

Empirical Performance Investigation of a Büchi Complementation Construction

Daniel Weibel

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Abstract

This will be the abstract.

Acknowledgements

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Chapter 1

The Fribourg Construction

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In this chapter we present the Fribourg construction. This is the Büchi complementation construction whose empirical investigation of performance makes up the core of this thesis (Chapters ?? and ??). The Fribourg construction belongs to the *slice-based* of the four complementation approaches that we presented in Section ???. That means it is based on reduced split trees, which we explained in Section ???. The construction has been developed at the University of Fribourg by Joel Allred and Ulrich Ultes-Nitsche¹. They published a description of the Fribourg construction in 2014 as a technical report entitled “Complementing Büchi Automata with a Subset-tuple Construction” [1].

The aim of this chapter is not to give a formally precise description of the Fribourg construction. This has been done very detailed by the authors of the construction in [1]. The same applies for proofs of correctness and complexity calculations. Rather, the aim of this chapter is to describe the construction in a practically oriented way. We want to convey the concrete actions one has to do when standing with a marker in front of a whiteboard with an automaton to complement. For the formal background we refer at any point to [1].

1.1 Basics

High-Level View

To begin with, the Fribourg construction consists of two sub-constructions that we call *upper part construction* and *lower part construction*. These two sub-constructions are chained together, such that the output of the upper part construction becomes the input of the lower part construction. Figure 1.1 illustrates this in a functional view of the Fribourg construction.

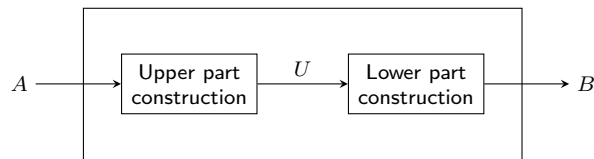


Figure 1.1: Functional view of the Fribourg construction with an automaton A as input and its complement B as output.

The automaton A to be complemented is the input for the upper part construction. The upper part construction builds up a new automaton by starting with an initial state and adding state by state. The output of the upper part construction is an intermediate automaton U . This intermediate automaton U will be the *upper part* of the final complement automaton. The lower part construction takes U as input and adds further states and transitions to it until finally outputting an automaton B which is the complement of the input automaton A . We say that the lower part construction attaches the *lower part* of the final complement automaton to the upper part. This terminology comes from the fact that it is convenient to draw the states of the lower part below the states of the upper part [1]. This also explains why the two sub-constructions are called upper part construction and lower part construction.

Generation of States

The two sub-constructions can be seen as modified subset constructions. Like the subset construction, they work on a set of existing states and add to each state one successor for each symbol of the alphabet. The principle of how successor states are generated is the same for both sub-construction. The difference between the two is that the lower part construction adds additional information to the states (the colours), so that the states generated by the lower part construction are different from the states generated by the upper part construction. Below we explain this basic principle of how new states are generated.

A state of the Fribourg consists of a tuple (that is, an ordered sequence) of subsets of states of the input automaton (note that we will from now on refer to the states of the input automaton as the *input-states*,

¹As mentioned, the authors call their construction *subset-tuple construction*, in this thesis we will however use the name *Fribourg construction*.

and to the states of the output automaton as *output-states*). This contrasts with the subset construction in which the output-states consist of a single subset of input-states. The states of the Fribourg construction are thus more structured than the states of the subset construction. We refer to the subsets of a tuple of a state as the *components* of this state.

The sequence of components of each state of the Fribourg construction is imposed by a slice (that is, a level) of a reduced split tree. We will explain the process of going from an existing state over the slices of a reduced split tree to a successor state further below. For now, we look at how a slice defines the structure of a state. Figure 1.2 shows a reduced split tree (on the left), and for each slice (framed by a shaded box), the state that this slice would define (on the right).

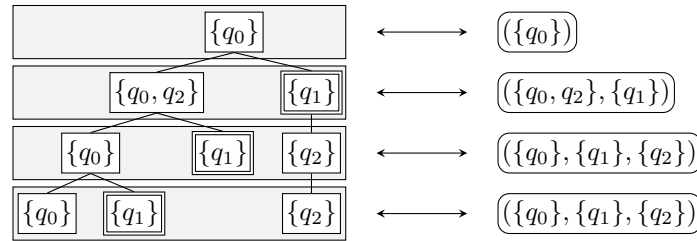


Figure 1.2: Relation between slices of a reduced split tree (left) and states of the output automaton of the Fribourg construction (right). The sequence of nodes in a slice determines the sequence of components in a state.

As can be seen in Figure 1.2, each node of a slice gives rise to a component in the corresponding state. To this end, it does not matter whether the nodes in the slices are siblings or whether their familial relations are. It is important to note, however, that the order of the nodes in a slice must be preserved in the order of the components in a state. It is similarly possible to interpret a state as a slice of a reduced split tree (indicated by the double-ended arrows in Figure 1.2). In this case, it is not possible to deduce the ancestors of the resulting nodes, however, this is not necessary for the construction.

The procedure of determining the successor of a given existing state on a certain alphabet symbol is as follows:

- Interpret the existing state as a slice of a reduced split tree
- Create the subsequent slice for the appropriate alphabet symbol
- Interpret the new slice as a state

The state that results from the new slice is the successor of the existing state for the given alphabet symbol. If, for example, we want to define the successor on the symbol a (a -successor) of the state $(\{q_0\})$, then as the first step we would create a slice representation of it that looks like the first slice from the top in Figure 1.2. Then, we create based on the input automaton the subsequent slice for symbol a , that might look like the second slice from the top in Figure 1.2. Interpreting this slice as a state results in $(\{q_0\}2, \{q_1\})$, which thus is the a -successor of $\{q_0\}$.

Of course the translation of states to and from slices is only a mental aid and not a necessary ingredient. It is possible to deduce $(\{q_0\}2, \{q_1\})$ from $\{q_0\}$, in our previous example, directly without the detour over slices of reduced split trees. However, by conceptually harnessing reduced split trees, we get many of the central points of the construction “for free”, because they are part of the general concept reduced split trees. This includes the splitting of accepting and non-accepting input-states, the placement of the accepting subset to the right of the non-accepting subset, and the retention of only the first occurrence of an input-state from right to left.

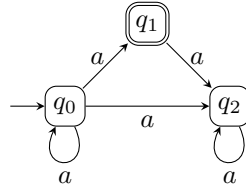


Figure 1.3: Example automaton.

General Remarks

1.2 The Construction

In this section, we describe the Fribourg construction in some more detail, and we illustrate its application with an example.

1.2.1 Upper-Part Construction

Description

The construction of the upper part is simple and works basically as described above. We start with an initial output-state containing only a single component with the initial state of the input automaton. Then, for each output-state q that has no successors so far, we create a successor slice for each symbol of the alphabet α , translate it to a state, and set it as the α -successor of q . This is repeated until all states have been processed.

In case that the resulting automaton is not complete (that is, one or more states do not have successors for certain alphabet symbols), then it is made complete by adding an accepting sink state. This sink state is not actually a part of the upper part, and it is not further processed during the rest of the construction. However, its presence is important in case the upper part is not complete.

The result of this first stage of the construction is a deterministic and complete automaton that does not contain any accepting states (except a possible sink state, but which, as mentioned, does not really belong to the upper part).

Example

We will illustrate the application of the Fribourg construction with the example automaton in Figure 1.3. This automaton has only one single alphabet symbol a . This choice was made to keep the example simple, because an alphabet size of, say 2, would double the number of steps and the number of transitions in the output-automaton. However, the procedure for automata with larger alphabets is exactly the same, just repeat the step of creating a successor state for the current state for each alphabet symbol.

The example automaton in Figure 1.3 does not accept any word, because it is impossible for any run to visit the only accepting state q_1 infinitely many times. The automaton A is thus empty. Consequently, the complement of A is universal, that is, it accepts every possible word².

Figure 1.4 shows the complete steps for creating the upper part from the example automaton in Figure 1.3. In Figure 1.4 (a), we start with a state containing only the component $\{q_0\}$, because q_0 is the initial state of A .

In Figure 1.4 (b), we determine the a -successor of the state $(\{q_0\})$. As explained, this works by looking at the state as a slice of a reduced split tree, and then creating the succeeding slice. For the case of $(\{q_0\})$, this gives the following two slices:

²The only possible ω -word with the alphabet $\Sigma = \{a\}$ is a^ω , that is an infinite sequence of a 's.

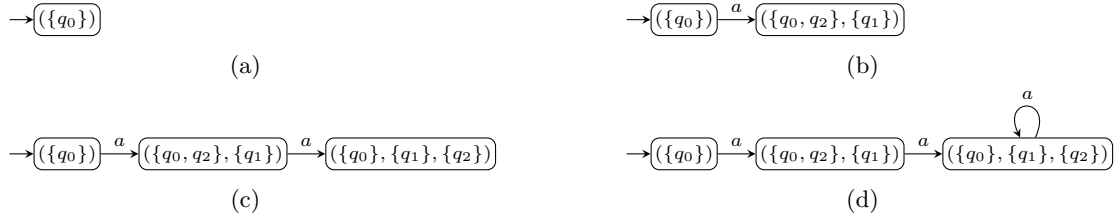
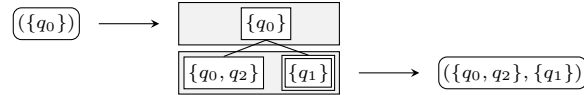
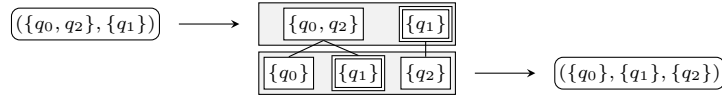


Figure 1.4: Steps for creating the upper part of the complement from the example input-automaton in Figure 1.3.



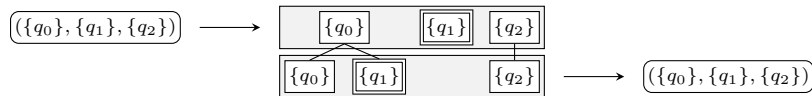
From the state q_0 in the example automaton A , we can reach states q_0 , q_1 , and q_2 with the symbol a . Since q_1 is accepting, it is separated from the other states and put as a separate child to the right of the other child in the new slice. Transforming this new slice back to a state yields $(\{q_0, q_2\}, \{q_1\})$, which is the a -successor of $(\{q_0\})$. The component $\{q_1\}$ is furthermore an accepting component, however, this does not matter in the construction of the upper part. Since there is only the single alphabet symbol a , we have already created all the successors of $(\{q_0\})$. If there would be more alphabet symbols, we would have to repeat the same procedure for each symbol.

In Figure 1.4 (c), we create the a -successor of the previously created $(\{q_0, q_2\}, \{q_1\})$. Applying the same procedure as before, we get the following two slices:



Since we use right-to-left reduced split trees, we have to create the new slice from right to left, that is, first determining the children of vertex q_1 , and then of $\{q_0, q_2\}$. From q_1 we can only reach q_2 on symbol a , thus the only child of $\{q_1\}$ is $\{q_2\}$. From the states in $\{q_0, q_2\}$, we can reach q_0 , q_1 , and q_2 on symbol a . However, q_1 already appears in the new slice, so it drops out. From the remaining states q_0 and q_2 , q_1 is accepting, so it becomes a separate right-child, whereas q_0 becomes the left-child. Translating this slice to a state yields $(\{q_0\}, \{q_1\}, \{q_2\})$, which is the a -successor of $(\{q_0, q_2\}, \{q_1\})$.

In Figure 1.4 (d), we determine in turn the a -successor of $(\{q_0\}, \{q_1\}, \{q_2\})$. Applying again the slice-procedure, we get the following:



Again, we process the vertices of the upper slice from right to left. The only a -successor of q_2 in automaton A is q_2 , thus $\{q_2\}$ is the only child of the vertex $\{q_2\}$ in the upper slice. The state q_1 has q_2 as its a -successor. However, q_2 already appears in the new slice, and thus it drops out. Since q_1 has no remaining a -successors, the vertex $\{q_1\}$ in the upper slice remains childless³. Finally, the a -successors of q_0 are q_0 , q_1 , and q_2 , however, as before, q_2 drops out because it already appears to the right, and q_0 and q_1 are separated because q_1 is accepting. Translating the new slice back to a state results in $(\{q_0\}, \{q_1\}, \{q_2\})$, which is identical to the current state. Thus, instead of adding a new state to the automaton, we just add an a -loop to $(\{q_0\}, \{q_1\}, \{q_2\})$.

At this stage, all the existing states have successors for all the alphabet symbols, and thus the construction of the upper part is completed. The next step is to attach the lower part to the upper part in order to form the final complement automaton.

³In the terminology that we will use starting from the next section, we say that the runs going through this q_1 “disappear”.

1.2.2 Lower-Part Construction

The construction of the lower part takes the states of the previously constructed upper part as input. This means that these states are taken as the initial “states to be processed”. Thus, the states of the upper part will get additional successors in the lower part, which makes the states of the upper part non-deterministic⁴. The states of the lower part, in turn, are deterministic, and do not have transitions back to the upper part. This means that once a run switches from the upper to the lower part, it stays there infinitely (or dies there).

The construction of the lower part proceeds principally in the same way as the construction of the upper part. However, it includes some additional “structure” in the form of a decoration of the components. In particular, every component of a lower-part state is assigned a colour. This colour is determined at creation time of the containing state, and is never changed⁵. These colours are distinguishing features for the containing states. This means that if two states contain the same components in the same order, but the components have different colours, then the two states are different. Clearly, this makes the number of possible states of the lower part much larger than the number of possible states of the upper part.

We denote these three colours for the components of the lower part by 0, 1 and 2. In order to determine the accepting set at the end of the construction, it is necessary to distinguish the states from the upper part from the states of the lower part. This problem is solved by previously assigning the special colour -1 to all components of upper part-states.

The assignment of a colour to a component of a lower-part state depends on three things:

1. Whether the component is accepting or non-accepting
2. The colour of the predecessor component
3. Whether the state containing the predecessor component contains any 2-coloured components

How much to describe the concept of predecessor component, as it is already described in Section 1.1?

The rules for assigning one of the colours 0, 1, and 2 to a component c are shown in Figure 1.5. There are two different sets of rules for the cases that the state containing the predecessor component *does* (Figure 1.5 (b)), or *does not* (Figure 1.5 (a)) contain components with colour 2. In each of these cases, the two remaining criteria, whether c is accepting or non-accepting, and the colour of the predecessor component c_{pred} , determine a single colour that must be assigned to component c (bold in Figure 1.5).

In the first case, that the predecessor state contains no 2-coloured components, the possible colours of the predecessor components are -1 , 0, and 1. Naturally, the predecessor component cannot be 2-coloured, but on the other hand, it might have colour -1 , if the predecessor state is a state of the upper part. For the other case, that the predecessor state contains 2-coloured components, the possible colours for the predecessor component naturally include colour 2, but do not include colour -1 , because a state containing 2-coloured components cannot be a state of the upper part.

The purpose of the colours is to signalise the presence or absence of certain runs of the input automaton on a specific word. Note that the complement of a non-deterministic automaton must accept a word if and only if *all* the runs of the input automaton on this words are rejecting. If there is a single run of the input automaton that accepts the word, then the complement automaton must not accept the word. Thus, we need a way to be sure that there are *no* accepting runs of the input automaton on a specific word, and then we can accept this word with the complement automaton.

Colour 2 Is used to signalise the presence of “dangerous” runs, that is, runs that have the potential to become accepting. If a component has colour 2, it means that there are input-runs that made a “right-turn”, in terms of slices of reduced split trees, that is, visited an accepting state (see rules in Figure 1.5 (a) line 1 and 2). Note that all the successor components of a 2-coloured component are also 2-coloured, no matter if they are accepting or non-accepting (Figure 1.5 (b) line 3). A “string” of 2-coloured components can only be cut if a 2-coloured component has no successor components

⁴Two points about this non-determinism are interesting. First, the states of the upper part are the only non-deterministic states, all the other states are deterministic. Second, the degree of non-determinism of these states is at most 2, and thus the degree of non-determinism of the entire complement automaton is at most 2.

⁵The colour of a component may be changed with the optimisations described in Section 1.3.

Colour of c_{pred}	c is non-accepting	c is accepting
-1	0	2
0	0	2
1	2	2

(a) Case A: the predecessor state has *no* 2-coloured components

Colour of c_{pred}	c is non-accepting	c is accepting
0	0	1
1	1	1
2	2	2

(b) Case B: the predecessor state *has* 2-coloured components

Figure 1.5: Rules for determining the colour of a component c , based on (1) the colour of the predecessor component c_{pred} , and (2) whether c is an accepting or non-accepting component. There are two set of rules that are shown in the two subfigures: (a) the predecessor state does not have any components with colour 2, and (b) the predecessor state does have one or more components with colour 2.

(no children in terms of reduced split trees). In this case we say that the 2-coloured component “disappears”.

Colour 1 Means basically the same as colour 2, namely that there are “dangerous” runs. The reason that colour 1 exists is a caveat that could arise if we would assign colour 2 to *every* component that just made a right-turn. In this case, it could happen that we miss the disappearance of 2-coloured components, and thus keep the containing output-state non-accepting instead of accepting. For this reason, the trick with colour 1 works as follows. If the predecessor state already contains 2-coloured components, then every component of the current state that deserves to be 2-coloured gets colour 1 instead of colour 2. This can be seen in Figure 1.5 (b) line 1 and 2. These are actually “dangerous” components kept “on hold”, because then trick goes on as follows. As soon as all the 2-coloured components of a state disappear, the successors of all the 1-coloured components get 2-coloured. This can be seen in Figure 1.5 (a) line 3. At this point, these “dangerous” components “on hold” get the real “dangerous” components.

Colour 0 Means the absence of “dangerous” runs. This is because the corresponding input-run did not make any right-turns, that is, they went only through non-accepting states. These runs are “safe” in the sense that so far they bear no risk of becoming accepting runs.

Wrapping up, for constructing the lower part of the output automaton, one just has to apply the same successor creation procedure as for the upper part, with the addition of assigning colours to the new states’ components according to the rules in Figure 1.5. In the end, when every state has been processed and the procedure ends, the only thing that is missing is to determine the accepting states of the resulting automaton. The rule is that every state of the lower part that does *not* contain any 2-coloured components is an accepting states. That means that every state of the automaton that contains exclusively 0-coloured and/or 1-coloured components is an accepting state.

In the following, we demonstrate the application of the lower-part construction by an example.

Example

We continue the complementation of the example automaton in Figure 1.3 with the construction of the lower part. Therefore, we start where we left off the example in the last section, namely with the upper part. For this example, we will use the following notation for specifying the colour of a component $\{q\}$:

- $\widehat{\{q\}}$: colour -1
- $\{q\}$: colour 0

- $\overline{\{q\}}$: colour 1
- $\overline{\overline{\{q\}}}$: colour 2

Figure 1.6 shows some of the steps of the construction of the lower part. In Figure 1.6 (a), we start with the upper part that we previously constructed in the last section. The only difference is that we assigned colour -1 to all of the components of the upper part.

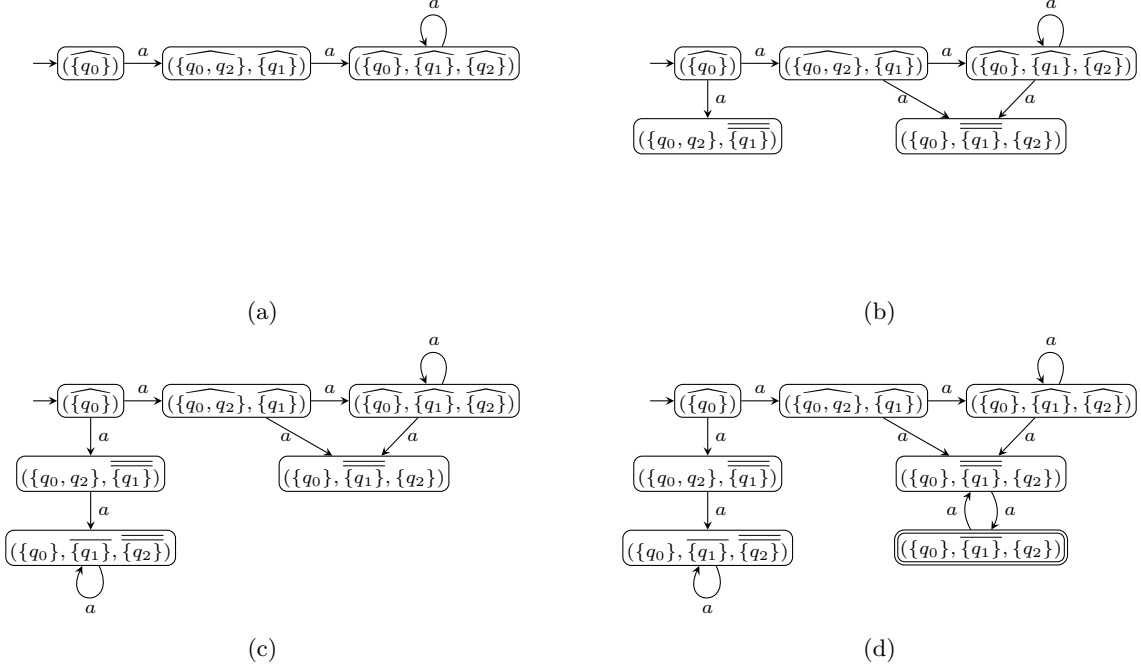
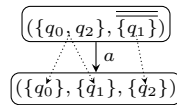


Figure 1.6: Selected steps of the construction of the lower part, starting with the upper part

In Figure 1.6 (b), we created the a -successors of the three states of the upper part. The structure of these new states, apart from the colours, is determined by the same method that we used for the upper part. The only difference in the construction of the lower part is that each component is assigned a colour. For both new states, the predecessor states do not contain any 2-coloured components, thus we only need to consider the colour rules in Figure 1.5 (a). Regarding the colour of the predecessor components, they all have colour -1 , thus we have to use the rule in Figure 1.5 (a) line 1 for all the new components. In this way, the components $\{q_0, q_2\}$, $\{q_0\}$, and $\{q_2\}$ are assigned colour 0, because they are non-accepting, and component $\{q_1\}$ gets colour 2, because it is accepting.

Note how we have to keep track for each component of the lower part whether it is accepting or non-accepting, and which is its predecessor component in the predecessor state.

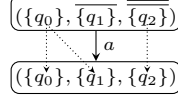
In Figure 1.6 (c), we added the a -successor to the state $\{\{q_0, q_2\}, \overline{\{q_1\}}\}$. Disregarding the colours, this state has the form $\{\{q_0\}, \{q_1\}, \{q_2\}\}$. Its predecessor state $\{\{q_0, q_2\}, \{q_1\}\}$ contains a 2-coloured component, thus we have to use the colour rules in Figure 1.5 (b). Now we need to know which are the predecessor components of the components in $\{\{q_0\}, \{q_1\}, \{q_2\}\}$. This information is contained in the two slices of the reduced split tree that were used to determine the structure of the new state. For the case of our two states, the successor relation of their components is as follows:



The predecessor component of $\{q_0\}$ is $\{q_0, q_2\}$, which has colour 0. Thus, we have to use the rule in Figure 1.5 (b) line 1, and $\{q_0\}$ gets the colour 0, because it is non-accepting. The predecessor component of $\{q_1\}$ is also $\{q_0, q_2\}$, and we have to use the same rule. However, since $\{q_1\}$ is accepting, it gets colour 1. Note how the use of colour 1 here prevents the introduction of a further 2-coloured component before

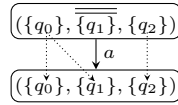
an already existing 2-coloured component has disappeared. The predecessor component of $\{q_2\}$ is the 2-coloured $\overline{\{q_1\}}$, and thus, according to the rule in Figure 1.5 (b) line 3, $\{q_2\}$ also gets colour 2.

Next, still in Figure 1.6 (c), we create in turn the successor state of $(\{q_0\}, \overline{\{q_1\}}, \overline{\{q_2\}})$. The structure of the components stays the same for the successor. The successor relation of the two states is as follows:



The result is that $\{q_0\}$ gets colour 0, $\{q_1\}$ gets colour 1, and $\{q_2\}$ gets colour 2. Thus, the successor state is identical to the current state, and we add loop.

Figure 1.6 (d) includes the remaining for arriving at the final complement automaton. First, we created the a -successor of the state $(\{q_0\}, \overline{\{q_1\}}, \{q_2\})$. The complement successor relation of this state with its successor is as follows:



According to the rules in Figure 1.5 (b), component $\{q_0\}$ gets colour 0, $\{q_1\}$ gets colour 1, and $\{q_2\}$ gets colour 0. This results in a new state, since the colours are different from the ones in the current state. Interesting here is that we have the case that a 2-coloured component “disappears”. This is because the component $\overline{\{q_1\}}$ has no successor component in the successor state. For the a -successor of the new state $(\{q_0\}, \overline{\{q_1\}}, \{q_2\})$, this means in turn that we have to use the rules in Figure 1.5 (a), what results in the already existing state $(\{q_0\}, \overline{\{q_1\}}, \{q_2\})$.

At this point, all the states in the automaton have been processed, and the construction is therefore completed. The only thing that remains to be done is to determine the accepting states of the automaton. The rule is that each state of the lower part that does not contain any 2-coloured component is an accepting state. In our automaton this applies only to the state $(\{q_0\}, \overline{\{q_1\}}, \{q_2\})$, which is thus the only accepting state of the automaton.

It can be easily seen that the automaton in Figure 1.6 accepts the word a^ω , which is not accepted by the input automaton in Figure 1.3. Thus, the result of our construction is a correct complement of the input automaton.

A loose upper bound for the worst-case state complexity of the entire construction (including the construction of both, the upper and the lower part) has been calculated to be in $O((1.59n)^n)$, where n is the number of states of the input automaton [1]. This result is subject to refinement in ongoing research by the authors of the Fribourg construction. As mentioned, this publication ([1]) also contains a formal description and a proof of correctness of the construction.

1.3 Optimisations

There are several optimisations to the basic Fribourg construction, which all have the goal to reduce the size of the output automaton. These optimisations are like “add-ons” and can be added to the basic construction and combined in different ways.

In this section, we describe three of these optimisations. For easier reference, we define an abbreviation for each optimisation: R2C, M1, and M2. These optimisations will also be subject to the empirical performance investigation of the Fribourg construction, starting from the next chapter, and there we will use the same abbreviations.

1.3.1 R2C: Remove States with Rightmost 2-Coloured Components

The R2C optimisation can be summarised as follows:

If the input automaton is complete, then states of the lower part whose rightmost component has colour 2 can be omitted.

This means that if during the construction of the lower part we determine a state that has a 2-coloured rightmost component, then we do not need to add this state to the automaton. This consequently also omits all the potential successors of this state from the automaton.

The reason for this is the following fact. If the input automaton is complete, then the rightmost component of an output-state *always* has at least one successor component (because of the completeness of the input automaton). However, this applies only to the rightmost component, as the successors of the other components might be omitted, due to the right-to-left precedence in right-to-left reduced split trees.

If the colour of the rightmost component is 2, then the successor component inherits this colour 2 (Figure 1.5 (b) line 3). This means inductively that all the successors of a state with a 2-coloured rightmost component will have a 2-coloured rightmost component. Or in other words, there is a 2-coloured component that will never disappear. Since states containing a 2-coloured component are non-accepting, these states form a cycle without a single accepting state, and this cycle can be removed without changing the language of the automaton.

Note, however, that the omission of these states can only be done if the input automaton is complete.

1.3.2 M1: Merge Components

The M1 optimisation allows the merging of adjacent components depending on their colour. With the merging of adjacent components, we mean the replacement of these components with their union (if regarding components as sets). The three merging rules are as follows.

1. Two adjacent 1-coloured components can be merged to a single 1-coloured component
2. Two adjacent 2-coloured components can be merged to a single 2-coloured component
3. A 2-coloured component adjacent to a 1-coloured component (in this order from left to right) can be merged to a single 2-coloured component

These mergings can be done recursively. This means that the result of a merging can again be subject to further merging, until nothing more can be merged. For example, the state $(\{q_0\}, \overline{\{q_1\}}, \overline{\{q_2\}}, \overline{\{q_3\}}, \overline{\{q_4\}}, \overline{\{q_5\}})$ can be transformed to $(\{q_0\}, \overline{\{q_1, q_2, q_3, q_4, q_5\}})$, by the recursively applying the above three merging rules.

Consequent applying of these mergings reduces the maximal number of states in the output automaton. An upper bound on the number of states in the lower part of the automaton has been calculated to be in $O((1.195n)^n)$, where n is the number of states of the input automaton [1]. This is considerably lower than the $O((1.59n)^n)$ worst-case state growth of the Fribourg construction without the M1 optimisation. A formal description and a proof of correctness of the M1 optimisation can be found in [1] (Section 4.E).

1.3.3 M2:

The M2 optimisation is the most involved of the three optimisations. Furthermore, it can only be applied together with the M1 optimisation. The main point of the M2 optimisation can be summarised as follows:

Every state of the lower part contains *at most* one 2-coloured component.

The purpose of this restriction is to further reduce the maximal number of states the construction can generate (that is, to reduce the worst-case state complexity of the construction).

- When determining the colours of the components of a new state, the components must be processed from right to left
- The first component that according to the rules in Figure 1.5 deserves colour 2 gets colour 2 as usual
 - If this component has a sibling⁶ to its left, then this sibling gets colour 2 as well

⁶With sibling we mean having the same predecessor component.

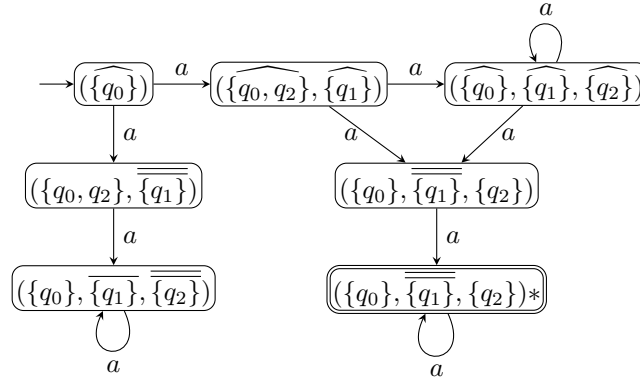


Figure 1.7: Result of applying the M2 optimisation to the complementation of the example automaton from Figure 1.3.

- From the point on where colour 2 has been assigned to a component (and possibly its sibling), all the further components that according to Figure 1.5 deserve colour 2 get colour 1 instead of colour 2

This leaves the new state in a situation where at most two components have colour 2, namely the first one that deserves it from the right, and its possible sibling. In the case that there was a sibling, the application of the M1 optimisation (which is necessary for the application of the M2 optimisation) merges these two components to a single 2-coloured component. This makes the state in any case having at most one 2-coloured component.

This modification of the construction requires further care to be taken when the only 2-coloured component of a state “disappears”, that is, has no successor components in the state under construction. In this case, one of the 1-coloured components of this state is made accepting. In more detail, the points to consider are as follows.

- Disappearance of a 2-coloured component: if the predecessor of a new state has a 2-coloured component, and if after the assignment of colours to the components of this new state, as described above, the new state has no 2-coloured component, then we say that the 2-coloured component of the predecessor state disappeared.
- When the disappearance of a 2-coloured component is detected, and if the state under construction contains at least one 1-coloured component, then the following is done:
 - The position where the successor component of the disappeared component *would* be is determined
 - Select the first 1-coloured component that is to the left of the first a 0-coloured component that is to the left of this position
 - * If the search arrives at the leftmost component of the state, then continue it starting from the rightmost component
 - * If there is exactly one 1-coloured component in the state, then directly select this component
 - Change the colour of the selected component from 1 to 2
 - Mark the state with a special mark (for example a *)
 - * This mark distinguished states. That is, if two states have the same components with the same colours, but one has a mark and the other not, then they are two different states.

The result of this procedure is that the state has a single 2-coloured component again. However, as mentioned, this state must be accepting, even though it contains a 2-coloured component. It is the purpose of the mark to distinguish this state from other states with a 2-coloured component. The last thing we have to do is to change the acceptance condition to include all states of the lower part containing no 2-coloured components, plus all states having a mark.

In this case, the difference is the marked state $(\{q_0\}, \overline{\overline{\{q_1\}}}, \{q_2\})^*$. It exists, because the 2-coloured component $\overline{\overline{\{q_1\}}}$ of the predecessor state disappears. According to the colour rules, the $\overline{\overline{\{q_1\}}}$ in the new state then gets colour 1. This is where the construction without the M2 optimisation would left off. With the M2 optimisation, however, we have to select one of the 1-coloured components of the new state and change its colour to colour 2. There is only one 1-coloured component in the state, $\overline{\overline{\{q_1\}}}$, and so we change its colour from 1 to 2. We also mark this state with a star. The successor of this marked state happens to be identical with itself (because the component $\overline{\overline{\{q_1\}}}$ again disappears), so we add a loop. In the end, the marked state is made accepting.

In [1] (Section 4.H) a very loose upper bound on the number of states of the lower part of $O((0.86n)^n)$ is proposed. This is a significant reduction from the upper bound of $O((1.195n)^n)$ that is achieved with the M1 optimisation. Furthermore, concrete calculations on the M2 optimisation suggest that the real upper bound might be as low as $O((0.76n)^n)$. This coincides with the established lower bound for Büchi complementation by Yan [55] and would make the construction optimal in the sense of worst-case state complexity. The actual complexity of the M2 optimisation is subject to further research by the authors of the Fribourg construction.

[1] Section 4.H

Appendix A

Plugin Installation and Usage

Since between the 2014-08-08 and 2014-11-17 releases of GOAL certain parts of the plugin interfaces have changed, and we adapted our plugin accordingly, the currently maintained version of the plugin works only with GOAL versions 2014-11-17 or newer. It is thus essential for any GOAL user to update to this version in order to use our plugin.

Appendix B

Median Complement Sizes of the GOAL Test Set

Bla bla bla

Appendix B. Median Complement Sizes of the GOAL Test Set

	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
1.0	269	308	254	236	238	297	266	156	207	68	1.0	269	308	254	236	238	297	266	156	207	68
1.2	960	1,407	1,479	2,150	1,152	1,090	942	1,206	718	104	1.2	960	1,407	1,479	2,150	1,152	1,090	942	1,206	718	104
1.4	3,426	2,915	2,752	3,393	2,693	3,265	2,263	2,425	1,844	154	1.4	3,426	2,915	2,752	3,393	2,693	3,265	2,263	2,425	1,844	154
1.6	3,799	3,698	4,901	3,926	3,960	3,655	2,580	1,905	2,124	155	1.6	3,799	3,698	4,901	3,926	3,960	3,655	2,580	1,905	2,124	155
1.8	3,375	3,169	3,420	3,967	3,943	3,132	2,246	1,144	971	114	1.8	3,375	3,169	3,420	3,967	3,943	3,093	2,246	1,144	971	114
2.0	1,906	2,261	2,383	2,884	2,354	2,096	1,169	932	568	98	2.0	1,906	2,184	2,383	2,818	2,354	1,989	1,127	885	568	97
2.2	1,467	1,633	1,795	1,942	1,611	1,640	569	499	330	78	2.2	1,410	1,561	1,639	1,884	1,609	1,588	496	464	284	78
2.4	924	1,232	1,319	1,317	1,056	886	514	314	182	59	2.4	884	1,200	1,234	1,184	939	806	373	256	165	55
2.6	625	763	880	945	828	684	316	175	132	44	2.6	575	731	815	860	751	575	246	162	114	43
2.8	483	584	836	690	575	395	240	151	103	41	2.8	431	530	672	466	371	274	174	120	85	36
3.0	319	450	557	523	367	313	155	116	84	32	3.0	232	325	344	360	269	169	91	85	53	27
(a) Fribourg											(b) Fribourg+R2C										
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
1.0	390	438	434	324	328	459	337	204	227	40	1.0	225	223	195	181	187	199	189	124	161	68
1.2	1,576	2,394	2,505	2,996	1,613	1,551	1,166	1,542	1,002	58	1.2	731	971	946	1,071	629	562	488	568	388	104
1.4	5,007	4,336	4,652	4,877	3,458	3,956	3,169	3,380	1,868	86	1.4	2,228	1,701	1,543	1,732	1,241	1,287	945	944	727	154
1.6	5,067	5,032	6,444	4,868	4,575	3,864	3,211	1,731	1,892	85	1.6	2,489	2,263	2,331	2,133	1,777	1,443	964	757	889	155
1.8	4,016	3,701	3,647	4,523	3,548	3,009	1,808	451	336	62	1.8	2,381	2,027	2,009	2,075	1,618	1,243	1,005	592	515	114
2.0	1,663	2,276	2,676	3,035	1,925	1,932	464	307	150	54	2.0	1,390	1,569	1,416	1,573	1,093	1,008	594	464	330	98
2.2	989	1,514	1,621	1,826	1,121	846	155	127	93	45	2.2	1,118	1,197	1,150	1,151	879	809	317	330	241	78
2.4	560	821	919	771	529	267	133	87	55	32	2.4	712	885	836	809	580	535	316	231	145	59
2.6	388	519	524	441	259	219	84	50	41	26	2.6	498	569	601	627	497	412	217	137	113	44
2.8	311	317	396	242	165	95	64	44	33	22	2.8	391	455	578	456	374	263	173	119	90	41
3.0	173	224	211	169	102	72	41	34	27	18	3.0	258	350	392	354	253	208	119	97	74	32
(c) Fribourg+R2C+C											(d) Fribourg+M1										
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
1.0	215	213	189	174	175	192	186	121	156	68	1.0	225	223	195	181	187	199	189	124	161	68
1.2	712	914	913	1,075	619	563	526	620	416	104	1.2	731	971	946	1,071	629	562	488	568	388	104
1.4	2,075	1,620	1,503	1,650	1,254	1,339	1,003	1,006	848	154	1.4	2,228	1,701	1,543	1,732	1,241	1,287	945	944	727	154
1.6	2,344	2,062	2,340	2,016	1,755	1,520	1,053	858	986	155	1.6	2,489	2,263	2,331	2,133	1,777	1,443	964	757	889	155
1.8	2,205	1,873	1,920	2,040	1,689	1,315	1,080	664	598	114	1.8	2,381	2,027	2,009	2,075	1,618	1,215	1,005	592	515	114
2.0	1,290	1,485	1,405	1,522	1,134	1,044	652	531	392	98	2.0	1,390	1,513	1,416	1,542	1,093	1,003	594	441	330	97
2.2	1,023	1,119	1,092	1,127	868	875	376	359	262	78	2.2	1,019	1,156	1,064	1,104	859	785	304	303	221	78
2.4	674	849	790	807	617	544	355	251	156	59	2.4	672	867	789	772	544	478	269	191	139	55
2.6	478	549	594	597	510	431	231	147	116	44	2.6	466	542	572	568	452	348	183	129	99	43
2.8	370	439	559	455	382	283	182	124	93	41	2.8	368	407	480	337	260	197	129	96	75	36
3.0	249	341	388	348	260	225	123	101	77	32	3.0	201	261	266	272	199	136	83	74	50	27
(e) Fribourg+M1+M2											(f) Fribourg+M1+R2C										
	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
1.0	329	303	279	240	229	288	230	157	160	40	1.0	126	118	97	60	51	52	62	36	48	30
1.2	988	1,392	1,356	1,352	751	741	608	704	516	58	1.2	432	517	345	262	160	126	92	120	109	40
1.4	2,939	2,581	2,066	2,190	1,351	1,622	1,132	1,261	932	86	1.4	1,044	331	133	89	45	22	19	31	27	20
1.6	3,150	2,900	2,842	2,218	1,885	1,563	1,177	821	896	85	1.6	358	24	11	5	4	6	5	3	3	4
1.8	2,782	2,485	2,047	2,180	1,625	1,269	855	395	309	62	1.8	19	5	1	1	1	1	1	1	1	1
2.0	1,338	1,638	1,544	1,566	979	957	349	261	147	54	2.0	1	1	1	1	1	1	1	1	1	1
2.2	838	1,125	993	1,027	667	521	153	125	93	45	2.2	1	1	1	1	1	1	1	1	1	1
2.4	494	700	624	524	296	214	126	87	55	32	2.4	1	1	1	1	1	1	1	1	1	1
2.6	327	434	383	334	212	163	82	50	41	26	2.6	1	1	1	1	1	1	1	1	1	1
2.8	283	273	305	202	144	95	60	44	33	22	2.8	1	1	1	1	1	1	1	1	1	1
3.0	164	200	173	142	92	72	41	34	27	18	3.0	1	1	1	1	1	1	1	1	1	1
(g) Fribourg+M1+R2C+C											(h) Fribourg+R										

Figure B.1: Median complement sizes of the 10,939 effective samples of the internal tests on the GOAL test set. The rows (1.0 to 3.0) are the transition densities, and the columns (0.1 to 1.0) are the acceptance densities.

	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0		0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
1.0	130	117	109	77	69	61	56	40	40	29	1.0	171	174	166	124	118	117	100	67	84	35
1.2	387	456	352	281	155	136	101	105	75	45	1.2	622	833	803	877	529	398	320	372	215	53
1.4	822	683	394	376	230	204	151	120	105	63	1.4	2,086	1,618	1,367	1,676	1,065	967	664	682	494	78
1.6	890	594	458	321	237	178	134	114	113	61	1.6	2,465	2,073	2,182	1,959	1,518	1,259	767	545	623	78
1.8	624	507	324	275	196	136	110	92	89	41	1.8	2,310	1,963	1,950	1,988	1,485	1,095	746	418	346	57
2.0	362	286	211	176	117	103	79	64	59	34	2.0	1,318	1,482	1,393	1,461	981	871	434	338	228	50
2.2	248	222	124	116	82	73	56	52	50	28	2.2	1,068	1,145	1,085	1,067	772	747	263	235	158	40
2.4	147	145	114	87	56	48	43	39	35	19	2.4	689	838	809	751	524	466	240	159	93	30
2.6	115	117	67	61	47	42	32	29	29	15	2.6	469	531	555	565	437	360	169	94	71	23
2.8	95	71	52	45	38	29	27	25	23	13	2.8	369	421	536	405	329	224	130	81	58	21
3.0	59	60	47	35	32	27	22	21	20	10	3.0	244	327	360	322	219	176	85	64	49	16

(a) Piterman+EQ+RO
(b) Slice+P+RO+MADJ+EG

Figure B.2: Median complement sizes of the 10,998 effective samples of the external tests without the Rank construction. The rows (1.0 to 3.0) are the transition densities, and the columns (0.1 to 1.0) are the acceptance densities.

Appendix C

Execution Times

Construction	Mean	Min.	P25	Median	P75	Max.	Total	\approx hours
Fribourg	8.5	2.5	3.3	4.9	7.3	586.0	93,351.2	259
Fribourg+R2C	6.6	2.2	2.9	4.2	6.4	219.7	72,545.7	202
Fribourg+R2C+C	8.5	2.2	2.6	3.5	6.4	582.9	93,396.2	259
Fribourg+M1	4.9	2.5	3.2	4.1	5.9	55.1	54,061.3	150
Fribourg+M1+M2	4.6	2.2	2.9	3.8	5.1	38.4	49,848.0	138
Fribourg+M1+R2C	4.4	2.2	2.8	3.6	5.3	42.5	48,572.0	135
Fribourg+M1+R2C+C	5.6	2.5	3.2	4.0	6.5	147.4	60,918.9	169
Fribourg+R	7.5	2.2	3.0	3.9	6.3	470.5	82,387.3	229

Table C.1: Execution times in CPU time seconds for the 10,939 effective samples of the GOAL test set.

Construction	Mean	Min.	P25	Median	P75	Max.	Total	\approx hours
Piterman+EQ+RO	3.0	2.2	2.6	2.8	3.0	42.9	21,410.6	59
Slice+P+RO+MADJ+EG	3.7	2.2	2.7	3.2	4.1	36.7	26,398.9	73
Rank+TR+RO	16.0	2.3	2.8	3.7	9.3	443.3	115,563.9	321
Fribourg+M1+R2C	4.0	2.2	2.7	3.1	4.4	410.4	28,970.8	80

Table C.2: Execution times in CPU time seconds for the 7,204 effective samples of the GOAL test set.

Construction	Mean	Min.	P25	Median	P75	Max.	Total	\approx hours
Piterman+EQ+RO	3.6	2.2	2.7	2.9	3.4	365.7	39,663.4	110
Slice+P+RO+MADJ+EG	4.3	2.2	2.9	3.7	5.0	42.4	47,418.2	132
Fribourg+M1+R2C	4.7	2.2	2.8	3.6	5.3	410.4	52,149.0	145

Table C.3: Execution times in CPU time seconds for the 10,998 effective samples of the GOAL test set without the Rank construction.

Construction	Michel 1	Michel 2	Michel 3	Michel 4	Fitted curve	Std. error
Fribourg	2.3	4.0	88.8	100,976.0	$(1.14n)^n$	0.64%
Fribourg+R2C	2.3	3.4	27.4	27,938.3	$(0.92n)^n$	0.64%
Fribourg+M1	2.2	3.6	17.9	6,508.4	$(0.72n)^n$	0.63%
Fribourg+M1+M2	2.3	3.5	13.8	2,707.4	$(0.62n)^n$	0.62%
Fribourg+M1+M2+R2C	2.5	3.5	10.8	2,332.6	$(0.61n)^n$	0.62%
Fribourg+R	2.4	3.7	86.0	101,809.6	$(1.14n)^n$	0.64%

Table C.4: Execution times in CPU time seconds for the four Michel automata.

Construction	Michel 1	Michel 2	Michel 3	Michel 4	Fitted curve	Std. error
Piterman+EQ+RO	2.5	3.8	42.6	75,917.4	$(1.08n)^n$	0.64%
Slice+P+RO+MADJ+EG	2.3	3.6	11.4	159.5	$(0.39n)^n$	0.38%
Rank+TR+RO	2.2	3.0	6.4	30.0	$(0.29n)^n$	0.18%
Fribourg+M1+M2+R2C	2.5	3.5	10.8	2,332.6	$(0.61n)^n$	0.62%

Table C.5: Execution times in CPU time seconds for the four Michel automata.

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