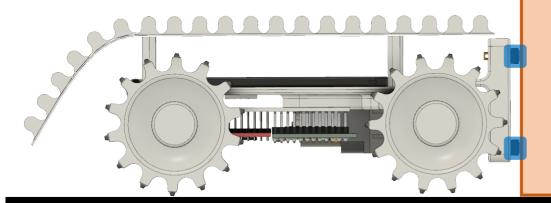
## Both switches are pressed Robot 1 stops

$$v_1 = 0$$



## Both switches are pressed Robot 2 stops

$$v_2 = 0$$

