Compiler Principle

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5 SEMANTIC ANALYSIS

The task of semantic analysis

- 1. Connect variable definitions to their uses ;
- 2. Check if each expression has a correct type;
- 3. Translates the abstract syntax into a simpler representation suitable for generating machine code.

5.1 Symbol Table

Maintenance of symbol tables mapping identifiers to their types and locations

Environment definition

- An environment is a set of bindings
 - ✓ denoted by the → arrow

```
1. function f( a:int ,b:int, c:int) =
2. { print_int (a+c);
3. let var j:= a+b
4. var a:= "hello"
5. in print(a); print_int(j)
6. end;
7. print_int(b)
8. }
```

```
line 1:
\sigma1 equal to \sigma0 + {a \mapsto int, b
\mapsto int, c \mapsto int}
line 3:
the table \sigma 2 = \sigma 1 + \{j \mapsto
int}
line 4:
the table \sigma 3 = \sigma 2 + \{a \mapsto
string}
```

Scope: where the identifiers are visible

Environment definition

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 - ✓ denoted by the → arrow

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    function f( a:int ,b:int, c:int) =
    { print_int (a+c);
    let var j:= a+b
    var a:= "hello"
    in print(a); print_int(j)
    end;
    print_int(b)
    }
```

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```

X + Y for tables is not the same as Y + X

Environment management

A functional style

• To keep σ_1 in pristine condition while creating create σ_2 and σ_3

An imperative style

- Modify σ 1 until it becomes σ 2.
- While σ 2 exists, we cannot look things up in σ 1.
- When done with σ 2, can undo the modification to get σ 1 back again.

Either the functional or imperative style of environment management can be used.

MULTIPLE SYMBOL TABLES

- There can be several active environments at once;
- Each module, or class has a symbol table σ of its own.

```
package M;
class E {
   static int a = 5;
class N {
   static int b = 10;
   static int a = E.a + b;
class D {
   static int d = E.a + N.a;
```

```
\sigma 1 = \{ a \mapsto int \}
\sigma 2 = \{ E \mapsto \sigma 1 \}
\sigma 3 = \{ b \mapsto int , a \mapsto int \}
\sigma 4 = \{ N \mapsto \sigma 3 \}
\sigma 5 = \{ d \mapsto int \}
\sigma 6 = \{ D \mapsto \sigma 5 \}
\sigma 7 = \sigma 2 + \sigma 4 + \sigma 6
```

In Java, forward reference is allowed so E, N, and D are all compiled in the environment σ_7 ; for this program the result is still $\{M \mapsto \sigma_7\}$.

Java

MULTIPLE SYMBOL TABLES

- There can be several active environments at once;
- Each module, or class has a symbol table σ of its own.

```
structure M =
struct
 structure E =
struct
   val a = 5;
 end
 structure N =
struct
   val b = 10
   val a = E.a + b
 end
 structure D =
```

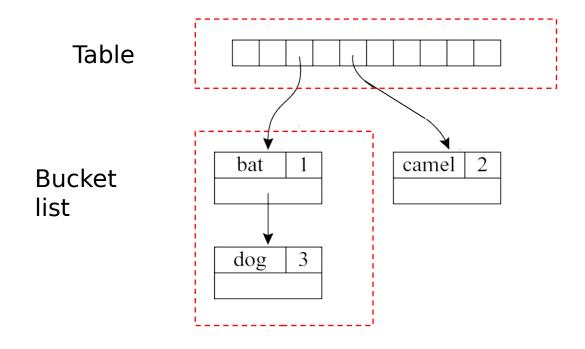
```
\sigma 1 = \{ a \mapsto int \}
\sigma 2 = \{ E \mapsto \sigma 1 \}
\sigma 3 = \{ b \mapsto int , a \mapsto int \}
\sigma 4 = \{ N \mapsto \sigma 3 \}
\sigma 5 = \{ d \mapsto int \}
\sigma 6 = \{ D \mapsto \sigma 5 \}
\sigma 7 = \sigma 2 + \sigma 4 + \sigma 6
```

The *N* is compiled using environment $\sigma_0 + \sigma_2$. *D* is compiled using $\sigma_0 + \sigma_2 + \sigma_4$ the result of the analysis is $\{M \mapsto \sigma_7\}$.

ML

 Using hash tables to implement the Imperative environments efficiently.

$$M1 = \{ bat \mapsto 1, camel \mapsto 2, dog \mapsto 3 \}$$



```
struct bucket { string key; void *binding; struct bucket
 *next; };
#define SIZE 109
struct bucket *table[SIZE];
unsigned int hash(char *s0)
{ unsigned int h=0; char *s;
  for (s=s0; *s; s++)
      h=h*65599 + * \overline{h} = (\alpha^{n-1}c_1 + \alpha^{n-2}c_2 + ..... + \alpha c_{n-1} + c_n)
       return h;
struct bucket *Bucket (string key, void *binding, struct
 bucket *next) {
  struct bucket *b=check malloc(sizeof(*b));
   b > leave — leave b > binding — bindings b > nave
```

```
void insert(string key, void *binding) {
  int index=hash(key)%SIZE;
  table[index]=Bucket( key, binding,
 table[index]); }
void *lookup(string key) {
   int index=hash(key)%SIZE
   struct bucket *b;
  for (b = table[index]; b; b=b->next)
      if (0==strcmp(b->key,key)) return b-
 >binding;
  return NULL; }
void pop( string key) {
   int index=hash(key)%SIZE
   table[index]=table[index].next; }
```

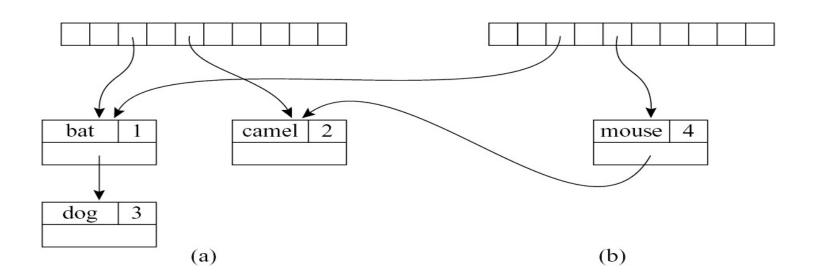
Consider $\sigma + \{a \mapsto \tau_2\}$ when σ contains $a \mapsto \tau_1$ already.

- The insert function leaves $a \mapsto \tau_1$ in the bucket and puts $a \mapsto \tau_2$ earlier in the list.
- When pop(a) is done at the end of a's scope, σ is restored.

(insertion and pop work in a stack-like fashion.)

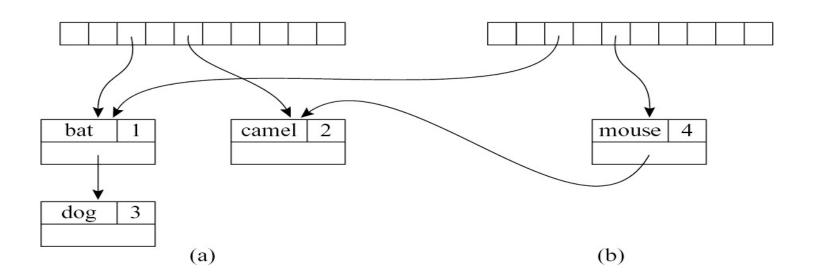
EFFICIENT FUNCTIONAL

M1 = { bat \mapsto 1,camel \mapsto 2,dog \mapsto 3 } add the binding mouse \mapsto 4



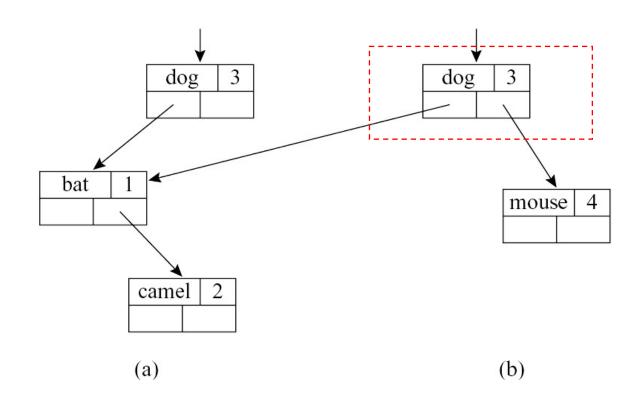
EFFICIENT FUNCTIONAL

- Compute $\sigma' = \sigma + \{a \mapsto \tau\}$ in such a way that still have σ available to look up identifiers.
- Create a new table by computing the "sum" of an existing table and a new binding.



EFFICIENT FUNCTIONAL

 Add a new node at depth d of the tree, we must create d new nodes — don't need to copy the whole tree.



 Convert each string to a symbol to avoid unnecessary string comparisons

$$h = (\alpha^{n-1}c_1 + \alpha^{n-2}c_2 + \dots + \alpha c_{n-1} + c_n)$$

- The Symbol module has these important properties: Comparing symbols for equality is fast (just pointer or integer comparison).
 - ✓ Comparing two symbols for "greater-than" (in some arbitrary ordering) is fast (in case we want to make binary search trees).
 - ✓ Extracting an integer hash key is fast (in case we want to make a hash table mapping symbols to something else).

The interface of symbols and symbol tables

```
typedef struct S_symbol_ *S_symbol;
S_symbol S_symbol (string);
string S_name(S_symbol);
typedef struct TAB_table_ *S_table;
S_table S_empty( void);
void S_enter( S_table t, S_symbol sym, void *value);
void *S_look( S_table t, S_symbol sym);
void S beginScope( S table t);
void S_endScope( S_table t);
```

```
static S symbol mksymbol (string name, S symbol
next)
  S_symbol s = checked malloc(sizeof(*s));
  s->name = name; s->next = next;
  return s;
S symbol S symbol (string name) {
 int index = hash(name)%SIZE;
 S symbol syms = hashtable[index], sym;
 for ( sym = syms; sym; sym = sym->next)
    if (0 == strcmp(sym->name, name)) return sym;
 sym = mksymbol(name,syms);
 hashtable[index] = sym;
 return sym;
```

```
string S name (S symbol sym) {
                            return sym->name;
S_table S_empty(void) {return TAB empty();}
void S enter(S table t, S symbol sym, void *value)
 {TAB enter(t, sym, value);}
void *S look(S table t, S symbol sym) {return
 TAB look(t, sym);}
```

Use destructive-update environment:

- S_beginScope: remembers the current state of the table
- S_endScope: restores the table to where it was at the most recent beginScope that has not already been ended.

```
static struct S_symbol_ marksym =
    { "<mark>", 0 };

void S_beginScope ( S_table t)
    { S_enter(t, &marksym, NULL); }

void S_endScope( S_table t)    {
        S_symbol s;
        do s= TAB_pop(t); while (s !=
        &marksym);
```

Auxiliary stack

- Showing in what order the symbols were "pushed" into the symbol table.
- As each symbol is popped, the head binding in its bucket is removed.

A global variable TOP

- showing the most recent Symbol bound in the table.
- "pushing": copy TOP into the prevtop field of the Binder.
- "stack" is threaded through the binders.

The end of Chapter 5(1)