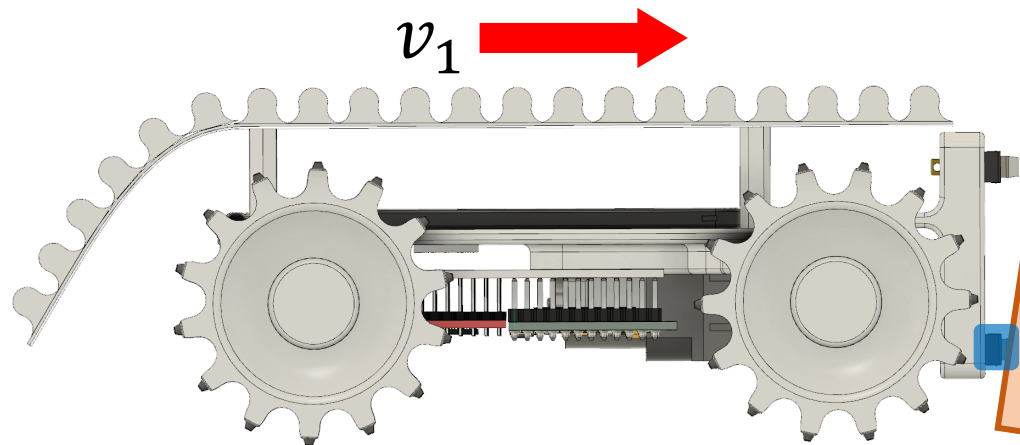


Top switch : released
Bottom switch: pressed

Robot 1 accelerates forward



Top switch : pressed
Bottom switch: released

Robot 2 accelerates forward

