# AC6354B Datasheet

# Zhuhai Jieli Technology Co.,LTD

Version: V1.0

Date: 2021.06.02

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# **AC6354B Features**

### **CPU**

- 32-bit DSP supports hardware Float Point Unit(FPU)
- Up to 240MHz programmable processor
- 64 Vectored interrupts
- 4 Levels interrupt priority

### **DSP Audio Processing**

- SBC, AAC Audio decodes supported for BT audio
- mSBC voice codecs supported for BT phone
- Supports MP2, MP3, WMA, APE, FLAC, AAC, MP4, M4A, WAV, AIF, AIFC audio decoding
- Packet Loss Concealment (PLC) for voice processing
- Acoustic echo cancellation/suppression (AEC,AES)
- Single/Dual MIC Environmental Noise Cancellation (ENC)
- Multi-band DRC limiter
- 30-band EQ configuration for voice Effects

### **Audio Codec**

- Two channels 16-bit DAC, SNR >= 92dB
- Three channels 16-bit ADC, SNR >= 90dB
- Sampling rates of 8KHz/11.025KHz/16KHz/22.05KHz/24KHz/32KHz/44.1KHz/48KHz are supported
- One analog MIC amplifier, build-in MIC bias generator
- Supports two PDM digital MIC inputs
- three channels Stereo analog MUX
- Supports cap-less, single-ended, and differential mode at the DAC path
- Supports 16ohm and 32ohm Speaker loading

### Bluetooth

- Compliant with Bluetooth
  V5.1+BR+EDR+BLE specification
- Meet class1 class2 and class3 transmitting

- power requirement
- Support GFSK and π/4 DQPSK all packet types
- Provides +6dbm transmitting power
- receiver with -90dBm sensitivity
- Fast AGC for enhanced dynamic range
- Supports a2dp\avctp\avdtp\avrcp\hfp\spp\smp\att\gap\ gatt\rfcomm\sdp\l2cap profile

### **Peripherals**

- One full speed USB 2.0 OTG controller
- Two PCM/IIS for external digital Audio code, supports host and device mode
- Four multi-function 16-bit timers, support capture and PWM mode
- Three 16-bit PWM generator for motor driving
- Three full-duplex basic UART, UART0 and UART1 supports DMA mode
- Three SPI interface supports host and device mode
- Two SD Card Host controller
- One hardware IIC interface supports host and device mode
- Four SPDIF receiving interface without analog amplify
- Supports HDMI ARC (Audio Return Channel) receiving
- Segment LCD panels
- Digital matrix LED panels
- Built-in Cap Sense Key controller
- 10-bit ADC for analog sampling
- External wake up/interrupt on all GPIOs

### **PMU**

- Low voltage LDO for internal digital and analog circuit supply
- 3uA current consumption in the soft-off mode
- Built-in LDO for the core, I/O, Bluetooth and flash

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### **Confidential**

- Built-in Li-Ion battery charger with up to 200mA charger current capability
- VBAT is 2.2V to 5.5V
- VDDIO is 2.2V to 3.6V

**Packages** 

# Storage temperature: -65°C to +150°C

Bluetooth Keyboard QFN52(6mm\*6mm)

**Temperature** 

**Applications** 

Operating temperature: -40°C to +85°C

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# 1. Pin Definition

# 1.1 Pin Assignment

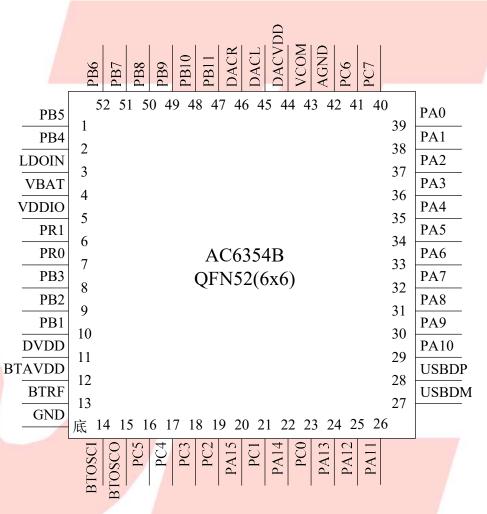


Figure 1-1 AC6354B\_QFN52 Package Diagram

# 1.2 Pin Description

Table 1-1 AC6354B\_QFN52 Pin Description

| PIN   | Name   | I/O  | Drive | Function                     | Other Function                   |
|-------|--------|------|-------|------------------------------|----------------------------------|
| NO.   | Name   | Туре | (mA)  | 1 unction                    | Other Function                   |
|       |        |      |       |                              | SD1CMDB: SD1 Command(B);         |
|       |        |      |       | GPIO                         | SD0DAT2B: SD1 Data2(B);          |
| 1     | PB5    | I/O  | /     |                              | PWM3: Timer3 PWM Output;         |
| 1     | PDS    | 1/0  |       | (High Voltage<br>Resistance) | CAP1: Timer1 Capture;            |
|       |        |      |       | Resistance)                  | UART0TXC: Uart0 Data Out(C);     |
|       |        |      |       | A                            | UART0RXC: Uart0 Data In(C);      |
|       |        |      |       |                              | SD1DAT0B: SD1 Data0(B);          |
|       |        |      | /     | 7./                          | SD0DAT3B: SD0 Data3(B);          |
|       |        |      | /     |                              | IIC_SCL_C: IIC SCL(C);           |
| 2     | PB4    | I/O  | 24/8  | GPIO                         | ADC7: ADC Input Channel 7;       |
|       |        |      | - /   | 7 /                          | UART0TXB: Uart0 Data Out(B);     |
|       |        |      |       |                              | LVD: Low Voltage Detect Input;   |
|       |        |      |       | 7 A                          | PWMCH2H: Motor PWM Channel2 (H); |
| 3     | LDO_IN | P    | /     | - V                          | Battery Charger Power In         |
| 4     | VBAT   | P    | /     |                              | Power Supply                     |
| 5     | VDDIO  | P    | /     |                              | IO Power 3.3V                    |
| 6     | PR1    | I/O  | 8     | GPIO                         | OSCO_32K: 32KHz OSC Out          |
| 7     | PR0    | I/O  | 8     | GPIO                         | OSCI_32K: 32KHz OSC In           |
| 8     | PB3    | I/O  | 24/8  | GPIO                         | PWM2: Timer2 PWM Output;         |
| 0     | PB3    | 1/0  | 24/8  | GPIO                         | ADC6: ADC Input Channel 6;       |
|       |        |      | 1     | GPIO                         |                                  |
| 9     | PB2    | I/O  | 8     | (High Voltage                | PWMCH1L: Motor PWM Channel1 (L); |
|       | 435    |      |       | Resistance)                  |                                  |
| _ ^ < |        |      |       | GPIO                         | Long Press Reset;                |
| 10    | PB1    | I/O  | 24/8  | (pull up)                    | ADC5: ADC Input Channel 5;       |
|       | >      |      |       | (Pair ap)                    | UART1RXA: Uart1 Data In(A);      |
| 11    | DVDD   | P    | /     |                              | Core Power 1.2V                  |
| 12    | BTAVDD | P    | /     |                              | BT Power                         |
| 13    | BTRF   | /    | /     |                              | BT Antenna                       |
| 14    | BTOSCI | I    | /     |                              | BT OSC In                        |
| 15    | BTOSCO | О    | /     |                              | BT OSC Out                       |

|     |       |     |                   |                   | SD1CLKA: SD1 Clock(A);                  |
|-----|-------|-----|-------------------|-------------------|---|
|     |       |     |                   |                   | SPI1DOB: SPI1 Data Out(B);              |
|     |       |     |                   |                   | UART2RXD: Uart2 Data In(D);             |
| 16  | PC5   | I/O | 24/8              | GPIO              | IIC_SDA_B: IIC SDA(B);                  |
|     |       |     |                   |                   | ADC13: ADC Input Channel 13;            |
|     |       |     |                   |                   | Touch15: Touch Input Channel 15;        |
|     |       |     |                   |                   | PWMCH5L: Motor PWM Channel5(L);         |
|     |       |     |                   |                   | SD1CMDA: SD1 Command(A);                |
|     |       |     |                   |                   | SPI1CLKB: SPI1 Clock(B);                |
|     |       |     |                   |                   | UART2TXD: Uart2 Data Out(D);            |
| 17  | PC4   | I/O | 24/8              | GPIO              | IIC SCL B: IIC SCL(B);                  |
|     |       |     |                   |                   | ADC10: ADC Input Channel 10;            |
|     |       |     |                   | A                 | Touch14: Touch Input Channel 14;        |
|     |       |     |                   |                   | PWMCH5H: Motor PWM Channel5(H);         |
| -   |       |     |                   |                   |   |
| 1.0 | DC2   | 1/0 | 24/0              | CDIO              | SD1DAT0A: SD1 Data0(A);                 |
| 18  | PC3   | I/O | 24/8              | GPIO              | SPI1DIB: SPI1 Data In(B); ALNK1_DAT1;   |
|     |       |     |                   |                   | Touch13: Touch Input Channel 13;        |
|     |       |     |                   |                   | SD1DAT1A: SD1 Data1(A); ALNK1_DAT0:     |
| 19  | PC2   | I/O | 24/8              | GPIO              | Touch12: Touch Input Channel 12;        |
|     |       |     |                   |                   | FPIN5: Motor Auto-Stop Protective Pin5; |
| 20  | PA15  | I/O | 24/8              | GPIO              | CAP2: Timer2 Capture;                   |
|     |       |     | /                 |                   | SD1DAT2A: SD1 Data2(A);                 |
| 21  | DC1   | 1/0 | 24/0              | CDIO              | Touch11: Touch Input Channel 11;        |
| 21  | PC1   | I/O | 24/8              | GPIO              | UART1RXB: Uart1 Data In(B);             |
| A   |       |     |                   |                   | FPIN4: Motor Auto-Stop Protective Pin4; |
| 22  | PA14  | I/O | 24/8              | GPIO              | FPIN0: Motor Auto-Stop Protective Pin0; |
|     |       | /   |                   | 14/4              | SD1DAT3A: SD1 Data3(A);                 |
|     |       |     |                   | 7 /               | Touch 10: Touch Input Channel 10;       |
| 23  | PC0   | I/O | 24/8              | GPIO              | UART1TXB: Uart1 Data Out(B);            |
| 1   |       |     | 7                 | 1                 | FPIN3: Motor Auto-Stop Protective Pin3; |
| 24  | PA13  | I/O | 24/8              | GPIO              |   |
|     |       |     |                   |                   | PWM1: Timer1 PWM Output;                |
| 25  | PA12  | I/O | 24/8              | GPIO              | ADC4: ADC Input Channel 4;              |
|     |       |     | - "               |                   | UARTORXD: Uart0 Data In(D);             |
| 26  | PA11  | I/O | 24/8              | GPIO              | UARTOTXD: Uart0 Data Out(D);            |
| 20  | 1711  | 1/0 | ∠ <del>1</del> /0 |                   | ` '                                     |
| 27  | HCDDM | 1/0 |                   | USB Negative      | UART1RXD: Uart1 Data In(D);             |
| 27  | USBDM | I/O | 4                 | Data              | SPI2DOB: SPI2 Data Out(B);              |
|     |       |     |                   | (pull down)       | IIC_SDA_A: IIC SDA(A);                  |
|     |       |     |                   |                   | UART1TXD: Uart1 Data Out(D);            |
| 28  | USBDP | I/O | 4                 | USB Positive Data | SPI2CLKB: SPI2 Clock(B);                |
|     |       |     |                   | (pull down)       | IIC_SCL_A: IIC SCL(A);                  |
|     |       |     |                   |                   | ADC12: ADC Input Channel 12;            |

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|    | 1    | 1     |      | ſ    |   |
|----|------|-------|------|------|---|
|    |      |       |      |      | SD0CLKA: SD0 Clock(A);                  |
|    |      | 0 I/O | 24/8 |      | ADC3: ADC Input Channel 3;              |
| 29 | PA10 |       |      | GPIO | TMR1: Timer1 Clock Input;               |
| 2) | TAIO |       | 24/0 | GHO  | Touch9: Touch Input Channel 9;          |
|    |      |       |      |      | UART2RXB: Uart2 Data In(B);             |
|    |      |       |      |      | PWMCH4L: Motor PWM Channel4(L);         |
|    |      | 4     |      |      | SD0CMA: SD0 Command(A);                 |
| 30 | DAO  | 1/0   | 24/9 | GPIO | Touch8: Touch Input Channel 8;          |
| 30 | PA9  | I/O   | 24/8 | GPIO | UART2TXB: Uart2 Data Out(B);            |
|    |      |       |      |      | PWMCH4H: Motor PWM Channel4(H);         |
| 21 | DAG  | I/O   | 24/9 | GPIO | SD0DAT3A: SD0 Data3(A);                 |
| 31 | PA8  | 1/0   | 24/8 | GPIO | FPIN2: Motor Auto-Stop Protective Pin2; |
|    |      |       |      | /    | SD0DAT2A: SD0 Data2(A);                 |
| 32 | PA7  | I/O   | 24/8 | GPIO | TMR0: Timer0 Clock Input;               |
|    |      |       |      |      | Touch7: Touch Input Channel 7;          |
|    |      |       |      | 7 /  | SD0DAT1A: SD0 Data1(A);                 |
|    |      |       | /    |      | ADC2: ADC Input Channel 2;              |
| 33 | PA6  | I/O   | 24/8 | GPIO | IIC_SDA_D: IIC SDA(D);                  |
|    |      |       |      |      | Touch6: Touch Input Channel 6;          |
|    |      |       |      |      | UART0RXA: Uart0 Data In(A);             |
|    |      |       |      | 7 /  | SD0DAT0A: SD0 Data0(A);                 |
|    |      |       | /    |      | ADC1: ADC Input Channel 1;              |
|    | D. 5 | 1/0   | 24/0 | CNIC | IIC_SCL_D: IIC SCL(D);                  |
| 34 | PA5  | I/O   | 24/8 | GPIO | Touch5: Touch Input Channel 5;          |
| F  |      |       |      |      | PWM0: Timer0 PWM Output;                |
| 1  |      |       |      | 7 /  | UART0TXA: Uart0 Data Out(A);            |
| 35 | PA4  | I/O   | 24/8 | GPIO | Touch4: Touch Input Channel 4;          |
|    |      |       |      | 1.1  | Touch3: Touch Input Channel 3;          |
| 36 | PA3  | I/O   | 24/8 | GPIO | UART2RXA: Uart2 Data In(A);             |
| A. |      |       |      |      | Touch2: Touch Input Channel 2;          |
| 37 | PA2  | I/O   | 24/8 | GPIO | UART2TXA: Uart2 Data Out(A);            |
|    |      |       |      |      | CAP3: Timer3 Capture;                   |
| 4  |      |       |      |      | Touch1: Touch Input Channel 1;          |
|    |      |       |      |      | ADC0: ADC Input Channel 0;              |
| 38 | PA1  | I/O   | 24/8 | GPIO | UART1RXC: Uart1 Data In(C);             |
|    |      |       |      |      | PWMCH0L: Motor PWM Channel0(L);         |
|    |      |       |      |      | Touch0: Touch Input Channel 0;          |
|    |      |       |      |      | CLKOUT0:                                |
| 39 | PA0  | I/O   | 24/8 | GPIO | UART1TXC: Uart1 Data Out(C);            |
|    |      |       |      |      | PWMCH0H: Motor PWM Channel0(H);         |
| 40 | PC7  | I/O   | /    | GPIO |   |
| 41 | PC6  | I/O   | /    | GPIO | ADC11: ADC Input Channel 11;            |
|    | I    | I     |      | l    | * ′                                     |

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|    |           |     |      | Ground for audio DAC |                                  |
|----|-----------|-----|------|----------------------|----------------------------------|
| 42 | AGND      | P   | /    | logic                |                                  |
| 43 | VCOM      |     |      | DAC Reference        |                                  |
|    |           |     |      | Power for audio DAC  |                                  |
| 44 | DACVDD    |     |      | logic                |                                  |
| 45 | DACL      | О   | /    | DAC Left Channel     |                                  |
| 46 | DACR      | О   | /    | DAC Right Channel    |                                  |
| 47 | PB11      | I/O | /    | GPIO                 | SDPG:SDC Power Gate;             |
|    |           |     |      |                      | SD0CMB: SD0 Command(B);          |
|    |           |     |      |                      | SPI2DOA: SPI2 Data Out(A);       |
| 10 | PB10      | I/O | 24/8 | GPIO                 | SD1DAT3B: SD1 Data3(B);          |
| 48 | PBIU      | 1/O | 24/8 | GPIO                 | ADC9: ADC Input Channel 9;       |
|    |           |     |      |                      | UART2RXC: Uart2 Data In(C);      |
|    |           |     |      | A Y                  | PWMCH3L: Motor PWM Channel3(L);  |
|    |           |     |      |                      | SD0 Clock(B);                    |
|    |           |     | 1    | 7.4                  | SPI2CLKA: SPI2 Clk(A);           |
|    |           |     |      | 7/                   | SD1DAT2B: SD1 Data2(B);          |
| 49 | PB9       | I/O | 24/8 | GPIO                 | CAP0: Timer0 Capture;            |
|    |           |     | - /  | 7 /                  | UART2TXC: Uart2 Data Out(C);     |
|    |           |     |      |                      | PWMCH3H: Motor PWM Channel3(H);  |
|    |           |     |      | 7/                   | SD0DAT0B: SD0 Data0(B);          |
|    |           |     | 1    |                      | SPI2 DIA: SPI2 Data In(A);       |
| 50 | PB8       | I/O | 24/8 | GPIO                 | SD1DAT1B: SD1 Data1(B);          |
|    |           | /   |      |                      | ADC8: ADC Input Channel 8;       |
| /  |           |     |      |                      | CLKOUT1: Clk Out1;               |
| 51 | PB7       | I/O | 24/8 | GPIO                 |                                  |
|    |           |     |      | 7 /                  | SD1CLKB: SD1 Clock(B);           |
|    |           |     |      |                      | SD0DAT1B: SD0 Data1(B);          |
|    |           |     |      |                      | IIC_SDA_C: IIC SDA(C);           |
| 52 | PB6       | I/O | 24/8 | GPIO                 | TMR3: Timer3 Clock Input;        |
|    |           |     |      | A                    | UARTORXB: Uarto Data In(B);      |
| 4  |           |     |      |                      | PWMCH2L: Motor PWM Channel2 (L); |
| 1  | Substrate | GND | -    | Substrate            |                                  |
|    |           |     |      | l                    |                                  |

# 2, Electrical Characteristics

## 2.1 Absolute Maximum Ratings

Table 2-1

| Symbol             | Parameter             | Min  | Max  | Unit |
|--------------------|-----------------------|------|------|------|
| Tamb               | Operating Temperature | -40  | +85  | °C   |
| Tstg               | Storage temperature   | -65  | +150 | °C   |
| VBAT               | Supply Voltage        | -0.3 | 5.5  | V    |
| LDO_IN             | Charger Voltage       | -0.3 | 6    | V    |
| V <sub>3.3IO</sub> | 3.3V IO Input Voltage | -0.3 | 3.6  | V    |

Note: The chip can be damaged by any stress in excess of the absolute maximum ratings listed below

## 2.2 PMU Characteristics

Table 2-2

| Symbol               | Parameter       | Min | Тур  | Max  | Unit | Test Conditions            |
|----------------------|-----------------|-----|------|------|------|----------------------------|
| VBAT                 | Voltage Input   | 2.2 | 3.7  | 5.5  | V    |                            |
| LDO_IN               | Charger Voltage | 4.5 | 5.0  | 5.5  | V    |                            |
| V <sub>3.3</sub>     | Voltage output  | 2.2 | 3.0  | 3.4  | V    | VBAT = 3.7V, 100mA loading |
| V <sub>BT_AVDD</sub> | Voltage output  | 1.2 | 1.25 | 1.35 | V    | VBAT=3.7V, 100mA loading   |
| I <sub>L3.3</sub>    | Loading current | -   | _//  | 150  | mA   | VBAT = 3.7V                |

# 2.3 IO Input/Output Electrical Logical Characteristics

Table 2-3

| IO input ch       | aracteristics                |               |     |            |      |                 |
|-------------------|------------------------------|---------------|-----|------------|------|-----------------|
| Symbol            | Parameter                    | Min           | Тур | Max        | Unit | Test Conditions |
| $ m V_{IL}$       | Low-Level Input<br>Voltage   | -0.3          | ı   | 0.3* VDDIO | V    | VDDIO = 3.0V    |
| $V_{ m IH}$       | High-Level Input<br>Voltage  | 0.7*<br>VDDIO | _   | VDDIO+0.3  | V    | VDDIO = 3.0V    |
| IO output c       | haracteristics               |               |     |            |      |                 |
| V <sub>OL</sub>   | Low-Level Output<br>Voltage  | _             | _   | 0.33       | V    | VDDIO = 3.0V    |
| $V_{\mathrm{OH}}$ | High-Level Output<br>Voltage | 2.7           | -   | _          | V    | VDDIO = 3.0V    |

## 2.4 Internal Resistor Characteristics

Table 2-4

| 1           | Port   | General<br>Output | High Drive   | Internal<br>Pull-Up<br>Resistor | Internal Pull-Down Resistor | Comment  |
|-------------|--|-------------------|--------------|---------------------------------|-----------------------------|--|
| PB:         | 0~PA15<br>PB1,<br>3, PB4,<br>6~PB10<br>0~PC5 | 8mA               | 24mA         | 10K                             | 10K                         | 1、PB1 default pull up 2、USBDM & USBDP                          |
| PB11<br>PC7 | Output0 Output1                              | 8mA               | 24mA<br>64mA | 10K                             | 10K                         | default pull down 3、PB0, PB2, PB5 can pull-up resistance to 5V |
| PB0,        | PB2, PB5                                     | 8mA               | /_           | 10K                             | 10K                         | 4 internal pull-up/pull-down                                   |
| PR          | .0-PR1                                       | 8mA               | _            | 10K                             | 10K                         | resistance   accuracy ±20%                                     |
| U           | SBDP   | 4mA               | <u> </u>     | 1.5K                            | 15K                         | ±2070  |
| US          | SBDM   | 4mA               | _            | 180K                            | 15K                         |  |

# 2.5 DAC Characteristics

Table 2-5

| Parameter          | Min | Тур  | Max  | Unit | Test Conditions        |
|--------------------|-----|------|------|------|------------------------|
| Frequency Response | 20  | / /_ | 20K  | Hz   |                        |
| THD+N              | _   | -75  | _ /  | dB   | 1KHz/0dB               |
| S/N                | _ / | 92   | _ /_ | dB   | 10Kohm loading         |
| Crosstalk          | -   | -80  | _    | dB   | With A-Weighted Filter |
| Output Swing       | _/  | 1    | _    | Vrms |                        |
|                    |     |      |      |      | 1KHz/-60dB             |
| Dynamic Range      | _ / | 90   | _    | dB   | 10Kohm loading         |
|                    |     |      |      |      | With A-Weighted Filter |
| DAC Output Power   | 11  | _    | _    | mW   | 32ohm loading          |

# 2.6 ADC Characteristics

Table 2-6

| Parameter     | Min | Тур | Max | Unit | Test Conditions |
|---------------|-----|-----|-----|------|-----------------|
| Dynamic Range | _   | 80  | _   | dB   | 1KHz/-60dB      |
| S/N           | _   | 90  | 91  | dB   |                 |
| THD+N         | _   | -70 | _   | dB   | 1KHz/-60dB      |
| Crosstalk     | _   | -80 | _   | dB   |                 |

## 2.7 BT Characteristics

## 2.7.1 Transmitter

### **Basic Data Rate**

**Table 2-7** 

| Paramete         | r       | Min | Тур | Max | Unit | Test Conditions |
|------------------|---------|-----|-----|-----|------|-----------------|
| RF Transmit P    | ower    |     | 4   | 6   | dBm  |                 |
| RF Power Contro  | l Range |     | 20  |     | dB   | 25°C,           |
| 20dB Bandwi      | idth    |     | 950 |     | KHz  | Power Supply    |
|                  | +2MHz   |     | -40 |     | dBm  |                 |
| Adjacent Channel | -2MHz   |     | -38 |     | dBm  | VBAT=3.7V       |
| Transmit Power   | +3MHz   |     | -44 | 7// | dBm  | 2441MHz         |
|                  | -3MHz   |     | -35 | 7 / | dBm  |                 |

## **Enhanced Data Rate**

Table 2-8

| Paramete            | Min            | Тур | Max | Unit | Test Conditions |              |
|---------------------|----------------|-----|-----|------|-----------------|--------------|
| Relative Po         | Relative Power |     |     |      | dB              |              |
| π/4 DQPSK           | DEVM RMS       |     | 6   |      | %               |              |
|                     | DEVM 99%       |     | 10  |      | %               | 25°C,        |
| Modulation Accuracy | DEVM Peak      |     | 15  |      | %               | Power Supply |
|                     | +2MHz          |     | -40 |      | dBm             | VBAT=3.7V    |
| Adjacent Channel    | -2MHz          |     | -38 |      | dBm             | 2441MHz      |
| Transmit Power      | +3MHz          | 1// | -44 |      | dBm             |              |
|                     | -3MHz          |     | -35 |      | dBm             |              |

### 2.7.2 Receiver

## **Basic Data Rate**

Table 2-9

| Parameter                         |       | Min | Тур | Max | Unit | Test Conditions |
|-----------------------------------|-------|-----|-----|-----|------|-----------------|
| Sensitivity                       |       |     | -90 |     | dBm  |                 |
| Co-channel Interference Rejection |       |     | -13 |     | dB   |                 |
|                                   | +1MHz |     | +5  |     | dB   | 25°C,           |
| Adjacent Channel                  | -1MHz |     | +2  |     | dB   | Power Supply    |
|                                   | +2MHz |     | +37 |     | dB   | VBAT=3.7V       |
| Interference Rejection            | -2MHz |     | +36 |     | dB   | 2441MHz         |
|                                   | +3MHz |     | +40 |     | dB   |                 |
|                                   | -3MHz |     | +35 |     | dB   |                 |

**Table 2-10** 

| Parameter                         |       | Min | Тур | Max | Unit | Test Conditions |
|-----------------------------------|-------|-----|-----|-----|------|-----------------|
| Sensitivity                       |       |     | -90 |     | dBm  |                 |
| Co-channel Interference Rejection |       |     | -13 |     | dB   |                 |
|                                   | +1MHz |     | +5  |     | dB   | 25°C,           |
|                                   | -1MHz |     | +2  |     | dB   | Power Supply    |
| Adjacent Channel                  | +2MHz |     | +37 |     | dB   | VBAT=3.7V       |
| Interference Rejection            | -2MHz |     | +36 |     | dB   | 2441MHz         |
| /                                 | +3MHz |     | +40 |     | dB   |                 |
|                                   | -3MHz |     | +35 |     | dB   |                 |

# 3. Package Information

# 3.1 QFN52(6mm\*6mm)

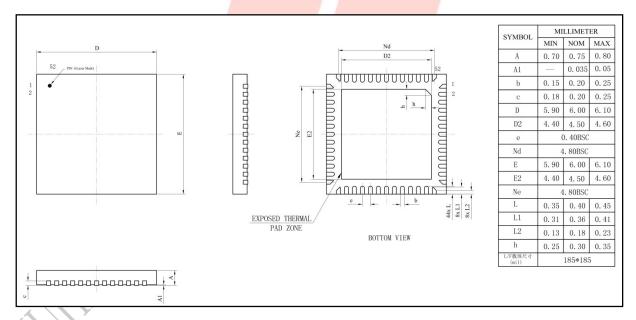


Figure 3-1. AC6354B\_QFN52 Package

# 4. Revision History

| Date       | Revision | Description     |
|------------|----------|-----------------|
| 2021.06.02 | V1.0     | Initial Release |
|            |          |                 |
|            | 1        |                 |

