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**Initial condition:** Specify the physical state at a particular time  $t_0$

Heat/Diffusion equation: The initial condition (e.g., temperature, concentration, ....)

$$u_t - ku_{xx} = 0; \quad u(x, 0) = \phi(x). \quad (51)$$

$$u = u(t, \vec{x})$$

$$u(t=t_0, \vec{x}) = \phi(\vec{x})$$

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- Wave equation: A pair of initial conditions

$$u_{tt} - c^2 u_{xx} = 0; \quad u(x, 0) = \phi(x), \quad u_t(x, 0) = \psi(x). \quad (52)$$

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### Boundary condition

Let  $D$  be a domain on which a PDE is defined. Let  $\mathbf{n}$  be the unit outer normal vector on  $\partial D$ . Let  $\Gamma \subseteq \partial D$ . The three most important kinds of boundary conditions are

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2. Neumann boundary condition:  $\frac{\partial u}{\partial \mathbf{n}}|_{\Gamma} = g(\mathbf{x}, t);$



directional derivative

(flux across the boundary  $\Gamma$ )

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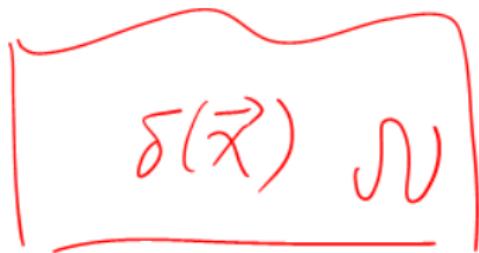
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On the whole boundary  $\partial D$ , one of these boundary conditions or a mixing of them could be imposed.

If the boundary data  $g(\mathbf{x}, t) = 0$  are set to be constantly zero, the boundary conditions are said to be **homogeneous**, otherwise, they are **inhomogeneous**.

## §1.5 Well-posedness of a PDE

A PDE in a domain  $D$  together with a set of initial and/or boundary conditions (or other auxiliary conditions) is said to be well-posed, if it meets the following three fundamental properties:

- (i) **Existence** — There exists at least one solution to the differential equation.

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- (i) **Existence** — There exists at least one solution to the differential equation.
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There exists a unique solution.

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- (ii) **Uniqueness** — Physical processes are causal: given the state at some time we should be able to produce only one state at all later times. There exists a unique solution.
- (iii) **Stability** — Small changes in the initial and/or boundary conditions (or other auxiliary conditions) should lead to small changes in the output. This means that if the data are changed a little, the  $\|\vec{b} - \vec{b}\| << 1$  corresponding solution changes only a little.

$$A \vec{x} = \vec{b}$$

If  $\vec{b}$  changes to  $\vec{b} + \delta\vec{b}$   
how about  $\vec{x}$

## §1.5 Well-posedness of a PDE

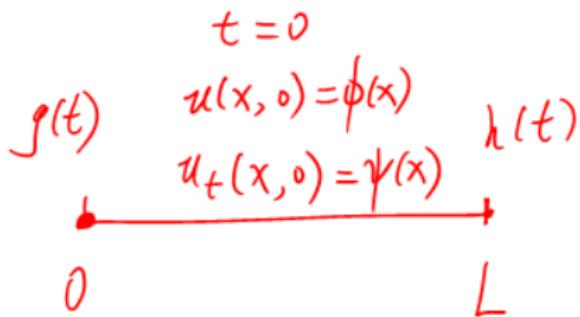
### Example: A well-posed problem

A vibrating string with an external force, whose ends are moved in a specified way, satisfies the problem

$$Tu_{tt} - \rho u_{xx} = f(x, t) \quad (53)$$

with the initial and boundary conditions for  $0 < x < L$ :

$$\begin{aligned} u(x, 0) &= \phi(x), & u_t(x, 0) &= \psi(x), \\ u(0, t) &= g(t), & u(L, t) &= h(t). \end{aligned}$$



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- The data for this problem consist of the five functions  $f(x, t)$ ,  $\phi(x)$ ,  $\psi(x)$ ,  $g(t)$ , and  $h(t)$ .

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- Stability** would mean that if any of these five functions are slightly perturbed, then  $u$  is also changed only slightly.

$$|\Delta u|_{L_2} < \alpha |\Delta g|_{L_2}$$

$$\begin{aligned} g(t) &\rightarrow g_1(t) \\ u(t, x) &\rightarrow u(t, x) + \Delta u \end{aligned}$$

## §1.6 Types of Second-Order Equations

$$u = u(x, y)$$

Second-order linear PDE

Let's consider the PDE

$$a_{11}u_{xx} + 2a_{12}u_{xy} + a_{22}u_{yy} + a_1u_x + a_2u_y + a_0u = 0. \quad (54)$$

This is a linear equation of order two in two variables with six real constant coefficients.

The factor 2 is introduced for convenience, largely due to the fact that

$$a_{12}u_{xy} + a_{21}u_{yx} = 2a_{12}u_{xy}. \quad (55)$$

$u_{xy} = u_{yx}$  is assumed

## §1.6 Types of Second-Order Equations

**Theorem:** Let  $A = \begin{bmatrix} a_{11} & \underline{\underline{a_{12}}} \\ \underline{\underline{a_{12}}} & a_{22} \end{bmatrix}$ . Then

- Equation (54) is of **elliptic type**, if  $\det(A) = a_{11}a_{22} - a_{12}^2 > 0$ . By a linear transform, it can be reduced to

$$u_{xx} + u_{yy} + \{ \text{terms of lower order 1 or 0} \} = 0. \quad (56)$$

$$\Delta u(x, y) = 0 \iff u_{xx} + u_{yy} = 0$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{Det}(A) = | > 0$$

$$\text{Eigenvalues : } \lambda_1 = \lambda_2 = 1 > 0$$

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- Equation (54) is of **hyperbolic type**, if  $\det(A) = a_{11}a_{22} - a_{12}^2 < 0$ . By a linear transform, it can be reduced to

$$u_{xx} - u_{yy} + \{\text{terms of lower order 1 or 0}\} = 0. \quad (57)$$

$$u_{tt} - c^2 u_{xx} = 0$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & -c^2 \end{pmatrix} \quad \text{Det}(A) = -c^2 < 0$$
$$\lambda_1 = 1 > 0, \lambda_2 = -c^2 < 0$$

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- Equation (54) is of **parabolic type**, if  $\det(A) = a_{11}a_{22} - a_{12}^2 = 0$ . By a linear transform, it can be reduced to

$$u_t - k u_{xx} = 0$$

$$u_{xx} + \{\text{terms of lower order 1 or 0}\} = 0, \quad (58)$$

(unless  $a_{11} = a_{12} = a_{22} = 0$ .)

$$A = \begin{pmatrix} 0 & 0 \\ 0 & -k \end{pmatrix} \quad \begin{aligned} \det(A) &= 0 \\ \lambda_1 &= 0 \\ \lambda_2 &= -k \end{aligned}$$

## §1.6 Types of Second-Order Equations

Representatives of three types

- Laplace equation:

$$u_{xx} + u_{yy} = 0 \quad (59)$$

We have  $a_{11} = a_{22} = 1$ ,  $a_{12} = 0$  so  $\det(A) = 1$ . It is **elliptic type**.

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- Wave equation:

$$u_{tt} - c^2 u_{xx} = 0 \quad (60)$$

We have  $a_{11} = 1$ ,  $a_{22} = -c^2$ ,  $a_{12} = 0$  so  $\det(A) = -c^2$ . It is **hyperbolic type**.

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We have  $a_{11} = 1, a_{22} = -c^2, a_{12} = 0$  so  $\det(A) = -c^2$ . It is **hyperbolic type**.

- Heat equation:

$$u_t - ku_{xx} = 0 \quad (61)$$

We have  $a_{11} = 0, a_{22} = -k, a_{12} = 0$  so  $\det(A) = 0$ . It is **parabolic type**.

## §1.6 Types of Second-Order Equations

### Example 1.

Classify each of the equations

(a)  $u_{xx} - 5u_{xy} = 0.$

(b)  $4u_{xx} - 12u_{xy} + 9u_{yy} + u_y = 0.$

(c)  $4u_{xx} + 6u_{xy} + 9u_{yy} = 0.$

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Classify each of the equations

$$(1-\lambda)(-\lambda) - \frac{25}{4} = 0$$

$$\lambda^2 - \lambda - \frac{25}{4} = 0$$

$$B = \begin{pmatrix} 4 & -6 \\ -6 & 9 \end{pmatrix}$$

$$(a) u_{xx} - 5u_{xy} = 0.$$

$$(\lambda - \frac{1}{2})^2 = \frac{13}{2}$$

$$(b) 4u_{xx} - 12u_{xy} + 9u_{yy} + u_y = 0.$$

$$(c) 4u_{xx} + 6u_{xy} + 9u_{yy} = 0.$$

$$\lambda_1 = \frac{1}{2} + \sqrt{\frac{13}{2}} > 0$$

**Solution:** We see that

$$\lambda_2 = \frac{1}{2} - \sqrt{\frac{13}{2}} < 0$$

- (a)  $a_{11} = 1, a_{22} = 0, a_{12} = -5/2 \Rightarrow a_{11}a_{22} - a_{12}^2 = -25/4 < 0 \Rightarrow$   
hyperbolic equation.

$$A = \begin{pmatrix} 1 & -\frac{5}{2} \\ -\frac{5}{2} & 0 \end{pmatrix}$$

$$\det(A) = -\frac{25}{4} < 0$$

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**Solution:** We see that

(a)  $a_{11} = 1, a_{22} = 0, a_{12} = -5/2 \Rightarrow a_{11}a_{22} - a_{12}^2 = -25/4 < 0 \Rightarrow$  hyperbolic equation.

(b)  $a_{11} = 4, a_{22} = 9, a_{12} = -6 \Rightarrow a_{11}a_{22} - a_{12}^2 = 0 \Rightarrow$  parabolic equation.

$$C = \begin{pmatrix} 4 & 3 \\ 3 & 9 \end{pmatrix}$$

$$\text{Det}(C) = 27 > 0$$

$$(4-\lambda)(9-\lambda) - 9 = 0 \Rightarrow \lambda^2 - 13\lambda + 27 = 0$$

$$\lambda_{1,2} = \frac{13 \pm \sqrt{61}}{2} > 0$$

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(c)  $a_{11} = 4, a_{22} = 9, a_{12} = 3 \Rightarrow a_{11}a_{22} - a_{12}^2 = 27 > 0 \Rightarrow$  elliptic equation.

## §1.6 Types of Second-Order Equations

### Second-order linear PDE: The general case

Suppose that there are  $n$  variables, denoted  $x_1, x_2, \dots, x_n$ , and the PDE is

$$\sum_{i,j=1}^n a_{ij} u_{x_i x_j} + \sum_{i=1}^n a_i u_{x_i} + a_0 u = 0. \quad (62)$$

with real constants  $a_{ij}$ ,  $a_i$ , and  $a_0$ . Since the mixed derivatives are equal, we may as well assume that  $a_{ij} = a_{ji}$ . Let  $A = (a_{ij})$  be the coefficient matrix. Further assume that the real numbers  $d_1, \dots, d_n$  are the eigenvalues of  $A$ .

## §1.6 Types of Second-Order Equations

### Definition

The PDE (62) is

- **elliptic:** if all the eigenvalues  $d_1, \dots, d_n$  are positive or negative.

*have the same sign*

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- **hyperbolic:** if none of the eigenvalues  $d_1, \dots, d_n$  vanish and one of them has the opposite sign from the  $(n - 1)$  others.

$$\prod_{i=1}^n d_i = \det(A) \neq 0$$

$$u_{tt} - c^2(u_{xx} + u_{yy} + u_{zz}) = 0$$

$i=1$

$$\begin{pmatrix} 1 & & & \\ & -c^2 & & \\ & & -c^2 & \\ & & & -c^2 \end{pmatrix}$$

$$\lambda_1 = 1 > 0 \quad \lambda_2 = \lambda_3 = \lambda_4 = -c^2 < 0$$

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- **ultrahyperbolic:** if none of the eigenvalues  $d_1, \dots, d_n$  vanish but at least two of them are positive and at least two are negative.
- **parabolic:** if exactly one of the eigenvalues  $d_1, \dots, d_n$  is zero and all the others have the same sign.

$$u_t - k(u_{xx} + u_{yy} + u_{zz}) = f(t, x)$$
$$\lambda_1 = 0, \quad \lambda_2 = \lambda_3 = \lambda_4 = -k$$
$$A = \begin{pmatrix} 0 & & & \\ & -k & & \\ & & -k & \\ & & & -k \end{pmatrix}$$

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- Laplace equation:  $u_{xx} + u_{yy} + u_{zz} = 0$  is elliptic because all the eigenvalues are 1.

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- Heat equation:  $u_t - k(u_{xx} + u_{yy} + u_{zz}) = 0$  is parabolic because one eigenvalue is 0 and all the others are  $-k$ .

# Summary

## First-order linear equation

In general, we are interested in solving the PDEs:

$$a(x, y)u_x + b(x, y)u_y + c(x, y)u = f(x, y), \quad (63)$$

where  $a, b, c, f$  are constants or continuous functions in some domain  $\Omega$ .

The method of characteristics is usually used to solve (63).

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$$\sum_{i,j=1}^n a_{ij} u_{x_i x_j} + \sum_{i=1}^n a_i u_{x_i} + a_0 u = 0. \quad (64)$$

where  $a_{ij}$ ,  $a_i$ , and  $a_0$  are constants or continuous functions in some domain  $\Omega$ . We will mainly discuss the following three typical PDEs in our later lectures.

- Wave equation:  $u_{tt} - c^2 \Delta u = 0$  (hyperbolic) Chapters 2-5.
- Heat equation:  $u_t - k \Delta u = 0$  (parabolic) Chapters 2-5.
- Laplace equation:  $\Delta u = 0$  (elliptic) Chapter 6.

# MH4110 Partial Differential Equations

## Chapter 2 - Waves and diffusions

# Synopsis

- ① Wave equation: General solution, d'Alambert's formula.
- ② Wave equation: Causality, The energy method.
- ③ Heat equation: Maximum principle, Uniqueness, and Stability.
- ④ Heat equation: The solution in an integral form, Interpretation of the solution.
- ⑤ Comparison of wave and heat equations.

## §2.1 The wave equation

### Wave equation

The wave equation on the whole real line takes the form

$$u_{tt} = c^2 u_{xx}, \quad -\infty < x < \infty, \tag{1}$$

where the constant  $c > 0$  is the wave speed. Physically, you can imagine a very long string in a transverse motion. It describes the dynamics of the amplitude  $u(x, t)$  of the point at position  $x$  on the string at time  $t$ .

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We use two methods to derive the general solution of (1):

- ① Factorization of the differential operator

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We use two methods to derive the general solution of (1):

- ① Factorization of the differential operator → reduce the PDE into 2 1st order PDEs
- ② Characteristic coordinates

## §2.1 The wave equation

Method 1: Factorization of the differential operator

## §2.1 The wave equation

### Method 1: Factorization of the differential operator

Observe that the second order linear operator of the wave equation factors into two first order operators

$$u_t + c u_x$$

$$u_{tt} - c^2 u_{xx} = \left( \frac{\partial}{\partial t} - c \frac{\partial}{\partial x} \right) \left( \frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right) u = 0. \quad (2)$$

$$\mathcal{L} = \frac{\partial^2}{\partial t^2} - c^2 \frac{\partial^2}{\partial x^2} = \left( \frac{\partial}{\partial t} - c \frac{\partial}{\partial x} \right) \left( \frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right)$$

$$\left( \frac{\partial}{\partial t} - c \frac{\partial}{\partial x} \right) \left( u_t + c u_x \right) = \frac{\partial}{\partial t} (u_t + c u_x) - c \frac{\partial}{\partial x} (u_t + c u_x)$$

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Define

$$v = \left( \frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right) u = u_t + cu_x. \quad (3)$$

$v(t, x)$

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Then (2) can be rewritten as

$$u_{tt} - c^2 u_{xx} = 0 \quad \xrightarrow{v = u_t + cu_x} \quad v_t - cv_x = 0. \quad (4)$$

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Define

$$v = \left( \frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right) u = u_t + cu_x. \quad (3)$$

Then (2) can be rewritten as

$$v_t - cv_x = 0. \quad \begin{matrix} \text{characteristic lines} \\ ct+x = \text{const.} \end{matrix} \quad (4)$$

Therefore, we can solve (4) to find  $v$ , and then find  $u$  by solving (3).

$$v(t, x) = h(ct + x)$$

## §2.1 The wave equation

Method 1: Factorization of the differential operator (Cont'd)

Applying **the method of characteristics** to (4) (see Chapter 1) leads to

$$v(x, t) = h(x + ct), \quad (5)$$

where  $h$  is an arbitrary function.

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Applying **the method of characteristics** to (4) (see Chapter 1) leads to

$$v(x, t) = h(x + ct), \quad (5)$$

where  $h$  is an arbitrary function.

Plugging (5) into (3) gives

$$u_t + cu_x = h(x + ct). \quad (6)$$

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Plugging (5) into (3) gives

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By assumption:

$$f(x+ct) \text{ is } (6)$$

(with  $f$  TBD) a particular solution

It is a linear inhomogeneous equation, whose general solution is a particular solution plus the general solution to the homogeneous equation:

$$u_t + cu_x = 0.$$

characteristic lines:  $ct - x = \text{const.}$

General solution:  $g(ct - x)$

## §2.1 The wave equation

### Method 1: Factorization of the differential operator (Cont'd)

The general solution of  $u_t + cu_x = 0$  is  $g(x - ct)$ , where  $g$  is an arbitrary function.

## §2.1 The wave equation

### Method 1: Factorization of the differential operator (Cont'd)

The general solution of  $u_t + cu_x = 0$  is  $g(x - ct)$ , where  $g$  is an arbitrary function.

We can check directly by differentiation that  $u = f(x + ct)$  is a particular solution of (6):

$$\text{LHS} = u_t + cu_x = cf'(x + ct) + cf'(x + ct), = 2cf'(x+ct) \quad (7)$$

where  $f'$  is the ordinary derivative of a function of one variable and  $f'(s)$  can be taken as  $f'(s) = h(s)/(2c)$ .

$$\text{RHS} = h(x+ct)$$

$$\text{LHS} = \text{RHS} \Rightarrow 2cf'(x+ct) = h(x+ct)$$

## §2.1 The wave equation

### Method 1: Factorization of the differential operator (Cont'd)

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Finally, we obtain the solution of (1) is

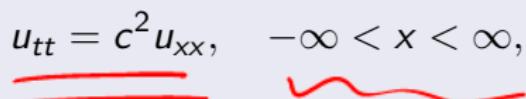
$$f(x) = \int_0^x \frac{h(s)}{2c} ds$$

$$u(x, t) = \underbrace{f(x + ct)}_{\text{particular}} + \underbrace{g(x - ct)}_{\text{general solution}}, \quad (8)$$

where  $f, g$  are arbitrary functions.

## §2.1 The wave equation

**Theorem:** The general solution of

$$u_{tt} = c^2 u_{xx}, \quad -\infty < x < \infty, \quad (9)$$


is

$$u(x, t) = f(x + ct) + g(x - ct), \quad (10)$$

where  $f, g$  are two arbitrary functions.

General Soln.

$$u_t - c u_x = 0, \quad -\infty < x < \infty \Rightarrow f(x+ct)$$

$$u_t + c u_x = 0, \quad -\infty < x < \infty \Rightarrow g(x-ct)$$

## §2.1 The wave equation

Method 2: Characteristic coordinates

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Method 2: Characteristic coordinates

Introduce the characteristic coordinates

$$u_{tt} - c^2 u_{xx} = 0$$

$$\xi = x + ct, \quad \eta = x - ct,$$

(11)

By the chain rule, we have

$$\left( \frac{\partial}{\partial t} + c \frac{\partial}{\partial x} \right) \left( \frac{\partial u}{\partial t} - c \frac{\partial u}{\partial x} \right) = 0$$

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \xi} + \frac{\partial}{\partial \eta}, \quad \frac{\partial}{\partial t} = c \frac{\partial}{\partial \xi} - c \frac{\partial}{\partial \eta},$$

(12)

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \xi} \underline{\frac{\partial \xi}{\partial x}} + \frac{\partial}{\partial \eta} \underline{\frac{\partial \eta}{\partial x}}$$

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Introduce the characteristic coordinates

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By the chain rule, we have

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and hence

$$\underline{\underline{\frac{\partial^2}{\partial x^2}}} = \frac{\partial^2}{\partial \xi^2} + 2 \frac{\partial^2}{\partial \xi \partial \eta} + \frac{\partial^2}{\partial \eta^2}, \quad \underline{\underline{\frac{\partial^2}{\partial t^2}}} = c^2 \left[ \frac{\partial^2}{\partial \xi^2} - 2 \frac{\partial^2}{\partial \xi \partial \eta} + \frac{\partial^2}{\partial \eta^2} \right]. \quad (13)$$

## §2.1 The wave equation

### Method 2: Characteristic coordinates (Cont'd)

So wave equation (1) or (9) takes the form

$$u_{tt} - c^2 u_{xx} = -4c^2 u_{\xi\eta} = 0, \quad (14)$$

which means that  $u_{\xi\eta} = 0$  since  $c \neq 0$ .



$$\begin{aligned} \frac{\partial}{\partial \eta} (u_\xi) &= 0 \Rightarrow u_\xi = h(\xi) \\ \Rightarrow u &= f(\xi) + g(\eta) \end{aligned}$$

## §2.1 The wave equation

### Method 2: Characteristic coordinates (Cont'd)

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The solution of the transformed equation (14) is

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Switch back to the original variables  $(x, t)$ , and we obtain the general solution

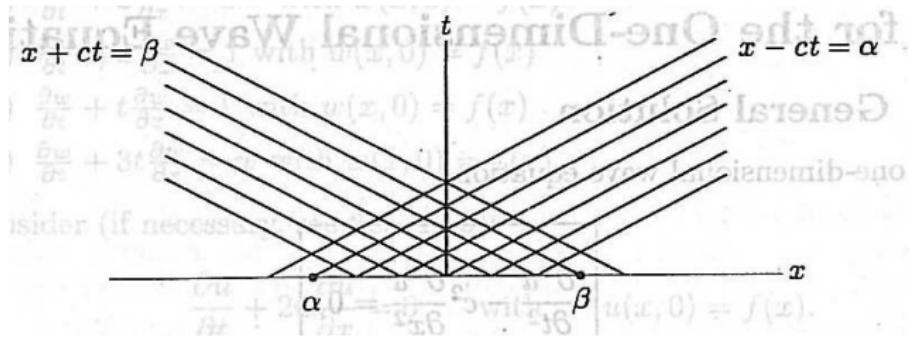
$$u(x, t) = f(x + ct) + g(x - ct), \quad (16)$$

where  $f, g$  are two arbitrary functions.

## §2.1 The wave equation

### Geometry of the wave equation

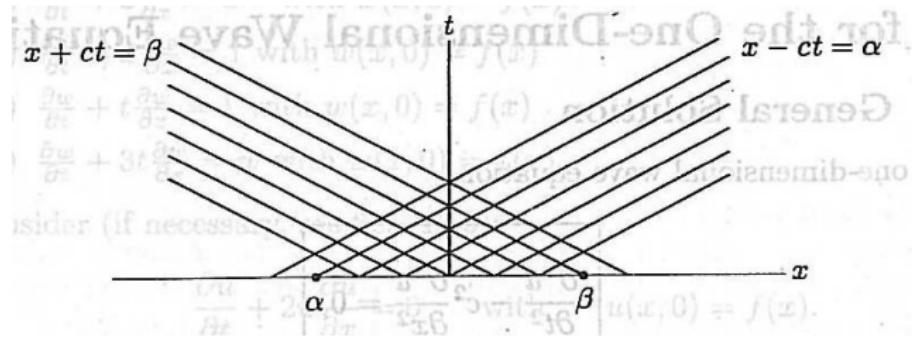
- The wave equation (1) has two families of characteristic lines:  
 $x \pm ct = \text{constant}$  (see Figure below).



## §2.1 The wave equation

### Geometry of the wave equation

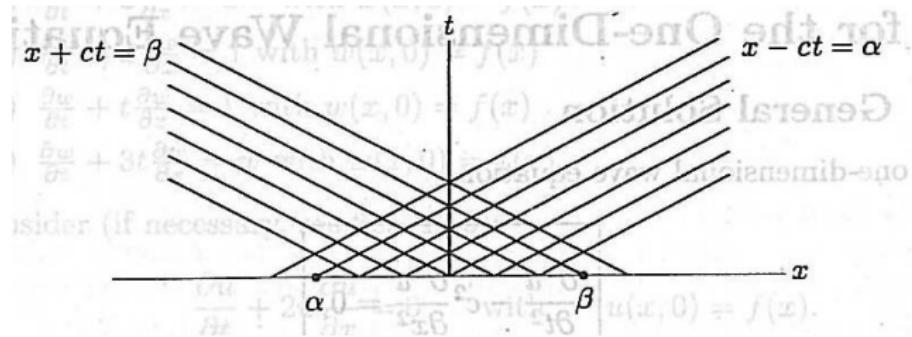
- The wave equation (1) has two families of characteristic lines:  $x \pm ct = \text{constant}$  (see Figure below).
- Part of the solution is constant along the corresponding characteristic line.



## §2.1 The wave equation

### Geometry of the wave equation

- The wave equation (1) has two families of characteristic lines:  
 $x \pm ct = \text{constant}$  (see Figure below).
- Part of the solution is constant along the corresponding characteristic line.
- One,  $g(x - ct)$  (is a constant along  $x - ct = \alpha$ ), is a wave of arbitrary shape traveling to the **right** at speed  $c$ .



## §2.1 The wave equation

$$u_{tt} - c^2 u_{xx} = 0$$

### Geometry of the wave equation

- The wave equation (1) has two families of characteristic lines:  $x \pm ct = \text{constant}$  (see Figure below).
- Part of the solution is constant along the corresponding characteristic line.
- One,  $g(x - ct)$  (is a constant along  $x - ct = \alpha$ ), is a wave of arbitrary shape traveling to the **right** at speed  $c$ .
- The other,  $f(x + ct)$  (is a constant along  $x + ct = \beta$ ), is a wave of another arbitrary shape traveling to the **left** at speed  $c$ .

