Data term
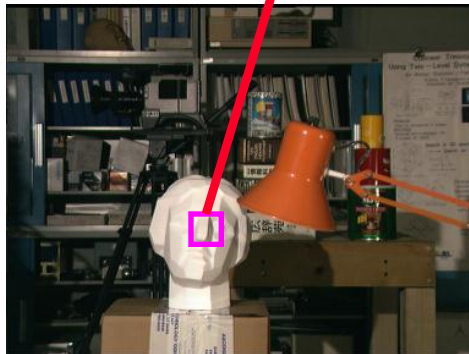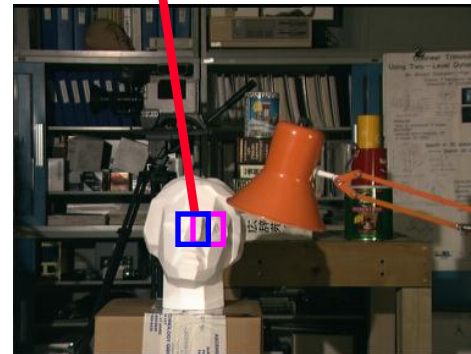
$$\psi_i(z_i) = d(\boxed{F^L(x_i, y_i)}, \boxed{F^R(x_i - z_i, y_i)})$$

Left image feature

Shifted right image feature

Left Camera Image

Right Camera Image