# MAT 653: Statistical Simulation

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## Monte Carlo Integration

Reading: R.C. Section 3.1-3.3 & Voss Section 3.1-3.3

#### Classical Monte Carlo Integration

General problem is to evaluate

$$\mathbb{E}_f[h(X)] = \int_{\mathcal{X}} h(x)f(x) \, dx$$

where h is some known function, X is r.v.  $\sim f$  and  $\mathcal{X} = supp(f)$ . In the following discussion, sometimes the underlying  $\mathcal{X}$  is implicitly assumed.

The principle of M.C. method for evaluating this is to generate an i.i.d. random sample sequence  $(X_1, \dots, X_n)$  from f and propose to estimate  $\mathbb{E}_f[h(X)]$  by empirical average

$$\overline{h}_n = \frac{1}{n} \sum_{j=1}^n h(X_j)$$

this is called M.C. estimator for  $\mathbb{E}_f[h(X)]$ .

If you have a realization for  $\overline{h}_n = \frac{1}{n} \sum_{j=1}^n h(X_j)$ , then this gives you an estimate for  $\mathbb{E}_f[h(X)]$ . This works because by Law of Large numbers,  $\overline{h}_n \to \mathbb{E}_f[h(X)]$ .

Properties of estimator  $\bar{h}_n$ 

1. 
$$\mathbb{E}_f(\overline{h}_n) = \mathbb{E}_f[h(X)]$$
 (i.e. bias=0)  
Proof:  $\mathbb{E}_f(\overline{h}_n) = \frac{1}{n} \sum_{j=1}^n \mathbb{E}_f[h(X_j)] = \frac{1}{n} \sum_{j=1}^n \mathbb{E}_f[h(X)] = \mathbb{E}_f[h(X)]$ 

2. 
$$\mathbb{V}ar_f(\overline{h}_n) = \frac{1}{n} \mathbb{V}ar_f[h(X)]$$

$$\begin{split} \mathbb{V}ar_f(\overline{h}_n) &= \mathbb{V}ar_f \left[\frac{1}{n}\sum_{j=1}^n h(X_j)\right] = \frac{1}{n^2} \mathbb{V}ar_f \left[\sum_{j=1}^n h(X_j)\right] \\ &\stackrel{(*)}{=} \frac{1}{n^2}\sum_{j=1}^n \mathbb{V}ar_f[h(X_j)] = \frac{1}{n^2}\sum_{j=1}^n \mathbb{V}ar_f[h(X)] = \frac{1}{n} \mathbb{V}ar_f[h(X)] \end{split}$$

where (\*) holds since  $X_j \stackrel{iid}{\sim} f$ ,  $Cov(X_i, X_j) = 0 \quad (i \neq j)$ 

And  $\mathbb{V}ar_f(\overline{h}_n)$  can also be estimated from  $(X_1, \dots, X_n)$  by  $\frac{1}{n^2} \sum_{i=1}^n \left[ h(X_i) - \frac{1}{n} \sum_{i=1}^n h(X_i) \right]^2$ .

Proof:

$$\mathbb{V}ar_{f}(\overline{h}_{n}) = \frac{1}{n} \mathbb{V}ar_{f}[h(X)] 
= \frac{1}{n} \mathbb{E}_{f}\{[h(X) - \mathbb{E}_{f}(h(X))]^{2}\} \quad (where \ \mathbb{E}_{f}(h(X)) can \ be \ estimated \ by \ \overline{h}_{n}) 
\leftarrow \frac{1}{n} \mathbb{E}_{f}\{[h(X) - \overline{h}_{n}]^{2}\} \quad (now \ estimate \ \mathbb{E}_{f}[h(X) - \overline{h}_{n}]^{2}) 
\leftarrow \frac{1}{n^{2}} \sum_{j=1}^{n} \left[h(X_{j}) - \overline{h}_{n}\right]^{2} 
= \frac{1}{n^{2}} \sum_{j=1}^{n} \left[h(X_{j}) - \frac{1}{n} \sum_{j=1}^{n} h(X_{i})\right]^{2}$$

**Example:** For  $\mathcal{N}(0,1)$ , want to estimate c.d.f  $\phi(t) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}} e^{-x} dx$ .

Say 
$$f(x) = \frac{1}{\sqrt{2\pi}}e^{-x}$$
, we can rewrite  $\phi(t) = \int_{-\infty}^{t} \frac{1}{\sqrt{2\pi}}e^{-x} dx = \int_{-\infty}^{\infty} \mathbf{1}_{(-\infty,t)}(x) f(x) dx$ .

Therefore, we can generate a sample of size n,  $\{X_i\}_{i=1}^n \stackrel{iid}{\sim} f$ , then use  $\overline{h}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{1}_{(-\infty,t)}(X_i)$  to estimate  $\phi(t)$ .

**Example** (Drawback of classical M.C. integration): If  $Z \sim \mathcal{N}(0,1)$ , and we are asked to evaluate P(Z > 4.5).

$$P(Z > 4.5) = \mathbb{E}_f[\mathbf{1}_{(4.5,\infty)}(Z)]$$

Even though we can use classical M.C. integration: generate a sample of size n,  $\{Z_i\}_{i=1}^n \stackrel{iid}{\sim} \mathcal{N}(0,1)$ , then use  $\overline{h}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{1}_{(4.5,\infty)}(Z_i)$  to estimate P(Z > 4.5). But actually, simulating  $\{Z_i\}_{i=1}^n \stackrel{iid}{\sim} \mathcal{N}(0,1)$  probably only produce a hit  $Z_i \in (4.5,\infty)$  once in large amount of iterations. However, using importance sampling can solve this issue.

### Importance Sampling

Given another p.d.f g s.t.  $supp(g) \supseteq supp(f)$ .

$$\mathbb{E}_f[h(X)] = \int h(x)f(x) \, dx = \int h(x) \frac{f(x)}{g(x)} g(x) \, dx = \mathbb{E}_g\left[h(X) \frac{f(X)}{g(X)}\right]$$

Now, we can generate a sample of size n,  $\{X_i\}_{i=1}^n \stackrel{iid}{\sim} g$ , then use  $\overline{h}_n = \frac{1}{n} \sum_{i=1}^n h(X_i) \frac{f(X_i)}{g(X_i)}$  to estimate  $\mathbb{E}_f[h(X)] = \int h(x) f(x) dx$ .

Where g is called **importance function**,  $\frac{f(X_i)}{g(X_i)}$  is called **importance weight** for  $X_i$  and  $\left(X_i, \frac{f(X_i)}{g(X_i)}\right)$  is called **importance sample**.  $\frac{1}{n} \sum_{i=1}^n h(X_i) \frac{f(X_i)}{g(X_i)}$  is called **importance sampling estimator** for  $\mathbb{E}_f[h(X)]$ .

**Example** (continue the previous example): recall that  $Z \sim \mathcal{N}(0,1)$ , and we are asked to evaluate P(Z > 4.5).

Now we can take g to be density function of  $\exp(1)$  (right) truncated at 4.5:

$$g(y) = P\left(exp(1) = y | exp(1) > 4.5\right) = \frac{P\left(exp(1) = y, exp(1) > 4.5\right)}{P\left(exp(1) > 4.5\right)} = \frac{P\left(exp(1) = y\right)}{P\left(exp(1) > 4.5\right)}$$
$$= \frac{e^{-y}}{1 - \int_0^{4.5} e^{-x} dx} = \frac{e^{-y}}{1 - (1 - e^{-4.5})} = e^{-(y - 4.5)} \quad (y > 4.5)$$

Now we can generate a sample of size n,  $\{Y_i\}_{i=1}^n \stackrel{iid}{\sim} g$ , recall  $f(x) = \frac{1}{\sqrt{2\pi}}e^{-x}$ , then the importance sampling estimator for  $P(Z > 4.5) = \mathbb{E}_f[\mathbf{1}_{(4.5,\infty)}(Z)]$  becomes

$$\frac{1}{n} \sum_{i=1}^{n} \mathbf{1}_{(4.5,\infty)}(Y_i) \frac{f(Y_i)}{g(Y_i)} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}_{(4.5,\infty)}(Y_i) \frac{e^{-\frac{Y_i^2}{2} + Y_i - 4.5}}{\sqrt{2\pi}} = \frac{1}{n} \sum_{i=1}^{n} \frac{e^{-\frac{Y_i^2}{2} + Y_i - 4.5}}{\sqrt{2\pi}}$$

where here  $\mathbf{1}_{(4.5,\infty)}(Y_i) = 1$  since  $\{Y_i\}_{i=1}^n \stackrel{iid}{\sim} g$ .

Remark: we need  $supp(g) \supseteq supp(f)$  to make sure the value of importance weight  $\frac{f(X_i)}{g(X_i)}$  is meaningful. Actually here having a weaker condition  $supp(g) \supseteq supp(h \times f)$  suffices since we have the fraction  $\frac{h(X_i)f(X_i)}{g(X_i)}$ .

#### Self-normalized version of importance sampling

Again, we want to evaluate  $\mathbb{E}_f[h(X)]$ . But now  $f \propto \tilde{f}$ ,  $g \propto \tilde{g}$ . Say  $f = c_o f_0$  where  $f_0$  is the unnormalized p.d.f,  $c_0$  is the normalizing constant. And  $g = c_1 g_1$ , where  $g_0$  is the unnormalized p.d.f,  $c_1$  is the normalizing constant.

Now, suppose we know  $f_0$  and  $g_0$ , but possibly not  $c_0$  and  $c_1$ . And suppose we know how to generate random sample from g.

$$\mathbb{E}_{f}[h(X)] = \int h(x)f(x) dx$$

$$= \frac{\int \frac{h(x)f(x)}{g(x)}g(x) dx}{\int \frac{f(x)}{g(x)}g(x) dx}$$

$$= \frac{\int \frac{f_{0}(x)}{g_{0}(x)}h(x)g(x) dx}{\int \frac{f_{0}(x)}{g_{0}(x)}g(x) dx} \quad (now \ w(x) := \frac{f_{0}(x)}{g_{0}(x)})$$

$$= \frac{\int w(x)h(x)g(x) dx}{\int w(x)g(x) dx} = \frac{\mathbb{E}_{g}[w(x)h(x)]}{\mathbb{E}_{g}[w(x)]}$$

Then we can generate a sample of size n,  $\{X_i\}_{i=1}^n \stackrel{iid}{\sim} g$ , and use  $\hat{\mu} = \frac{\frac{1}{n} \sum_{i=1}^n w(X_i) h(X_i)}{\frac{1}{n} \sum_{i=1}^n w(X_i)}$  to estimate  $\mu = \mathbb{E}_f[h(X)]$ . Here  $\hat{\mu}$  is called **Self-normalized importance sampling estimator** for  $\mu$ .

The reason why  $\hat{\mu} \to \mu$ .

$$\hat{\mu} = \frac{\frac{1}{n} \sum_{i=1}^{n} \frac{f_0(X_i)}{g_0(X_i)} h(X_i)}{\frac{1}{n} \sum_{i=1}^{n} \frac{f_0(X_i)}{g_0(X_i)}} = \frac{\frac{1}{n} \sum_{i=1}^{n} \frac{f(X_i)}{g(X_i)} h(X_i)}{\frac{1}{n} \sum_{i=1}^{n} \frac{f(X_i)}{g(X_i)}} \xrightarrow{LLN} \underbrace{\mathbb{E}_g \left[ \frac{f(X)}{g(X)} h(X) \right]}_{\mathbb{E}_g \left[ \frac{f(X)}{g(X)} \right]}$$

The last term equals to  $\int \frac{h(x)f(x)}{g(x)}g(x)\,dx/\int \frac{f(x)}{g(x)}g(x)\,dx=\int h(x)f(x)\,dx=\mathbb{E}_f[h(X)]=\mu.$