

This is weijia's P1_homework for EECS 476

1. run the simple 2-Dimensional robot simulator
2. test the simulator
3. create my own package `cs_create_pkg my_stdr_control roscpp std_msgs`
4. build up `file.cpp` in my package/src
5. write up `REDEME.md` and `CMakelists.txt` ensure code can run
6. write code to make robot can move to upper left of the maze
7. record
8. zip and submit