

# Localization and Uncertainty

Mathematical Foundations of Signal Processing

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# Outline

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- Time and frequency
  - Continuous-time (CT)
  - Discrete Time (DT)
- Uncertainty relations
- Scale and resolution

## Goal:

- To understand the intuition behind time-frequency analysis

## Why:

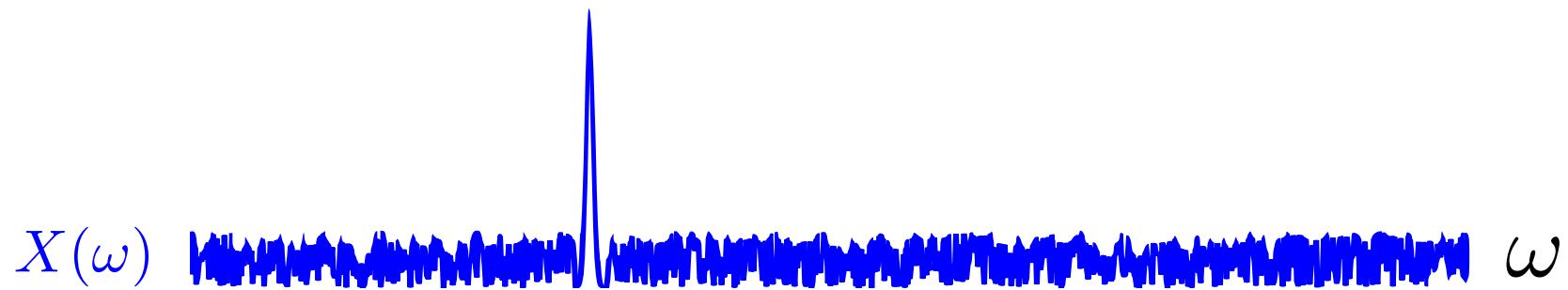
- To understand what we can expect from individual vectors in a basis

## Readings:

- Chapter 7

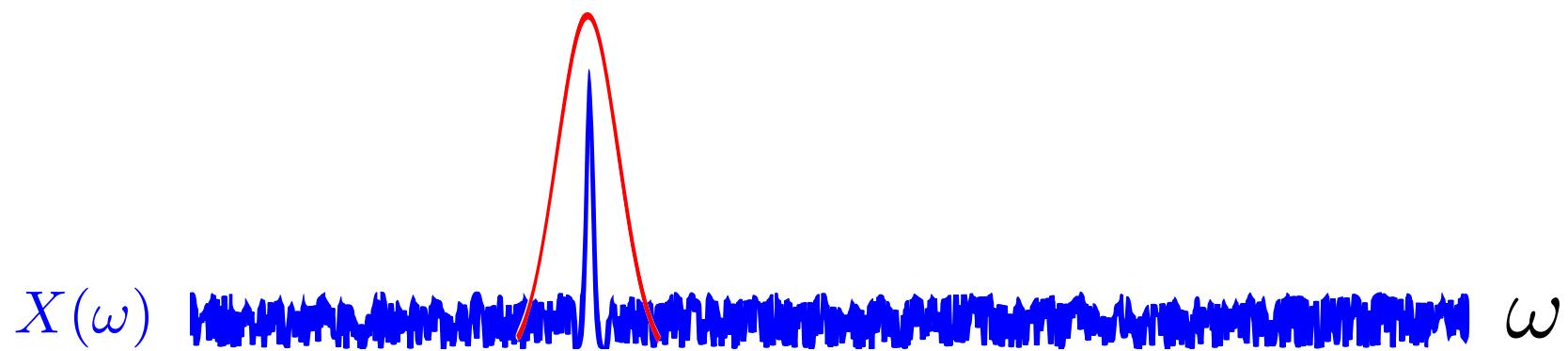
# Motivation

- filtering



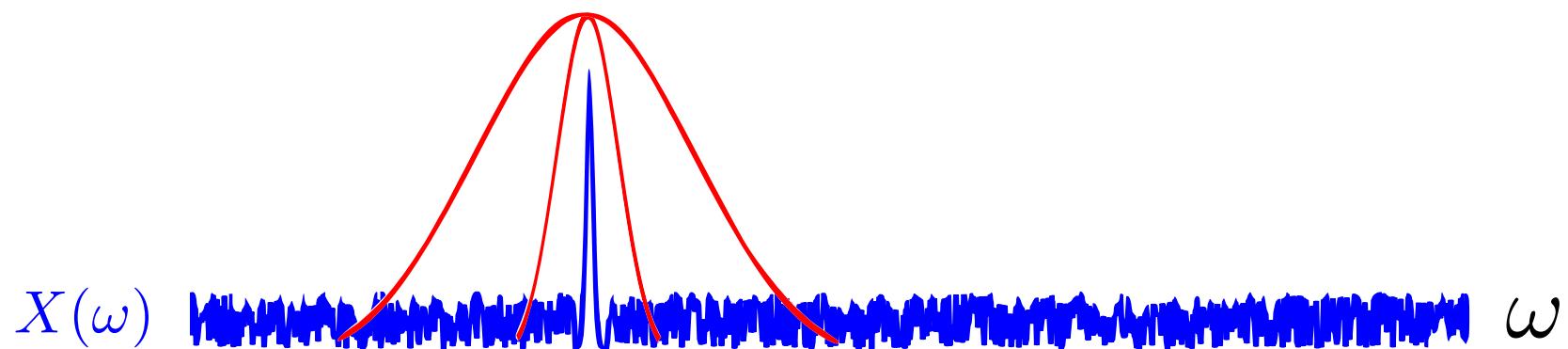
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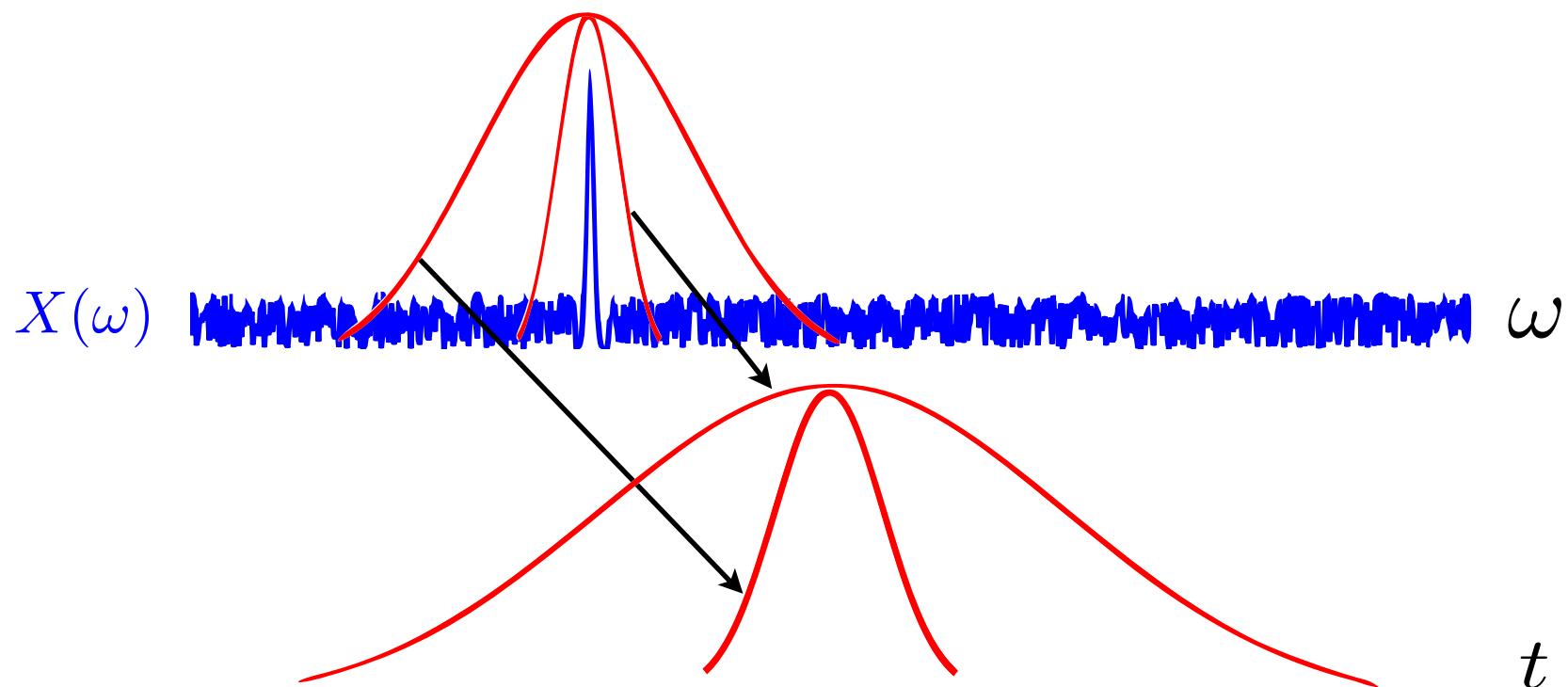
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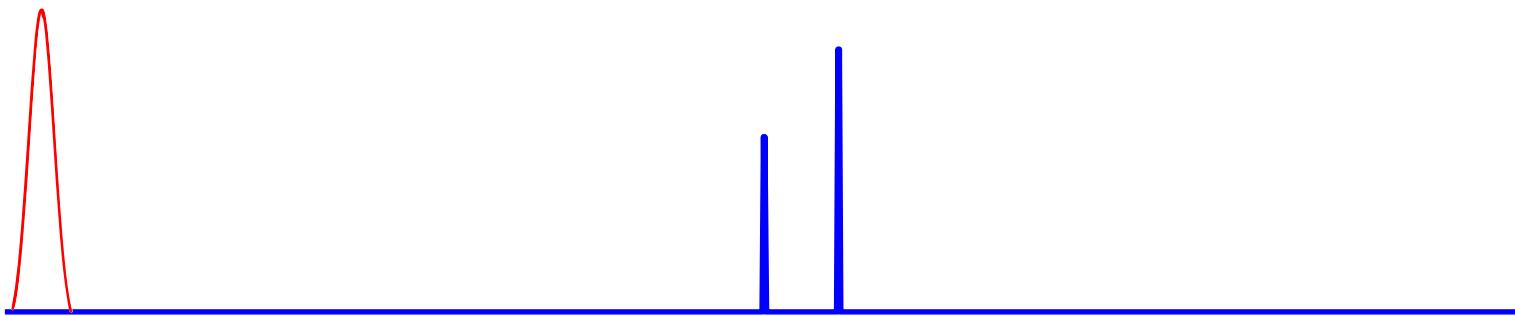
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# Motivation

- Representation:

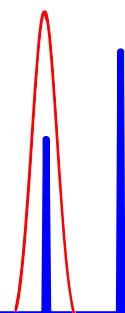
$$x(t) = \sum_{n \in \mathbb{Z}} \alpha_n \varphi(t - nt_0)$$



# Motivation

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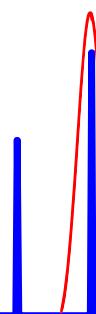
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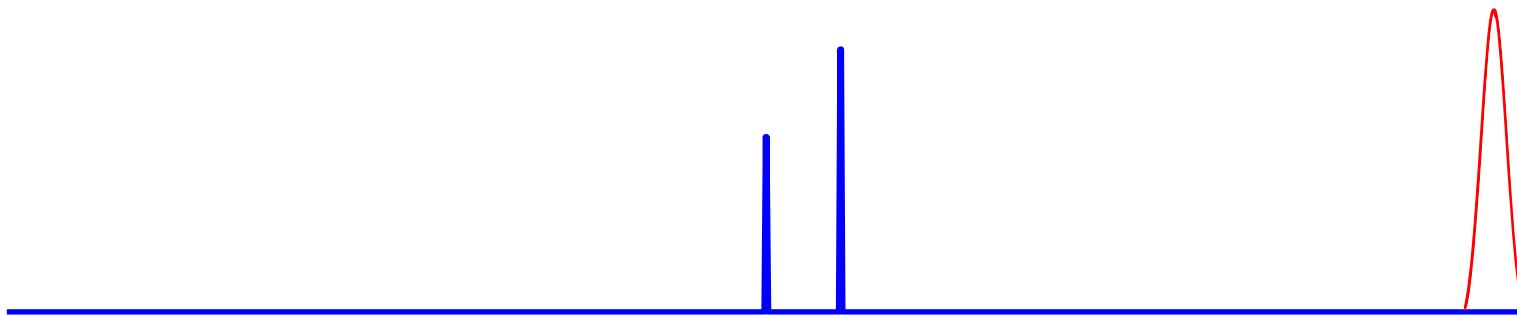
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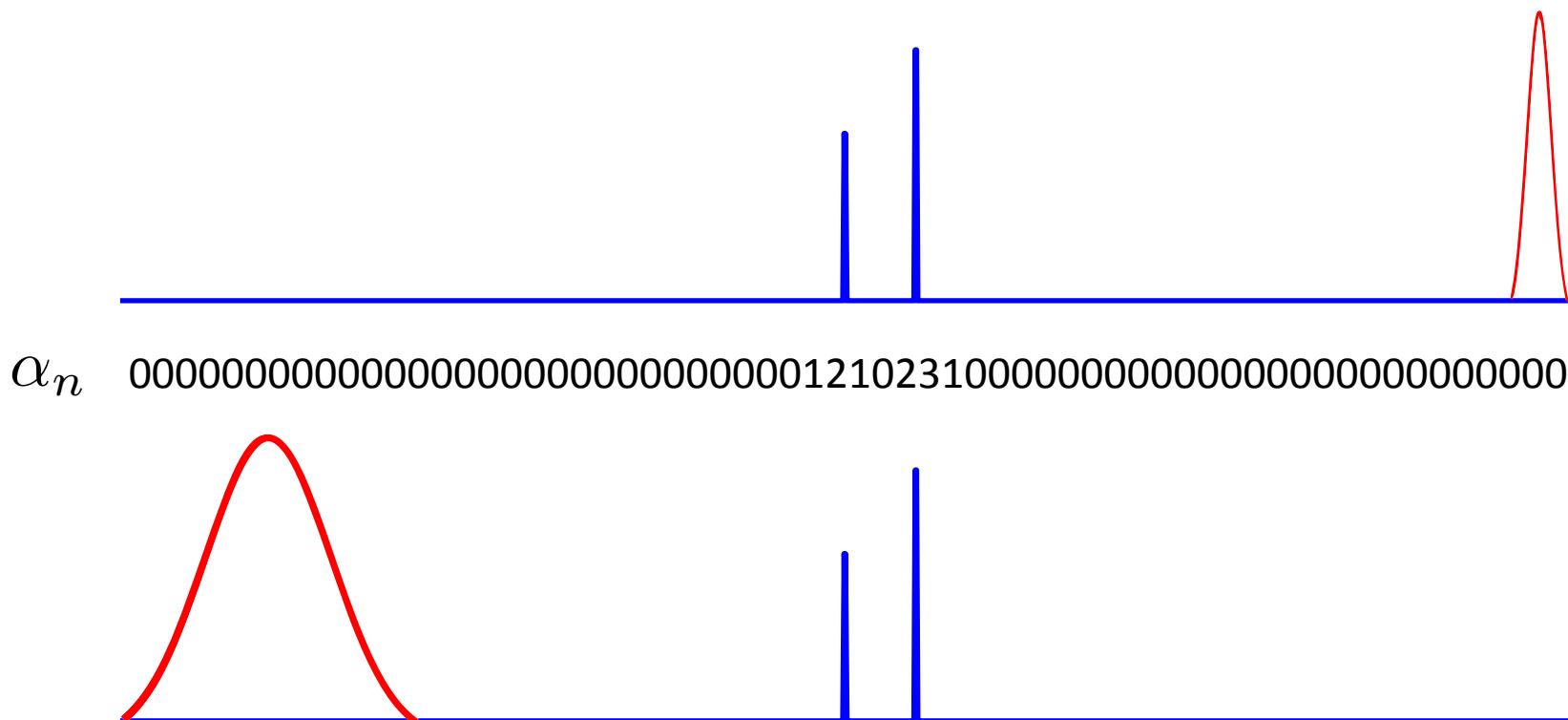
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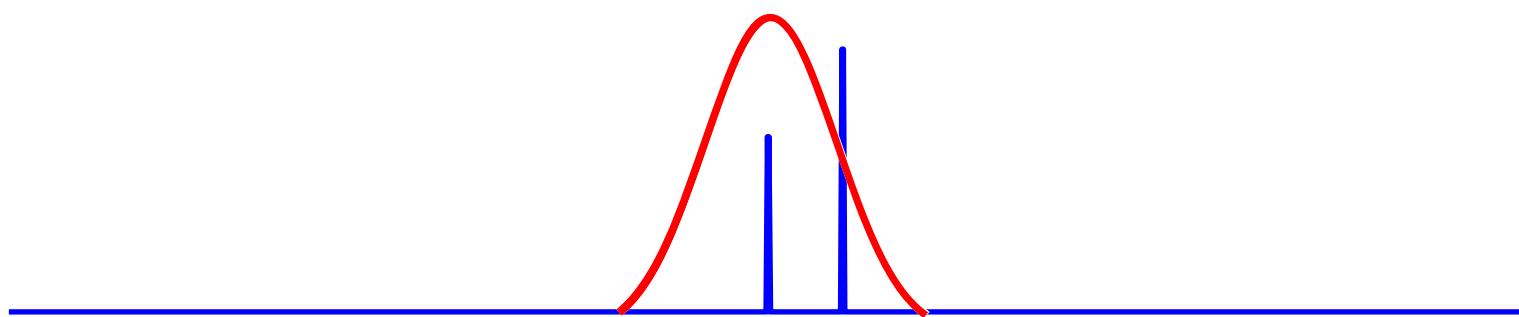
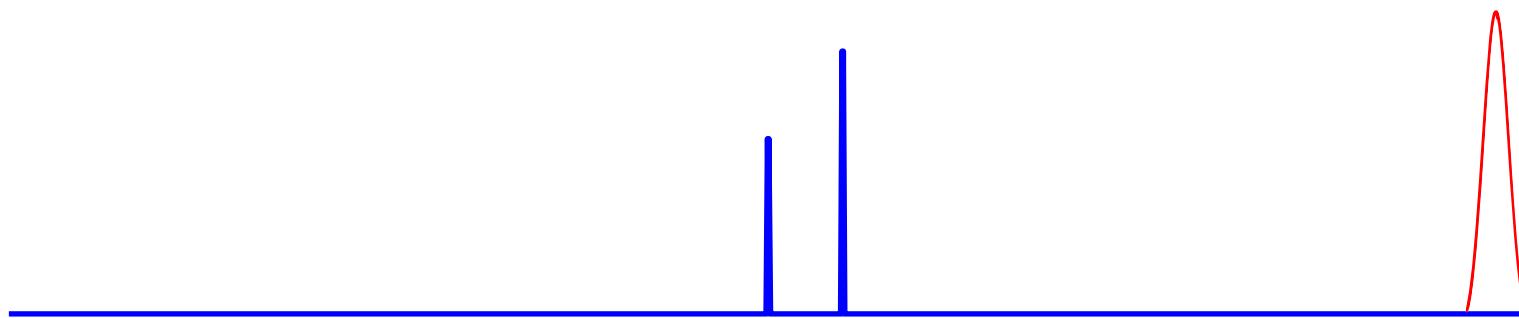
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# Motivation

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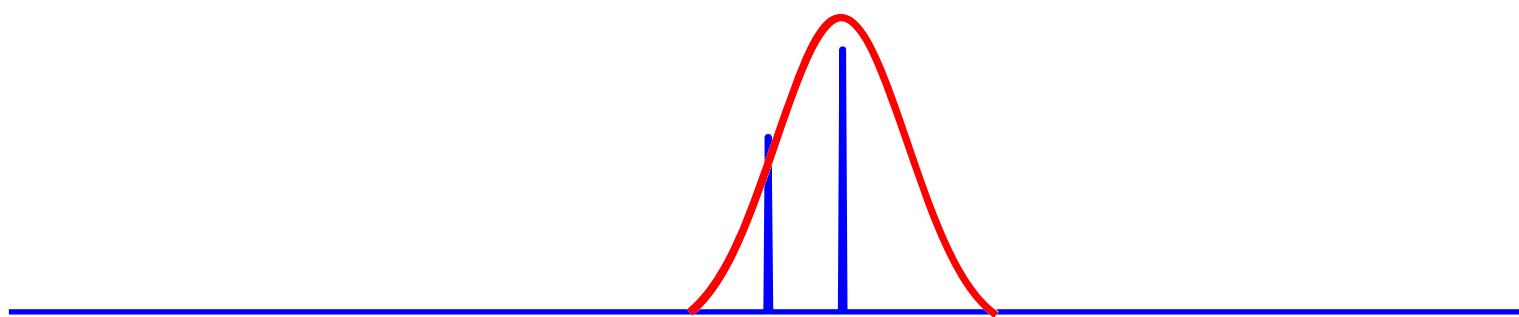
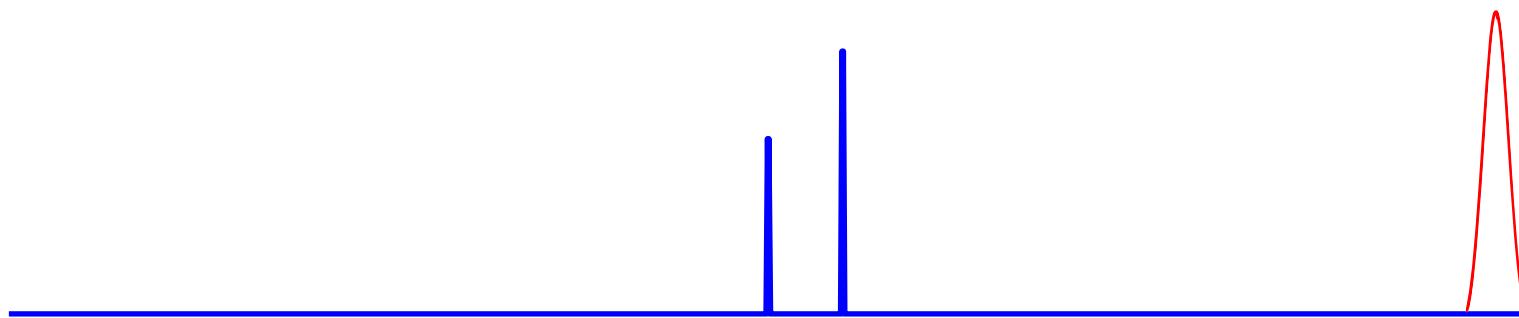
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# Motivation

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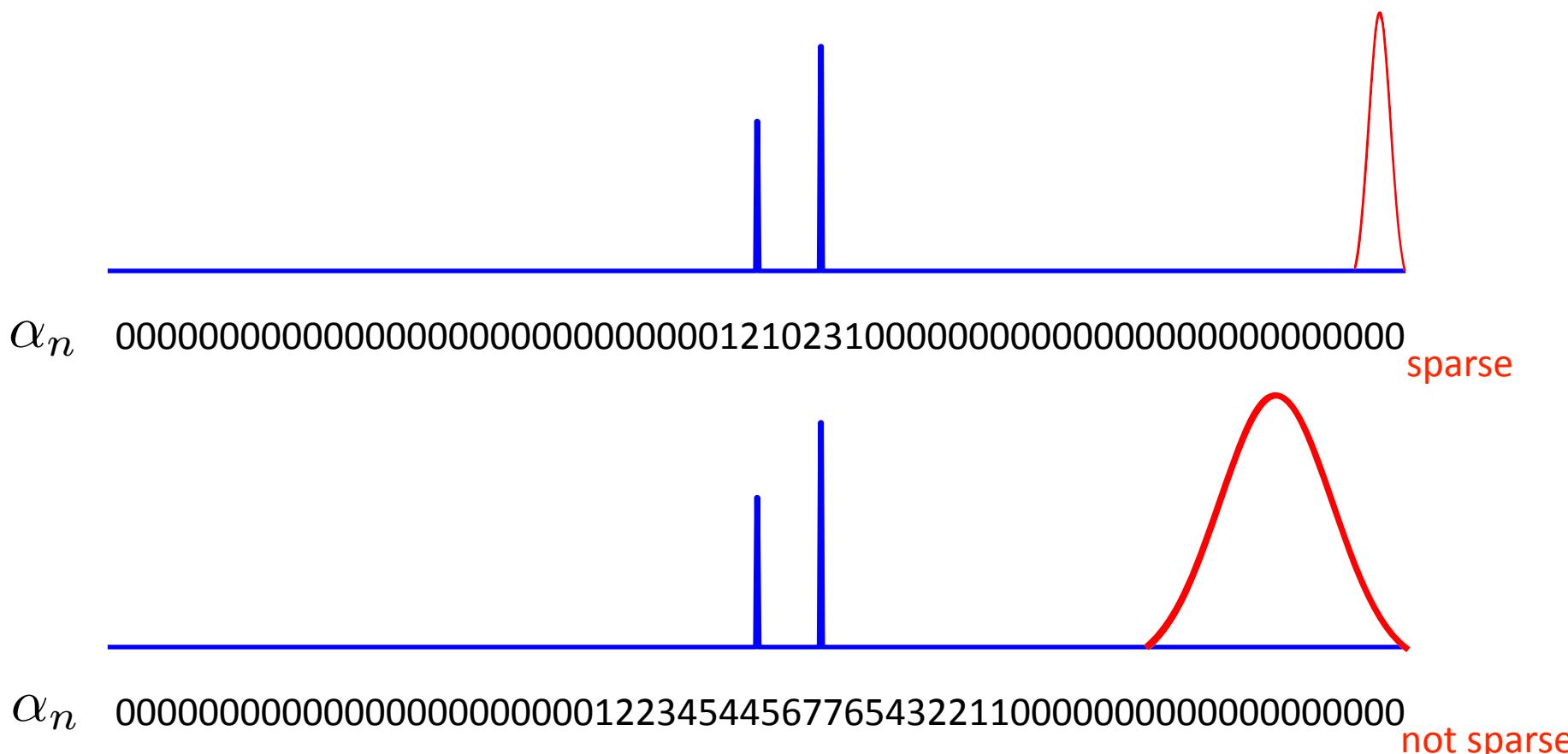
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# Motivation

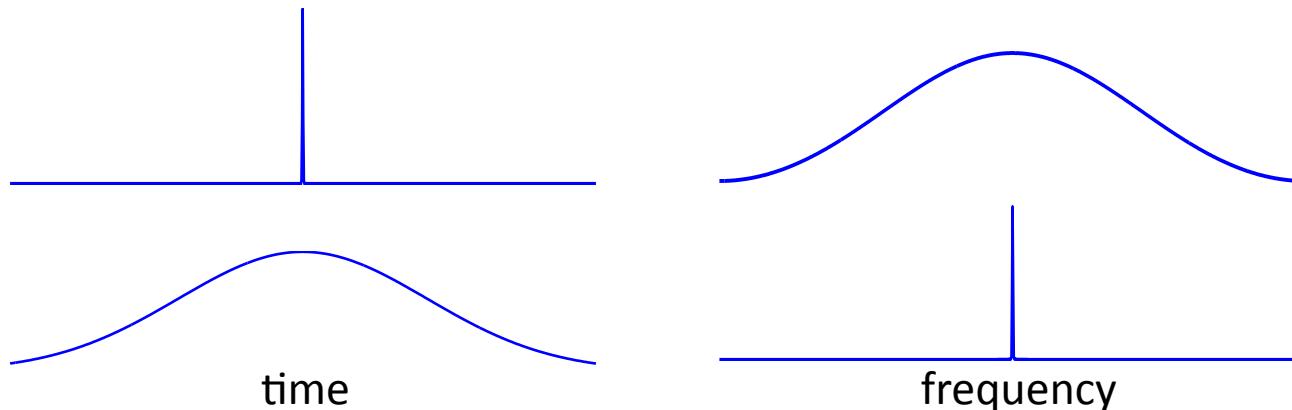
- **Representation:**

$$x(t) = \sum_{n \in \mathbb{Z}} \alpha_n \varphi(t - nt_0)$$



# What?

- Most of the times we want something “localized” (= “compact”= “sharp”) in time and frequency
  - in frequency -> more selective
  - in time -> better resolution and sparsity of coefficients
- Is it possible to be compact both in time and in frequency?!
  - Theme: localization both in **time** and **frequency** is **limited!**



$$\begin{aligned} \delta(t) &\quad \xleftrightarrow{\text{FT}} \quad 1, \\ 1 &\quad \xleftrightarrow{\text{FT}} \quad 2\pi\delta(\omega). \end{aligned}$$

# We want to tell you about...

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- The **spread** of a signal in time and frequency
- The trade off: **uncertainty principle**
  - Concentrated in one domain  $\longrightarrow$  spread in the other domain
$$x(t) \longrightarrow X(\omega)$$
$$X(t) \longrightarrow 2\pi x(-\omega)$$
  - The product of the spreads has a lower bound
- **Scaling** trades between the time and frequency spreads
- **Resolution** is related to
  - Bandwidth of the signal
  - Number of degrees of freedom per unit of measure

# How do we define localization?

- Probability density function (PDF)

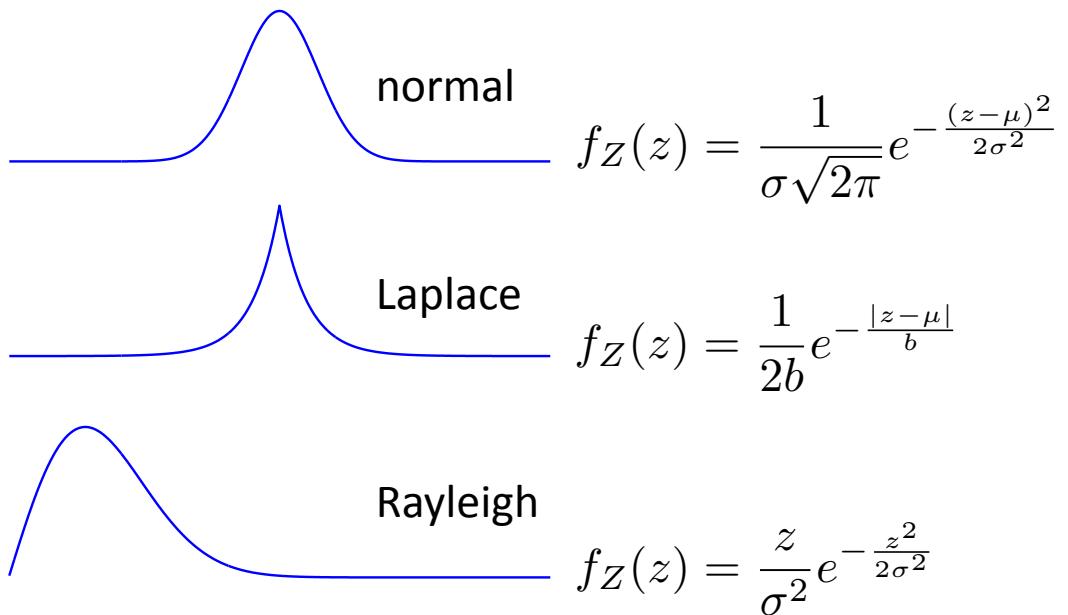
$$Z \sim f_Z(z)$$

$$\Pr(z_1 \leq Z \leq z_2) = \int_{z_1}^{z_2} f_Z(z) dz \quad \int f_Z(z) dz = 1$$

# How do we define localization?

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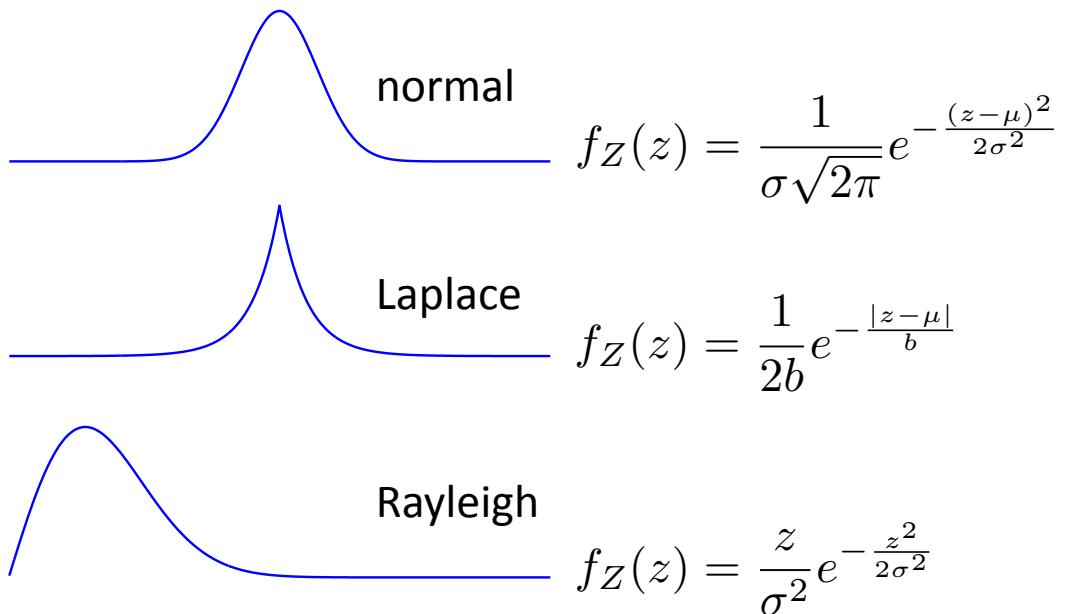
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# How do we define localization?

- Probability density function (PDF)

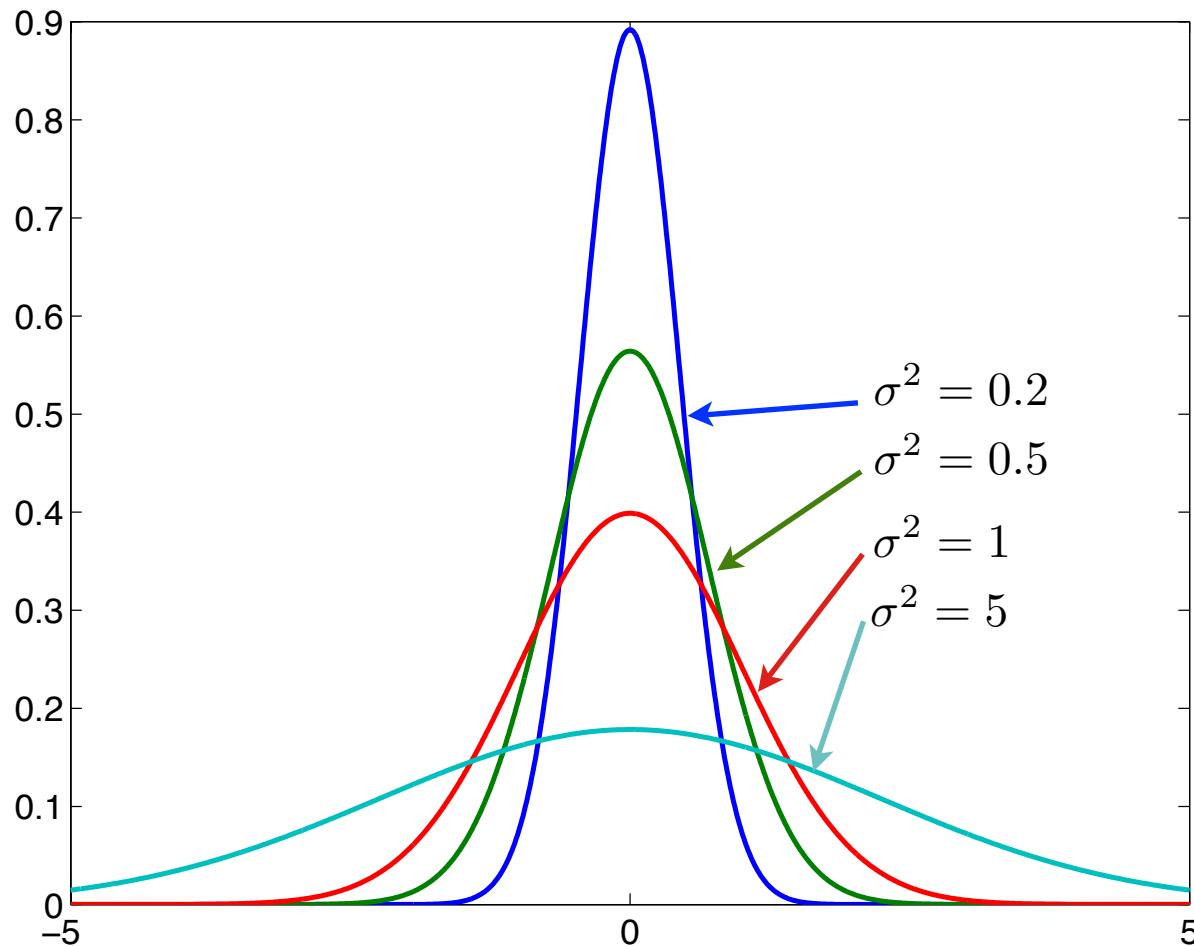
$$Z \sim f_Z(z)$$



**center:**  $\mu_Z = \mathbb{E}[Z] = \int z f_Z(z) dz$

**variance:**  $\sigma_Z^2 = \mathbb{E}[(Z - \mu_Z)^2] = \int (z - \mu_Z)^2 f_Z(z) dz$

# Variance versus Spread



- larger variance = more spread

# Time localization

- Time **center** and **spread**

$$\int_{-\infty}^{\infty} \frac{|x(t)|^2}{\|x\|^2} dt = 1$$

$$\mu_t \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} t \frac{|x(t)|^2}{\|x\|^2} dt$$

$$\Delta_t^2 \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} (t - \mu_t)^2 \frac{|x(t)|^2}{\|x\|^2} dt$$

- This is like the variance of  $t$ , where  $t \sim \frac{|x(t)|^2}{\|x\|^2}$

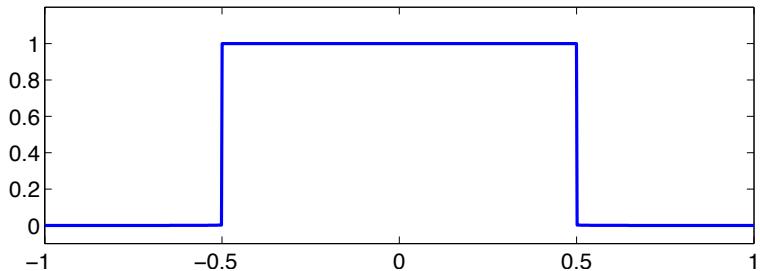
# Some examples

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## i. The box function

$$b(t) = \begin{cases} 1 & -\frac{1}{2} < t \leq \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$$

has  $\mu_t = 0$  and  $\Delta_t^2 = \frac{1}{12}$

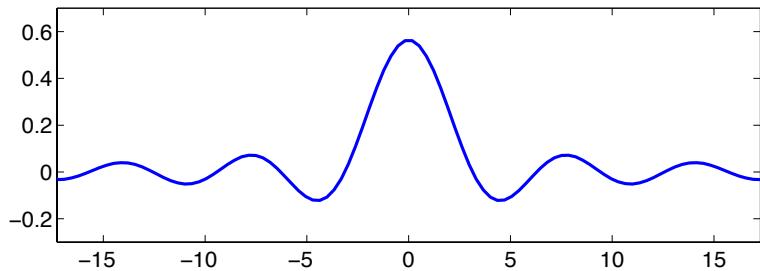


## ii. The sinc function

$$x(t) = \frac{1}{\sqrt{\pi}} \frac{\sin t}{t}$$

$|x(t)|^2$  decays only as  $\frac{1}{|t|^2}$

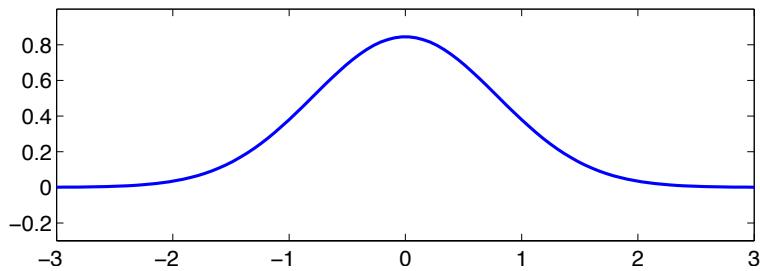
so  $\Delta_t^2$  is infinite



## iii. Gaussian function

$$g(t) = \left( \frac{2\alpha}{\pi} \right)^{\frac{1}{4}} e^{-\alpha t^2}$$

has  $\mu_t = 0$  and  $\Delta_t^2 = \frac{1}{4\alpha}$



# Frequency Localization

- Frequency center and spread

$$\|X(\omega)\|^2 = 2\pi\|x(t)\|^2$$

$$\int_{-\infty}^{\infty} \frac{|X(\omega)|^2}{2\pi\|x\|^2} dt = 1$$

$$\mu_f \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} \omega \frac{|X(\omega)|^2}{2\pi\|x\|^2} dt$$

$$\Delta_f^2 \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} (\omega - \mu_f)^2 \frac{|X(\omega)|^2}{2\pi\|x\|^2} dt$$

- This is like the variance of  $\omega$  where  $\omega \sim \frac{|X(\omega)|^2}{2\pi\|x\|^2}$

# The Heisenberg Uncertainty Principle

Given a function  $x \in \mathcal{L}^2(\mathbb{R})$ , the product of its squared time and frequency spreads is lower bounded as

$$\Delta_t^2 \Delta_f^2 \geq \frac{1}{4}$$

- The lower bound is attained by **Gaussian** functions:

$$x(t) = \gamma e^{-\alpha t^2}, \quad \alpha > 0$$

- Proof: on the board!

# Proof for Absents

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- STEP 1

$$\begin{aligned} \left| \int_{-\infty}^{\infty} t x(t) x'(t) dt \right|^2 &\stackrel{(a)}{\leq} \int_{-\infty}^{\infty} |t x(t)|^2 dt \int_{-\infty}^{\infty} |x'(t)|^2 dt \\ &\stackrel{(b)}{=} \underbrace{\int_{-\infty}^{\infty} |t x(t)|^2 dt}_{=\Delta_t^2} \underbrace{\frac{1}{2\pi} \int_{-\infty}^{\infty} |j\omega X(\omega)|^2 d\omega}_{=\Delta_f^2} = \Delta_t^2 \Delta_f^2, \end{aligned}$$

(a) Cauchy Schwarz, (b) Parseval

- STEP 2

$$\begin{aligned} \int_{-\infty}^{\infty} t x(t) x'(t) dt &\stackrel{(a)}{=} \frac{1}{2} \int_{-\infty}^{\infty} t \frac{dx^2(t)}{dt} dt \stackrel{(b)}{=} \frac{1}{2} [tx^2(t)]_{-\infty}^{\infty} - \frac{1}{2} \int_{-\infty}^{\infty} x^2(t) dt \\ &\stackrel{(c)}{=} -\frac{1}{2} \int_{-\infty}^{\infty} x^2(t) dt \stackrel{(d)}{=} -\frac{1}{2}, \end{aligned}$$

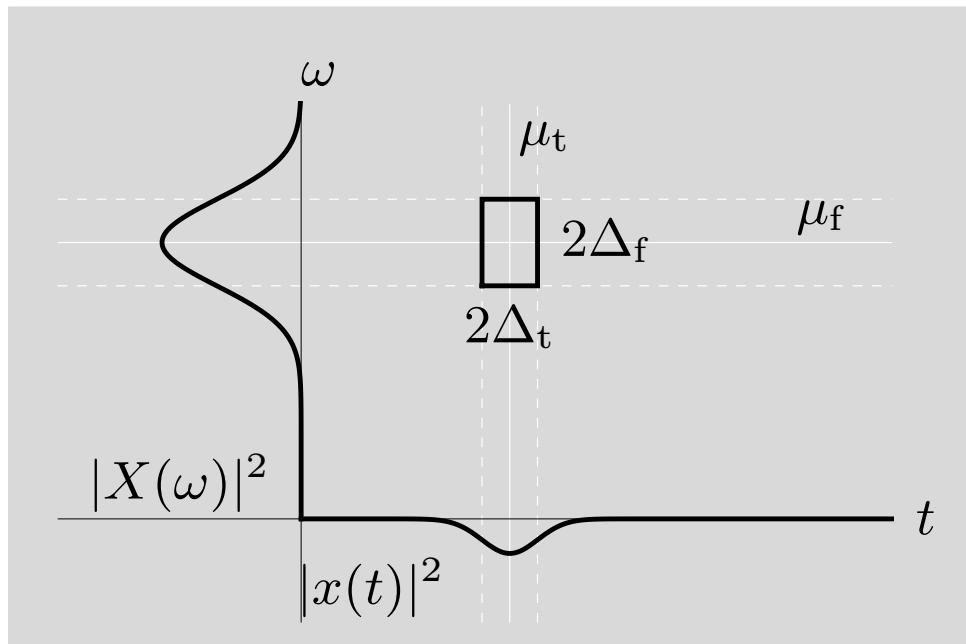
(a)  $(x^2(t))' = 2x'(t)x(t)$

(b) integration by parts

(c)  $\lim_{t \rightarrow \infty} tx^2(t) = 0$

# Heisenberg Boxes

- Time-frequency plane and H-boxes
  - Time/frequency centered at  $(\mu_t, \mu_f)$
  - Extent of rectangular box  $(2\Delta_t, 2\Delta_f)$



**Heisenberg:** The box area is at least 2!

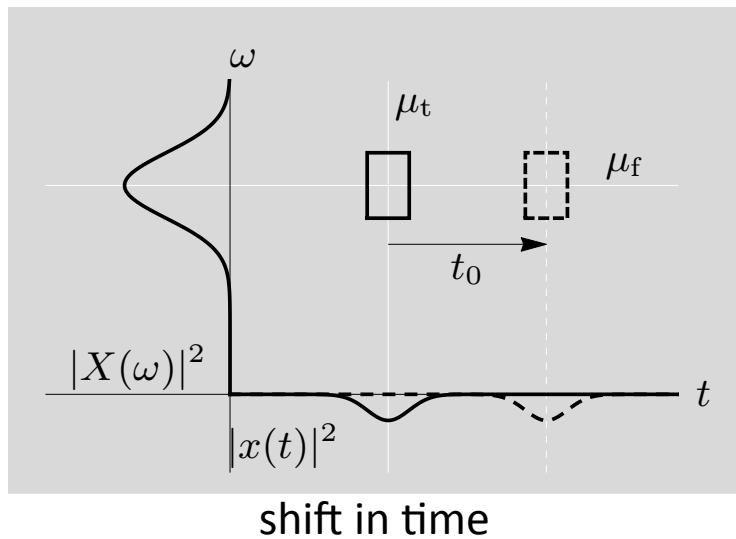
# Time Shift, Frequency Shift

- Shift in time

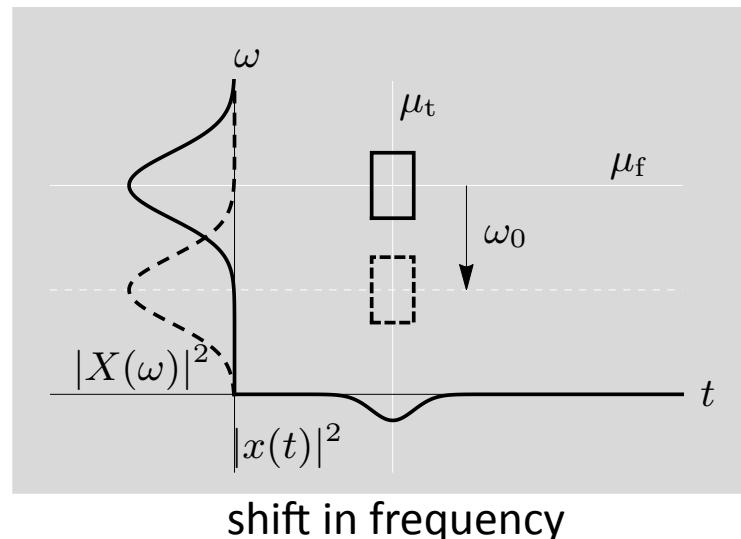
$$y(t) = x(t - t_0) \quad \xleftrightarrow{\text{FT}} \quad Y(\omega) = e^{-j\omega t_0} X(\omega).$$

- Shift in frequency

$$y(t) = e^{j\omega_0 t} x(t) \quad \xleftrightarrow{\text{FT}} \quad Y(\omega) = X(\omega - \omega_0).$$



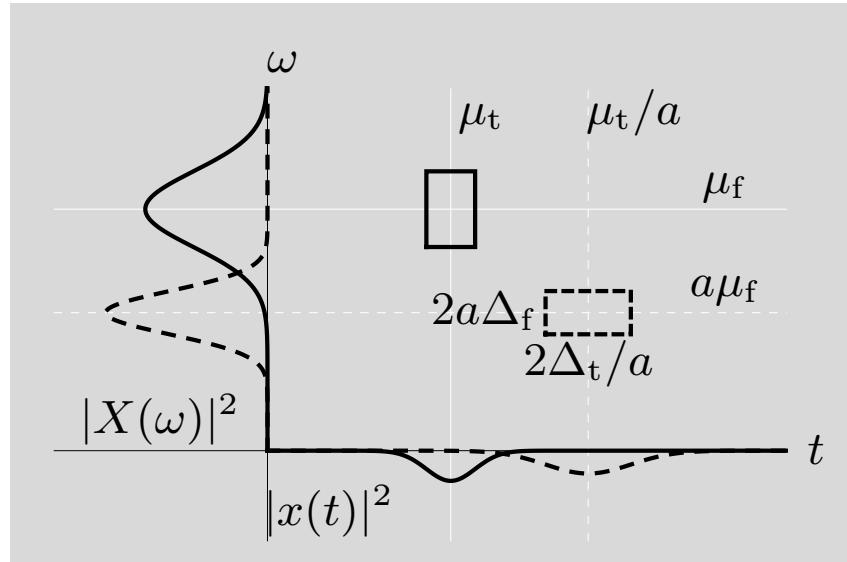
- Any volunteers?



# Energy Conserving Scaling

- scaling

$$\begin{aligned} y(t) &= \sqrt{a} x(at) & \xleftrightarrow{\text{FT}} & Y(\omega) = \frac{1}{\sqrt{a}} X\left(\frac{\omega}{a}\right). \\ \|y\|^2 &= \|x\|^2 \end{aligned}$$



- shifting or scaling does not change the area of the box!
  - narrowing a signal in one domain must widen it in the other!

# Shift and Scaling: Summary

Function	Time center	Time spread	Fourier transform	Frequency center	Frequency spread
$x(t)$	$\mu_t$	$\Delta_t$	$X(\omega)$	$\mu_f$	$\Delta_f$
$x(t - t_0)$	$\mu_t + t_0$	$\Delta_t$	$e^{-j\omega t_0} X(\omega)$	$\mu_f$	$\Delta_f$
$e^{j\omega_0 t} x(t)$	$\mu_t$	$\Delta_t$	$X(\omega - \omega_0)$	$\mu_f + \omega_0$	$\Delta_f$
$\sqrt{a}x(at)$	$\mu_t/a$	$\Delta_t/a$	$X(\omega/a)/\sqrt{a}$	$a\mu_f$	$a\Delta_f$

# Discrete-time sequences

- Similar definitions to continuous-time
- Sequences with  $2\pi$ -periodic DTFT

$$\sum_{n \in \mathbb{Z}} \frac{|x_n|^2}{\|x\|^2} = 1$$

$$\int_{-\pi}^{\pi} \frac{|X(e^{j\omega})|^2}{2\pi\|x\|^2} dt = 1$$

- centers and spreads

$$\mu_n \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} n \frac{|x_n|^2}{\|x\|^2}$$

$$\Delta_n^2 \stackrel{\text{def}}{=} \sum_{n \in \mathbb{Z}} (n - \mu_n)^2 \frac{|x_n|^2}{\|x\|^2}$$

$$\mu_f \stackrel{\text{def}}{=} \int_{-\pi}^{\pi} \omega \frac{|X(e^{j\omega})|^2}{2\pi\|x\|^2} dt$$

$$\Delta_f^2 \stackrel{\text{def}}{=} \int_{-\pi}^{\pi} (\omega - \mu_f)^2 \frac{|X(e^{j\omega})|^2}{2\pi\|x\|^2} dt$$

# Heisenberg Uncertainty Principle

Given a sequence  $x \in \ell^2(\mathbb{Z})$ , with  $X(e^{j\pi}) = 0$ , the product of its squared time and frequency spreads is lower bounded as

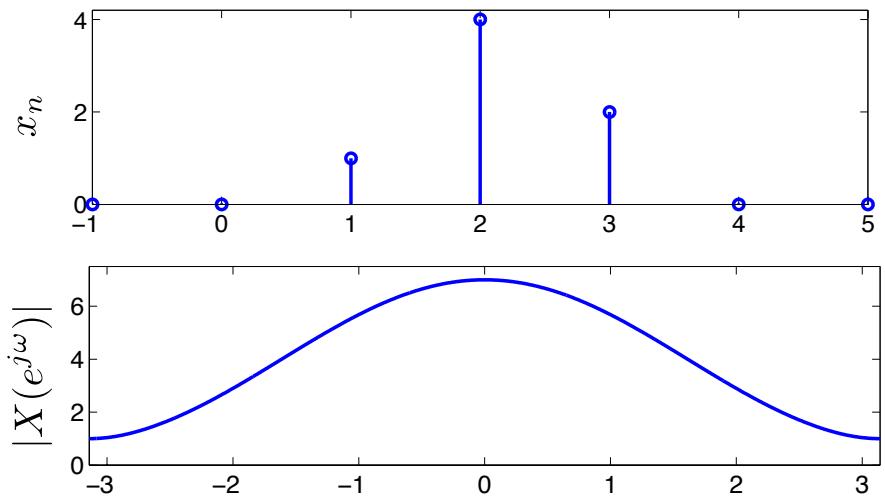
$$\Delta_n^2 \Delta_f^2 > \frac{1}{4}$$

- lower bound cannot be achieved
- Necessary condition

$$x_n = 1 + 4 \delta_{n-1} + 2 \delta_{n-2}$$

$$X(e^{j\pi}) \neq 0$$

$$\Delta_n^2 \Delta_f^2 = 0.239 < \frac{1}{4}$$



# Time Shift, Frequency Shift

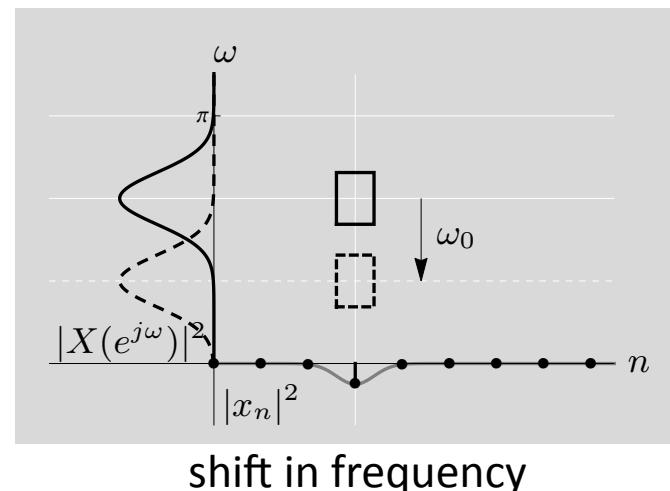
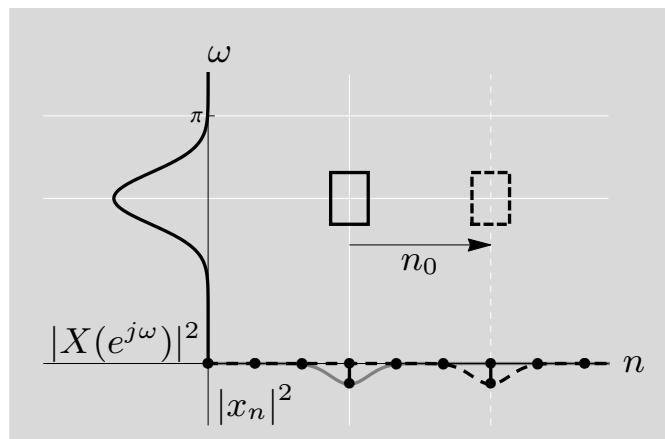
- Shift in time

$$y_n = x_{n-n_0} \quad \xleftrightarrow{\text{DTFT}} \quad Y(e^{j\omega}) = e^{-j\omega n_0} X(e^{j\omega}).$$

- Shift in frequency

$$y_n = e^{j\omega_0 n} x_n \quad \xleftrightarrow{\text{DTFT}} \quad Y(e^{j\omega}) = X(e^{j(\omega-\omega_0)}).$$

$$\begin{cases} X(e^{j\omega}) = 0, & \omega \in (\pi - \omega_0, \pi] \\ X(e^{j\omega}) = 0, & \omega \in (-\pi, -\pi - \omega_0] \end{cases} \quad \begin{array}{l} \text{if } \omega_0 \in (0, \pi] \\ \text{if } \omega_0 \in (-\pi, 0] \end{array}$$



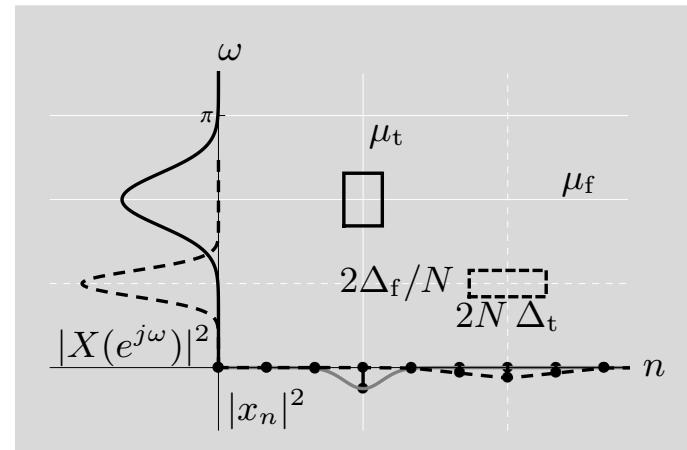
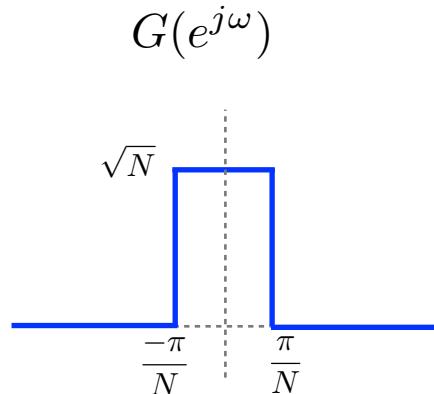
# Upsampling Sequences

- Upsampling by  $N \in \mathbb{Z}^+$  followed by ideal lowpass filtering

$$y_n = g_n *_n \begin{cases} x_{n/N}, & \text{for } n/N \in \mathbb{Z}; \\ 0, & \text{otherwise,} \end{cases} \quad \xleftrightarrow{\text{DTFT}} \quad Y(e^{j\omega}) = \sqrt{N} X(e^{jN\omega}).$$

$$\begin{aligned}\mu_t(y) &= N\mu_t(x), \\ \Delta_t(y) &= N\Delta_t(x).\end{aligned}$$

$$\begin{aligned}\mu_f(y) &= \frac{1}{N}\mu_f(x), \\ \Delta_f(y) &= \frac{1}{N}\Delta_f(x).\end{aligned}$$



Upsampling + filtering

# Downsampling Sequences

- Downsampling by  $N \in \mathbb{Z}^+$  preceded by ideal lowpass filtering

$$y_n = (g * x)_{Nn} \quad \xleftrightarrow{\text{DTFT}} \quad Y(e^{j\omega}) = \frac{1}{\sqrt{N}} X(e^{j\omega/N}), \quad \omega \in [-\pi, \pi],$$

- provided that  $x \in \text{BL}[-\pi/N, \pi/N]$  (filtering does not affect the signal)

$$\begin{aligned} \mu_t(y) &= \frac{1}{N} \mu_t(x), & \mu_f(y) &= N \mu_f(x), \\ \Delta_t(y) &= \frac{1}{N} \Delta_t(x), & \Delta_f(y) &= N \Delta_f(x), \end{aligned}$$

# Shift and Scaling for Sequences: Summary

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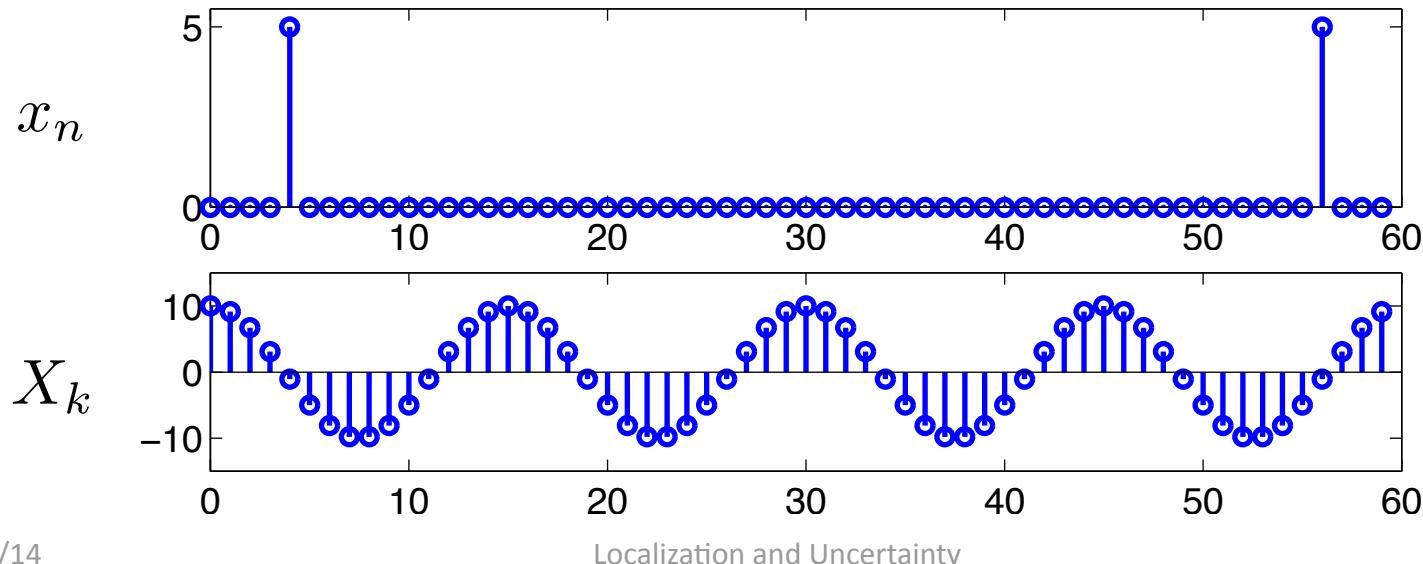
Sequence	Time center	Time spread	DTFT	Frequency center	Frequency spread
$x_n$	$\mu_t$	$\Delta_t$	$X(e^{j\omega})$	$\mu_f$	$\Delta_f$
$x_{n-n_0}$	$\mu_t + n_0$	$\Delta_t$	$e^{-j\omega n_0} X(e^{j\omega})$	$\mu_f$	$\Delta_f$
$e^{j\omega_0 n} x_n$	$\mu_t$	$\Delta_t$	$X(e^{j(\omega - \omega_0)})$	$\mu_f + \omega_0$	$\Delta_f$
upsampled & postfiltered	$N\mu_t$	$N\Delta_t$	$\sqrt{N}X(e^{jN\omega})$	$\mu_f/N$	$\Delta_f/N$
prefiltered & downsampled	$\mu_t/N$	$\Delta_t/N$	$\frac{1}{\sqrt{N}}X(e^{j\omega/N})$	$N\mu_f$	$N\Delta_f$

# Uncertainty Principle for finite-length sequences

Let  $x_n \in \mathbb{C}^N$  with DFT  $X_k$ . Let  $N_n$  and  $N_k$  denote the number of nonzero components of  $x$  and  $X$ , respectively. Then

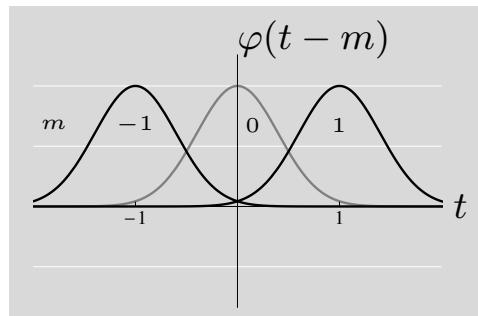
$$N_n N_k \geq N$$

- sequences cannot be sparse in both domains!

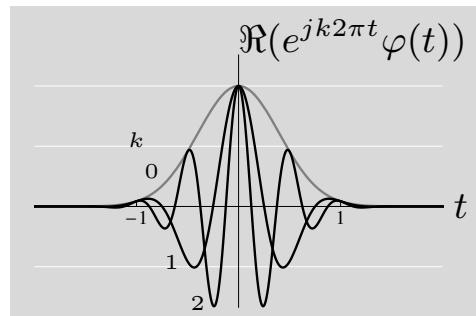


# Localization for set of functions

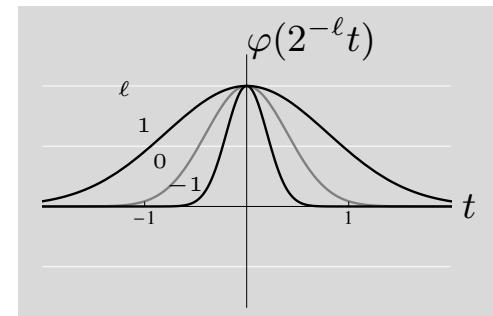
- Prototype function:  $\varphi(t) : (\mu_t, \Delta_t, \mu_f, \Delta_f)$
- Shifts in time:  $\Phi_1 = \{\varphi(t - mt_0)\}_{m \in \mathbb{Z}}$
- Shifts in frequency:  $\Phi_2 = \{e^{jk\omega_0 t} \varphi(t)\}_{k \in \mathbb{Z}}$
- Scale:  $\Phi_3 = \{\varphi(a^{-\ell} t)\}_{\ell \in \mathbb{Z}}$



shifts in time



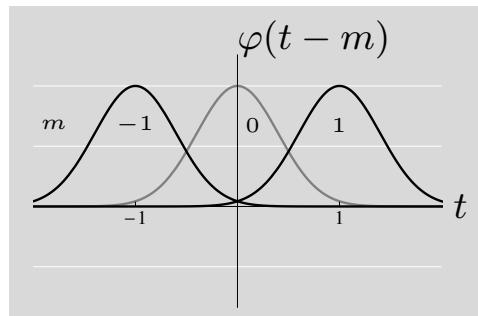
shifts in frequency



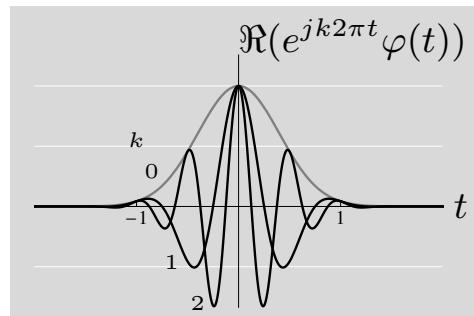
scales in time/freq.

# Localization for set of functions

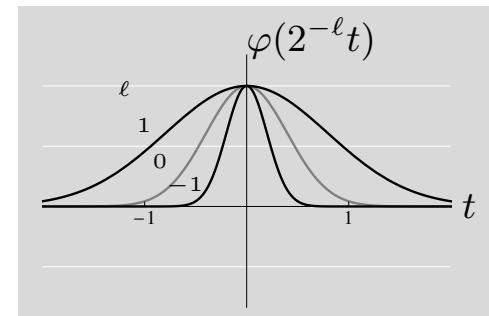
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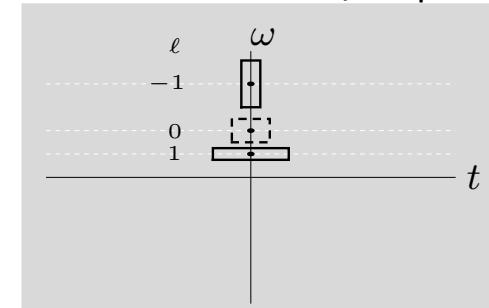
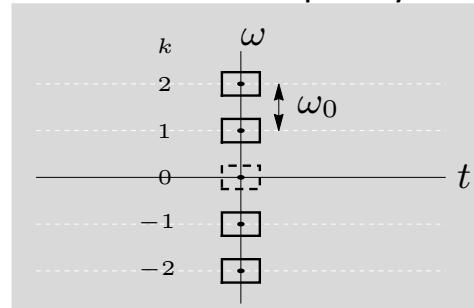
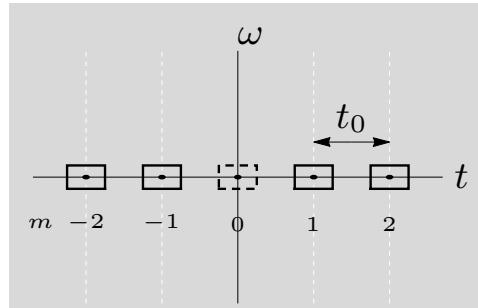
shifts in time



shifts in frequency



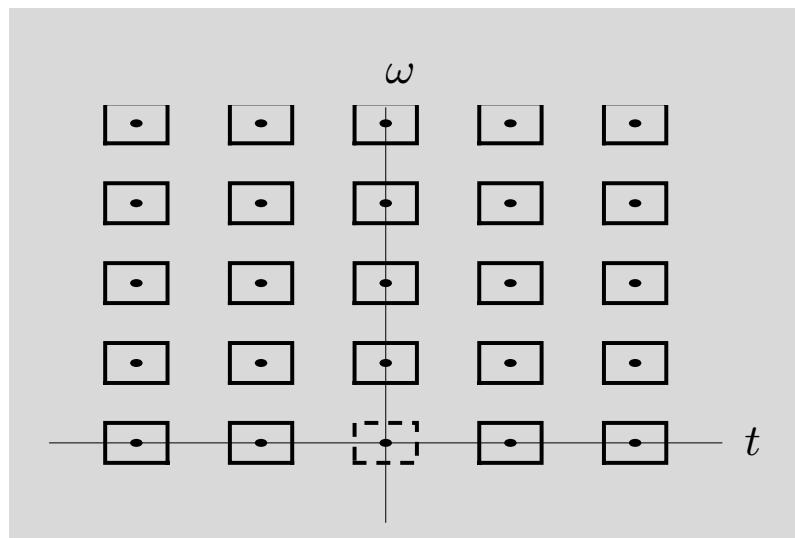
scales in time/freq.



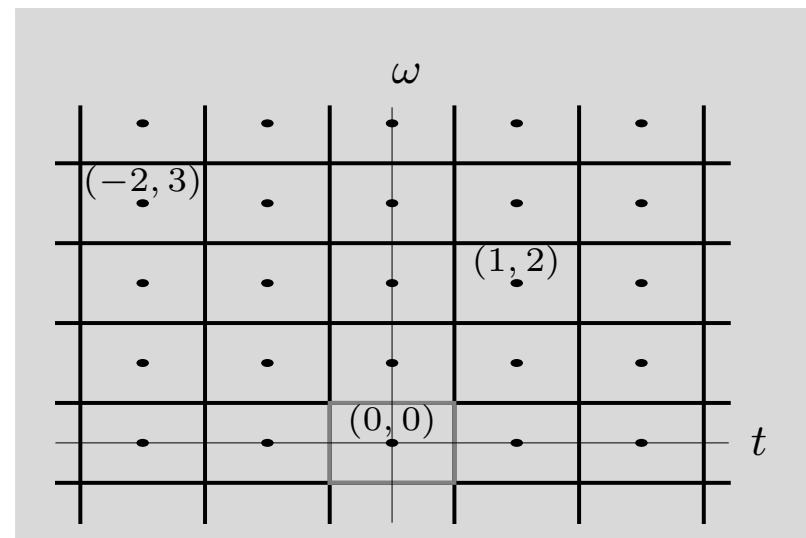
# Time-Frequency Tilings

- Time shift and modulation

$$\varphi_{k,m}(t) = e^{jk\omega_0 t} \varphi(t - mt_0), \quad k, m \in \mathbb{Z}.$$



actual plot



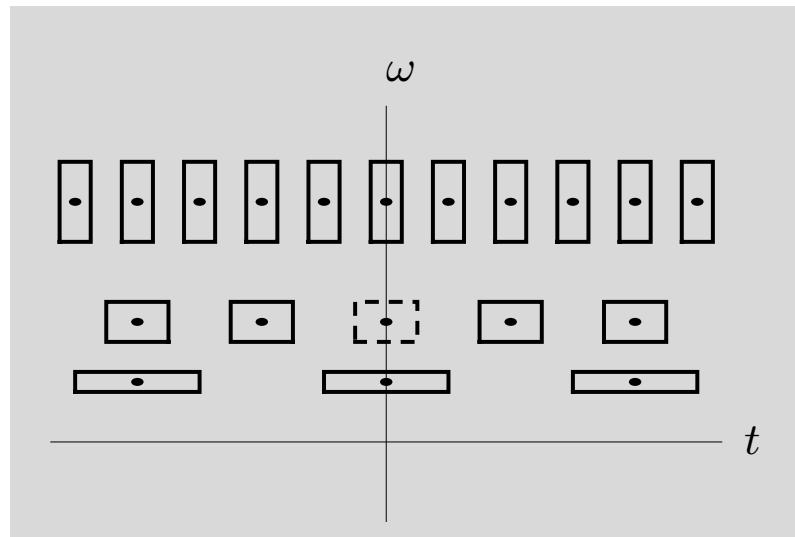
idealized tiling

assumption here:  $\mu_t = 0$   
 $\mu_f = 0$

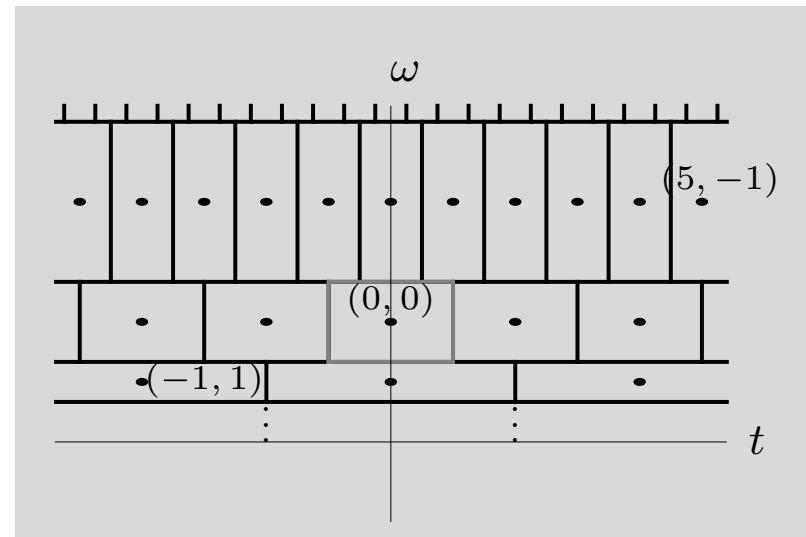
# Time-Frequency Tilings

- Time shift and scaling

$$\varphi_{\ell,m}(t) = \varphi(a^{-\ell}t - mt_0), \quad \ell, m \in \mathbb{Z}.$$



actual plot



idealized tiling

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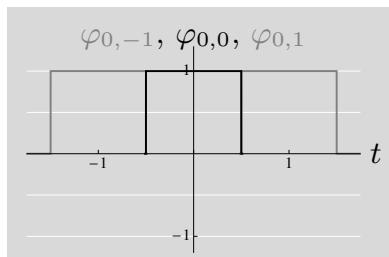
# Idealized vs. Actual Tilings

- Example (local Fourier basis)

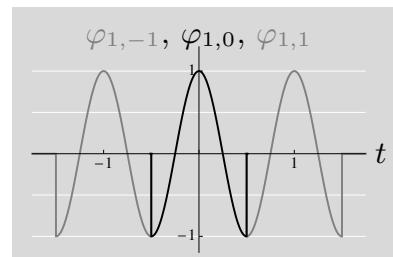
$$\varphi(t) = \begin{cases} 1 & \text{for } |t| \leq 1/2; \\ 0 & \text{otherwise} \end{cases} \quad t_0 = 1, \quad \omega_0 = 2\pi$$

$$\varphi_{k,m}(t) = e^{jk2\pi t} \varphi(t - m)$$

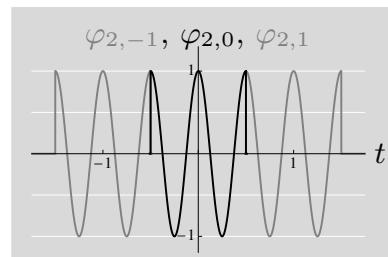
$k = 0$



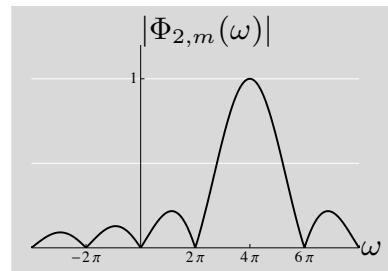
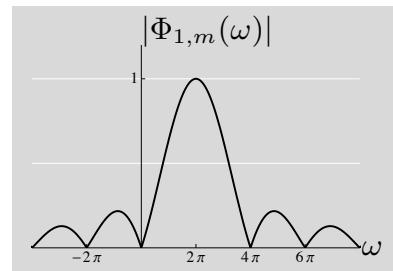
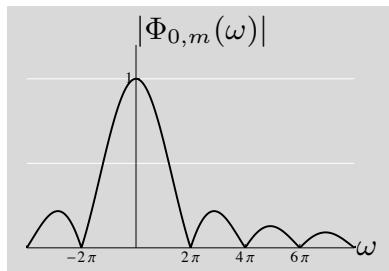
$k = 1$



$k = 2$



Basis functions (real parts only).



Magnitudes of the Fourier transform.

# Idealized vs. Actual Tilings

- Example (local Fourier basis)

$$\varphi(t) = \begin{cases} 1 & \text{for } |t| \leq 1/2; \\ 0 & \text{otherwise} \end{cases} \quad t_0 = 1, \quad \omega_0 = 2\pi$$

$$\varphi_{k,m}(t) = e^{jk2\pi t} \varphi(t - m)$$

- For the box function

$$\Delta_t = \frac{1}{2\sqrt{3}} \quad \Delta_f = \infty$$

# Idealized vs. Actual Tilings

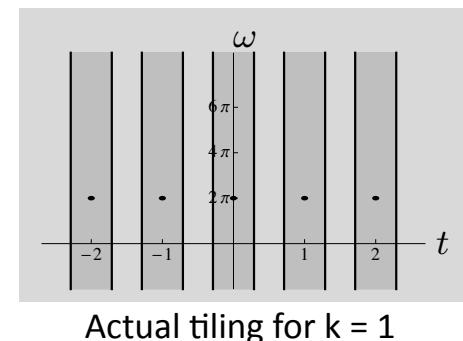
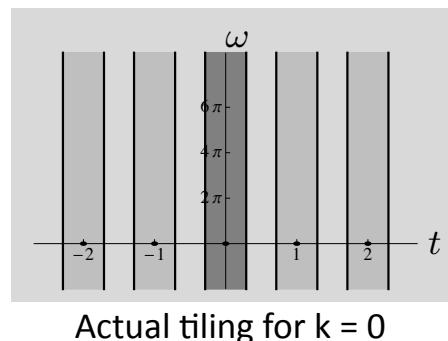
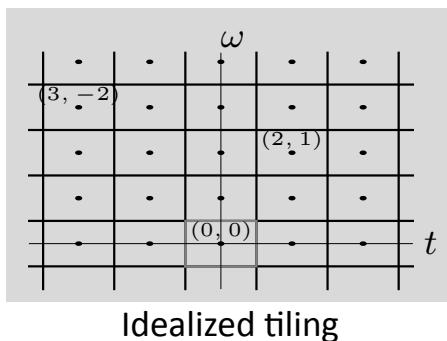
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# Resolution

- Sharp and blurry images
  - Even with the same number of samples
  - Intuitively related to the bandwidth



# Resolution

- Intuitively related to bandwidth
  - Sharp and blurry images
- More universal : Number of degrees of freedom (DoF) per unit time (space)
  - A signal in  $BL[-\omega_0/2, \omega_0/2]$  has  $\omega_0/2\pi$  DoF per unit time
    - It can be specified with this many samples (Nyquist)



- Functions can have infinite bandwidth and finite resolution



# Wrap Up

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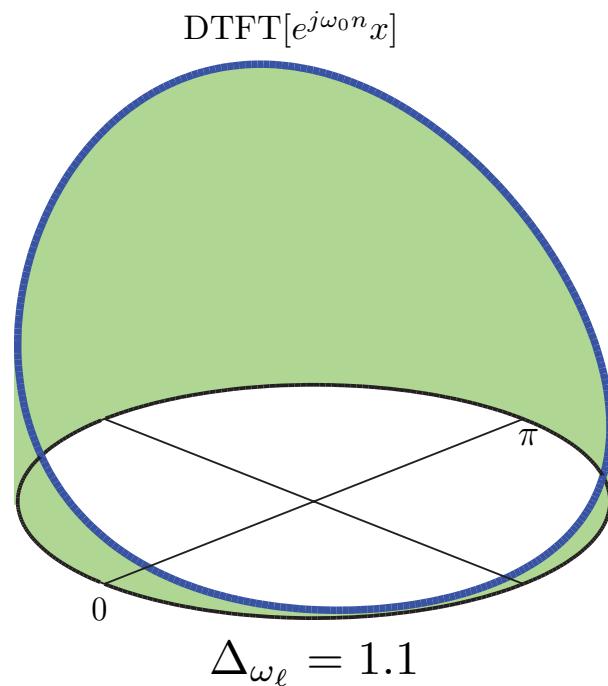
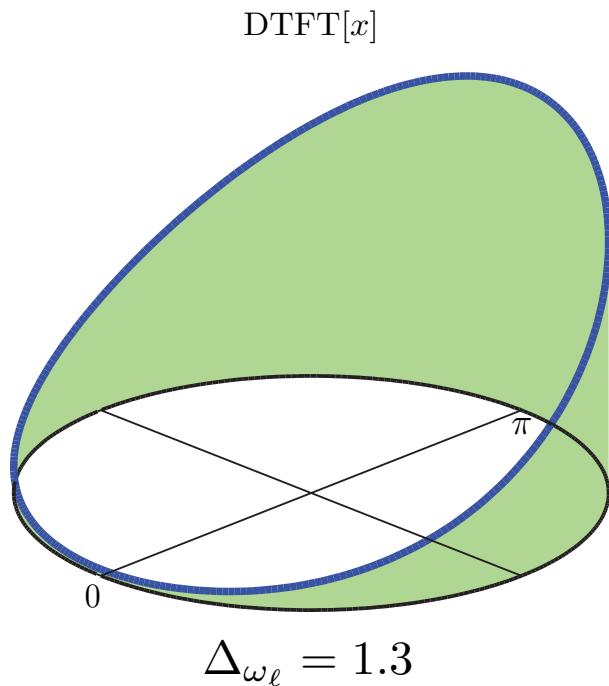
- Filtering and representation
- Localization in time and frequency
  - Measuring the spreads
  - Continuous/continuous
  - Discrete/continuous
  - Discrete/discrete
- Uncertainty Principle
  - No free lunch as usual
- Time-frequency tilings
- Resolution
  - Degrees of freedom

# Bad rumors about DTFT variance!

- zero-at-pi condition!

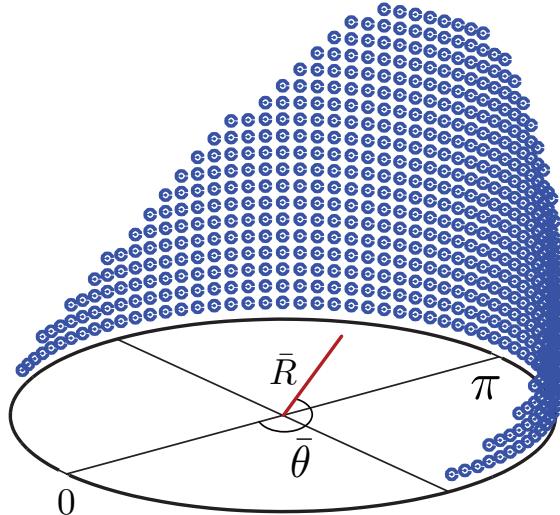
$$x_n = 1 + 4\delta_{n-1} + 2\delta_{n-2} \quad X(e^{j\pi}) \neq 0 \quad \eta_\ell = 0.239 < \frac{1}{4}$$

- if I am periodic, then I want something periodic!



## Suspect no.2: circular statistics

- distributions on a circle!



$$x_n = e^{j\theta_n}$$

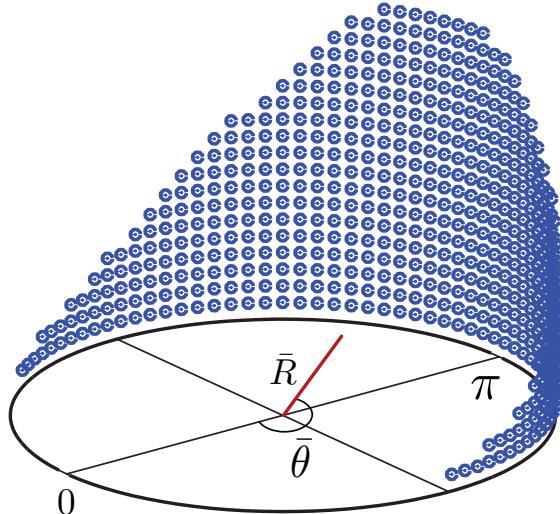
$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_n = \bar{R} e^{j\bar{\theta}}$$

$$\bar{\theta} \neq \frac{1}{n} \sum_{i=1}^n \theta_n$$

- mean and variance:

# Suspect no.2: circular statistics

- distributions on a circle!



$$x_n = e^{j\theta_n}$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_n = \bar{R} e^{j\bar{\theta}}$$

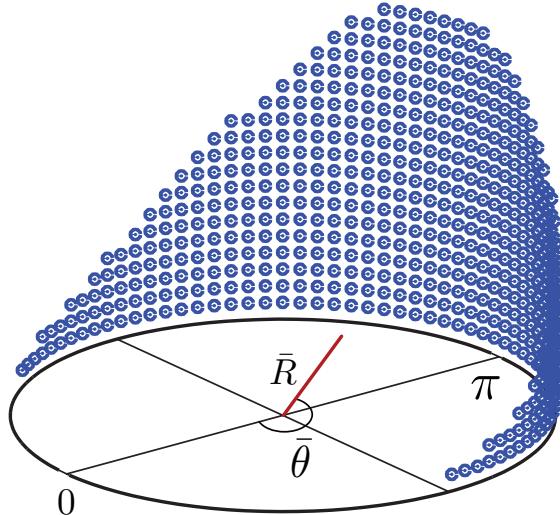
$$\bar{\theta} \neq \frac{1}{n} \sum_{i=1}^n \theta_n$$

- mean and variance:

$$\mathbb{E}[\theta] \approx \arg[\bar{x}]$$

## Suspect no.2: circular statistics

- distributions on a circle!



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$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_n = \bar{R} e^{j\bar{\theta}}$$

$$\bar{\theta} \neq \frac{1}{n} \sum_{i=1}^n \theta_n$$

- mean and variance:

$$\text{var}[\theta] \approx 2(1 - \bar{R})$$

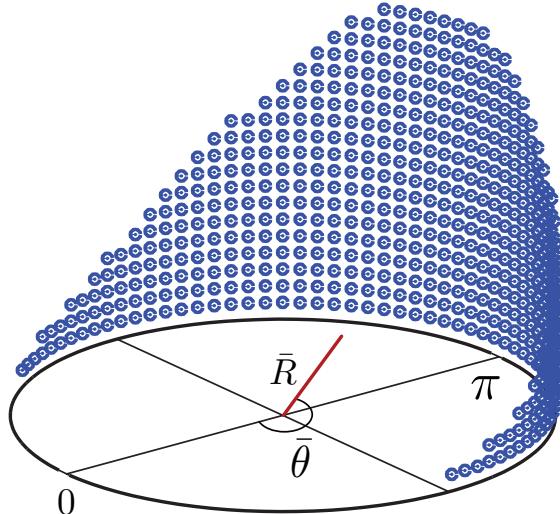
$$\mathbb{E}[\theta] \approx \arg[\bar{x}]$$

$$\text{or } \approx 1 - \bar{R}^2$$

$$\text{or } \approx \frac{1}{\bar{R}^2} - 1$$

## Suspect no.2: circular statistics

- distributions on a circle!



$$x_n = e^{j\theta_n}$$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_n = \bar{R} e^{j\bar{\theta}}$$

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- mean and variance:

$$\mathbb{E}[\theta] \approx \arg[\bar{x}]$$

$$\text{var}[\theta] \approx 2(1 - \bar{R})$$

$$\text{or } \approx 1 - \bar{R}^2$$

$$\text{or } \approx \frac{1}{\bar{R}^2} - 1$$

# Circular statistics for the DTFT

- First trigonometric moment

$$\tau(x) = \int_{-\pi}^{\pi} e^{j\omega} \frac{|X(e^{j\omega})|^2}{2\pi\|x\|^2} d\omega = \frac{1}{\|x\|^2} \sum_{i \in \mathbb{Z}} x_i x_{i+1}^*$$

- Periodic mean and variance

$$\mu_{\omega_p} = \arg[\tau(x)]$$

$$\Delta_{\omega_p}^2 = \frac{1}{|\tau(x)|^2} - 1 = \left| \frac{\|x\|^2}{\sum_{n \in \mathbb{Z}} x_n x_{n+1}^*} \right|^2 - 1$$

- These definitions are periodic!

$$\mu_{\omega_p}(x_n e^{-j\omega_0 n}) = \mu_{\omega_p}(x_n) - \omega_0$$

$$\Delta_{\omega_p}(x_n e^{-j\omega_0 n}) = \Delta_{\omega_p}(x_n)$$

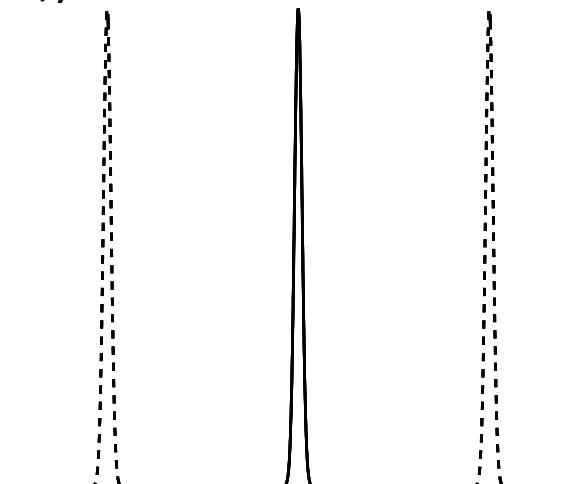
# Mr. Heisenberg meets suspect no.2

- Heisenberg uncertainty principle

For  $x_n \in \ell^2(\mathbb{Z})$ , with  $\|x_n\|_0 > 1$ ,

$$\eta_p = \Delta_n \Delta_{\omega_p} > \frac{1}{4}$$

- [Prestin99]: no sequence can achieve the lower bound!
- **Asymptotically wrapped Gaussians** can achieve it!
  - But then they are not really periodic anymore ;)



# maximally compact sequences

- Find the most compact sequence in time for a given frequency spread

$$\begin{aligned}\Delta_{n,\text{opt}}^2 &= \underset{x_n}{\text{minimize}} \quad \Delta_n^2 \\ &\text{subject to} \quad \Delta_{\omega_p}^2 = \text{fixed}\end{aligned}$$

- Call the solution **maximally compact**

find maximally  
compact sequences

=

find zero-mean, real, positive,  
unit norm maximally compact  
sequences

# Find them

---

- A whole season in one slide!

$$\Delta_{n,\text{opt}}^2 = \underset{x_n}{\text{minimize}} \quad \sum_{n \in \mathbb{Z}} n^2 x_n^2$$

subject to  $\sum_{n \in \mathbb{Z}} x_n x_{n+1} = \frac{1}{\sqrt{1 + \sigma^2}},$

$$\sum_{n \in \mathbb{Z}} x_n^2 = 1.$$

# Find them

---

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$$\Delta_{n,\text{opt}}^2 = \underset{x_n}{\text{minimize}} \quad \sum_{n \in \mathbb{Z}} n^2 x_n^2$$

subject to  $\sum_{n \in \mathbb{Z}} x_n x_{n+1} = \frac{1}{\sqrt{1 + \sigma^2}}, \rightarrow$

$$\sum_{n \in \mathbb{Z}} x_n^2 = 1.$$

$$\underset{\boldsymbol{x}}{\text{minimize}} \quad \boldsymbol{x}^T \boldsymbol{A} \boldsymbol{x}$$

subject to  $\boldsymbol{x}^T \boldsymbol{B} \boldsymbol{x} = \alpha,$   
 $\boldsymbol{x}^T \boldsymbol{x} = 1,$

$$\boldsymbol{A} = \begin{bmatrix} \ddots & & & & \\ & 2^2 & & 0 & \\ & & 1^2 & & \\ & & & 0 & \\ & & & & 1^2 \\ & 0 & & 2^2 & \\ & & & & \ddots \end{bmatrix}, \quad \boldsymbol{B} = \begin{bmatrix} \ddots & & & & & 0 \\ & \frac{1}{2} & & \frac{1}{2} & & \\ & 0 & \frac{1}{2} & 0 & \frac{1}{2} & \\ & & 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ & & & & 0 & \ddots \end{bmatrix}$$

# Find them

---

- A whole season in one slide!

$$\underset{\mathbf{x}}{\text{minimize}} \quad \text{tr}(\mathbf{A}\mathbf{x}\mathbf{x}^T)$$

subject to  $\text{tr}(\mathbf{B}\mathbf{x}\mathbf{x}^T) = \alpha$

$$\text{tr}(\mathbf{x}\mathbf{x}^T) = 1.$$



$$\underset{\mathbf{x}}{\text{minimize}} \quad \mathbf{x}^T \mathbf{A} \mathbf{x}$$

subject to  $\mathbf{x}^T \mathbf{B} \mathbf{x} = \alpha,$

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# Find them

---

- A whole season in one slide!

$$\underset{\mathbf{x}}{\text{minimize}} \quad \text{tr}(\mathbf{A}\mathbf{x}\mathbf{x}^T)$$

$$\begin{aligned} \text{subject to} \quad & \text{tr}(\mathbf{B}\mathbf{x}\mathbf{x}^T) = \alpha \\ & \text{tr}(\mathbf{x}\mathbf{x}^T) = 1. \end{aligned}$$

$$\underset{\mathbf{X}}{\text{minimize}} \quad \text{tr}(\mathbf{AX})$$

$$\begin{aligned} \text{subject to} \quad & \text{tr}(\mathbf{BX}) = \alpha \\ & \text{tr}(\mathbf{X}) = 1 \\ & \mathbf{X} \succeq 0, \text{ rank}(\mathbf{X}) = 1. \end{aligned}$$

$$\mathbf{A} = \begin{bmatrix} \ddots & & & & & \\ & 2^2 & & 0 & & \\ & & 1^2 & & & \\ & & & 0 & & \\ & & & & 1^2 & \\ & 0 & & & & 2^2 \\ & & & & & \ddots \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} \ddots & & & & & 0 \\ & \frac{1}{2} & 0 & \frac{1}{2} & 0 & \\ & & \frac{1}{2} & 0 & \frac{1}{2} & \\ & & & 0 & \frac{1}{2} & \\ & & & & \frac{1}{2} & \\ & 0 & & & & \ddots \end{bmatrix}$$

# Find them

- A whole season in one slide!

$$\underset{\mathbf{X}}{\text{minimize}} \quad \text{tr}(\mathbf{AX})$$

$$\text{subject to} \quad \text{tr}(\mathbf{BX}) = \alpha$$

$$\text{tr}(\mathbf{X}) = 1$$

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$$\mathbf{A} = \begin{bmatrix} \ddots & & & & & \\ & 2^2 & & 0 & & \\ & & 1^2 & & & \\ & & & 0 & & \\ & & & & 1^2 & \\ & 0 & & & & 2^2 \\ & & & & & \ddots \end{bmatrix}, \quad \mathbf{B} = \begin{bmatrix} \ddots & & & & & 0 \\ & \frac{1}{2} & 0 & \frac{1}{2} & 0 & \frac{1}{2} \\ & & \frac{1}{2} & 0 & \frac{1}{2} & 0 \\ & 0 & & \frac{1}{2} & 0 & \frac{1}{2} \\ & & & & \ddots & \end{bmatrix}$$

# Semidefinite program

- relaxation

$$\begin{aligned} & \underset{\mathbf{X}}{\text{minimize}} && \text{tr}(\mathbf{A}\mathbf{X}) \\ & \text{subject to} && \text{tr}(\mathbf{B}\mathbf{X}) = \alpha \\ & && \text{tr}(\mathbf{X}) = 1 \\ & && \mathbf{X} \succeq 0, \text{ rank}(\mathbf{X}) = 1. \end{aligned}$$

- tight relaxation [shapiro82] (m: number of constraints)

$$\text{rank}(\mathbf{X}^{\text{opt}}) \leq \lfloor (\sqrt{8m + 1} - 1)/2 \rfloor \leq 1$$

- here  $m = 2$ , thus

$$\text{rank}(\mathbf{X}^{\text{opt}}) \leq 1$$

- we can drop the rank constraint!
- now just use cvx!

# Semidefinite program

- relaxation

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- tight relaxation [shapiro82] (m: number of constraints)

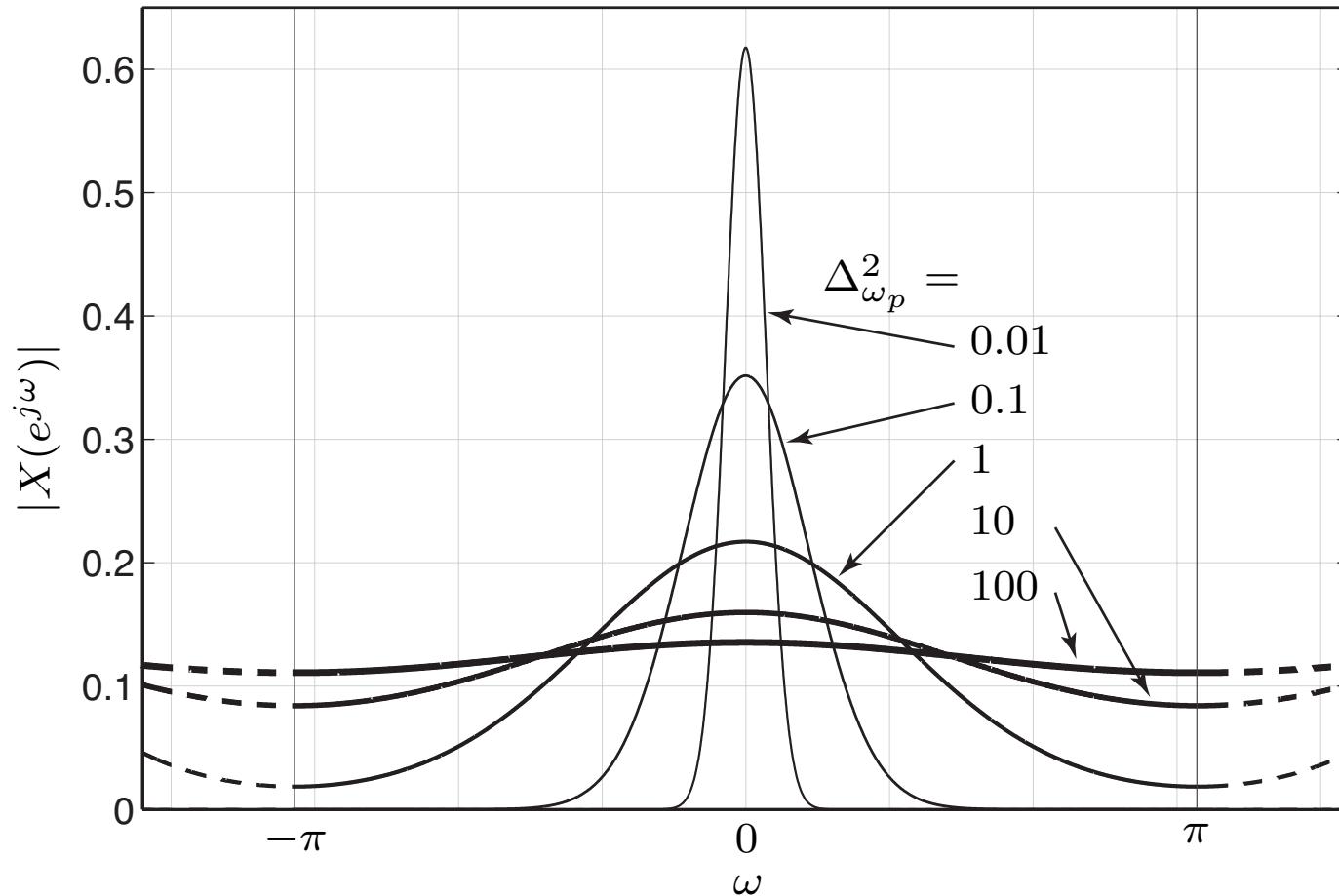
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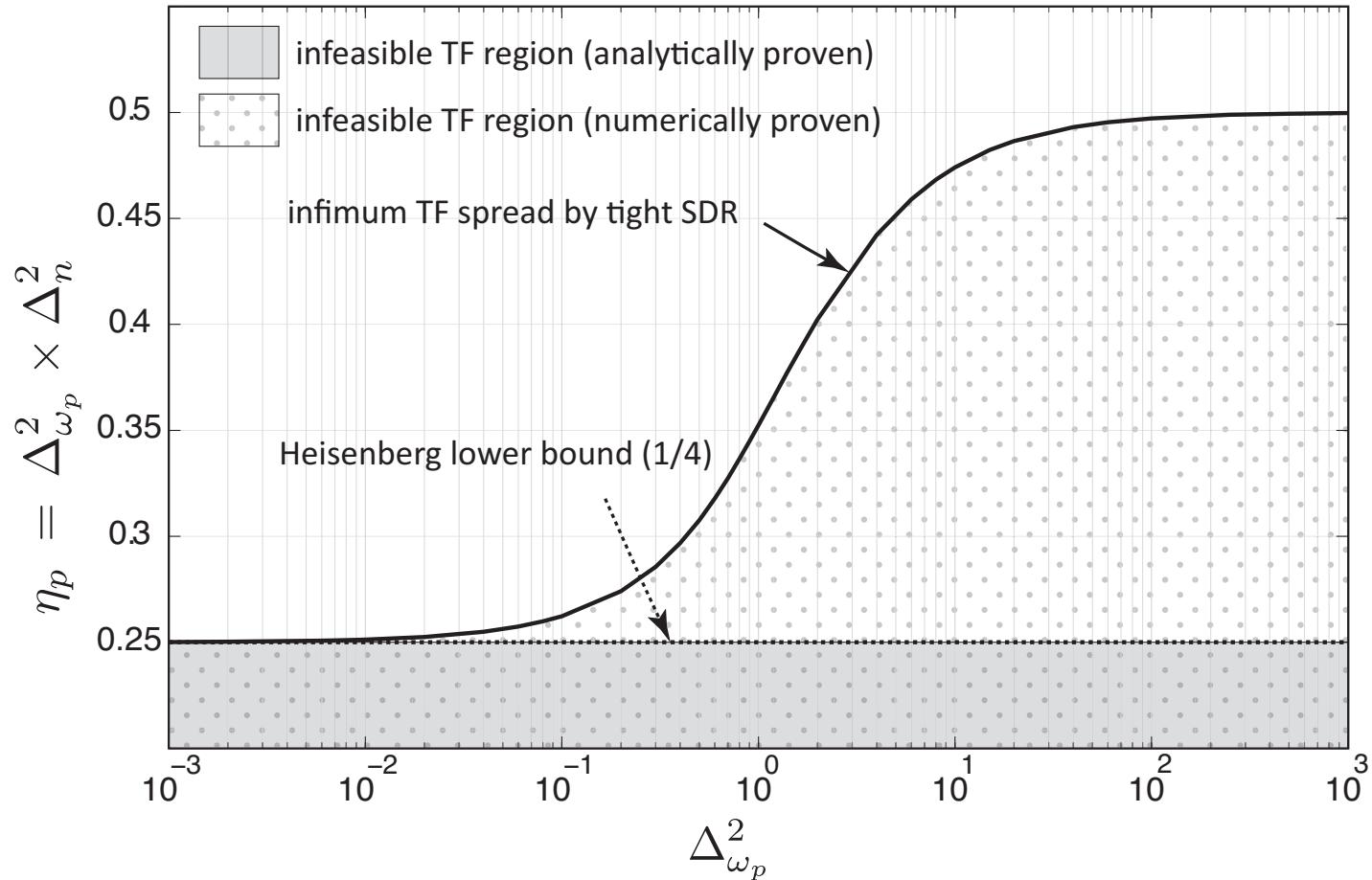
$$\text{rank}(\mathbf{X}^{\text{opt}}) \leq 1$$

- we can drop the rank constraint!
- now just use cvx!

# Experiments



# Mr. Heisenberg is no good here!



# Solve the dual instead

- Primal

$$\underset{\mathbf{X}}{\text{minimize}} \quad \text{tr}(\mathbf{AX})$$

$$\begin{aligned} \text{subject to} \quad & \text{tr}(\mathbf{BX}) = \alpha \\ & \text{tr}(\mathbf{X}) = 1 \end{aligned}$$

- Dual

$$\mathbf{X} \succeq 0$$

$$\underset{\lambda_1, \lambda_2}{\text{maximize}} \quad \alpha \lambda_1 + \lambda_2$$

$$\text{subject to} \quad \mathbf{A} - \lambda_1 \mathbf{B} - \lambda_2 \mathbf{I} \succeq 0$$

for the primal and dual, strong duality holds!

# Analytic lower bound

- A sufficient condition

If  $\lambda_2 \leq 1 - \sqrt{1 + \lambda_1^2}$ , then

$$\boldsymbol{A} - \lambda_1 \boldsymbol{B} - \lambda_2 \boldsymbol{I} \succ 0$$

- Lower bound

$$\underset{\lambda_1, \lambda_2}{\text{maximize}} \quad \alpha \lambda_1 + \lambda_2$$

$$\text{subject to} \quad \lambda_2 \leq 1 - \sqrt{1 + \lambda_1^2}$$

- et voilà!

If  $x_n$  is maximally compact for a given  $\Delta_{\omega_p}^2 = \sigma^2$ , then

$$\eta_p = \Delta n^2 \Delta_{\omega_p}^2 \geq \sigma^2 \left( 1 - \sqrt{\frac{\sigma^2}{1 + \sigma^2}} \right)$$

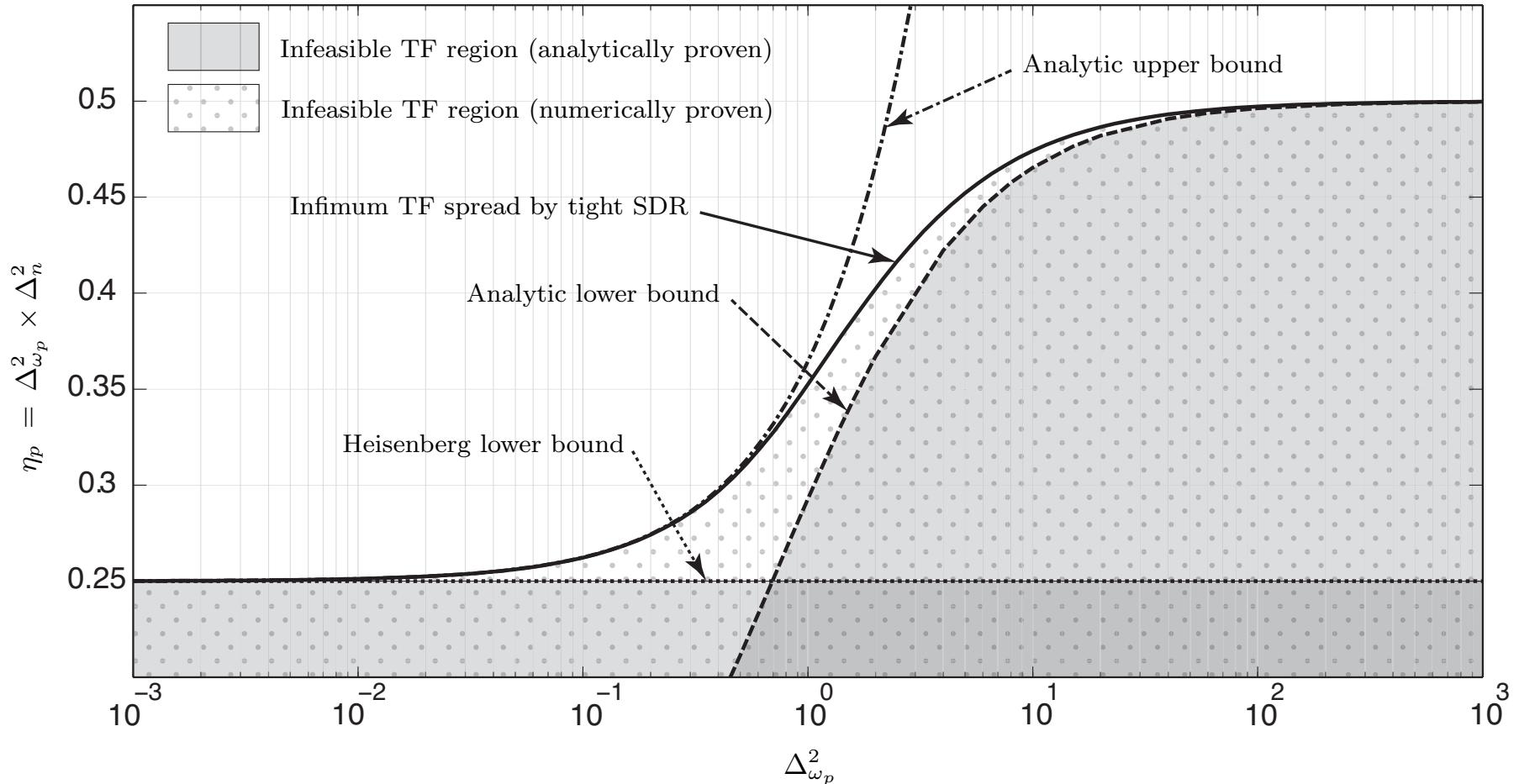
# Analytic Upper Bound

- we can also find an analytic upper bound

if  $x_n$  is maximally compact for a given  $\Delta_{\omega_p} = \sigma^2$ , then for small values of  $\sigma$ , we have

$$\eta_p = \Delta_n^2 \Delta_{\omega_p}^2 \leq \frac{\sigma^2}{8} \left( \frac{\sqrt{1 + \sigma^2}}{\sqrt{1 + \sigma^2} - 1} - \frac{1}{2} \right).$$

# Together we can ...



# A Benchmark for compactness

