## **Dense Stereo Estimation**

## **Data term**

$$\psi_i(z_i) = d(F^L(x_i, y_i), F^R(x_i - z_i, y_i))$$
 Left image Shifted right feature image feature

## **Smoothness term**

$$\psi_{ij}(z_i, z_j) = K|z_i - z_j|$$