view_frames Result Recorded at time: 1519826908.449 face_pos base_link Broadcaster: /face_tablet_tf_broadcaster Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 53.125 Hz Most recent transform: 0.000 (1519826908.449 sec old) Most recent transform: 1519826908.304 (0.145 sec old) Buffer length: 0.000 sec Buffer length: 0.320 sec base_motor_holder tablet_pos Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec rotating_plate Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1519826908.449 sec old) Buffer length: 0.000 sec plate_link Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec main_link_1 Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec main_link_2 Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec dummy_link Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec tablet_bracket Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1519826908.449 sec old) Buffer length: 0.000 sec tablet_bracket_2 Broadcaster: /robot_state_publisher Average rate: 13.330 Hz Most recent transform: 1519826908.309 (0.140 sec old) Buffer length: 0.300 sec tablet