

Vikas Dhiman

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RESEARCH INTERESTS

Safe Control, Machine Learning, Robotics, Localization, Mapping, and Navigation

WORK EXPERIENCE

Postdoctoral Researcher

Jacobs School of Engineering, University of California San Diego

Advisors: Prof. Henrik Christensen and Prof. Nikolay Atanasov

Primary Focus: Safe control of robots under uncertainty, learning navigation costs from imitation, tightly coupled semantic localization, and visual-inertial odometry and game-theoretic patrolling with heterogeneous agents.

San Diego, CA

March 2019 - Present

Research Assistant

EECS, University of Michigan

Advisor: Prof. Jason J. Corso

Primary Focus: Localization, mapping, and navigation in mobile robots using probabilistic graphical models and reinforcement learning.

Ann Arbor, MI

Aug 2014 - Dec 2018

Research Intern

NEC Lab America, INC.

Mentor: Prof. Manmohan Chandraker

Project: Occlusion-aware models for localization

Cupertino, CA

May 2014 - Aug 2014

Research Assistant

Dept. of CSE, State University of New York at Buffalo

Advisor: Prof. Jason J. Corso

Primary Focus: Multi-robot localization, mapping, and navigation in mobile robots for search and rescue.

Buffalo, NY

Jan 2012 - May 2014

Senior IT Engineer

D.E. Shaw Software India Private Ltd.

Responsibilities: Automation of data collection, scraping, parsing, and visualization jobs.

Hyderabad, India

2008 - 2012

EDUCATION

University of Michigan

Ph.D. in Electrical and Computer Engineering

Advisor: Jason J. Corso

Dissertation title: Towards Better Navigation: Optimizing Algorithms for Mapping, Localization and Planning

Ann Arbor, MI

2014 - 2018

State University of New York at Buffalo

M.S. in Computer Science and Engineering

Buffalo, NY

2012 - 2014

Indian Institute of Technology Roorkee, India

B.S. in Electrical Engineering

Roorkee, India

2004 - 2008

PUBLICATIONS ¹

13. **V. Dhiman***, M. J. Khojasteh*, M. Franceschetti, and N. Atanasov. Control barriers in Bayesian learning of system dynamics. *IEEE Transactions on Automatic Control (Under Review)*, 2020 (Submitted).
12. T. Wang, **V. Dhiman**, and N. Atanasov. Inverse reinforcement learning for autonomous navigation via differentiable semantic mapping and planning. *International Journal of Robotics Research (Under Review)*, 2020 (Submitted).

¹h5-Index (h5) provided by Google Scholar. CVPR, AAAI, IROS and ICRA are premier conferences in computer vision and Robotics. For each, typical number of submissions is around 2000 and the overall acceptance rate is around 25%. CVPR is the highest rated publication venue for computer vision and eighth-highest across all engineering and computer science, according to Google Scholar metrics.

11. M. Shan, **V. Dhiman**, Q. Feng, J. Li, and N. Atanasov. OrcVIO: Object residual constrained Visual-Inertial Odometry. *IEEE Transactions on Robotics (Under Review)*, 2020 (Submitted).
10. M. J. Khojasteh*, **V. Dhiman***, M. Franceschetti, and N. Atanasov. Probabilistic safety constraints for learned high relative degree system dynamics. In *Proceedings of the 2nd Conference on Learning for Dynamics and Control*, volume 120 of *Proceedings of Machine Learning Research*, pages 781–792, The Cloud, 10–11 Jun 2020. PMLR.
9. T. Wang, **V. Dhiman**, and N. Atanasov. Learning navigation costs from demonstration with semantic observations. In *Learning for Dynamics and Control*. PMLR, 2020.
8. T. Wang, **V. Dhiman**, and N. Atanasov. Learning navigation costs from demonstration in partially observable environments. In *IEEE International Conference on Robotics and Automation (ICRA)*, pages 4434–4440, 2020. (h5: 71)
7. J. Bi, **V. Dhiman**, T. Xiao, and C. Xu. Learning from interventions using hierarchical policies for safe learning. In *AAAI Conference on Artificial Intelligence*, volume 34, pages 10352–10360, 2020. (h5: 56)
6. S. Kumar, **V. Dhiman**, P. A. Koch, and J. J. Corso. Learning compositional sparse bimodal models. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 40(5):1032–1044, 2018. (h5: 114)
5. **V. Dhiman**, Q. Tran, J. Corso, and M. Chandraker. A continuous occlusion model for road scene understanding. In *IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, pages 4331–4339, June 2016. (h5: 158)²
4. **V. Dhiman**, A. Kundu, F. Dellaert, and J. J. Corso. Modern MAP inference methods for accurate and faster occupancy grid mapping on higher order factor graphs. In *IEEE International Conference on Robotics and Automation (ICRA)*, 2014. (h5: 71)
3. S. Kumar, **V. Dhiman**, and J. J. Corso. Learning compositional sparse models of bimodal percepts. In Carla E. Brodley and Peter Stone, editors, *Proceedings of AAAI Conference on Artificial Intelligence*, pages 366–372. AAAI Press, 2014. (h5: 56)
2. J. Ryde, **V. Dhiman**, and R. Platt. Voxel planes: Rapid visualization and meshification of point cloud ensembles. In *IEEE/RSJ International Conference on Intelligent Robots and Systems*, 2013. (h5: 50)
1. **V. Dhiman**, J. Ryde, and J. J. Corso. Mutual localization: Two camera relative 6-dof pose estimation from reciprocal fiducial observation. In *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2013. (h5: 50)

SOFTWARE

Control Barriers in Bayesian Learning of System Dynamics

github.com/wecacuee/Bayesian_CBF

A critical investigation of Deep-Reinforcement Learning for Navigation

github.com/umrobotslang/does-drl-learn-to-navigate

Learning compositional sparse bimodal models

bitbucket.org/surenkum/bimodal_sparse

Modern MAP inference methods for occupancy grid mapping on higher order factor graphs.

github.com/wecacuee/modern-occupancy-grid

Voxel Planes: Rapid visualization and meshification of point cloud ensembles

bitbucket.org/wecacuee/voxelplanes

Mutual Localization: Two camera relative 6-dof pose estimation from reciprocal fiducial observation.

github.com/wecacuee/mutual_localization

TEACHING

Lecture on Filtering and SLAM (Course: Introduction to Robotics)

Oct 2019

bit.ly/2W2rrfZ

A lecture on Simultaneous Localization and Mapping with slides adapted from Prof Henrik Christensen. I developed a simple jupyter notebook example of EKF implementation as a part of exposure to SLAM concepts.

Lecture on Probabilistic graphical models (Course: Computer Vision)

Nov 2017

vikasdhiman.info/eecs442/20171109.html

A lecture on the basics of probabilistic graphical models in class on introduction to computer vision. The students had limited background in machine learning and probability.

Lecture on OpenGM2 at (Course: Probabilistic Graphical Models)

Jan 2015

github.com/wecacuee/opengmdemo

A lecture on the usage of the library OpenGM2 with an in class demo of OpenGM2 library applied to a simple problem. This gave the students a quick start on their course projects.

Outreach on Computer Vision and Pinhole Cameras (Camp: Xplore Engineering)

Jun 2015, 2016

vikasdhiman.info/xplore-workshop/pinhole.pdf

Organized a workshop for middle school students to create interest in sciences and the field of computer vision and explain modern cameras through pinhole cameras.

SERVICE AS REVIEWER

- IEEE Control Systems Letters Submission 2020
- IEEE American Control Conference 2020
- IEEE Robotics and Automation Letters 2019
- IEEE International Conference on Robotics and Automation 2014, 2016 - 18, 2020
- IEEE/RSJ International Conference on Intelligent Robots and Systems 2013, 2016, 2020
- IEEE Conference on Computer Vision and Pattern Recognition 2014, 2016
- Indian Conference on Computer Vision, Graphics and Image Processing 2014, 2016
- Association for the Advancement of Artificial Intelligence 2015
- International Journal of Computer Vision 2014
- International Journal of Robotics Research 2016

REFERENCE LIST

Jason J. Corso

jjcorso@umich.edu

Associate Professor, EECS, University of Michigan, Ann Arbor, MI.

Henrik Christensen

hichristensen@ucsd.edu

Director, Institute of Contextual Robotics, University of California San Diego, San Diego, CA.

Nikolay Atanasov

natanasov@ucsd.edu

Assistant Professor, ECE, University of California, San Diego, CA.