

Before you turn this problem in, make sure everything runs as expected. First, **restart the kernel** (in the menubar, select Kernel→Restart) and then **run all cells** (in the menubar, select Cell→Run All).

Make sure you fill in any place that says `YOUR CODE HERE` or "YOUR ANSWER HERE", as well as your name and collaborators below:

In []: NAME = ""
COLLABORATORS = ""

Differentiation options

1. Numerical differentiation

2. Symbolic differentiation

3. Automatic differentiation

A. Forward mode differentiation

B. Reverse mode differentiation

Numpy \longleftrightarrow Pytorch
+ GPU
+ Automatic differentiation

def f(x):
 return

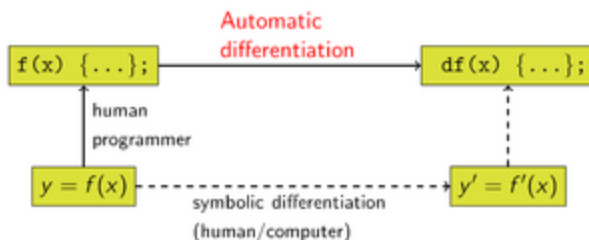
For
n-dim
 $O(n)$

1. Numerical differentiation :
derivative : $2n$ calls to function f

2. Symbolic differentiation

3. Automatic differentiation

check numerical-jacobian
 $\left. \frac{\partial f}{\partial x_i} \right|_z = \frac{f(z + \begin{bmatrix} \epsilon \\ 0 \\ \vdots \\ 0 \end{bmatrix}) - f(z)}{\epsilon}$ $\epsilon = 1e-6$
 $\frac{\partial f}{\partial x_i} = \frac{f(z + \begin{bmatrix} \epsilon \\ 0 \\ \vdots \\ 0 \end{bmatrix}) - f(z)}{\epsilon}$



3.A Forward mode

Example:

$$z = f(x_1, x_2) = x_1 x_2 + \sin(x_1)$$

3.B Reverse mode

② Symbolic diff. ^{close} [Automatic diff] Tensorflow
Pytorch
Jax

$x = \text{Symbol}()$
 $f = x^{**2} + 2**x$
 \downarrow $\text{grad}(f, x) \rightarrow$ print a functional form of derivative

Diff wrt
 Auto diff

- a) $\text{sym}'(\text{sym}(x))$ more optimizations possible in symbolic derivatives
- b) Derivative computation is done for all x input
- c) $f(x)$ has to be computed as a separate process

Auto. Diff

① Create a library of atomic function derivative function

atomic function	\longleftrightarrow	derivative function
$(f(x) + g(x))$	\longleftrightarrow	$\frac{d}{dx} f(x) + \frac{d}{dx} g(x)$
$*$		
$**$		
sin	\longleftrightarrow	cos
cos	\longleftrightarrow	-sin
exp	\longleftrightarrow	exp

② Write the function whose derivative you want in terms of the atomic functions

③ Then derivative of any program written in terms of atomic functions, can be computed by chain rule.
How?

$$f(x) = \exp(-x^{**}2)$$

$$f(x) = \exp(\underbrace{\underbrace{\underbrace{\text{mul}(-\underbrace{\text{pow}(x, 2), -1)}_{\text{deriv}})}_{y}}_{z})$$

$$f(x) = \underbrace{\frac{\partial \exp(z)}{\partial z}}_{(1)} \cdot \underbrace{\frac{\partial \text{mul}(y)}{\partial y}}_{(2)} \cdot \underbrace{\frac{\partial \text{pow}(x, 2)}{\partial x}}_{(1)}$$

Auto Diff { Forward diff (3)
 Reverse mode
Backward diff. (Backpropagation) } [computation complexity is diff.]

Example:

$$x_1 = \text{ForwardDiff}(1, 1)$$

$$x_2 = \text{ForwardDiff}(2, 0)$$

$$z = f(x_1, x_2) = x_1 x_2 + \sin(x_1)$$

$$x_1 + x_2$$

$$\text{ForwardDiff}(\sin(1), \cos(1))$$

$$\text{ForwardDiff}(2, 2)$$

```
In [ ]: import numpy as np
class ForwardDiff:
    def __init__(self, value, grad=None):
        self.value = value
        self.grad = np.zeros_like(value) if grad is None else grad

    def __add__(self, other):
        cls = type(self)
        other = other if isinstance(other, cls) else cls(other)
        out = cls(self.value + other.value,
                  self.grad + other.grad)
        return out
    __radd__ = __add__

    def __repr__(self):
        return f"{self.__class__.__name__}(data={self.value}, grad={self.grad})"

x = ForwardDiff(2, 1)
y = ForwardDiff(3, 0)
```

printing
this
class

f = x + y
f

$$f.\text{grad} = \frac{df}{dx}$$

$$f(x, y) = x + y$$

$$\frac{d}{dx} f(x, y) = \left[\frac{dx}{dx} \right] + \left[\frac{dy}{dx} \right] = 1 + 0 = 1$$

```
In [ ]: oldFD = ForwardDiff # Bad practice: do not do it
class ForwardDiff(oldFD):
    def __mul__(self, other):
        cls = type(self)
        other = other if isinstance(other, cls) else cls(other)
        out = cls(self.value * other.value,
                  other.value * self.grad +
                  self.value * other.grad)
        return out
    __rmul__ = __mul__

x = ForwardDiff(2, 0)
y = ForwardDiff(3, 1)
```

f1 = x * y
f2 = 2*x + 3*y + x*y
f1, f2

$$f(x, y) = x * y$$

$$\frac{d}{dz} f(x, y) = x \frac{dy}{dz} + y \frac{dx}{dz}$$

```
In [ ]: oldFD = ForwardDiff # Bad practice: do not do it
class ForwardDiff(oldFD):
    def log(self):
        cls = type(self)
        return cls(np.log(self.value),
                  1/self.value * self.grad)
    def exp(self):
        cls = type(self)
```

$$\frac{d}{dz} \log(x) = \frac{1}{x} \cdot \frac{dx}{dz}$$

```

out_val = np.exp(self.value)
return cls(out_val,
            out_val * self.grad)

def sin(self):
    cls = type(self)
    return cls(np.sin(self.value),
               np.cos(self.value) * self.grad)

def cos(self):
    cls = type(self)
    return cls(np.cos(self.value),
               -np.sin(self.value) * self.grad)

def __pow__(self, other):
    cls = type(self)
    other = other if isinstance(other, cls) else cls(other)
    return (self.log() * other).exp()

def __neg__(self): # -self
    return self * -1

def __sub__(self, other): # self - other
    return self + (-other)

def __truediv__(self, other): # self / other
    return self * other**-1

def __rtruediv__(self, other): # other / self
    return other * self**-1

```

$$\frac{d}{dz} \exp(x) = \exp(x) \frac{dx}{dz}$$

```

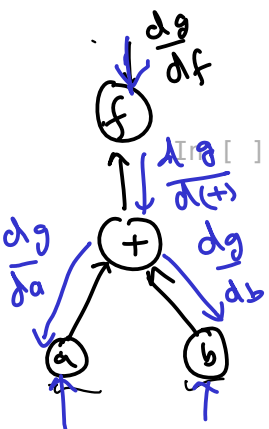
x = ForwardDiff(2, 1)
y = ForwardDiff(3, 0)

f = x**y
f

```

$$\frac{dx}{dz} = 1$$

$$\frac{dy}{dz} = 0$$



```

import numpy as np
def add_vjp(a, b, grad):
    return grad, grad

```

```

def no_parents_vjp(grad):
    return (grad,)

```

```

class ReverseDiff:

```

```

    def __init__(self, value, parents=(), op='', vjp=no_parents_vjp):
        self.value = value
        self.parents = parents
        self.op = op
        self.vjp = vjp
        self.grad = None

```

```

    def backward(self, grad):

```

vjp = vector-jacobian-product

$$f(a, b) = a + b$$

$$\frac{dg}{da} = \left[\frac{dg}{df} \cdot \frac{df}{da} \right] = \frac{dg}{df}$$

given $\frac{dg}{df}$

$$g(f)$$

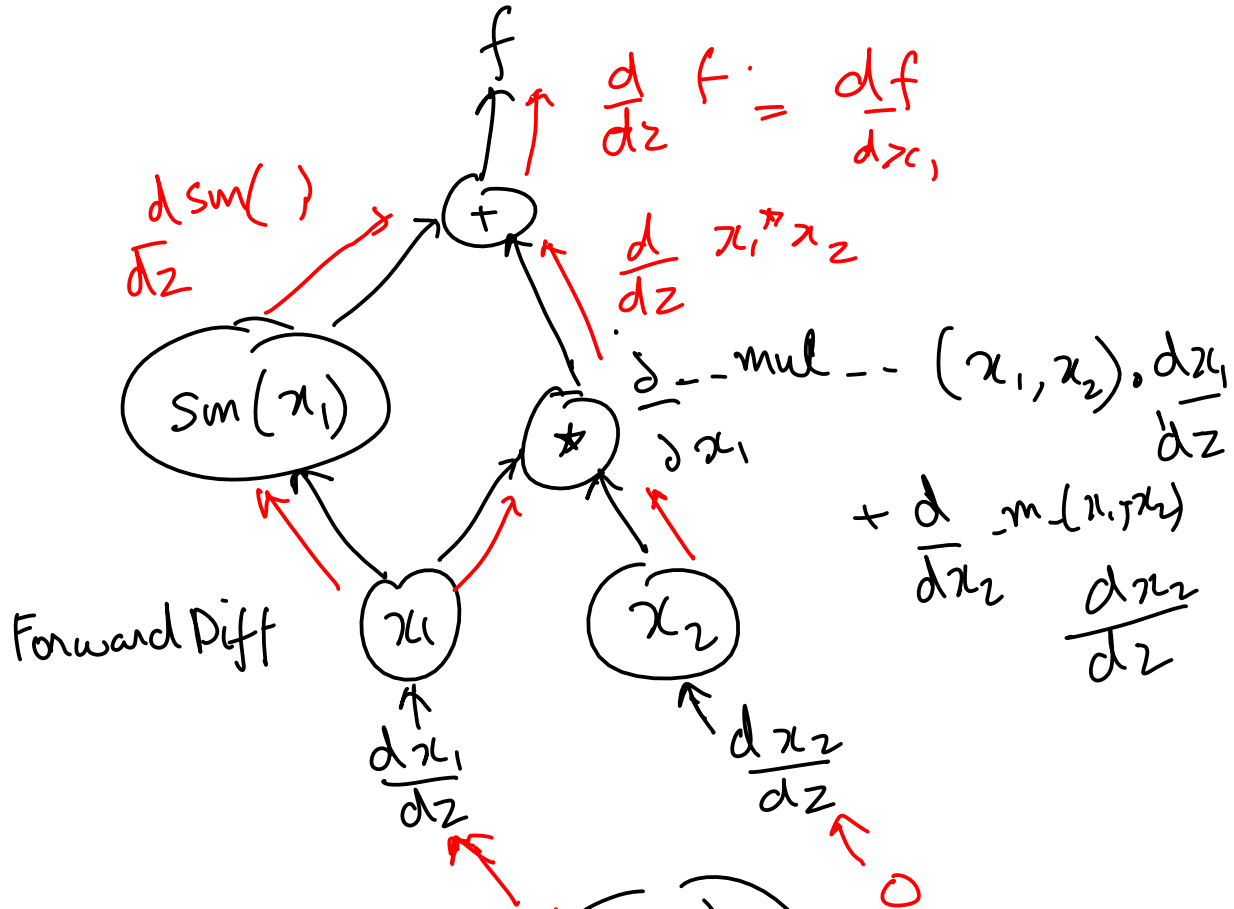
$$f(a, b) = a + b$$

arguments
to the operation

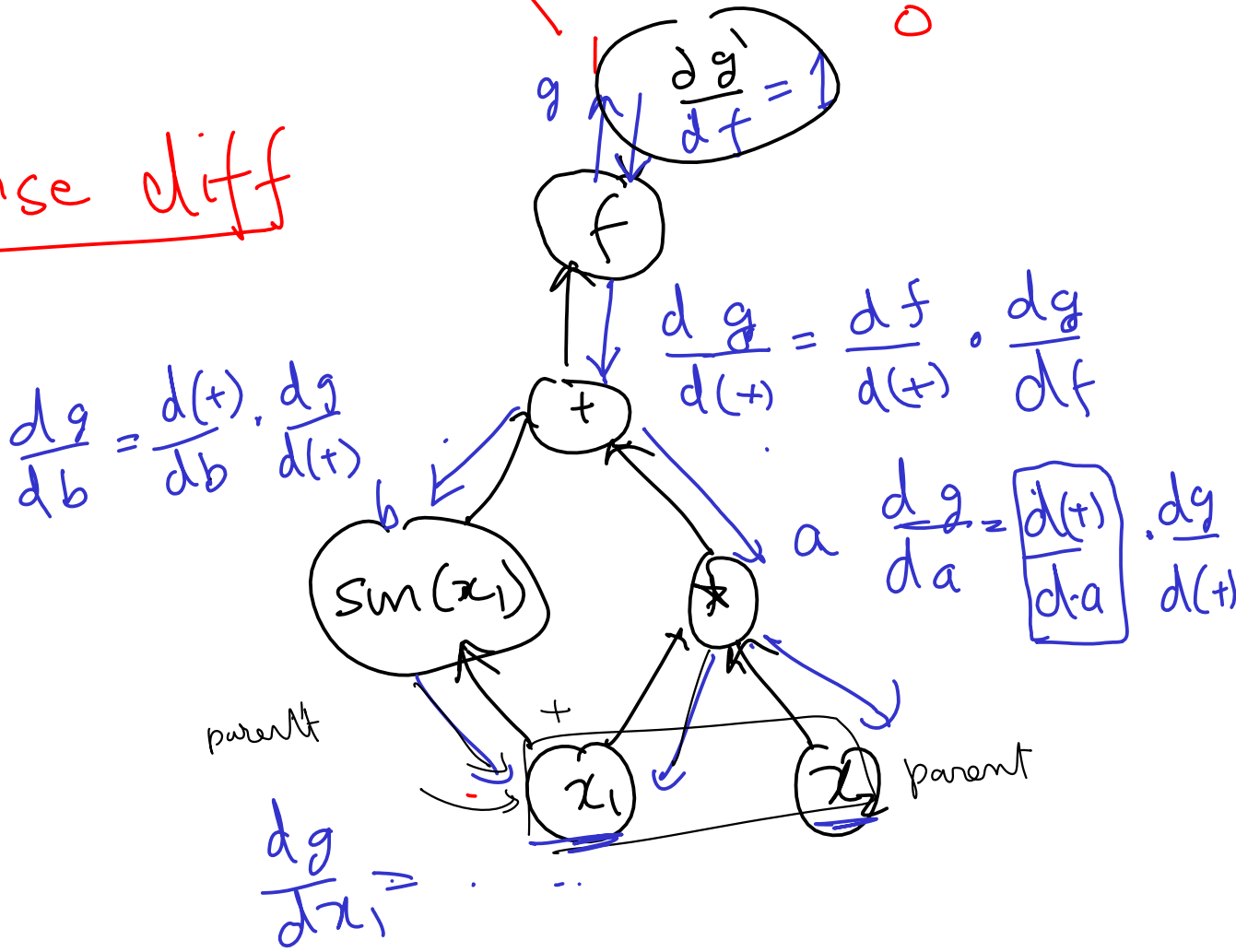
$$\frac{dg}{db} = \frac{dg}{df} \cdot \frac{df}{db} = \frac{dg}{df}$$

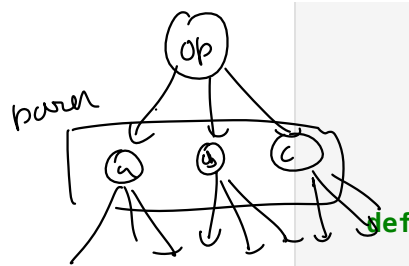
Forward Diff

$$f(x) = x_1^* x_2 + \sin(x_1)$$



Reverse diff





```

self.grad = grad + self.grad
op_args = [p.value for p in self.parents]
grads = self.vjp(*op_args, grad)
for g, p in zip(grads, self.parents):
    p.backward(g)

```

if self.grad is not None: grad

$x_1 = \text{ReverseDiff}(2)$
 $y = \text{Rev}$

```

def __add__(self, other):
    cls = type(self)
    other = other if isinstance(other, cls) else cls(other)
    out = cls(self.value + other.value,
               parents=(self, other),
               op='+',
               vjp=add_vjp)
    return out

__radd__ = __add__

def __repr__(self):
    cls = type(self)
    return f"{cls.__name__}(value={self.value}, parents={self.parents},

```

```

x = ReverseDiff(2)
y = ReverseDiff(3)

```

```

f = x + y + 3
f.backward(1)
f
x.grad, y.grad

```

$$\frac{dg}{df} = 1$$

In []: `oldRD = ReverseDiff # Bad practice: do not do it`

```

def mul_vjp(a, b, grad):
    return grad * b, grad * a

class ReverseDiff(oldRD):
    def __mul__(self, other):
        cls = type(self)
        other = other if isinstance(other, cls) else cls(other)
        out = cls(self.value * other.value,
                   parents=(self, other),
                   op='*',
                   vjp=mul_vjp)
        return out

    __rmul__ = __mul__

```

```

x = ReverseDiff(2)
y = ReverseDiff(3)

```

```

f1 = 5*x + 7*y
f1.backward(1)
x.grad, y.grad

```

$$g = f_1$$

$$\frac{dg}{df} = 1$$

In []: `f2 = x*y`
`f2.backward(1)`

$$f(g(h(x)))$$

$$\frac{\partial f(g(h(x)))}{\partial x} = \frac{\partial f}{\partial g} \cdot \frac{\partial g}{\partial h} \cdot \frac{\partial h}{\partial x}$$

Forward diff

$$\frac{\partial f(g(h(x)))}{\partial x} = \left(\frac{\partial f}{\partial g} \left(\frac{\partial g}{\partial h} \left(\frac{\partial h}{\partial x}, \frac{dx}{dz} \right) \right) \right)$$

Forward diff

$$\frac{dx}{dz} = 1$$

$$\text{sum} = 0$$

for i in range(10):

sum += i

Reverse mod diff

$$\frac{\partial f(g(h(x)))}{\partial x} = \left(\left(\frac{\partial g}{\partial f}, \frac{\partial f}{\partial g} \right) \frac{\partial g}{\partial h} \right) \frac{\partial h}{\partial x}$$

Reverse diff

Computational complexity of Forward Diff
 \propto number of inputs

Computational complexity of Reverse mode dfl
 \propto number of outputs
