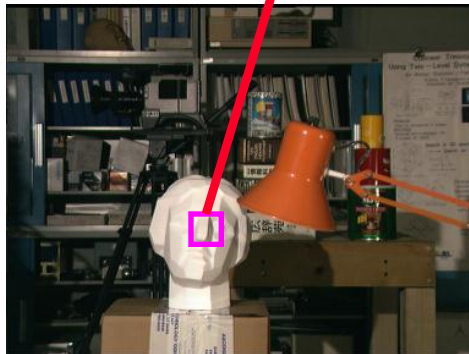


Dense Stereo Estimation

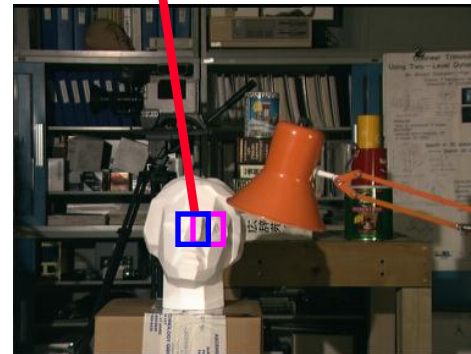
Data term

$$\psi_i(z_i) = d(\boxed{F^L(x_i, y_i)}, \boxed{F^R(x_i - z_i, y_i)})$$

**Left image
feature** **Shifted right
image feature**



Left Camera Image



Right Camera Image