

MH4110 Partial Differential Equations

Chapter 1 - Where PDEs come from

- ① Basic concepts.
- ② First-Order Linear Equations.
- ③ Flows, Vibrations, and Diffusions.
- ④ Initial and Boundary Conditions.
- ⑤ Well-Posed Problems.
- ⑥ Types of Second-Order Equations.

§1.1 Basic concepts

Some notations

$$u_x = \frac{\partial u}{\partial x} = \partial_x u, \quad u_{xy} = \frac{\partial^2 u}{\partial x \partial y} = \partial_{xy} u, \quad (1)$$

$$\nabla u = \text{grad } u = u_x \mathbf{i} + u_y \mathbf{j} = (u_x, u_y); \quad \Delta u = u_{xx} + u_{yy}, \quad (2)$$

$$\text{div } \mathbf{F} = \nabla \cdot \mathbf{F} = u_x + v_y + w_z, \quad (3)$$

where $\mathbf{F} = (u, v, w)$, and

$$\begin{aligned} \nabla \times \mathbf{F} = \text{curl } \mathbf{F} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u & v & w \end{vmatrix} \\ &= (w_y - v_z)\mathbf{i} + (u_z - w_x)\mathbf{j} + (v_x - u_y)\mathbf{k}. \end{aligned} \quad (4)$$

Notice that

$$\text{div}(\nabla u) = \Delta u. = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \quad (5)$$

§1.1 Basic concepts

Definition

A **partial differential equation**, PDE in short, is an identity that relates the independent variables x, y, \dots , the dependent variable u , and the partial derivatives of u . A PDE can be expressed in the general form

$$F(\underbrace{x, y, \dots}_{(1)}, \underbrace{u}_{(2)}, \underbrace{u_x, u_y, \dots, u_{xx}, u_{xy}, u_{yy}, \dots}_{(3)}) = 0.$$

§1.1 Basic concepts

Definition

A **partial differential equation**, PDE in short, is an identity that relates the independent variables x, y, \dots , the dependent variable u , and the partial derivatives of u . A PDE can be expressed in the general form

$$F(x, y, \dots, u, u_x, u_y, \dots, u_{xx}, u_{xy}, u_{yy}, \dots) = 0.$$

Example A (not in the textbook)

For a function $u(x, t)$ of one spatial variable x and the time variable t , the heat equation is

$$\frac{\partial u}{\partial t} - \alpha \frac{\partial^2 u}{\partial x^2} = 0.$$

§1.1 Basic concepts

Examples of PDEs:

- Linear operator
- $$\left(\frac{\partial}{\partial x} + y \frac{\partial}{\partial y}\right)(cu + v) = \left(c \frac{\partial}{\partial x} u + cy \frac{\partial}{\partial y} u\right) + \left(\frac{\partial}{\partial x} v + y \frac{\partial}{\partial y} v\right)$$
- $$\mathcal{L}(cu + v) = (cu + v)_x + (cu + v)y_y = c \mathcal{L}u + \mathcal{L}v$$
- ✓ ① $u_x + u_y = 0$ (transport) 1st order PDE
 - ✓ ② $u_x + yu_y = 0$ (transport) $\mathcal{L} = \frac{\partial}{\partial x} + y \frac{\partial}{\partial y}$
 - ✗ ③ $u_x + \underline{u}u_y = 0$ (shock wave) $\mathcal{L}(cu + v) \neq c \mathcal{L}u + \mathcal{L}v$
 - ✓ ④ $u_{xx} + u_{yy} = \Delta u = 0$ (Laplace's equation)
 - ✗ ⑤ $u_{tt} - u_{xx} + u^3 = 0$ (wave with interaction)
 - ✗ ⑥ $u_t + uu_x + u_{xxx} = 0$ (dispersive wave)
 - ✓ ⑦ $u_{tt} + u_{xxxx} = 0$ (vibrating bar) 4th order PDE
 - ✓ ⑧ $u_t - iu_{xx} = 0$ ($i = \sqrt{-1}$) (quantum mechanics) 2nd order PDE
 - ✗ ⑨ $|\nabla T(x, y, z)| = \frac{1}{c(x, y, z)}$ (Eikonal equation)

§1.1 Basic concepts

Definition

The **order** of a PDE is the order of the highest partial derivative that appears in the equation.

§1.1 Basic concepts

Definition

The **order** of a PDE is the order of the highest partial derivative that appears in the equation.

Definition

A **solution** of a PDE is a function $u(x, y, \dots)$ that satisfies the equation identically, at least in some region of the x, y, \dots variables.

$$B((x, y, z), d)$$

§1.1 Basic concepts

Definition

The **order** of a PDE is the order of the highest partial derivative that appears in the equation.

Definition

A **solution** of a PDE is a function $u(x, y, \dots)$ that satisfies the equation identically, at least in some region of the x, y, \dots variables.

The second order heat equation

$$u(t, x) = 2\alpha t + x^2 + C_1 x + C_2$$
$$\frac{\partial u}{\partial t} - \alpha \frac{\partial^2 u}{\partial x^2} = 0$$

has a solution

$$u(t, x) = 2\alpha t + x^2.$$
$$\frac{\partial u}{\partial x} = 2x$$
$$\frac{\partial^2 u}{\partial x^2} = 2$$
$$\text{LHS} = \frac{\partial u}{\partial t} - \alpha \frac{\partial^2 u}{\partial x^2}$$
$$= 2\alpha - \alpha \cdot 2$$
$$= 0$$

RHS = 0

§1.1 Basic concepts

x, y vectors

$$A(x + \alpha y) = Ax + \alpha Ay \quad A \text{ matrix}$$

Definition

\mathcal{L} is an operator. If

$$\mathcal{L}(u + v) = \mathcal{L}u + \mathcal{L}v \quad \mathcal{L}(cu) = c\mathcal{L}u \quad (6)$$

holds for any functions u, v and any constant c , then \mathcal{L} is called **linear operator**.

$$\mathcal{L}(cu + v) = c\mathcal{L}u + \mathcal{L}v$$

§1.1 Basic concepts

Definition

\mathcal{L} is an operator. If

$$\mathcal{L}(u + v) = \mathcal{L}u + \mathcal{L}v \quad \mathcal{L}(cu) = c\mathcal{L}u \quad (6)$$

holds for any functions u, v and any constant c , then \mathcal{L} is called **linear operator**.

Definition

The equation

$$\mathcal{L}u = g \quad (7)$$

is called **linear** if \mathcal{L} is a linear operator. g is a given function of the independent variables. If $g = 0$, equation (7) is called a **homogeneous linear equation**, otherwise it is called an **inhomogeneous linear equation**.

$$Ax = b \quad \left\{ \begin{array}{l} b = 0 \quad \text{homogeneous} \\ b \neq 0 \quad \text{inhomogeneous} \end{array} \right.$$

§1.1 Basic concepts

Superposition Principle

- For the equation $\mathcal{L}u = 0$, if u and v are both solutions, so is $(u + v)$. If u_1, u_2, \dots, u_n are all solutions, so is any linear combination

$$c_1 u_1(x) + c_2 u_2(x) + \dots + c_n u_n(x) = \sum_{j=1}^n c_j u_j(x) \quad (c_j = \text{constants}).$$

§1.1 Basic concepts

Superposition Principle

- For the equation $\mathcal{L}u = 0$, if u and v are both solutions, so is $(u + v)$.
If u_1, u_2, \dots, u_n are all solutions, so is any linear combination

$$c_1 u_1(x) + c_2 u_2(x) + \dots + c_n u_n(x) = \sum_{j=1}^n c_j u_j(x) \quad (c_j = \text{constants}).$$

- The sum of a homogeneous solution and an inhomogeneous solution is an inhomogeneous solution.

$$\mathcal{L}u_1 = 0 \quad \mathcal{L}u_2 = g$$

$$Ax_1 = 0 \quad Ax_2 = b$$

$$A(x_1 + x_2) = b$$

$$\mathcal{L}(u_1 + u_2) = g$$

§1.1 Basic concepts

Review on second order linear ODE with constant coefficients

Find the general solution of

$$y'' + ay' + by = 0 \quad (8)$$

where a and b are constants.

§1.1 Basic concepts

Review on second order linear ODE with constant coefficients

Find the general solution of

$$y'' + ay' + by = 0 \quad (8)$$

where a and b are constants.

Look for a solution of the form $y = e^{\lambda x}$. Plugging into eqn. (8), we find that $e^{\lambda x}$ is a solution if and only if

$$\lambda^2 + a\lambda + b = 0.$$

- 1 If $a^2 - 4b > 0$, the characteristic function has two distinct real roots λ_1 and λ_2 . The general solution is $y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$.
- 2 If $a^2 - 4b = 0$, the characteristic function has one real root λ . The general solution is $y = c_1 e^{\lambda x} + c_2 x e^{\lambda x}$.
- 3 If $a^2 - 4b < 0$, the characteristic function has a pair of complex conjugate roots $\lambda = \alpha \pm i\beta$. The general solution is $y = c_1 e^{\alpha x} \cos(\beta x) + c_2 e^{\alpha x} \sin(\beta x)$.

§1.1 Basic concepts

ODE-like equation
↑

Example 1

Find all $u(x, y)$ satisfying the equation $u_{xx} = 0$.

$$\text{If } u = u(x)$$

$$\text{then } u_{xx} = 0 \Rightarrow u_x = C_1 \Rightarrow u(x) = C_1 x + C_2$$

$$u = u(x, y) \quad \text{a constant in terms of } x$$

$$u_{xx} = 0 \Leftrightarrow \frac{\partial}{\partial x}(u_x) = 0 \Rightarrow u_x = g(y)$$

$$u(x, y) = x g(y) + f(y) \quad \Leftarrow$$

§1.1 Basic concepts

Example 1

Find all $u(x, y)$ satisfying the equation $u_{xx} = 0$.

-
- If $u = u(x)$, we know $u(x) = c_1 + c_2x$, where c_1 and c_2 are arbitrary constants.

§1.1 Basic concepts

Example 1

Find all $u(x, y)$ satisfying the equation $u_{xx} = 0$.

-
- If $u = u(x)$, we know $u(x) = c_1 + c_2x$, where c_1 and c_2 are arbitrary constants.
 - u is a function of x and y , so are $u_x = u_x(x, y)$ and $u_{xx} = u_{xx}(x, y)$.

§1.1 Basic concepts

Example 1

Find all $u(x, y)$ satisfying the equation $u_{xx} = 0$.

-
- If $u = u(x)$, we know $u(x) = c_1 + c_2x$, where c_1 and c_2 are arbitrary constants.
 - u is a function of x and y , so are $u_x = u_x(x, y)$ and $u_{xx} = u_{xx}(x, y)$.
 - $u_{xx} = 0$ indicates that u_x is independent of x . But u_x is dependent on y . So $u_x = f(y)$. $f(y)$ is arbitrary.

§1.1 Basic concepts

Example 1

Find all $u(x, y)$ satisfying the equation $u_{xx} = 0$.

- If $u = u(x)$, we know $u(x) = c_1 + c_2x$, where c_1 and c_2 are arbitrary constants.
- u is a function of x and y , so are $u_x = u_x(x, y)$ and $u_{xx} = u_{xx}(x, y)$.
- $u_{xx} = 0$ indicates that u_x is independent of x . But u_x is dependent on y . So $u_x = f(y)$. $f(y)$ is arbitrary.
- Integrate again to get $u(x, y) = xf(y) + g(y)$, where $f(y)$ and $g(y)$ are arbitrary.

§1.1 Basic concepts

Example 2

Solve the PDE $u_{xx} + u = 0$. Here $u = u(x, y)$.

§1.1 Basic concepts

Example 2

Solve the PDE $u_{xx} + u = 0$. Here $u = u(x, y)$.

$$\lambda^2 + 1 = 0 \quad \lambda_{1,2} = \pm i$$

- If $u = u(x)$, we know $u(x) = c_1 \cos x + c_2 \sin x$, where c_1 and c_2 are arbitrary constants.

in terms of x

§1.1 Basic concepts

Example 2

Solve the PDE $u_{xx} + u = 0$. Here $u = u(x, y)$.

-
- If $u = u(x)$, we know $u(x) = c_1 \cos x + c_2 \sin x$, where c_1 and c_2 are arbitrary constants.
 - u is a function of x and y . The arbitrary constants c_1 and c_2 above should be replaced by the arbitrary functions $f(y)$ and $g(y)$.

§1.1 Basic concepts

Example 2

Solve the PDE $u_{xx} + u = 0$. Here $u = u(x, y)$.

-
- If $u = u(x)$, we know $u(x) = \underline{c_1} \cos x + c_2 \sin x$, where c_1 and c_2 are arbitrary constants.
 - u is a function of x and y . The arbitrary constants c_1 and c_2 above should be replaced by the arbitrary functions $f(y)$ and $g(y)$.
 - The solution is $u(x, y) = \underline{f(y)} \cos x + g(y) \sin x$.

§1.1 Basic concepts

Example 3

Solve the PDE $u_{xy} = 0$. Here $u = u(x, y)$.

$$u_{xy} = 0 \iff \frac{\partial}{\partial y}(u_x) = 0$$

$$\Downarrow$$
$$u_x = f(x)$$

$$\implies u(x, y) = \int_a^x f(s) ds + g(y)$$

§1.1 Basic concepts

Example 3

Solve the PDE $u_{xy} = 0$. Here $u = u(x, y)$.

-
- Integrate in x , regarding y as fixed, we get

$$u_y(x, y) = f(y)$$

§1.1 Basic concepts

Example 3

Solve the PDE $u_{xy} = 0$. Here $u = u(x, y)$.

-
- Integrate in x , regarding y as fixed, we get

$$u_y(x, y) = f(y)$$

- Integrate in y , regarding x as fixed, we get

$$u(x, y) = F(y) + G(x)$$

where $F' = f$. Both $f(y)$ and $G(x)$ are arbitrary functions.

§1.1 Basic concepts

Moral

- For an ODE of order m , we get m arbitrary constants in the solution.
- A PDE has arbitrary functions in its solution.

§1.1 Basic concepts

Moral

- For an ODE of order m , we get m arbitrary constants in the solution.
- A PDE has arbitrary functions in its solution.

A few things to keep in mind

- Mixed derivatives are equal throughout this course: $u_{xy} = u_{yx}$.
- The chain rule is used frequently in PDEs; for instance,

$$\frac{\partial}{\partial x} [f(g(x, t))] = f'(g(x, t)) \cdot \frac{\partial g}{\partial x}(x, t).$$

- Derivatives of integrals like $I(t) = \int_{a(t)}^{b(t)} f(x, t) dx$

$$\frac{dI}{dt} = \int_{a(t)}^{b(t)} \frac{\partial f}{\partial t}(x, t) dx + f(b(t), t)b'(t) - f(a(t), t)a'(t).$$

§1.1 Basic concepts

Green's Theorem

Let D be a bounded plane domain with a piecewise C^1 boundary curve $C = \text{bdy } D$. Consider C to be parametrized so that it is traversed once with D on the left. Let $p(x, y)$ and $q(x, y)$ be any C^1 functions defined on $\bar{D} = D \cup C$. Then

$$\iint_D (q_x - p_y) dx dy = \int_C p dx + q dy. \quad (9)$$

§1.1 Basic concepts

Green's Theorem

Let D be a bounded plane domain with a piecewise C^1 boundary curve $C = \text{bdy } D$. Consider C to be parametrized so that it is traversed once with D on the left. Let $p(x, y)$ and $q(x, y)$ be any C^1 functions defined on $\bar{D} = D \cup C$. Then

$$\iint_D (q_x - p_y) dx dy = \int_C p dx + q dy. \quad (9)$$

Divergence Theorem

Let D be a bounded spatial domain with a piecewise C^1 boundary surface S . Let \mathbf{n} be the unit outward normal vector on S . Let $\mathbf{f}(\mathbf{x})$ be any C^1 vector field on $\bar{D} = D \cup S$. Then

$$\iiint_D \nabla \cdot \mathbf{f} d\mathbf{x} = \iint_S \mathbf{f} \cdot \mathbf{n} dS. \quad (10)$$

§1.1 Basic concepts

Summary

A **differential equation**, DE in short, is an equation involving an unknown function and its derivatives. For example,

$$\frac{du}{dx} = 5x + 3 \quad (\text{or } u' = 5x + 3), \quad (11)$$

and

$$\frac{\partial^2 u(x, y)}{\partial x^2} + \frac{\partial^2 u(x, y)}{\partial y^2} = \cos(xy) \quad (\text{or } \Delta u = \cos(xy)). \quad (12)$$

§1.1 Basic concepts

Summary

A **differential equation**, DE in short, is an equation involving an unknown function and its derivatives. For example,

$$\frac{du}{dx} = 5x + 3 \quad (\text{or } u' = 5x + 3), \quad (11)$$

and

$$\frac{\partial^2 u(x, y)}{\partial x^2} + \frac{\partial^2 u(x, y)}{\partial y^2} = \cos(xy) \quad (\text{or } \Delta u = \cos(xy)). \quad (12)$$

- If the unknown function is a function of a single variable (e.g., $u(x), u(t), \dots$) and the involved derivatives are ordinary derivatives, then this DE is an **ordinary differential equation (ODE)**, e.g., the equation (11).

§1.1 Basic concepts

Summary

A **differential equation**, DE in short, is an equation involving an unknown function and its derivatives. For example,

$$\frac{du}{dx} = 5x + 3 \quad (\text{or } u' = 5x + 3), \quad (11)$$

and

$$\frac{\partial^2 u(x, y)}{\partial x^2} + \frac{\partial^2 u(x, y)}{\partial y^2} = \cos(xy) \quad (\text{or } \Delta u = \cos(xy)). \quad (12)$$

- If the unknown function is a function of a single variable (e.g., $u(x), u(t), \dots$) and the involved derivatives are ordinary derivatives, then this DE is an **ordinary differential equation (ODE)**, e.g., the equation (11).
- A **partial differential equation (PDE)** is one involving a function of two or more variables, in which the derivatives are partial derivatives, for example, the equation (12).