JINXIN LIU

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★ Core Deep Learning: distribution shift; robust; self-supervised models; DA/DG.



[Under review]

EDUCATION

2019.09 - 2024.06 **Zhejiang University** Ph.D., Computer Science Hangzhou, China ★ Zhejiang University & Westlake University Joint Ph.D. Program ★ Advisor: Prof. Donglin Wang **Chongqing University of Posts and Telecommunications** 2015.09 - 2019.06 B.Eng., Communications Engineering Chongqing, China ★ Cumulative GPA: 3.8/4.0 Rank: 1/42 (for four consecutive years) RESEARCH INTERESTS ★ Deep RL: model-free RL; unsupervised RL and skill learning; offline RL; planning and inference.

Large Model:

[4] **Jinxin L**, Lipeng Z, Li H, and Donglin W.

CLUE: Calibrated Latent Guidance for Offline Reinforcement Learning. PDF

★ Large Model:		
SELECTED PUBLICATIONS		
[1] Jinxin L , Hongyin Z, and Donglin W.	[ICLR, 2022]	
DARA: Dynamics-Aware Reward Augmentation in Offline Reinforcement Learning. PDF		
[2] Jinxin L, Donglin W, Qiangxing T, and Zhengyu C.	[AAAI, 2022]	
Learn Goal-Conditioned Policy with Intrinsic Motivation for Deep Reinforcement Learning. PDF		
[3] Jinxin L, Hao S, Donglin W, Yachen K, and Qiangxing T.	[NeurIPS, 2021]	
Unsupervised Domain Adaptation with Dynamics-Aware Rewards in Reinforcement Learning. PDF		
[4] Zifeng Z, Kun L, Jinxin L, Donglin W, and Yilang G.	[ICLR, 2023]	
Behavior Proximal Policy Optimization. PDF		
[5] Yao L, <u>Jinxin L</u> , Zhentao T, Bin W, Jianye H, and Ping L.	[ICML, 2023]	
ChiPFormer: Transferable Chip Placement via Offline Decision Transformer.		
[6] Yachen K, Diyuan S, <u>Jinxin L</u> , Li H, and Donglin W.	[ICML, 2023]	
Beyond Reward: Offline Preference-Guided Policy Optimization. PDF		
[7] Qiangxing T, Guanchu W, <u>Jinxin L</u> , Donglin W, and Yachen K.	[IJCAI, 2020]	
Independent Skill Transfer for Deep Reinforcement Learning. PDF		
[8] Qiangxing T, <u>Jinxin L</u> , Donglin W, and Ao T.	[CIKM, 2019]	
Time Series Prediction with Interpretable Data Reconstruction. PDF		
SELECTED PREPRINTS		
[1] Jinxin L, Li H, Yachen K, Zifeng Z, Donglin W, and Huazhe X.	[Under review]	
CEIL: Generalized Contextual Imitation Learning. PDF		
[3] Jinxin L, Hongyin Z, Zifeng Z, Yachen K, Donglin W, and Bin W.	[Under review]	
Design from Policies: Conservative Test-Time Adaptation for Offline Policy Optimization. PDF		
[2] <u>Jinxin L</u> , Ziqi Z, Zhenyu W, Zifeng Z, Yachen K, Sibo G, and Donglin W.	[Under review]	
Beyond OOD State Actions: Supported Cross-Domain Offline Reinforcement Learning. PDF		

INTERNSHIP EXPERIENCE

National Scholarship

First Prize of China Undergraduate Mathematical Contest in Modeling

★ Research Intern (2022.06 - 2022.10)	Noah's Ark Lab, Huaw
Finished with two papers on [1] chip placement tasks and [2] standar [1] We proposed ChiPFormer that can exploit offline placement deseffective finetuning for unseen chip circuits, and reduce the placement [2] We proposed DROP that can exploit offline placement designs to	signs to learn transferable policies, promont runtime from hours to minutes. PDF learn transferable policies, promote effectives.
finetuning for unseen chip circuits, and reduce the placement runtime	e from hours to minutes. PDF
★ Visiting Student (2018.10 - 2019.05)	Westlake Universi
Finished with two papers on time series prediction: [PDF] & [PDF].	
ACADEMIC SERVICES	
★ Talks	
[2] Beyond Design from Data: Design from Policies is All You	
[3] Control as Inference: A General Review	Second Research Institute of CASI
[4] Unsupervised Reinforcement Learning for Skill Discovery	Westlake Robot Learning Symposiu
[5] Hi, Robot: Training a Versatile Robot from Scratch[6] Time Series Prediction with Interpretable Data Reconstruct	Talk to the Future, Westlake Universi
*	tion Zhejiang Universi
★ Teaching	Head TA in Fell 2021 and Spring 202
[1] Deep Reinforcement Learning	Head TA in Fall 2021 and Spring 202
★ Conference Reviewer	A and amin Comin
ICML, ICLR, NeurIPS, IJCAI, AAAI, KDD, and IROS.	Academic Service
RESEARCH PROJECT	
★ Government Sponsored Research	Core Membe
[1] NSFC General Program	Grant No. 6217621
[2] National Science and Technology Innovation 2030 - <i>Major</i>	•
[3] Development of the Blind-Guiding Quadruped Robot Syste	· ·
★ Company Sponsored Research	Core Membe
[1] Machine Learning and Robot Behavioral Learning	Bright Dream Robotics, Guangdor
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	estlake UniMuyuan Joint Research Ins
SELECTED AWARDS & HONORS	
Outstanding Student	202
Best Poster Award at WISE 2021	202
Suwu Scholarship	202
Second Prize of National Mobile Internet Application Develop	-
Advanced Individuals of Scientific and Technological Innovation	on 201

2017

2017