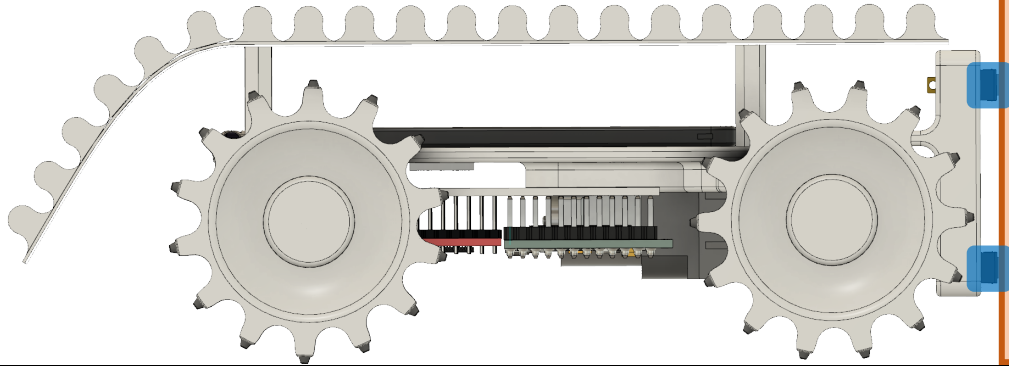


Both switches are pressed

Robot 1 stops

$$v_1 = 0$$



Both switches are pressed

Robot 2 stops

$$v_2 = 0$$

