```
In []: img, label = all_training_data[99]
img.shape, label

Out[]: (torch.Size([3, 32, 32]), 1)

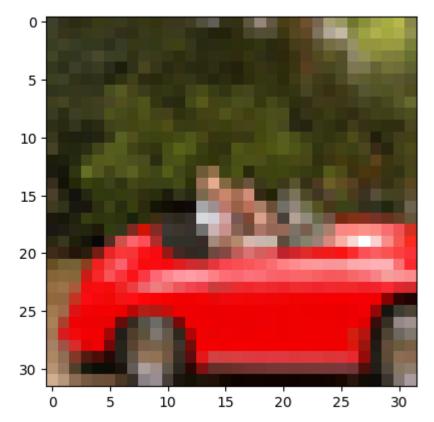
In []: import matplotlib.pyplot as plt
plt.imshow(img.permute(1, 2, 0))

WARNING:matplotlib.image:Clipping input data to the valid range for imshow w
ith RGB data ([0..1] for floats or [0..255] for integers).
```

Out[]: <matplotlib.image.AxesImage at 0x7feacb580850>



Out[]: <matplotlib.image.AxesImage at 0x7feac19ae8b0>



```
In [ ]: imgs = torch.stack([img_t for img_t, _ in all_training_data], dim=3)
        imgs.reshape(3, -1).mean(dim=-1), imgs.reshape(3, -1).std(dim=-1)
Out[]: (tensor([-1.2762e-06, -1.7074e-04, 1.1819e-04]),
         tensor([1.0001, 0.9999, 1.0000]))
In [ ]: import pickle
        cifar meta = pickle.load(open("data/cifar-10-batches-py/batches.meta", "rb")
        class names = [c.decode('utf-8') for c in cifar meta[b'label names']]
        class names
Out[]: ['airplane',
         'automobile',
         'bird',
         'cat',
         'deer',
         'dog',
         'frog',
         'horse',
         'ship',
         'truck']
In [ ]: # Hyper parameters
        learning rate = 1e-3 # controls how fast the gradient descent goes
        batch size = 64
        epochs = 5
        momentum = 0.9
        training dataloader = DataLoader(training data, shuffle=True, batch size=bat
        validation dataloader = DataLoader(validation data, batch size=batch size)
        test dataloader = DataLoader(test data, batch size=batch size)
        X, y = next(iter(training dataloader))
        X. shape
Out[]: torch.Size([64, 3, 32, 32])
In [ ]: !pip install tensorboard
```

```
Looking in indexes: https://pypi.org/simple, https://us-python.pkg.dev/colab
-wheels/public/simple/
Requirement already satisfied: tensorboard in /usr/local/lib/python3.9/dist-
packages (2.12.1)
Requirement already satisfied: google-auth<3,>=1.6.3 in /usr/local/lib/pytho
n3.9/dist-packages (from tensorboard) (2.17.2)
Requirement already satisfied: protobuf>=3.19.6 in /usr/local/lib/python3.9/
dist-packages (from tensorboard) (3.20.3)
Requirement already satisfied: numpy>=1.12.0 in /usr/local/lib/python3.9/dis
t-packages (from tensorboard) (1.22.4)
Requirement already satisfied: tensorboard-plugin-wit>=1.6.0 in /usr/local/l
ib/python3.9/dist-packages (from tensorboard) (1.8.1)
Requirement already satisfied: requests<3,>=2.21.0 in /usr/local/lib/python
3.9/dist-packages (from tensorboard) (2.27.1)
Requirement already satisfied: markdown>=2.6.8 in /usr/local/lib/python3.9/d
ist-packages (from tensorboard) (3.4.3)
Requirement already satisfied: tensorboard-data-server<0.8.0,>=0.7.0 in /us
r/local/lib/python3.9/dist-packages (from tensorboard) (0.7.0)
Requirement already satisfied: absl-py>=0.4 in /usr/local/lib/python3.9/dist
-packages (from tensorboard) (1.4.0)
Requirement already satisfied: setuptools>=41.0.0 in /usr/local/lib/python3.
9/dist-packages (from tensorboard) (67.6.1)
Requirement already satisfied: werkzeug>=1.0.1 in /usr/local/lib/python3.9/d
ist-packages (from tensorboard) (2.2.3)
Requirement already satisfied: google-auth-oauthlib<1.1,>=0.5 in /usr/local/
lib/python3.9/dist-packages (from tensorboard) (1.0.0)
Requirement already satisfied: wheel>=0.26 in /usr/local/lib/python3.9/dist-
packages (from tensorboard) (0.40.0)
Requirement already satisfied: qrpcio>=1.48.2 in /usr/local/lib/python3.9/di
st-packages (from tensorboard) (1.53.0)
Requirement already satisfied: rsa<5.>=3.1.4 in /usr/local/lib/python3.9/dis
t-packages (from google-auth<3,>=1.6.3->tensorboard) (4.9)
Requirement already satisfied: pyasn1-modules>=0.2.1 in /usr/local/lib/pytho
n3.9/dist-packages (from google-auth<3,>=1.6.3->tensorboard) (0.2.8)
Requirement already satisfied: six>=1.9.0 in /usr/local/lib/python3.9/dist-p
ackages (from google-auth<3,>=1.6.3->tensorboard) (1.16.0)
Requirement already satisfied: cachetools<6.0,>=2.0.0 in /usr/local/lib/pyth
on3.9/dist-packages (from google-auth<3,>=1.6.3->tensorboard) (5.3.0)
Requirement already satisfied: requests-oauthlib>=0.7.0 in /usr/local/lib/py
thon3.9/dist-packages (from google-auth-oauthlib<1.1,>=0.5->tensorboard) (1.
3.1)
Requirement already satisfied: importlib-metadata>=4.4 in /usr/local/lib/pyt
hon3.9/dist-packages (from markdown>=2.6.8->tensorboard) (6.2.0)
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.9/dist
-packages (from requests<3,>=2.21.0->tensorboard) (3.4)
Requirement already satisfied: urllib3<1.27,>=1.21.1 in /usr/local/lib/pytho
n3.9/dist-packages (from requests<3,>=2.21.0->tensorboard) (1.26.15)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.
9/dist-packages (from requests<3,>=2.21.0->tensorboard) (2022.12.7)
Requirement already satisfied: charset-normalizer~=2.0.0 in /usr/local/lib/p
ython3.9/dist-packages (from requests<3,>=2.21.0->tensorboard) (2.0.12)
Requirement already satisfied: MarkupSafe>=2.1.1 in /usr/local/lib/python3.
9/dist-packages (from werkzeug>=1.0.1->tensorboard) (2.1.2)
Requirement already satisfied: zipp>=0.5 in /usr/local/lib/python3.9/dist-pa
ckages (from importlib-metadata>=4.4->markdown>=2.6.8->tensorboard) (3.15.0)
```

Requirement already satisfied: pyasn1<0.5.0,>=0.4.6 in /usr/local/lib/python

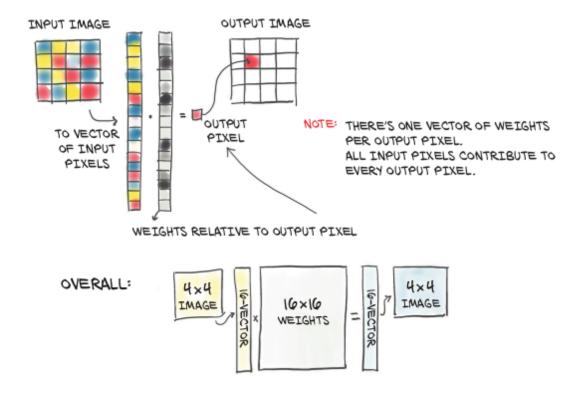
```
3.9/dist-packages (from pyasn1-modules>=0.2.1->google-auth<3,>=1.6.3->tensor board) (0.4.8)
Requirement already satisfied: oauthlib>=3.0.0 in /usr/local/lib/python3.9/d ist-packages (from requests-oauthlib>=0.7.0->google-auth-oauthlib<1.1,>=0.5->tensorboard) (3.2.2)
```

```
In [ ]: %load_ext tensorboard
%tensorboard --logdir=runs
```

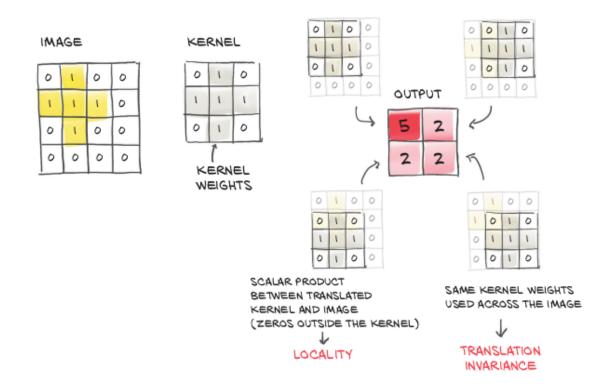
```
In [44]: from torch.utils.tensorboard import SummaryWriter
         import os
         writer = SummaryWriter()
         loss = torch.nn.CrossEntropyLoss()
         # TODO:
         # Define model = ?
         model = tnn.Sequential(
             tnn.Flatten(),
             tnn.Linear(3*32*32, 100),
             tnn.ReLU().
             tnn.Linear(100, 10))
         def loss and accuracy(model, loss, validation dataloader, device=DEVICE):
                 # Validation loop
                 validation size = len(validation dataloader.dataset)
                 num batches = len(validation dataloader)
                 test loss, correct = 0, 0
                 with torch.no grad():
                     model.eval() # Put model in eval mode, affects layers like dropd
                     for X, y in validation dataloader:
                         X = X.to(device)
                         y = y.to(device)
                         pred = model(X)
                         test loss += loss(pred, y)
                         correct += (pred.argmax(dim=-1) == y).type(DTYPE).sum()
                 test loss /= num batches
                 correct /= validation size
                 return test loss, correct
         def train(model, loss, training dataloader, validation dataloader, device=DE
             # Define optimizer
             optimizer = torch.optim.SGD(model.parameters(), lr=learning rate, moment
             model.to(device)
             t0 = 0
             if not ignore chkpt and os.path.exists(f"runs/{chkpt name}"):
                 checkpoint = torch.load(f"runs/{chkpt name}")
                 model.load state dict(checkpoint['model state dict'])
                 optimizer.load state dict(checkpoint['optimizer state dict'])
                 t0 = checkpoint['epoch']
```

```
for t in range(t0, epochs):
        # Train loop
        training size = len(training dataloader.dataset)
        nbatches = len(training dataloader)
        model.train() # Put model in train mode, affects layers like dropout
        for batch, (X, y) in enumerate(training dataloader):
            X = X.to(device)
            y = y.to(device)
            # Compute prediction and loss
            pred = model(X)
            loss t = loss(pred, y)
            # Backpropagation
            optimizer.zero grad()
            loss t.backward()
            optimizer.step()
            if batch % 100 == 0:
                writer.add scalar("Train/loss batch", loss t, t*nbatches +
                loss t, current = loss t.item(), (batch + 1) * len(X)
                print(f"loss: {loss t:>7f} [{current:>5d}/{training size:>5
        writer.add scalar("Train/loss", loss t, t)
        valid loss, correct = loss and accuracy(model, loss, validation data
        writer.add scalar("Valid/loss", valid loss, t)
        writer.add scalar("Valid/accuracy", correct, t)
        print(f"Validation Error: \n Accuracy: {(100*correct):>0.1f}%, Avg l
        if t % 3 == 0:
            torch.save({
                'epoch': t,
                'model state dict': model.state dict(),
                'optimizer state dict': optimizer.state_dict()
                }, f"runs/{chkpt name}")
    return model
# trained model = train(model, loss, training dataloader, validation dataloa
# test loss, correct = loss and accuracy(model, loss, test dataloader)
# print(f"Test Error: \n Accuracy: {(100*correct):>0.1f}%, Avg loss: {test l
```

Limits of fully connected layers

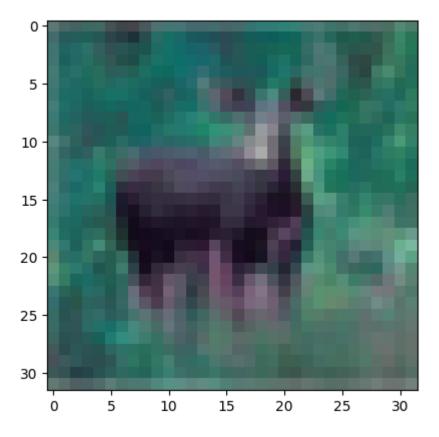


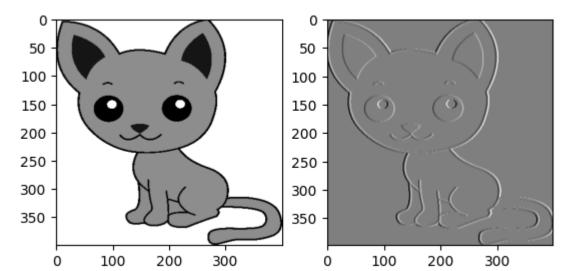
Convolutions bring translation invariance



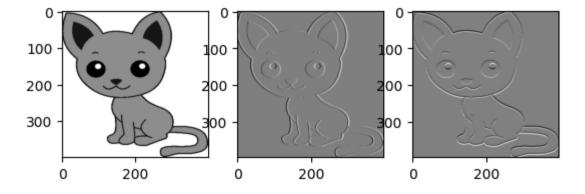
```
In [ ]: img, label = training_data[99]
plt.imshow(img.permute(1, 2, 0) * t.Tensor(DATASET_STD) + t.Tensor(DATASET_N
```

Out[]: <matplotlib.image.AxesImage at 0x7feac18e0d00>



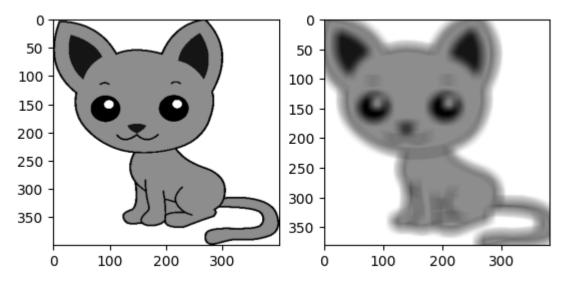


Out[]: <matplotlib.image.AxesImage at 0x7fea240aef40>



```
In [ ]: import math
        ks=20
        conv = torch.nn.Conv2d(1, 1, kernel size=ks).to(DEVICE)
        with torch.no grad():
            imin = -ks//2
            imax = imin + ks
            i = torch.arange(imin, imax).to(DTYPE)
            j = torch.arange(imin, imax).to(DTYPE)
            sigma = torch.Tensor([ks//6])
            grid_x, grid_y = torch.meshgrid(i, j, indexing='ij')
            \#conv.weight[:] = torch.exp(- (grid_x**2 + grid_y**2)) / (2*sigma**2))
            conv.weight[:] = torch.ones((ks, ks)) / ks**2
            conv.bias[:] = 0
        conved2 = conv(sobelimg)
        fig, axes = plt.subplots(1, 2)
        axes[0].imshow(sobelimg[0].detach().cpu(), cmap='gray')
        axes[1].imshow(conved2[0].detach().cpu(), cmap='gray')
```

Out[]: <matplotlib.image.AxesImage at 0x7fea1c5e1af0>



In []: !wget https://github.com/rajatsaxena/OpenCV/raw/master/mario.jpg -0 imgs/mar
!wget https://github.com/rajatsaxena/OpenCV/raw/master/mario_template.jpg -0

```
rio.jpg
      Resolving github.com (github.com)... 140.82.121.4
       Connecting to github.com (github.com)|140.82.121.4|:443... connected.
      HTTP request sent, awaiting response... 302 Found
      Location: https://raw.githubusercontent.com/rajatsaxena/OpenCV/master/mario.
       ipa [followina]
       --2023-04-11 18:15:12-- https://raw.githubusercontent.com/rajatsaxena/OpenC
      V/master/mario.jpg
      Resolving raw.githubusercontent.com (raw.githubusercontent.com)... 185.199.1
       08.133, 185.199.109.133, 185.199.110.133, ...
       Connecting to raw.githubusercontent.com (raw.githubusercontent.com) [185.199.
       108.133|:443... connected.
      HTTP request sent, awaiting response... 200 OK
      Length: 7301 (7.1K) [image/jpeg]
       Saving to: 'imgs/mario.jpg'
       imgs/mario.jpg
                          in 0s
       2023-04-11 18:15:12 (55.6 MB/s) - 'imgs/mario.jpg' saved [7301/7301]
       --2023-04-11 18:15:12-- https://github.com/rajatsaxena/OpenCV/raw/master/ma
       rio template.jpg
      Resolving github.com (github.com)... 140.82.121.3
       Connecting to github.com (github.com)|140.82.121.3|:443... connected.
      HTTP request sent, awaiting response... 302 Found
      Location: https://raw.githubusercontent.com/rajatsaxena/OpenCV/master/mario
       template.jpg [following]
       --2023-04-11 18:15:12-- https://raw.githubusercontent.com/rajatsaxena/OpenC
      V/master/mario template.jpg
       Resolving raw.githubusercontent.com (raw.githubusercontent.com)... 185.199.1
       08.133, 185.199.109.133, 185.199.110.133, ...
       Connecting to raw.githubusercontent.com (raw.githubusercontent.com) [185.199.
       108.133|:443... connected.
      HTTP request sent, awaiting response... 200 OK
       Length: 855 [image/jpeg]
       Saving to: 'imgs/mario template.jpg'
       imgs/mario template 100%[=========] 855 --.-KB/s
                                                                         in 0s
       2023-04-11 18:15:13 (41.1 MB/s) - 'imgs/mario template.jpg' saved [855/855]
In [ ]: with torch.no grad():
            sobelimg = torchvision.io.read image('imgs/mario.jpg').to(DEVICE)
            #sobelimg = torchvision.transforms.functional.rgb to grayscale(sobelimg|
            sobelimg = sobelimg.to(DTYPE) / sobelimg.max()
            patch = torchvision.io.read image('imgs/mario template.jpg').to(DEVICE)
            #patch = torchvision.transforms.functional.rgb to grayscale(patch[:3, ...
            patch = patch.to(DTYPE) / patch.max()
            fig, ax = plt.subplots(figsize=(0.5,0.5))
            ax.imshow(patch.permute(1, 2, 0).cpu())
        kr, kc = patch.shape[1:]
        conv = torch.nn.Conv2d(3, 1, kernel size=(kr, kc)).to(DEVICE)
```

--2023-04-11 18:15:12-- https://github.com/rajatsaxena/OpenCV/raw/master/ma

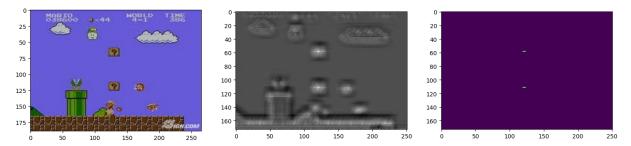
```
with torch.no_grad():
    patch = (patch - patch.mean()) / patch.std()
    conv.weight[:] = patch
    conv.bias[:] = 0

sobelimgnormed = (sobelimg - sobelimg.mean()) / sobelimg.std()
conved2 = conv(sobelimgnormed)

fig, axes = plt.subplots(1, 3, figsize=(18, 6))
axes[0].imshow(sobelimg.permute(1, 2, 0).detach().cpu())
axes[1].imshow(conved2[0].detach().cpu(), cmap='gray')
axes[2].imshow((conved2[0].abs() > 380).detach().cpu())
```

Out[]: <matplotlib.image.AxesImage at 0x7fea1d62fa00>





Learning with Convolutions

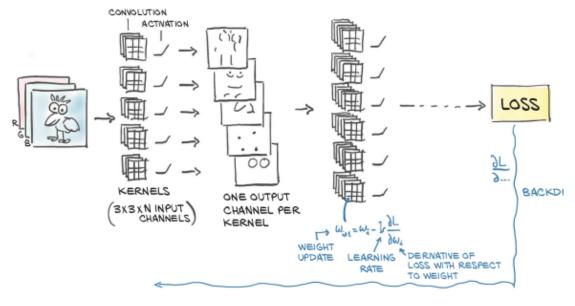
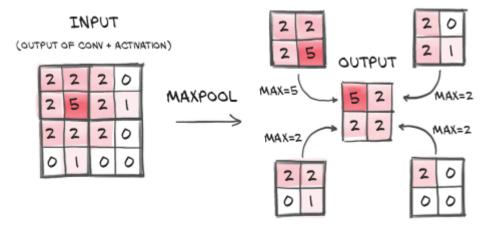


Figure 8.6 The process of learning with convolutions by estimating the gradient at the kernel weights and updating them individually in order to optimize for the loss

Maxpooling



Eiguro 9 7 May pooling in detail

```
In []: conv = tnn.Conv2d(3, 16, 3, stride=2, padding=1) # number of weights = 3*3*
        img, label = training_data[99]
        conv(img).shape
Out[]: torch.Size([16, 16, 16])
In [ ]: import os
        torch.manual seed(17)
        DATASET MEAN = [0.4914, 0.4822, 0.4465]
        DATASET STD = [0.2470, 0.2435, 0.2616]
        # Getting the dataset, the Pytorch way
        all training data = torchvision.datasets.CIFAR10(
            root="data",
            train=True,
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                         DATASET STD)]) # dataset std
        test data = torchvision.datasets.CIFAR10(
            root="data",
            train=False,
            download=True,
            transform=Compose([ToTensor(),
                               Normalize(DATASET MEAN, # dataset mean
                                         DATASET STD)]) # dataset std
        training data, validation data = torch.utils.data.random split(all training
        training dataloader = DataLoader(training data, shuffle=True, batch size=bat
        validation dataloader = DataLoader(validation data, batch size=batch size)
        test dataloader = DataLoader(test data, batch size=batch size)
```

```
loss = torch.nn.CrossEntropyLoss()
 model = tnn.Sequential(
     tnn.Conv2d(3, 16, 3, padding=1), # 32x32 image 3 channels
     tnn.ReLU(),
     tnn.MaxPool2d(2), # -> 16x16 image with 16 channels
     tnn.Conv2d(16, 16, 3, padding=1), # 16x16 image with 16 channels
     tnn.MaxPool2d(2), # -> 8x8 image with 16 channels
     tnn.Flatten(),
     tnn.Linear(16*8*8, 100),
     tnn.ReLU(),
     tnn.Linear(100, 10))
 trained model = train(model, loss, training dataloader, validation dataloade
                      chkpt name='conv model chkpt.pt', ignore chkpt=True)
 test loss, correct = loss and accuracy(model, loss, test dataloader)
 print(f"Test Error: \n Accuracy: {(100*correct):>0.1f}%, Avg loss: {test los
Files already downloaded and verified
Files already downloaded and verified
Validation Error:
 Accuracy: 35.3%, Avg loss: 1.825797
Validation Error:
 Accuracy: 43.3%, Avg loss: 1.586233
```

In []: