



- The most probable (Max a Posteriori (MAP)) labelling is defined as:

$$\mathbf{x}^* = \arg \max_{\mathbf{x} \in \mathbf{L}} \Pr(\mathbf{x} | \mathbf{D}) = \arg \min_{\mathbf{x} \in \mathbf{L}} E(\mathbf{x})$$