



Mathematical Foundations of Signal Processing

Mathematical Foundations of Signal Processing

Benjamín Béjar Haro
Mihailo Kolundžija
Reza Parhizkar
Martin Vetterli

November 3, 2014

Where are we now?

① Geometrical Tools

- Hilbert spaces, projections etc.

② Modeling and Analysis

- Transforms, DT and CT systems, etc.

③ Measuring and Processing

- *Sampling and Interpolation*
- Approximation and Compression
- Localization and Uncertainty
- Compressed Sensing

④ Applications

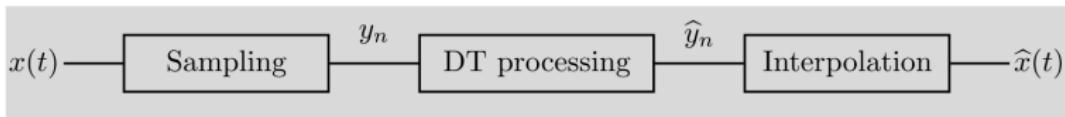
Sampling and Interpolation

- ① Why Sampling?
- ② Sampling and Interpolation as operators in a Hilbert space
- ③ Sampling and Interpolation of finite-dim vectors
- ④ Sampling and Interpolation of sequences in $\ell^2(\mathbb{Z})$
- ⑤ Sampling and Interpolation of functions

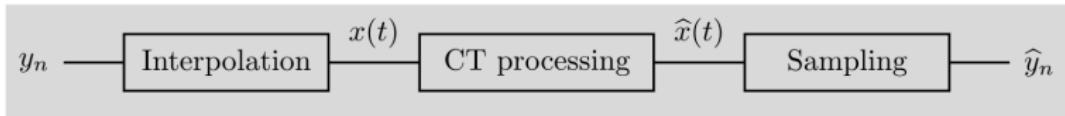
Why Sampling?

Why Sampling?

- World is analog (ch 4). But storing and processing more convenient digitally (ch 3).
- Sampling is the bridge: Given a signal (function) we record its values only at certain instants of time. Trading continuous time description of signal (function) with description based on countable set of values (sequence).
- Convenient but *often lossy*

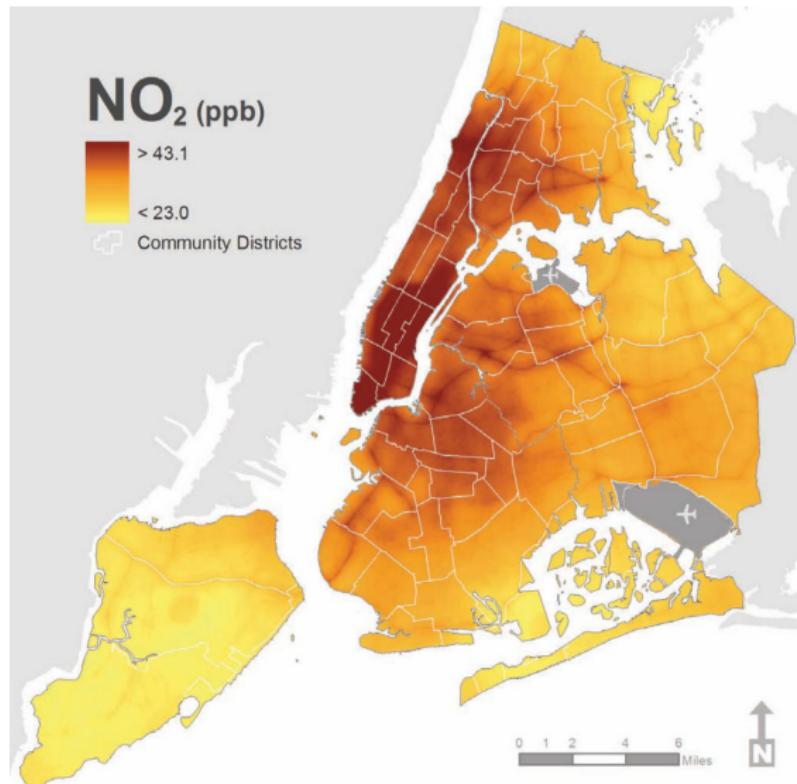


(a) Digital signal processing.

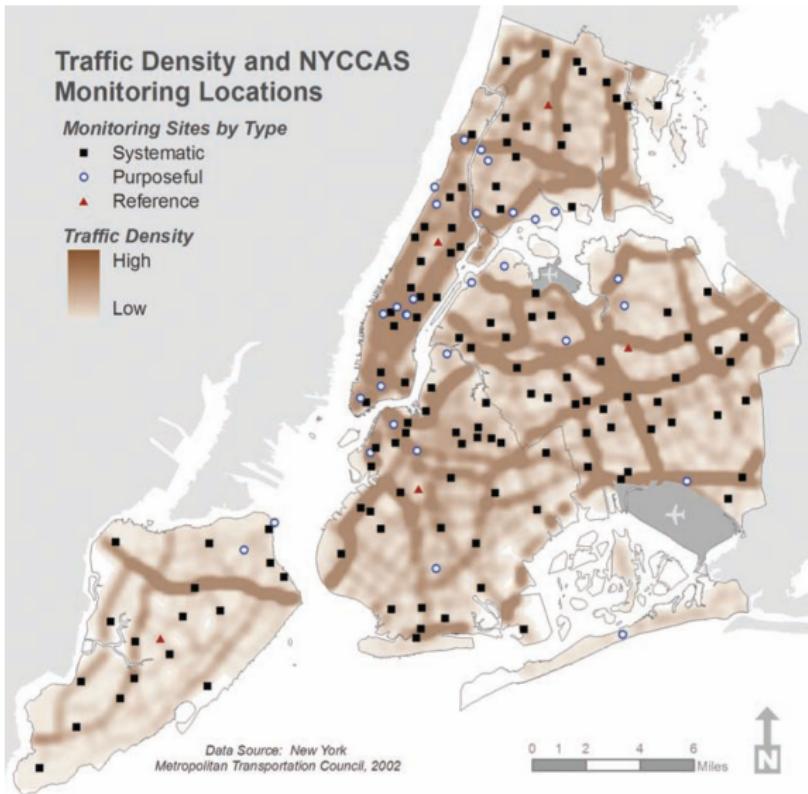


(b) Digital communications.

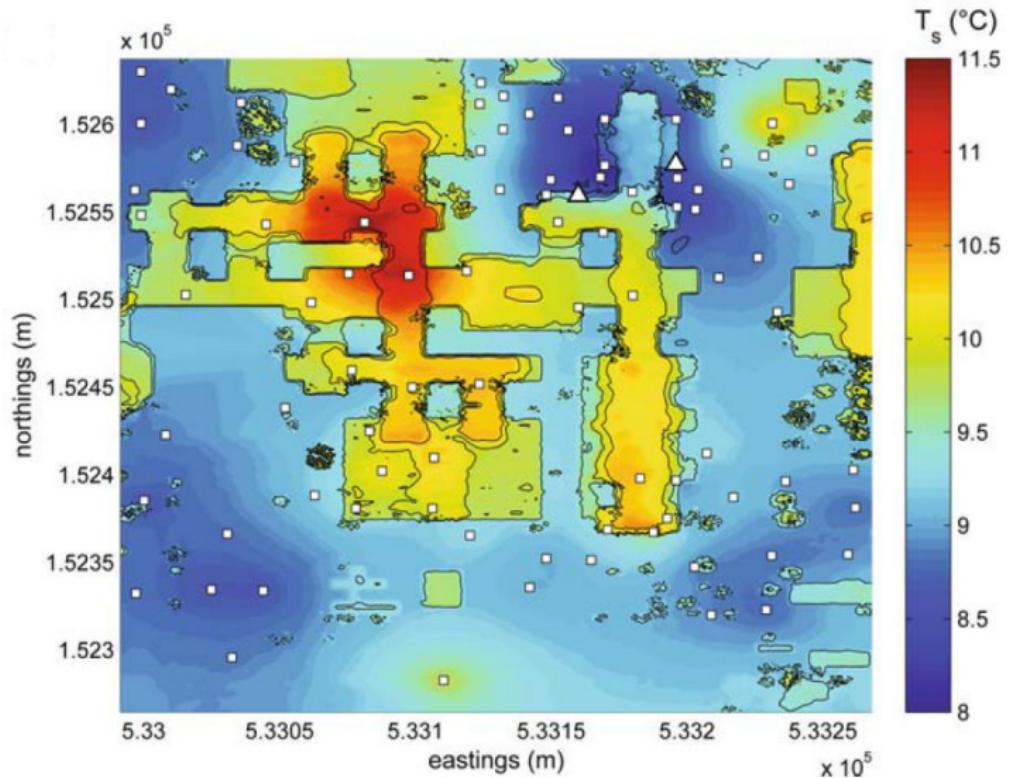
Example: Pollution concentration measurement



Example: Traffic density measurement

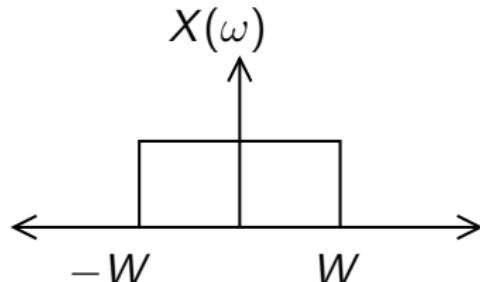


Example: Temperature distribution on campus

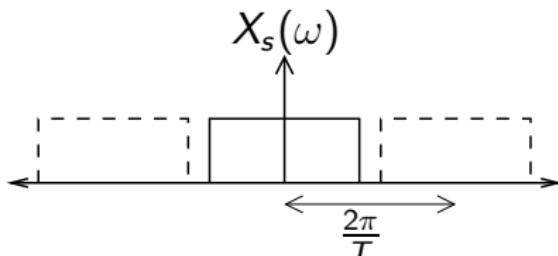
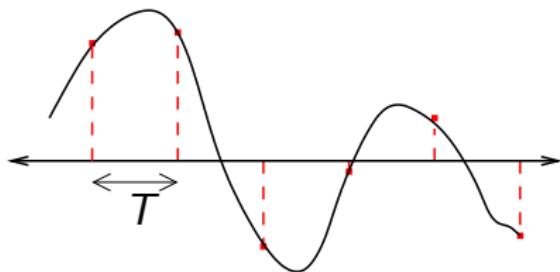


Classical sampling

- Given 1-D bandlimited signal



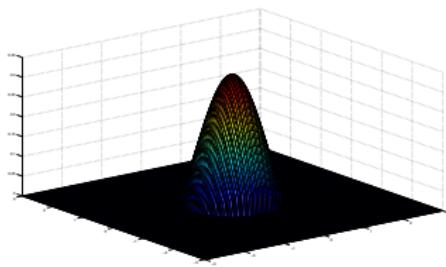
- Perfect recovery via uniform sampling provided $T \leq \frac{\pi}{W}$



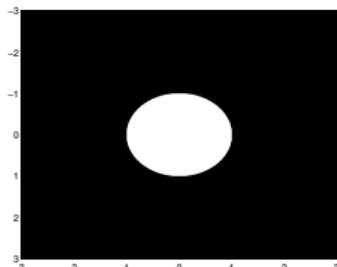
Classical sampling in higher dimensions

- Given: spatially bandlimited field $f : \mathbb{R}^d \mapsto \mathbb{C}$

$$\mathcal{F}(\omega) := \int f(r) e^{-j\langle \omega, r \rangle} dr = 0 \text{ for } \omega \notin \Omega$$



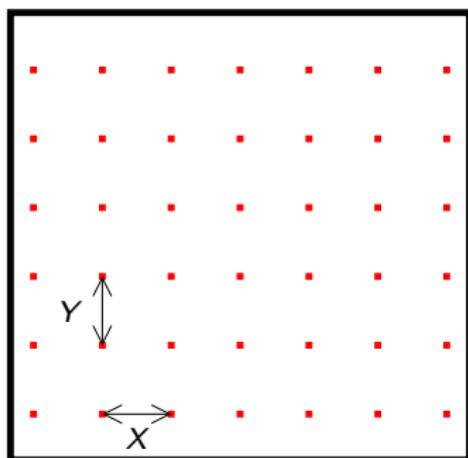
Spectrum $|\mathcal{F}(\omega_x, \omega_y)|$



Support of spectrum Ω

Classical sampling in higher dimensions

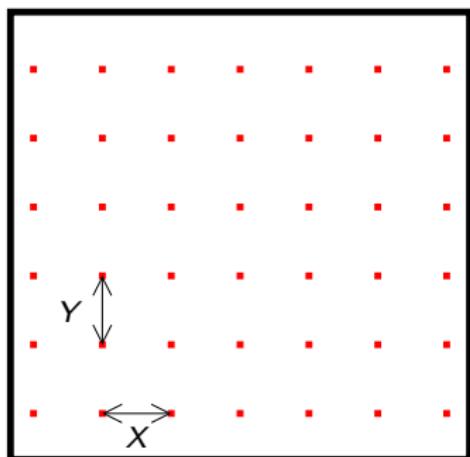
- Sampling on a lattice



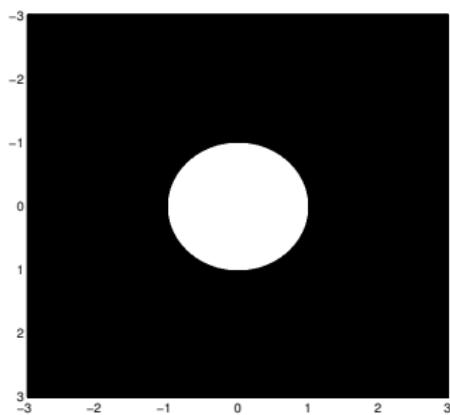
Sampling lattice

Classical sampling in higher dimensions

- Sampling on a lattice



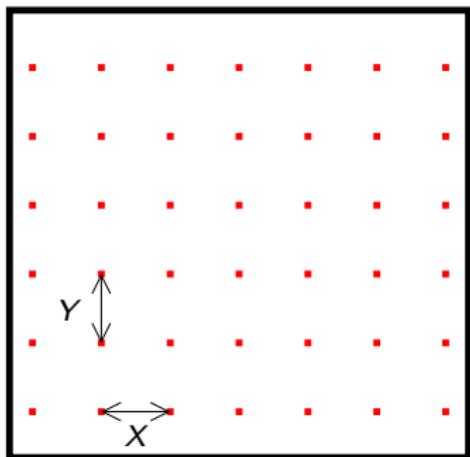
Sampling lattice



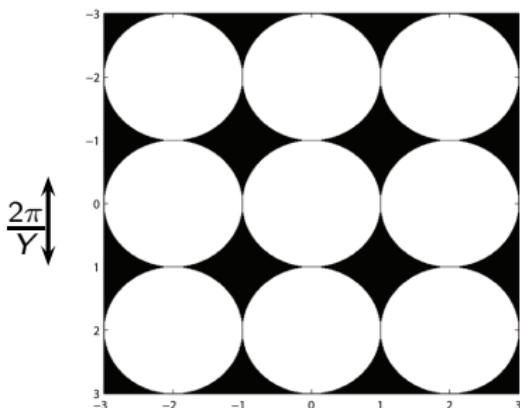
Original spectrum

Classical sampling in higher dimensions

- Sampling on a lattice



Sampling lattice

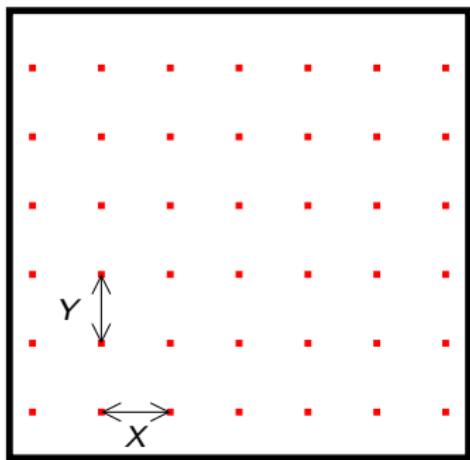


No aliasing in sampled spectrum for

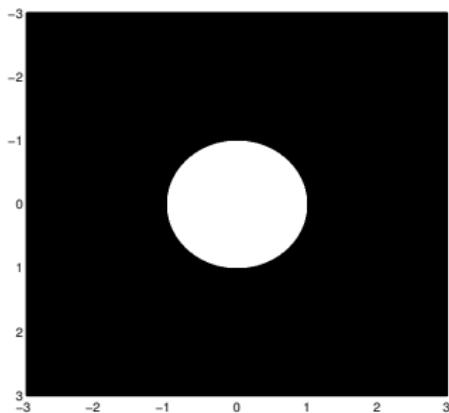
$$X = Y \leq \frac{\pi}{R}$$

Classical sampling in higher dimensions

- Sampling on a lattice



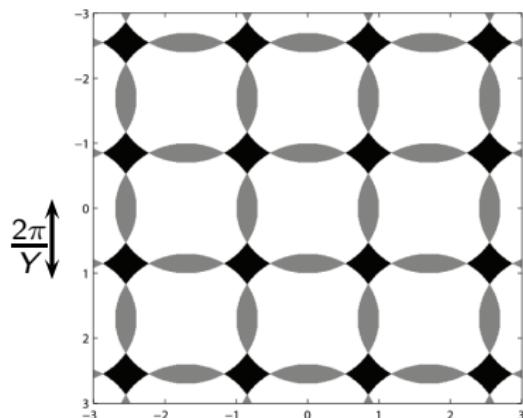
Sampling lattice



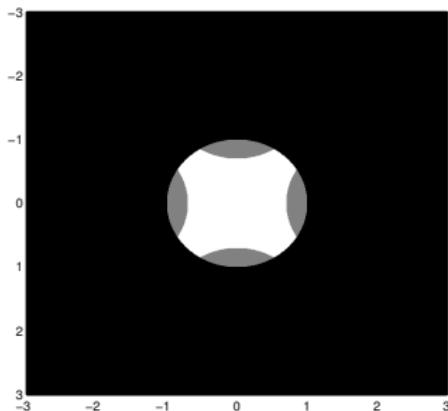
Perfect recovery of original spectrum

Classical sampling in higher dimensions

- Sampling on a lattice



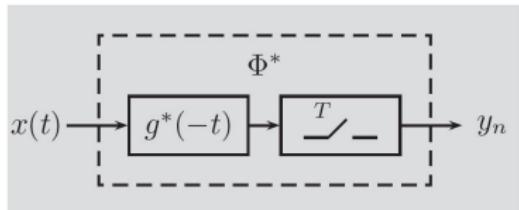
Aliased sampled spectrum



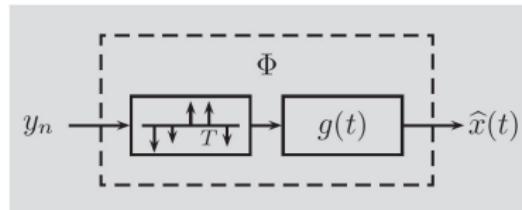
Perfect recovery impossible

- Lattice should be fine enough \equiv Nyquist criterion in \mathbb{R}^d

Sampling and Interpolation as Operators



(a) Sampling.



(b) Interpolation.

- Two questions arise:
 - 1) *How much information* about the signal is contained in the samples?
 - 2) To what extent can we *recover* the signal from the sequence of samples?
- Classical sampling theorem: If x is in $\text{BL}[-\frac{\pi}{T}, \frac{\pi}{T}]$ and $g(t) = \text{sinc}(\frac{\pi t}{T})$ then $\hat{x}(t) = x(t)$

Classical sampling theorem

Theorem (Sampling theorem)

If function x is in $\text{BL}[-\pi/T, \pi/T]$,

$$x(t) = \sum_{n \in \mathbb{Z}} x(nT) \operatorname{sinc}\left(\frac{\pi}{T}(t - nT)\right), \quad t \in \mathbb{R}.$$

- We will see:
 - 1) Why is this true?
 - 2) What are the properties of Φ that make this true?
 - 3) What happens when x is not in $\text{BL}[-\frac{\pi}{T}, \frac{\pi}{T}]$?
 - 4) Can we use different filters in place of g^* and g ?
 - 5) What properties do \hat{x} have in such a case?
- All answers provided via *Hilbert space interpretation*

Sampling and Interpolation as operators in a Hilbert space

If you think about it...

- Classical sampling is a *linear transform* from *Hilbert space* $\mathcal{L}^2(\mathbb{R})$ to *Hilbert space* $\ell^2(\mathbb{Z})$ that admits a more compact representation
 - *Potentially lossy*: Only bandlimited signals can be recovered from the samples
- Classical interpolation is a *linear transform* from *Hilbert space* $\ell^2(\mathbb{Z})$ to *Hilbert space* $\mathcal{L}^2(\mathbb{R})$
 - Embeds information within the bandlimited subspace of $\mathcal{L}^2(\mathbb{R})$

Other kinds of Sampling and Interpolation

- Typical definition of sampling and interpolation:

$$\text{discrete-time signal } (\ell^2(\mathbb{Z})) \quad \begin{matrix} \xrightarrow{\text{interpolation}} \\ \Leftrightarrow \\ \xleftarrow{\text{sampling}} \end{matrix} \quad \text{continuous-time signal } (\mathcal{L}^2(\mathbb{R}))$$

- It could also be

$$\text{low-rate sequence } (\ell^2(\mathbb{Z})) \quad \begin{matrix} \xrightarrow{\text{interpolation}} \\ \Leftrightarrow \\ \xleftarrow{\text{sampling}} \end{matrix} \quad \text{high-rate sequence } (\ell^2(\mathbb{Z}))$$

- Can be extended to

$$\text{shorter finite-length vector } \mathbb{C}^N \quad \begin{matrix} \xrightarrow{\text{interpolation}} \\ \Leftrightarrow \\ \xleftarrow{\text{sampling}} \end{matrix} \quad \text{longer finite-length vector } \mathbb{C}^M$$

- All the above can be interpreted as *linear operators between two Hilbert spaces*

Sampling and Interpolation Operators

We shall discuss sampling and interpolation in the following cases:

- Finite dimensional vectors
- Sequences in $\ell^2(\mathbb{Z})$
- Functions in $\mathcal{L}^2(\mathbb{R})$

Sampling and Interpolation of finite-dim vectors

Sampling and Interpolating Finite dimensional vectors

- Sampling and interpolation are linear operators between finite dimensional subspaces, *for example*, \mathbb{R}^N and \mathbb{R}^M (or \mathbb{C}^N and \mathbb{C}^M) with $N < M$.
 - Represented by *matrix multiplication*
- Sampling will take M values and produce $N < M$ values
 - Sampling matrix is *fat* - i.e., has more columns than rows
- Interpolation will take N values and produce $M > N$ values
 - Interpolation matrix is *tall* - i.e., has more rows than columns

Sampling and interpolation with orthonormal vectors

Sampling

$$y = \begin{bmatrix} \text{---} & \varphi_0^* & \text{---} \\ \text{---} & \varphi_1^* & \text{---} \\ \vdots & & \vdots \\ \text{---} & \varphi_{N-1}^* & \text{---} \end{bmatrix}_{N \times M} \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_{N-1} \end{bmatrix}_{M \times 1} = \Phi^* x.$$

where φ_n^* is the n -th row of Φ^* .

Equivalently, $y_n = \langle x, \varphi_n \rangle$.

Here Φ^* is a $N \times M$ (*fat*) matrix, or equivalently an operator:

$$\Phi^* : \mathbb{C}^M \mapsto \mathbb{C}^N$$

We assume φ_n , $n = 0, \dots, N - 1$ to be *orthonormal*

$$\langle \varphi_n, \varphi_k \rangle = \delta_{n-k} \Leftrightarrow \Phi^* \Phi = I, \text{ where } N < M.$$

Sampling and interpolation with orthonormal vectors

Sampling

$$y = \begin{bmatrix} \text{---} & \varphi_0^* & \text{---} \\ \text{---} & \varphi_1^* & \text{---} \\ \vdots & & \vdots \\ \text{---} & \varphi_{N-1}^* & \text{---} \end{bmatrix}_{N \times M} \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_{N-1} \end{bmatrix}_{M \times 1} = \Phi^* x .$$

Since $N < M$ sampling is a lossy operation

Sampling operator Φ^* has max rank N and $M - N$ dimensional null space $\mathcal{N}(\Phi^*)$ with orthogonal complement $S = \mathcal{N}(\Phi^*)^\perp = \text{span}(\{\varphi_n\}_{n=0,\dots,N-1})$.

When a vector $x \in \mathbb{R}^M$ is sampled *information about the component of x in S is preserved* and is captured by Φ^*x , while the *component in the null space $\mathcal{N}(\Phi^*)$ is lost*. I.e., $y = \Phi^*x_S$.

Sampling and interpolation with orthonormal vectors

Interpolation

$$\hat{x} = \begin{bmatrix} & & & \\ & | & | & | \\ & \varphi_0 & \varphi_1 & \cdots & \varphi_{N-1} \\ & | & | & & | \\ & & & & y_0 \\ & & & & y_1 \\ & & & & \vdots \\ & & & & y_{N-1} \end{bmatrix}_{M \times N} = \Phi y = \sum_{n=0}^{N-1} y_n \varphi_n,$$

where φ_n is the n -th column of Φ .

Since $N < M$, Φ is a *tall matrix*.

As was true for Φ^* , Φ has maximum rank N and the interpolation operator has an N dimensional range $S = \text{span}(\{\varphi_n\}_{n=0,\dots,N-1})$. This subspace is the same as the orthogonal complement of the null space of the sampling operator,

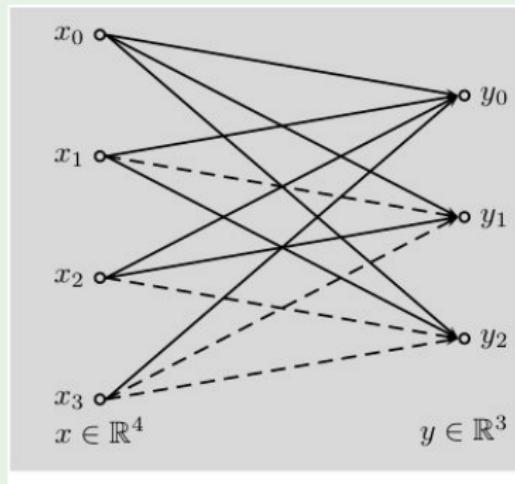
$$\mathcal{R}(\Phi) = S = \mathcal{N}(\Phi^*)^\perp.$$

Sampling and Interpolation Operators

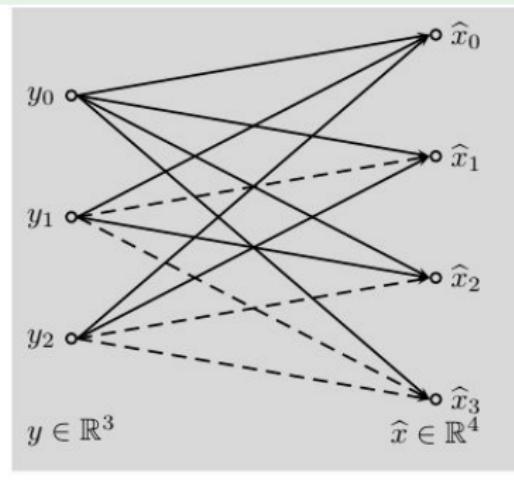
Finite dimensional vectors

Sampling and Interpolation in \mathbb{R}^4

Let us define sampling of $x \in \mathbb{R}^4$ to obtain three samples $y \in \mathbb{R}^3$, where solid lines have weight $1/2$, while dashed lines have weight $-1/2$; for example,
 $y_1 = (x_0 - x_1 + x_2 - x_3)/2$.



(a) Sampling.



(b) Interpolation.

An example

Sampling and Interpolation in \mathbb{R}^4

Consider sampling matrix with orthonormal rows

$$\Phi^* = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \end{bmatrix}_{3 \times 4},$$

with

$$\mathcal{N}(\Phi^*) = \left\{ \alpha \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \right\}, \text{ and } S = \left\{ \alpha_0 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \alpha_1 \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \right\}.$$

For instance

$$\Phi^* \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} = \Phi^* \left(\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} \right) = \Phi^* \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \Phi^* \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

An example

Sampling and Interpolation in \mathbb{R}^4

Now the interpolator operator can be written as

$$\Phi = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & -1 \end{bmatrix}_{4 \times 3},$$

The range of Φ is given by

$$S = \left\{ \alpha_0 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \alpha_1 \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \mid \alpha_0, \alpha_1, \alpha_2 \in \mathbb{C} \right\}.$$

Can verify

$$\mathcal{R}(\Phi) = S = \mathcal{N}(\Phi^*)^\perp.$$

Interpolation followed by sampling

- Since sampling vectors are orthonormal we have

$$\Phi^* \Phi = I.$$

- This means that

$$\Phi^* \Phi y = y, \text{ for all } y \in \mathbb{C}^N$$

i.e., any vector y in the smaller space can be recovered perfectly by interpolating followed by sampling

- In this case, we say sampling and interpolation operators are *consistent*

Sampling followed by interpolation

- Sampling followed by interpolation

$$\Phi\Phi^* = P$$

Here P is an *orthogonal projection operator* because P is

idempotent:

$$P^2 = \Phi\Phi^*\Phi\Phi^* = \Phi(\Phi^*\Phi)\Phi^* = \Phi\Phi^* = P$$

and *self-adjoint*

$$P^* = (\Phi\Phi^*)^* = \Phi\Phi^* = P$$

- Therefore, $\hat{x} = Px$ is the *best least square approximation* of x in $S = (\mathcal{N}(\Phi^*))^\perp = \mathcal{R}(\Phi)$.

$$\hat{x} = \arg \min_{x_S \in S} \|x - x_S\|, \quad x - \hat{x} \perp S.$$

In particular, $\hat{x} = x$ when $x \in S$

Aside: In general Hilbert spaces

- Same ideas extend to general Hilbert spaces, e.g., sequences ($\ell^2(\mathbb{Z})$) or functions ($\mathcal{L}^2(\mathbb{R})$)
- Sampling using *orthonormal vectors* in finite-dimensional vector spaces is analogous to classical sampling in $\mathcal{L}^2(\mathbb{R})$ with *sinc-filter* for filtering and reconstructing
 - There subspace $S = \text{BL}\left[\frac{-\pi}{T}, \frac{\pi}{T}\right]$
 - To be discussed later

Sampling and interpolation with non-orthonormal vectors

Sampling

$$y = \begin{bmatrix} \text{---} & \tilde{\varphi}_0^* & \text{---} \\ \text{---} & \tilde{\varphi}_1^* & \text{---} \\ \vdots & & \vdots \\ \text{---} & \tilde{\varphi}_{N-1}^* & \text{---} \end{bmatrix}_{N \times M} \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_{N-1} \end{bmatrix}_{M \times 1} = \tilde{\Phi}^* x.$$

where $\tilde{\varphi}_n^*$ is the n -th row of $\tilde{\Phi}^*$.

As before assume $\tilde{\Phi}^*$ has full rank N and $M - N$ dimensional null space $\mathcal{N}(\tilde{\Phi}^*)$ with orthogonal complement $\tilde{S} = \mathcal{N}(\tilde{\Phi}^*)^\perp = \text{span}(\{\tilde{\varphi}_n\}_{n=0,\dots,N-1})$.

When a vector $x \in \mathbb{R}^M$ is sampled *information about the component of x in \tilde{S} is preserved* and is captured by $\tilde{\Phi}^* x$, while the *component in the null space $\mathcal{N}(\tilde{\Phi}^*)$ is lost*.

Sampling with non-orthonormal vectors: Example

Sampling and Interpolation in \mathbb{R}^4

Consider sampling matrix with non-orthonormal rows

$$\tilde{\Phi}^* = \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}_{3 \times 4},$$

with

$$\mathcal{N}(\tilde{\Phi}^*) = \left\{ \beta \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right\}, \text{ and } \tilde{S} = \left\{ \beta_0 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \beta_1 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} + \beta_2 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}.$$

Sampling and interpolation with non-orthonormal vectors

Interpolation

Interpolation represented by $M \times N$ matrix Φ , but is not the adjoint of $\tilde{\Phi}^*$

Interpolation output lies in

$$S = \mathcal{R}(\Phi) = \left\{ \sum_{k=0}^{N-1} \alpha_k \varphi_k \mid \alpha \in \mathbb{C}^N \right\}.$$

A possible choice of Φ is the *pseudoinverse of $\tilde{\Phi}^*$* :

$$\Phi = \tilde{\Phi}(\tilde{\Phi}^* \tilde{\Phi})^{-1}$$

In such a case $S = \tilde{S}$

Sampling and interpolation with non-orthonormal vectors

Interpolation followed by sampling

Interpolation followed by sampling is defined by $\tilde{\Phi}^* \Phi$

We say sampling and interpolation operators are *consistent* when Φ is a right inverse of $\tilde{\Phi}^*$:

$$\tilde{\Phi}^* \Phi = I \quad \Leftrightarrow \quad \langle \varphi_n, \tilde{\varphi}_k \rangle = \delta_{n-k}.$$

In this case, the vectors are biorthogonal

They form a *biorthogonal pair* of bases for S when $S = \tilde{S}$, e.g., when Φ is the pseudoinverse of $\tilde{\Phi}^*$. In this case they are called *ideally matched*.

Sampling and interpolation with non-orthonormal vectors

Interpolation followed by sampling

Consider sampling operator

$$\tilde{\Phi}^* = \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}_{3 \times 4}.$$

Two possible consistent interpolators (i.e., right-inverses):

$$\Phi_1 = \frac{1}{2} \begin{bmatrix} 3 & -2 & 1 \\ 1 & 2 & -1 \\ -1 & 2 & 1 \\ 1 & -2 & 3 \end{bmatrix}$$

$$\Phi_2 = \begin{bmatrix} 2 & -1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 2 \end{bmatrix}$$

Pseudoinverse. Ideally matched

Not pseudoinverse. Not ideally matched

Sampling and interpolation with non-orthonormal vectors

Sampling followed by interpolation

Sampling followed by interpolation is defined by $P = \tilde{\Phi}\tilde{\Phi}^*$

When sampling and interpolation operators are *consistent* P is a *projection operator*

$$P^2 = (\tilde{\Phi}\tilde{\Phi}^*)(\tilde{\Phi}\tilde{\Phi}^*) = \tilde{\Phi}(\tilde{\Phi}^*\tilde{\Phi})\tilde{\Phi}^* = \tilde{\Phi}/\tilde{\Phi}^* = \tilde{\Phi}\tilde{\Phi}^* = P$$

If Φ is the *pseudoinverse* of $\tilde{\Phi}^*$, then P is self-adjoint and hence is an *orthogonal projection operator*

$$\begin{aligned} P^* &= (\tilde{\Phi}\tilde{\Phi}^*)^* = (\tilde{\Phi}(\tilde{\Phi}^*\tilde{\Phi})^{-1}\tilde{\Phi}^*)^* = \tilde{\Phi}((\tilde{\Phi}^*\tilde{\Phi})^{-1})^*\tilde{\Phi}^* \\ &= \tilde{\Phi}(\tilde{\Phi}^*\tilde{\Phi})^{-1}\tilde{\Phi}^* = \tilde{\Phi}\tilde{\Phi}^* = P \end{aligned}$$

In this case $S = \tilde{S}$ and sampling and interpolation operators are called *ideally matched*.

Sampling and interpolation with non-orthonormal vectors

Sampling followed by interpolation

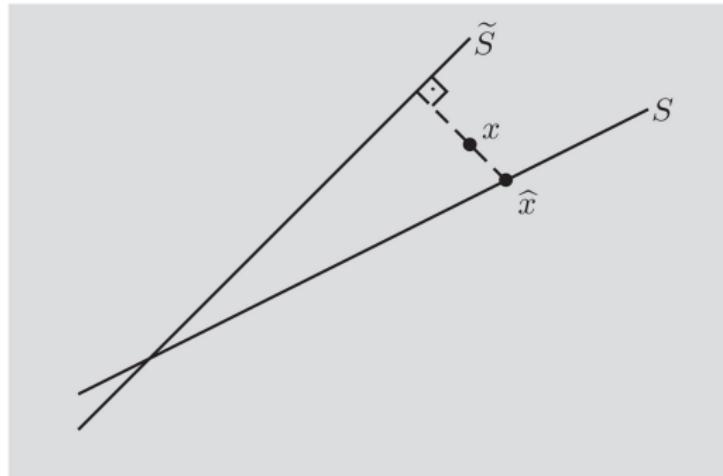
Theorem (Recovery for vectors, nonorthogonal)

Let sampling operator $\tilde{\Phi}^* : \mathbb{C}^M \rightarrow \mathbb{C}^N$ and interpolation operator $\Phi : \mathbb{C}^N \rightarrow \mathbb{C}^M$ satisfy consistency condition $\tilde{\Phi}^* \Phi = I$. Then, with $S = \mathcal{R}(\Phi)$, $\tilde{S} = \mathcal{N}(\tilde{\Phi}^*)^\perp$, $P = \Phi \tilde{\Phi}^*$, and $\hat{x} = Px$:

- ① P is a projection operator with range S , and $x - \hat{x} \perp \tilde{S}$. In particular, $\hat{x} = x$ when $x \in S$.
- ② If Φ is the pseudoinverse of $\tilde{\Phi}^*$, then $S = \tilde{S}$ and P is an orthogonal projection operator onto S . Hence Px gives best approximation of x in S .

Sampling and interpolation with non-orthonormal vectors

Subspaces defined in sampling and interpolation



\widetilde{S} represents what can be measured; it is the orthogonal complement of the null space of the sampling operator $\widetilde{\Phi}^*$. S represents what can be reproduced; it is the range of the interpolation operator Φ . When sampling and interpolation are *consistent*, $\Phi\widetilde{\Phi}^*$ is a projection and $x - \hat{x}$ is orthogonal to \widetilde{S} . When furthermore $S = \widetilde{S}$, the projection becomes an orthogonal projection and the sampling and interpolation are *ideally matched*.

Recap

- Sampling and interpolation as *linear operators* between Hilbert spaces
 - Simplest example: Finite dimensional vector spaces
- Sampling matrix Φ^* is *fat* and interpolation matrix Φ is *tall*
- Case 1: Orthogonal sampling vectors (columns of Φ). Then:

$$\Phi^* \Phi = I \quad \text{and} \quad \Phi \Phi^* \text{ is an orthogonal projection operator}$$

- Case 2: Non-orthogonal sampling vectors
 - Sampling $\tilde{\Phi}^*$ and interpolation Φ are *consistent* when
$$\tilde{\Phi}^* \Phi = I$$
 - If Φ is pseudoinverse of $\tilde{\Phi}^*$ then sampling and interpolation operators are *ideally matched* and $\Phi \tilde{\Phi}^*$ forms an orthogonal projection
- Read: Chapter 5, sections 5.1-5.2

Sampling and Interpolation of sequences in $\ell^2(\mathbb{Z})$

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

A different Hilbert Space: Sequences in ℓ^2

We will study downsampling and upsampling of sequences in $\ell^2(\mathbb{Z})$ using Hilbert space framework

- *Shift invariant subspaces of ℓ^2*

A subspace $S \in \ell^2$ is a shift-invariant subspace with respect to shift $L \in \mathbb{Z}^+$ when $x_n \in S$ implies $x_{n-kL} \in S$ for every integer k .

- *Subspace of bandlimited sequences*

A sequence $x_n \in \ell^2(\mathbb{Z})$ is said to have bandwidth $\omega_0 \in (0, 2\pi]$ if the discrete time Fourier transform $X(e^{j\omega})$ satisfies

$$X(e^{j\omega}) = 0 \text{ for all } |\omega| > \frac{\omega_0}{2}.$$

We define then the subspace of ω_0 bandlimited sequences as

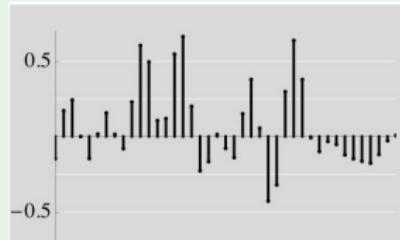
$$BL[-\omega_0/2, \omega_0/2] = \{x_n \mid x_n \text{ has bandwidth at most } \omega_0\}.$$

Remark: *Subspace of bandlimited sequences is shift invariant (prove it!)*

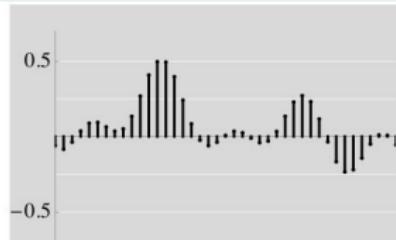
Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in ℓ^2

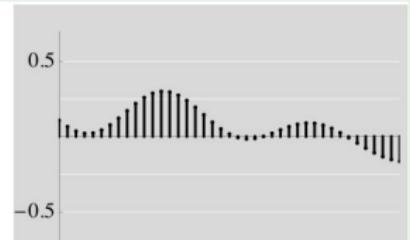
Bandlimited sequences



(a) $\text{BL}[-\pi/2, \pi/2]$.



(b) $\text{BL}[-\pi/4, \pi/4]$.



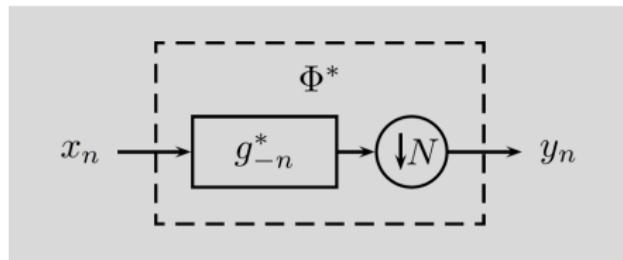
(c) $\text{BL}[-\pi/8, \pi/8]$.

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in ℓ^2 : Sampling

We define as sampling of a sequence $x_n \in \ell^2$ the operation of filtering by g_{-n}^* and downsampling by integer $N > 1$ and we denote it with the operator Φ^*

$$y_n = (\Phi^* x)_n$$



$$\begin{aligned} y_k &= (\Phi^* x)_k = (g_{-n}^* *_n x_n)|_{n=kN} = \left(\sum_{m \in \mathbb{Z}} x_m g_{m-n}^* \right) \Big|_{n=kN} \\ &= \sum_{m \in \mathbb{Z}} x_m g_{m-kN}^* = \langle x_m, g_{m-kN} \rangle_m = \langle x, \varphi_k \rangle, \end{aligned}$$

where $\varphi_{k,n} = g_{n-kN}$, $n \in \mathbb{Z}$.

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in ℓ^2 : Sampling

The sampling operator Φ^* is now an infinite matrix with rows equal to φ^* and its shifts by integer multiples of N .

We assume these rows to be *orthonormal*,

$$\langle \varphi_k, \varphi_\ell \rangle = \delta_{k-\ell} \quad \Leftrightarrow \quad \langle g_{n-kN}, g_{n-\ell N} \rangle_n = \delta_{k-\ell}$$

or equivalently, $\Phi^* \Phi = I$.

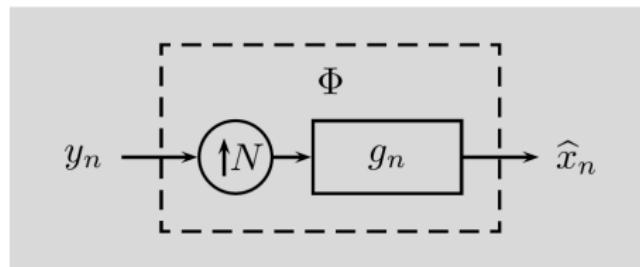
The sampling operator Φ^* has a nontrivial null space $\mathcal{N}(\Phi^*)$ and $S = \mathcal{N}(\Phi^*)^\perp = \text{span}(\{\varphi_n\}_{n \in \mathbb{Z}})$.

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in ℓ^2 : Interpolation

We define as interpolation of a sequence $y_n \in \ell^2$ the operation of upsampling by integer $N > 1$ and filtering by g_n , and we denote it with the operator Φ

$$\hat{x}_n = (\Phi y)_n$$



$$\hat{x}_n = (\Phi y)_n = \sum_{k \in \mathbb{Z}} y_k g_{n-kN} = \left(\sum_{k \in \mathbb{Z}} y_k \varphi_k \right)_n,$$

The interpolation operator Φ is now an infinite matrix with columns equal to φ and its shifts by integer multiples of N .

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sampling and Interpolation in ℓ^2

Set $N = 2$ and choose

$$g_{-n} = \frac{1}{\sqrt{2}} \begin{bmatrix} \cdots & 0 & 1 & \boxed{1} & 0 & 0 & \cdots \end{bmatrix}.$$

Then the sampling reads

$$\begin{bmatrix} \vdots \\ y_0 \\ y_1 \\ \vdots \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \ddots & & & & & & \\ \cdots & \boxed{1} & 1 & 0 & 0 & \cdots \\ \cdots & 0 & 0 & 1 & 1 & \cdots \\ \ddots & \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \vdots \\ x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} = \Phi^* x.$$

For every two inputs samples x_{2k} and x_{2k+1} , we get one output sample $y_k = (x_{2k} + x_{2k+1})\sqrt{2}$, and we have

$$\mathcal{N}(\Phi^*) = \{x \in \ell^2(\mathbb{Z}) \mid x_{2k} = -x_{2k+1}, k \in \mathbb{Z}\}.$$

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sampling and Interpolation in ℓ^2

$$S = \mathcal{N}(\Phi^*)^\perp = \{x \in \ell^2(\mathbb{Z}) \mid x_{2k} = x_{2k+1} \text{ for all } k \in \mathbb{Z}\}$$
$$= \left\{ \cdots + \alpha_{-1} \begin{bmatrix} \vdots \\ 0 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} + \alpha_0 \begin{bmatrix} \vdots \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} + \alpha_1 \begin{bmatrix} \vdots \\ 0 \\ 0 \\ 1 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} + \cdots \mid \alpha \in \ell^2(\mathbb{Z}) \right\}.$$

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sampling and Interpolation in ℓ^2

We have $g = \frac{1}{\sqrt{2}} [\dots \ 0 \ 0 \ \boxed{1} \ 1 \ 0 \ \dots]^T$.

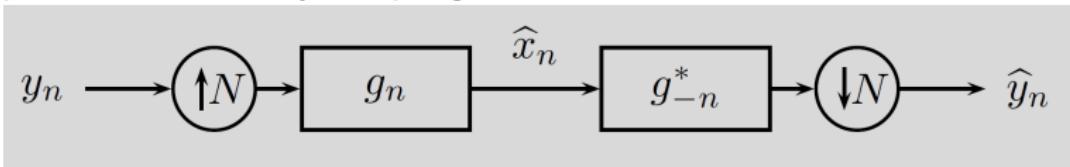
The output of interpolation with $N = 2$ and postfilter g is

$$\begin{bmatrix} \vdots \\ \boxed{\hat{x}_0} \\ \hat{x}_1 \\ \hat{x}_2 \\ \hat{x}_3 \\ \vdots \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} \dots & \boxed{1} & 0 & \dots \\ \dots & 1 & 0 & \dots \\ \dots & 0 & 1 & \dots \\ \dots & 0 & 1 & \dots \\ \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} \vdots \\ \boxed{y_0} \\ y_1 \\ \vdots \end{bmatrix} = \Phi y.$$

For every input sample y_k , we get two output samples $x_{2k} = x_{2k+1} = y_k/\sqrt{2}$.

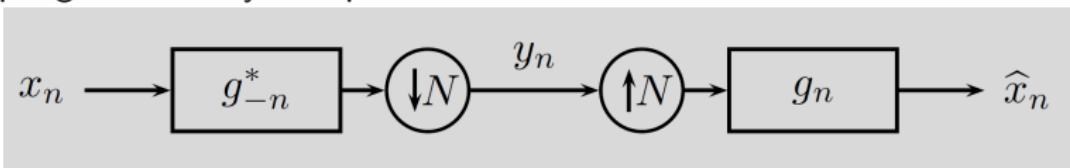
Sampling and Interpolation in $\ell^2(\mathbb{Z})$

- Interpolation followed by sampling



Since $\Phi^* \Phi = I$ we have $\hat{y}_n = y_n$.

- Sampling followed by interpolation



$$\Phi \Phi^* = P.$$

As before P is an orthogonal projection operator. Therefore, Px is the best least square approximation of x in S .

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Theorem (Recovery for sequences, orthogonal)

Assume filter g is such that,

$$\langle \varphi_k, \varphi_\ell \rangle = \delta_{k-\ell} \quad \Leftrightarrow \quad \langle g_{n-kN}, g_{n-\ell N} \rangle_n = \delta_{k-\ell}.$$

Then,

$$\hat{x}_n = \sum_{k \in \mathbb{Z}} y_k g_{n-kN}, \quad n \in \mathbb{Z},$$

where

$$y_k = \sum_{m \in \mathbb{Z}} x_m g_{m-kN}^*, \quad k \in \mathbb{Z},$$

is the best approximation of x in $S = \mathcal{R}(\Phi)$:

$$\hat{x} = \arg \min_{x_S \in S} \|x - x_S\|, \quad x - \hat{x} \perp S.$$

In particular, $\hat{x} = x$ when $x \in S$.

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in $BL[-\omega_0/2, \omega_0/2] \subset \ell^2(\mathbb{Z})$

$$g_n = \frac{1}{\sqrt{N}} \operatorname{sinc} \left(\frac{\pi n}{N} \right), \quad n \in \mathbb{Z}, \quad \xleftrightarrow{\text{DTFT}} \quad G(e^{j\omega}) = \begin{cases} \sqrt{N}, & |\omega| \leq \pi/N; \\ 0, & \text{otherwise,} \end{cases}$$

Like in continuous time, we have that g is a generator with shift N of $BL[-\pi/N, \pi/N]$ (Prove it!). Moreover, as before, shifted versions are orthonormal,

$$\begin{aligned} \langle g_{n-kN}, g_{n-\ell N} \rangle_n &= \frac{1}{2\pi} \langle e^{-j\omega kN} G(e^{j\omega}), e^{-j\omega \ell N} G(e^{j\omega}) \rangle_\omega \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j\omega(k-\ell)N} |G(e^{j\omega})|^2 d\omega \\ &= \frac{N}{2\pi} \int_{-\pi/N}^{\pi/N} e^{-j\omega(k-\ell)N} d\omega = \delta_{k-\ell}. \end{aligned}$$

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in $BL[-\omega_0/2, \omega_0/2] \subset \ell^2(\mathbb{Z})$

Theorem (Projection to bandlimited subspace)

Using sinc filter for g we have

$$\hat{x}_n = \frac{1}{\sqrt{N}} \sum_{k \in \mathbb{Z}} y_k \operatorname{sinc}\left(\frac{\pi}{N}(n - kN)\right), \quad n \in \mathbb{Z},$$

where

$$y_k = \frac{1}{\sqrt{N}} \sum_{n \in \mathbb{Z}} x_n \operatorname{sinc}\left(\frac{\pi}{N}(n - kN)\right), \quad k \in \mathbb{Z},$$

is the best approximation of x in $BL[-\pi/N, \pi/N]$:

$$\hat{x} = \arg \min_{x_{BL} \in BL[-\pi/N, \pi/N]} \|x - x_{BL}\|, \quad x - \hat{x} \perp BL[-\pi/N, \pi/N].$$

In particular, $\hat{x} = x$ when $x \in BL[-\pi/N, \pi/N]$.

Sampling and Interpolation in $\ell^2(\mathbb{Z})$

Sequences in $BL[-\omega_0/2, \omega_0/2] \subset \ell^2(\mathbb{Z})$

Other results from sampling of functions can be generalized:

- Sampling without prefilter
- Sampling with non-orthogonal functions

Summary

- Sampling and Interpolation as linear operators between Hilbert spaces
 - Intuition from finite dimensional Euclidean spaces ($\mathbb{C}^M \rightleftarrows \mathbb{C}^N$)
 - Generalizes to sampling of functions ($L^2(\mathbb{R}) \rightleftarrows \ell^2(\mathbb{Z})$) and sequences ($\ell^2(\mathbb{Z}) \rightleftarrows \ell^2(\mathbb{Z})$)
- *Consistency*: Interpolation followed by Sampling is identity
- *Ideally matched*: Sampling followed by Interpolation is orthogonal projection onto $S = \mathcal{R}(\Phi) = \mathcal{N}(\tilde{\Phi}^*)^\perp$
 - Ideally matched interpolator: Pseudoinverse of Sampling operator
 - For orthonormal vectors, pseudoinverse is the adjoint!
- Reading: Sections 5.1, 5.2, 5.3.1 and parts of 5.3.2 up to Theorem 5.7.
Shannon's original paper sections I and II.