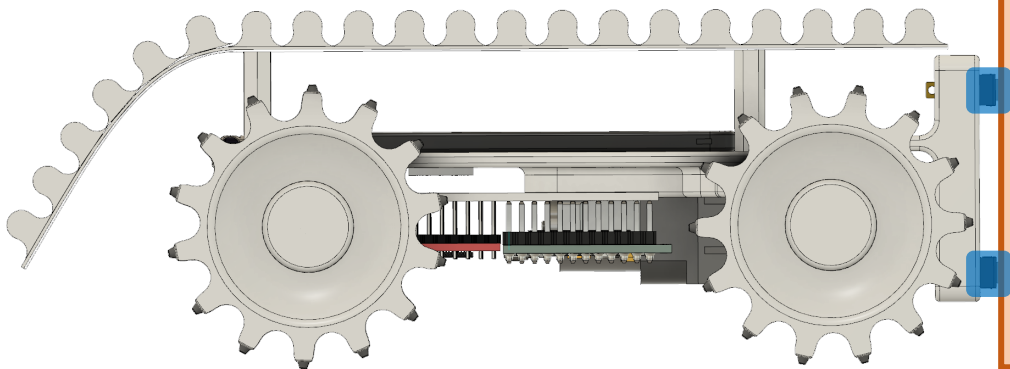


Top switch : pressed
Bottom switch: pressed

Robot 1 stops



Top switch : pressed
Bottom switch: pressed

Robot 2 stops

