JINXIN LIU   研究方向: 强化学习

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EDUCATION 教育

浙江大学, 西湖大学   2019.09 - 2024.06
博士研究生, 计算机科学与技术   Hangzhou, China

★ Zhejiang University & Westlake University Joint Ph.D. Program
★ Advisor: Prof. Donglin Wang (国家科技创新 2030 重大项目, 首席科学家)

重庆邮电大学   2015.09 - 2019.06
工学学士, 通信工程, 卓越工程师班   Chongqing, China

★ Cumulative GPA: 3.8/4.0   Rank: 1/42 (连续 4 年 排名第一)

RESEARCH INTERESTS 研究经历

★ **Deep Reinforcement Learning (RL)**: focusing on general and ready-to-be-deployed RL algorithms,
  i.e., imitation learning, reward-free RL, unsupervised RL (learning skills), and RL in real-world tasks (games).

★ **Planning and Inference**: offline RL, offline-to-online RL, embodied agent, and design from data.

★ **Distribution Shift**: RL dynamics/embodiment adaptation, multi-goal RL, sim2real, and sample-efficient RL.

SELECTED PUBLICATIONS 部分文章

[1] **Jinxin L**, Li H, Yachen K, Zifeng Z, Donglin W, and Huazhe X.   [NeurIPS, 2023]
  CEIL: Generalized Contextual Imitation Learning. [PDF](#)

[2] **Jinxin L**, Hongyin Z, Zifeng Z, Yachen K, Donglin W, and Bin W.   [NeurIPS, 2023]
  Design from Policies: Conservative Test-Time Adaptation for Offline Policy Optimization. [PDF](#)

[3] **Jinxin L**, Lipeng Z, Li H, and Donglin W.   [CoRL, 2023]
  CLUE: Calibrated Latent Guidance for Offline Reinforcement Learning. [PDF](#)

[4] **Jinxin L**, Hongyin Z, and Donglin W.   [ICLR, 2022]
  DARA: Dynamics-Aware Reward Augmentation in Offline Reinforcement Learning. [PDF](#)

[5] **Jinxin L**, Donglin W, Qiangxing T, and Zhengyu C.   [AAAI, 2022]
  Learn Goal-Conditioned Policy with Intrinsic Motivation for Deep Reinforcement Learning. [PDF](#)

[6] **Jinxin L**, Hao S, Donglin W, Yachen K, and Qiangxing T.   [NeurIPS, 2021]
  Unsupervised Domain Adaptation with Dynamics-Aware Rewards in Reinforcement Learning. [PDF](#)

[7] Zifeng Z, Kun L, **Jinxin L**, Donglin W, and Yilang G.   [ICLR, 2023]
  Behavior Proximal Policy Optimization. [PDF](#)

[8] Yao L, **Jinxin L**, Zhentao T, Bin W, Jianye H, and Ping L.   [ICML, 2023]
  ChiPFormer: Transferable Chip Placement via Offline Decision Transformer. [PDF](#)

[9] Yachen K, Diyuan S, **Jinxin L**, Li H, and Donglin W.   [ICML, 2023]
  Beyond Reward: Offline Preference-Guided Policy Optimization. [PDF](#)

[10] Qiangxing T, Guanchu W, **Jinxin L**, Donglin W, and Yachen K.   [IJCAI, 2020]
  Independent Skill Transfer for Deep Reinforcement Learning. [PDF](#)

[11] Qiangxing T, **Jinxin L**, Donglin W, and Ao T.   [CIKM, 2019]
  Time Series Prediction with Interpretable Data Reconstruction. [PDF](#)

SELECTED PREPRINTS 最新工作

[1] **Jinxin L**, Ziqi Z, Zhenyu W, Zifeng Z, Yachen K, Sibo G, and Donglin W.   [Under review]
  Beyond OOD State Actions: Supported Cross-Domain Offline Reinforcement Learning. [PDF](#)

INTERNSHIP EXPERIENCE 实习经历

★ Research Intern (2022.06 - 2022.10)   Noah's Ark Lab, Huawei

Finished with two papers on [1] **chip placement tasks** and [2] **standard offline reinforcement learning tasks**:

[1] We proposed ChiPFormer that can exploit offline placement designs to learn transferable policies, promote effective finetuning for unseen chip circuits, and *reduce the placement runtime from hours to minutes*. [PDF]

[2] We proposed Design fROm Policies that decouples the iterative bi-level offline RL from the offline training phase, *forming a non-iterative bi-level paradigm and avoiding the iterative error propagation over two levels.* [PDF]

★ Visiting Student (2018.10 - 2019.05)   Westlake University

Early-stage research training: finished with two papers (1st author) on time series prediction: [PDF] & [PDF].

ACADEMIC SERVICES 学术

★ Talks

[1] *Beyond Design from Data: Design from Policies is All You Need*   Ali Cloud, Alibaba

[2] *Diffusion-Guided Diversity for Offline RL*   Noah's Ark Lab, Huawei

[3] *Control as Inference: A General Review*   Second Research Institute of CASIC

[4] *Unsupervised Reinforcement Learning for Skill Discovery*   Westlake Robot Learning Symposium

[5] *Hi, Robot: Training a Versatile Robot from Scratch*   Talk to the Future, Westlake University

[6] *Time Series Prediction with Interpretable Data Reconstruction*   Zhejiang University

★ Teaching

[1] Deep Reinforcement Learning   Head TA in Fall 2021 and Spring 2023

★ Conference Reviewer

ICML, ICLR, NeurIPS, IJCAI, AAAI, KDD, and IROS.   Academic Services

RESEARCH PROJECT 研究课题

★ Government Sponsored Research

[1] NSFC General Program (*Deep RL on real quadruped robot*)   Grant No. 62176215

[2] National Science and Technology Innovation 2030 - *Major Project*   Grant No. 2022ZD0208800

[3] Development of the Blind-Guiding Quadruped Robot System   Hangzhou 2022 Asian Games

★ Company Sponsored Research

[1] Machine Learning and Robot Behavioral Learning   Bright Dream Robotics, Guangdong

[2] Quadruped Robot Platform on Farmland Protection   Westlake Uni.-Muyuan Joint Research Inst.

[3] Development of Low Cost Navigation Equipment   Westlake Uni.-Muyuan Joint Research Inst.

Responsible for   Core Members

○ RL theory: research on RL sample efficiency, domain adaptation, and sim2real issues.

○ Real-world robot deployment: Deploying RL algorithms on a robotic arm and a quadruped robot.

SELECTED AWARDS & HONORS 荣誉奖励

Outstanding Student (<10%)	2022
Su-Wu Scholarship (<5%)	2021
Best Poster Award at WISE 2021 (<5%)	2021
The only Grand Prize at Electronic Design Innovation Challenge (<1%)	2018
Advanced Individuals of Scientific and Technological Innovation (<5%)	2018
Second Prize of National Mobile Internet Application Development Competition (<10%)	2018
National Scholarship (<5%)	2017
First Prize of China Undergraduate Mathematical Contest in Modeling (Chongqing; <5%)	2017
National Encouragement Scholarship (<10%)	2016